

Title: Cyclic causal modelling with a graph separation property in classical and quantum theories

Speakers: Carla Ferradini

Series: Quantum Foundations, Quantum Information

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# **Cyclic causal modelling with a graph separation property in classical and quantum theories**

(on arXiv soon)

Carla Ferradini



Victor Gitton

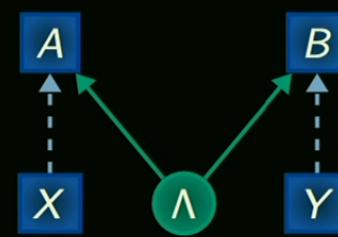
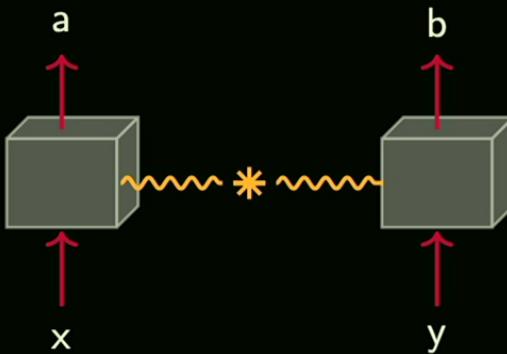


V. Vilasini

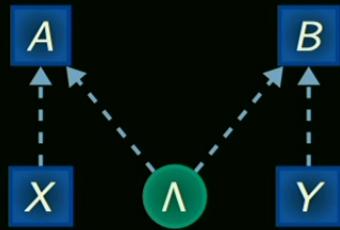
**ETH** zürich

Causalworlds 2024 — September 18, 2024

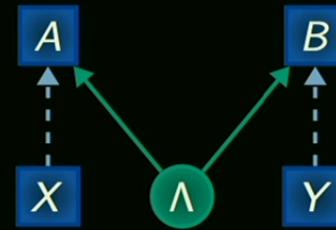
# Cyclic causal modelling with a graph separation property in classical and quantum theories



# Cyclic causal modelling with a graph separation property in **classical** and **quantum** theories



Hidden variable model

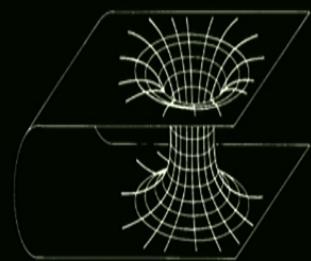


Quantum scenario

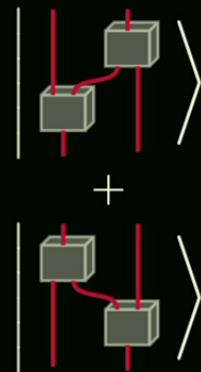
(Robert Spekkens tutorial)

# Cyclic causal modelling with a graph separation property in classical and quantum theories

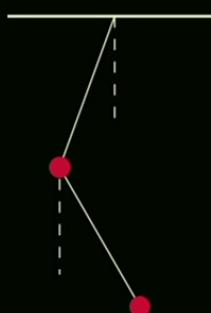
CTCs  
Solutions of GR



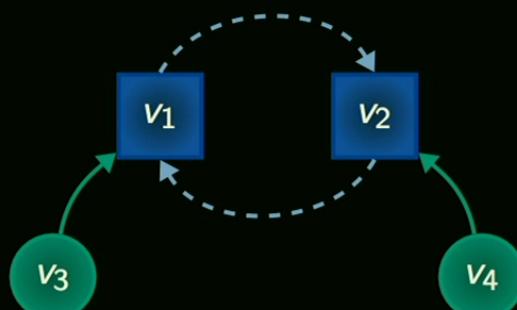
Indefinite causality  
(Cyril Branciard tutorial)



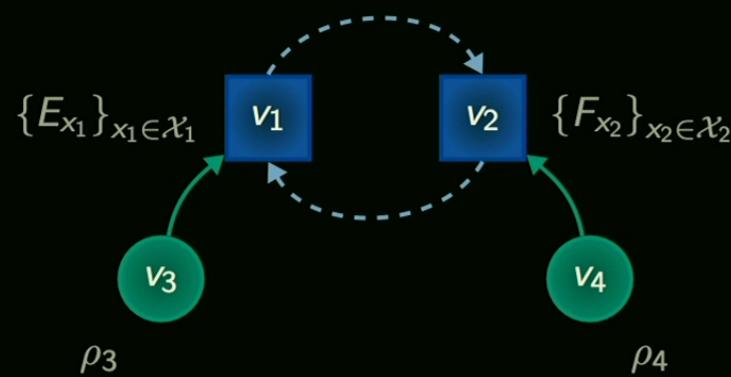
Feedback processes  
(Joris M. Mooij talk)



## Evaluating probabilities



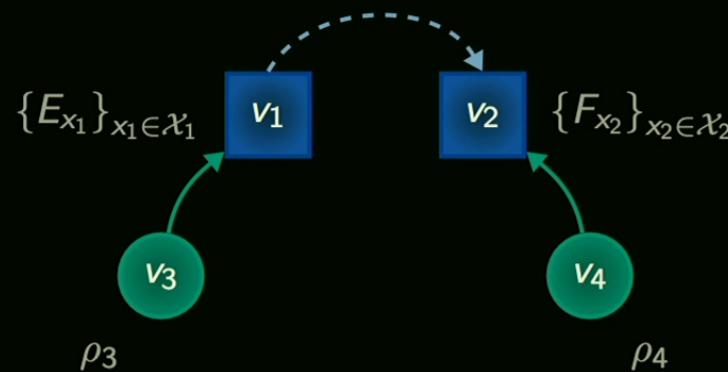
## Evaluating probabilities



$$P(x_1, x_2)?$$

## Evaluating probabilities

For any causal model on **acyclic**  $G$

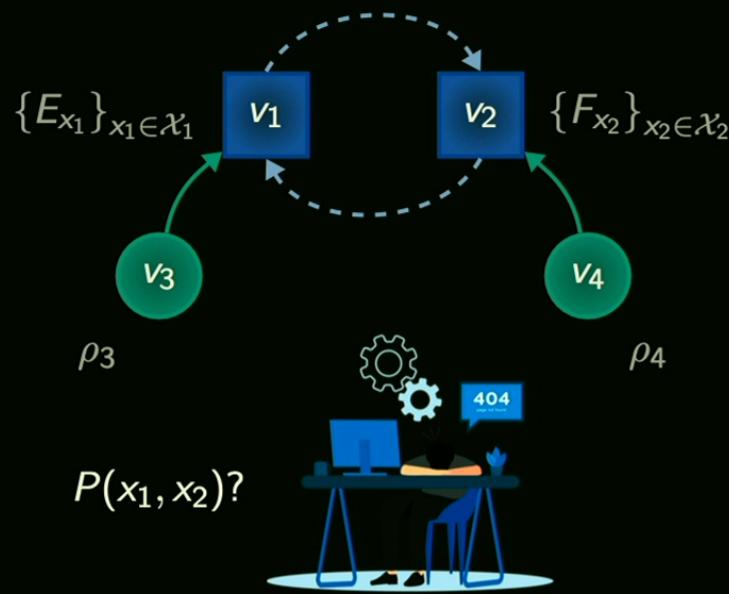


$$P(x_1, x_2) = \text{Tr} [(\mathcal{E}_{x_1} \otimes \mathcal{F}_{x_2})(\rho_3 \otimes |x_1\rangle\langle x_1| \otimes \rho_4)]$$

[Henson et al. *New J. Phys.* 16 113043 (2014)]  
[Barrett et al. arXiv:1906.10726 (2019)]

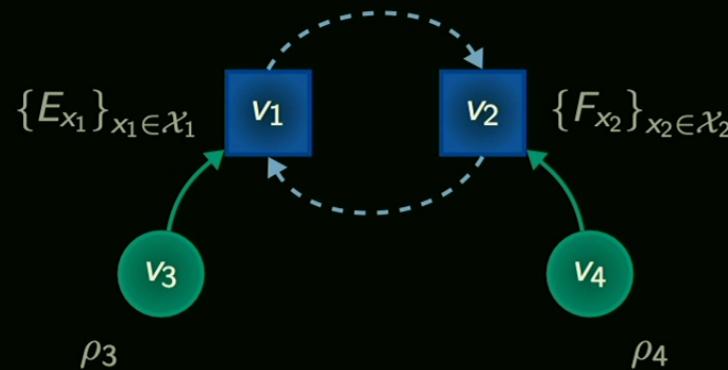
## Evaluating probabilities

For any causal model on **arbitrary**  $G$



## Evaluating probabilities

For a **subset** of cyclic causal models on  $G$



$$P(x_1, x_2)$$

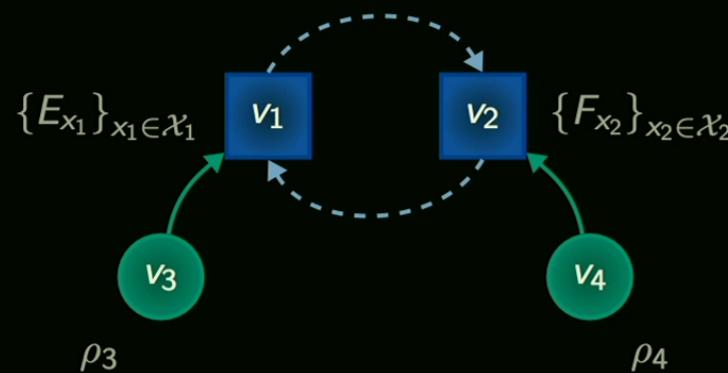
[Forré et al. arXiv:1710.08775 (2017)]

[Bongers et al. *Ann. Statist.* 49(5): 2885-2915 (2021)]

[Barrett et al. *Nat. Commun.* 12, 885 (2021)]

## Evaluating probabilities

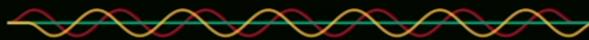
For any causal model\* on arbitrary  $G$



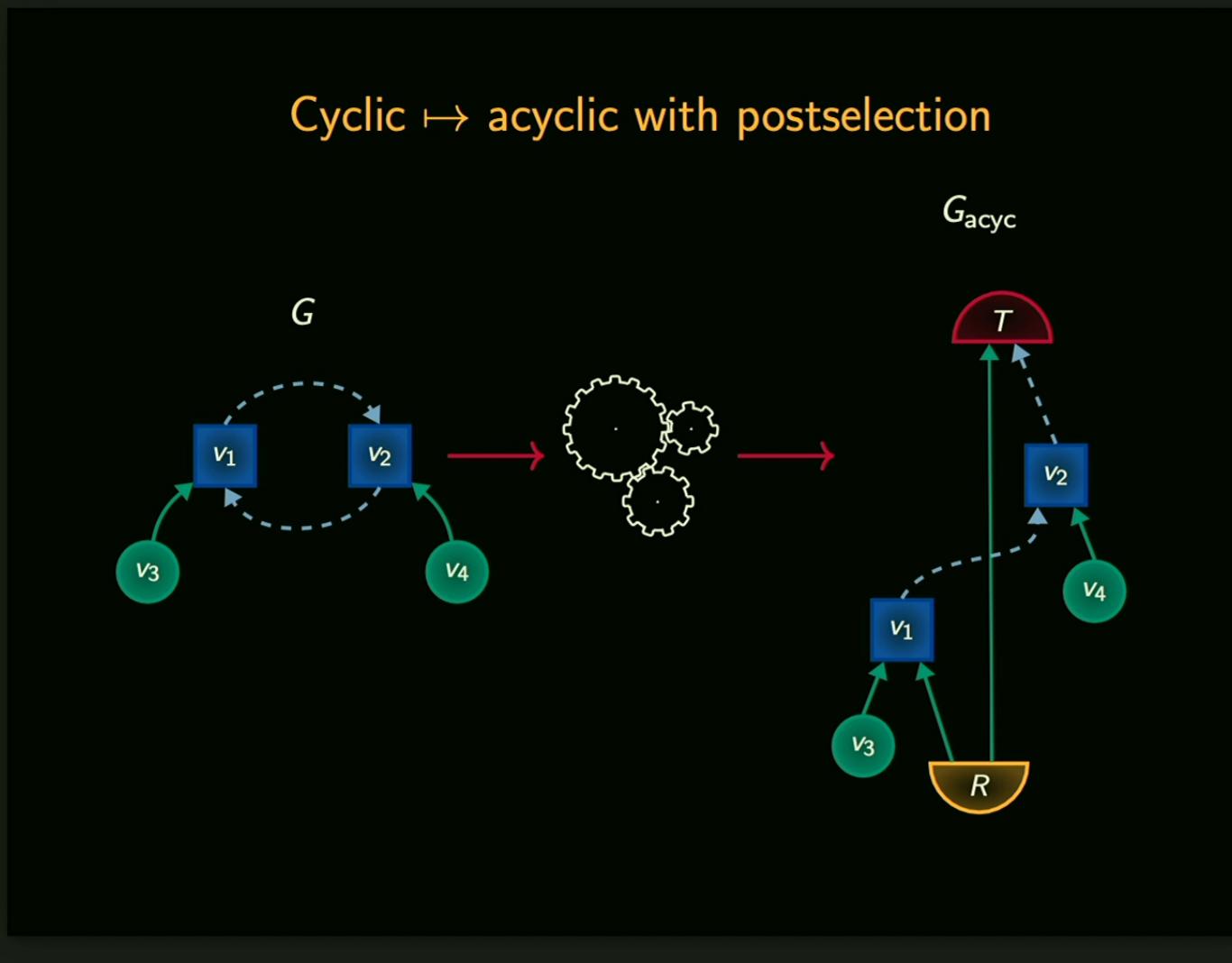
$$P(x_1, x_2)$$

\*with finite dimensional  $\mathcal{H}$  and discrete random variables

## **Breaking the cycles**



## Cyclic $\mapsto$ acyclic with postselection

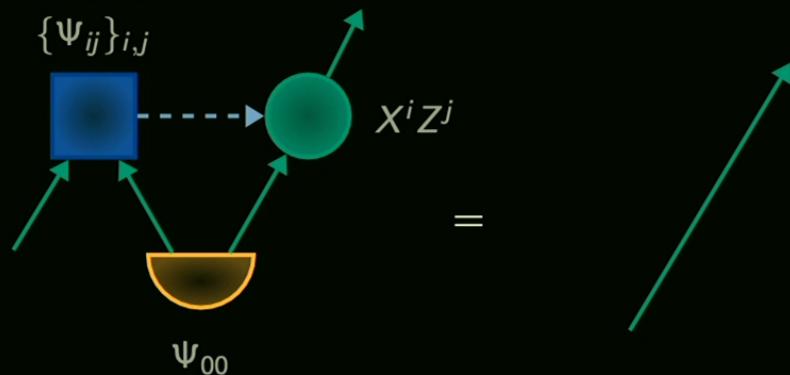


## Ingredient

Goal: simulate an identity channel

Bell meas.

$$\{\Psi_{ij}\}_{i,j}$$

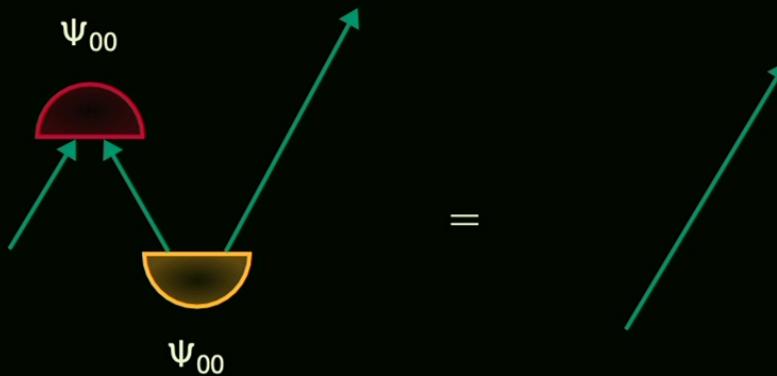


Teleportation protocol

## Ingredient

Goal: simulate an identity channel

Postselected teleportation protocol ✓

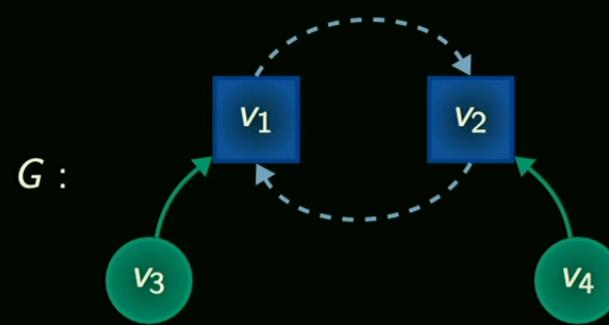


$$\text{Tr}_{AB}[|\Psi_{00}\rangle\langle\Psi_{00}|_{AB}\rho_A|\Psi_{00}\rangle\langle\Psi_{00}|_{BC}] = p\sqrt{\rho_C}$$

[Lloyd et al. *Phys. Rev. Lett.* 106, 040403 (2011)]  
[Lloyd et al. *Phys. Rev. D* 84, 025007 (2011)]

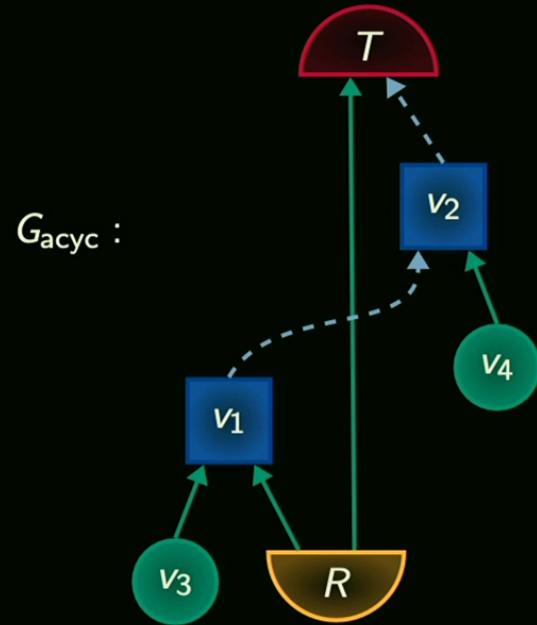
## Recipe

Given a causal model on  $G = (V, E)$



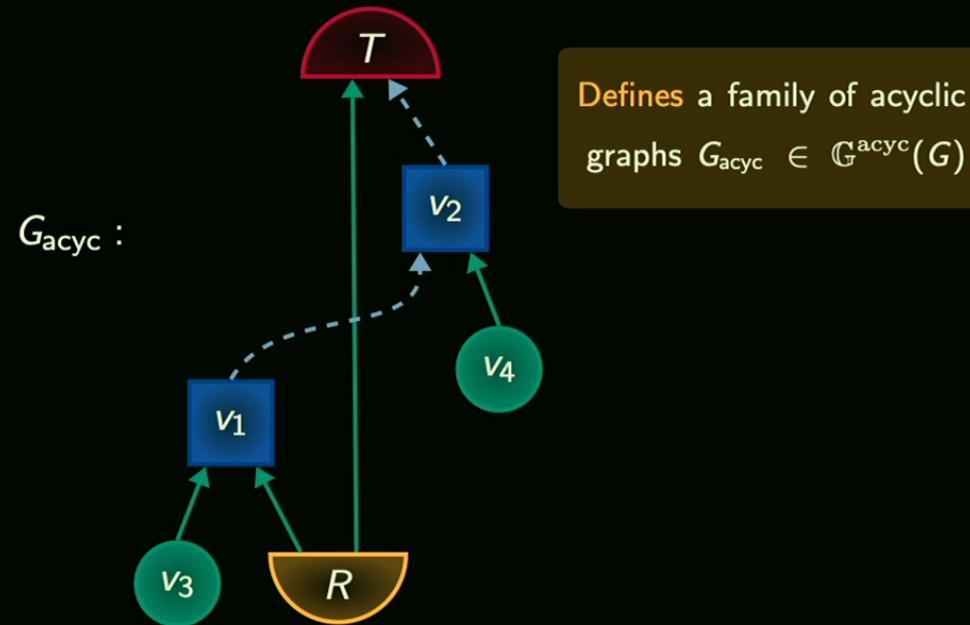
## Recipe

Step 2: add postselected teleportations to missing edges



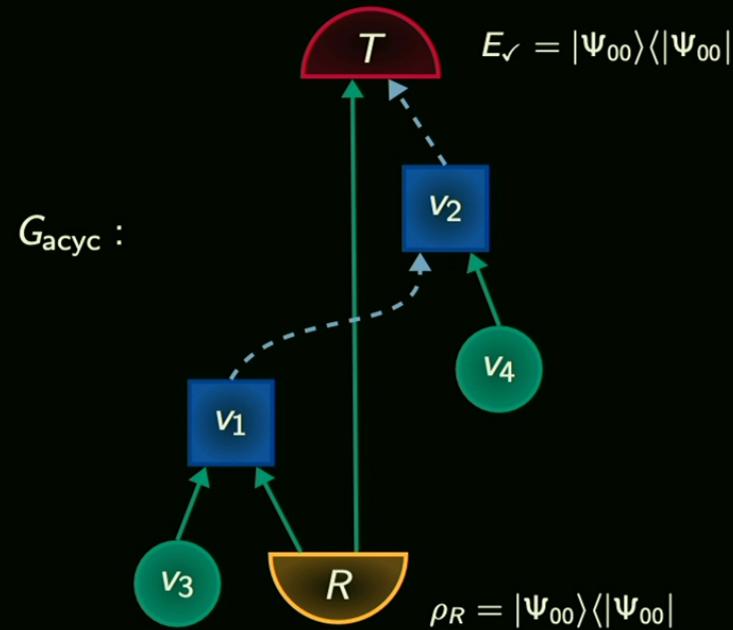
## Recipe

Step 2: add postselected teleportations to missing edges



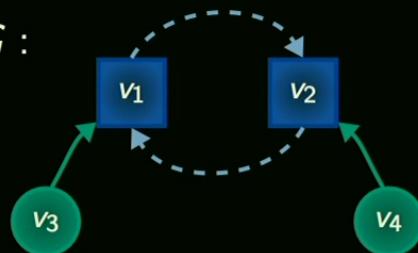
## Recipe

**Step 3:** define a cm with postselected teleportation protocols  
on the added nodes of  $G_{\text{acyc}}$

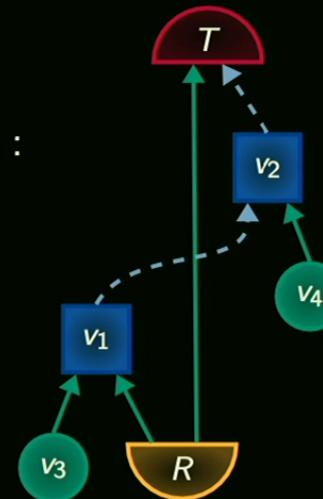


## Recipe

$G :$



$G_{\text{acyc}} :$

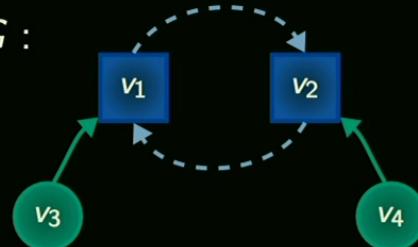


$$\Pr_G(x_1, x_2)$$

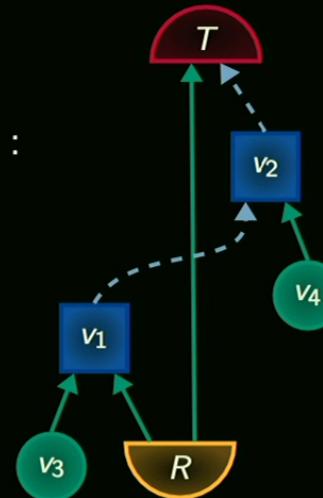
$$\Pr_{G_{\text{acyc}}}(x_1, x_2 | t = \checkmark)$$

## Recipe

$G :$



$G_{\text{acyc}} :$

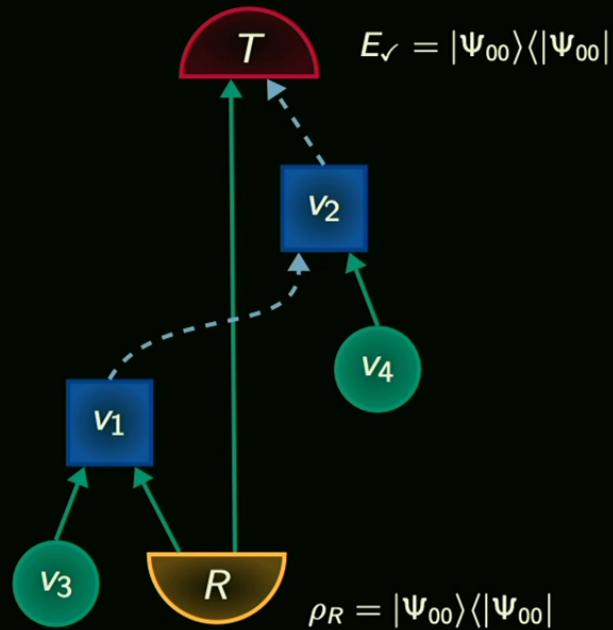


Define  $\Pr_G(x_1, x_2) := \Pr_{G_{\text{acyc}}}(x_1, x_2 | t = \checkmark)$

**Thm:** the probability rule is independent on the choice of  $G_{\text{acyc}} \in \mathbb{G}^{\text{acyc}}(G)$

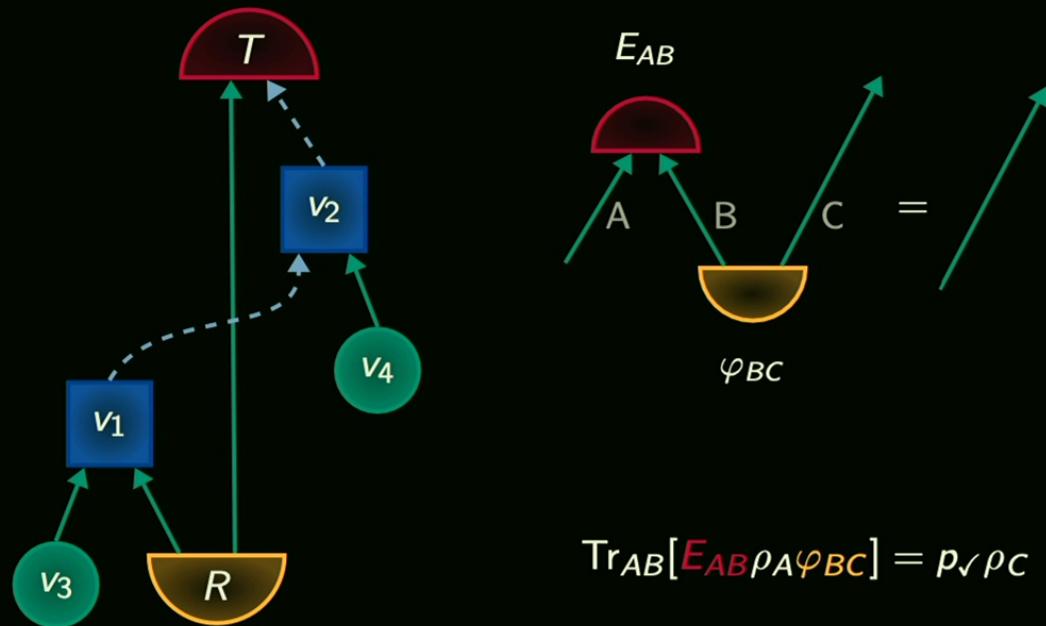
## Fine tuning?

**Step 3:** define a cm with postselected teleportation protocols on the added nodes of  $G_{\text{acyc}}$



## Fine tuning?

**Step 3:** define a cm with any postselected teleportation protocols on the added nodes of  $G_{\text{acyc}}$



## Graph separation property: $p$ -separation



## Graph separation property: $d$ -separation

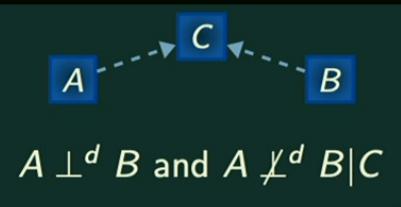
Given a directed graph  $G$  and a compatible probability  $\Pr$

Graph structure

$\downarrow$   
 $d$ -separation in  $G$   
 $\perp^d$

Causal mechanisms

$\downarrow$   
 $independencies$  in  $\Pr$   
 $\perp\!\!\!\perp$



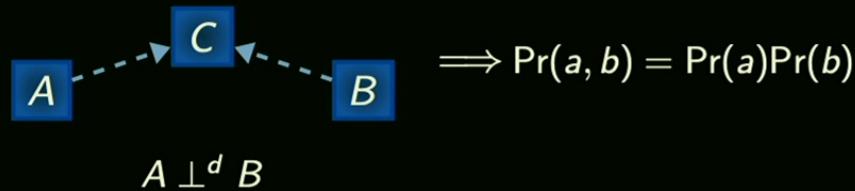
$A \perp\!\!\!\perp B|C$  if  
 $\Pr(a, b|c) = \Pr(a|c)\Pr(b|c)$

[Pearl. Cambridge University Press (2009)]

## *d*-separation theorem

$G$  is acyclic

**Soundness:** If  $A \perp^d B|C$  in  $G$ , then for all causal models  
 $A \perp\!\!\!\perp B|C$  in  $\Pr$

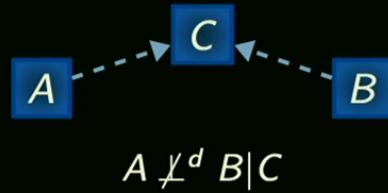


[Pearl. *Cambridge University Press* (2009)]

## *d*-separation theorem

$G$  is acyclic

**Completeness:** If  $A \not\perp\!\!\! \perp B|C$  in  $G$ , then there exists a causal model where  $A \not\perp\!\!\! \perp B|C$  in  $\text{Pr}$



$$A \not\perp\!\!\! \perp B|C$$

[Pearl. *Cambridge University Press* (2009)]

## *d*-separation theorem

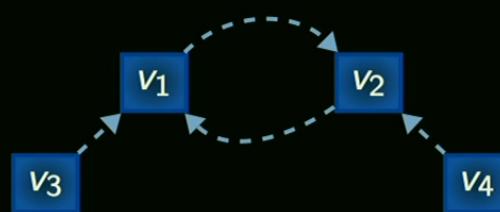
$G$  is acyclic

**Completeness:** If  $A \not\perp\!\!\! \perp B|C$  in  $G$ , then there exists a causal model where  $A \not\perp\!\!\! \perp B|C$  in  $\Pr$



[Pearl. *Cambridge University Press* (2009)]

## Failure of $d$ -separation in cyclic graphs



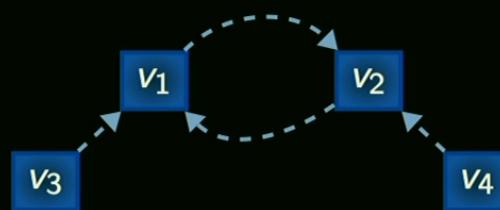
$$v_3 \perp^d v_4 \stackrel{\text{d-sep.}}{\implies} x_3 \perp\!\!\!\perp x_4 \text{ for all causal models}$$

Causal model:

$$\begin{aligned} x_1 &= x_3 \oplus x_2 \quad \implies \quad x_3 = x_4 \\ x_2 &= x_1 \oplus x_4 \end{aligned}$$

[Neal. *JAIR*, 12:87–91, (2000)]  
 [Pearl. *Cambridge University Press* (2009)]

## Failure of $d$ -separation in cyclic graphs



$v_3 \perp^d v_4 \stackrel{d\text{-sep.}}{\implies} x_3 \perp\!\!\!\perp x_4$  for all causal models

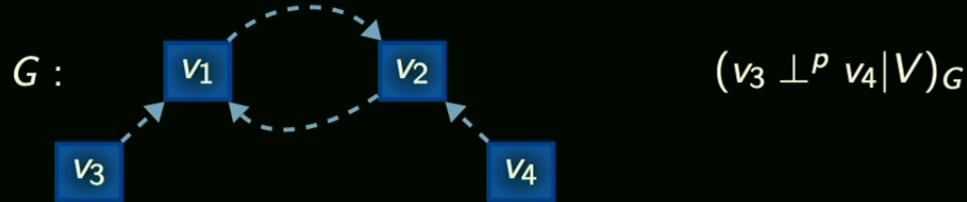
Causal model:

$$\begin{aligned} x_1 &= x_3 \oplus x_2 &\implies x_3 &= x_4 &\implies \Pr(x_3, x_4) &\propto \delta_{x_3, x_4} \\ x_2 &= x_1 \oplus x_4 \end{aligned}$$

$x_3 \not\perp\!\!\!\perp x_4$

[Neal. *JAIR*, 12:87–91, (2000)]  
[Pearl. *Cambridge University Press* (2009)]

## Defining $p$ -separation

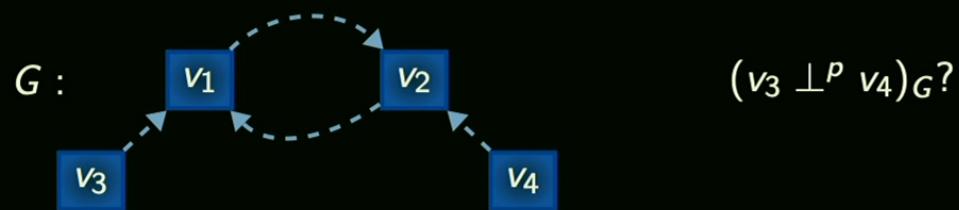


if and only if

$\exists G_{\text{acyc}} \in \mathbb{G}^{\text{acyc}}(G)$  such that  $(v_3 \perp^d v_4 | V, \textcolor{red}{T})$

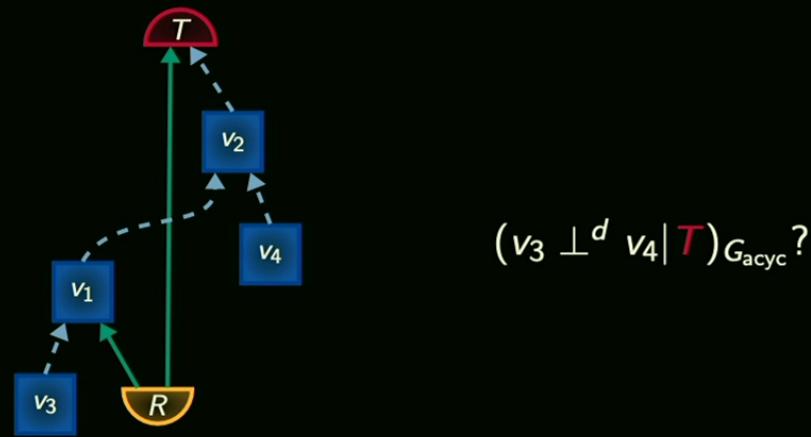
“ $p$ ” for *postselection* — name suggested by Yilè Yīng

## Defining $p$ -separation



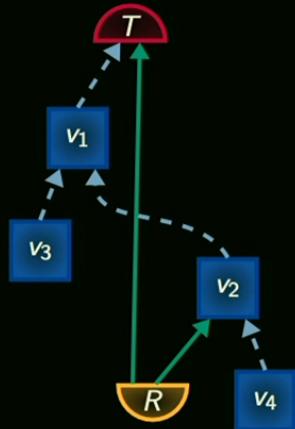
## Defining $p$ -separation

$$\mathbb{G}_{\text{acyc}}(G) = \left\{ \begin{array}{c} \text{Diagram 1: } \text{A directed acyclic graph with nodes } v_1, v_2, v_3, v_4, R, T. \\ \text{Diagram 2: } \text{A directed acyclic graph with nodes } v_1, v_2, v_3, v_4, R, T_1, T_2. \\ \vdots \\ \text{Diagram } n: \text{A directed acyclic graph with nodes } v_1, v_2, v_3, v_4, R_1, R_2, T_1, T_2, \dots \\ \vdots \end{array} \right\}$$



## Defining $p$ -separation

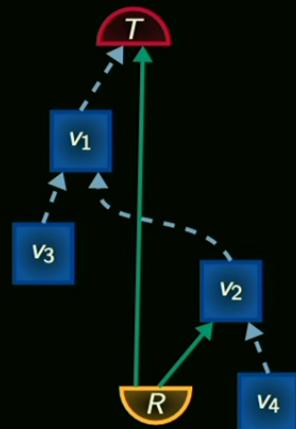
$$\mathbb{G}_{\text{acyc}}(G) = \left\{ \begin{array}{c} \text{Diagram 1: } \text{A directed acyclic graph with nodes } v_1, v_2, v_3, v_4 \text{ and a root node } R. \\ \text{Diagram 2: } \text{A similar DAG with nodes } v_1, v_2, v_3, v_4 \text{ and root } R. \\ \vdots \\ \text{Diagram } n: \text{A DAG with nodes } v_1, v_2, v_3, v_4 \text{ and root } R_1. \\ \vdots \\ \text{Diagram } m: \text{A DAG with nodes } v_1, v_2, v_3, v_4 \text{ and roots } R_1, R_2. \end{array} \right\}$$



$(v_3 \perp^d v_4 | T)_{G_{\text{acyc}}}$ ?

## Defining $p$ -separation

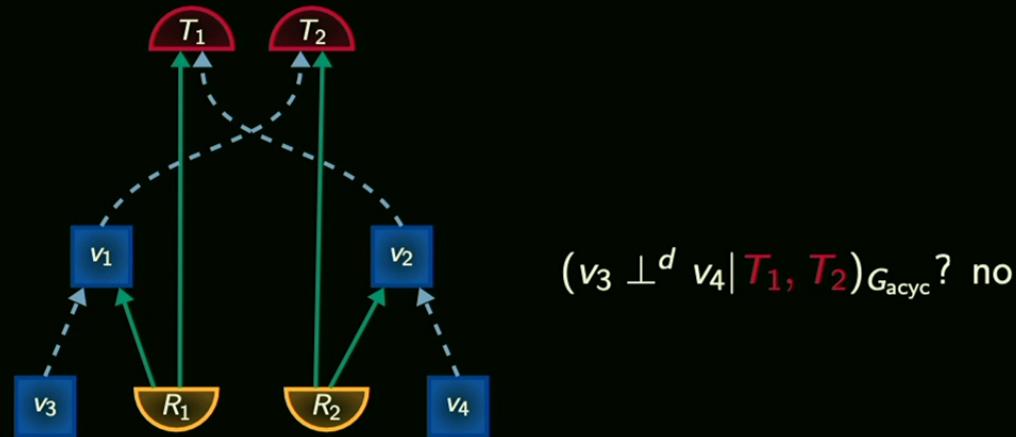
$$\mathbb{G}_{\text{acyc}}(G) = \left\{ \begin{array}{c} \text{Diagram 1: } \text{A directed acyclic graph with nodes } v_1, v_2, v_3, v_4 \text{ and a root node } R. \\ \text{Diagram 2: } \text{A similar DAG with nodes } v_1, v_2, v_3, v_4 \text{ and a root node } R. \\ \vdots \\ \text{Diagram } n: \text{A DAG with nodes } v_1, v_2, v_3, v_4 \text{ and a root node } R_1. \\ \vdots \\ \text{Diagram } m: \text{A DAG with nodes } v_1, v_2, v_3, v_4 \text{ and a root node } R_2. \\ \vdots \\ \dots \end{array} \right\}$$



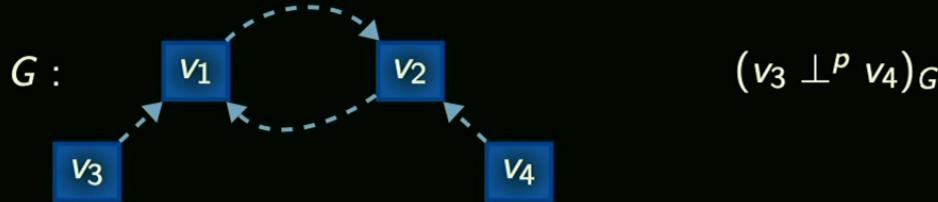
$(v_3 \perp^d v_4 | T)_{G_{\text{acyc}}}?$  no

## Defining $p$ -separation

$$\mathbb{G}^{\text{acyc}}(G) = \left\{ \begin{array}{c} \text{Diagram showing nodes } v_1, v_2, v_3, v_4 \text{ and regions } R, T. \\ v_1 \text{ and } v_2 \text{ are in } R, v_3 \text{ and } v_4 \text{ are in } T. \\ \text{Solid green arrows: } v_3 \rightarrow v_1, v_3 \rightarrow v_2, v_4 \rightarrow v_1, v_4 \rightarrow v_2. \\ \text{Dashed black arrows: } v_1 \rightarrow v_3, v_2 \rightarrow v_3, v_1 \rightarrow v_4, v_2 \rightarrow v_4. \\ \text{Dashed green arrow: } v_3 \rightarrow v_4. \end{array} \right\}$$



## Defining $p$ -separation



if and only if

$\exists G_{\text{acyc}} \in \mathbb{G}^{\text{acyc}}(G)$  such that  $(v_3 \perp^d v_4 | \textcolor{red}{T})$

$\implies (v_3 \not\perp^p v_4)_G$

## *p*-separation theorem

for any  $G$

**Soundness:** If  $A \perp^p B|C$  in  $G$ , then for all causal models  
 $A \perp\!\!\!\perp B|C$  in  $\text{Pr}$

**Completeness:** If  $A \not\perp^p B|C$  in  $G$ , then there exists a  
causal model where  $A \not\perp\!\!\!\perp B|C$  in  $\text{Pr}$

For causal models\* on arbitrary  $G$

\*with finite dimensional  $\mathcal{H}$  and discrete random variables

## **Further results and Outlook**



## Further results

- Simplified methodology for functional causal models  
→ number and existence of solutions
- Describe quantum Bayesian networks, process matrices, . . .  
→ characterising subsets of cyclic models

[Henson et al. *New J. Phys.* 16 113043 (2014)]

[Barrett et al. arXiv:1906.10726 (2019)]

[Costa et al. *New J. Phys.* 18 063032 (2016)]

## Further results

- Simplified methodology for functional causal models  
→ number and existence of solutions
- Describe quantum Bayesian networks, process matrices, . . .  
→ characterising subsets of cyclic models
- Definition of interventions (in preparation)  
→ effect of cyclicity on signalling
- Mapping tensor networks to cyclic causal models (in preparation)  
→ emergence of space-time and notion of causality

[Cotler et al. *J. High Energ. Phys.* 42 (2019)]

## Outlook

**Causal discovery algorithms** use  $d$ -separation for acyclic  $G$

→ use  $p$ -separation in the cyclic case

**Indefinite causal structures** are described with cyclic models

→ characterise special subsets, e.g., violating causal inequalities or causally non-separable

**Causal compatibility problems** compatibility of  $\text{Pr}$  with  $G$

→ extend known techniques for acyclic  $G$ , e.g., inflation, to cyclic mapping them to acyclic with postselection

**Studying spacetime emergence** using tensor networks

→ emergence of space time geometry from operational properties of causal models

[Wolfe et al. *J. Causal Inference* (2019)]

**Thank you**

