

Title: Lecture - Strong Gravity, PHYS 777

Speakers: William East

Collection/Series: Strong Gravity (Elective), PHYS 777, February 24 - March 28, 2025

Subject: Strong Gravity

Date: March 07, 2025 - 11:30 AM

URL: <https://pirsa.org/25030047>

Extrinsic Curvature

$$K_{ab} = -\nabla_a n_b - \underbrace{(n^c \nabla_c n_a)}_{=a_c} n_b$$

Foliation

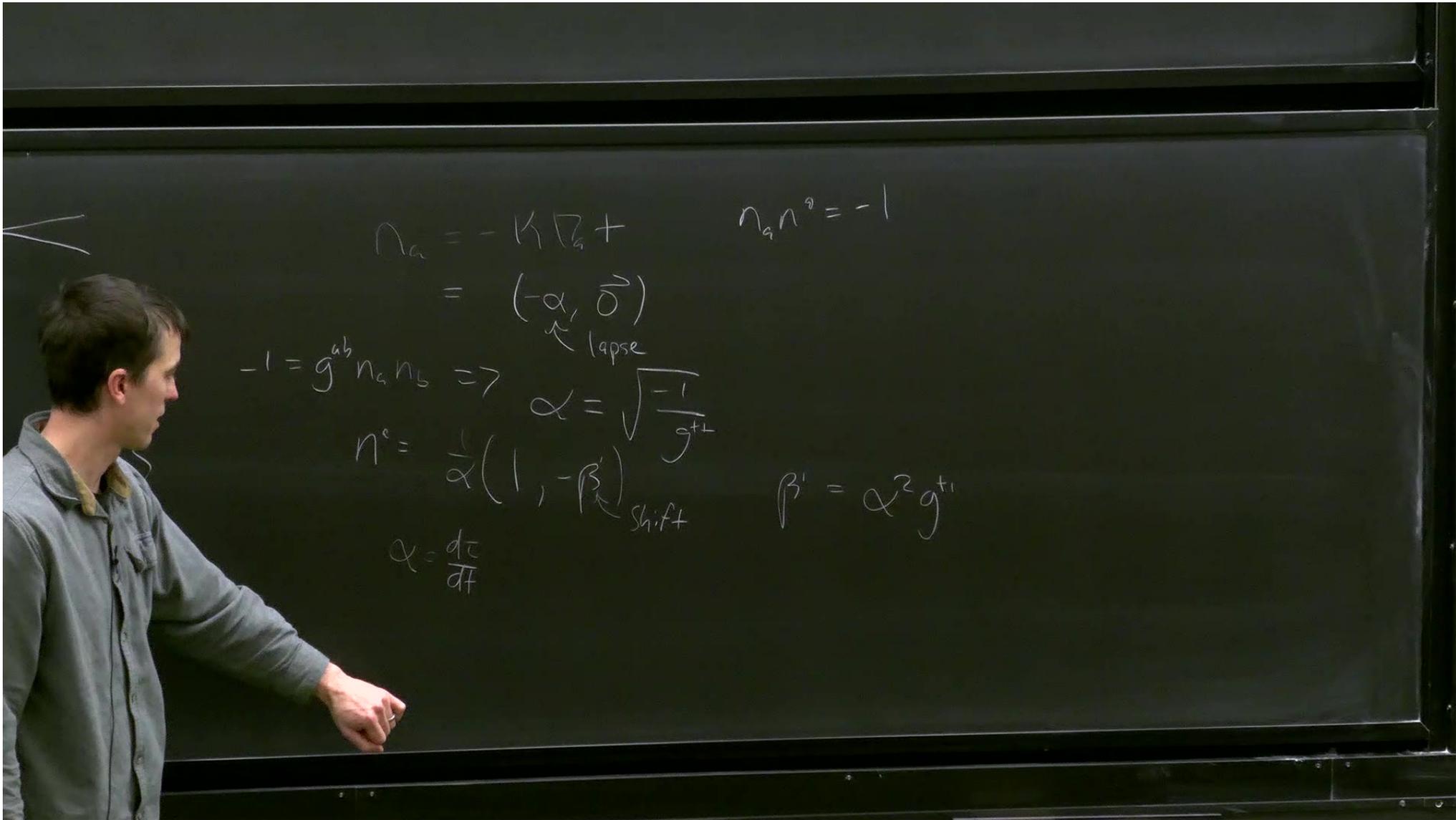
$$M = \{ \Sigma_t \}_{t \in \mathbb{R}}$$

$$\Sigma_t = \{ x^a \in M \mid t(x^a) = t \}$$

slice or leaf

t smooth, $\nabla_c t \neq 0$

M is globally hyperbolic



$$n_a = -K \nabla_a t \quad n_a n^a = -1$$

$$= (-\alpha, \vec{0})$$

↑ lapse

$$-1 = g^{ab} n_a n_b \Rightarrow \alpha = \sqrt{\frac{-1}{g^{tt}}}$$

$$n^c = \frac{1}{\alpha}(1, -\beta^i)$$

↑ shift

$$\beta^i = \alpha^2 g^{ti}$$

$$\alpha = \frac{dt}{d\tau}$$

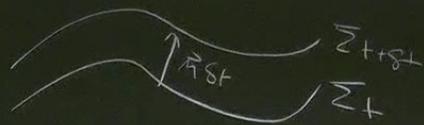
$$\begin{aligned}
 n_a &= -K \nabla_a t & n_a n^a &= -1 \\
 &= (-\alpha, \vec{0}) & & \\
 & \quad \uparrow \text{lapse} & & \\
 -1 &= g^{ab} n_a n_b \Rightarrow \alpha = \sqrt{-\frac{1}{g^{tt}}} \\
 n^c &= \frac{1}{\alpha} (1, -\beta^i) & & \\
 & \quad \uparrow \text{shift} & & \\
 \alpha &= \frac{dt}{d\tau} & -\beta^i &= \frac{dx^i}{dt} \\
 \beta^i &= \alpha^2 g^{ti}
 \end{aligned}$$

Evolution operator

$$m_\alpha = d n_\alpha$$

$$m^\alpha \nabla_\alpha t = 1$$

$$t(p + \delta t \vec{m}) = t(p) + \delta t$$



$$\mathcal{L}_n \delta t = n^\alpha \nabla_\alpha t$$

M is globally hyperbolic

$$\mathcal{L}_n \gamma_{ab} = n^c \nabla_c \gamma_{ab} + \gamma_{cb} \nabla_c n^a + \gamma_{ac} \nabla_b n^c$$
$$\nabla_c \gamma_{ab} = \nabla_c (n_a n_b)$$

$\gamma + \delta t$

$$= -2K_{ab}$$

$$\mathcal{L}_m \gamma_{ab} = -2\alpha K_{ab}$$

$$(3) R_{abc}{}^d U_d = (D_a D_b - D_b D_a) U_c$$

$$R^c{}_{dab} n^a = (\nabla_a \nabla_b - \nabla_b \nabla_a) U^c$$

$$D_a D_b U_c = \gamma_a^d \gamma_b^e \gamma_c^f \nabla_d (\gamma_e^g \gamma_f^h \nabla_g U_h)$$

$$\gamma_{ab} = g_{ab} + n_a n_b$$

$$(3) R^c{}_{dab} = \gamma_a^e \gamma_b^f \gamma_h^c \gamma_d^g R^h{}_{gef} - K_a^c K_{db} + K_b^c K_{ad}$$

$$(3) R_{db} + K K_{db} - K_b^a K_{ad} = \gamma_b^f \gamma_h^e \gamma_d^g R^h{}_{gef} \quad (\square)$$

$$(3) R + K^2 - K_{ab} K^{ab} = R + 2 R_{ab} n^a n^b \quad (*)$$

$$R^c \text{ das } n^d = (\nabla_a \nabla_b - \nabla_b \nabla_a) n^c$$

$$\gamma^c \delta^e \gamma_a^f \gamma_b^g R^d{}_{efg} = D_b k_a^c - D_a k_b^c$$

$$n^e \delta_b^g R_{eg} = D_b k - D_a k_b^a \quad \text{☺}$$

h)

$$+ k_b^c k_{ad}$$

$$\gamma^a R_{\nu} \quad \gamma^a n R_{\nu} \quad \delta^a n R \quad n R = 0$$

(□)

(*)

$$\gamma_{ac} n^a \gamma_b^e R_{fed}^c n^f = \gamma_{ac} n^a \delta_b^c (V_e V_d n^c - V_d V_e n^c)$$

$$\left[\nabla_b n_a = -K_{ab} - D_a \ln \alpha n_b \right]$$

$$\gamma_{ac} n^a \gamma_b^e R_{fed}^c n^f = -K_{af} K_b^f + \frac{1}{\alpha} D_b D_a \alpha + \gamma_{ac} \gamma_b^e n^f \nabla_f K_{ce}$$

$$\gamma_{ac} n^a \gamma_b^e R_{fed}^c n^f = \frac{1}{\alpha} \frac{\varphi}{\alpha_m} K_{ab} + \frac{1}{\alpha} D_a D_b \alpha + K_{af} K_b^f \quad (\Delta)$$

$$R_{ab} - \frac{1}{2} R g_{ab} = 8\pi T_{ab}$$

$$E = T_{ab} n^a n^b \quad \text{energy density}$$

$$p^a = -\gamma^a_c n^b T_{ab} \quad \text{momentum density}$$

$$S_{ab} = \gamma^c_a \gamma^d_b T_{cd} \quad \text{matter stress tensor}$$

$$T = g^{ab} T_{ab} = S - E$$

Fluid $T_{ab} = (\rho + P) u_a u_b + P g_{ab}$

M is globally hyperbolic

$$R_{ab} - \frac{1}{2} R g_{ab} = 8\pi T_{ab}$$

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Fluid $T_{ab} = (\rho + P) U_a U_b + P g_{ab}$

$$E = (\rho + P) W^2 - P$$

$$p^a = (E + P) U^a$$

$$S_{ab} = (E + P) U_a U_b + P \gamma_{ab}$$

$$W = -n_a U^a$$

$$U^a = \frac{1}{W} \gamma^a_b U^b \quad \text{Eulerian velocity}$$

$$R_{ab} n^a n^b + \frac{1}{2} R = 8\pi E$$

$$(*) \Rightarrow {}^3R + K^2 - K_{ab} K^{ab} = 16\pi E$$

$$R_{ab} \delta_c^a n^b - \frac{1}{2} R \delta_c^a \delta_c^a = -8\pi p_c$$

$$(\odot) \Rightarrow D_a K_b^a - D_b K = 8\pi p_b$$

$$R_{ab} = 8\pi \left(T_{ab} - \frac{1}{2} T g_{ab} \right)$$

$$\gamma_c^a \gamma_d^b R_{ab} = 8\pi \left[S_{cd} - \frac{1}{2} (S-E) \gamma_{cd} \right]$$

(\diamond , Δ)

$$-\frac{1}{2} \mathcal{L}_m K_{cd} - \frac{1}{2} D_c D_d \alpha + {}^3R_{cd} + K K_{cd} - 2K_{ca} K^a_d = 8\pi [\dots]$$

$$\mathcal{L}_m \gamma_{ab} = -2\alpha K_{ab}$$

$$E^{ab} = G^{ab} - 8\pi T^{ab}$$

Constraints: $E^{ab} n_b = 0$ $E^{tb} = 0$

$$\nabla_a E^{ab} = \nabla_a \overset{0}{\cancel{G^{ab}}} - 8\pi \nabla_a \overset{0}{\cancel{T^{ab}}} = 0$$

$$\nabla_t E^{tb} = \text{terms involving } E_{as}, \partial_t E_{as}$$

Maxwell Eqs

$$\nabla \cdot \vec{E} = \rho, \quad \nabla \cdot \vec{B} = 0 \quad \text{constraints}$$

$$\partial_t \vec{E} = \nabla \times \vec{B} - \vec{j}, \quad \partial_t \vec{B} = -\nabla \times \vec{E}$$

evolution eqns

$$\partial_t (\nabla \cdot \vec{B}) = 0$$

$$\partial_t (\nabla \cdot \vec{E}) = -\nabla \cdot \vec{j}$$

$$\partial_t \rho + \nabla \cdot \vec{j} = 0$$

$$\partial_t (\nabla \cdot \vec{E} - \rho) = 0$$