

Title: Statistical Physics Lecture - 120523

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$$Z \approx \frac{1}{(\pi V)^{N/2}} \int D^N \varphi e^{-S(\varphi)}$$

$$S(\varphi) \approx \frac{1}{2V} \sum_k (r+k^2) |\varphi_k|^2 - h \varphi_0$$

$$+ \frac{u}{4!V^3} \sum_{\substack{k_1, k_2, \\ k_3, k_4}} \varphi_{k_1} \varphi_{k_2} \varphi_{k_3} \varphi_{k_4} \delta_{k_1+k_2+k_3+k_4, 0}$$

$$Z \approx \frac{1}{(\pi V)^{N/2}} \int D^N \varphi e^{-S(\varphi)}$$

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Let's rewrite Z as $S_0(\varphi^-) + S_0(\varphi^+)$

$$Z = \frac{1}{(\pi V)^{N/2}} \int^{\Lambda} \mathcal{P}^N \varphi e^{-S_0(\varphi) - S_I(\varphi)}$$

We will set $H=0 \rightarrow$ don't need it to compute η and ν .

$$\int^{\Lambda} \mathcal{P}^N \varphi e^{-S'(\varphi^-)}$$

Focus on:

$$e^{-S_0(\varphi^-)} \int D^N \varphi^+ e^{-S_0(\varphi^+)} e^{-S_I(\varphi^- + \varphi^+)}$$

$e^{-S(\varphi^-)}$

$$\varphi e^{-S_0(\varphi^-)} \left(\frac{\int D^N \varphi^+ e^{-S_0(\varphi^+)} e^{-S_I(\varphi^- + \varphi^+)}}{\int D^N \varphi^+ e^{-S_0(\varphi^+)}} \right)$$

← avg. with $e^{-S_0(\varphi^+)}$ as prob. dist.

$$= e^{-S_0(\varphi^-)} \left\langle e^{-S_I(\varphi^- + \varphi^+)} \right\rangle_+$$

This allows us to use the
cumulant expansion.

$$S'(\varphi^-) \approx -\ln \left(e^{-S_0(\varphi^-)} \left\langle e^{-S_I(\varphi^- + \varphi^+)} \right\rangle_+ \right)$$

$$\ln(1+x) \approx x - \frac{x^2}{2}$$

$$e^{-S_I(\varphi^- + \varphi^+)} \approx 1 - S_I + \frac{S_I^2}{2}$$

$$\ln \left(\left\langle 1 - S_I + \frac{S_I^2}{2} \right\rangle_+ \right) \approx \left\langle -S_I + \frac{S_I^2}{2} \right\rangle_+ - \frac{\langle S_I \rangle_+^2}{2}$$

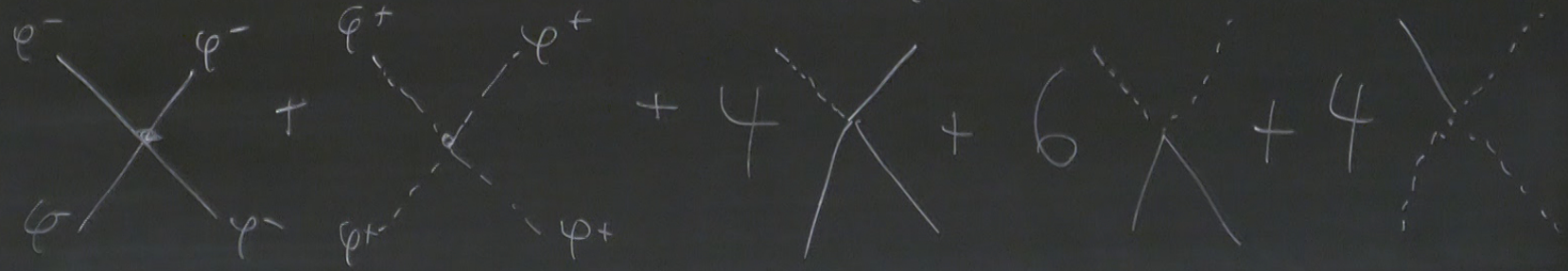
$$\ln \left\langle e^{-S_I} \right\rangle_+ = -\langle S_I \rangle_+ + \frac{1}{2} \left(\langle S_I^2 \rangle_+ - \langle S_I \rangle_+^2 \right)$$

So we'll get terms like $\langle \phi_{k_1} \phi_{k_2} \phi_{k_3} \phi_{k_4} \rangle +$
 $= \langle \phi_{k_1} \phi_{k_2} \rangle \langle \phi_{k_3} \phi_{k_4} \rangle + \langle \phi_{k_1} \phi_{k_3} \rangle \langle \phi_{k_2} \phi_{k_4} \rangle + \dots$

Wick's Theorem

$$S_I(\psi^- + \psi^+) = \frac{i}{4!V^3} \sum_{k_1 k_2 k_3 k_4} \phi_{k_1} \phi_{k_2} \phi_{k_3} \phi_{k_4} \delta_{k_1 + k_2 + k_3 + k_4, 0}$$

$\psi^+ \psi^+ \psi^- \psi^-$ $\psi^+ \psi^- \psi^+ \psi^-$ $\psi^+ \psi^- \psi^- \psi^+$



$$\varphi_{k_1} = \varphi_{k_1}^+ + \varphi_{k_1}^-$$

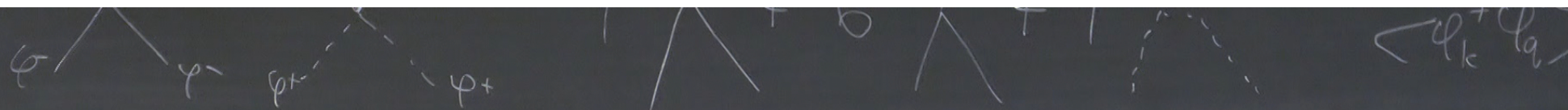
Rules

- each solid external leg carries a φ_k^-
- each dashed external leg carries a φ_k^+
- each vertex involves a $\frac{u}{4!V^3} \delta_{k_1+k_2+k_3+k_4, 0}$
- each internal line carries a $\langle \varphi_k^+ \varphi_q^+ \rangle_+$, can be computed

$$\langle \varphi_k^+ \varphi_q^+ \rangle_+ = \begin{cases} \frac{V \delta_{k+q, 0}}{r+k^2}, & \text{if } |k|, |q| \geq \frac{\Lambda}{b} \\ 0, & \text{otherwise} \end{cases}$$

$$\langle \phi_k^+ \phi_q \rangle_+ = \begin{cases} \frac{v}{r+k^2} \delta_{k+q,0} & \text{if } |k|, |q| \leq \frac{b}{2} \\ 0 & \text{otherwise} \end{cases}$$

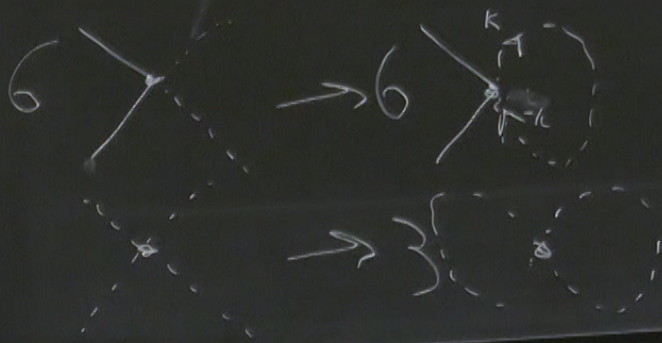
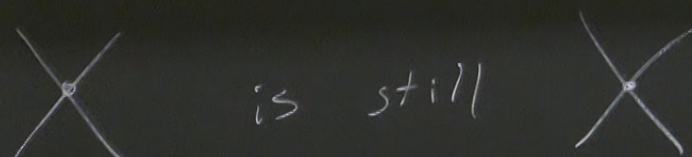
$$|\phi_k^+|^2 \stackrel{q=-k}{=} e^{-(r+k^2)|\phi_k^+|^2} \quad (\text{Feynman integral trick})$$



\downarrow
 $\langle S_5 \rangle_+$

$\langle \psi^- \psi^- \psi^+ \psi^+ \rangle_+$

12	34
13	24
14	23



$$\langle S_5 \rangle_+ \rightarrow X + 6 \text{ (circle)} + 3 \text{ (circles)}$$

What about about $\langle S_I^2 \rangle - \langle S_{I+} \rangle^2$
 For S_I^2 we have

$$\begin{aligned}
 & (X + 4Y + 6Z + 4W + \dots)^2 \\
 &= XX + 8XY + 12XZ + \dots
 \end{aligned}$$

we will remove all disconnected diagrams with this term

$-\langle S_{I+} \rangle^2$ is only the connected diagrams for $\langle S_I^2 \rangle$

$$\langle S_I^2 \rangle_+ - \langle S_I \rangle_+^2 =$$



$$16 \begin{array}{c} | \text{---} | \\ 4 \cdot 4 \end{array} + 72 \begin{array}{c} \text{---} \text{---} \\ 6 \cdot 6 \cdot 2 \end{array} + 96 \begin{array}{c} | \text{---} \text{---} \\ 4 \cdot 4 \cdot 3 \cdot 2 \end{array}$$

$$+ 96 \begin{array}{c} \text{---} \text{---} \\ 4 \cdot 4 \cdot 6 \end{array} + 144 \begin{array}{c} \text{---} \text{---} \\ 4 \cdot 4 \cdot 3 \cdot 3 \end{array} + 144 \begin{array}{c} \text{---} \text{---} \\ 6 \cdot 6 \cdot 2 \cdot 2 \end{array}$$

$$+ 72 \begin{array}{c} \text{---} \text{---} \\ 6 \cdot 6 \cdot 2 \end{array} + 24 \begin{array}{c} \text{---} \\ 4 \end{array}$$

Now \dots is for $k \equiv |k_p^+| > \frac{\Lambda}{b}$

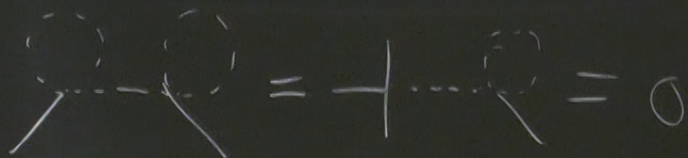
\dots is for $|k_p^-| < \frac{\Lambda}{b}$



involves two vertices with

$$k_1^- - k_2^+ + k_3^+ - k_3^- = 0$$

$$k_1^- - k_2^+ = 0 \quad \times \text{ can't happen}$$



We will also drop diagrams with no external legs - no φ^- dependence



- Diagrams with six external legs introduce φ^6 terms.



$$\frac{1}{2}(\langle S_I^2 \rangle_+ - \langle S_I \rangle_+^2) \approx 36$$

non

$$S'(\varphi^-)^2 X + 6 \langle S_I \rangle_+ = 36$$

$$\langle S_I^2 \rangle_+ - \langle S_I \rangle_+^2 =$$

Computing the Diagrams:

$$X = \sum_{\substack{k_1, k_2 \\ k_3, k_4}} \varphi_{k_1}^- \varphi_{k_2}^- \varphi_{k_3}^- \varphi_{k_4}^- \frac{u}{4!V^3} \delta_{k_1+k_2+k_3+k_4, 0}$$

$$G \text{ (diagram)} = \sum_{k_1, k_2} \varphi_{k_1}^- \varphi_{k_2}^- G \delta_{k_1+k_2, 0} \frac{u}{4!V^3} \sum_q \frac{V}{r+q^2} \left\langle \varphi_k^+ \varphi_q^+ \right\rangle$$

$$= \frac{1}{2V} \sum_k |\varphi_k^-|^2 \frac{u}{2} \underbrace{\left(\frac{1}{V} \sum_{|q, p| > \frac{\Lambda}{h}} \frac{1}{r+q^2} \right)}_{I_1(b)}$$

$$+ \frac{1}{2} \left(\frac{1}{r} + \frac{1}{r'} - \frac{1}{r''} \right) \left(\frac{1}{r} + \frac{1}{r'} \right)^d$$

$$k_3 + k_4 = 0$$

$$\langle \varphi_k^+ \varphi_q^+ \rangle$$

$$\frac{V}{r + q^2}$$

$$I_1(k) \sim \frac{S_{D-1}}{(2\pi)^D} \int_{\frac{1}{b}}^{\infty} \frac{q^{D-1} dq}{r + q^2}$$

Solid angle

$$= e^{-S_0(\varphi^-)} \left(\int D^d \varphi^+ e^{-S_0(\varphi^+)} \right) \langle e^{-S_I(\varphi^- + \varphi^+)} \rangle_+$$

prob. dist.

$$\ln \langle 1 - S_I + \frac{S_I^2}{2} \rangle_+ \approx -\langle S_I \rangle_+ + \frac{\langle S_I^2 \rangle_+}{2}$$

$$\ln \langle e^{-S_I} \rangle_+ = -\langle S_I \rangle_+ + \frac{1}{2} (\langle S_I^2 \rangle_+ - \langle S_I \rangle_+^2)$$

Computing the Diagrams:

$$X = \sum_{\substack{k_1, k_2 \\ k_3, k_4}} \varphi_{k_1}^- \varphi_{k_2}^- \varphi_{k_3}^- \varphi_{k_4}^- \frac{u}{4!V^3} \delta_{k_1+k_2+k_3+k_4, 0}$$

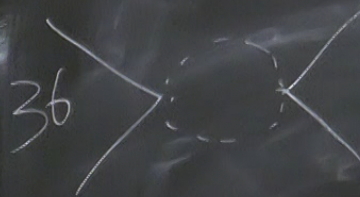
$$6 \langle \dots \rangle = \sum_{t_1, t_2} \varphi_{k_1}^- \varphi_{k_2}^- 6 \delta_{k_1+k_2, 0} \frac{u}{4!V^3} \sum_q \frac{V}{r+q^2} \langle \varphi_k^+ \varphi_q^+ \rangle$$

$$= \frac{1}{2V} \sum_k |\varphi_k^-|^2 \frac{u}{2} \underbrace{\left(\frac{1}{V} \sum_{|q|=r} \frac{1}{r+q^2} \right)}_{I_1(b)}$$

$$I_1(b) \sim \frac{S_{D-1}}{(2\pi)^D} \int_{\Lambda/b}^{\Lambda} \frac{q^{D-1} dq}{r+q^2}$$

Solid angle

$I_1(b)$



$$= 36 \sum_{\substack{k_1, k_2 \\ k_3, k_4}} \varphi_{k_1}^- \varphi_{k_2}^- \varphi_{k_3}^- \varphi_{k_4}^- \delta_{k_1+k_2-q_1+q_2, 0} \delta_{k_3+k_4+q_1-q_2, 0} \frac{u^2}{4!4!V}$$

$$k_1+k_2-q_1+q_2=0 \rightarrow k_1+k_2+k_3+k_4=0$$

$$k_3+k_4+q_1-q_2=0$$

$$\approx \frac{u}{16V^3} \sum_{\substack{k_1, k_2 \\ k_3, k_4}} \varphi_{k_1}^- \varphi_{k_2}^- \varphi_{k_3}^- \varphi_{k_4}^- \delta_{k_1+k_2+k_3+k_4, 0} I_2(b)$$

$$\frac{S_{D-1}}{(2\pi)^D} \int_{\tau_0}^{\tau_1} d\tau$$

$I_1(b)$

$$\varphi_{k_2}^- \varphi_{k_3}^- \varphi_{k_4}^- \delta_{k_1+k_2-q_1+q_2,0} \delta_{k_3+k_4+q_1-q_2,0} \frac{u^2}{4!4!V^6} \sum_{q_1, q_2} \frac{V}{r+q_1} \frac{V}{r+q_2}$$

$$k_1+k_2-q_1+q_2=0 \rightarrow k_1+k_2+k_3+k_4=0 \quad q_1=q_2$$


$$k_3+k_4+q_1-q_2=0$$

$$\varphi_{k_2}^- \varphi_{k_3}^- \varphi_{k_4}^- \delta_{k_1+k_2+k_3+k_4,0} \quad I_2(b)$$

$$\frac{S_{D-1}}{(2\pi)^D} \int_{\Lambda} d^D q \frac{q^{D-1}}{(r+q)^2}$$

$$2V \sum_k \frac{1}{k} \frac{1}{k} \frac{1}{2} \frac{1}{V} \sum_{|a_n| > \frac{\Lambda}{2}} \frac{1}{r+a^2}$$

$I_1(b)$

36 \rightarrow  $= 36 \sum_{\substack{k_1, k_2 \\ k_3, k_4}} \varphi_{k_1} \varphi_{k_2} \varphi_{k_3} \varphi_{k_4} \delta_{k_1+k_2-q_1+q_2, 0} \delta_{k_3+k_4+q_1-q_2, 0}$

Like $(\varphi_{k_1} \varphi_{k_2} \varphi_{k_3} \varphi_{k_4})$

$\frac{u^2}{4! 4! V^6} \sum_{q_1, q_2} \frac{V}{r+q_1} \frac{V}{r+q_2}$

$q_1 = q_2$

$k_1+k_2-q_1+q_2=0 \rightarrow k_1+k_2+k_3+k_4=0$

$k_3+k_4+q_1-q_2=0$

$\approx \frac{u}{16V^3} \sum_{\substack{k_1, k_2 \\ k_3, k_4}} \varphi_{k_1}^- \varphi_{k_2}^- \varphi_{k_3}^- \varphi_{k_4}^- \delta_{k_1+k_2+k_3+k_4, 0} I_2(b)$

$\int_{\frac{\Lambda}{2}}^{\Lambda} dq \frac{q^{D-1}}{(r+q^2)^2}$

- Diagrams with six external legs introduce φ^6 terms.



$$\frac{1}{2}(\langle S_I^2 \rangle_+ - \langle S_I \rangle_+^2) \approx 36 \text{ } \langle \text{diagram} \rangle$$

$$S'(\varphi^-) \approx X + 6 \langle \text{diagram} \rangle - 36 \langle \text{diagram} \rangle + S_0(\varphi^-)$$

Rescaling: $N' = \frac{N}{b^D}$ $V' = \frac{V}{b^D}$ $k' = kb$ $\psi'_k = z\psi_k$

$$S'(\psi') \approx \frac{b^{-D}}{2V'} \sum_k \left(r + \underbrace{b^{-2}k'}_{S_0(\psi')} + \frac{u}{2} I_1(b) \right) z^{-2} |\psi'_k|^2 + \frac{b^{-3D}}{4! V'^3}$$

RGT:
$$\begin{cases} r' = b^2 \left(r + \frac{u I_1(b)}{2} \right) \\ u' = b^{4-D} \left(u - \frac{3}{2} u^2 I_2(b) \right) \end{cases}$$

$$b^{-D} z^{-2} = b^2$$

$$z = b^{(2+D)/2}$$

What is the $\frac{\partial r'}{\partial b}, \frac{\partial u'}{\partial b}, \frac{\partial I_1(b)}{\partial b}, \dots$

Leibniz rule:

$$\frac{d}{dx} \int_{a(x)}^{b(x)} f(x,t) dt = f(x, b(x)) \cdot b'(x) - f(x, a(x)) \cdot a'(x) + \int_{a(x)}^{b(x)} \frac{\partial f}{\partial x}(x,t) dt$$

$$+ \frac{b^{-3D}}{4! V^3} \sum_{k'} \left(u - \frac{3}{2} u^2 I_2(b) \right) \approx -4 \varphi'_{k_1} \varphi'_{k_2} \varphi'_{k_3} \varphi'_{k_4} \delta_{k_1' + k_2' + k_3' + k_4', 0}$$

$a = b^2$
 $b^{(2+D)/2}$

is the β -function?

$$\frac{\partial I_1(b)}{\partial b}, \quad \frac{\partial I_2(b)}{\partial b}$$

$$t = f(x, b(x)) \frac{d}{dx} b(x) - f(x, a(x)) \frac{d}{dx} a(x) + \int_{a(x)}^{b(x)} \frac{\partial}{\partial x} f(x, t) dt$$

$$\left\{ \begin{aligned} \frac{dr'}{db} &= 2b \left(r + \frac{u}{2} \frac{k_D}{r + \Lambda^2 b^{-2}} \right) \\ \frac{du'}{db} &= (4-D) b^{3-D} \left(u - \frac{3u^2}{2} \frac{k_D}{(r + \Lambda^2 b^{-2})} \right) \end{aligned} \right.$$

$$k_D = \frac{S_{D-1} \Lambda^D b^{-1-D}}{(2\pi)^D}$$

Now what are the fixed points?

$(r^*, u^*) = (0, 0)$ is one \leftarrow Gaussian fixed point

$t \rightarrow s = e^{b-1} \leftarrow$ is 1 for no rescaling

$$\begin{cases} s \frac{dr}{ds} \Big|_{b=1} = 2(r + \frac{1}{2} K_0 \Lambda^{-2} u - \frac{1}{2} K_0 u r \Lambda^{-4}) & u \rightarrow g \\ & r \rightarrow t \end{cases}$$

$$V = \frac{t}{2} \psi$$

$$s \frac{dt}{ds} = -\beta(t)$$

$$s \frac{dg}{ds} = -\beta(g)$$

$$s \frac{du}{ds} = -\frac{3u^2}{2} \frac{K_0}{(r+\Lambda^2)^2}$$

$[D=4]$

the fixed points?

is one ← Gaussian fixed point

is 1 for no rescaling

$$K_0 \Lambda^{-2} u - \frac{1}{2} K_0 u r \Lambda^{-4}$$

$$u \rightarrow g$$

$$r \rightarrow t$$

$$\frac{K_D}{(r+\Lambda^2)^2}$$

Francis' Notes

$$V = \frac{t}{2} \phi^2 + \frac{g}{4!} \phi^4$$

$$\int \frac{d}{ds} t = -\beta_t(t, g) = 2t + g - tg$$

$$\int \frac{d}{ds} g = -\beta_g(t, g) = -3g^2$$

$\partial_x J_a(x), J(x)$

$$\left\{ \begin{aligned} \frac{dr'}{db} &= 2b \left(r + \frac{u}{2} \frac{k_D}{r + \Lambda^2 b^{-2}} \right) \\ \frac{du'}{db} &= (4-D) b^{3-D} \left(u - \frac{3u^2}{2} \frac{k_D}{(r + \Lambda^2 b^{-2})} \right) \end{aligned} \right.$$

$$k_D = \frac{S_{D-1} \Lambda^D b^{-1-D}}{(2\pi)^D}$$

$$\frac{1}{r + \Lambda^2} = \frac{\Lambda^{-2}}{\frac{r}{\Lambda^2} + 1} \approx \Lambda^{-2} \left(1 - \frac{r}{\Lambda^2} \right)$$

Now

$t \rightarrow (r \rightarrow s)$

$S \rightarrow$

$\left\{ \begin{aligned} S \frac{dr'}{ds} \\ S \frac{du'}{ds} \end{aligned} \right.$

Leibniz rule:

$$\frac{d}{dx} \int_{a(x)}^{b(x)} f(x,t) dt = f(x, b(x)) \frac{d}{dx} b(x) - f(x, a(x)) \frac{d}{dx} a(x) + \int_{a(x)}^{b(x)} \frac{\partial}{\partial x} f(x,t) dt$$

Now what are the fixed points?

$(r^*, u^*) = (0, 0)$ is one ← Gaussian fixed point

$s = e^{b-1}$ ← is 1 for no rescaling

$$\begin{cases} s \frac{dr}{ds} \Big|_{b=1} = 2(r + \frac{1}{2} K_0 \Lambda^{-2} u - \frac{1}{2} K_0 u r \Lambda^{-4}) & u \rightarrow g \\ s \frac{du}{ds} = -\frac{3u^2}{2} \frac{K_0}{(r+\Lambda^2)^2} & r \rightarrow t \end{cases}$$

[D=4]

Francis' Notes

$$V = \frac{t}{2} \phi^2 + \frac{g}{4!} \phi^4$$

$$s \frac{d}{ds} t = -\beta_t(t, g) = 2t + g - tg$$

$$s \frac{d}{ds} g = -\beta_g(t, g) = -3g^2$$