

Title: Lecture - Numerical Methods, PHYS 777

Speakers: Erik Schnetter, Dustin Lang

Collection/Series: Numerical Methods (Core), PHYS 777-, January 6 - February 5, 2025

Subject: Other

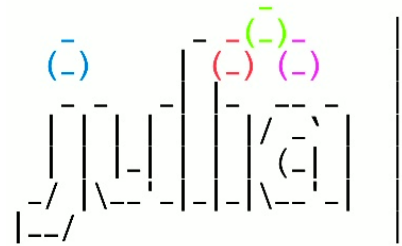
Date: January 21, 2025 - 11:30 AM

URL: <https://pirsa.org/25010059>

```
[0.0, Inf, 0.872, Inf, Inf, Inf, 1.578, Inf, 1.021, Inf]  
[0.0, Inf, 0.872, Inf, 2.552, 2.188, 1.36, 1.771, 1.021, Inf]  
[0.0, 2.818, 0.872, 2.619, 2.334, 1.97, 1.36, 1.771, 1.021, 2.696]  
[0.0, 2.601, 0.872, 2.619, 2.334, 1.97, 1.36, 1.771, 1.021, 2.478]  
10-element Vector{TropicalNumbers.TropicalMinPlusF64}:
```

```
0.0s  
2.600792423391039s  
0.8719003118656656s  
2.6190329085774406s  
2.334107684888196s  
1.96995040396643s  
1.3599975906970543s  
1.7711435879056907s  
1.02086987187335s  
2.4779254788367306s
```

```
julia>  
eschnett@Redshift-8:~/src/jl/NotDijkstra (2025-01-21 11:31:30)  
$ julia --project=@.
```



Documentation: <https://docs.julialang.org>
Type "?" for help, "]"?" for Pkg help.
Version 1.11.2 (2024-12-01)
Official <https://julialang.org/> release

```
julia> using NotDijkstra  
julia> █
```

```
10x10 SparseArrays.SparseMatrixCSC{TropicalNumbers.TropicalMinPlusF64, Int64} with 32 stored entries:
  0.0s      .      .      .      .      .
      .      0.0s      .      .      .      .
0.8719003118656656s  0.05550151483328558s  0.0s      0.9935300439902324s  .      .
      .      .      .      .      .      .
      .      0.125643803387122s  .      .      .      .
      .      .      0.7057980161772197s  0.3391277188237043s  .      .
      .      .      .      .      0.7502737160323407s  .      .
      .      .      0.14896956000768435s  .      .      0.8957801727894336s
      .      0.7690538188199524s  .      .      .      0.0s
```

```
julia> A = make_graph(6)
6x6 SparseArrays.SparseMatrixCSC{TropicalNumbers.TropicalMinPlusF64, Int64} with 17 stored entries:
  0.0s      .      0.7293677262492938s  .      .      0.9469708549161011s
      .      0.0s      .      0.6429511466880946s  .      0.3186848631156003s
0.4857170995024712s  .      0.0s  0.11333391522005432s  0.7297566008797851s  .
      .      0.07492701414885905s  .      0.0s  0.5899681807658527s  .
      .      .      .      .      .      0.0s  0.4902845611914799s
      .      .      0.045368414340598684s  .      .      .      0.0s
```

```
julia> Matrix(A)
6x6 Matrix{TropicalNumbers.TropicalMinPlusF64}:
  0.0s  Inf_s  0.7293677262492938s  Inf_s  Inf_s  0.9469708549161011s
  Inf_s  0.0s  Inf_s  0.6429511466880946s  Inf_s  0.3186848631156003s
0.4857170995024712s  Inf_s  0.0s  0.11333391522005432s  0.7297566008797851s  Inf_s
  Inf_s  Inf_s  0.07492701414885905s  0.0s  0.5899681807658527s  Inf_s
  Inf_s  Inf_s  Inf_s  Inf_s  Inf_s  0.0s  0.4902845611914799s
  Inf_s  Inf_s  0.045368414340598684s  Inf_s  Inf_s  Inf_s  0.0s
```

```
julia> █
```

```
s.var"#8#9"  
  @ SparseArrays ~/.julia/juliaup/julia-1.11.2+0.aarch64.apple.darwin14/share/julia/stdlib/v1.11/SparseArrays/src/sparsematrix.jl:1361  
[5] ftranspose(A::SparseArrays.SparseMatrixCSC{...}, f::Function, eltype::Type{...})  
  @ SparseArrays ~/.julia/juliaup/julia-1.11.2+0.aarch64.apple.darwin14/share/julia/stdlib/v1.11/SparseArrays/src/sparsematrix.jl:1455  
[6] copy  
  @ ~/.julia/juliaup/julia-1.11.2+0.aarch64.apple.darwin14/share/julia/stdlib/v1.11/SparseArrays/src/sparsematrix.jl:1460 [inlined]  
[7] SparseMatrixCSC  
  @ ~/.julia/juliaup/julia-1.11.2+0.aarch64.apple.darwin14/share/julia/stdlib/v1.11/SparseArrays/src/sparsematrix.jl:921 [inlined]  
[8] _sparsifystructured  
  @ ~/.julia/juliaup/julia-1.11.2+0.aarch64.apple.darwin14/share/julia/stdlib/v1.11/SparseArrays/src/higherorderfns.jl:1178 [inlined]  
[9] map  
  @ ./tuple.jl:356 [inlined]  
[10] copy  
  @ ~/.julia/juliaup/julia-1.11.2+0.aarch64.apple.darwin14/share/julia/stdlib/v1.11/SparseArrays/src/higherorderfns.jl:1167 [inlined]  
[11] materialize  
  @ ./broadcast.jl:867 [inlined]  
[12] broadcast_preserving_zero_d  
  @ ./broadcast.jl:856 [inlined]  
[13] +(A::SparseArrays.SparseMatrixCSC{...}, B::LinearAlgebra.Adjoint{...})  
  @ Base ./arraymath.jl:8  
[14] top-level scope  
  @ REPL[5]:1
```

Some type information was truncated. Use `show(err)` to see complete types.

julia> █

```
[7] SparseMatrixCSC
    @ ~/.julia/juliaup/julia-1.11.2+0.aarch64.apple.darwin14/share/julia/stdlib/v1.11/SparseArrays/src/sparsematrix.jl:
921 [inlined]
[8] _sparsifystructured
    @ ~/.julia/juliaup/julia-1.11.2+0.aarch64.apple.darwin14/share/julia/stdlib/v1.11/SparseArrays/src/higherorderfns.j
l:1178 [inlined]
[9] map
    @ ./tuple.jl:356 [inlined]
[10] copy
    @ ~/.julia/juliaup/julia-1.11.2+0.aarch64.apple.darwin14/share/julia/stdlib/v1.11/SparseArrays/src/higherorderfns.j
l:1167 [inlined]
[11] materialize
    @ ./broadcast.jl:867 [inlined]
[12] broadcast_preserving_zero_d
    @ ./broadcast.jl:856 [inlined]
[13] +(A::SparseArrays.SparseMatrixCSC{...}, B::LinearAlgebra.Adjoint{...})
    @ Base ./arraymath.jl:8
[14] top-level scope
    @ REPL[5]:1
```

Some type information was truncated. Use `show(err)` to see complete types.

```
julia> Matrix(A)
6x6 Matrix{TropicalNumbers.TropicalMinPlusF64}:
      0.0s  Inf_s      0.7293677262492938s      Inf_s      Inf_s      0.9469708549161011s
      Inf_s  0.0s      Inf_s      0.6429511466880946s      Inf_s      0.3186848631156003s
0.4857170995024712s  Inf_s      0.0s      0.11333391522005432s  0.7297566008797851s      Inf_s
      Inf_s  Inf_s      0.07492701414885905s      0.0s      0.5899681807658527s      Inf_s
      Inf_s  Inf_s      Inf_s      Inf_s      Inf_s      0.0s      0.4902845611914799s
      Inf_s  Inf_s      0.045368414340598684s      Inf_s      Inf_s      Inf_s      0.0s
```

```
julia> █
```

```
@ REPL[5]:1
Some type information was truncated. Use `show(err)` to see complete types.
```

```
julia> Matrix(A)
6×6 Matrix{TropicalNumbers.TropicalMinPlusF64}:
  0.0s  Inf_s  0.7293677262492938s  Inf_s  Inf_s  0.9469708549161011s
  Inf_s  0.0s  Inf_s  0.6429511466880946s  Inf_s  0.3186848631156003s
0.4857170995024712s  Inf_s  0.0s  0.11333391522005432s  0.7297566008797851s  Inf_s
  Inf_s  Inf_s  0.07492701414885905s  0.0s  0.5899681807658527s  Inf_s
  Inf_s  Inf_s  Inf_s  Inf_s  Inf_s  0.0s  0.4902845611914799s
  Inf_s  Inf_s  0.045368414340598684s  Inf_s  Inf_s  Inf_s  0.0s
```

```
julia> x = make_initial(6)
6-element Vector{TropicalNumbers.TropicalMinPlusF64}:
 0.0s
 Inf_s
 Inf_s
 Inf_s
 Inf_s
 Inf_s
```

```
julia> A*x
6-element Vector{TropicalNumbers.TropicalMinPlusF64}:
 0.0s
 Inf_s
0.4857170995024712s
 Inf_s
 Inf_s
 Inf_s
```

```
julia> █
```

```
Inf_s
0.5310855138430699_s

julia> A*A*A*x
6-element Vector{TropicalNumbers.TropicalMinPlusF64}:
 0.0_s
 0.8497703769586702_s
 0.4857170995024712_s
 0.5606441136513303_s
 1.0213700750345498_s
 0.5310855138430699_s

julia> A*A*A*A*x
6-element Vector{TropicalNumbers.TropicalMinPlusF64}:
 0.0_s
 0.8497703769586702_s
 0.4857170995024712_s
 0.5606441136513303_s
 1.0213700750345498_s
 0.5310855138430699_s

julia> A*A*A*A*A*x
6-element Vector{TropicalNumbers.TropicalMinPlusF64}:
 0.0_s
 0.8497703769586702_s
 0.4857170995024712_s
 0.5606441136513303_s
 1.0213700750345498_s
 0.5310855138430699_s

julia> █
```

```
0.5606441136513303s
1.0213700750345498s
0.5310855138430699s
```

```
julia> A*A*A*A*A*x
6-element Vector{TropicalNumbers.TropicalMinPlusF64}:
```

```
0.0s
0.8497703769586702s
0.4857170995024712s
0.5606441136513303s
1.0213700750345498s
0.5310855138430699s
```

```
julia> find_costs9
ERROR: UndefVarError: `find_costs9` not defined in `Main`
Suggestion: check for spelling errors or missing imports.
```

```
julia> find_costs(A)
ERROR: MethodError: no method matching find_costs(::SparseArrays.SparseMatrixCSC{TropicalNumbers.TropicalMinPlusF64, Int64})
The function `find_costs` exists, but no method is defined for this combination of argument types.
```

```
Closest candidates are:
  find_costs(::AbstractMatrix, ::AbstractVector)
  @ NotDijkstra ~/src/jl/NotDijkstra/src/NotDijkstra.jl:34
```

```
Stacktrace:
 [1] top-level scope
  @ REPL[14]:1
```

```
julia> █
```



```
julia> find_costs9
ERROR: UndefVarError: `find_costs9` not defined in `Main`
Suggestion: check for spelling errors or missing imports.

julia> find_costs(A)
ERROR: MethodError: no method matching find_costs(::SparseArrays.SparseMatrixCSC{TropicalNumbers.TropicalMinPlusF64, Int64})
The function `find_costs` exists, but no method is defined for this combination of argument types.
```

Closest candidates are:
find_costs(::AbstractMatrix, ::AbstractVector)
@ NotDijkstra ~/src/jl/NotDijkstra/src/NotDijkstra.jl:34

Stacktrace:
[1] top-level scope
@ REPL[14]:1

```
julia> find_costs(A, x)
[0.0, Inf, Inf, Inf, Inf, Inf]
[0.0, Inf, 0.486, Inf, Inf, Inf]
[0.0, Inf, 0.486, 0.561, Inf, 0.531]
[0.0, 0.85, 0.486, 0.561, 1.021, 0.531]
6-element Vector{TropicalNumbers.TropicalMinPlusF64}:
 0.0s
 0.8497703769586702s
 0.4857170995024712s
 0.5606441136513303s
 1.0213700750345498s
 0.5310855138430699s
```

```
julia> █
```

```
module ChebyshevPSI2025
```

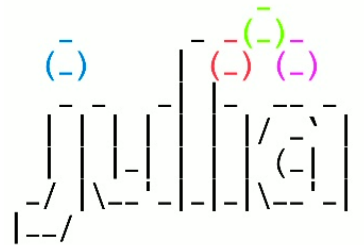
```
using CairoMakie
using FastGaussQuadrature
using SixelTerm
```

```
export cheb
cheb(i::Integer, x::Real) = cos(i * acos(x))
```

```
export plotchebs
function plotchebs(n::Integer)
    fig = Figure(; size=(640, 480))
    ax = Axis(fig[1, 1]; title="Chebyshev polynomials", xlabel="x", ylabel="T(x)")
    xs = 1.0 : 0.1 : -1.1
    ys = [cheb(i, x) for i in 0:n, x in xs]
    plot!(ax, xs, ys, :b, :c, :m, :y)
end
```

U:--- ChebyshevPSI2025.jl Top (7,11) (Julia v6 company)

wezterm x 2: julia x 3: cactus x 4: kotekan x 5: kotekan x 6: pgr x 7: yggdrasil x 8: wezterm x 9: UnicodeGraphics x 10: TUI x 11: Julia x 12: Julia x 13: Julia x +



Documentation: <https://docs.julialang.org>

Type "?" for help, "]"?" for Pkg help.

Version 1.11.2 (2024-12-01)
Official <https://julialang.org/> release

```
julia> using ChebyshevPSI2025
```

```
Precompiling ChebyshevPSI2025...
```

```
12 dependencies successfully precompiled in 81 seconds. 262 already precompiled.
```

```
█
```

```

julia>
Documentation: https://docs.julialang.org
Type "?" for help, "]??" for Pkg help.
Version 1.11.2 (2024-12-01)
Official https://julialang.org/ release

```

```

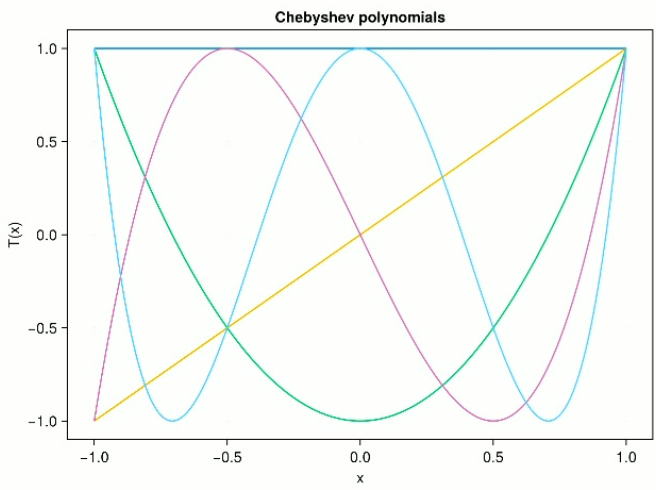
julia> using ChebyshevPSI2025
Precompiling ChebyshevPSI2025...
12 dependencies successfully precompiled in 81 seconds. 262 already precompiled.

```

```

julia> plotchebs(4)

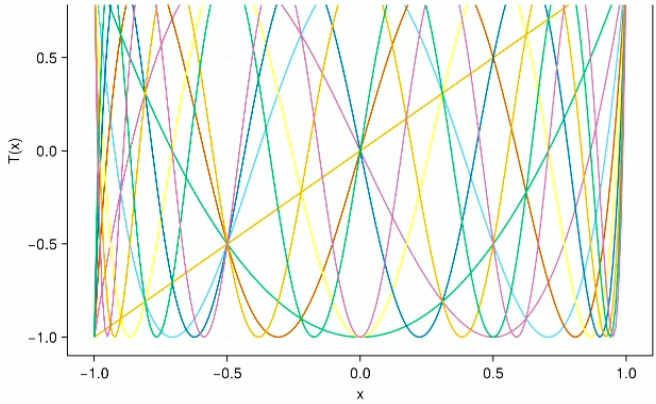
```



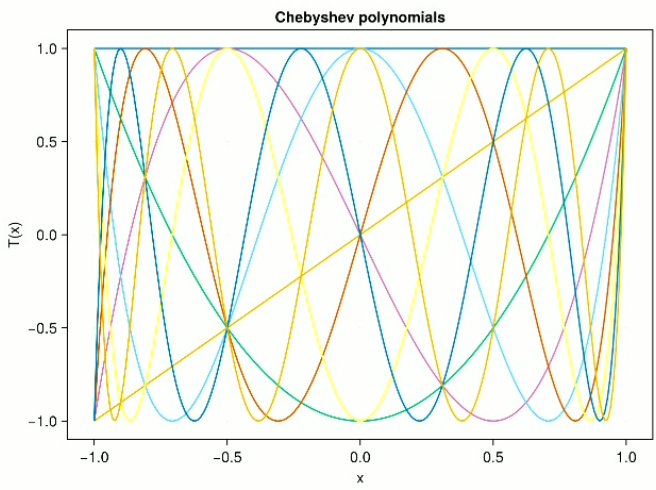
```

julia> █

```



julia> plotchebs(8)



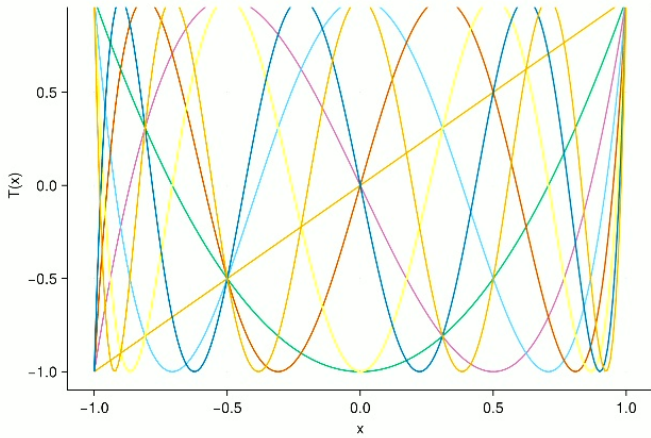
julia> █

```
module ChebyshevPSI2025

using CairoMakie
using FastGaussQuadrature
using SixelTerm

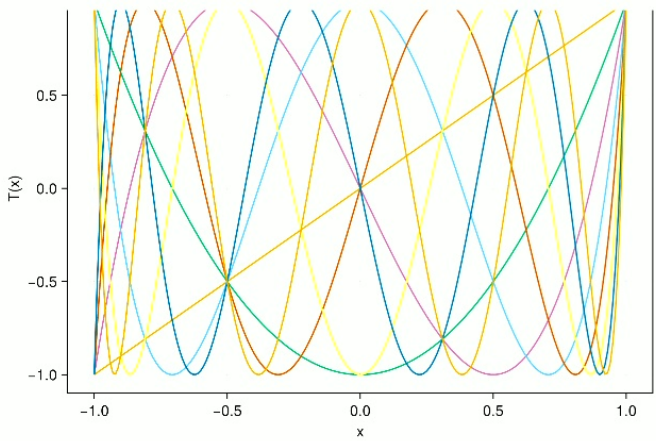
export cheb
cheb(i::Integer, x::Real) = cos(i * acos(x))

export plotchebs
function plotchebs(n::Integer)
    fig = Figure(; size=(640, 480))
    ax = Axis(fig[1, 1]; title="Chebyshev polynomials", xlabel="x", ylabel="T(x)")
```



julia> █

```
IntervalSets.jl<IntervalSets> - (307 x 45)  
  
for i in 0:n  
    lines!(xs, cheb.(i, xs))  
end  
return fig  
end  
  
# We promise we won't use more than that many Chebyshev coefficients  
const num_quadrature_points = 100  
const chebdot_points, chebdot_weights = gausschebyshevT(num_quadrature_points)  
const legdot_points, legdot_weights = gausslegendre(num_quadrature_points)  
  
export chebdot  
function chebdot(f, g)
```



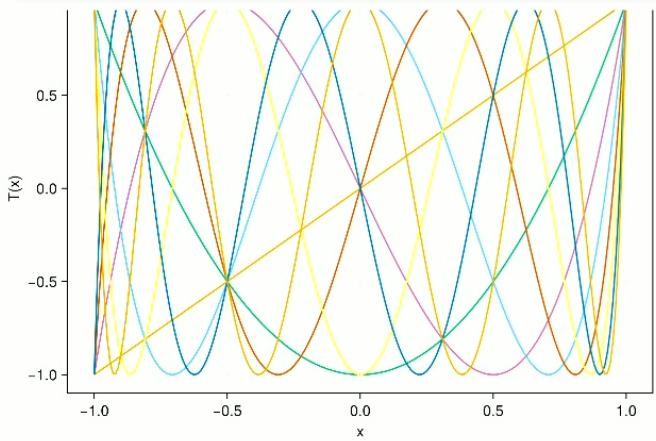
julia> █

```
export check_chebdot
function check_chebdot(n::Integer)
    chop(x) = abs(x) < 10*eps(typeof(x)) ? zero(x) : x
    for i in 0:n, j in 0:n
        val = chebdot(x -> cheb(i, x), x -> cheb(j, x))
        println("< T($i) | T($j) > = $(chop(val))")
    end
    return
end

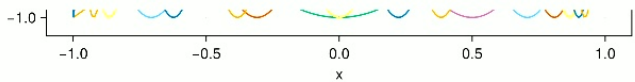
export chebproject
function chebproject(f, n::Integer)
```

U:--- ChebyshevP512025.jl 43% (48,47) (Julia +6 company)

wezterm x 2: Julia x 3: cactus x 4: kotekan x 5: kotekan x 6: pgr x 7: yggdrasil x 8: wezterm x 9: UnicodeGraphics x 10: TUI x 11: Julia x 12: Julia x 13: Julia x +



```
julia> check_chebdot(4)[]
```



```
julia> check_chebdot(4)
< T(0) | T(0) > = 3.1415926535897922
< T(0) | T(1) > = 0.0
< T(0) | T(2) > = 0.0
< T(0) | T(3) > = 0.0
< T(0) | T(4) > = 0.0
< T(1) | T(0) > = 0.0
< T(1) | T(1) > = 1.5707963267948966
< T(1) | T(2) > = 0.0
< T(1) | T(3) > = 0.0
< T(1) | T(4) > = 0.0
< T(2) | T(0) > = 0.0
< T(2) | T(1) > = 0.0
< T(2) | T(2) > = 1.5707963267948966
< T(2) | T(3) > = 0.0
< T(2) | T(4) > = 0.0
< T(3) | T(0) > = 0.0
< T(3) | T(1) > = 0.0
< T(3) | T(2) > = 0.0
< T(3) | T(3) > = 1.5707963267948961
< T(3) | T(4) > = 0.0
< T(4) | T(0) > = 0.0
< T(4) | T(1) > = 0.0
< T(4) | T(2) > = 0.0
< T(4) | T(3) > = 0.0
< T(4) | T(4) > = 1.5707963267948966
```

julia> █


```
return
end

export chebproject
function chebproject(f, n::Integer)
    cs = zeros(n+1)
    for i in 0:n
        cs[i+1] = chebdot(x -> cheb(i, x), f) / (i == 0 ? pi : pi/2)
    end
    return cs
end

export chebeval
chebeval(cs::AbstractVector{<Real>}, x::Real) = sum(cs[i+1] * cheb(i, x) for i in 0:length(cs)-1)
```

```
< T(2) | T(2) > = 1.5707963267948966
< T(2) | T(3) > = 0.0
< T(2) | T(4) > = 0.0
< T(3) | T(0) > = 0.0
< T(3) | T(1) > = 0.0
< T(3) | T(2) > = 0.0
< T(3) | T(3) > = 1.5707963267948961
< T(3) | T(4) > = 0.0
< T(4) | T(0) > = 0.0
< T(4) | T(1) > = 0.0
< T(4) | T(2) > = 0.0
< T(4) | T(3) > = 0.0
< T(4) | T(4) > = 1.5707963267948966
```

julia> █

```
return
end

export chebproject
function chebproject(f, n::Integer)
    cs = zeros(n+1)
    for i in 0:n
        cs[i+1] = chebdot(x -> cheb(i, x), f) / (i == 0 ? pi : pi/2)
    end
    return cs
end

export chebeval
```

```
< T(2) | T(2) > = 1.5707963267948966
< T(2) | T(3) > = 0.0
< T(2) | T(4) > = 0.0
< T(3) | T(0) > = 0.0
< T(3) | T(1) > = 0.0
< T(3) | T(2) > = 0.0
< T(3) | T(3) > = 1.5707963267948961
< T(3) | T(4) > = 0.0
< T(4) | T(0) > = 0.0
< T(4) | T(1) > = 0.0
< T(4) | T(2) > = 0.0
< T(4) | T(3) > = 0.0
< T(4) | T(4) > = 1.5707963267948966
```

```
julia> chebproject(sin, 4)
```

```
IntervalSets.jl<IntervalSets> -- (307 x 45)
cs[i+1] = chebdot(x -> cheb(i, x), f) / (i == 0 ? pi : pi/2)
end
return cs
end

export chebeval
chebeval(cs::AbstractVector, x::Real) = sum(cs[i+1] * cheb(i, x) for i in 0:length(cs)-1)

export check_chebproject
function check_chebproject(f, n::Integer)
    cs = chebproject(f, n)
    f'(x) = chebeval(cs, x)
end
```

```
3.754821498949985e-17
0.8801011714898671
7.951386703658792e-17
-0.03912670796533693
1.479841414292053e-16

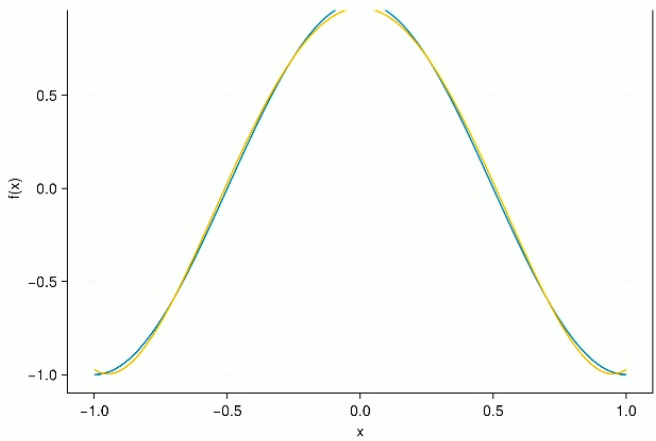
julia> chebproject(cos, 4)
5-element Vector{Float64}:
 0.7651976865579667
 4.417437057588218e-17
-0.22980696986380106
 5.0800526162264503e-17
 0.004953277928219779

julia> █
```

```
ax = Axis(fig[1, 1]; title="Chebyshev expansion (n=$n)", xlabel="x", ylabel="f(x)")
xs = -1:0.01:+1
lines!(xs, f.(xs))
lines!(xs, f'.(xs))
return fig
end

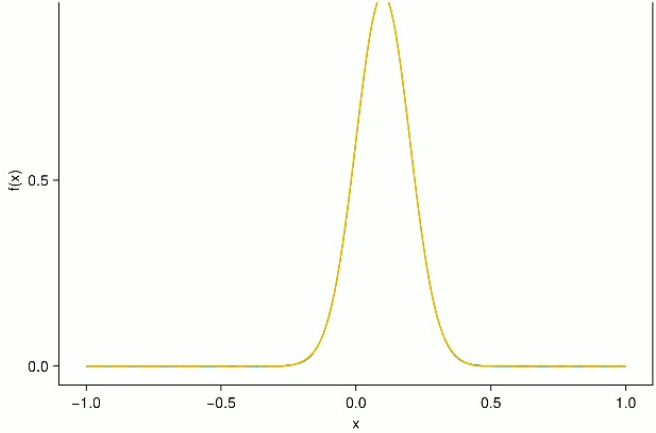
export gaussian
gaussian(x) = exp(-1/2 * ((x-0.1)/0.1)^2)

export check_convergence
function check_convergence(f, nmax::Integer)
    errors = zeros(nmax+1)
    for n in 0:nmax
        # ...
    end
end
```

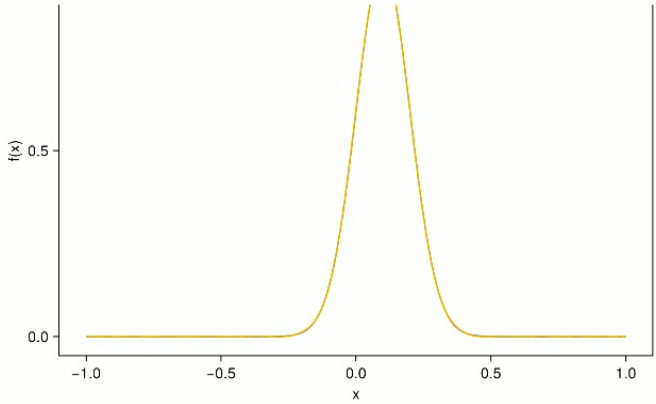


```
julia> check_chebproject(gaussian, 4)
```

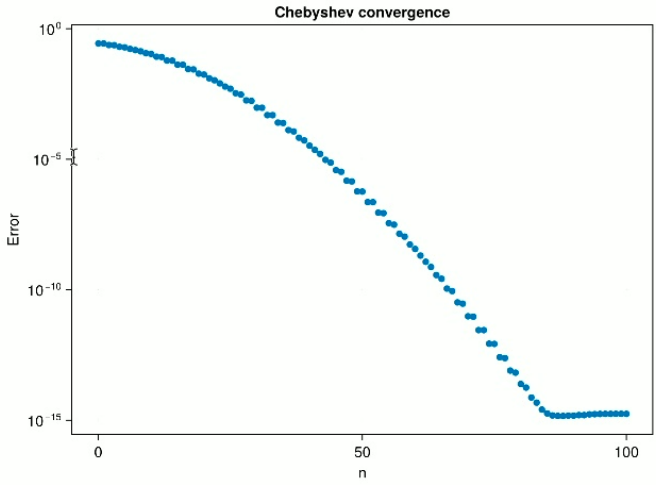
```
IntervalSets.jl<IntervalSets> - (307 x 45)  
  
ax = Axis(fig[1, 1]; title="Chebyshev expansion (n=$n)", xlabel="x", ylabel="f(x)")  
xs = -1:0.01:+1  
lines!(xs, f.(xs))  
lines!(xs, f'.(xs))  
return fig  
end  
  
export gaussian  
gaussian(x) = exp(-1/2 * ((x-0.1)/0.1)^2)  
  
export check_convergence  
function check_convergence(f, nmax::Integer)  
    errors = zeros(nmax+1)  
    for n in 0:nmax  
        errors[n] = norm(f - chebfit(xs, f, n))  
    end  
end
```



```
julia> check_convergence(gaussian, 1
```



```
julia> check_convergence(gaussian, 100)
```



```
julia> █
```

```
module ChebyshevPSI2025
```

```
using CairoMakie
using FastGaussQuadrature
using SixelTerm
```

```
export cheb
cheb(i::Integer, x::Real) = cos(i * acos(x))
```

```
export plotchebs
function plotchebs(n::Integer)
    fig = Figure(; size=(640, 480))
    ax = Axis(fig[1, 1]; title="Chebyshev polynomials", xlabel="x", ylabel="T(x)")
    xs = -1:0.01:+1
    for i in 0:n
        lines!(xs, cheb.(i, xs))
    end
    return fig
end
```

```
# We promise we won't use more than that many Chebyshev coefficients
const num_quadrature_points = 100
const chebdot_points, chebdot_weights = gausschebyshevt(num_quadrature_points)
const legdot_points, legdot_weights = gausslegendre(num_quadrature_points)
```

```
export chebdot
function chebdot(f, g)
    integral = sum(chebdot_weights .* f.(chebdot_points) .* g.(chebdot_points))
    return integral
end
```

```
IntervalSets.jl Top (28,0) (Julia +6 company)
Beginning of buffer
```

```
const num_quadrature_points = 100
const chebdot_points, chebdot_weights = gausschebyshevt(num_quadrature_points)
const legdot_points, legdot_weights = gausslegendre(num_quadrature_points)

export chebdot
function chebdot(f, g)
    integral = sum(chebdot_weights .* f.(chebdot_points) .* g.(chebdot_points))
    return integral
end

export chebnorm
chebnorm(f) = sqrt(chebdot(f, f) / pi)

export legdot
function legdot(f, g)
    integral = sum(legdot_weights .* f.(legdot_points) .* g.(legdot_points))
    return integral
end

export legnorm
legnorm(f) = sqrt(legdot(f, f) / 2)

export check_chebdot
function check_chebdot(n::Integer)
    chop(x) = abs(x) < 10*eps(typeof(x)) ? zero(x) : x
    for i in 0:n, j in 0:n
        val = chebdot(x -> cheb(i, x), x -> cheb(j, x))
        println("< T($i) | T($j) > = $(chop(val))")
    end
end
```



```
function chebproject(f, n::Integer)
    cs = zeros(n+1)
    for i in 0:n
        cs[i+1] = chebdot(x -> cheb(i, x), f) / (i == 0 ? pi : pi/2)
    end
    return cs
end

export chebeval
chebeval(cs::AbstractVector, x::Real) = sum(cs[i+1] * cheb(i, x) for i in 0:length(cs)-1)

export check_chebproject
function check_chebproject(f, n::Integer)
    cs = chebproject(f, n)
    f'(x) = chebeval(cs, x)

    fig = Figure(; size=(640, 480))
    ax = Axis(fig[1, 1]; title="Chebyshev expansion (n=$n)", xlabel="x", ylabel="f(x)")
    xs = -1:0.01:+1
    lines!(xs, f.(xs))
    lines!(xs, f'.(xs))
    return fig
end

export gaussian
gaussian(x) = exp(-1/2 * ((x-0.1)/0.1)^2)

export check_convergence
function check_convergence(f, nmax::Integer)
```

Semi-Ring:

\oplus - assoc
comm

N

$$N \oplus x = x$$

\odot - assoc

I

$$I \odot x = x$$

cancel

$$N \odot x = N$$

distib.

Semi-Ring

$$\oplus \quad \begin{array}{l} \text{assoc} \\ \text{comm} \end{array}$$

$$N \quad N \oplus x = x$$

$$\odot \quad \begin{array}{l} \text{assoc} \\ \text{I} \end{array}$$

$$I \quad I \odot x = x$$

$$N \odot x = N$$

distrib

Tropical Numbers

min - plus

$$\mathbb{R}_{\geq 0} \cup \{\infty\}$$

$$\oplus \quad \begin{array}{l} \text{min} \\ N = \infty \end{array}$$

$$\odot \quad \begin{array}{l} + \\ I = 0 \end{array}$$

$[-1, +1]$ Chebyshev $T_i(x)$

$$\langle f | g \rangle = \int_{-1}^{+1} f(x) g(x) \frac{1}{\sqrt{1-x^2}} dx$$

$$f(x) = \sum_{i=0}^n c^i T_i(x)$$

$i=1$] Chebyshev $T_i(x)$

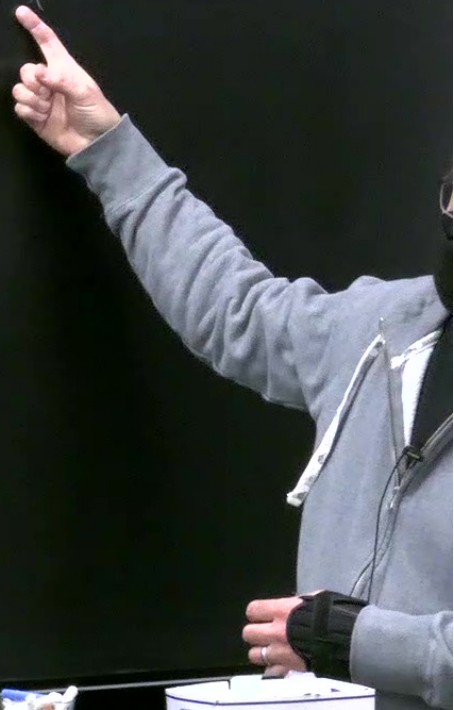
$$f(x) = \sum_{i=0}^n c^i T_i(x)$$

$$\int_{-1}^1 f(x) \frac{1}{\sqrt{1-x^2}} dx = \sum_{i=0}^n c^i \int_{-1}^1 T_i(x) T_i(x) \frac{1}{\sqrt{1-x^2}} dx$$

$= \delta_{ij} \pi \begin{cases} 1 & \text{if } i=0 \\ 1/2 & \text{otherwise} \end{cases}$

$$\langle f | g \rangle = \int_{-1}^1 f(x) g(x) \frac{1}{\sqrt{1-x^2}} dx$$

$$\frac{1}{h_j} \langle T_j | f \rangle = c^j$$



$$x = x$$

$$\textcircled{1} x = x$$

$$\textcircled{2} x = N$$

$$f(x) = \sin(x)$$

$$f = x \rightarrow \sin(x)$$

$$(x, y) \rightarrow \sin(x) + \cos(y)$$