

Title: Classical Physics Lecture - 090823

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Collection: Classical Physics 2023/24

Date: September 08, 2023 - 9:00 AM

URL: <https://pirsa.org/23090028>

Proof (Noether 1st)

If $\tilde{\delta}_s q(t)$ is an infinitesimal sym of L , i.e. $\tilde{\delta}_s L = \frac{d}{dt} R_s$, then

$$Q_s(t) = \sum_i p_i \tilde{\delta}_s q^i - R_s \quad \text{is conserved}$$

on shell of the e.o.m.

$$\left[p_i(t) = \frac{\partial L}{\partial \dot{q}^i}(q(t), \dot{q}(t), t) \right]$$

$$\tilde{\delta}_s L = \boxed{\frac{d}{dt} R_s}$$

$$= \sum_i \left(\frac{\partial L}{\partial q^i} \tilde{\delta} q^i + \frac{\partial L}{\partial \dot{q}^i} \tilde{\delta} \dot{q}^i \right), \quad \tilde{\delta} \dot{q}^i = \frac{d}{dt} \tilde{\delta} q^i$$

$$= \sum_i \left(\underbrace{\left(\frac{\partial L}{\partial q^i} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}^i} \right)}_{\text{E.L. eqm}} \tilde{\delta} q^i + \frac{d}{dt} \left(\underbrace{\frac{\partial L}{\partial \dot{q}^i}}_{p_i} \tilde{\delta} q^i \right) \right)$$

Rearranging, $\frac{d}{dt} \left(\sum_i p_i \tilde{\delta} q^i - R_s \right) = - \sum_i (E.L.)_i \tilde{\delta} q^i \stackrel{\wedge}{=} 0$

$$\dot{\tilde{\delta}}_i^j = \frac{d}{dt} \tilde{\delta}_i^j$$

$$+ \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_i} \tilde{\delta}_i^j \right)$$

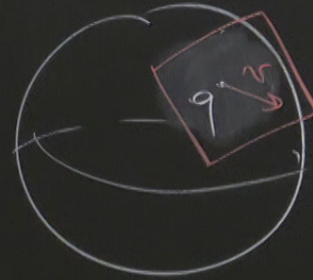
\tilde{p}_i

$$\tilde{\delta}_i^j - R_s = - \sum_i (EL)_i \tilde{\delta}_i^j \stackrel{\wedge}{=} 0$$

$$TQ \ni (q^i, v^i)$$

$$T^*Q \ni (q^i, p_i)$$

TQ



$$p_i = \frac{\partial L}{\partial v^i}$$

$$(v^i)' = \varepsilon R^i_j v^j$$

$$P_i' = \frac{\partial L(v')}{\partial v'^i} = \sum_j \frac{\partial v^j}{\partial v'^i} \frac{\partial L}{\partial v^j} = (R^{-1})^j_i P_j$$

↑
inverse!

$$L(v') = L(v)$$

$$\sum_j P_j v^j = \sum_j P_j' v'^j$$

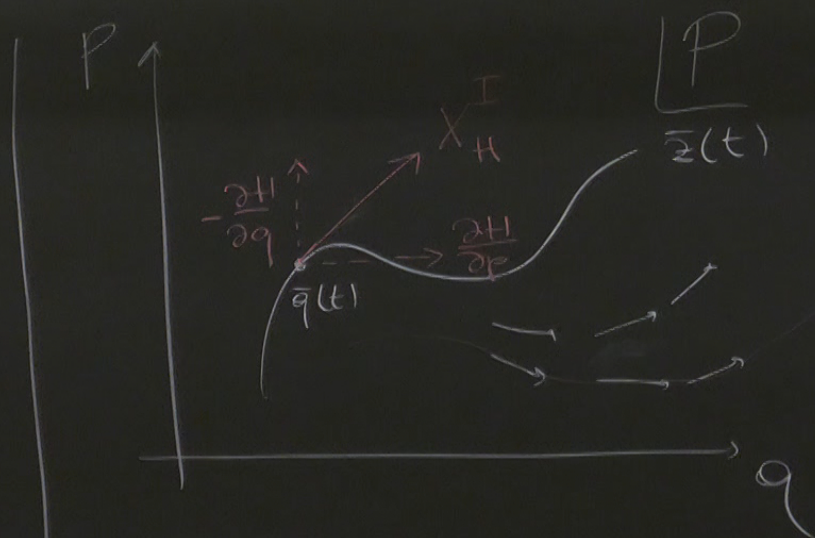
$\begin{matrix} \uparrow & \uparrow \\ T^* & T \\ \mathcal{Q} & \mathcal{Q} \end{matrix}$

PHASE SPACE STRUCTURES

$$\mathcal{P} := T^*Q \quad \text{phase space}$$

$$\cup_{\mathbb{I}} \mathbb{I} = (q^i, p_i) \quad \begin{array}{l} \mathbb{I} = 1, \dots, 2n \\ i = 1, \dots, n \end{array}$$

$\dim(\mathcal{P})$ must be even.



on shell history

$$\bar{z}(t) = (\bar{q}(t), \bar{p}(t))$$

$$\dot{\bar{z}}^I = X_H^I(\bar{z}(t))$$

$$X^I = \begin{pmatrix} \partial H / \partial p_i \\ -\partial H / \partial q_i \end{pmatrix}$$

$$\begin{cases} \dot{\bar{q}}^i = \left. \frac{\partial H}{\partial p_i} \right|_{(\bar{q}, \bar{p}, t)} \\ \dot{\bar{p}}_i = - \left. \frac{\partial H}{\partial q^i} \right|_{(\bar{q}, \bar{p}, t)} \end{cases}$$

$$\dot{\bar{z}}^I = X_H^I(\bar{z}(t))$$

$$X_H^I = \begin{pmatrix} \partial H / \partial p_i \\ -\partial H / \partial q^i \end{pmatrix} \text{ Hamiltonian vector field}$$

$$\begin{cases} \dot{q}^i = \frac{\partial H}{\partial p_i} |_{(\bar{q}, \bar{p}, t)} \\ \dot{p}_i = -\frac{\partial H}{\partial q^i} |_{(\bar{q}, \bar{p}, t)} \end{cases}$$

Analogy w/ fluid dyn.

- history of system in P = trajectory of fluid particle
- Hamilt. v.f. X_H^I = velocity field of fluid

$$\dot{\bar{z}}^I = X_H^I(\bar{z}(t))$$

$$X_H^I = \begin{pmatrix} \partial H / \partial p_i \\ -\partial H / \partial q^i \end{pmatrix} \text{ Hamiltonian} \\ \text{vector field}$$

off shell

on shell

$$\begin{cases} \dot{\bar{q}}^i = \frac{\partial H}{\partial p_i} \Big|_{(\bar{q}, \bar{p}, t)} \\ \dot{\bar{p}}_i = -\frac{\partial H}{\partial q^i} \Big|_{(\bar{q}, \bar{p}, t)} \end{cases}$$

Analogy w/ fluid dyn.

- history of system in \mathcal{P} = trajectory of fluid particle
- Hamilt. v.f. X_H^I = velocity field of fluid

$$F: \mathcal{P} \times \mathbb{R} \mapsto \mathbb{R}$$

$$(z, t) \mapsto F(z, t)$$

given an onshell history $\bar{z}(t)$:

$$f_{\bar{z}}(t) = F(\bar{z}(t), t)$$

$\frac{d}{dt} f_{\bar{z}} =$ change of F along
the trajectory

$$= \frac{\partial F}{\partial t} + \sum_i \frac{\partial F}{\partial q^i} \dot{q}^i + \frac{\partial F}{\partial p_i} \dot{p}_i \Big|_{\bar{z}}$$

$$= \frac{\partial F}{\partial t} + \sum_i \left(\frac{\partial F}{\partial q^i} \frac{\partial H}{\partial p_i} - \frac{\partial F}{\partial p_i} \frac{\partial H}{\partial q^i} \right) \Big|_{\bar{z}}$$

Poisson bracket

$$\{ \cdot, \cdot \} : C^\infty(P) \times C^\infty(P) \longrightarrow C^\infty(P)$$

$$(F, H) \mapsto \{F, H\} = \sum_i \frac{\partial F}{\partial q^i} \frac{\partial H}{\partial p_i} - \frac{\partial F}{\partial p_i} \frac{\partial H}{\partial q^i}$$

$$\Rightarrow \dot{f}_z = \partial_t F + \{F, H\} \Big|_{\bar{z}}$$

or more conveniently

$$\dot{F} = \partial_t F + \{F, H\} "$$

$$\frac{F}{p_i} \dot{p}_i \Big|_{\bar{z}}$$

$$\frac{F \partial H}{p_i \partial q^i} \Big|_{\bar{z}}$$

$$\dot{\bar{z}}^I = X_H^I(\bar{z}(t))$$

$$X_H^I = \begin{pmatrix} \partial H / \partial p_i \\ -\partial H / \partial q^i \end{pmatrix} \text{ Hamiltonian vector field}$$

(1) off shell
on shell

$$\begin{cases} \dot{\bar{q}}^i = \frac{\partial H}{\partial p_i} \Big|_{(\bar{q}, \bar{p}, t)} \\ \dot{\bar{p}}_i = -\frac{\partial H}{\partial q^i} \Big|_{(\bar{q}, \bar{p}, t)} \end{cases}$$

vector field over P
↓
one arrow at $p \in P$
↓
at all P 's

Analogy w/ fluid dyn.

- history of system in $P =$ trajectory of fluid patch
- Hamilt. v.f. $X_H^I =$ velocity field of fluid

Poisson bracket

$$\{ \cdot, \cdot \} : C^\infty(P) \times C^\infty(P) \longrightarrow C^\infty(P)$$

$$(F, H) \mapsto \{F, H\} = \sum_i \frac{\partial F}{\partial q_i} \frac{\partial H}{\partial p_i} - \frac{\partial F}{\partial p_i} \frac{\partial H}{\partial q_i}$$

$$\Rightarrow \dot{f}_z = \partial_t F + \{F, H\} \Big|_{\bar{z}}$$

or more conveniently

$$\dot{F} = \partial_t F + \{F, H\}$$

↖ Hamilton's eom

$$\frac{\partial F}{\partial p_i} \dot{p}_i \Big|_{\bar{z}}$$

$$\left(\frac{\partial F}{\partial p_i} \frac{\partial H}{\partial q_i} \right) \Big|_{\bar{z}}$$

properties of $\{ \cdot, \cdot \}$

1) skew sym

$$\{F, G\} + \{G, F\} = 0$$

2) (bi) linear

$$\{F, aG + H\} = a\{F, G\} + \{F, H\}$$

\uparrow
 $a \in \mathbb{R}$

3) Jacobi

$$\{F, \{G, H\}\} + \{G, \{H, F\}\} + \{H, \{F, G\}\} = 0 \leftarrow \left(\frac{\partial}{\partial q} \right)$$

4) Leibniz

$$\{F, GH\} = \{F, G\}H + \{F, H\}G$$

A vector space $V (= C^\infty(P))$ with a bracket satisfying (1-3) is a Lie algebra, and the bracket is called a Lie bracket.

, }

$$\{F, G\} + \{G, F\} = 0$$

$$\{F, aG + H\} = a\{F, G\} + \{F, H\}$$

\uparrow
 $a \in \mathbb{R}$

$$\{F, \{G, H\}\} + \{G, \{H, F\}\} + \{H, \{F, G\}\} = 0 \leftarrow \left(\frac{\partial}{\partial q} \frac{\partial}{\partial p} = \frac{\partial}{\partial p} \frac{\partial}{\partial q} \right)$$

$$\{F, GH\} = \{F, G\}H + \{F, H\}G$$

$(= C^\infty(P))$ with a bracket satisfying (1-3)
and the bracket is called a Lie bracket.

Revisited time translation sym:

Recall H on a history is its energy.

$$\frac{dE}{dt} = \dot{H} = \partial_t H + \underbrace{\{H, H\}}_{\text{skew} = 0} = \partial_t H = \overset{\text{Legendre}}{\uparrow} -\partial_t L$$

\Rightarrow if $\partial_t H = 0$ then energy is conserved
 \updownarrow
 $\partial_t L$

Rmk (Quantum theory)

$$\{q^i, q^j\} = 0 = \{P_i, P_j\}$$
$$\{q^i, P_j\} = \delta_j^i = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{otherwise} \end{cases}$$

Remind us of

$$[\hat{q}^i, \hat{q}^j] = 0 = [\hat{P}_i, \hat{P}_j]$$

$$[\hat{q}^i, \hat{P}_j] = i\hbar \delta_j^i$$

every)

$$\delta_{ij}^i = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{otherwise} \end{cases}$$

$$F \in C^\infty(P \times \mathbb{R})$$

$$\dot{F} = \partial_t F + \{F, H\}$$

Ehrenfest thm

$$\hat{F} : \mathcal{H} \times \mathbb{R} \rightarrow \mathcal{H}$$

\swarrow Hilbert space
 \searrow time

$$[\hat{P}_i, \hat{P}_j]$$

with δ_{ij}

$$\frac{d}{dt} \langle \hat{F} \rangle = \langle \partial_t \hat{F} \rangle + \frac{1}{i\hbar} \langle [\hat{F}, \hat{H}] \rangle$$

Canonical transf.

can we choose other q, p 's that suit us better?

i.e. $(q, p) \mapsto (Q, P) = (Q(q, p), P(q, p))$

such that the formulation of Ham. mech. does not change?

$$f(q, p) = F(Q(q, p), P(q, p)) \quad \text{same for } g(q, p) = G(\dots)$$

$$\{F, G\}_{(Q, P)} \stackrel{!}{=} \{f, g\}_{(q, p)}$$

$$\{f, g\}_{(q, p)} = \sum_i \frac{\partial f}{\partial q^i} \frac{\partial g}{\partial p_i} - \frac{\partial f}{\partial p_i} \frac{\partial g}{\partial q^i}$$

$$L = \sum_k \left[\frac{\partial F}{\partial Q^k} \right] \left[\frac{\partial G}{\partial q^k} \right]$$

$$= \sum_{k, l} \{Q^k, Q^l\}_{(P, q)} \frac{\partial F}{\partial Q^k} \frac{\partial G}{\partial Q^l} + \text{same for } P$$

$$+ \{Q^k, P_l\}_{(q, P)} \left(\frac{\partial F}{\partial Q^k} \frac{\partial G}{\partial P_l} - \frac{\partial F}{\partial P_l} \frac{\partial G}{\partial Q^k} \right)$$

$$\stackrel{!}{=} \{F, G\}_{(P, Q)}$$

we need:

$$\left[\begin{array}{l} \{Q^k, Q^e\}_{(q,P)} = 0 = \{P_k, P_e\}_{(q,P)} \\ \{Q^k, P_e\}_{(q,P)} = \delta^k_e \end{array} \right.$$

we then call $(q,P) \mapsto (Q,P)$

a canonical transformation

for P

$$\left(\frac{\partial G}{\partial Q^k} \right)$$

Infinitesimal canonical transf.

$$Q^i = q^i + \epsilon \delta q^i, \quad \delta q^i = \delta q^i(q, p)$$

$$P_i = p_i + \epsilon \delta p_i, \quad \delta p_i = \delta p_i(q, p)$$

$$\{Q^i, P_j\} \stackrel{!}{=} \delta_j^i$$

$$\underbrace{\{q^i, p_j\}}_{\delta_j^i} + \epsilon \left(\underbrace{\{q^i, \delta p_j\}}_{=0} + \underbrace{\{\delta q^i, p_j\}}_{=0} \right)$$

$$\text{iff. } \frac{\partial \delta p_j}{\partial p_i} + \frac{\partial \delta q^i}{\partial q^i} = 0 \quad (*)$$

therefore if

$$\left\{ \begin{array}{l} \delta q^i = \{q^i, F\} = \frac{\partial F}{\partial p_i} \\ \delta p_i = \{p_i, F\} = -\frac{\partial F}{\partial q^i} \end{array} \right.$$

for some $F(p, q)$, then $(*) = 0$

therefore if

$$\begin{cases} \delta q^i = \{q^i, F\} = \frac{\partial F}{\partial p_i} \\ \delta p_i = \{p_i, F\} = -\frac{\partial F}{\partial q^i} \end{cases}$$

for some $F(p, q)$, then $(*) = 0$

This means that

$\delta z^I = \{z^I, F\}$ is an
infinitesimal
canonical transf.

Rmk

In particular
time evolution ($F=H$)
is a canonical transformation, i.e.

$$\begin{cases} q_0^i = \text{the value of } q^i \text{ at time } t_0 \\ p_0^i = \text{---} \text{---} p_i \text{---} \text{---} \\ q_1^i = \text{---} \text{---} \text{---} \text{---} t_1 \\ p_1^i = \text{---} \text{---} \end{cases}$$

then $(q_0, p_0) \rightarrow (q_1, p_1)$
is a canonical
transf.

$z(t)$ off shell
 on shell

$$\dot{z}^I = X_H^I(z(t)) \quad X_H^I = \begin{pmatrix} \partial H / \partial p_i \\ -\partial H / \partial q^i \end{pmatrix} \text{ Hamiltonian vector field}$$

$$\ddot{z}^I = \{z^I, H\} / \dot{z}^I$$

$$X_H = \sum_I X_H^I \frac{\partial}{\partial z^I}$$

$$X_H^I(z) = \{z^I, H\}$$

$$\sum_I X_H^I \frac{\partial F}{\partial z^I} = \{F, H\} \leftrightarrow X_H = \{ \cdot, H \}$$

a vector field is a "directional derivative" and in particular

$$X : C^\infty(P) \rightarrow C^\infty(P)$$

$$X(af + g) = aX(f) + X(g)$$

$$X(fg) = fX(g) + gX(f)$$

therefore if

$$\begin{cases} \delta q^i = \{q^i, F\} = \frac{\partial F}{\partial p_i} \\ \delta p_i = \{p_i, F\} = -\frac{\partial F}{\partial q^i} \end{cases}$$

for some $F(p, q)$, then

This means that

$$\delta z^I = \{z^I, F\}$$

infinitesimal
canonical transf.