

Title: Multi-loop Null Polygons from Fishnet theory to N=4 SYM

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Abstract: "Null Polygons" in N=4 SYM theory describe the multi-point correlators of 1/2-BPS local operators with large R-charge, when they approach the vertices of a light-like polygon. The leading UV divergences of null polygons is conjectured to satisfy a hierarchy of coupled Toda field theory equations [E.O., Vieira '22]. I will present some progress towards the prediction of Null Polygons beyond leading logarithms via the hexagons technique, appropriately truncated in the light-cone regime. The method, still conjectural, relies on a series of weak-coupling derivations performed in the Fishnet limit of the theory, where the hexagon representation is derived in the basis of eigenfunctions of a conformal Heisenberg magnet in the principal series. I will present a number of worked-out examples for multi-point multi-loop Fishnet Feynman integrals and Null Polygons.

Zoom link

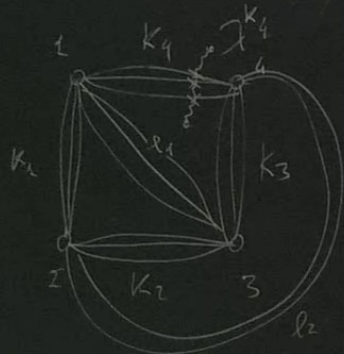
Null Polygons from Fishnet Theory to $N=4$ SYM

$N=4$ SYM $\Phi_{\pm}, \Psi_a, A_{\mu}$ $SU(N)$ $(\phi_{\pm})_{ij}$ $N \rightarrow \infty$ $g_{YM} \rightarrow 0$ $\lambda = \frac{g_{YM}^2 N}{8\pi^2}$

$O_k(y^{\pm}, x^{\pm}) = \text{Tr}(y \cdot \Phi)^{L_k}$; $\Delta(\lambda) = \Delta(0) = L_k$

$\langle O_1 O_2 O_{\Delta, l} \rangle = C_{12(\Delta, l)}(\lambda)$

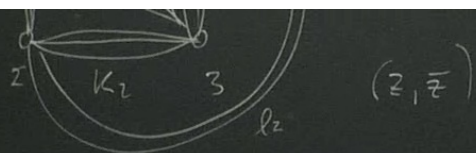
$$\langle 0_1 0_2 0_3 0_4 \rangle_{\lambda=0} \sim \sum_{\underline{k}, \underline{l}} \left(\frac{y_1 - y_2}{x_{12}^2} \right)^{k_1} \left(\frac{y_2 - y_3}{x_{23}^2} \right)^{k_2} \left(\frac{y_3 - y_4}{x_{34}^2} \right)^{k_3} \left(\frac{y_1 - y_4}{x_{14}^2} \right)^{k_4} \left(\frac{y_1 y_3}{x_{13}^2} \right)^{l_1} \left(\frac{y_2 y_4}{x_{24}^2} \right)^{l_2}$$



$$+ \lambda G_{\underline{k}, \underline{l}}^{(1)} + \lambda^2 G_{\underline{k}, \underline{l}}^{(2)} + \dots =$$

$k_i \gg 1$

$$= P_{l_1}(z_1, \bar{z}_1) \times P_{l_2}(z_1, \bar{z}_1)$$



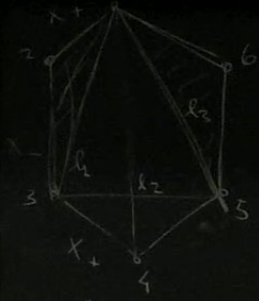
$$= P_{l_1}(z, \bar{z}) \times P_{l_2}(z, \bar{z})$$

$$\cdot (t_1 \partial_{t_1} + t_6 \partial_{t_6})(t_5 \partial_{t_5} + t_6 \partial_{t_6}) \log P_{l_1, l_2, l_3} = t_6^2 \frac{P_{l_1, l_2, l_3+1} P_{l_1, l_2, l_3-1}}{P_{l_1, l_2, l_3}^2};$$

$$\cdot t_2 = t_6 = 0 \quad P_{l_1, l_2, l_3} = \tau_{l_2}(t_3) \tau_{l_1+l_2+l_3}(t_1) \tau_{l_3}(t_5)$$

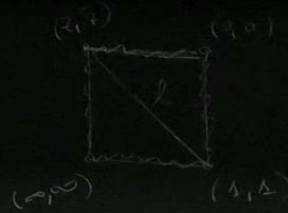
$$\tau_l(s) = \det_{1 \leq i, j \leq l} I_{|i-j|}(2s); \quad P_{l_1, l_2, l_3} \text{ for } l_1, l_2, l_3 \in \{0, 1\}$$

$$\langle O_1, O_2, O_{\Delta, l} \rangle = C_{12(\Delta, l)}(\lambda)$$



$$x_{i+1}^2 \rightarrow 0$$

$$t_i^2 = \int_0^\infty \log(x_{i+1}^2) \log(x_{i+1}^2) dx$$



$$z \rightarrow 0$$

$$\bar{z} \rightarrow \infty$$

$$S_i^2 = -\lambda \log z \log \bar{z}$$



$$e^{-(t_1^2 + \dots + t_6^2)} P_{l_1, l_2, l_3}(t_1, \dots, t_6)$$

$$T_e(s) \begin{cases} s_1 = -\lambda \log z \\ s_2 = \log \bar{z} \end{cases}$$

$$(s_1 \partial_1)(s_2 \partial_2) \log \tilde{T}_e(s_1, s_2) = \frac{\tilde{T}_{e+1} \tilde{T}_{e-1}}{\tilde{T}_e^2}$$

Fishnet Theory

γ -deformation $N=4$ SYM

$$\varphi_a \rightarrow q_a = (q_{a,1}, q_{a,2}, q_{a,3}) \quad SU(4)$$

$$[\varphi_a, \varphi_b] = \kappa \varphi_a \varphi_b - \frac{1}{\kappa} \varphi_b \varphi_a; \quad q_{A\mu} = (0, 0, 0) \quad X, Y, Z$$

$$\kappa = e^{i q_a \wedge q_b}; \quad q_a \wedge q_b = -q_a^+ \begin{pmatrix} 0 & \gamma_1 & -\gamma_2 \\ -\gamma_1 & 0 & \gamma_3 \\ \gamma_2 & -\gamma_3 & 0 \end{pmatrix} \cdot q_b;$$

$$\gamma_3 \rightarrow -i\infty; \quad \lambda \rightarrow \infty \mid \xi_3^2 = \lambda e^{i\gamma_3} \text{ finite}$$

$$[X, Y]_{\kappa} [X, Y]_{\kappa} = e^{2i\gamma_3} XY \bar{X} \bar{Y} + \text{subleading} \\ \rightarrow \xi^2 XY \bar{X} \bar{Y}$$

$$p_1, q_0 = -q_2 \begin{pmatrix} -\gamma_1 & 0 & \gamma_3 \\ \gamma_2 & -\gamma_3 & 0 \end{pmatrix} \cdot q_0;$$

$$[X, Y]_K [X, Y]_K = e^{i\theta_3} XY \bar{X} \bar{Y} + \text{subleading} \\ \rightarrow \sum^2 XY \bar{X} \bar{Y}$$

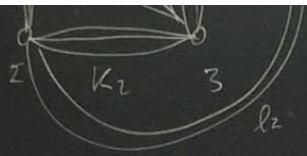


$$= \hat{B}^{(2)}(z|y) \rightarrow \hat{B}; [\hat{B}, \hat{t}(u)] = 0$$

$$\Psi_{a_1 a_2 a_3}(u_1, u_2, u_3); u_j \in \mathbb{R}, a \in \mathbb{Z}_+$$

$SU(2)$ R-matrix

$$\Psi_{a_1 a_2}(u_1, u_2) = R_{a_1 a_2}(u_1, u_2) \Psi_{a_2 a_1}(u_1, u_2) R_{a_1 a_2}(u_1, u_2)$$



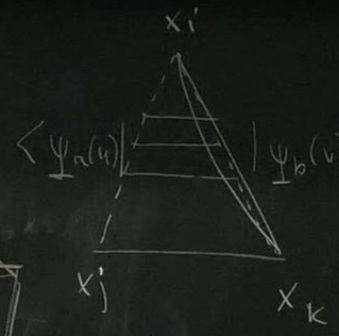
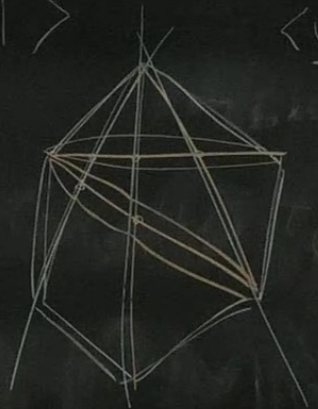
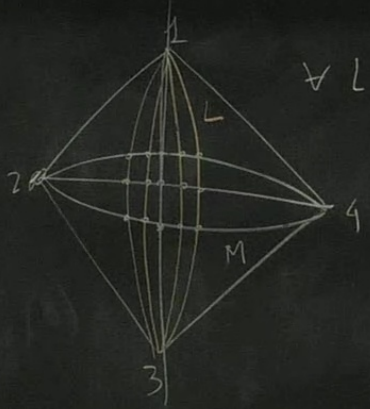
(z, \bar{z})

$$= P_{l_1}(z, \bar{z}) \times P_{l_2}(z, \bar{z})$$

$$\langle \text{Tr}(X^L(x_1) Y^M(x_2) \bar{X}^L(x_3) \bar{Y}^M(x_4)) \rangle$$

$\forall L, M$

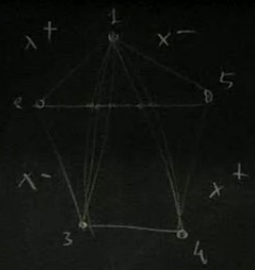
[Basso, Dixon]



$$\langle \psi_a(u) | \psi_b(v) \rangle = E_b(v) \times \langle \psi_a(u) | \psi_b(v) \rangle$$

$$q_a \wedge q_b = -q_2^+ \begin{pmatrix} -\gamma_1 & 0 & \gamma_2 \\ \gamma_2 & \gamma_3 & 0 \\ \gamma_2 & \gamma_3 & 0 \end{pmatrix} \cdot q_b;$$

$$[X, Y]_K [X, Y]_K = l^{21} \gamma_3 XY \bar{X} \bar{Y} + \text{subleading} \\ \rightarrow \sum^2 XY \bar{X} \bar{Y}$$



$$\sim \sum_{a,b=1}^{\infty} ab \int_{\mathbb{R}} \int_{\mathbb{R}} du dv \frac{|\bar{z}_1|^{2iu} |\bar{z}_2|^{2iv} \text{Heb}(u,v)}{(u^2 + \frac{a^2}{4})^{1+l_1} (v^2 + \frac{b^2}{4})^{1+l_2}}$$

$$\text{Tr}_{ab} \left[\text{Reb}(u-v) \left(\frac{\bar{z}_1}{z_1} \right)^{\frac{1}{J_a}} \otimes \left(\frac{\bar{z}_2}{z_2} \right)^{\frac{1}{J_b}} \right]$$

$$l_1=3, l_2=2 \quad \mathbb{Z}_1, \mathbb{Z}_2$$

$$z_1 \rightarrow 0, \bar{z}_1 \rightarrow \infty$$

$$z_2 \rightarrow 0, \bar{z}_2 \rightarrow \infty$$

SU(2|2)

$$\frac{z_1}{z_2} \rightarrow 0$$