

**Title:** Lecture - Relativity, PHYS 604

**Speakers:** Ghazal Geshnizjani

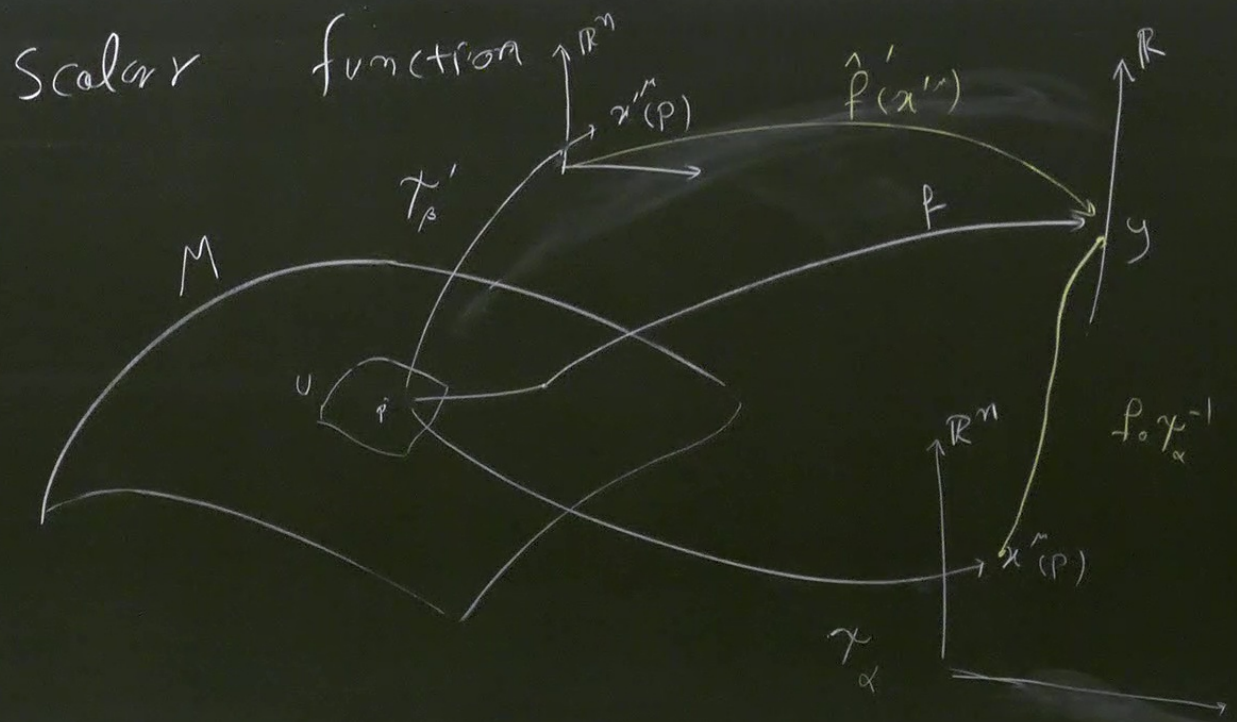
**Collection/Series:** Relativity (Core), PHYS 604, November 12 - December 11, 2024

**Subject:** Cosmology, Strong Gravity

**Date:** November 18, 2024 - 10:45 AM

**URL:** <https://pirsa.org/24110026>

**Abstract:**



$$f: M \rightarrow \mathbb{R}$$

$$f(p) = y$$

$$f(\xi_\alpha^{-1}(x^\alpha)) = f \circ \xi_\alpha^{-1}(x^\alpha)$$

$$f \circ \xi_\alpha^{-1}: \mathbb{R}^n \rightarrow \mathbb{R}$$

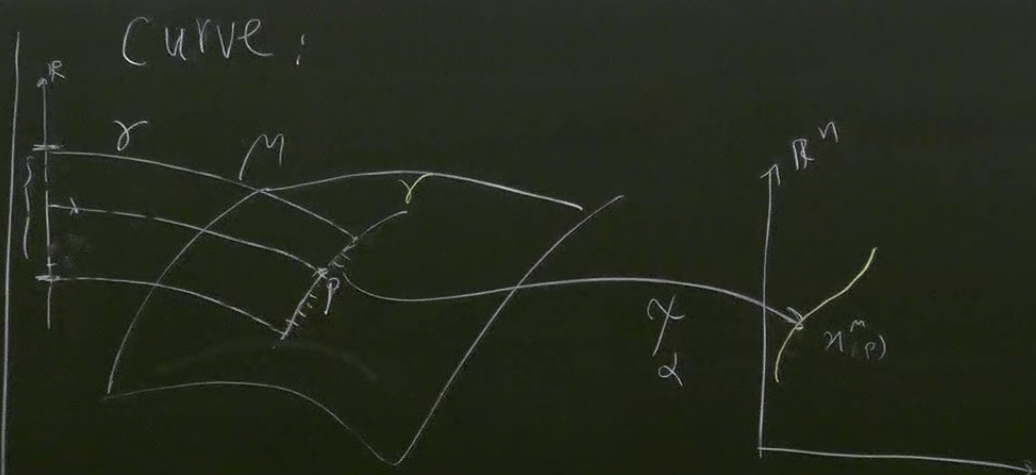
$$\hat{f}(x^\alpha) = y = \hat{f}'(x^\alpha)$$

$$\xi_\alpha(p) = (x^0, x^1, \dots)$$

$$= f \circ \gamma^{-1}(x^m)$$

$$\mathbb{R}^m \rightarrow \mathbb{R}$$

$$f(x) = y = \hat{f}'(x^m)$$



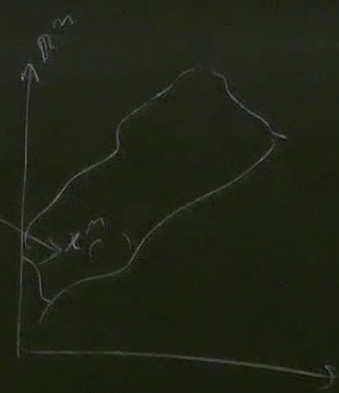
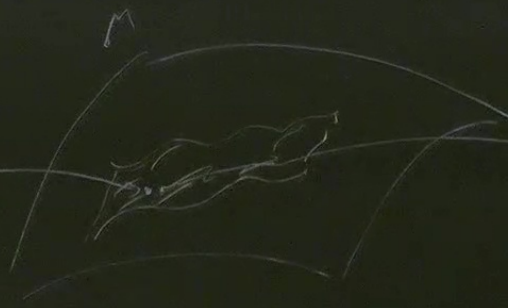
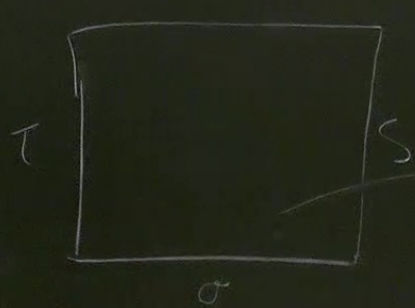
$(x^{(+)}, x^{(+)}, \dots)$

$$\gamma: I \rightarrow M \quad \gamma(\lambda) = p \quad x^m = \gamma_\alpha(\gamma(\lambda)) = \gamma_\alpha \circ \gamma(\lambda) \quad \gamma_\alpha \circ \gamma: I \rightarrow \mathbb{R}^m$$

$$I \subset \mathbb{R}$$

$$\gamma_\alpha(\lambda)$$





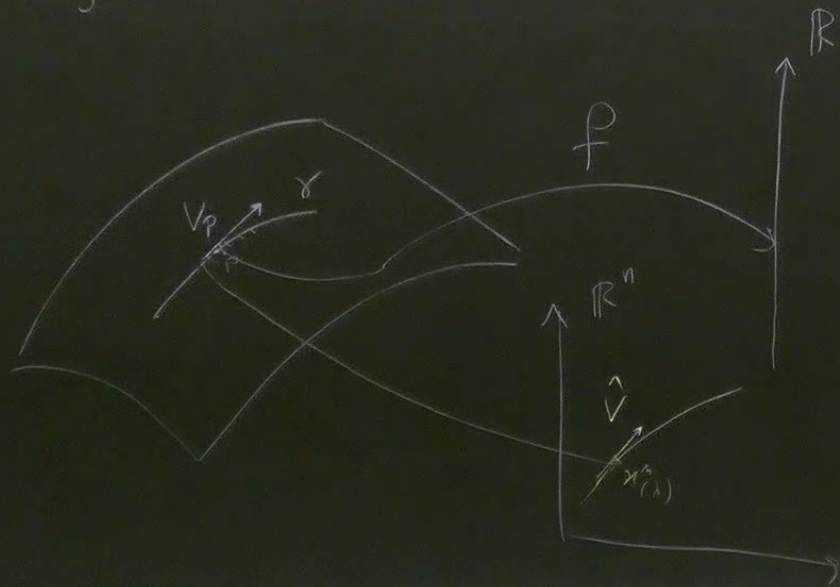
$$S: U \subset \mathbb{R}^2 \rightarrow M$$

$$x^M(\tau, \sigma) = \gamma_\alpha \circ S(\tau, \sigma)$$



Tensors

Tangent vector  $\rightarrow$  directed derivative at a point

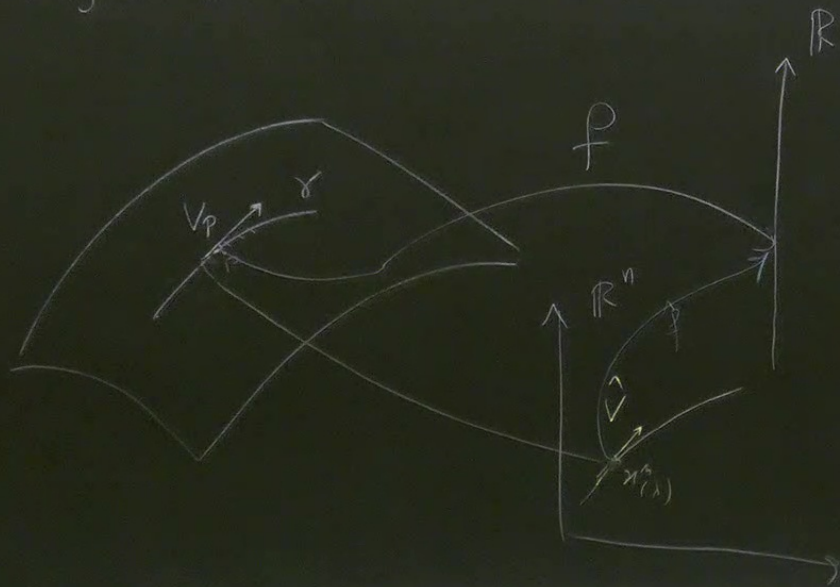


$$f: M \rightarrow \mathbb{R}$$
$$v_P^{(M)} = \frac{df}{d\lambda} \in \mathbb{R}$$



# Tensors

Tangent vector  $\rightarrow$  directed derivative at a point



$$f: M \rightarrow \mathbb{R}$$

$$V_p^{(M)}(f) = \frac{df}{d\lambda} \in \mathbb{R}$$

$$\left. \frac{d\hat{f}(x^i)}{d\lambda} \right|_p = \frac{dx^i}{d\lambda} \cdot \left. \frac{\partial \hat{f}}{\partial x^i}(x^i) \right|_p$$

$$V_P^{(n)}(f) = \frac{dx^n}{dt} \Big|_P \hat{f} \quad \text{for } \gamma$$

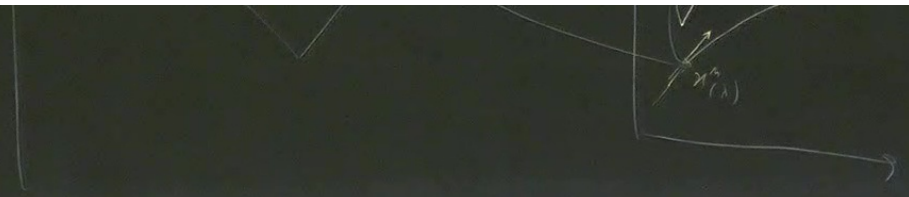
$$V_P^{(n)}: f \rightarrow \mathbb{R}$$

$$\check{D}(af+bg) = a\check{D}(f) + b\check{D}(g)$$

$$\check{D}(fg) = f\check{D}(g) + g\check{D}(f)$$

Def. let  $\mathcal{F}$  be a collection of  $C^\infty$  scalar functions, A tangent Vector





$$V_x(f) = \left. \frac{d(f \circ x)}{dt} \right|_P = \frac{dx^i}{dt} \partial_i f \Big|_P = \dot{x}^i \partial_i f$$

$$D(a f + b g) = a \tilde{D}(f) + b \tilde{D}(g)$$

$$\tilde{D}(f g) = f \tilde{D}(g) + g \tilde{D}(f)$$

der functions. A tangent vector  $V$  at point  $P \in M$  is a map  $V: \tilde{f} \rightarrow \mathbb{R}$



$$V_P^{(x)}(f) = \frac{dx^m}{dt} \Big|_P \hat{f} \Big|_P$$

$$V_P^{(x)}: f \rightarrow \mathbb{R}$$

$$\tilde{D}(af+bg) = a\tilde{D}(f) + b\tilde{D}(g)$$

$$\tilde{D}(fg) = f\tilde{D}(g) + g\tilde{D}(f)$$

Def. let  $\mathcal{F}$  be a collection of  $C^\infty$  scalar functions. A tangent vector such that  $V$  is linear and obeys Leibniz rule.

Theorem / Definition

The set of all tangent vectors at  $P$  forms a

Tangent Vector Space  $T_P M$

Same dimension  $n$ ,  $\left\{ \hat{e}_\mu = \frac{\partial}{\partial x^\mu} \right\}$  basis

$x^\mu$

$$V = V^\mu \hat{e}_\mu = V^\mu \frac{\partial}{\partial x^\mu}$$

$$V(f) = V^\mu \frac{\partial f(x^\alpha)}{\partial x^\mu} = V^\mu \frac{\partial x^\alpha}{\partial x^\mu} \frac{\partial f(x^\alpha)}{\partial x^\alpha} = \left( V^\mu \frac{\partial x^\alpha}{\partial x^\mu} \right) \frac{\partial f}{\partial x^\alpha}$$

$$V^\mu \frac{\partial x^\alpha}{\partial x^\mu}$$

$$V = V^\mu \frac{\partial}{\partial x^\mu} = V^\mu \frac{\partial x^\alpha}{\partial x^\mu} \frac{\partial}{\partial x^\alpha}$$



Vectors at  $P$  forms a

$T_P M$

Same dimension  $n$ ,  $\left\{ \hat{e}_\alpha = \frac{\partial}{\partial x^\alpha} \right\}$  basis

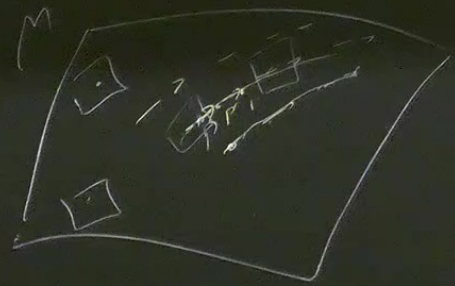
$$V^{\alpha, \mu} = V^\alpha(x) \frac{\partial x^{\mu, \nu}}{\partial x^\alpha}$$

$$\frac{\partial f(x)}{\partial x^\alpha} = V^\alpha(x) \frac{\partial x^{\mu, \nu}}{\partial x^\alpha} \frac{\partial f}{\partial x^{\mu, \nu}}$$

$$V = V^\alpha(x) \frac{\partial}{\partial x^\alpha} = V^\alpha(x) \frac{\partial x^{\mu, \nu}}{\partial x^\alpha} \frac{\partial}{\partial x^{\mu, \nu}}$$



$$e_M(f) = \int_M f$$



$$\mathcal{U} = \left\{ \mathcal{U}_p \in T_p M \text{ for all } p \in M, V(f) \text{ is smooth} \right\}$$

$$\mathcal{U}(f) = M \longrightarrow \mathbb{R}$$

$$\mathcal{U}(f)(p) = V_p(f)$$

Tangent bundle:  $TM = \bigcup_p T_p M \quad \forall p \in M$

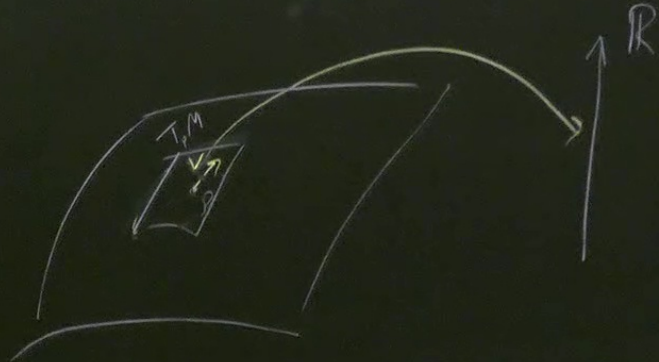


Cotangent vector (1-form)  $\omega$  at  $P \in M$  is linear Map  $\omega: T_P M$

$$\langle \omega | u \rangle = \alpha$$

$$\omega(v) \in \mathbb{R}$$

$$\begin{matrix} \vec{u} & \vec{v} & = & \alpha \\ \in \mathbb{R}^m & \in \mathbb{R}^n \end{matrix}$$



$$\omega(v_1 + v_2) = \omega(v_1) + \omega(v_2)$$

$\omega \in T_P^* M$  cotangent vector space



basis  $T_p M$ :  $\hat{e}_\nu = \frac{\partial}{\partial x^\nu}$  or  $\partial_\nu$

$$T_p^* M: \underbrace{\hat{e}^\mu (\hat{e}_\nu)}_{\text{basis}} = \delta^\mu_\nu$$

coordinate basis  $dx^\mu$

$$dx^\mu \left( \frac{\partial}{\partial x^\nu} \right) = \delta^\mu_\nu$$

$$\frac{\partial x^\mu}{\partial x^\nu} = \delta^\mu_\nu$$

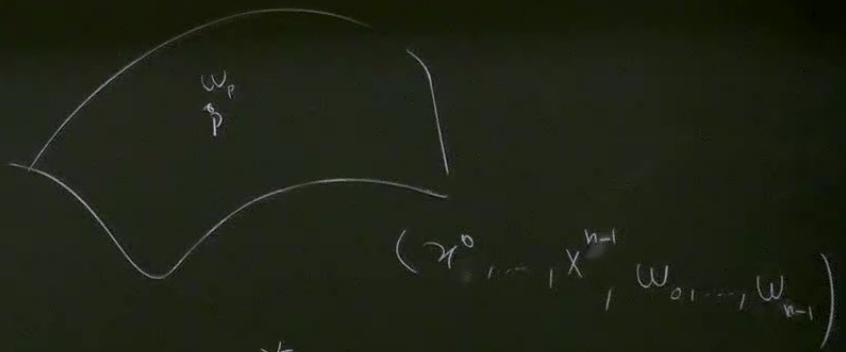
$$df(V) \equiv V(f)$$



$$V(f) = \left. \frac{df(x)}{dx} \right|_p = \frac{dx^m}{dx^\alpha} \left. \frac{\partial f(x^m)}{\partial x^m} \right|_p = \nabla_\alpha f^m$$

$$W = w_m dx^m = \left( w_m \frac{\partial x^m}{\partial x'^\alpha} \right) dx'^\alpha = w'_\alpha dx'^\alpha$$

$$w'_\alpha = w_m \frac{\partial x^m}{\partial x'^\alpha}$$



Cotangent bundle =  $T^*M = \cup T_p^*M$

Tensor: A tensor of type  $(k, l)$  of Rank  $k+l$  is a multi linear Map

$$T: T_p^* \times \dots \times T_p^* \times T_p \times \dots \times T_p \rightarrow \mathbb{R}$$

(2,1)

$\underbrace{\hspace{2cm}}_k$

$\underbrace{\hspace{2cm}}_l$

$$T(w, z, V) \in \mathbb{R}$$

$$d_x^m \quad d_x^r$$

$$T = T^{m,r} \quad d_x^m \otimes d_x^r$$

$$T(a w_1 + b w_2, c z, V_1 + V_2) = a T(w_1, c z, V_1 + V_2) + b T(w_2, c z, V_1 + V_2)$$



is a multi linear Map

$$\delta_m \otimes \delta_r \otimes dx^\alpha$$

$$T(w, z, V) = \left( T_{\alpha}^{\mu\nu} \delta_m \otimes \delta_r \otimes dx^\alpha \right) \left( w_\gamma dx^\gamma z_\sigma dx^\sigma V^\beta \right)$$

$$= T_{\beta}^{\gamma\sigma} w_\gamma z_\sigma V^\beta$$



Tensor: A tensor of type  $(k, l)$  of Rank  $k+l$  is a multi linear Map

$$T: \underbrace{T_p^* \times \dots \times T_p^*}_k \times \underbrace{T_p \times \dots \times T_p}_l \rightarrow \mathbb{R}$$

$(2, 1)$

$$T(w, z, v) \in \mathbb{R}$$

$$\partial_m dx^r$$

$$T = T^{rv} \partial_m \otimes \partial_r \otimes dx^s$$

$$\frac{\partial x^i}{\partial x^r} \frac{\partial x^j}{\partial x^s}$$

$$T(a w_1 + b w_2, c z, v_1 + v_2) = a T(w_1, c z, v_1 + v_2) + b T(w_2, c z, v_1 + v_2)$$