

Title: Advanced General Relativity - 240306

Speakers: Eric Poisson

Collection: Advanced General Relativity (PHYS7840)

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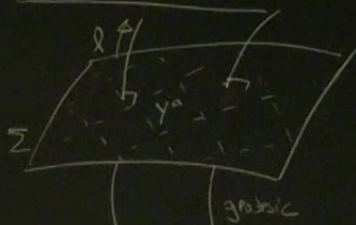
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HYPERSURFACES — EXTRINSIC CURVATURE

↳ spacelike, timelike

Intrinsic geometry of Σ

Gaussian coordinates



$$ds^2 = \epsilon dl^2 + g_{ab}(l, y) dy^a dy^b$$

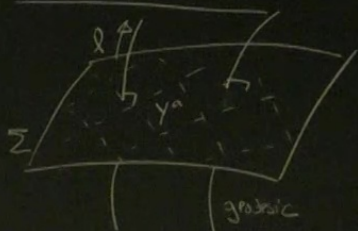
l = proper distance (or time)

$$\epsilon = \begin{cases} -1 & \Sigma \text{ spacelike} \\ +1 & \Sigma \text{ timelike} \end{cases} \quad \begin{matrix} h_{ab} = g_{ab}(l=0) \\ \text{↳ induced metric} \end{matrix}$$

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Intrinsic geometry of Σ

$$- h_{ab} \rightarrow D_a \rightarrow R^a{}_{bcd}$$

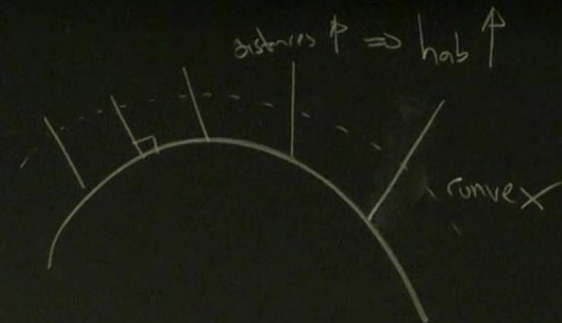
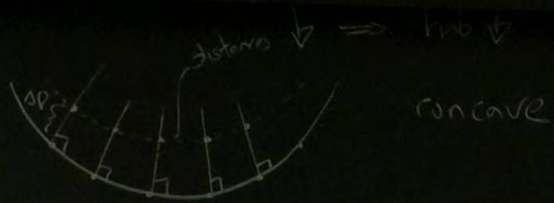
Extrinsic geometry (how surface bends)

$$- K_{ab} \text{ (extrinsic curvature)}$$

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"bending" $\sim \partial_l h_{ab} \sim K_{ab}$

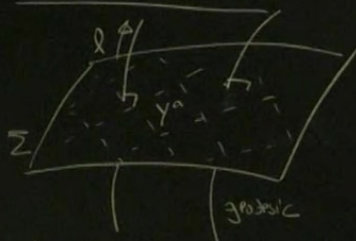
$$\text{Def: } K_{ab} = \frac{1}{2} \partial_l g_{ab} \Big|_{l=0}$$

(defined in terms of Gaussian curvatures)

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$$- K_{ab} \text{ (extrinsic curvature)}$$

$$\Gamma^a{}_{bc} \equiv \Gamma^a{}_{bc}[h] \text{ (3D)} \quad \text{vs} \quad {}^4\Gamma^{\alpha}{}_{\beta\gamma}[g]$$

Extrinsic geometry (how surface bends)

— K_{ab} (extrinsic curvature)

$$\Gamma_{bc}^a \equiv \Gamma_{bc}^a[h] \quad (3D) \quad \text{vs} \quad {}^4\Gamma_{\beta\delta}^\alpha[g]$$

$$R^a{}_{bcd} \equiv R^a{}_{bcd}[h] \quad \text{vs} \quad {}^4R^{\alpha}{}_{\beta\gamma\delta}[g]$$

$$R_{ab} \equiv R_{ab}[h] \quad \text{vs} \quad R_{\alpha\beta}[g]$$

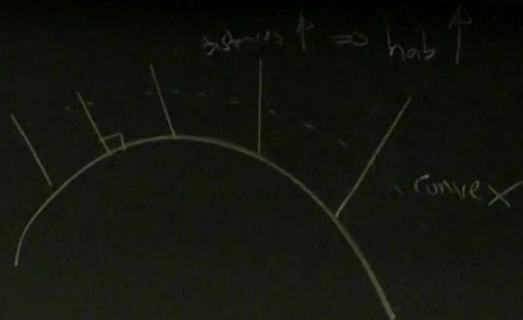
$$D_a[h] \quad \text{vs} \quad \nabla_\alpha[g]$$

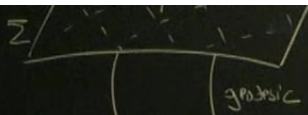


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$$h_{ab} = g_{ab}(l=0)$$

↳ induced metric

$$\Gamma_{bc}^a \equiv \Gamma_{bc}^a[h] \quad (3D)$$

$$R^a{}_{bcd} \equiv R^a{}_{bcd}[h]$$

$$R_{ab} \equiv R_{ab}[h]$$

$$D_a[h]$$

$$\text{vs } 4\Gamma_{\rho\sigma}^\alpha[g]$$

$$\text{vs } 4R^{\alpha}{}_{\rho\sigma\delta}[g]$$

$$4R_{\alpha\beta}[g]$$

$$\text{vs } \nabla_\alpha[g]$$



concave

$$\text{distances } \uparrow \Rightarrow h_{ab} \uparrow$$



convex

$$\text{Def: } K_{ab} = \frac{1}{2} \partial_l g_{ab} \Big|_{l=0}$$

(defined in terms of Gaussian curvatures)

nonvanishing Christoffel symbols:

$$4\Gamma_{ab}^d = -\frac{1}{2}\epsilon \partial_d g_{ab} \xrightarrow{\Sigma} -\epsilon K_{ab}$$

$$4\Gamma_{eb}^a \xrightarrow{\Sigma} K^a_b \equiv h^{am} K_{mb}$$

$$4\Gamma_{bc}^a = \Gamma_{bc}^a[h]$$

nonvanishing Riemann components

$$4R_{ealb} = -\frac{1}{2}\partial_e^2 g_{ab} + K_a^m K_{mb}$$

$$4R_{labc} = D_c K_{ab} - D_b K_{ac}$$

$$4R_{abcd} = R_{abcd} - \epsilon(K_{ac}K_{bd} - K_{ad}K_{bc})$$

nonvanishing Einstein components:

$$\begin{cases} 4G_{ll} = -\frac{1}{2}(\epsilon R + K_{ab}K^{ab}) \\ 4G_{ea} = D_b K^b_a - D_a K^b_b \end{cases}$$

$$4G_{ab} = \text{complicated, involves } \partial_e^2 g_{ab}$$

$$K \equiv h^{ab} K_{ab}$$

nonvanishing Christoffel symbols:

$$4\Gamma_{ab}^{\lambda} = -\frac{1}{2}\epsilon \partial_{\lambda} g_{ab} \xrightarrow{\Sigma} -\epsilon K_{ab}$$

$$4\Gamma_{eb}^a \stackrel{\Sigma}{=} K^a_b \equiv h^{am} K_{mb}$$

$$4\Gamma_{bc}^a = \Gamma_{bc}^a[h]$$

nonvanishing Riemann components

$$4R_{labb} = -\frac{1}{2} \partial_{\lambda}^2 g_{ab} + K_a^m K_{mb}$$

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nonvanishing Einstein components:

$$4G_{ll} = -\frac{1}{2} (\epsilon R + K_{ab} K^{ab} - K^2) \quad K \equiv h^{ab} K_{ab}$$

$$4G_{la} = D_b K_a^b - D_a K$$

$$4G_{ab} = \text{complicated, involves } \partial_{\lambda}^2 g_{ab}$$

$$\left. \begin{aligned} G_{ll} &= -\frac{1}{2} (\epsilon K + K_{ab} K^{ab} - K^2) & K &\equiv h^{ab} K_{ab} \\ 4G_{ab} &= D_b K_a^b - D_a K \\ 4G_{ab} &= \text{complicated, involves } \partial^2 g_{ab} \end{aligned} \right\}$$

Covariant definition of K_{ab}

Claim =
$$K_{ab} = e_a^\alpha e_b^\beta \nabla_\alpha n_\beta$$

Gaussian coordinates:
$$K_{ab} \stackrel{*}{=} \nabla_a n_b = (\cancel{D_a} n_b - 4\Gamma_{ab}^\alpha n_\alpha) = -\epsilon \Gamma_{ab}^\alpha$$

$$\stackrel{*}{=} (-\epsilon)(-\epsilon K_{ab}) = K_{ab} \quad (\text{equality in Gaussian coordinates})$$

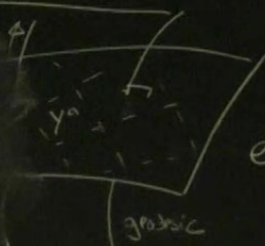
scalars \rightarrow equality in all coordinates.

4D: scalars (same in all coordinate systems x^α)
3D: tensor (symmetric)

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$$x^\alpha \equiv (t, y^a)$$

$$n^\alpha \equiv (1, 0, 0, 0)$$

$$n_\alpha \equiv (\varepsilon, 0, 0, 0)$$

$$e_a^\alpha \equiv \delta_a^\alpha$$

$$e_i^\alpha \equiv (0, 1, 0, 0)$$

$$ds^2 = g_{ab}(y) dy^a dy^b$$

(for distance (or time))

$$g_{\alpha\beta} = \begin{pmatrix} \varepsilon & 0 \\ 0 & g_{ab} \end{pmatrix}$$

Gauss-Codazzi eqns:

$$4R_{\mu\nu\rho\sigma} n^\mu e_a^\nu e_b^\rho e_c^\sigma = D_c K_{ab} - D_b K_{ac}$$

$$4R_{\mu\nu\rho\sigma} e_a^\mu e_b^\nu e_c^\rho e_d^\sigma = R_{abcd} - \varepsilon (K_{ac} K_{bd} - K_{ad} K_{bc})$$

$$4G_{\mu\nu} n^\mu n^\nu = -\frac{1}{2} (\varepsilon R + K_{ab} K^{ab} - K^2)$$

$$4G_{\mu\nu} n^\mu e_a^\nu = D_b K_a^b - D_a K$$

(covariant w.r.t. x^α)

Ex 1 is 2D sphere



$$3D : x^a = (x, y, z)$$

$$2D : y^a = (\theta, \varphi)$$

embedding relations

$$x = R \sin \theta \cos \varphi$$

$$y = R \sin \theta \sin \varphi$$

$$z = R \cos \theta$$

$$n_a = (\sin \theta \cos \varphi, \sin \theta \sin \varphi, \cos \theta)$$

$$e_a^\alpha = \partial x^\alpha / \partial y^a$$

$$h_{ab} = g_{\alpha\beta} e_a^\alpha e_b^\beta = \begin{pmatrix} R^2 & 0 \\ 0 & R^2 \sin^2 \theta \end{pmatrix}$$

$$K_{ab} = e_a^\alpha e_b^\beta \nabla_\alpha n_\beta = \begin{pmatrix} R & 0 \\ 0 & R \sin^2 \theta \end{pmatrix} = \frac{1}{R} h_{ab}$$

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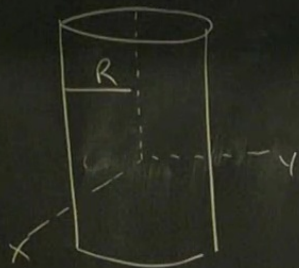
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$$K = 2/R$$

check this!

Ex 2: cylinder



$$3D: X^\alpha = (x, y, z)$$

$$2D: y^a = (z, \varrho)$$

$$\text{embedding relations: } \begin{cases} x = R \cos \varrho \\ y = R \sin \varrho \\ z = z \end{cases}$$

$$\underline{\Phi} = x^2 + y^2 = R^2$$

$$n_\alpha = (\cos \varrho, \sin \varrho, 0)$$

$$h_{ab} = \begin{pmatrix} 1 & 0 \\ 0 & R^2 \end{pmatrix}$$

$$h_{ab} dy^a dy^b = dz^2 + R^2 d\varrho^2 \quad (\text{flat})$$

$$K_{ab} = \begin{pmatrix} 0 & 0 \\ 0 & R \end{pmatrix}$$

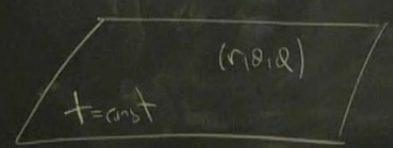
$$K = 1/R$$



$$\Phi = x^2 + y^2 = R^2 \quad | z = z$$

Ex 3: $t = \text{const}$ slice of Schwarzschild

$$ds^2 = -f dt^2 + f^{-1} dr^2 + r^2 d\Omega^2$$



$$h_{ab} = \begin{pmatrix} f^{-1} & 0 & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & r^2 \sin^2 \theta \end{pmatrix}$$

$$K_{ab} = 0 \quad (\text{static time})$$

$$X^\alpha = (t, r, \theta, \varphi) \quad \begin{cases} t = t \\ r = r \\ \theta = \theta \\ \varphi = \varphi \end{cases}$$

$$Y^\alpha = (r, \theta, \varphi)$$

