

Title: Advanced General Relativity - 240228 (afternoon)

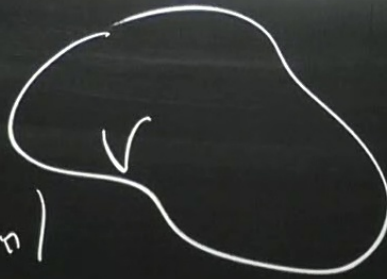
Speakers: Eric Poisson

Collection: Advanced General Relativity (PHYS7840)

Date: February 28, 2024 - 1:30 PM

URL: <https://pirsa.org/24020007>

4D Integration



Levi-Civita tensor (Volume Form)

$$\int_V f \, dV$$
$$dV = \sqrt{-g} \, d^4 X$$

$$\epsilon_{\alpha\beta\gamma\delta} \equiv \sqrt{-g} \, [\alpha\beta\gamma\delta]$$

tensor

$$\text{permutation symbol} = \begin{cases} +1 & \text{even permutation of } 0123 \\ -1 & \text{odd " " " } 0123 \\ 0 & \text{if any two indices agree} \end{cases}$$

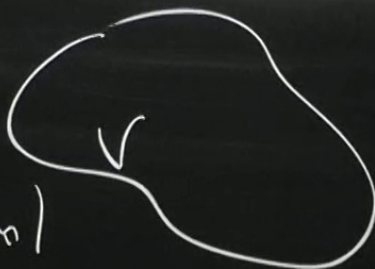
$$[0123] = 1$$

$$[1320] = -[0321] = +[0123] = 1$$

Matrix M^α_β

$$\rightarrow \det(M^\alpha_\beta) = [\alpha\beta\gamma\delta] M^\alpha_0 M^\beta_1 M^\gamma_2 M^\delta_3 = \begin{vmatrix} M^0_0 & M^0_1 & M^0_2 & M^0_3 \\ M^1_0 & M^1_1 & M^1_2 & M^1_3 \\ \vdots & \vdots & \vdots & \vdots \end{vmatrix}$$

4D Integration



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Coordinate transform: $x^\alpha \rightarrow z^\mu$

$$g_{\mu\nu} = g_{\alpha\beta} \frac{\partial x^\alpha}{\partial z^\mu} \frac{\partial x^\beta}{\partial z^\nu} \rightarrow \det(g_{\mu\nu}) = \det(g_{\alpha\beta}) \left[\det\left(\frac{\partial x^\alpha}{\partial z^\mu}\right) \right]^2$$

$$\sqrt{-\det(g_{\mu\nu})} = \sqrt{-\det(g_{\alpha\beta})} \det\left(\frac{\partial x^\alpha}{\partial z^\mu}\right)$$

$$\int_V [z] = \sqrt{-\det(g_{\mu\nu})} \int_V z$$

$$= \sqrt{-\det(g_{\alpha\beta})} \det\left(\frac{\partial x^\alpha}{\partial z^\mu}\right) \int_V z$$

$$= \int_V [x]$$

Integrate using z -coordinates: $\int \sqrt{|g|} = \sqrt{-\det(g_{\mu\nu})} \int d^4z$

Consider:

$$\epsilon_{\alpha\beta\gamma\delta} \frac{\partial X^\alpha}{\partial z^0} \frac{\partial X^\beta}{\partial z^1} \frac{\partial X^\gamma}{\partial z^2} \frac{\partial X^\delta}{\partial z^3} dz^0 dz^1 dz^2 dz^3$$

$$= \sqrt{-\det(g_{\mu\nu})} \underbrace{[\alpha\beta\gamma\delta]}_{\det(\partial X^\alpha / \partial z^\mu)} \frac{\partial X^\alpha}{\partial z^0} \frac{\partial X^\beta}{\partial z^1} \frac{\partial X^\gamma}{\partial z^2} \frac{\partial X^\delta}{\partial z^3} dz^0 dz^1 dz^2 dz^3$$

$$\det(\partial X^\alpha / \partial z^\mu) = \text{Jacobian}$$

$$= \underbrace{\sqrt{-\det(g_{\mu\nu})}}_{\sqrt{-\det(g_{\mu\nu})}} \det(\partial X^\alpha / \partial z^\mu) dz^0 dz^1 dz^2 dz^3 = \int \sqrt{|g|}$$

Consider:

$$\boxed{\epsilon_{\alpha\beta\gamma\delta} \frac{\partial X^\alpha}{\partial z^0} \frac{\partial X^\beta}{\partial z^1} \frac{\partial X^\gamma}{\partial z^2} \frac{\partial X^\delta}{\partial z^3} dz^0 dz^1 dz^2 dz^3}$$

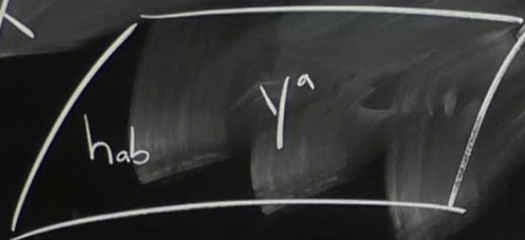
$$= \sqrt{-\det(g_{\alpha\beta})} \underbrace{[\alpha\beta\gamma\delta]}_{\det(\partial X^\alpha / \partial z^\mu)} \frac{\partial X^\alpha}{\partial z^0} \frac{\partial X^\beta}{\partial z^1} \frac{\partial X^\gamma}{\partial z^2} \frac{\partial X^\delta}{\partial z^3} dz^0 dz^1 dz^2 dz^3$$

$$\det(\partial X^\alpha / \partial z^\mu) = \text{Jacobian}$$

$$= \underbrace{\sqrt{-\det(g_{\alpha\beta})} \det(\partial X^\alpha / \partial z^\mu)}_{\sqrt{-\det(g_{\mu\nu})}} dz^0 dz^1 dz^2 dz^3 = dz^0 dz^1 dz^2 dz^3 = dz^4$$

3D \rightarrow hypersurface

x^α



Consider:

$$\epsilon_{\alpha\beta\gamma\delta} \frac{\partial x^\beta}{\partial y^1} \frac{\partial x^\gamma}{\partial y^2} \frac{\partial x^\delta}{\partial y^3} = d\Sigma_\alpha$$

\hookrightarrow vector-valued volume element on Σ

$$d\Sigma = \sqrt{\epsilon} \det(h_{ab}) dy^1 dy^2 dy^3$$

CAUTION

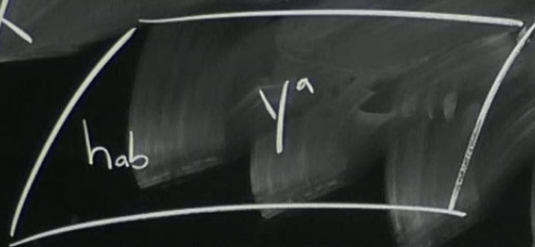
TO AVOID THE CAUTION, THE USER MUST READ THE INSTRUCTIONS OF THE BOARD.
SI È NECESSARIO IL PRIMO
LIVELLO DI INSTRUZIONE.
ATTENZIONE: LEGGERE LE ISTRUZIONI.

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3D \rightarrow hypersurface

x^α



Consider:

$$\epsilon_{\alpha\beta\gamma} \frac{\partial x^\beta}{\partial y^1} \frac{\partial x^\gamma}{\partial y^2} \frac{\partial x^\alpha}{\partial y^3} = \delta \Sigma_\alpha$$

\hookrightarrow vector-valued volume element on Σ

$$\delta \Sigma = \sqrt{\epsilon \det(h_{ab})} dy^1 dy^2 dy^3$$

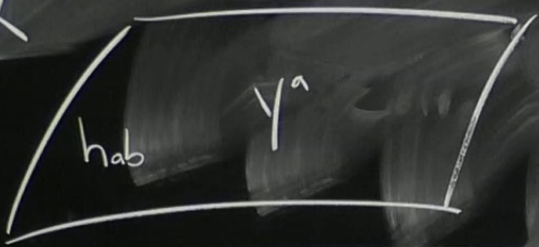
undirected surface element

$$\rightarrow n_\alpha \delta \Sigma$$

directed surface element

3D \rightarrow hypersurface

x^α



Consider:

$$\epsilon_{\alpha\beta\gamma\delta} \frac{\partial x^\beta}{\partial y^1} \frac{\partial x^\gamma}{\partial y^2} \frac{\partial x^\delta}{\partial y^3} = \partial \Sigma_\alpha$$

\hookrightarrow vector-valued volume element on Σ

$$\partial \Sigma = \sqrt{\epsilon \det(h_{ab})} dy^1 dy^2 dy^3$$

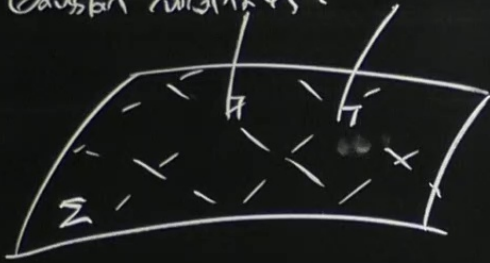
undirected surface element

$$\rightarrow n_\alpha \partial \Sigma$$

directed surface element

$$\partial \Sigma_\alpha = \epsilon n_\alpha \partial \Sigma$$

Gaussian coordinates:



$$x^\alpha \equiv (t, y^a)$$

$$n^\alpha \equiv (1, 0, 0, 0)$$

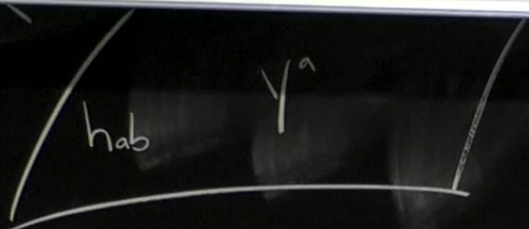
$$n_\alpha \equiv (\varepsilon, 0, 0, 0)$$

$$e_i^\alpha \equiv (0, 1, 0, 0), \dots$$

$$\sqrt{-g} \equiv \sqrt{-\varepsilon h}$$

$$\begin{aligned} \delta \Sigma_\alpha &= \varepsilon_{\alpha p s \delta} e_1^p e_2^s e_3^\delta \delta^3 y = \sqrt{-g} [\alpha p s \delta] e_1^p e_2^s e_3^\delta \delta^3 y \\ &\equiv \sqrt{-\varepsilon h} [\alpha 1 2 3] \delta^3 y \equiv \sqrt{-\varepsilon h} \delta^4 y \delta_\alpha^l \end{aligned}$$

$$n_\alpha \delta \Sigma^\alpha = \varepsilon \delta_\alpha^l$$



$\epsilon_{\beta\gamma\delta} \frac{\partial x^\beta}{\partial y^1} \frac{\partial x^\gamma}{\partial y^2} \frac{\partial x^\delta}{\partial y^3} = \epsilon_{\beta\gamma\delta} \frac{\partial x^\beta}{\partial y^1} \frac{\partial x^\gamma}{\partial y^2} \frac{\partial x^\delta}{\partial y^3}$
 ↳ vector-valued volume element on Σ

$$\delta\Sigma = \sqrt{-\epsilon} \det(h_{ab}) \, dy^1 dy^2 dy^3$$

unoriented surface element

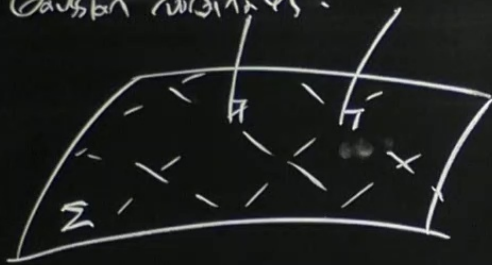
$$\rightarrow n_\alpha \delta\Sigma$$

oriented surface element

$$\sqrt{-\epsilon} h = \begin{cases} \sqrt{h} & \text{spacelike} \\ \sqrt{-h} & \text{timelike} \end{cases}$$

$$\delta\Sigma_\alpha = \epsilon n_\alpha \delta\Sigma$$

Gaussian coordinates:



$$x^\alpha = (t, y^a)$$

$$n^\alpha = (1, 0, 0, 0)$$

$$n_\alpha = (\epsilon, 0, 0, 0)$$

$$e_i^\alpha = (0, 1, 0, 0), \dots$$

$$\sqrt{-g} = \sqrt{-\epsilon h}$$

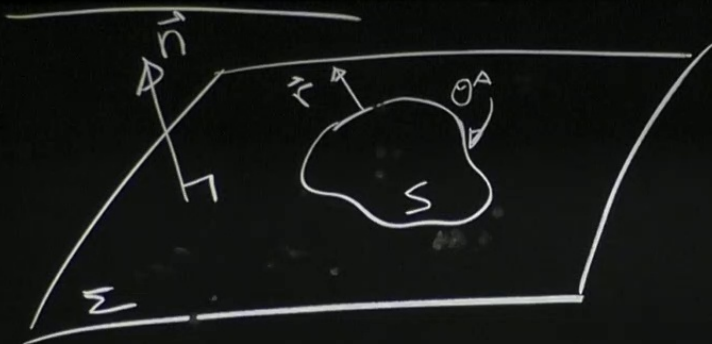
$$\begin{aligned} \partial \bar{Z}_\alpha &= \epsilon_{\alpha p q r} e_1^p e_2^q e_3^r \delta^3 y = \sqrt{-g} [\alpha p q r] e_1^p e_2^q e_3^r \delta^3 y \\ &\stackrel{*}{=} \sqrt{-\epsilon h} [\alpha 1 2 3] \delta^3 y \stackrel{*}{=} \sqrt{-\epsilon h} \delta^4 y \delta_\alpha^l \end{aligned}$$

$$n_\alpha \partial \bar{Z} = \epsilon \delta_\alpha^l \sqrt{-\epsilon h} \delta^3 y$$

$$\partial \bar{Z}_\alpha \stackrel{*}{=} \epsilon n_\alpha \partial \bar{Z}$$

$$\partial \bar{Z}_\alpha = \epsilon n_\alpha \partial \bar{Z}$$

2D surface



two normals: n^α , r^α
 r^α normal to S in Σ
 \downarrow
 normal to Σ

$$n_\alpha n^\alpha = \epsilon$$

$$r_\alpha r^\alpha = -\epsilon$$

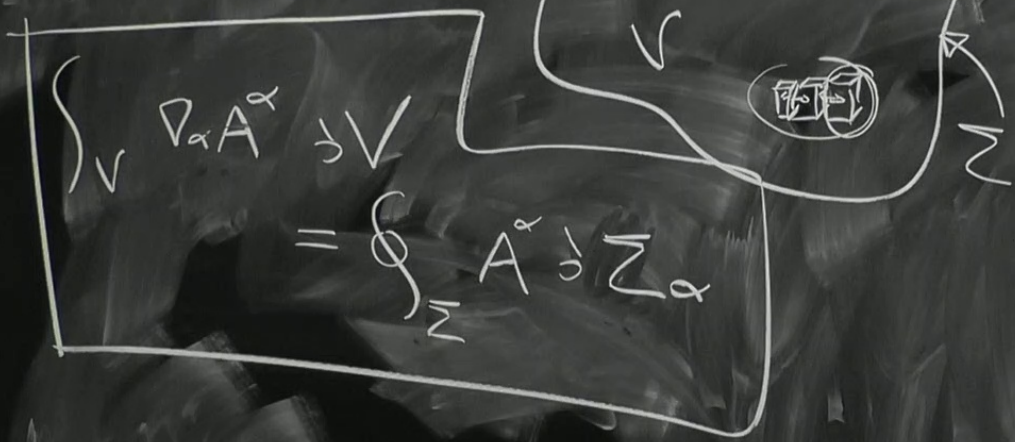
surface element: $\delta S_{\alpha\beta} = \epsilon_{\alpha\beta\gamma\delta} \frac{\partial X^\gamma}{\partial \theta^2} \frac{\partial X^\delta}{\partial \theta^3} = \text{antisymmetric in } \alpha, \beta$

$$= (r_\alpha n_\beta - n_\alpha r_\beta) \delta S$$

$$\delta S = \sqrt{\det(g_{AB})} \delta^2 \theta$$

\hookrightarrow induced metric in θ^A coordinates.

Gauss's Theorem



$$\int_V \nabla_\alpha A^\alpha \rightarrow V$$

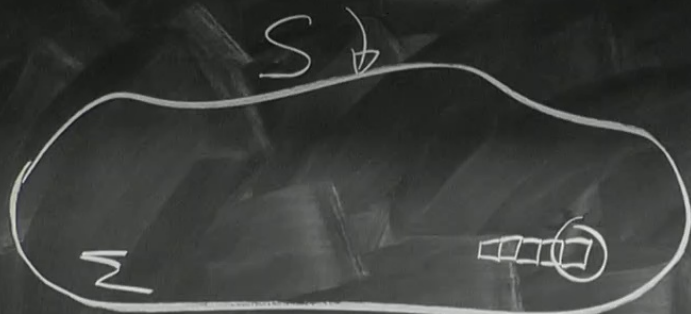
$$= \oint_\Sigma A^\alpha \rightarrow \Sigma_\alpha$$

V : 4D region in spacetime

Σ : $\partial V \equiv$ boundary of V
 \equiv hypersurface

A^α - arbitrary vector field

Stokes's Theorem



Σ : hypersurface (3D)

S : boundary = $\partial\Sigma$ (2D)

$B^{\alpha\beta}$: antisymmetric tensor fields

$$\int_{\Sigma} \nabla_{\mu} B^{\alpha\beta} \partial\Sigma_{\alpha} = \frac{1}{2} \oint_S B^{\alpha\beta} \partial S_{\alpha\beta}$$