

Title: Advanced General Relativity - 240117

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Collection: Advanced General Relativity (PHYS7840)

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Lie derivative

$$\mathcal{L}_\xi A^\alpha = \xi^\beta \partial_\beta A^\alpha - A^\beta \partial_\beta \xi^\alpha$$

$$\mathcal{L}_\xi \omega_\alpha = \xi^\beta \partial_\beta \omega_\alpha + \omega_\beta \partial_\alpha \xi^\beta$$

$$\mathcal{L}_\xi T^{\alpha\beta} = \xi^\gamma \partial_\gamma T^{\alpha\beta} - T^{\gamma\beta} \partial_\gamma \xi^\alpha - T^{\alpha\gamma} \partial_\gamma \xi^\beta$$

$$\mathcal{L}_\xi T^\alpha_\beta = \xi^\gamma \partial_\gamma T^\alpha_\beta - T^\delta_\beta \partial_\gamma \xi^\alpha + T^\alpha_\gamma \partial_\beta \xi^\gamma$$

$$\mathcal{L}_\xi T_{\alpha\beta} = \xi^\gamma \partial_\gamma T_{\alpha\beta} + T_{\delta\beta} \partial_\alpha \xi^\delta + T_{\alpha\gamma} \partial_\beta \xi^\gamma$$



$$\partial_{\xi} T_{\beta} = \xi^{\alpha} \partial_{\alpha} T_{\beta} - T_{\beta}^{\alpha} \partial_{\alpha} \xi + T_{\alpha\beta} \partial_{\alpha} \xi$$

$$\partial_{\xi} T_{\alpha\beta} = \xi^{\gamma} \partial_{\gamma} T_{\alpha\beta} + T_{\beta\gamma} \partial_{\alpha} \xi^{\gamma} + T_{\alpha\gamma} \partial_{\beta} \xi^{\gamma}$$

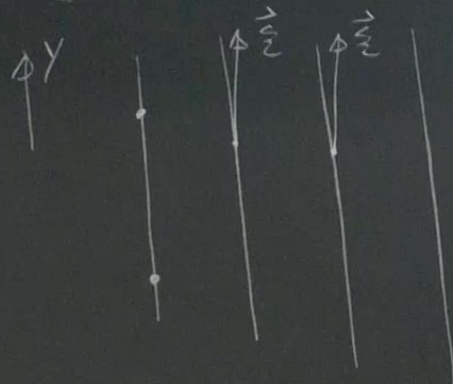
Killing vectors

In some coordinates (t, x, y, z) , suppose that $\partial_y g_{\mu\nu} \stackrel{*}{=} 0$

$$\mathcal{L}_{\xi} T_{\beta} = \xi^{\alpha} \partial_{\alpha} T_{\beta} - T_{\beta}^{\alpha} \partial_{\alpha} \xi + T_{\alpha\beta} \partial_{\alpha} \xi$$

$$\mathcal{L}_{\xi} T_{\alpha\beta} = \xi^{\gamma} \partial_{\gamma} T_{\alpha\beta} + T_{\alpha\beta} \partial_{\alpha} \xi^{\gamma} + T_{\alpha\gamma} \partial_{\beta} \xi^{\gamma}$$

Killing vectors



In some coordinates (t, x, y, z) , suppose that $\partial_y g_{\mu\nu} \stackrel{*}{=} 0$

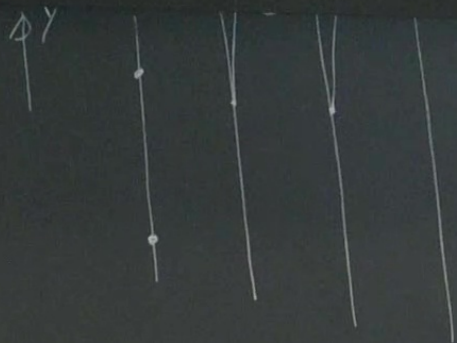
$$\xi^{\mu} \stackrel{*}{=} (0, 0, 1, 0)$$

$$\mathcal{L}_{\xi} g_{\mu\nu} = \underbrace{\xi^{\lambda} \partial_{\lambda} g_{\mu\nu}}_{\substack{\partial_y g_{\mu\nu} \\ \stackrel{*}{=} 0}} + \underbrace{g_{\lambda\nu} \partial_{\mu} \xi^{\lambda}}_{\stackrel{*}{=} 0} + \underbrace{g_{\mu\lambda} \partial_{\nu} \xi^{\lambda}}_{\stackrel{*}{=} 0}$$

$$\stackrel{*}{=} 0$$

$$\mathcal{L}_\xi T_\beta = \xi^\alpha \partial_\alpha T_\beta - T_\beta^\alpha \partial_\alpha \xi + T_{\alpha\beta} \partial_\alpha \xi$$

$$\mathcal{L}_\xi T_{\alpha\beta} = \xi^\gamma \partial_\gamma T_{\alpha\beta} + T_{\alpha\beta} \partial_\alpha \xi^\gamma + T_{\alpha\gamma} \partial_\beta \xi^\gamma$$



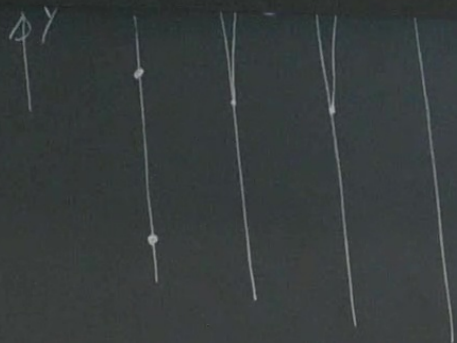
$$\xi = (\xi^\alpha, \xi^\beta)$$

$$\mathcal{L}_\xi g_{\mu\nu} = \underbrace{\xi^\lambda \partial_\lambda g_{\mu\nu}}_{\stackrel{*}{=} 0} + \underbrace{g_{\lambda\nu} \partial_\mu \xi^\lambda}_{\stackrel{*}{=} 0} + \underbrace{g_{\mu\lambda} \partial_\nu \xi^\lambda}_{\stackrel{*}{=} 0}$$

$$\stackrel{*}{=} 0 \rightarrow \boxed{\mathcal{L}_\xi g_{\alpha\beta} = 0}$$

$$\mathcal{L}_{\xi} T_{\beta} = \xi^{\alpha} \partial_{\alpha} T_{\beta} - T_{\beta}^{\alpha} \partial_{\alpha} \xi^{\gamma} + T_{\alpha\beta} \partial_{\gamma} \xi^{\alpha}$$

$$\mathcal{L}_{\xi} T_{\alpha\beta} = \xi^{\gamma} \partial_{\gamma} T_{\alpha\beta} + T_{\alpha\beta} \partial_{\gamma} \xi^{\gamma} + T_{\alpha\gamma} \partial_{\beta} \xi^{\gamma}$$



$$\mathcal{L}_{\xi} g_{\mu\nu} = \underbrace{\xi^{\lambda} \partial_{\lambda} g_{\mu\nu}}_{\substack{= 0 \\ \text{in}}} + \underbrace{g_{\lambda\nu} \partial_{\mu} \xi^{\lambda}}_{= 0} + \underbrace{g_{\mu\lambda} \partial_{\nu} \xi^{\lambda}}_{= 0}$$

$\stackrel{*}{=} 0$

\rightarrow

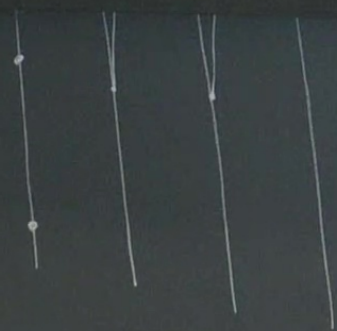
$$\boxed{\mathcal{L}_{\xi} g_{\alpha\beta} = 0}$$

in all coordinates

$$\mathcal{L}_{\xi} T_{\beta} = \xi^{\alpha} \partial_{\alpha} T_{\beta} - T_{\beta}^{\alpha} \partial_{\alpha} \xi + T_{\alpha\beta} \partial_{\alpha} \xi$$

$$\mathcal{L}_{\xi} T_{\alpha\beta} = \xi^{\gamma} \partial_{\gamma} T_{\alpha\beta} + T_{\alpha\beta} \partial_{\alpha} \xi^{\gamma} + T_{\alpha\gamma} \partial_{\beta} \xi^{\gamma}$$

ϕ



$$\mathcal{L}_{\xi} g_{\mu\nu} = \underbrace{\xi^{\lambda} \partial_{\lambda} g_{\mu\nu}}_{\substack{= 0 \\ *}} + \underbrace{g_{\lambda\nu} \partial_{\mu} \xi^{\lambda}}_{= 0} + \underbrace{g_{\mu\lambda} \partial_{\nu} \xi^{\lambda}}_{= 0}$$

$\stackrel{*}{=} 0$

\rightarrow

$$\mathcal{L}_{\xi} g_{\alpha\beta} = 0 \quad \text{in all coordinates}$$

$\xi^{\alpha} \equiv$ killing vector

$$\mathcal{L}_\xi | \beta = \xi^\alpha \partial_\alpha | \beta - | \beta \partial_\alpha \xi^\alpha + | \alpha \partial_\beta \xi^\alpha$$

$$\mathcal{L}_\xi T_{\alpha\beta} = \xi^\alpha \partial_\alpha T_{\alpha\beta} + T_{\alpha\beta} \partial_\alpha \xi^\alpha + T_{\alpha\gamma} \partial_\beta \xi^\gamma$$

$$0 = \mathcal{L}_\xi g_{\alpha\beta} = \xi^\alpha \underbrace{\partial_\alpha g_{\alpha\beta}}_0 + \underbrace{g_{\alpha\beta} \partial_\alpha \xi^\alpha}_{\partial_\alpha (g_{\alpha\beta} \xi^\alpha)} + \underbrace{g_{\alpha\gamma} \partial_\beta \xi^\gamma}_{\partial_\beta (g_{\alpha\gamma} \xi^\gamma)}$$

$$\rightarrow \boxed{\nabla_\alpha \xi_\beta + \nabla_\beta \xi_\alpha = 0} \text{ killing's equation}$$

$$\nabla(\alpha \xi_\beta) = 0$$

$$\nabla_\alpha \xi_\beta = \text{antisymmetric}$$

Example - Minkowski metric

$$ds^2 = -dt^2 + dx^2 + dy^2 + dz^2$$

$\frac{10}{}$ { 4 translational Killing vect
3 rotational KV
3 boost KV

Example - spherical symmetry, static

$$ds^2 = -A(r) dt^2 + B(r) dr^2 + r^2 (d\theta^2 + \sin^2\theta d\phi^2)$$

$$\begin{aligned} \xi_{(t)}^\alpha &= (1, 0, 0, 0) \checkmark & \xi_{(\theta)}^\alpha &= (0, 0, \sin\theta, \cot\theta \cos\theta) \checkmark \\ \xi_{(r)}^\alpha &= (0, 1, 0, 0) \checkmark & \xi_{(\phi)}^\alpha &= (0, 0, -\cos\theta, \cot\theta \sin\theta) \checkmark \end{aligned}$$

$$\mathcal{L}_\xi T_{\alpha\beta} = \xi^\gamma \partial_\gamma T_{\alpha\beta} - T_{\alpha\beta} \partial_\gamma \xi^\gamma + T_{\gamma\alpha} \partial_\beta \xi^\gamma + T_{\gamma\beta} \partial_\alpha \xi^\gamma$$

$$\mathcal{L}_\xi T_{\alpha\beta} = \xi^\gamma \partial_\gamma T_{\alpha\beta} + T_{\alpha\beta} \partial_\gamma \xi^\gamma + T_{\gamma\alpha} \partial_\beta \xi^\gamma + T_{\gamma\beta} \partial_\alpha \xi^\gamma$$

$$0 = \mathcal{L}_\xi g_{\alpha\beta} = \xi^\gamma \underbrace{\partial_\gamma g_{\alpha\beta}}_0 + \underbrace{g_{\alpha\beta} \partial_\gamma \xi^\gamma}_{\partial_\alpha (g_{\alpha\beta} \xi^\alpha)} + \underbrace{g_{\gamma\alpha} \partial_\beta \xi^\gamma}_{\partial_\beta (g_{\gamma\alpha} \xi^\alpha)}$$

$$\rightarrow \boxed{\nabla_\alpha \xi_\beta + \nabla_\beta \xi_\alpha = 0} \quad \text{killing's equation}$$

$$\nabla(\alpha \xi_\beta) = 0$$

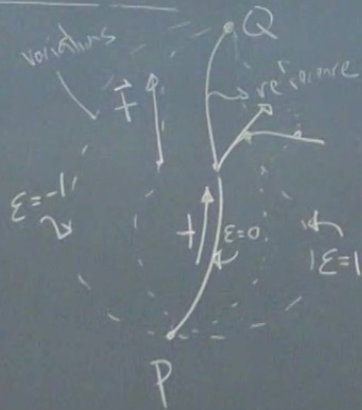
$$\nabla_\alpha \xi_\beta = \text{antisymmetric}$$



3 boost KV

$$\xi(Q) = (0, 0, 0, 1)^\vee \quad \xi(P) = (1, 0, 0, 0)^\vee$$

Geodesics



A timelike geodesic extremizes proper time between two (neighbouring) points

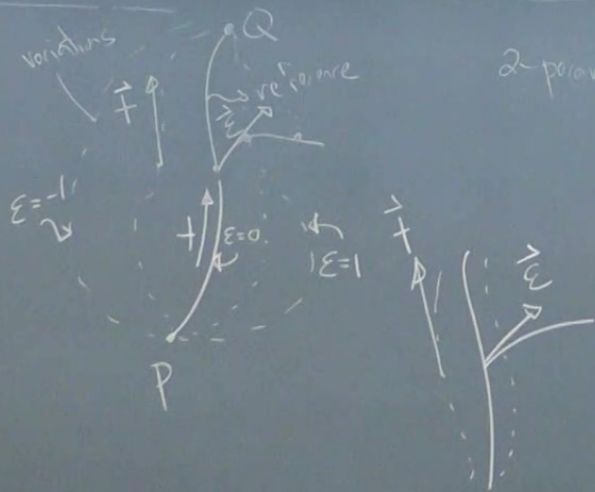
2-parameter family of curves: $X^\alpha(t, \epsilon)$

t vary, ϵ fixed \rightarrow motion along each curve

ϵ vary, t fixed \rightarrow motion across curves

3 boost KV

$$\xi(Q) = (0, 0, 0, 1) \quad \xi(P) = (1, 0, 0, 0)$$



2-parameter family of curves: $X^\alpha(t, \epsilon)$

t vary, ϵ fixed \rightarrow motion along each curve $\rightarrow t^\alpha = \left(\frac{\partial X^\alpha}{\partial t} \right)_\epsilon$
 ϵ vary, t fixed \rightarrow motion across curves $\rightarrow \epsilon^\alpha = \left(\frac{\partial X^\alpha}{\partial \epsilon} \right)_t$

Show: $\mathcal{L}_\epsilon t^\alpha = 0 = \mathcal{L}_t \epsilon^\alpha$

$$\epsilon^\beta \nabla_\beta t^\alpha = t^\beta \nabla_\beta \epsilon^\alpha$$

$$\overset{*}{=} 0 \rightarrow \boxed{\mathcal{L}_\xi g_{\alpha\beta} = 0} \text{ in all coordinates}$$

$\xi^\alpha \equiv \text{killing vector}$

Lie derivative

$$\mathcal{L}_\xi A^\alpha = \xi^\beta \partial_\beta A^\alpha - A^\beta \partial_\beta \xi^\alpha$$

$$\begin{aligned} \mathcal{L}_\xi t^\alpha &= \xi^\beta \partial_\beta t^\alpha - t^\beta \partial_\beta \xi^\alpha \\ &= \frac{\partial}{\partial \xi} t^\alpha - \frac{\partial}{\partial t} \xi^\alpha \\ &= \frac{\partial}{\partial \xi} \frac{\partial X^\alpha}{\partial t} - \frac{\partial}{\partial t} \frac{\partial X^\alpha}{\partial \xi} \\ &= 0 \quad \checkmark \end{aligned}$$

$= 0 \checkmark$



proper time: $d\tau^2 = -ds^2 = -g_{\alpha\beta} dx^\alpha dx^\beta$

$$d\tau = \sqrt{-g_{\alpha\beta} dx^\alpha dx^\beta} = \sqrt{-g_{\alpha\beta} \frac{dx^\alpha}{dt} \frac{dx^\beta}{dt}} dt$$

$$\Delta\tau = \int_P^Q \sqrt{-g_{\alpha\beta} \frac{dx^\alpha}{dt} \frac{dx^\beta}{dt}} dt$$

$= 0 \checkmark$

P

$$\Delta T = \int_P^Q \sqrt{-3\alpha^2 + \beta} dt = \sqrt{-3\alpha^2 + \beta} dt$$

$$S = - \int_0^1 \sqrt{-3\alpha^2 + \beta} dt$$

P

$$S = - \int_0^1 \sqrt{-2ap + a^2 + b^2} dt$$

$$L = - \sqrt{-2ap + a^2 + b^2}$$

$$\delta S = S(\epsilon) - S(0) = \epsilon \left. \frac{\partial S}{\partial \epsilon} \right|_{\epsilon=0} = \int_0^1 \frac{\partial L}{\partial \epsilon} dt$$

$$\frac{\partial L}{\partial \epsilon} = \epsilon^{\mu} \frac{\partial L}{\partial \epsilon^{\mu}}$$

$$= \epsilon^{\mu} \frac{\partial L}{\partial \epsilon^{\mu}} = \epsilon^{\mu} \left(\frac{\partial L}{\partial \epsilon^{\alpha}} \frac{\partial \epsilon^{\alpha}}{\partial \epsilon^{\mu}} + \frac{\partial L}{\partial \epsilon^{\beta}} \frac{\partial \epsilon^{\beta}}{\partial \epsilon^{\mu}} \right)$$

$$= \frac{\partial L}{\partial \epsilon^{\alpha}} \epsilon^{\mu} \frac{\partial \epsilon^{\alpha}}{\partial \epsilon^{\mu}}$$

P

$$S = - \int_0^1 \sqrt{-\dot{x}^2 + \dot{y}^2} dt$$

$$L = - \sqrt{-\dot{x}^2 + \dot{y}^2}$$

$$\delta S = S(\epsilon) - S(0) = \epsilon \left. \frac{\delta S}{\delta \epsilon} \right|_{\epsilon=0} = \int_0^1 \frac{\partial L}{\partial \epsilon} dt$$

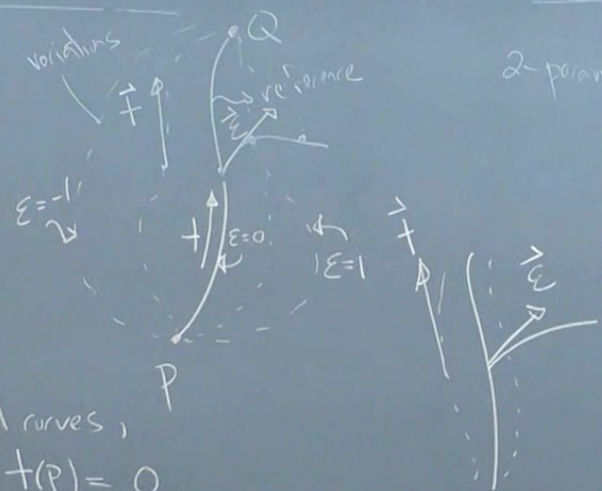
$$\frac{\partial L}{\partial \epsilon} = \epsilon^\mu \partial_\mu L$$

$$= \epsilon^\mu \partial_\mu L = \epsilon^\mu \left(\frac{\partial L}{\partial x^\alpha} \partial_\mu x^\alpha + \frac{\partial L}{\partial \dot{x}^\alpha} \partial_\mu \dot{x}^\alpha \right)$$

$$= \underbrace{\frac{\partial L}{\partial x^\alpha}}_{\equiv p_\alpha} \underbrace{\epsilon^\mu \partial_\mu x^\alpha}_{\equiv \delta x^\alpha}$$

3 boost KV

$$\vec{z}(Q) = (0, 0, 1, 1)$$



For all curves,
 $t(P) = 0$
 $t(Q) = 1$

2-parameter family of curves: $X^\alpha(t, \epsilon)$

t vary, ϵ fixed \rightarrow motion along each curve $\rightarrow t^\alpha = \left(\frac{\partial X^\alpha}{\partial t} \right)_\epsilon$
 ϵ vary, t fixed \rightarrow motion across curves $\rightarrow \epsilon^\alpha = \left(\frac{\partial X^\alpha}{\partial \epsilon} \right)_t$

Show: $\mathcal{L}_\epsilon t^\alpha = 0 = \mathcal{L}_t \epsilon^\alpha$

$$\epsilon^\beta \nabla_\beta t^\alpha = t^\beta \nabla_\beta \epsilon^\alpha \quad \checkmark$$

$$\boxed{P^\alpha \equiv \frac{\partial L}{\partial \dot{x}^\alpha}}$$

$$= \frac{\partial L}{\partial \dot{x}^\alpha} \underbrace{\epsilon^\mu \nabla_\mu \dot{x}^\alpha}_{\equiv P_\alpha}$$

$$\frac{\partial L}{\partial \dot{x}^\alpha} = P_\alpha \epsilon^\mu \nabla_\mu \dot{x}^\alpha = P_\alpha \frac{D\dot{x}^\alpha}{dt}$$

$$\delta S = \int_0^1 P_\alpha \frac{D\dot{x}^\alpha}{dt} dt$$

$$= P_\alpha \dot{x}^\alpha \Big|_0^1 - \int_0^1 \dot{x}^\alpha \frac{DP_\alpha}{dt} dt$$

3 boost KV

$$\vec{e}(Q) = (0, 0, 0, 1)$$

Rules of variation — ε^α is arbitrary between P and Q, but zero at P and Q

$$\delta S = 0 \Rightarrow \int_0^1 \varepsilon^\alpha \frac{Dp_\alpha}{dt} dt \rightarrow \boxed{\frac{Dp_\alpha}{dt} = 0} \text{ (geodesic equation)}$$

$$p_\alpha = \frac{\partial L}{\partial \dot{x}^\alpha} ; L = -\sqrt{-g_{\alpha\beta} \dot{x}^\alpha \dot{x}^\beta}$$

∂T

$$p_\alpha = \frac{\partial L}{\partial \dot{x}^\alpha} ; L = -\sqrt{-g_{\alpha\beta} \dot{x}^\alpha \dot{x}^\beta}$$

$$L = -(-g_{\alpha\beta} \dot{x}^\alpha \dot{x}^\beta)^{1/2}$$

$$p_\alpha = \frac{\partial L}{\partial \dot{x}^\alpha} = -\frac{1}{2} (-g_{\alpha\beta} \dot{x}^\alpha \dot{x}^\beta)^{-1/2} (-g_{\mu\nu}) \left(\underbrace{\frac{\partial \dot{x}^\mu}{\partial \dot{x}^\alpha}}_{\delta_\alpha^\mu} \dot{x}^\nu + \dot{x}^\mu \underbrace{\frac{\partial \dot{x}^\nu}{\partial \dot{x}^\alpha}}_{\delta_\alpha^\nu} \right)$$

$$= \frac{1}{2} \left(\frac{1}{-L} \right) (g_{\alpha\nu} \dot{x}^\nu + g_{\alpha\mu} \dot{x}^\mu)$$

$$p_\alpha = \frac{1}{-L} \dot{x}^\alpha \quad p^\alpha = \frac{1}{-L} \dot{x}^\alpha$$

$$\boxed{P^\alpha = \frac{\partial L}{\partial \dot{x}^\alpha}}$$

$$= \frac{\partial L}{\partial \dot{x}^\alpha} \underbrace{\varepsilon^\mu \nabla_\mu \dot{x}^\alpha}_{\equiv P_\alpha} = P_\alpha \varepsilon^\mu \nabla_\mu \dot{x}^\alpha$$

$$\frac{\partial L}{\partial \varepsilon^\alpha} = P_\alpha \varepsilon^\mu \nabla_\mu \dot{x}^\alpha = P_\alpha \frac{D \dot{x}^\alpha}{dt}$$

$$\frac{D P^\alpha}{dt} = 0 \rightarrow \frac{D}{dt} \left(\frac{\dot{x}^\alpha}{(-L)} \right) = \frac{1}{(-L)} \frac{D \dot{x}^\alpha}{dt} - \frac{1}{(-L)^2} \frac{d(-L)}{dt} \dot{x}^\alpha$$

$$\boxed{\frac{D \dot{x}^\alpha}{dt} = k \dot{x}^\alpha}$$

$$\rightarrow \boxed{\frac{D \dot{x}^\alpha}{dt} = \underbrace{\frac{1}{(-L)} \frac{d(-L)}{dt}}_k \dot{x}^\alpha}$$

$$= \frac{1}{2} \left(\frac{1}{-L} \right) (\partial_{x^\mu} t^\mu + \partial_{x^\alpha} t^\mu)$$

$$\boxed{p_\alpha = \frac{1}{-L} t_\alpha} \quad \boxed{p^\alpha = \frac{1}{-L} t^\alpha}$$

After variation — choose $t \equiv$ proper time T .

$$L = - \sqrt{g_{\alpha\beta} \frac{\partial x^\alpha}{\partial T} \frac{\partial x^\beta}{\partial T}} = - \sqrt{\frac{\partial T^2}{\partial T^2}} = -$$

$$L = -1$$

$$K = 0$$

$$\rightarrow \boxed{\frac{D}{dT} \left(\frac{\partial x^\alpha}{\partial T} \right) = 0}$$

geodesic eqn
(proper time
parametrization)