

Title: Relativity Lecture - 101623

Speakers: David Kubiznak

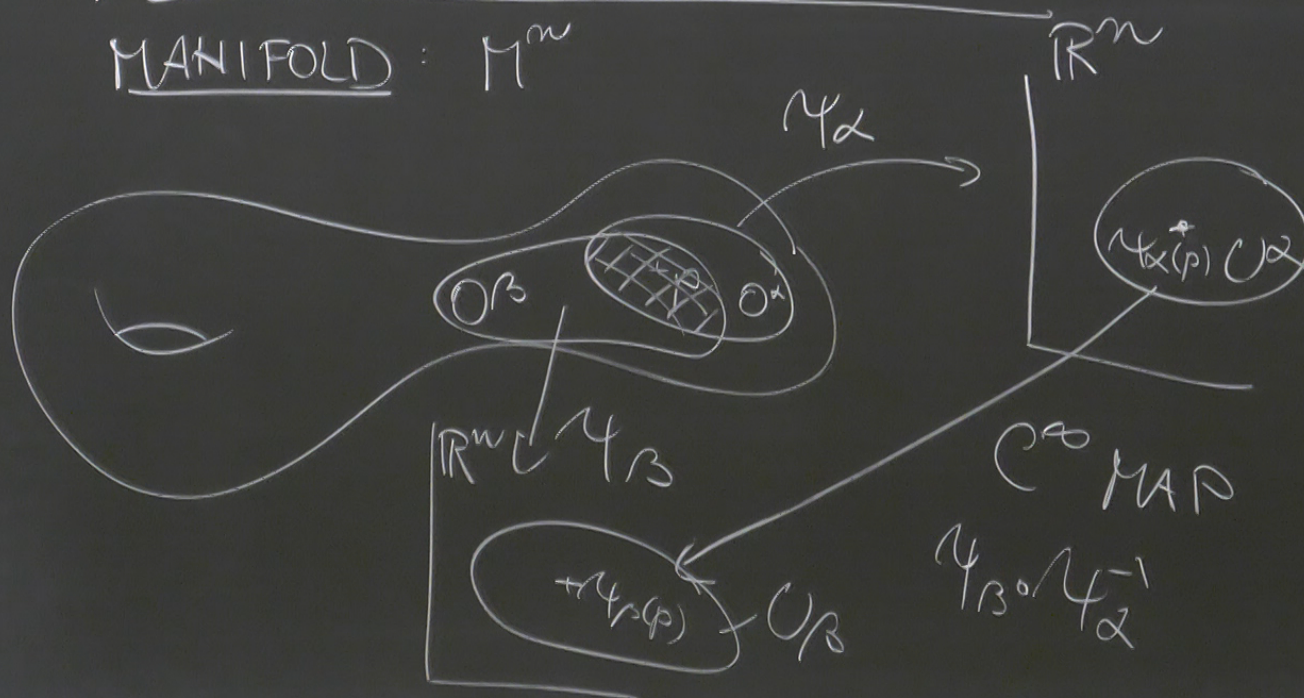
Collection: Relativity 2023/24

Date: October 16, 2023 - 9:00 AM

URL: <https://pirsa.org/23100038>

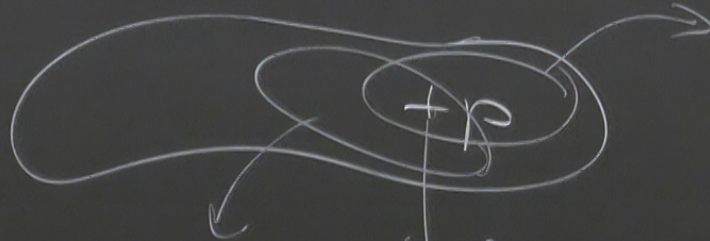
2) DIFFERENTIAL GEOMETRY

MANIFOLD: M^m



TENSORS = INVARIANT OBJECTS THAT LIVE ON M^m ,

SCALAR $f: M \rightarrow \mathbb{R}$

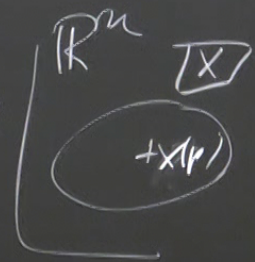
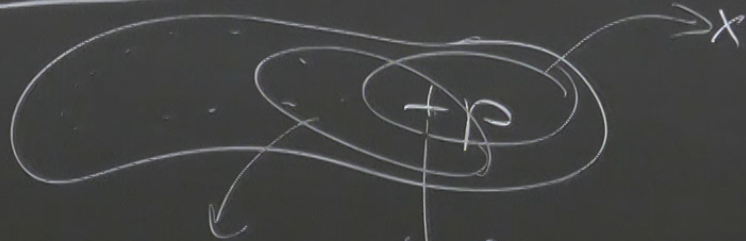


$$f(p) = f(x(p)) = f'(x'(p))$$

$$f(x) = f'(x')$$

TENSORS = INVARIANT OBJECTS THAT LIVE ON M^m ,

SCALAR: $f: M \rightarrow \mathbb{R}$

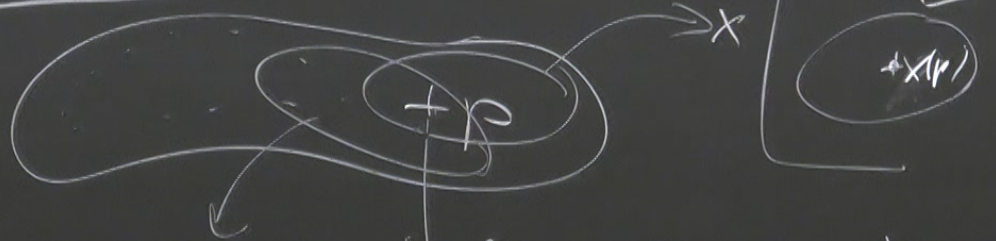


$$f(p) = f(x(p)) = f'(x'(p))$$

$$\boxed{f(x) = f'(x')}$$

TENSORS = INVARIANT OBJECTS THAT LIVE ON M^m ,

SCALAR: $f: M \rightarrow \mathbb{R}$



$$f(p) = f(x(p)) = f'(x'(p))$$

$$\boxed{f(x) = f'(x')}$$

AT LINE ON M^m ,

TANGENT VECTOR

$$V^M = (v_1^1, v_1^2, v_1^3) \leftrightarrow \hat{V} = V^M \frac{\partial}{\partial x^M}$$

$f'(x(p))$

AT LIVE ON M^m ,

TANGENT VECTOR

$$V^M = (v_1^1, v_1^2, v_1^3) \leftrightarrow \hat{V}_f = V^M \left(\frac{\partial}{\partial x^M} \right) f$$

DIRECTIONAL DERIVATIVE

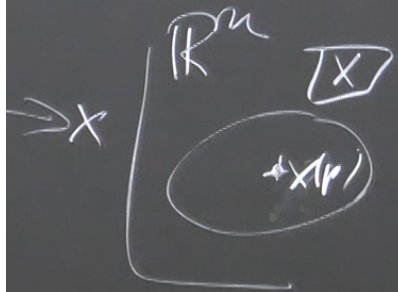
V AT POINT $p \in M$ $V: \mathcal{F} \rightarrow \mathbb{R}$

LINEAR: $V(af + bg) = aV(f) + bV(g)$

LEIBNITZ: $V(fg) = V(f)g(p) + f(p)V(g)$

POINTS THAT LIVE ON M^m ,

• TANGENT VECTOR



$$V^M = (v_1^1, v_1^2, v_1^3) \leftrightarrow \hat{V}_f = V^M \left(\frac{\partial}{\partial x^M} \right) f$$

DIRECTIONAL DERIVATIVE

$$f(x(p)) = f'(x'(p))$$

V AT POINT $p \in M$ $V: \mathcal{F} \rightarrow \mathbb{R}$

i) LINEAR: $V(af + bg) = aV(f) + bV(g)$

ii) LEIBNITZ: $V(fg) = V(f)g(p) + f(p)V(g)$

SPEC: $V(f=c) = ?$

$$V(f^2) = V(cf) \stackrel{i)}{=} cV(f) = \underline{cV(c)}$$

$$\stackrel{ii)}{=} fV(f) + fV(f) = \underline{2cV(c)}$$

SPEC: $V(f=c) = ?$

$$V(f^2) = V(cf) \stackrel{i)}{=} cV(f) = \underline{cV(c)}$$

$$\stackrel{ii)}{=} fV(f) + fV(f) = \underline{2cV(c)}$$

$$\Rightarrow \boxed{V(c) = 0}$$

SPEC: $V(f=c) = ?$

$$V(f^2) = V(cf) \stackrel{i)}{=} cV(f) = \underline{cV(c)}$$

$$\stackrel{ii)}{=} fV(f) + fV(f) = \underline{2cV(c)}$$

$$\Rightarrow \boxed{V(c) = 0}$$

HOMEWORK: WHY WE EXPECT LEIBNIZ?

THEOREM: SET OF TANGENT VECTORS AT p FORMS
 A TANGENT VECTOR SPACE $T_p M$ WHICH HAS
 THE SAME DIMENSIONALITY AS M . AND HAS
 COORDINATE BASIS $\frac{\partial}{\partial x^i}$. ANY $V \in T_p M$
 CAN BE WRITTEN AS

$$V = \underbrace{V^i}_{\text{COMPONENTS}} \underbrace{\frac{\partial}{\partial x^i}}_{\text{BASIS}}$$

TANGENT VECTORS AT p FORMS
TANGENT SPACE $T_p M$ WHICH HAS

IDENTIFICATION AS \mathbb{R}^n . AND HAS

IDENTIFICATION AS $\frac{\partial}{\partial x^i}$. ANY $V \in T_p M$

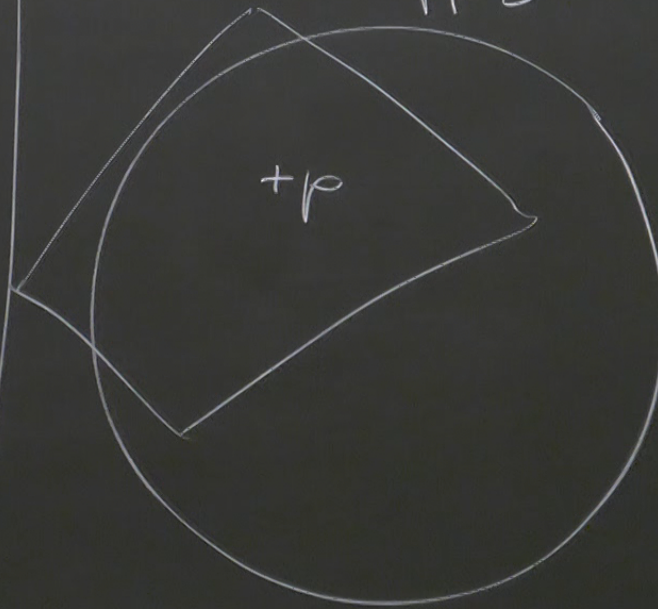
AS

$\frac{\partial}{\partial x^i}$

ITS BASIS

EX:

$M = S^2$

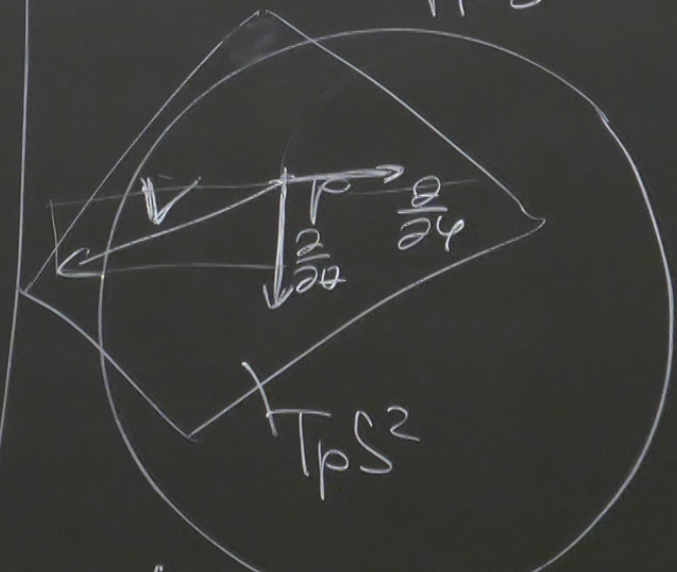


TANGENT VECTORS AT p FORMS
 TANGENT SPACE $T_p M$ WHICH HAS
 DIMENSIONALITY AS M . AND HAS
 BASIS $\frac{\partial}{\partial x^i}$. ANY $V \in T_p M$
 CAN BE WRITTEN
 AS

$\frac{\partial}{\partial x^i}$
 $\frac{\partial}{\partial x^i}$
 BASIS

EX:

$M = S^2$



$$V = V^\theta \frac{\partial}{\partial \theta} + V^\phi \frac{\partial}{\partial \phi}$$

UNDER CHANGE OF COORDINATES, V REMAINS INVARIANT!

$$x \rightarrow x'(x)$$

$$V = V_M \frac{\partial}{\partial x^M} \Rightarrow \left(V_M \frac{\partial x^{N'}}{\partial x^M} \right) \frac{\partial}{\partial x^{N'}}$$

CHAIN RULE

$V^{N'}$

$$V^{N'} = \frac{\partial x^{N'}}{\partial x^M} V^M$$

TRANSF. OF COMPONENTS!

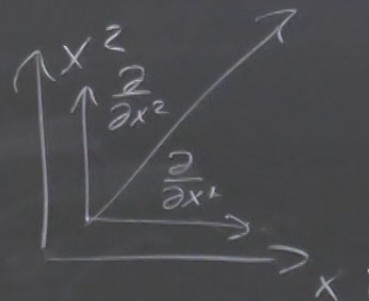
SPEC: $V(f=c) = ?$

$$V(f^2) = V(cf) \stackrel{i)}{=} cV(f) = \underline{cV(c)}$$

$$\stackrel{ii)}{=} fV(f) + fV(f) = \underline{2cV(c)}$$

$$\Rightarrow \boxed{V(c) = 0}$$

HOMEWORK: WHY WE EXPECT



THEOREM:

A TANGENT
THE SAME
COORDINATES
CAN

(UNDER CHANGE OF COORDINATES, V REMAINS INVARIANT!

COMPONENTS

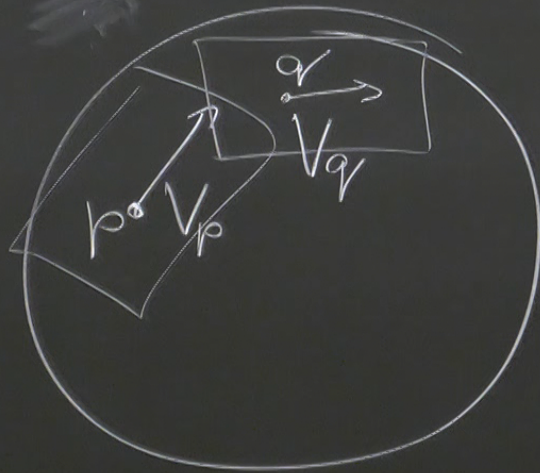
BASIS

$$V = V^\varphi \frac{\partial}{\partial \varphi} + V^\theta \frac{\partial}{\partial \theta}$$

• TANGENT VECTOR FIELD

$$\sum V/p \quad \forall p \in M$$

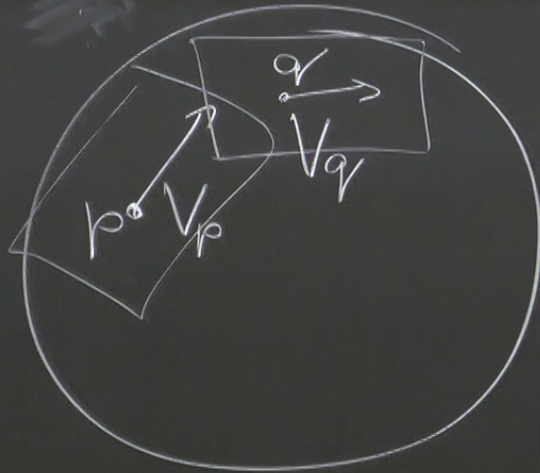
$V(f)$.. SMOOTH FUNCTION }



• TANGENT VECTOR FIELD

$$\sum V/p \quad \forall p \in M$$

$V(f)$.. SMOOTH FUNCTION }



TANGENT BUNDLE

$$TM = \bigcup_p T_p M$$

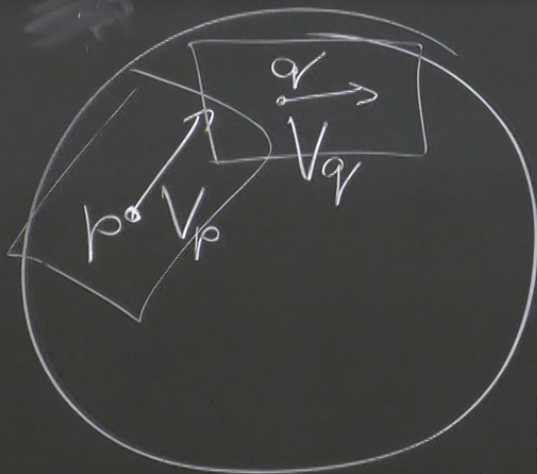
• TANGENT VECTOR FIELD

$$\sum V/p \quad \forall p \in M$$

$V(f)$.. SMOOTH FUNCTION }

M

MENTS!



TANGENT BUNDLE
 $TM = \bigcup_p T_p M$

TM HAS LOCAL COORDS.

$$(x^M, v^N)$$

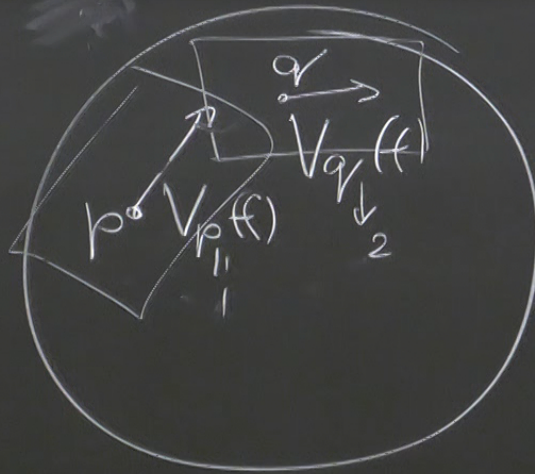
TANGENT VECTOR FIELD

$$\sum V/p \quad \forall p \in M$$

$V(f)$.. SMOOTH FUNCTION }

M

MENTS!



TANGENT BUNDLE
 $TM = \bigcup_p T_p M$

TM HAS LOCAL COORDS.

(x^M, v^N)

DEF: A COTANGENT VECTOR (DUAL VECTOR, 1-FORM) ω AT $p \in M$ IS A MAP $\omega: T_p M \rightarrow \mathbb{R}$.

COTANGENT VECTORS FORM A COTANGENT VECTOR SPACE

$T_p^* M$ WITH COORDINATE BASIS dx^i_p .

DEF: A COTANGENT VECTOR (DUAL VECTOR, 1-FORM) ω AT $p \in M$ IS A MAP $\omega: T_p M \rightarrow \mathbb{R}$.

COTANGENT VECTORS FORM A COTANGENT VECTOR SPACE

$T_p^* M$ WITH COORDINATE BASIS dx^i

$$dx^i \left(\frac{\partial}{\partial x^j} \right) = \delta^i_j$$

DEF: A COTANGENT VECTOR (DUAL VECTOR, 1-FORM) ω AT $p \in M$ IS A ^{LINEAR} MAP $\omega: T_p M \rightarrow \mathbb{R}$.

COTANGENT VECTORS FORM A COTANGENT VECTOR SPACE

$T_p^* M$ WITH COORDINATE BASIS dx^i

$$dx^i \left(\frac{\partial}{\partial x^j} \right) = \delta^i_j$$

DEF: A COTANGENT VECTOR (DUAL VECTOR, 1-FORM) ω AT $p \in M$ IS A ^{LINEAR} MAP $\omega: T_p M \rightarrow \mathbb{R}$.

COTANGENT VECTORS FORM A COTANGENT VECTOR SPACE

$T_p^* M$ WITH COORDINATE BASIS dx^i

$$dx^i \left(\frac{\partial}{\partial x^j} \right) = \delta^i_j$$

COMPONENTS BASIS

$$\omega = \omega_\mu dx^\mu$$

$$\omega(V) = \omega_{\mu} dx^{\mu}(V) = \omega_{\mu} \underbrace{dx^{\mu} \left(V^{\nu} \frac{\partial}{\partial x^{\nu}} \right)}_{\delta^{\mu}_{\nu}} = \omega_{\mu} V^{\mu}$$

$$\omega(v) = \omega_p dx^i(v) + \omega_p dx^j(v)$$

COTANGENT BUNDLE $T^*M = \bigcup_p T_p^*M$

LOCAL COORDS. (x^M, ω_v)

CE

SIS



DEF: TENSOR: OF TYPE (k, l) OF RANK $(k+l)$ IS A
MULTILINEAR MAP

$$T: \underbrace{T_p^* \times T_p^* \times \dots \times T_p^*}_k \times \underbrace{T_p \times \dots \times T_p}_l \rightarrow \mathbb{R}$$

δt^v

COTANGENT BUNDLE $T^*M = \bigcup_p T_p^*M$

LOCAL COORDS.

(x^μ, ω_ν)

HAMILTONIAN MECH.

"MOMENTUM"

$\omega = \omega_\mu dx^\mu = \omega_\nu \frac{\partial x^\mu}{\partial x^\nu} dx^\nu$

$\omega_\nu = \frac{\partial x^\mu}{\partial x^\nu} \omega_\mu$

DEF: TENSOR OF TYPE (r, l) OF RANK $(r+l)$ IS A
MULTILINEAR MAP

$$T: \underbrace{T_p^* \times T_p^* \times \dots \times T_p^*}_r \times \underbrace{T_p \times \dots \times T_p}_l \rightarrow \mathbb{R}$$

$$T^{\alpha_1 \dots \alpha_r \beta_1 \dots \beta_l} = \frac{\partial x^{\alpha_1}}{\partial x^{\beta_1}} \dots \frac{\partial x^{\alpha_r}}{\partial x^{\beta_r}} T^{\delta_1 \dots \delta_r \epsilon_1 \dots \epsilon_l}$$

$$T = T^\alpha_{\beta\gamma} \left(\frac{\partial}{\partial x^\alpha} \otimes dx^\beta \otimes dx^\gamma \right)$$

COMPONENTS
BASIS

$$T^\alpha_{\beta\gamma} = T \left(dx^\alpha, \frac{\partial}{\partial x^\beta}, \frac{\partial}{\partial x^\gamma} \right)$$

HOMEWORK ?

TENSOR ALGEBRA.

i) $T + S$ IF T & S ARE OF THE SAME TYPE.

ii) TENSOR PRODUCT \otimes

$$T \otimes S$$

BIGGER TENSOR

EX. $T = T^{\alpha}_{\beta} \frac{\partial}{\partial x^{\alpha}} \otimes dx^{\beta}$, $S = S_{\alpha\beta} dx^{\alpha} dx^{\beta}$

TENSOR ALGEBRA:

i) $T + S$ IF T & S ARE OF THE SAME TYPE.

ii) TENSOR PRODUCT \otimes

$$T \otimes S$$

BIGGER TENSOR

EX. $T = T^\alpha{}_\beta \frac{\partial}{\partial x^\alpha} \otimes dx^\beta$, $S = S_{\alpha\beta} dx^\alpha dx^\beta$

$$T \otimes S = \underbrace{T^\alpha{}_\beta S_{\alpha\beta}}_{(T \otimes S)^\alpha{}_\beta} \underbrace{\frac{\partial}{\partial x^\alpha} \otimes dx^\beta \otimes dx^\beta}_{\text{BASIS}}$$

iii) CONTRACTION .. "CREATES SMALLER TENSORS"

$$T = T^{\alpha}_{\beta} \frac{\partial}{\partial x^{\alpha}} \otimes dx^{\beta}$$

$$T_{\text{CONTR}} = T^{\alpha}_{\beta} \underbrace{dx^{\beta} \left(\frac{\partial}{\partial x^{\alpha}} \right)}_{\delta^{\beta}_{\alpha}} = T^{\alpha}_{\alpha}$$

(dx^M)

$$\omega = \omega_\mu dx^\mu = \left(\omega_\mu \frac{\partial x^\mu}{\partial x^\nu} \right) dx^\nu$$

$\omega_\nu \frac{\partial x^\nu}{\partial x^\mu} \omega_\mu$

$$T(V_1, V_2, \omega_1, \omega_2)$$

$\rightarrow \mathbb{R}$



(105) / \mathbb{R}^n

BASIS

① CONNECTION

WE WANT TO DIFFERENTIATE TENSORS

TO PRODUCE NEW TENSORS \circ

REMINO:

$$\left. \frac{df}{dt} \right|_{t_0} = \lim_{s \rightarrow 0} \frac{f(t_0+s) - f(t_0)}{s}$$

i) $t_0 \leftrightarrow p \in M, \quad t_0+s \leftrightarrow p + \delta p \in M$

ii) HOW TO COMPARE V_p & $V_{p+\delta p}$ ^{↑ WHAT IS THIS?}
WHEN THEY LIVE IN DIFFERENT SPACES?

A MIX OF UP & DOWN INDICES.

3 STANDARD
POSSIBILITIES

LIE DERIVATIVE (NEED A VECTOR
FIELD U)

A MIX OF UP & DOWN INDICES.

3 STANDARD
POSSIBILITIES

LIE DERIVATIVE (NEED A VECTOR
FIELD U)
SIMPLEST (RUTH'S COURSE!)

EXTERIOR DERIVATIVE (ONLY WORKS ON
ANTISYMMETRIC TENSORS)

POSSIBILITIES

SIMPLEST

(NEED A VECTOR FIELD \underline{U})
(RUTH'S COURSE!)

EXTERIOR DERIVATIVE

(NO NEED FOR ADD. STRUCTURE)

(ONLY WORKS ON ANTI-SYMMETRIC TENSORS)

COVARIANT DERIVATIVE

(MOST COMPLICATED)

NEEDS CONNECTION

$\nabla_{\alpha} \beta^{\gamma}$



3 STANDARD
POSSIBILITIES

LIE DERIVATIVE (NEED A VECTOR
FIELD \underline{U})
SIMPLEST (RUTH'S COURSE!)

EXTERIOR DERIVATIVE (ONLY WORKS ON
(NO NEED FOR ADD. STRUCTURE) ANTISYMMETRIC TENSORS)

COVARIANT DERIVATIVE (MOST COMPLICATED)
NEEDS CONNECTION $\nabla_{\alpha} \beta_{\mu}$



TANGEN

LIE DERIVATIVE (NEED A VECTOR FIELD \underline{U})

SIMPLEST (RUTH'S COURSE!)

$$\mathcal{L}_U f = U^M \partial_M f$$

EXTERIOR DERIVATIVE (ONLY WORKS ON ANTISYMMETRIC TENSORS)
(NO NEED FOR ADD. STRUCTURE)

$$U^M \nabla_M f$$

COVARIANT DERIVATIVE (MOST COMPLICATED)
NEEDS CONNECTION $\nabla_{\alpha} \beta^{\gamma}$

HAS LOCAL COOR