

Title: Advanced General Relativity - 240228

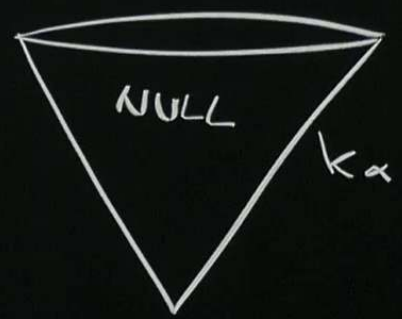
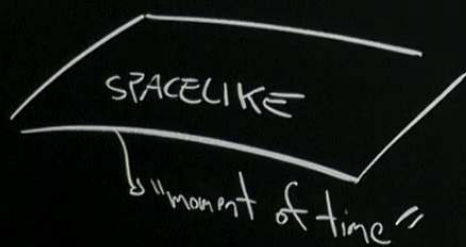
Speakers: Eric Poisson

Collection: Advanced General Relativity (PHYS7840)

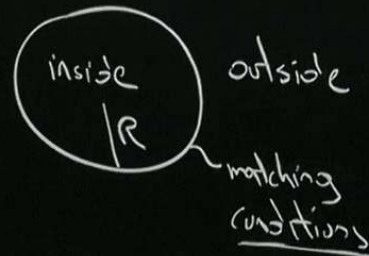
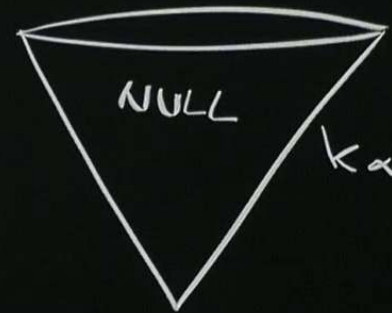
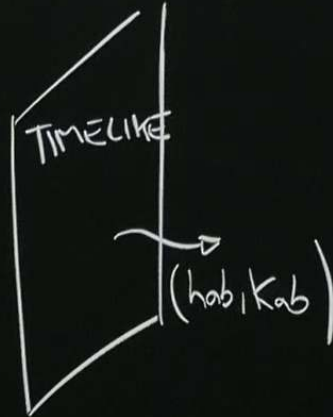
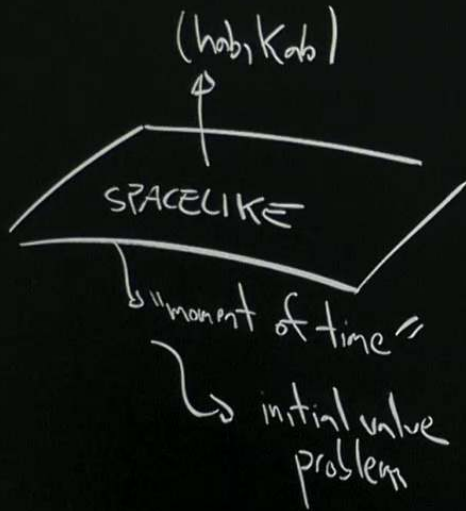
Date: February 28, 2024 - 10:30 AM

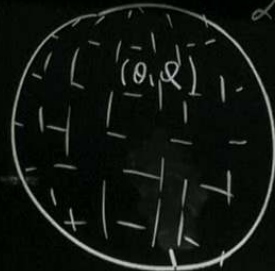
URL: <https://pirsa.org/24020003>

HYPERSURFACES (3D submanifold)



# HYPERSURFACES (3D submanifold)





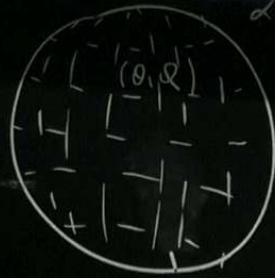
2D sphere in 3D space

constraint on coordinates  $\equiv X^2 + Y^2 + Z^2 = R^2$

embedding relations:

$$\begin{cases} X = R \sin \theta \cos \varphi \\ Y = R \sin \theta \sin \varphi \\ Z = R \cos \theta \end{cases}$$

constraint:  $\Phi(X^\alpha) = 0$



2D sphere in 3D space

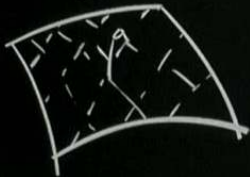
constraint on coordinates =  $X^2 + Y^2 + Z^2 = R^2$

embedding relations :

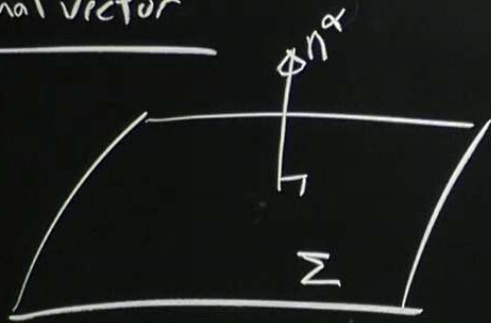
$$\begin{cases} X = R \sin \theta \cos \varphi \\ Y = R \sin \theta \sin \varphi \\ Z = R \cos \theta \end{cases}$$

constraint :  $\Phi(X^\alpha) = \text{const.}$

embedding rlns :  $X^\alpha = X^\alpha(Y^a)$



Normal vector



Normal vector — unit vector  $n_\alpha n^\alpha = \epsilon = \begin{cases} -1 & \Sigma \text{ spacelike} \\ +1 & \Sigma \text{ timelike} \end{cases}$   
— point in direction of increasing  $\Phi$  (convention)

$$n_\alpha \propto \nabla_\alpha \Phi$$

$$\text{Ex: } t = \text{const}$$

$$\Phi = t = \text{const}$$

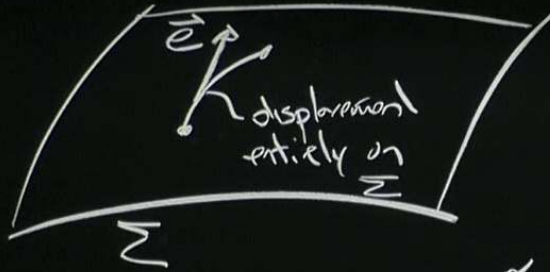
$$\nabla_\alpha \Phi = (1, 0, 0, 0)$$

$$n_\alpha = (-1, 0, 0, 0)$$

$$n^\alpha = (1, 0, 0, 0)$$

$$n_\alpha = \epsilon \rho \nabla_\alpha \Phi$$
$$\rho = \left| \sum^{\mu\nu} \nabla_\mu \Phi \nabla_\nu \Phi \right|^{-1/2}$$

tangent vectors



Intrinsic displacement

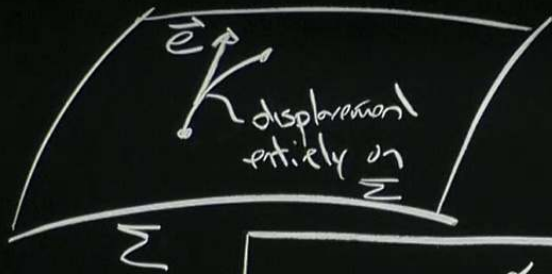
$$x^\alpha = x^\alpha(y^a) \rightarrow \text{curves on } \Sigma$$

$$dx^\alpha = \left( \frac{\partial x^\alpha}{\partial y^a} \right) dy^a = e_a^\alpha dy^a$$

$$e_a^\alpha \equiv \frac{\partial x^\alpha}{\partial y^a} \equiv \text{tangent vectors (basis on } \Sigma \text{)}$$

→ spacetime vector  
hypersurface co-vector

## tangent vectors



## Intrinsic displacement

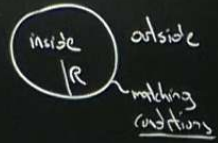
$$x^\alpha = x^\alpha(y^a) \rightarrow \text{curves on } \Sigma$$

$$dx^\alpha = \left( \frac{\partial x^\alpha}{\partial y^a} \right) dy^a = e_a^\alpha dy^a$$

$$\boxed{e_a^\alpha \equiv \frac{\partial x^\alpha}{\partial y^a}} \equiv \text{tangent vectors (basis on } \Sigma)$$

→ spacetime vector  
hypersurface co-vector.

"amount of time"  
 ↳ initial value problem



2D sphere in 3D space



constraint on coordinates:  $x^2 + y^2 + z^2 = R^2$

embedding relations:  $\begin{cases} x = R \sin \theta \cos \varphi \\ y = R \sin \theta \sin \varphi \\ z = R \cos \theta \end{cases}$

constraint:  $\Phi(x^\alpha) = \text{const} \checkmark$

embedding rhs:  $X^\alpha = X^\alpha(\vartheta, \varphi) = R \sin \theta$



$n_\alpha = (-1, 0, 0, 0)$   
 $n^\alpha = (1, 0, 0, 0)$

Sphere

$\Phi = x^2 + y^2 + z^2 \quad \nabla_\alpha \Phi = (2x, 2y, 2z)$

$\rightarrow n_\alpha = (x/R, y/R, z/R)$

$\begin{cases} e^a_\theta = (R \cos \theta \cos \varphi, R \cos \theta \sin \varphi, -R \sin \theta) = (R \sin \theta \cos \varphi, R \sin \theta \sin \varphi, R \cos \theta) \\ e^a_\varphi = (-R \sin \theta \sin \varphi, R \sin \theta \cos \varphi, 0) \end{cases}$

# Sphere

$$\Phi = x^2 + y^2 + z^2 \quad \nabla_x \Phi = (2x, 2y, 2z)$$

$$\rightarrow n_x = (x/R, y/R, z/R)$$

$$\left\{ \begin{array}{l} e^a_\theta = (R \cos \theta \cos \varphi, R \cos \theta \sin \varphi, -R \sin \theta) \\ e^a_\varphi = (-R \sin \theta \sin \varphi, R \sin \theta \cos \varphi, 0) \end{array} \right. = (R \sin \theta \cos \varphi, R \sin \theta \sin \varphi, R \cos \theta)$$

$$e^a_\varphi = (-R \sin \theta \sin \varphi, R \sin \theta \cos \varphi, 0)$$

$$h_{\theta\theta} = R^2$$

$$h_{\varphi\varphi} = R^2 \sin^2 \theta$$

$$h_{\theta\varphi} = 0$$

$$ds^2|_{\text{sphere}} = R^2 (\dot{\theta}^2 + \sin^2 \theta \dot{\varphi}^2)$$

Intrinsic geometry:  $h_{ab} \rightarrow |bc \rightarrow R_{bcd}$

$h^{ab}$  = inverse metric

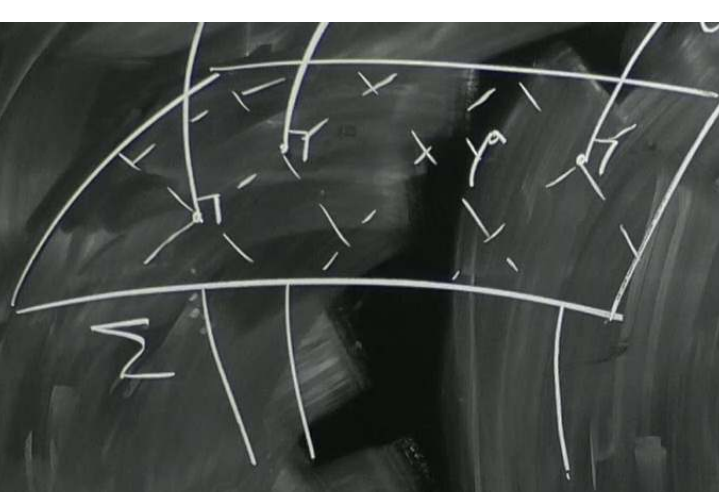
$$h^{ab} h_{bc} = \delta^a_c$$

$$h = \det(h_{ab})$$

completeness relation:

$$g^{\alpha\beta} = \epsilon n^\alpha n^\beta + \underbrace{h^{ab} e_a^\tau e_b^\beta}_{\text{"ppf"}}$$

check this!



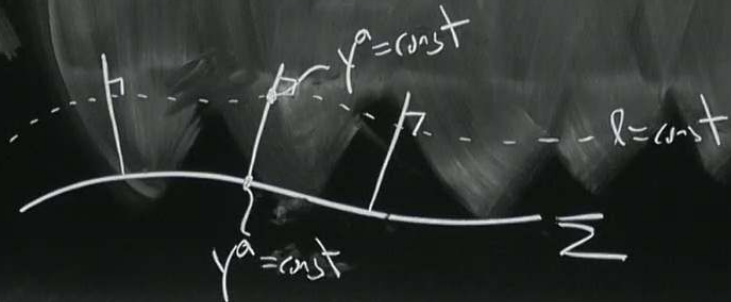
CS of orthogonal geodesics

$l \equiv$  proper time (or distance) measured  
 on each orthogonal geodesic,  
 with  $l=0$  on  $\Sigma$

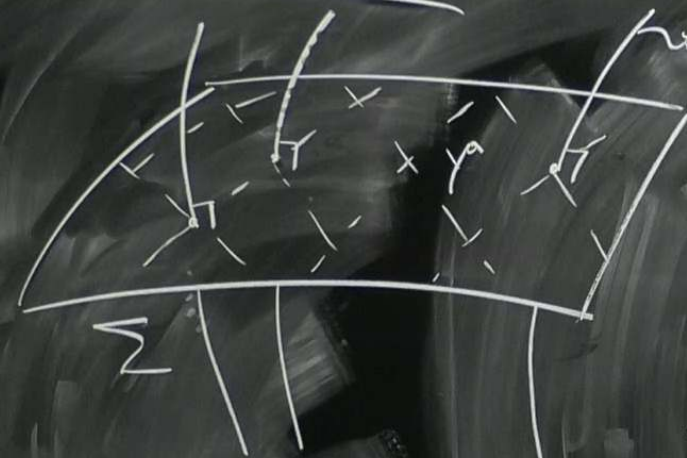
$$x^\alpha = (l, y^a)$$

$\Sigma$

$$x^a = (l, y^a)$$



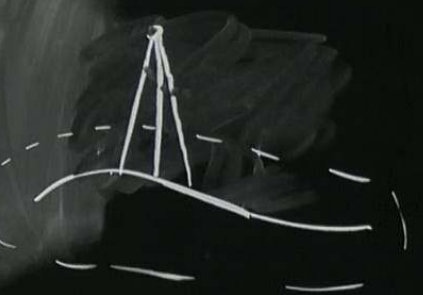
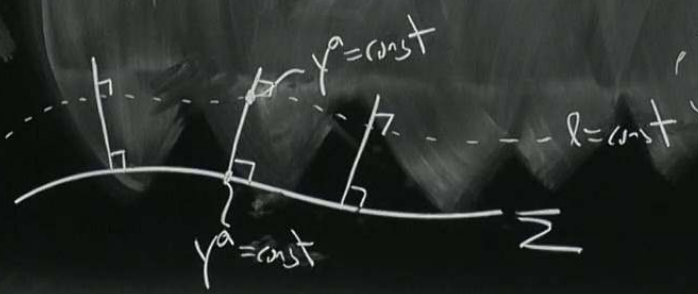
orthogonal normal coordinates



orthogonal geodesics

$l \equiv$  proper time (or distance) measured on each orthogonal geodesic, with  $l=0$  on  $\Sigma$

$$x^\alpha = (l, y^a)$$



CAUTION

$$\delta S^2 = \varepsilon \delta l^2 + \gamma_{ab}(l, y) \delta y^a \delta y^b$$

$$X^\alpha \equiv (l, y^a)$$

$$h_{ab} = \gamma_{ab}(l=0, y)$$

$$n^\alpha \equiv (1, 0, 0, 0)$$

$$\det(\gamma_{\alpha\beta}) \equiv \varepsilon \det(\gamma_{ab})$$

$$n_\alpha \equiv (\varepsilon, 0, 0, 0)$$

$$e_1^\alpha \equiv (0, 1, 0, 0)$$

$$\delta V = \sqrt{-3} \delta^4 X$$

$$e_2^\alpha \equiv (0, 0, 1, 0)$$

$$e_3^\alpha \equiv (0, 0, 0, 1)$$

CAUTION

$$ds^2 = \varepsilon dl^\alpha + g_{ab}(l, y) dy^a dy^b$$

$$X \equiv (l, y^a)$$

$$h_{ab} = g_{ab}(l=0, y)$$

$$n^\alpha \equiv (1, 0, 0, 0)$$

$$n_\alpha \equiv (\varepsilon, 0, 0, 0)$$

$$\det(g_{\alpha\beta}) \equiv \varepsilon \det(g_{ab})$$

$$e_1^\alpha \equiv (0, 1, 0, 0)$$

$$e_2^\alpha \equiv (0, 0, 1, 0)$$

$$e_3^\alpha \equiv (0, 0, 0, 1)$$

$$\partial V = \sqrt{-g} \partial^\alpha X$$

$$\equiv \sqrt{-\varepsilon h} \partial^\alpha X$$

CAUTION  
 Do not touch the screen when the screen is on. Please do not touch the screen when the screen is on.  
 To be used only for display  
 when the screen is on.

$$e_2^{\alpha} =^* (0, 1, 0, 1, 1, 0)$$

$$e_3^{\alpha} =^* (0, 1, 0, 1, 0, 1)$$

$$=^* \sqrt{-\epsilon h} \delta^{\alpha X}$$

Spacetime volume element in Gaussian coordinates, at  $\Sigma$

$$\delta V =^* \sqrt{-\epsilon h} \delta x^3 \delta y^3$$

$$n_{\alpha}^{\alpha} = \epsilon$$

$$-\epsilon h : \begin{cases} h & (\text{spacelike}) \\ -h & (\text{timelike}) \end{cases}$$

CAUTION