

Title: GPTs and the probabilistic foundations of quantum theory - Lecture

Speakers: Alexander Wilce

Collection: GPTs and the probabilistic foundations of quantum theory - mini-course

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GPT^s = General Probability
Theory

Plan

1. Probabilistic models ← Today
2. " " , Linearized
3. Composite models, entanglement
4. Probabilistic theories / category theory
5. Other topics?

History

New!

Hordy '00

Barrett '04 (S?)

|||

Chris Fuchs

QIT!

Foulis/Randall

Old!

von Neumann '37

Mackey '57, '63

→ "Quantum Logics" 60's - early 1980's

5. Other topics:

classical

In elem. prob. theory

(E, α)
outcome-set \uparrow α \uparrow prob. weight

$$\alpha: E \rightarrow \mathbb{R}$$

$$\alpha(x) \geq 0 \quad \forall x,$$

$$\sum_{x \in E} \alpha(x) = 1$$

Def: A test space (or manual)
is a collection

$\mathcal{M} = \{E, F, \dots\}$ of outcome-sets.

Let $\bar{X} = \cup \mathcal{M}$, then a prob. weight

is a f.n. $\alpha: \bar{X} \rightarrow \mathbb{R}$

$$\forall x \in \bar{X} \quad \alpha(x) \geq 0, \quad \sum_{x \in E} \alpha(x) = 1 \quad \forall \underline{E} \in \mathcal{M}$$

Def: A test space (or manual)

A prob model is a collection

is a pair

(M, Q)

$Q \subseteq \text{Pr}(M)$

↑
all "prob.
weights"

$M = \{E, F, \dots\}$ of outcome-sets.

Let $\bar{X} = \cup M$, then a prob. weight

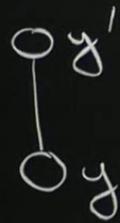
is a f.n $\alpha: \bar{X} \rightarrow \mathbb{R}$

$$\forall x \in \bar{X} \quad \alpha(x) \geq 0, \quad \sum_{x \in E} \alpha(x) = 1 \quad \forall E \in M$$

$$\underline{\underline{\Sigma}} \underline{\underline{1}} : m = \{ \{x, x'\}, \{y, y'\} \}$$

E

F

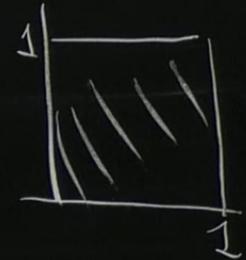


$$\alpha(x') = 1 - \alpha(x)$$

$$\alpha(y') = 1 - \alpha(y)$$

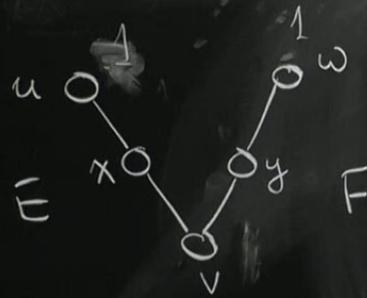
$$\alpha \leftrightarrow (\alpha(x), \alpha(y)) \in \mathbb{R}^2$$

Greechie diagram



5. Other topics?

Ex 2



$$m = \left\{ \{u, x, v\}, \{v, y, w\} \right\}$$

$$\alpha(x) = 1 - (\alpha(u) + \alpha(v))$$

$$\alpha(y) = 1 - (\alpha(v) + \alpha(w))$$

Exc



$\equiv M$

* If $E, F \in M$, $E \subseteq F$

If $y \in F \setminus E$, $\alpha(y) = 0 \quad \forall \alpha \in Pr(M)$

so assume M "irredundant": $E \subseteq F \Rightarrow E = F$
 $\forall E, F \in M$

* $Pr(M)$ always convex in \mathbb{R}^X
Usual to assume for a model (M, Ω)
that Ω is convex.

$$\sum_{i=1}^{\infty} 3 = 3$$

Let (S, Σ) be a measurable space

↑ set ↑ a σ -boolean algebra of subsets of S "events"

* $a_1, a_2, \dots \in \Sigma$
 $\bigcup_{i=1}^{\infty} a_i \in \Sigma$

prob. measure: $0 \leq \mu(a)$,
 $\mu: \Sigma \rightarrow \mathbb{R}$ $\mu(S) = 1$

* $\emptyset, S \in \Sigma$

$\{a_i\}$ pairwise disjoint

* $a \in \Sigma \Rightarrow a^c = S - a \in \Sigma$

$\Rightarrow \sum_{i=1}^{\infty} \mu(a_i) = \mu\left(\bigcup_{i=1}^{\infty} a_i\right)$

Let

$\mathcal{M} = \mathcal{M}(S, \Sigma)$ consist of
all countable partitions of S by sets $a \in \Sigma$

Then (Exc)

$\text{Pr}(\mathcal{M}) = \text{prob. measures on } (S, \Sigma)$

$\|x\| = 4$ Let \mathcal{H} be a Hilbert space.

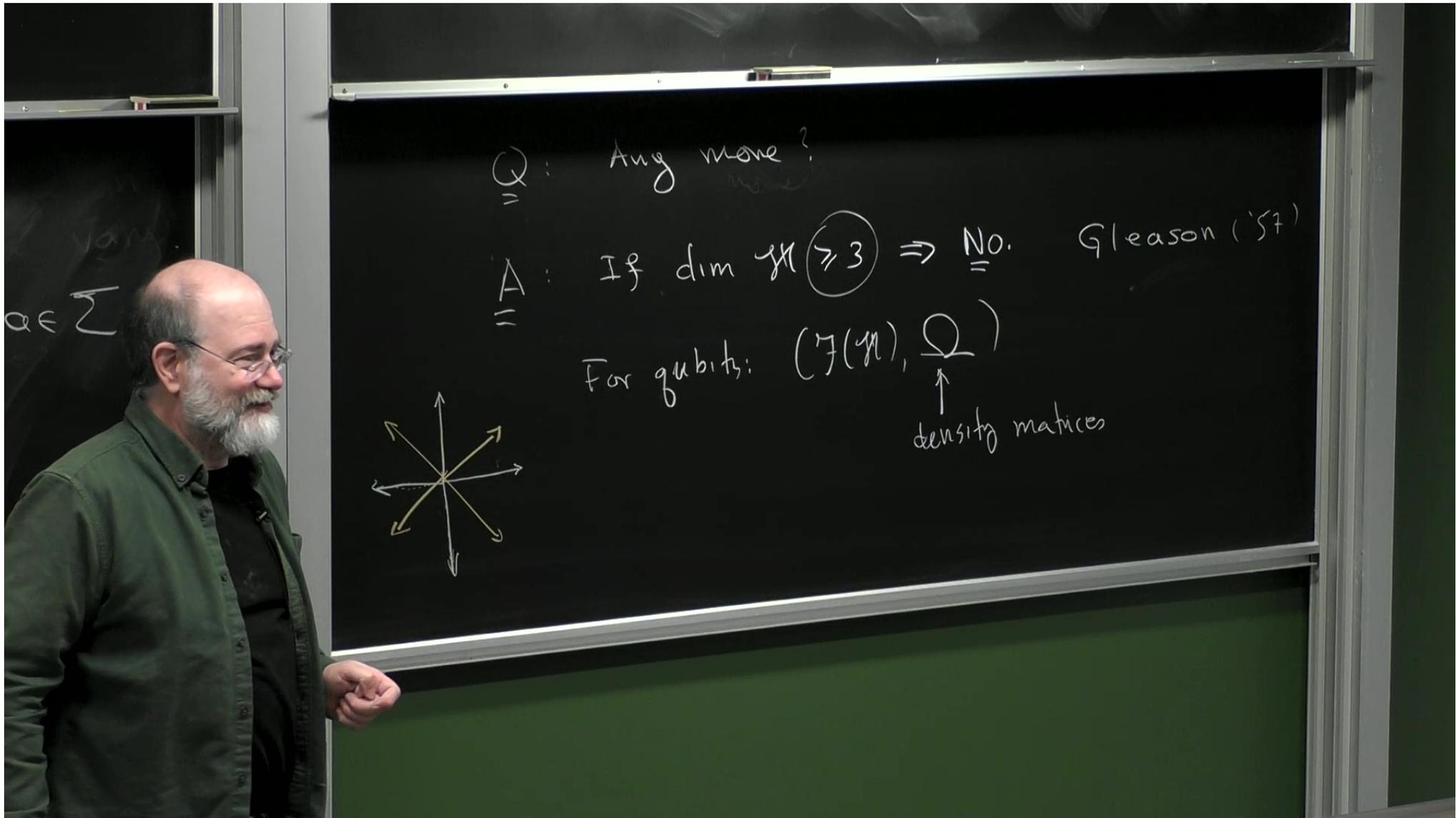
The frame manual is $\{E \in \mathcal{H} \mid E \text{ is an ONB}\}$

$$\mathcal{F}(\mathcal{H}) = \{E \in \mathcal{H} \mid E \text{ is an ONB}\}$$

What's a prob. weight?

If $v \in \mathcal{H}, \|v\|=1 \Rightarrow d_v(x) = |\langle v, x \rangle|^2$

If W a density op. $\Rightarrow d_W(x) = \langle Wx, x \rangle = \text{Tr}(W P_x)$



Q: Aug move?

A: If $\dim \mathcal{H} \geq 3 \Rightarrow$ No. Gleason ('57)

For qubits: $(\mathcal{F}(\mathcal{H}), \mathcal{Q})$
↑
density matrices

