

Title: Motion Groupoids

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Collection: Higher Categorical Tools for Quantum Phases of Matter

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Abstract: The braiding statistics of point particles in 2-dimensional topological phases are given by representations of the braid groups. One approach to the study of generalised particles in topological phases, loop particles in 3-dimensions for example, is to generalise (some of) the several different realisations of the braid group.

In this talk I will construct for each manifold  $M$  its motion groupoid  $\text{Mot}_M$ , whose object class is the power set of  $M$ . I will discuss several different, but equivalent, quotients on motions leading to the motion groupoid. In particular that the quotient used in the construction  $\text{Mot}_M$  can be formulated entirely in terms of a level preserving isotopy relation on the trajectories of objects under flows -- worldlines (e.g. monotonic 'tangles').

I will also give a construction of a mapping class groupoid  $\text{MCG}_M$  associated to a manifold  $M$  with the same object class. For each manifold  $M$  I will construct a functor  $F: \text{Mot}_M \rightarrow \text{MCG}_M$ , and prove that this is an isomorphism if  $\pi_0$  and  $\pi_1$  of the appropriate space of self-homeomorphisms of  $M$  is trivial. In particular there is an isomorphism in the physically important case  $M=[0,1]^n$  with fixed boundary, for any  $n \in \mathbb{N}$ .

I will discuss several examples throughout.

# MOTION GROUPOIDS

arXiv:2103.10377, with Paul Martin, João Faria Martins

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## BRIEF OVERVIEW

- (I) **Construction of the motion groupoid  $\text{Mot}_{\underline{M}}$  of a pair  $\underline{M} = (M, A)$ .**  
Morphisms are equivalence classes of continuous flows of ambient space  $M$  which fix  $A$ , acting on  $\mathcal{P}M$ . Recover classical definition of the motion group associated to a manifold  $M$  and a submanifold  $N \in \mathcal{P}M$ , by looking at the morphism group at  $N$ . Obtain groups isomorphic to braid groups, loop braid groups.
- (II) **Construction of mapping class groupoid  $\text{MCG}_{\underline{M}}$ .**  
Morphisms are now equivalence classes of homeomorphisms of  $M$ , fixing  $A$ . The object set is again  $\mathcal{P}M$ . Again obtain groups isomorphic to braid groups, loop braid groups.
- (III) **Construction of functor  $F: \text{Mot}_{\underline{M}} \rightarrow \text{MCG}_{\underline{M}}$ .**  
We prove that this is an isomorphism when  $\pi_0$  and  $\pi_1$  of space of homeomorphisms of  $M$  fixing  $A$  are trivial. E.g.  $\underline{M} = ([0, 1]^n, \partial[0, 1]^n)$ .

## MOTIVATION

**AIM:** To construct algebraic structures useful for modelling generalised particle motion in topological phases.

- Very general ambient space, particle types allowed.
- Study object sets in a unified way, questions about skeletons etc.
- Allows access to higher categorical structures e.g. monoidal.
- Facilitates passage between motions and generalised tangles/ defect TQFT
- Morphisms which do not start and end in the same configuration allowed.
- Expect interesting new algebraic structures

## SPACE OF SELF-HOMEOMORPHISMS OF A MANIFOLD $M$

Let  $\underline{M} = (M, A)$  be a pair of a manifold and a subset. Let  $H_{\underline{M}} \subset \mathbf{Top}(M, M)$  is the set of homeomorphisms of  $M$  which fix  $A$  pointwise with the compact-open topology. Notice this also has a group structure.

### Lemma

(Hatcher) Let  $X$  be a compact space and  $Y$  a metric topological space with metric  $d$ . Then

(i) the function

$$d'(f, g) := \sup_{x \in X} d(f(x), g(x))$$

is a metric on  $\mathbf{Top}(X, Y)$ ; and

(ii) the compact open topology on  $\mathbf{Top}(X, Y)$  is the same as the one defined by the metric  $d'$ .

## GROUPOIDS OF SELF HOMEOMORPHISMS

Let  $\underline{M} = (M, A)$  be a pair of a manifold and a subset.

### Lemma

There is a (left) group action

$$\begin{aligned}\sigma: H_{\underline{M}} \times \mathcal{P}M &\rightarrow \mathcal{P}M \\ (f, N) &\mapsto f(N).\end{aligned}$$

## GROUPOIDS OF SELF HOMEOMORPHISMS

### Proposition

Thus there is an action groupoid  $\text{Homeo}_{\underline{M}}$  obtained from  $\sigma$ . Explicitly the object set is  $\mathcal{P}M$  and the morphisms in  $\text{Homeo}_{\underline{M}}(N, N')$  are triples  $(f, N, f(N))$  where

- $f: M \rightarrow M$  is a homeomorphism,
- $f(N) = N'$ ,
- $f$  fixes  $A$  pointwise.

We will denote triples  $(f, N, f(N)) \in \text{Homeo}_{\underline{M}}(N, N')$  as  $f: N \rightsquigarrow N'$ .

Identity:  $\text{id}_M: N \rightsquigarrow N$  Inverse:  $f: N \rightsquigarrow N' \mapsto f^{-1}: N' \rightsquigarrow N$ .

We will also sometimes identify  $\text{Homeo}_{\underline{M}}(N, N')$  with the projection to the first element of the triple. Then can equip morphism sets with a topology and  $H_{\underline{M}} = \text{Homeo}_{\underline{M}}(\emptyset, \emptyset) = \text{Homeo}_{\underline{M}}(M, M)$  and every  $\text{Homeo}_{\underline{M}}(N, N') \subseteq H_{\underline{M}}$ . Notice each self-homeomorphism  $f$  of  $M$  will belong to many such  $\text{Homeo}_{\underline{M}}(N, N')$ .

## FLOWS

### Definition

Fix a manifold, subset pair  $\underline{M} = (M, A)$ . A **flow** in  $\underline{M}$  is a map  $f \in \mathbf{Top}(\mathbb{I}, \mathbf{H}_{\underline{M}})$  with  $f_0 = \text{id}_M$ . Define,

$$\text{Flow}_{\underline{M}} = \{f \in \mathbf{Top}(\mathbb{I}, \mathbf{H}_{\underline{M}}) \mid f_0 = \text{id}_M\}.$$

### Example

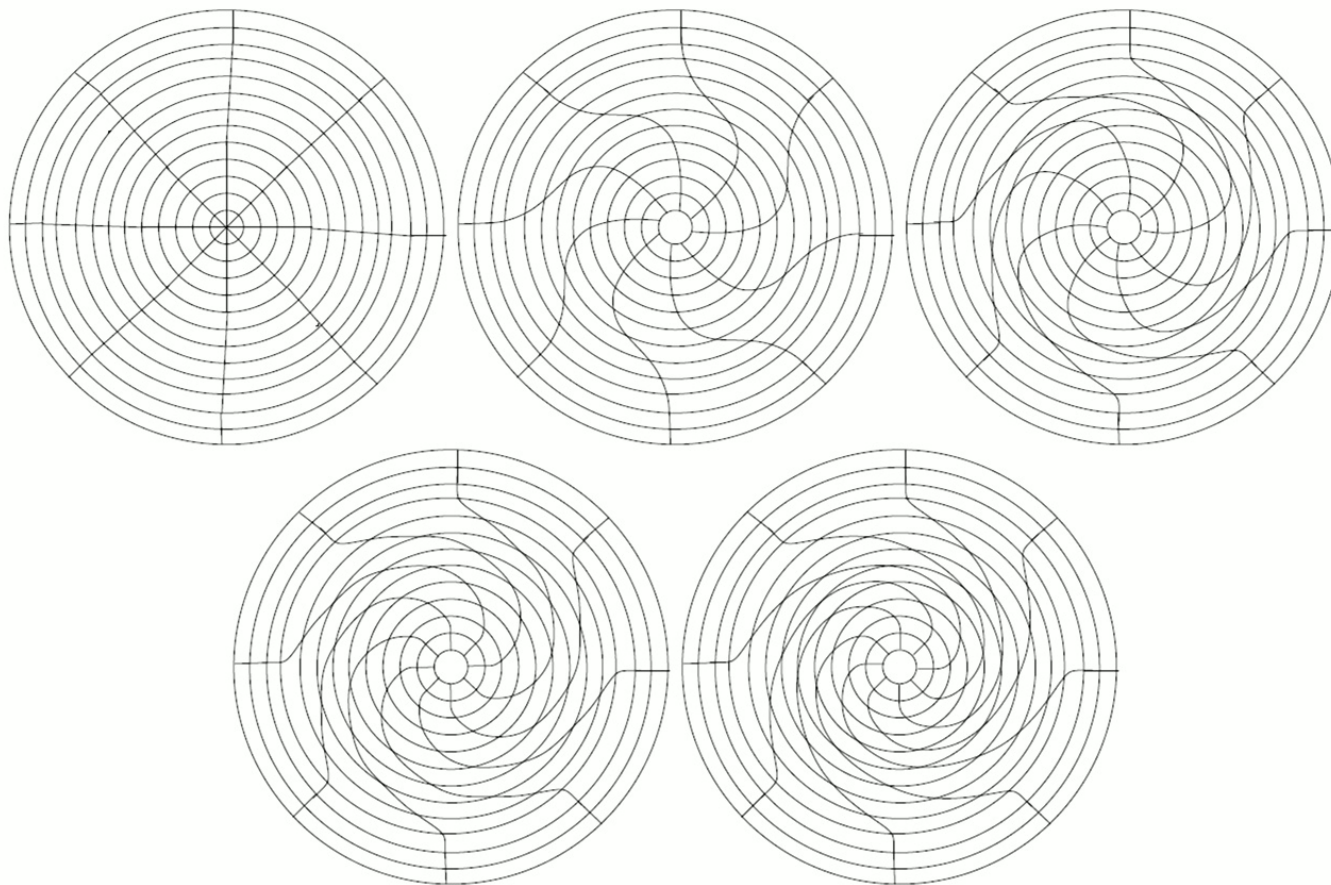
For any manifold  $M$  the path  $f_t = \text{id}_M$  for all  $t$ , is a flow. We will denote this flow  $\text{Id}_M$ .

### Example

For  $M = S^1$  (the unit circle) we may parameterise by  $\theta \in \mathbb{R}/2\pi$  in the usual way. Consider the functions  $\tau_\phi : S^1 \rightarrow S^1$  ( $\phi \in \mathbb{R}$ ) given by  $\theta \mapsto \theta + \phi$ , and note that these are homeomorphisms. Then consider the path  $f_t = \tau_{t\pi}$  ('half-twist'). This is a flow.



EXAMPLE  $M = D^2$



## OBTAINING NEW FLOWS FROM OLD

### Lemma

Let  $M$  be a manifold. For any flow  $f$  in  $\underline{M} = (M, A)$ , then  $(f^{-1})_t = f_t^{-1}$  is a flow.

**NOTE:** Proof uses that  $H_{\underline{M}}$  is a topological group when  $M$  is locally compact and locally connected (Arens). This means the product map and inverse map are continuous.

### Lemma

Let  $M$  be a manifold. There exists a set map

$$\begin{aligned} \bar{\phantom{f}} : \text{Flow}_{\underline{M}} &\rightarrow \text{Flow}_{\underline{M}} \\ f &\mapsto \bar{f} \end{aligned}$$

with

$$\bar{f}_t = f_{(1-t)} \circ f_1^{-1}. \quad (1)$$

## OBTAINING NEW FLOWS FROM OLD

### Proposition

Let  $M$  be a manifold. There exists a composition

$$\begin{aligned} * : \text{Flow}_{\underline{M}} \times \text{Flow}_{\underline{M}} &\rightarrow \text{Flow}_{\underline{M}} \\ (f, g) &\mapsto g * f \end{aligned}$$

where

$$(g * f)_t = \begin{cases} f_{2t} & 0 \leq t \leq 1/2, \\ g_{2(t-1/2)} \circ f_1 & 1/2 \leq t \leq 1. \end{cases} \quad (2)$$

For a pair  $\underline{M} = (M, A)$ ,  $(\text{Flow}_{\underline{M}}, *)$  is a magma.

## OBTAINING NEW PRE-MOTIONS FROM OLD

### Proposition

Let  $M$  be a manifold. There is an associative composition

$$\begin{aligned} \cdot : \text{Flow}_{\underline{M}} \times \text{Flow}_{\underline{M}} &\rightarrow \text{Flow}_{\underline{M}} \\ (f, g) &\mapsto g \cdot f \end{aligned}$$

where  $(g \cdot f)_t = g_t \circ f_t$ .

**NOTE:** Again proof uses that  $H_{\underline{M}}$  is a topological group.

### Lemma

For a manifold  $M$ ,  $(\text{Flow}_{\underline{M}}, \cdot)$  is a group, with identity  $\text{Id}_M$  and inverse map  $(f^{-1})_t = (f_t)^{-1}$ .

### Lemma

For  $f, g \in \text{Flow}_{\underline{M}}$ ,  $f^{-1} \stackrel{p}{\sim} \bar{f}$  and  $g \cdot f \stackrel{p}{\sim} g * f$ .

## MOTIONS

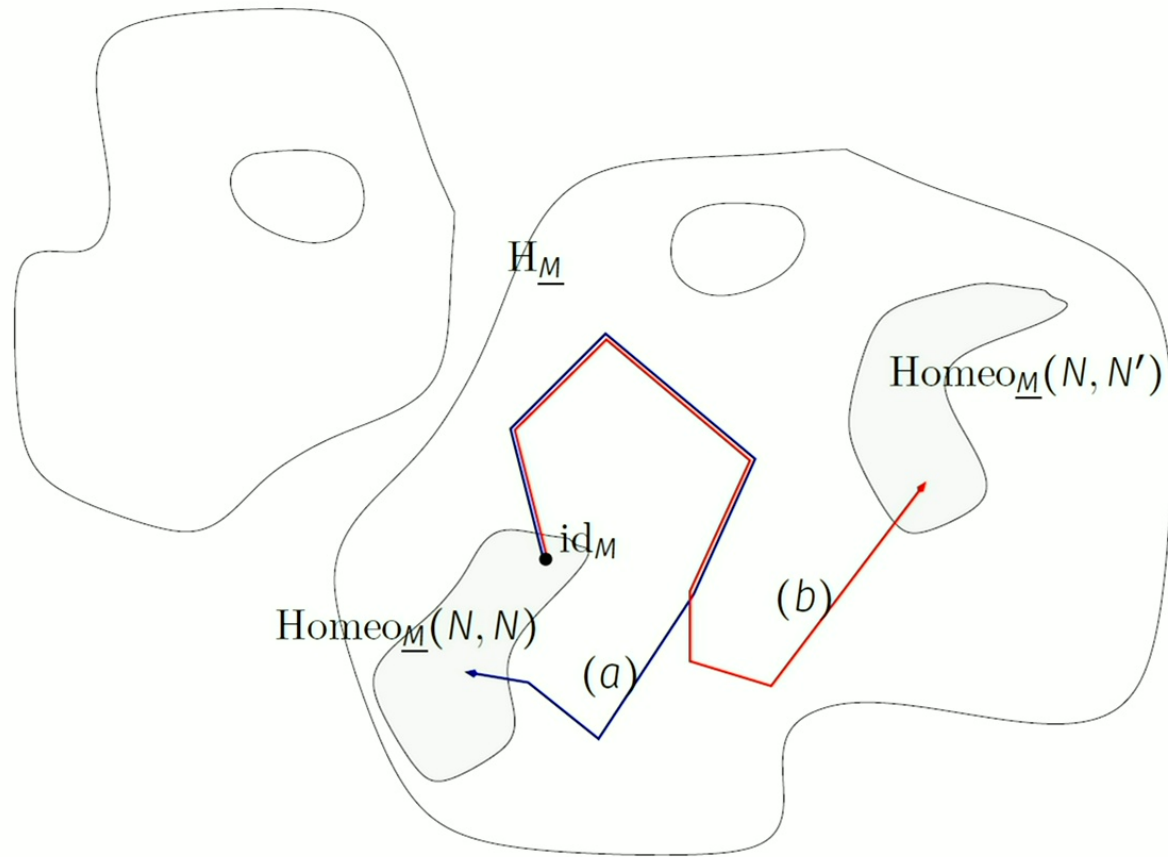
### Definition

Fix a  $\underline{M} = (M, A)$ . A **motion** in  $M$  is a triple  $(f, N, f_1(N))$  consisting of a flow  $f \in \text{Flow}_{\underline{M}}$ , a subset  $N \subseteq M$  and the image of  $N$  at the endpoint of  $f$ ,  $f_1(N)$ .

We will denote such a triple by  $f: N \curvearrowright N'$  where  $f_1(N) = N'$ , and say it is a motion from  $N$  to  $N'$ .

$$Mt_M(N, N') = \{\text{motions } f: N \curvearrowright N'\}$$

# MOTIONS



## MOTIONS

For any  $N \in M$ ,  $Id_M: N \curvearrowright N$  is a motion. Let  $f: N \curvearrowright N'$  and  $g: N' \curvearrowright N''$  be motions in  $M$ , then  $g \cdot f: N \curvearrowright N''$  ( $(g \cdot f)_t = g_t \circ f_t$ ) is a motion.

### Lemma

There is a group action of  $(\text{Flow}_M, \cdot)$  on  $\mathcal{P}M$ , thus there is an action groupoid

$$\text{Mt}_M = (\mathcal{P}M, \text{Mt}_M(N, N'), \cdot, \text{Id}_M, f^{-1}).$$

Similarly  $g * f: N \curvearrowright N''$  is a motion.

### Lemma

There is a magma action of  $(\text{Flow}_M, *)$  on  $\mathcal{P}M$  we obtain an action magmoid

$$\text{Mt}_M^* = (\mathcal{P}M, \text{Mt}_M(N, N'), *).$$

## MOTIONS AS MAPS $M \times \mathbb{I} \rightarrow M \times \mathbb{I}$

### Definition

Let  $\underline{M} = (M, A)$  and  $\underline{M \times \mathbb{I}} = (M \times \mathbb{I}, A \times \mathbb{I})$ , and  $N, N' \subset M$  subsets. Let

$$\text{Mt}_{\underline{M}}^{\text{hom}}(N, N') \subset \text{H}_{\underline{M \times \mathbb{I}}}$$

denote the subset of homeomorphisms  $g \in \text{H}_{\underline{M \times \mathbb{I}}}$  such that

- (I)  $g(m, 0) = (m, 0)$  for all  $m \in M$ ,
- (II)  $g(M \times \{t\}) = M \times \{t\}$  for all  $t \in \mathbb{I}$ , and
- (III)  $g(N \times \{1\}) = N' \times \{1\}$ .

### Theorem (T., Faria Martins, Martin)

Let  $M$  be a manifold and  $N, N' \subset M$ . There is a bijection

$$\begin{aligned} \Theta: \text{Mt}_{\underline{M}}(N, N') &\rightarrow \text{Mt}_{\underline{M}}^{\text{hom}}(N, N'), \\ f &\mapsto ((m, t) \mapsto (f_t(m), t)). \end{aligned}$$



## MOTIONS AS MAPS $M \times \mathbb{I} \rightarrow M \times \mathbb{I}$

### Theorem

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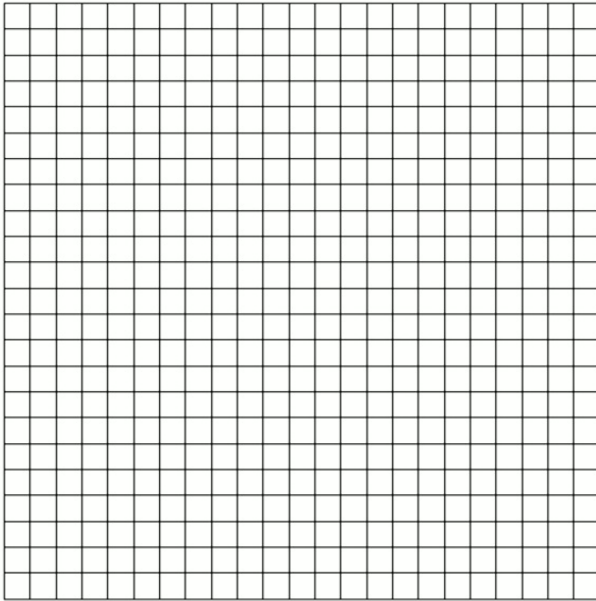
### Idea of proof

(e.g. Hatcher) As  $M$  is locally compact, Hausdorff, there is a bijection

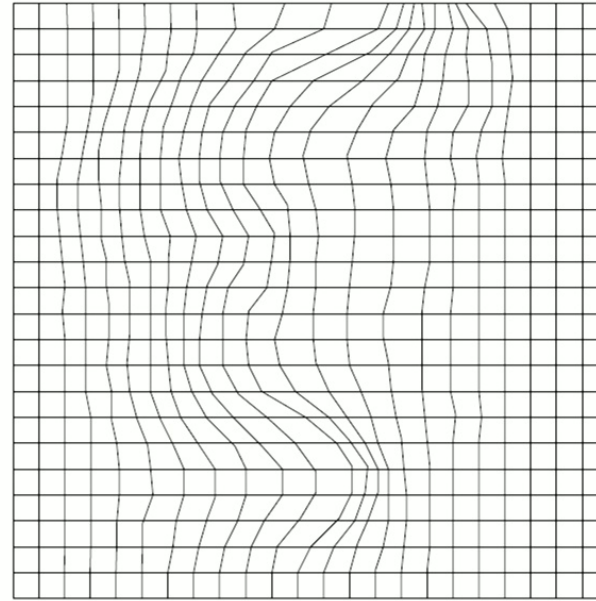
$$\Phi: \text{Top}(\mathbb{I}, \text{TOP}(M, M)) \rightarrow \text{Top}(M \times \mathbb{I}, M).$$

(Coming from an adjunction between the product functor  $M \times -$  and the hom functor  $\text{TOP}(M, -)$ ). It follows that the image is continuous. To show that the image is a homeomorphism we need that  $\text{TOP}^h(M, M)$  is a topological group.

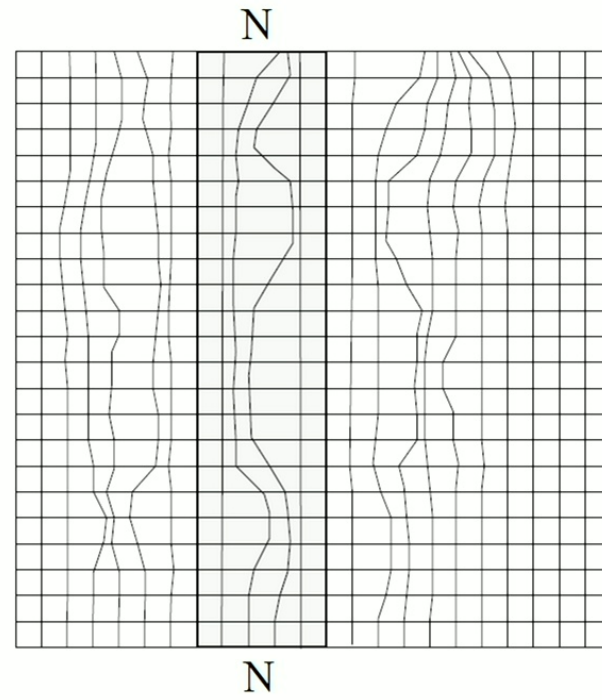
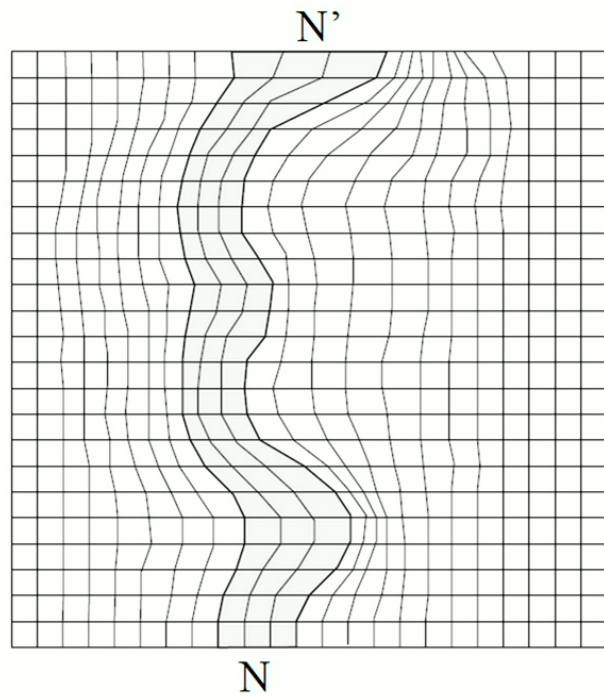
$$M = \mathbb{I}$$



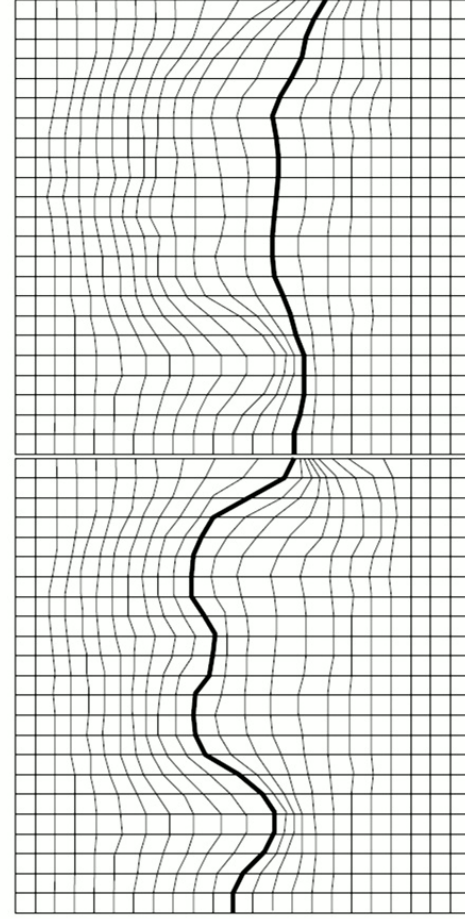
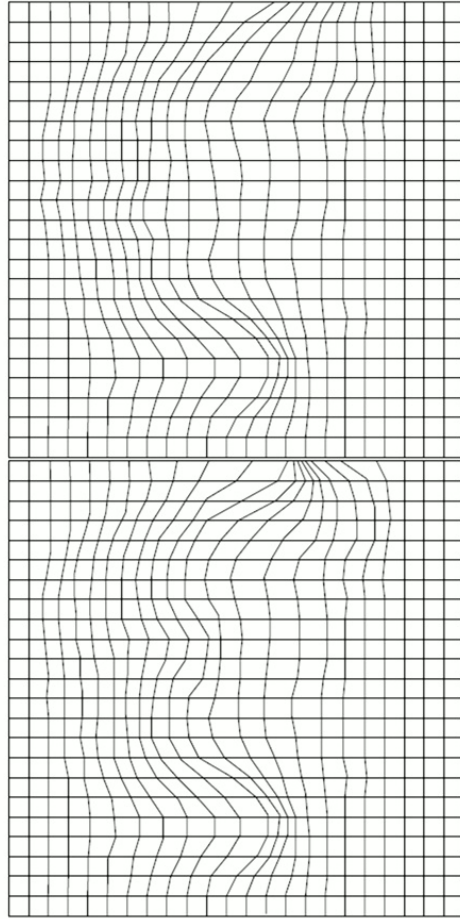
↔



$$M = \mathbb{I}$$



\* COMPOSITION WHEN  $M = \mathbb{I}$



## CONGRUENCE BY SET-STATIONARY MOTIONS

### Definition

Let  $\underline{M} = (M, A)$  be a manifold, subset pair and  $N \subset M$  a subset. A motion  $f: N \curvearrowright N$  in  $\underline{M}$  is said to be  $N$ -stationary if  $f_t(N) = N$  for all  $t \in \mathbb{I}$ . Define

$$\text{SetStat}_{\underline{M}}^N = \{f: N \curvearrowright N \in \text{Mt}_{\underline{M}}(N, N) \mid f_t(N) = N \text{ for all } t \in \mathbb{I}\}.$$

### Example

Let  $M = D^2$  and let  $\tau_{2\pi}$  denote a flow such that  $(\tau_{2\pi})_t$  is a  $2\pi t$  rotation of the disk. Now let  $N$  be a circle centred on the centre of the disk. Then  $\tau_{2\pi}: N \curvearrowright N$  is  $N$ -stationary.

### Example

Let  $M = D^2$ , the 2-disk and let  $N \subset M$  be a finite set of points. Then a motion  $f: N \curvearrowright N$  is  $N$ -stationary if and only if  $f_t(x) = x$  for all  $x \in N$  and  $t \in \mathbb{I}$ . More generally this holds if  $N$  is a totally disconnected subspace of  $M$ , e.g.  $\mathbb{Q}$  in  $\mathbb{R}$ .

## CONGRUENCE BY SET-STATIONARY MOTIONS

### Lemma

For  $N, N' \in M$ , denote by  $\overset{m}{\sim}$  the relation

$$f: N \hookrightarrow N' \overset{m}{\sim} g: N \hookrightarrow N' \text{ if } \bar{g} * f \in [\text{SetStat}_{\underline{M}}^N]_p$$

on  $\text{Mt}_{\underline{M}}(N, N')$ . This is an equivalence relation.

We call this motion-equivalence and denote by  $[f: N \hookrightarrow N']_m$  the motion-equivalence class of  $f: N \hookrightarrow N'$ .

### Idea of proof

Quotient first by path-homotopy. Then classes which intersect  $\text{SetStat}_{\underline{M}}^N(N, N)$  form a totally disconnected normal subgroupoid. Can be proved in general that for any totally disconnected, normal subgroupoid  $\mathcal{H}$  of a groupoid  $\mathcal{G}$  there is a congruence given by the relation  $g_1 \sim g_2$  if  $g_2^{-1} *_{\mathcal{G}} g_1 \in \mathcal{H}$ . This leads to an equivalent relation to the given relation.

## MOTION GROUPOID

### Theorem

Let  $\underline{M} = (M, A)$  where  $M$  is a manifold and  $A \subset M$  a subset. There is a groupoid

$$\text{Mot}_{\underline{M}} = (\mathcal{P}M, \text{Mt}_{\underline{M}}(N, N') / \overset{m}{\sim}, *, [\text{Id}_M]_m, [f]_m \mapsto [\bar{f}]_m)$$

where

- (I) objects are subsets of  $M$ ;
- (II) morphisms between subsets  $N, N'$  are motion-equivalence classes  $[f: N \curvearrowright N']_m$  of motions;
- (III) composition of morphisms is given by

$$[g: N' \curvearrowright N'']_m * [f: N \curvearrowright N']_m = [g * f: N \curvearrowright N'']_m.$$

- (IV) the identity at each object  $N$  is the motion-equivalence class of  $\text{Id}_M: N \curvearrowright N$ ,  $(\text{Id}_M)_t(m) = m$  for all  $m \in M$ ;
- (V) the inverse for each morphism  $[f: N \curvearrowright N']_m$  is the motion-equivalence class of  $\bar{f}: N' \curvearrowright N$  where  $\bar{f}_t = f_{(1-t)} \circ f_1^{-1}$ .

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## MOTION GROUPOID

### Proposition

Let  $\underline{M} = (M, A)$  where  $M$  is a manifold and  $A \subset M$  a subset, then

$$\text{Mot}_{\underline{M}} = (\mathcal{P}M, \text{Mt}_{\underline{M}}(N, N') / \overset{m}{\sim}, \cdot, [\text{Id}_M]_m, [f]_m \mapsto [f^{-1}]_m).$$

### Proof

It is sufficient to observe that motions which are path equivalent are motion equivalent. Let  $g, f$  be flows satisfying  $f \overset{p}{\sim} g$ , then  $\bar{g} * f \overset{p}{\sim} g^{-1} \cdot f \overset{p}{\sim} g^{-1} \cdot g$ , using that  $\bar{g} \overset{p}{\sim} g^{-1}$ , and  $g * f \overset{p}{\sim} g \cdot f$ . Then for all  $t \in \mathbb{I}$ ,  $(g^{-1} \cdot g)_t(N) = N$ , hence it is stationary.



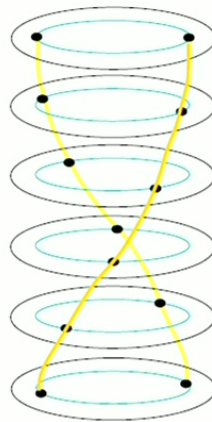
Suppose  $N \subset \mathbb{I} \setminus \{0, 1\}$  is a compact subset with a finite number of connected components i.e.  $N$  is a union of points and closed intervals.

We can assign a word in  $\{a, b\}$  to  $N$  by representing each point in  $N$  by  $a$  and each interval by  $b$ , ordered in the obvious way using the natural ordering on  $\mathbb{I}$ . Let  $N' \subset \mathbb{I} \setminus \{0, 1\}$  be another subset defined in the same way. If the word assigned to  $N$  and  $N'$  is the same,  $|\text{Mot}_{\mathbb{I}}(N, N')| = 1$ . Otherwise  $\text{Mot}_{\mathbb{I}}(N, N') = \emptyset$ .

## BRAID GROUPS AND LOOP BRAID GROUPS

### Theorem (T., Faria Martins, Martin)

Let  $n$  be a positive integer. Consider  $M = D^2$ . Given any finite subset  $K$ , with  $n$  elements, in the interior of  $D^2$ , then  $\text{Mot}_{D^2}(K, K)$  is isomorphic to the braid group in  $n$  strands (as in 'Theory of Braids', Artin). In particular the image of the class of a motion which moves points as below is an elementary braid on two strands.



Also if  $\underline{D^3} = (D^3, \partial D^3)$  and  $L \subset D^3$  is an unlink in the interior with  $n$  components, then  $\text{Mot}_{\underline{D^3}}(L, L)$  is isomorphic to the extended loop braid group<sub>24</sub> (as in 'A journey through loop braid groups', Damiani).

## RELATING MOTION GROUPOIDS

### Lemma

Let  $(M, A)$  and  $(M', A')$  be pairs such that there exists a homeomorphism  $\psi: M \rightarrow M'$  satisfying  $\psi(A) = A'$ . Then there is an isomorphism of categories

$$\Psi: \text{Mot}_{\underline{M}} \rightarrow \text{Mot}_{\underline{M}'}$$

defined as follows. On objects  $N \subset M$ ,  $\Psi(N) = \psi(N)$ . For a motion  $f: N \curvearrowright N'$  in  $M$ , let  $(\psi \circ f \circ \psi^{-1})_t = \psi \circ f_t \circ \psi^{-1}$ . Then  $\Psi$  sends the equivalence class  $[f: N \curvearrowright N']_m$  to the equivalence class  $[\psi \circ f \circ \psi^{-1}: \psi(N) \rightarrow \psi(N')]_m$ .

## RELATING AUTOMORPHISM GROUPS

### Proposition

For any pair  $(M, A)$  and subset  $N \subseteq M$  there is an involutive endofunctor on  $\text{Mot}_M$  defined by

$$\begin{aligned}\text{Mot}_M(N, N) &\cong \text{Mot}_M(M \setminus N, M \setminus N), \\ f: N \curvearrowright N' &\mapsto f: M \setminus N \curvearrowright M \setminus N' .\end{aligned}$$

Notice that generally these automorphism groups are not connected *in* the motion groupoid - this would imply  $N$  homeomorphic to  $M \setminus N$ .

# ALTERNATIVE EQUIVALENCE RELATIONS ON THE MOTION GROUPOID

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## WORLDLINES OF MOTIONS

### Definition

The worldline of a motion  $f: N \curvearrowright N'$  in a manifold  $M$  is

$$W(f: N \curvearrowright N') := \bigcup_{t \in [0,1]} f_t(N) \times \{t\} \subseteq M \times \mathbb{I}.$$

### Proposition

Let  $f, g: N \curvearrowright N'$  be motions with the same worldline, so we have

$$W(f: N \curvearrowright N') = W(g: N \curvearrowright N').$$

Then  $f: N \curvearrowright N'$  and  $g: N \curvearrowright N'$  are motion equivalent.

### Proof

For all  $t \in \mathbb{I}$ ,  $(g^{-1} \cdot f)_t(N) = g_t^{-1} \circ g_t(N) = N$ . Thus  $g^{-1} \cdot f$  is  $N$ -stationary, and hence  $\bar{g} * f$  path-homotopic to a stationary motion.

### Theorem (T., Faria Martins, Martin)

Let  $\underline{M} = (M, A)$  where  $M$  is a manifold and  $A \subset M$  a subset. Two motions  $f, f': N \hookrightarrow N'$  in  $\text{Mt}_{\underline{M}}$  are motion equivalent if, and only if, their worldlines are level preserving ambient isotopic, relative to  $(M \times (\{0, 1\})) \cup (A \times \mathbb{I})$ , pointwise.

## RELATIVE PATH-EQUIVALENCE

### Definition

Fix a pair  $(M, A)$ . Define a relation on  $\text{Mt}_{\underline{M}}(N, N')$  as follows. Let  $f: N \curvearrowright N' \stackrel{rp}{\sim} g: N \curvearrowright N'$  if the motions  $f: N \curvearrowright N'$  and  $g: N \curvearrowright N'$  are relative path-homotopic. This means there exists a continuous map

$$H: \mathbb{I} \times \mathbb{I} \rightarrow \underline{H}_M$$

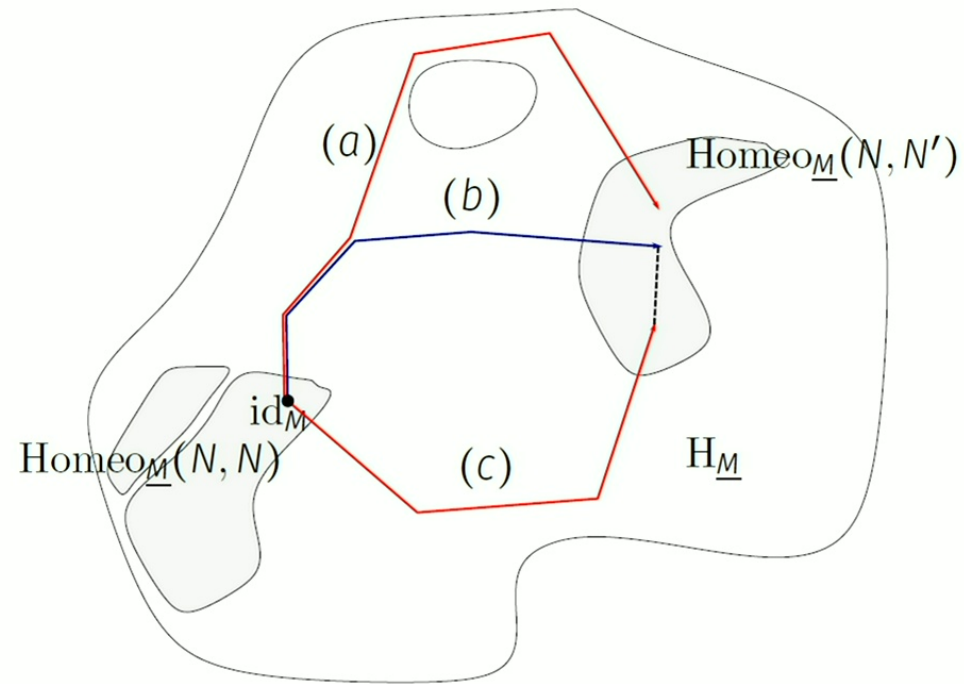
such that

- for any fixed  $s \in \mathbb{I}$ ,  $t \mapsto H(t, s)$  is a motion from  $N$  to  $N'$ ,
- for all  $t \in \mathbb{I}$ ,  $H(t, 0) = f_t$ , and
- for all  $t \in \mathbb{I}$ ,  $H(t, 1) = g_t$ .

We call such a homotopy a relative path-homotopy.



## RELATIVE PATH-EQUIVALENCE



## RELATIVE PATH-EQUIVALENCE

### Theorem (T. , Faria Martins, Martin)

For a pair  $\underline{M} = (M, A)$  and a motion  $f: N \curvearrowright N'$  in  $\underline{M}$  we have

$$[f: N \curvearrowright N']_{rp} = [f: N \curvearrowright N']_m.$$

### Key ingredients of proof

Direct construction of appropriate homotopies. Uses normality of stationary motions.

Relative path equivalence is precisely the equivalence relation in the relative fundamental group, hence

$$\text{Mot}_{\underline{M}}(N, N) = \pi_1(\text{Homeo}_{\underline{M}}(\emptyset, \emptyset), \text{Homeo}_{\underline{M}}(N, N), \text{id}_M)$$

We will need this later!

## MAPPING CLASS GROUPOID

Recall that for a pair  $\underline{M} = (M, A)$  and for subsets  $N, N' \subset M$ , morphisms in  $\text{Homeo}_{\underline{M}}(N, N')$  are triples denoted  $\mathfrak{f}: N \rightsquigarrow N'$  where  $\mathfrak{f} \in \mathbb{H}_{\underline{M}}$  and  $\mathfrak{f}(N) = N'$ . We also think of the elements of  $\text{Homeo}_{\underline{M}}(N, N')$  as the projection to the first coordinate of each triple i.e.  $\mathfrak{f} \in \mathbb{H}_{\underline{M}}$  such that  $\mathfrak{f}(N) = N'$ .

### Definition

Let  $N, N' \subset M$ . For any  $\mathfrak{f}: N \rightsquigarrow N'$  and  $\mathfrak{g}: N \rightsquigarrow N'$  in  $\text{Homeo}_{\underline{M}}(N, N')$ ,  $\mathfrak{f}: N \rightsquigarrow N'$  is said to be isotopic to  $\mathfrak{g}: N \rightsquigarrow N'$ , denoted by  $\overset{i}{\sim}$ , if there exists a continuous map

$$H: M \times \mathbb{I} \rightarrow M$$

such that

- for all fixed  $s \in \mathbb{I}$ , the map  $m \mapsto H(m, s)$  is in  $\text{Homeo}_{\underline{M}}(N, N')$ ,
- for all  $m \in M$ ,  $H(m, 0) = \mathfrak{f}(m)$ , and
- for all  $m \in M$ ,  $H(m, 1) = \mathfrak{g}(m)$ .

We call such a map an isotopy from  $\mathfrak{f}: N \rightsquigarrow N'$  to  $\mathfrak{g}: N \rightsquigarrow N'$ .

## MAPPING CLASS GROUPOIDS

### Lemma

The family of relations  $(\text{Homeo}_{\underline{M}}(N, N'), \overset{i}{\sim})$  for all pairs  $N, N' \subseteq M$  are a congruence on  $\text{Homeo}_{\underline{M}}$ .

### Theorem (T., Faria Martins, Martin)

Let  $\underline{M} = (M, A)$  be a manifold submanifold pair. There is a groupoid

$$\text{MCG}_{\underline{M}} = (\mathcal{P}M, \text{Homeo}_{\underline{M}}(N, N') / \overset{i}{\sim}, \circ, [\text{id}_M], [f] \mapsto [f^{-1}]).$$

We call this the mapping class groupoid of  $M$ .

## MAPPING CLASS GROUPOIDS

Using bijection

$$\Phi: \text{Top}(\mathbb{I}, \text{TOP}(M, M)) \rightarrow \text{Top}(M \times \mathbb{I}, M),$$

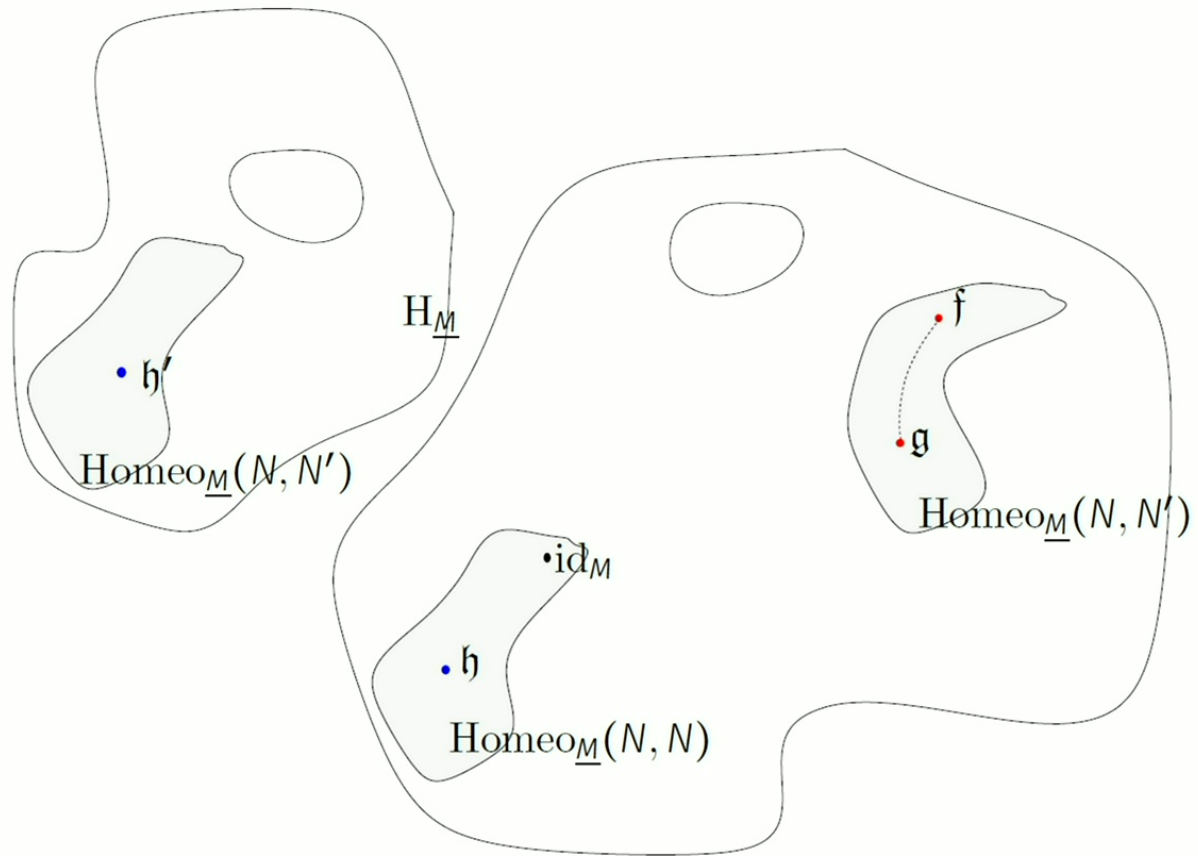
a continuous map  $M \times \mathbb{I} \rightarrow M$  which is an isotopy corresponds to a path  $\mathbb{I} \rightarrow \text{Homeo}_M(N, N')$  from  $\mathfrak{f}$  to  $\mathfrak{g}$ . Hence

### Lemma

Let  $M$  be a manifold. We have that as sets

$$\text{MCG}_{\underline{M}}(N, N') = \pi_0(\text{Homeo}_{\underline{M}}(N, N')).$$

# MAPPING CLASS GROUPOIDS



## MAPPING CLASS GROUPOID, $M = S^1$

### Example

If  $\underline{S^1} = (S^1, \emptyset)$ , we have

$$\text{MCG}_{\underline{S^1}}(\emptyset, \emptyset) = \mathbb{Z}/2\mathbb{Z}.$$

$H_{S^1}$  has two path-components, containing respectively the orientation preserving and the orientation reversing homeomorphisms from  $S^1$  to itself. Each is homotopic to  $S^1$  (Hamstrom). Therefore the homomorphism  $\pi_0(\text{Homeo}_{\underline{S^1}}(\emptyset, \emptyset)) \rightarrow \{\pm 1\} \cong \mathbb{Z}/2\mathbb{Z}$  induced by the degree homomorphism  $\text{deg}: H_{S^1} = \text{Homeo}_{\underline{S^1}}(\emptyset, \emptyset) \rightarrow \{\pm 1\}$  is an isomorphism.

## EXAMPLE

### Proposition

Let  $\underline{D^2} = (D^2, \partial D^2)$ . The morphism group  $\text{MCG}_{\underline{D^2}}(\emptyset, \emptyset)$  is trivial.

### Proof

(This follows from the Alexander trick.) Suppose we have  $f: \emptyset \sim \emptyset$  in  $\underline{D^2}$ . Define

$$f_t(x) = \begin{cases} t f(x/t) & 0 \leq |x| \leq t, \\ x & t \leq |x| \leq 1. \end{cases}$$

Notice that  $f_0 = \text{id}_{D^2}$  and  $f_1 = f$  and each  $f_t$  is continuous. Moreover:

$$\begin{aligned} H: D^2 \times \mathbb{I} &\rightarrow D^2, \\ (x, t) &\mapsto f_t(x) \end{aligned}$$

is a continuous map. So we have constructed an isotopy from any boundary preserving self-homeomorphism of  $D^2$  to  $\text{id}_{D^2}$ .



FUNCTOR FROM THE MOTION  
GROUPOID TO THE MAPPING CLASS  
GROUPOID

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## FUNCTOR $F: \text{Mot}_{\underline{M}} \rightarrow \text{MCG}_{\underline{M}}$

### Theorem (T., Faria Martins, Martin)

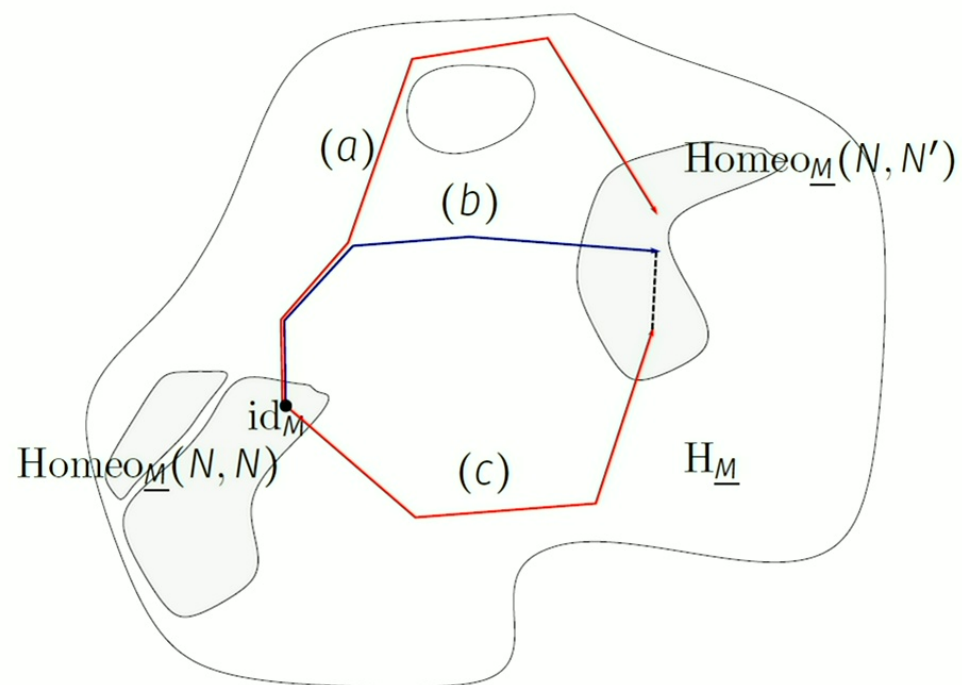
Let  $\underline{M} = (M, A)$ . There is a functor

$$F: \text{Mot}_{\underline{M}} \rightarrow \text{MCG}_{\underline{M}}$$

which is the identity on objects and on morphisms we have

$$F([f: N \hookrightarrow N']_m) = [f_1: N \xrightarrow{\sim} N']_i.$$

## WELL DEFINEDNESS OF $F$



## FUNCTOR $F: \text{Mot}_{\underline{M}} \rightarrow \text{MCG}_{\underline{M}}$

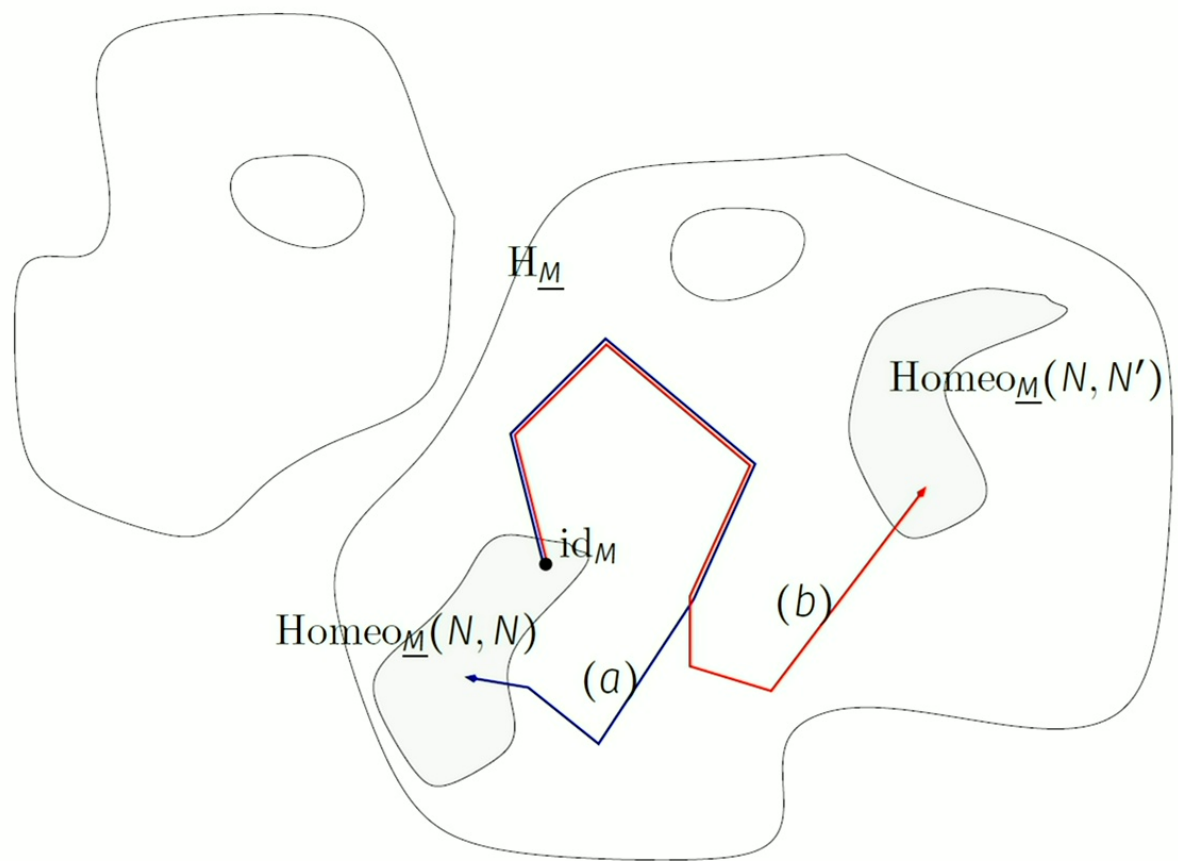
### Lemma

The functor

$$F: \text{Mot}_{\underline{M}} \rightarrow \text{MCG}_{\underline{M}}$$

is full if and only if  $\pi_0(\text{Homeo}_M(\emptyset, \emptyset), \text{id}_M)$  is trivial.

# FUNCTOR $F: \text{Mot}_{\underline{M}} \rightarrow \text{MCG}_{\underline{M}}$



## FUNCTOR $F: \text{Mot}_{\underline{M}} \rightarrow \text{MCG}_{\underline{M}}$

(Hatcher) Let  $X$  be a space,  $Y \subset X$  a subspace and  $x_0 \in Y$  a basepoint. There is a long exact sequence:

$$\begin{aligned} \dots \rightarrow \pi_n(Y, \{x_0\}) \xrightarrow{i_*^n} \pi_n(X, \{x_0\}) \xrightarrow{j_*^n} \pi_n(X, Y, \{x_0\}) \\ \xrightarrow{\partial^n} \pi_{n-1}(Y, \{x_0\}) \xrightarrow{i_*^{n-1}} \dots \xrightarrow{i_*^0} \pi_0(X, \{x_0\}). \end{aligned}$$

Maps  $i$  and  $j$  are inclusions. Maps  $\partial$  are restrictions to single face, in particular

$$\begin{aligned} \partial^1: \pi_1(X, A, \{x_0\}) &\rightarrow \pi_0(A, \{x_0\}), \\ [\gamma]_{\text{rp}} &\mapsto [\gamma(1)]_{\text{p}}. \end{aligned}$$

## FUNCTOR $F: \text{Mot}_{\underline{M}} \rightarrow \text{MCG}_{\underline{M}}$

Recall  $\text{Mot}_{\underline{M}}(N, N) = \pi_1(\text{Homeo}_{\underline{M}}(\emptyset, \emptyset), \text{Homeo}_{\underline{M}}(N, N), \text{id}_M)$  and  $\text{MCG}_{\underline{M}}(N, N) = \pi_0(\text{Homeo}_{\underline{M}}(N, N), \text{id}_M)$ .

### Lemma

Let  $\underline{M} = (M, A)$  be a manifold, subset pair, and fix a subset  $N \subset M$ . Then we have a long exact sequence

$$\begin{aligned} \dots \rightarrow \pi_n(\text{Homeo}_{\underline{M}}(N, N), \text{id}_M) &\xrightarrow{j_*^n} \pi_n(\text{Homeo}_{\underline{M}}(\emptyset, \emptyset), \text{id}_M) \xrightarrow{j_*^n} \\ \pi_n(\text{Homeo}_{\underline{M}}(\emptyset, \emptyset), \text{Homeo}_{\underline{M}}(N, N), \text{id}_M) &\xrightarrow{\partial^n} \pi_{n-1}(\text{Homeo}_{\underline{M}}(N, N), \text{id}_M) \xrightarrow{j_*^{n-1}} \\ \dots \xrightarrow{\partial^2} \pi_1(\text{Homeo}_{\underline{M}}(N, N), \text{id}_M) &\xrightarrow{j_*^1} \pi_1(\text{Homeo}_{\underline{M}}(\emptyset, \emptyset), \text{id}_M) \\ &\xrightarrow{j_*^1} \text{Mot}_{\underline{M}}(N, N) \xrightarrow{F} \text{MCG}_{\underline{M}}(N, N) \xrightarrow{j_*^0} \pi_0(\text{Homeo}_{\underline{M}}(\emptyset, \emptyset), \text{id}_M) \end{aligned}$$

where all maps are group maps and  $F$  is the appropriate restriction of the functor  $F: \text{Mot}_{\underline{M}} \rightarrow \text{MCG}_{\underline{M}}$ .

## FUNCTOR $F: \text{Mot}_{\underline{M}} \rightarrow \text{MCG}_{\underline{M}}$

### Lemma

Suppose

- $\pi_1(\text{Homeo}_{\underline{M}}(\emptyset, \emptyset), \text{id}_M)$  is trivial, and
- $\pi_0(\text{Homeo}_{\underline{M}}(\emptyset, \emptyset), \text{id}_M)$  is trivial.

Then there is a group isomorphism

$$F: \text{Mot}_{\underline{M}}(N, N) \xrightarrow{\sim} \text{MCG}_{\underline{M}}(N, N).$$



## FUNCTOR $F: \text{Mot}_{\underline{M}} \rightarrow \text{MCG}_{\underline{M}}$

### Theorem (T., Faria Martins, Martin)

Let  $M$  be a manifold. If

- $\pi_1(\text{Homeo}_{\underline{M}}(\emptyset, \emptyset), \text{id}_M)$  is trivial, and
- $\pi_0(\text{Homeo}_{\underline{M}}(\emptyset, \emptyset), \text{id}_M)$  is trivial,

the functor

$$F: \text{Mot}_{\underline{M}} \rightarrow \text{MCG}_{\underline{M}},$$

is an isomorphism of categories.

## FUNCTOR $F: \text{Mot}_{\underline{M}} \rightarrow \text{MCG}_{\underline{M}}$

### Proof

Suppose  $\pi_1(\text{Homeo}_{\underline{M}}(\emptyset, \emptyset), \text{id}_M)$  and  $\pi_0(\text{Homeo}_{\underline{M}}(\emptyset, \emptyset), \text{id}_M)$  are trivial. Already proved  $F$  is full. We check  $F$  is faithful. Let  $[f: N \curvearrowright N']_m$  and  $[f': N \curvearrowright N']_m$  be in  $\text{Mot}_{\underline{M}}(N, N')$ . If  $F([f: N \curvearrowright N']_m) = F([f': N \curvearrowright N']_m)$ , then

$$\begin{aligned} [\text{id}_M: N \curvearrowright N]_m &= F([f': N \curvearrowright N']_m)^{-1} \circ F([f: N \curvearrowright N']_m) \\ &= F([f': N \curvearrowright N']_m^{-1} * [f: N \curvearrowright N']_m) \\ &= F([\bar{f}' * f: N \curvearrowright N]_m). \end{aligned}$$

By group isomorphism this is true if and only if

$$[\bar{f}' * f: N \curvearrowright N]_m = [\text{Id}_M: N \curvearrowright N]_m$$

which is equivalent to saying  $\text{Id}_M * (\bar{f}' * f)$  is path-equivalent to a stationary motion, and hence that  $\bar{f}' * f$  is path-equivalent to the stationary motion (since  $\text{Id}_M * (\bar{f}' * f) \stackrel{p}{\sim} \bar{f}' * f$ ). So we have  $[f: N \curvearrowright N']_m = [f': N \curvearrowright N']_m$ .

## EXAMPLES: $M = D^n$

### Proposition

Let  $D^n$  be the  $n$ -disk, and  $\underline{D}^n = (D^n, \partial D^n)$ . Then we have an isomorphism

$$F: \text{Mot}_{\underline{D}^n} \rightarrow \text{MCG}_{\underline{D}^n}.$$

## EXAMPLES: $M = D^n$

### Proposition

Let  $D^n$  be the  $n$ -disk, and  $\underline{D}^n = (D^n, \partial D^n)$ . Then we have an isomorphism

$$F: \text{Mot}_{\underline{D}^n} \rightarrow \text{MCG}_{\underline{D}^n}.$$

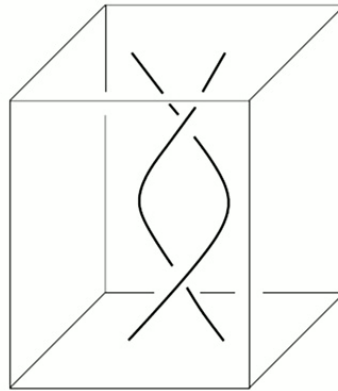
### Idea of proof

We proved that  $\text{MCG}_{\underline{D}^2}(\emptyset, \emptyset) = \pi_0(\text{Homeo}_{\underline{D}^2}(\emptyset, \emptyset), \text{id}_M)$  is trivial. Alexander trick gives same result for all  $n$ . Also  $\text{Homeo}_{\underline{D}^n}(\emptyset, \emptyset)$  is contractible (Hamstrom).

## EXAMPLES: $M = D^2$

Suppose we don't fix the boundary. Let  $P_2 \subset D^2$  be a subset consisting of two points equidistant from the centre of the disk. Let  $\tau_\pi$  be the path in  $\text{TOP}^h(D^2, D^2)$  such that  $\tau_{\pi t}$  is a  $\pi t$  rotation of the disk.

The motion  $\tau_\pi: P_2 \curvearrowright P_2$  represents a non-trivial equivalence class in  $\text{Mot}_{D^2}$ , and its end point also represents a non-trivial element of  $\text{MCG}_{D^2}$ . Now consider the motion  $\tau_\pi * \tau_\pi: P_2 \curvearrowright P_2$ .



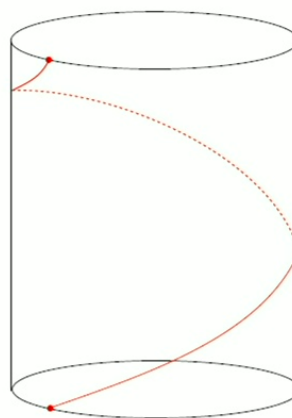
## EXAMPLES: $M = D^2$

In fact, the map  $F: \text{Mot}_{D^2} \rightarrow \text{MCG}_{D^2}$  is neither full nor faithful. The space  $\text{Homeo}_{D^2}$  is homotopy equivalent to  $S^1 \sqcup S^1$ , where the first connected component corresponds to orientation preserving homeomorphisms and the second orientation reversing (Hamstrom). Hence we have that  $\pi_1(\text{Homeo}_{D^2}(\emptyset, \emptyset), \text{id}_{D^2}) = \mathbb{Z}$  where the single generating element corresponds to the  $2\pi$  rotation. And  $\pi_0(\text{Homeo}_{D^2}(\emptyset, \emptyset), \text{id}_{D^2}) = \mathbb{Z}/2\mathbb{Z}$ . So we have an exact sequence:

$$\dots \rightarrow \pi_1(\text{Homeo}_{D^2}(N, N), \text{id}_{D^2}) \xrightarrow{j_*^1} \mathbb{Z} \rightarrow \text{Mot}_{D^2}(N, N) \rightarrow \text{MCG}_{D^2}(N, N) \rightarrow \mathbb{Z}/2\mathbb{Z}.$$

## EXAMPLES: $M = S^1$

Let  $P \subset S^1$  be a subset containing a single point in  $S^1$ . Similarly to the disk, there is a non-trivial morphism in  $\text{Mot}_{\underline{S^1}}(P, P)$  represented by a  $2\pi$  rotation of the circle.



## EXAMPLES: $M = S^1$

Note that the connected component containing  $\text{id}_{S^1}$  of  $\text{Homeo}_{S^1}(P, P)$  is contractible, (Hamstrom). In particular  $\pi_1(\text{Homeo}_{S^1}(P, P), \text{id}_{S^1})$  is trivial. We also have that  $S^1 \sqcup S^1$  is a strong deformation retract of  $\text{Homeo}_{S^1}(\emptyset, \emptyset)$ , with the first copy of  $S^1$  corresponding to orientation preserving homeomorphisms and the second to orientation reversing. Hence the sequence becomes

$$\dots \rightarrow \{1\} \rightarrow \mathbb{Z} \rightarrow \text{Mot}_{S^1}(P, P) \rightarrow \text{MCG}_{S^1}(P, P) \rightarrow \mathbb{Z}/2\mathbb{Z}.$$

The exact sequence gives an injective map

$\mathbb{Z} \cong \pi_1(\text{Homeo}_{S^1}(\emptyset, \emptyset), \text{id}_{S^1}) \rightarrow \text{Mot}_{S^1}(P, P)$ , sending  $n \in \mathbb{Z}$  to the equivalence class of the flow tracing a  $2n\pi$  rotation of the circle  $S^1$ . The space  $\text{Homeo}_{S^1}(P, P)$  only has two connected components, consisting of orientations preserving and orientation reversing homeomorphisms of  $S^1$  fixing  $P$ . Hence the exact sequence becomes:

$$\dots \rightarrow \{1\} \rightarrow \mathbb{Z} \xrightarrow{\cong} \text{Mot}_{S^1}(P, P) \xrightarrow{0} \text{MCG}_{S^1}(P, P) \xrightarrow{\cong} \mathbb{Z}/2\mathbb{Z}.$$



# MOTION GROUPOIDS

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