

Title: Tutorial 3A: Bootstrapping GNY model

Speakers: Aike Liu

Collection: Mini-Course of Numerical Conformal Bootstrap

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Hyperion Tutorial 2

Bootstrap Fermions & GNY

Bootstrap Mini Course: Tutorial 3a

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scalars-3d/fermions-3d

Bound.hs

Crossing
equations

OPE coefficients

Set up SDP

Project.hs

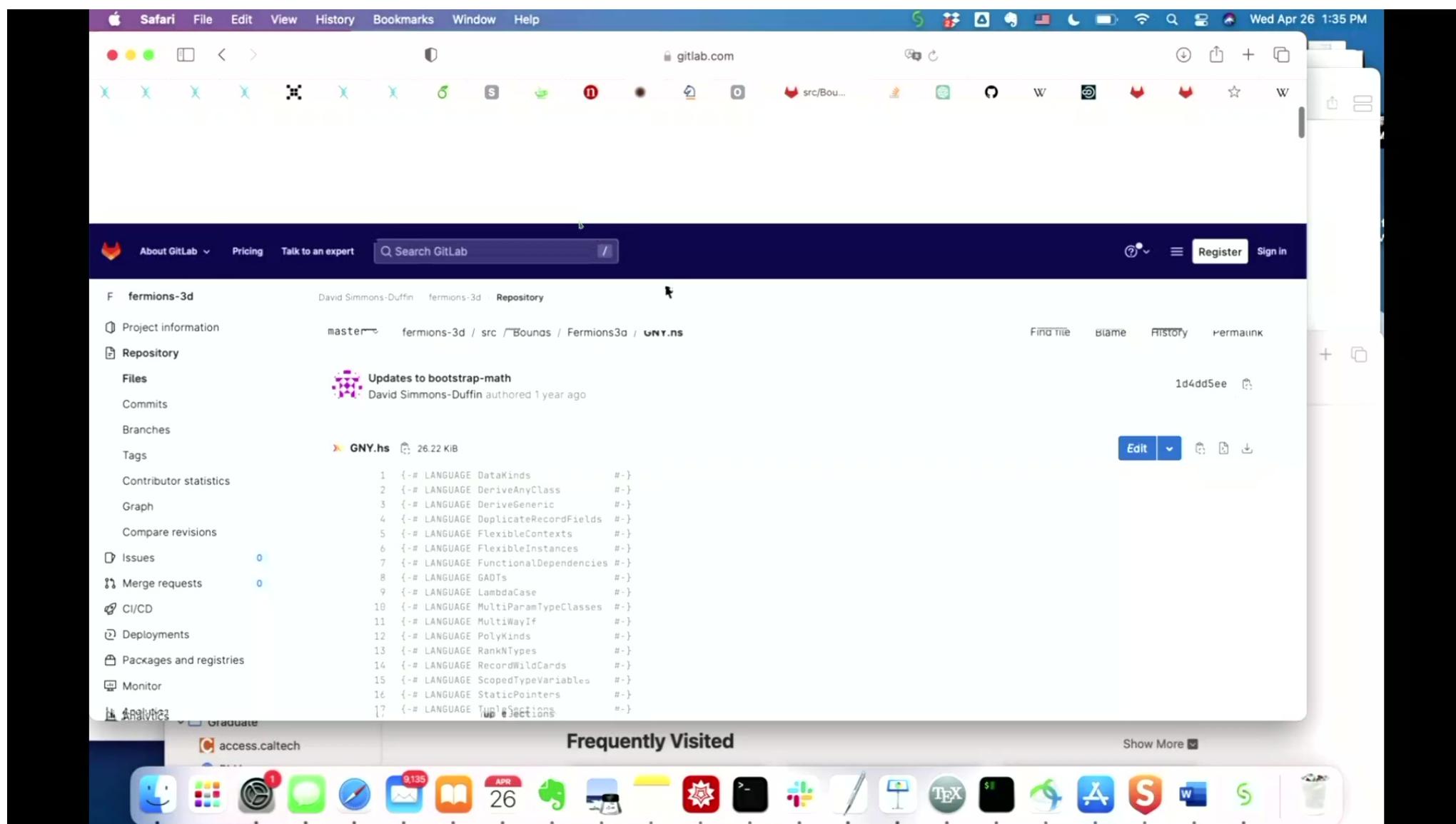
Impose gaps, set up
OPE search

Numerical parameters

such as Λ , κ (pole order),
precisions and SDPB
parameters

submit HPC remote job

- Four fermions bootstrap $\langle\psi\psi\psi\psi\rangle$
 - Crossing Equations
 - OPE channels in SO(3) basis
 - 3d Block types
- GNY bootstrap mixing (σ, ψ) with $O(N)$ symmetry
 - $O(N)$ representation
 - Crossing Equations with global symmetry blocks



- Four fermions bootstrap $\langle\psi\psi\psi\psi\rangle$
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- GNY bootstrap mixing (σ, ψ) with $O(N)$ symmetry
 - $O(N)$ representation
 - Crossing Equations with global symmetry blocks

$$\lambda_{\psi\psi O}^a \quad \langle\psi\psi|\psi\psi\rangle = -\langle\psi\psi|\psi\psi\rangle$$

$$[\frac{1}{2}, -\frac{1}{2}, 0]^{\pm} \quad [\frac{1}{2}, \frac{1}{2}, -1]^{\pm}$$
$$\langle\uparrow\uparrow\uparrow\uparrow\uparrow\rangle^+, \langle\uparrow\uparrow\uparrow\uparrow\uparrow\rangle^-, \langle\uparrow\uparrow\downarrow\downarrow\rangle^+, \langle\uparrow\downarrow\uparrow\downarrow\rangle^+, \langle\downarrow\uparrow\uparrow\downarrow\rangle^+$$

$$\partial_y^{2n}\partial_x^{2m+1}g_{\langle\uparrow\uparrow\uparrow\uparrow\rangle^+} = 0, \quad n \geq 1, m \geq 0,$$
$$\partial_y^{2n}\partial_x^{2m+1}g_{\langle\uparrow\downarrow\uparrow\downarrow\rangle^+} = 0, \quad n \geq 0, m \geq 0,$$
$$\partial_y^{2n}\partial_x^{2m+1}(g_{\langle\uparrow\uparrow\downarrow\downarrow\rangle^+} + g_{\langle\downarrow\uparrow\uparrow\downarrow\rangle^+}) = 0, \quad n \geq 0, m \geq 0,$$
$$\partial_y^{2n}\partial_x^{2m}(g_{\langle\uparrow\uparrow\downarrow\downarrow\rangle^+} - g_{\langle\downarrow\uparrow\uparrow\downarrow\rangle^+}) = 0, \quad n \geq 0, m \geq 0,$$
$$\partial_y^{2n+1}\partial_x^{2m}g_{\langle\uparrow\uparrow\uparrow\uparrow\rangle^-} = 0, \quad n \geq 0, m \geq 0,$$

External operators

```
data ExternalOp s = Psi  
    deriving (Show, Eq, Ord, Enum, Bounded)  
  
instance (Reifies s Rational) => HasRep (ExternalOp s) (B3d.ConformalRep Rational) where  
    rep psi = B3d.ConformalRep (reflect psi) (1/2)
```

<ψψψψ> so `ExternalOp` contains one operator only.

No need for `ExternalDims`

```
data ConformalRep a = ConformalRep  
    { delta :: a  
    , spin :: HalfInteger  
    } deriving (Eq, Ord, Show, Generic, Binary, F  
  
data FourFermions3d = FourFermions3d  
    { deltaPsi :: Rational  
    , spectrum :: Spectrum (Int, B3d.Parity)  
    , objective :: Objective  
    , spins :: [Int]  
    , blockParams :: B3d.Block3dParams  
    } deriving (Show, Eq, Ord, Generic, Binary, ToJSON, FromJSON)  
  
data Objective  
= Feasibility  
| StressTensorOPEBound BoundDirection  
deriving (Show, Eq, Ord, Generic, Binary, ToJSON, FromJSON)
```

Crossing Equations

\diamond is the infix operator defined in the **Semigroup** type class.

```
crossingEqsWithFlavorSign
  :: forall s a b . (Ord b, Fractional a, Eq a)
  => Sign 'XDir
  -> FourPointFunctionTerm (ExternalOp s) B3d.Q4Struct b a
  -> V 5 (Taylors 'XT, FreeVect b a)
crossingEqsWithFlavorSign fSign g0 = toV
  ( (V.filter positiveN .
    xtTaylors (fSign<>xOdd) yEven, g (u,u,u,u) yEven)
  , (xtTaylors (fSign<>xOdd) yEven, g (u,d,u,d) yEven)
  , (xtTaylors (fSign<>xOdd) yEven, g (u,u,d,d) yEven + g (d,u,u,d) yEven)
  , (xtTaylors (fSign<>xEven) yEven, g (u,u,d,d) yEven - g (d,u,u,d) yEven)
  , (xtTaylors (fSign<>xEven) yOdd, g (u,u,u,u) yOdd)
  )
where
  u = 1/2
  d = -1/2
  g qs sgn = g0 Psi Psi Psi Psi (B3d.Q4Struct qs sgn)
  positiveN (TaylorCoeff (Derivative (_,n))) = n > 0
```

Crossing Equations

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  positiveN (TaylorCoeff (Derivative (_,n))) = n > 0
```

$$\langle \uparrow\uparrow\uparrow\uparrow\rangle^+, \langle \uparrow\uparrow\uparrow\uparrow\rangle^-, \langle \uparrow\uparrow\downarrow\downarrow\rangle^+, \langle \uparrow\downarrow\uparrow\downarrow\rangle^+, \langle \downarrow\uparrow\uparrow\downarrow\rangle^+$$

$$\partial_y^{2n} \partial_x^{2m+1} g_{\langle \uparrow\uparrow\uparrow\uparrow \rangle^+} = 0, \quad n \geq 1, m \geq 0,$$

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$$\partial_y^{2n} \partial_x^{2m+1} (g_{\langle \uparrow\uparrow\downarrow\downarrow \rangle^+} + g_{\langle \downarrow\uparrow\uparrow\downarrow \rangle^+}) = 0, \quad n \geq 0, m \geq 0,$$

$$\partial_y^{2n} \partial_x^{2m} (g_{\langle \uparrow\uparrow\downarrow\downarrow \rangle^+} - g_{\langle \downarrow\uparrow\uparrow\downarrow \rangle^+}) = 0, \quad n \geq 0, m \geq 0,$$

$$\partial_y^{2n+1} \partial_x^{2m} g_{\langle \uparrow\uparrow\uparrow\uparrow \rangle^-} = 0, \quad n \geq 0, m \geq 0,$$

Crossing Equations

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  :: forall s a b . (Ord b, Fractional a, Eq a)
  => Sign 'XDir
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  -> V [5] (Taylors 'XT, FreeVect b a)
crossingEqsWithFlavorSign fSign g0 = toV
  ( V.filter positiveN .
    xtTaylors (fSign <> xOdd) yEven, g (u,u,u,u) yEven)
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)
where
  u = 1/2
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  g qs sgn = g0 Psi Psi Psi Psi (B3d.Q4Struct qs sgn)
  positiveN (TaylorCoeff (Derivative (_,n))) = n > 0
```

Crossing Matrix

```
crossingMatFF
  :: forall j s a. (KnownNat j, Fractional a, Eq a)
  => V j (OPECoefficient (ExternalOp s) (B3d.S03Struct Rational Rational Delta)) a)
  -> Tagged s (CrossingMat j 5 B3d.Block3d a)
crossingMatFF channel =
  pure $ mapBlocks B3d.Block3d $
  crossingMatrix channel (crossingEqs @s)
```

OPE channels

```
data Channel j b where
  ParityEven_SpinEven :: B3d.ConformalRep Delta -> Channel 2 B3d.Block3d
  -- | When l=0, only one of the parity even spin even structures is
  -- allowed
  ParityEven_Scalar   :: Delta           -> Channel 1 B3d.Block3d
  ParityOdd_SpinEven :: B3d.ConformalRep Delta -> Channel 1 B3d.Block3d
  ParityOdd_SpinOdd  :: B3d.ConformalRep Delta -> Channel 1 B3d.Block3d
  IdentityChannel    :: Channel 1 B3d.IdentityBlock3d
  StressTensorChannel :: Channel 1 B3d.Block3d
```

OPE	$\mathcal{O} \in (l, P, \mu)$
$\psi \times \psi$	($l \in 2\mathbb{Z}$, even)
	($l \in 2\mathbb{Z}$, odd,
	($l \in 2\mathbb{Z} + 1$, odd,

This is a data type containing **6 constructors**. For general channels, we have three channels depending on parity and spins. Notice that we have one special case on **Parity_Even** $spin = 0$ operator.

Unlike the channels in Ising Bootstrap where the only type parameter is **j**, the channel of spinning bootstrap has two phantom type variables **j** and **b**. This is because identity block is different than general blocks in **Blocks_3d**.

```

mat [ParityEven_SpinEven] internalRep) = crossingMatFF $  

fmap (opeCoeffIdentical_ Psi internalRep) $  

-- | These structures are related by an l-dependent linear  

-- transformation to r1, r2 from [1]  

toV [so3 0 l, so3 1 l)  

where  

l = B3d.spin internalRep

```

OPE	$\mathcal{O} \in (l, P, \mu)$	$\langle \psi^i \psi^j \mathcal{O}^a \rangle$ Structures
$\psi \times \psi$	$l \in 2\mathbb{Z}$, even	$ 0, l\rangle$
	$l \in 2\mathbb{Z}$, odd,	$(\sqrt{l+1} 1, l+1\rangle - \sqrt{l} 1, l-1\rangle)$
	$l \in 2\mathbb{Z} + 1$, odd,	$(\sqrt{l+1} 1, l-1\rangle + \sqrt{l} 1, l+1\rangle)$

```

mat [ParityOdd_SpinOdd] internalRep) = crossingMatFF $  

fmap (opeCoeffIdentical_ Psi internalRep) $ toV r4  

where  

l = B3d.spin internalRep  

-- | This is related by an l-dependent coefficient to r4 from [1]  

r4 = sqrt (realToFrac l + 1) *^ so3 1 (l-1)  

+ sqrt (realToFrac l) *^ so3 1 (l+1)

```

OPE channels

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data Channel j b where
  ParityEven_SpinEven :: B3d.ConformalRep Delta -> Channel 2 B3d.Block3d
  -- | When l=0, only one of the parity even spin even structures is
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  ParityEven_Scalar   :: Delta           -> Channel 1 B3d.Block3d
  ParityOdd_SpinEven :: B3d.ConformalRep Delta -> Channel 1 B3d.Block3d
  ParityOdd_SpinOdd  :: B3d.ConformalRep Delta -> Channel 1 B3d.Block3d
  IdentityChannel    :: Channel 1 B3d.IdentityBlock3d
  StressTensorChannel :: Channel 1 B3d.Block3d
```

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  ParityOdd_SpinOdd  :: B3d.ConformalRep Delta -> Channel 1 B3d.Block3d
  IdentityChannel    :: Channel 1 B3d.IdentityBlock3d
  StressTensorChannel :: Channel 1 B3d.Block3d

so3 :: (Num a, Eq a) => HalfInteger -> HalfInteger -> FreeVect B3d.S03StructLabel a
so3 j12 j123 = vec (B3d.S03StructLabel j12 j123)                                this is a singleton vector

mat
  :: forall s a j b . (Reifies s Rational, Floating a, Eq a)
  => Channel j b
  -> Tagged s (CrossingMat j 5 b a)
```

```

mat [ParityEven_SpinEven] internalRep) = crossingMatFF $  

fmap (opeCoeffIdentical_ Psi internalRep) $  

-- | These structures are related by an l-dependent linear  

-- transformation to r1, r2 from [1]  

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where  

l = B3d.spin internalRep

```

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	$l \in 2\mathbb{Z}$, odd,	$ 1, l\rangle$
	$l \in 2\mathbb{Z} + 1$, odd,	$(\sqrt{l+1} 1, l+1\rangle - \sqrt{l} 1, l-1\rangle)$

```

mat [ParityOdd_SpinOdd] internalRep) = crossingMatFF $  

fmap (opeCoeffIdentical_ Psi internalRep) $ toV r4  

where  

l = B3d.spin internalRep  

-- | This is related by an l-dependent coefficient to r4 from [1]  

r4 = sqrt (realToFrac l + 1) *^ so3 1 (l-1)  

+ sqrt (realToFrac l) *^ so3 1 (l+1)

```

```
mat IdentityChannel =
  pure $ mapBlocks B3d.IdentityBlock3d $
  crossingMatrix (toV identityOpe) (crossingEqs @s)
where
  identityOpe o1 o2
    | o1 == o2 = vec (rep @(ExternalOp s) o1)
    | otherwise = 0
```

```

-- | Data needed for "bulk" positivity conditions not associated with
-- external operators, the identity or the stress tensor.
data BulkConstraint where
  BulkConstraint
    :: KnownNat j -- ^ Existentially quantify over j
    => DeltaRange -- ^ Isolated or Continuum constraint
    -> Channel j B3d.Block3d -- ^ The associated Channel
    -> BulkConstraint

bulkConstraints :: FourFermions3d -> [BulkConstraint]
bulkConstraints f = do
  parity <- [minBound .. maxBound]
  l <- case parity of
    B3d.ParityEven -> filter even (spins f)
    B3d.ParityOdd -> spins f
  (delta, range) <- listDeltas (l, parity) (spectrum f)
  let internalRep = B3d.ConformalRep delta (fromIntegral l)
  pure $ case (parity, even l, l) of
    (B3d.ParityEven, True, 0) -> BulkConstraint range $ ParityEven_Scalar delta
    (B3d.ParityEven, True, _) -> BulkConstraint range $ ParityEven_SpinEven internalRep
    (B3d.ParityOdd, True, _) -> BulkConstraint range $ ParityOdd_SpinEven internalRep
    (B3d.ParityOdd, False, _) -> BulkConstraint range $ ParityOdd_SpinOdd internalRep
    _ -> error "Internal representation disallowed"

```

This code is restructured a little compared with IsingSigEps.hs
The bootstrapConstraint function is moved to **ffSDP**

```
mat IdentityChannel =
  pure $ mapBlocks B3d.IdentityBlock3d $
  crossingMatrix (toV identityOpe) (crossingEqs @s)
where
  identityOpe o1 o2
    | o1 == o2 = vec (rep @(ExternalOp s) o1)
    | otherwise = 0
```

```

ffSDP
:: forall a m.
  ( Binary a, Typeable a, RealFloat a, Applicative m
  , BlockFetchContext B3d.Block3d a m
  )
=> FourFermions3d
-> SDPB.SDP m a
ffSDP f@FourFermions3d{..} = runTagged deltaPsi $ do
  let dv = derivsVecFF f
  bulk <- for (bulkConstraints f) $
    \(BulkConstraint range c) ->
      BSDP.bootstrapConstraint blockParams dv range <$> mat c
  unit <- mat IdentityChannel
  stress <- mat StressTensorChannel
  let
    stressConstraint = BSDP.isolatedConstraint blockParams dv stress
    (cons, obj, norm) = case objective of
      Feasibility ->
        ( stressConstraint : bulk
        , BSDP.bootstrapObjective blockParams dv $ zero `asTypeOf` unit
        , BSDP.bootstrapNormalization blockParams dv $ unit
        )
      StressTensorOPEBound dir ->
        ( bulk
        , BSDP.bootstrapObjective blockParams dv unit
        , BSDP.bootstrapNormalization blockParams dv $ boundDirSign dir *^ stress
        )
  return $ SDPB.SDP
  { SDPB.objective      = obj
  , SDPB.normalization = norm
  , SDPB.positiveConstraints = cons
  }

```

Compare to **isingSigEpsSDP**,
 this function replace some **do**
 notation with **let**

```
instance ToSDP FourFermions3d where
    type SDPFetchKeys FourFermions3d = '[ B3d.BlockTableKey ]'
    toSDP = ffSDP

instance SDPFetchBuildConfig FourFermions3d where
    sdpFetchConfig _ _ boundFiles =
        liftIO . B3d.readBlockTable (blockDir boundFiles) :&: FetchNil
    sdpDepBuildChain _ bConfig boundFiles =
        SomeBuildChain $ noDeps $ block3dBuildLink bConfig boundFiles

instance Static (Binary FourFermions3d)           where closureDict = cPtr (static Dict)
instance Static (Show FourFermions3d)              where closureDict = cPtr (static Dict)
instance Static (ToSDP FourFermions3d)             where closureDict = cPtr (static Dict)
instance Static (ToJSON FourFermions3d)            where closureDict = cPtr (static Dict)
instance Static (SDPFetchBuildConfig FourFermions3d) where closureDict = cPtr (static Dict)
instance Static (BuildInJob FourFermions3d)         where closureDict = cPtr (static Dict)
```

```

ffSDP
:: forall a m.
  ( Binary a, Typeable a, RealFloat a, Applicative m
  , BlockFetchContext B3d.Block3d a m
  )
=> FourFermions3d
-> SDPB.SDP m a
ffSDP f@FourFermions3d{..} = runTagged deltaPsi $ do
  let dv = derivsVecFF f
  bulk <- for (bulkConstraints f) $
    \(BulkConstraint range c) ->
      BSDP.bootstrapConstraint blockParams dv range <$> mat c
  unit <- mat IdentityChannel
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  let
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        , BSDP.bootstrapNormalization blockParams dv $ unit
        )
      StressTensorOPEBound dir ->
        ( bulk
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        , BSDP.bootstrapNormalization blockParams dv $ boundDirSign dir *^ stress
        )
  return $ SDPB.SDP
  { SDPB.objective      = obj
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Compare to **isingSigEpsSDP**,
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      Feasibility ->
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      StressTensorOPEBound dir ->
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  return $ SDPB.SDP
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  }

```

Compare to **isingSigEpsSDP**,
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GNY (σ , Ψ) with O(N)

1. Define data types for the external operators
2. Define data types for global symmetry representations
3. Define your computational problem (physical model and constraints) and goals (test feasible solutions or bound OPEs)
4. Write down crossing equations
5. Define OPE channels and three-point structures
6. Convert the bootstrap problem into an SDP

$$\begin{aligned}\sigma : & \quad (0, \text{odd}, \bullet) \\ \psi_i : & \quad (\tfrac{1}{2}, \text{even}, \square).\end{aligned}$$

$$\left. \begin{array}{l} \{\lambda_{\sigma\sigma\mathcal{O}}^a, \lambda_{\sigma\psi\mathcal{O}}^a, \lambda_{\psi\psi\mathcal{O}}^a\} \\ \\ \langle\sigma\sigma|\psi\psi\rangle = \langle\psi\sigma|\sigma\psi\rangle, \\ \langle\psi\sigma|\psi\sigma\rangle = -\langle\psi\sigma|\psi\sigma\rangle \\ \langle\psi\psi|\psi\psi\rangle = -\langle\psi\psi|\psi\psi\rangle \end{array} \right\}$$

$$\begin{aligned}T_{a_{\text{conf}}, a_{\text{flavor}}}^{ijk} &= t_{a_{\text{conf}}}^{ijk} Q_{a_{\text{flavor}}}^{ijk}, \\ T_{I_{\text{conf}}, a_{\text{flavor}}}^{ijkl} &= t_{I_{\text{conf}}}^{ijkl} Q_{I_{\text{flavor}}}^{ijkl}.\end{aligned}$$

src/Bounds/Scalars3d/ONRep.hs

```
import Bounds.Scalars3d.ONRep (ON3PtStruct(..),  
                                ON4PtStruct(..),  
                                ONRep(..),  
                                evalONBlock)
```

O(N) representations of a single operator

```
data ONRep = ONSinglet | ONVector | ONSymTensor | ONAntiSymTensor  
deriving (Show, Eq, Ord, Generic, Binary, ToJSON, FromJSON, Bounded, Enum)
```

$$\begin{aligned} Q_{\bullet}^{\bullet,\bullet} &= 1, \\ Q_{\square}^{i,j} &= \delta^{ij}, \\ Q_{\square}^{ij,\bullet} &= \delta^{ij}, \\ Q_{\square\square}^{ij,(kl)} &= \frac{1}{2} (\delta^{ik}\delta^{jl} + \delta^{il}\delta^{jk}) - \frac{1}{N}\delta^{ij}\delta^{kl}, \\ Q_{\square\square}^{ij,[kl]} &= \frac{1}{2} (\delta^{ik}\delta^{jl} - \delta^{il}\delta^{jk}). \end{aligned}$$

```
data ON3PtStruct n = ON3PtStruct ONRep ONRep ONRep  
deriving (Eq, Ord)
```

O(N) three-point structures is unique.

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$\psi_i = (\frac{1}{2}, \text{even}, \dots)$

$$\left\{ \begin{array}{l} \{\lambda_{\sigma\sigma O}^s, \lambda_{\sigma\sigma O}^s, \lambda_{\nu\nu O}^s\} \\ \langle \sigma\sigma | \psi\psi \rangle = \langle \psi\sigma | \sigma\psi \rangle, \\ \langle \psi\sigma | \psi\sigma \rangle = -\langle \psi\sigma | \psi\sigma \rangle \\ \langle \psi\psi | \psi\psi \rangle = -\langle \psi\psi | \psi\psi \rangle \end{array} \right. \quad \left\{ \begin{array}{l} T_{A_{\text{loop}} A_{\text{loop}}}^{ijk} = t_{A_{\text{loop}}}^{ijk} Q_{A_{\text{loop}}}^{ijk}, \\ T_{L_{\text{loop}} L_{\text{loop}}}^{ijkl} = t_{L_{\text{loop}}}^{ijkl} Q_{L_{\text{loop}}}^{ijkl}. \end{array} \right.$$

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src/Bounds/Scalars3d/ONRep.hs

```
import Bounds.Scalars3d.ONRep (ON3PtStruct(..),
                                ON4PtStruct(..),
                                ONRep(..),
                                evalONBlock)

data ONRep = ONSinglet | ONVector | ONSymTensor | ONAntiSymTensor
deriving (Show, Eq, Ord, Generic, Binary, ToJSON, FromJSON, Bounded, Enum)
```

ON representations of a single operator

```
data ONRep = ONSinglet | ONVector | ONSymTensor | ONAntiSymTensor
deriving (Show, Eq, Ord, Generic, Binary, ToJSON, FromJSON, Bounded, Enum)

data ON3PtStruct n = ON3PtStruct ONRep ONRep ONRep
deriving (Eq, Ord)
ON three-point structures is unique
```

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src/Bounds/Fermions3d/GNY.hs

```
T_{A_{\text{loop}} A_{\text{loop}}}^{ijk} = t_{A_{\text{loop}}}^{ijk} Q_{A_{\text{loop}}}^{ijk}.
```

```
newtype Lorentz_DM_Struct = Lorentz_DM_Struct B3d_303StructLabel
deriving (Eq, Ord)

instance ThreePointStructure
(B3d_303StructLabel a b, ON3PtStruct a)
Lorentz_DM_Struct
(B3d_ConformalRep a, ONRep)
```

77853239775956797334435696400505729899306224529205911688646780604326943421

src/Bounds/Scalars3d/ONRep.hs

```
import Bounds.Scalars3d.ONRep (ON3PtStruct(..),
                                ON4PtStruct(..),
                                ONRep(..),
                                evalONBlock)
```

O(N) representations of a single operator

```
data ONRep = ONSinglet | ONVector | ONSymTensor | ONAntiSymTensor
deriving (Show, Eq, Ord, Generic, Binary, ToJSON, FromJSON, Bounded, Enum)
```

$Q_{\bullet}^{*\bullet} \equiv 1,$

$Q_{\square}^{ij} = \delta^{ij},$

$Q_{\square}^{ij,\bullet} = \delta^{ij},$

$Q_{\square}^{ij,(kl)} = \frac{1}{2} (\delta^{ik}\delta^{jl} + \delta^{il}\delta^{jk}) - \frac{1}{N} \delta^{ij}\delta^{kl},$

$Q_{\square}^{ij,[kl]} = \frac{1}{2} (\delta^{ik}\delta^{jl} - \delta^{il}\delta^{jk}).$

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T3-Fermion&GNY

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O(N) representations of a single operator

```
data ONRep = ONSinglet | ONVector | ONSymTensor | ONAntiSymTensor
deriving (Show, Eq, Ord, Generic, Binary, ToJSON, FromJSON, Bounded, Enum)
```

$Q_{\bullet}^{*,*} = 1,$

$Q_{\square}^{ij} = \delta^{ij},$

$Q_{\square}^{ij,*} = \delta^{ij},$

$Q_{\text{irrep}}^{(\mathcal{O}_1 \mathcal{O}_2), \mathcal{O}}$

$Q_{\square\square}^{ij,(kl)} = \frac{1}{2} (\delta^{ik} \delta^{jl} + \delta^{il} \delta^{jk}) - \frac{1}{N} \delta^{ij} \delta^{kl},$

$Q_{\square\square}^{ij,[kl]} = \frac{1}{2} (\delta^{ik} \delta^{jl} - \delta^{il} \delta^{jk}).$

O(N) three-point structures is unique.

```
data ON3PtStruct n = ON3PtStruct ONRep ONRep ONRep
deriving (Eq, Ord)
```

src/Bounds/Fermions3d/GNY.hs

$T_{a_{\text{conf}}, a_{\text{flavor}}}^{ijk} = t_{a_{\text{conf}}}^{ijk} Q_{a_{\text{flavor}}}^{ijk}.$

newtype Lorentz_ON_Struct = Lorentz_ON_Struct B3d S03StructLabel

deriving (Eq, Ord)

instance ThreePointStructure

(B3d S03Struct a b, ON3PtStruct a)

Lorentz_ON_Struct

(B3d ConformalReg a, ONRep)

(B3d ConformalReg b, ONRep) where

makeStructure (l1, r1) (l2, r2) (l3, r3) (Lorentz_ON_Struct s03Struct) =

(makeStructure l1 l2 l3 s03Struct, ON3PtStruct r1 r2 r3)

As mentioned, O(N) three-point structure is unique, hence, we just need a "wrapper".

And declare this newtype an instance of ThreePointStructure

77853239775956797334435696400505729899306224529205911688646780604326943421

src/Bounds/Scalars3d/ONRep.hs

```
import Bounds.Scalars3d.ONRep (ON3PtStruct(..),  
                                ON4PtStruct(..),  
                                ONRep(..),  
                                evalONBlock)
```

O(N) representations of a single operator

```
data ONRep = ONSinglet | ONVector | ONSymTensor | ONAntiSymTensor  
deriving (Show, Eq, Ord, Generic, Binary, ToJSON, FromJSON, Bounded, Enum)
```

$$\begin{aligned} Q_{\bullet}^{\bullet,\bullet} &= 1, \\ Q_{\square}^{i,j} &= \delta^{ij}, \\ Q_{\square}^{ij,\bullet} &= \delta^{ij}, \\ Q_{\square\square}^{ij,(kl)} &= \frac{1}{2} (\delta^{ik}\delta^{jl} + \delta^{il}\delta^{jk}) - \frac{1}{N}\delta^{ij}\delta^{kl}, \\ Q_{\square\square}^{ij,[kl]} &= \frac{1}{2} (\delta^{ik}\delta^{jl} - \delta^{il}\delta^{jk}). \end{aligned}$$

```
data ON3PtStruct n = ON3PtStruct ONRep ONRep ONRep  
deriving (Eq, Ord)
```

O(N) three-point structures is unique.

src/Bounds/Scalars3d/ONRep.hs

Evaluate O(N) flavor blocks, the result is a number

```
evalONBlock :: (Reifies n Rational, Fractional a, Eq a) => Block (ON3PtStruct n) (ON4PtStruct n) -> a
evalONBlock (Block (ON3PtStruct r1 r2 r) (ON3PtStruct r4 r3 r')) f
| r /= r' = 0
| otherwise = case ((r1, r2, r3, r4), r, f) of
  ((ONVector, ONVector, ONVector, ONVector), _, _) -> FV.coeff f (onVectorBlock r)
  ((ONSinglet, ONSinglet, ONSinglet, ONSinglet), ONSinglet, Unique) -> 1
  ((ONVector, ONVector, ONSinglet, ONSinglet), ONSinglet, Unique) -> 1
  ((ONSinglet, ONSinglet, ONVector, ONVector), ONSinglet, Unique) -> 1
  ((ONVector, ONSinglet, ONVector, ONSinglet), ONSinglet, Unique) -> 1
```

Coefficient of f, a ON4PtStruct, in the vector (onVectorBlock r)

onVectorBlock

```
:: forall n a . (Reifies n Rational, Fractional a, Eq a)
=> ONRep
```

```
-> FreeVect (ON4PtStruct n) a
```

onVectorBlock r = case r of

```
ONSinglet      -> v12_34
```

```
ONSymTensor   -> 1/2 *^ (v13_24 + v23_14) - 1/nGroup *^ v12_34
```

```
ONAntiSymTensor -> 1/2 *^ (v23_14 - v13_24)
```

```
_              -> 0
```

```
where
```

ON4PtStruct's are invariant under crossing

ONRep's are representations of operators

src/Bounds/Scalars3d/ONRep.hs

```
import Bounds.Scalars3d.ONRep (ON3PtStruct(..),  
                                ON4PtStruct(..),  
                                ONRep(..),  
                                evalONBlock)
```

O(N) representations of a single operator

```
data ONRep = ONSinglet | ONVector | ONSymTensor | ONAntiSymTensor  
deriving (Show, Eq, Ord, Generic, Binary, ToJSON, FromJSON, Bounded, Enum)
```

$$\begin{aligned} Q_{\bullet}^{\bullet,\bullet} &= 1, \\ Q_{\square}^{i,j} &= \delta^{ij}, \\ Q_{\square}^{ij,\bullet} &= \delta^{ij}, \\ Q_{\square\square}^{ij,(kl)} &= \frac{1}{2} (\delta^{ik}\delta^{jl} + \delta^{il}\delta^{jk}) - \frac{1}{N}\delta^{ij}\delta^{kl}, \\ Q_{\square\square}^{ij,[kl]} &= \frac{1}{2} (\delta^{ik}\delta^{jl} - \delta^{il}\delta^{jk}). \end{aligned}$$

```
data ON3PtStruct n = ON3PtStruct ONRep ONRep ONRep  
deriving (Eq, Ord)
```

O(N) three-point structures is unique.

src/Bounds/Fermions3d/GNY.hs

$$T_{a_{\text{conf}}, a_{\text{flavor}}}^{ijk} = t_{a_{\text{conf}}}^{ijk} Q_{a_{\text{flavor}}}^{ijk},$$

```
newtype Lorentz_ON_Struct = Lorentz_ON_Struct B3d.S03StructLabel
deriving (Eq, Ord)

instance ThreePointStructure
(B3d.S03Struct a a b, ON3PtStruct n)
Lorentz_ON_Struct
(B3d.ConformalRep a, ONRep)
(B3d.ConformalRep b, ONRep) where
makeStructure (l1,r1) (l2,r2) (l3,r3) (Lorentz_ON_Struct so3Struct) =
(makeStructure l1 l2 l3 so3Struct, ON3PtStruct r1 r2 r3)
```

As mentioned, O(N) three-point structure is unique, hence, we just need a “wrapper”.

And declare this newtype an instance of [ThreePointStructure](#)

src/Bounds/Fermions3d/GNY.hs

```
data ChannelType = ChannelType HalfInteger B3d.Parity ONRep
  deriving (Show, Eq, Ord, Generic, Binary, ToJSON, FromJSON, ToJS

data GNY = GNY
  { externalDims :: ExternalDims
  , nGroup      :: Rational
  , spectrum    :: Spectrum ChannelType
  , objective   :: Objective
  , spins        :: [HalfInteger]
  , blockParams :: B3d.Block3dParams
  } deriving (Show, Eq, Ord, Generic, Binary, ToJSON, FromJSON)
```

```
data Spectrum r = Spectrum
  { twistGap      :: Rational
  , deltaGaps     :: Map r Delta
  , deltaIsolateds :: Map r (Set Delta)
  } deriving (Show, Eq, Ord, Generic, Bin
```

src/Bounds/Fermions3d/GNY.hs

$$T_{a_{\text{conf}}, a_{\text{flavor}}}^{ijk} = t_{a_{\text{conf}}}^{ijk} Q_{a_{\text{flavor}}}^{ijk},$$

```
newtype Lorentz_ON_Struct = Lorentz_ON_Struct B3d.S03StructLabel
deriving (Eq, Ord)

instance ThreePointStructure
(B3d.S03Struct a a b, ON3PtStruct n)
Lorentz_ON_Struct
(B3d.ConformalRep a, ONRep)
(B3d.ConformalRep b, ONRep) where
makeStructure (l1,r1) (l2,r2) (l3,r3) (Lorentz_ON_Struct so3Struct) =
(makeStructure l1 l2 l3 so3Struct, ON3PtStruct r1 r2 r3)
```

As mentioned, O(N) three-point structure is unique, hence, we just need a “wrapper”.

And declare this newtype an instance of [ThreePointStructure](#)

src/Bounds/Scalars3d/ONRep.hs

```
import Bounds.Scalars3d.ONRep (ON3PtStruct(..),  
                                ON4PtStruct(..),  
                                ONRep(..),  
                                evalONBlock)
```

O(N) representations of a single operator

```
data ONRep = ONSinglet | ONVector | ONSymTensor | ONAntiSymTensor  
deriving (Show, Eq, Ord, Generic, Binary, ToJSON, FromJSON, Bounded, Enum)
```

$$\begin{aligned} Q_{\bullet}^{\bullet,\bullet} &= 1, \\ Q_{\square}^{i,j} &= \delta^{ij}, \\ Q_{\square}^{ij,\bullet} &= \delta^{ij}, \\ Q_{\square\square}^{ij,(kl)} &= \frac{1}{2} (\delta^{ik}\delta^{jl} + \delta^{il}\delta^{jk}) - \frac{1}{N}\delta^{ij}\delta^{kl}, \\ Q_{\square\square}^{ij,[kl]} &= \frac{1}{2} (\delta^{ik}\delta^{jl} - \delta^{il}\delta^{jk}). \end{aligned}$$

```
data ON3PtStruct n = ON3PtStruct ONRep ONRep ONRep  
deriving (Eq, Ord)
```

O(N) three-point structures is unique.

src/Bounds/Fermions3d/GNY.hs

```
data ChannelType = ChannelType HalfInteger B3d.Parity ONRep
  deriving (Show, Eq, Ord, Generic, Binary, ToJSON, FromJSON, ToJS

data GNY = GNY
  { externalDims :: ExternalDims
  , nGroup      :: Rational
  , spectrum    :: Spectrum ChannelType
  , objective   :: Objective
  , spins        :: [HalfInteger]
  , blockParams :: B3d.Block3dParams
  } deriving (Show, Eq, Ord, Generic, Binary, ToJSON, FromJSON)
```

```
data Spectrum r = Spectrum
  { twistGap      :: Rational
  , deltaGaps     :: Map r Delta
  , deltaIsolateds :: Map r (Set Delta)
  } deriving (Show, Eq, Ord, Generic, Bin
```

```

mat
  :: forall j b n s a . (Reifies s ExternalDims, Reifies n Rational, Fractional b)
  => Channel j b
  -> Tagged '(n,s) (CrossingMat j [22] b a)

mat (SpinEven_ParityEven_TensorSym iConformalRep) = crossingMatGNY $ toV
  ( opeCoeffIdentical_ Psi iRep (so3 0 l)
  , opeCoeffIdentical_ Psi iRep (so3 1 l)
  )
where
  iRep = (iConformalRep, ONSymTensor)
  l = B3d.spin iConformalRep

```

OPE	$\mathcal{O} \in (l, P, \mu)$	$\langle \psi^i \psi^j \mathcal{O}^a \rangle$ Structures
	($l \in 2\mathbb{Z}$, even, $\mu \in \{\bullet, \square\}$)	$T_{\mu}^{ija} 0, l\rangle$ $T_{\mu}^{ija} 1, l\rangle$
$\psi \times \psi$	($l \in 2\mathbb{Z} + 1$, even, $\mu = \square$)	$T_{\mu}^{ija} 0, l\rangle$ $T_{\mu}^{ija} 1, l\rangle$
	($l \in 2\mathbb{Z}$, odd, $\mu \in \{\bullet, \square\}$)	$T_{\mu}^{ija}(\sqrt{l+1} 1, l+1\rangle - \sqrt{l} 1, l-1\rangle)$
	($l \in 2\mathbb{Z} + 1$, odd, $\mu \in \{\bullet, \square\}$)	$T_{\mu}^{ija}(\sqrt{l+1} 1, l-1\rangle + \sqrt{l} 1, l+1\rangle)$
	($l \in (2\mathbb{Z})_{\geq 2}$, odd, $\mu = \square$)	$T_{\mu}^{ija}(\sqrt{l+1} 1, l-1\rangle + \sqrt{l} 1, l+1\rangle)$
	($l \in 2\mathbb{Z} + 1$, odd, $\mu = \square$)	$T_{\mu}^{ija}(\sqrt{l+1} 1, l+1\rangle - \sqrt{l} 1, l-1\rangle)$

```
-- External
mat ExternalOpChannel =
  pure . mapBlocksFreeVect (evalFlavorCoeff . unzipBlock) $
  crossingMatrixExternal opeCoefficients (crossingEqsGNY @n) [Sig,Psi]
where
  evalFlavorCoeff (b,f) = evalONBlock f *^ vec (B3d.Block3d b)
  opeCoefficients :: V 1 (OPECoefficientExternal (ExternalOp s) (B3d.S03Struct Rational Rational Det))
  opeCoefficients = toV $ \o1 o2 o3 ->
    FV.mapBasis (makeStructure (rep o1) (rep o2) (rep o3)) $
    case (o1, o2, o3) of
      (Psi,Psi,Sig) -> - so3 1 1
      (Psi,Sig,Psi) -> so3 (1/2) 0
      (Sig,Psi,Psi) -> - so3 (1/2) 1 --Flipped sign
      _ -> 0
```

```
-- External
mat ExternalOpChannel =
  pure . mapBlocksFreeVect (evalFlavorCoeff . unzipBlock) $
  crossingMatrixExternal opeCoefficients (crossingEqsGNY @n) [Sig,Psi]
where
  evalFlavorCoeff (b,f) = evalONBlock f *^ vec (B3d.Block3d b)
  opeCoefficients :: V 1 (OPECoefficientExternal (ExternalOp s) (B3d.S03Struct Rational Rational Det))
  opeCoefficients = toV $ \o1 o2 o3 ->
    FV.mapBasis (makeStructure (rep o1) (rep o2) (rep o3)) $
    case (o1, o2, o3) of
      (Psi,Psi,Sig) -> - so3 1 1
      (Psi,Sig,Psi) -> so3 (1/2) 0
      (Sig,Psi,Psi) -> - so3 (1/2) 1 --Flipped sign
      _ -> 0
```

src/Bounds/Scalars3d/ONRep.hs

```
data ON4PtStruct n = QPlus | QMinus | Q3 | Unique  
deriving (Eq, Ord)
```

$$\langle\sigma\sigma\sigma\sigma\rangle : Q = 1$$

$$\langle\psi\psi\sigma\sigma\rangle : Q = \delta^{ij}$$

$$\langle\psi\psi\psi\psi\rangle : Q^+ = \delta^{ij}\delta^{kl} + \delta^{il}\delta^{jk}, \text{ crossing even,}$$

$$Q^3 = \delta^{ik}\delta^{jl}, \text{ crossing even,}$$

$$Q^- = \delta^{ij}\delta^{kl} - \delta^{il}\delta^{jk}, \text{ crossing odd.}$$

src/Bounds/Fermions3d/GNY.hs

Crossing Equations from $\langle \psi\psi\psi\psi \rangle$ $\langle \sigma\sigma\sigma\sigma \rangle$

crossingEqSSSS

```
:: forall s a b .  
  FourPointFunctionTerm (ExternalOp s) B3d.Q4Struct b a  
-> V 1 (Taylors 'XT, FreeVect b a)  
crossingEqSSSS g = toV  
(xtTaylors xOdd yEven, g Sig Sig Sig Sig (B3d.Q4Struct (0,0,0,0) yEven))
```

j1 = j2 = j3 = j4 = 0

From FourFermions.hs

crossingEqsWithFlavorSign

```
:: forall s a b . (Ord b, Fractional a, Eq a)  
=> Sign 'XDir  
-> FourPointFunctionTerm (ExternalOp s) B3d.Q4Struct b a  
-> V 5 (Taylors 'XT, FreeVect b a)  
crossingEqsWithFlavorSign fSign g0 = toV
```

Add flavor structures

Crossing Equations of $\langle\psi\psi\sigma\sigma\rangle$, $\langle\psi\sigma\psi\sigma\rangle$

`crossingEqsFFSS`

```
:: forall s a b . (Ord b, Fractional a, Eq a)
=> FourPointFunctionTerm (ExternalOp s) B3d.Q4Struct b a
-> V 6 (Taylors 'XT, FreeVect b a)
```

`crossingEqsFFSS gθ = toV`

```
( ( xtTaylors xOdd yEven, g s s u u yEven + g u s s u yEven ) -- ^
, ( xtTaylors xEven yEven, g s s u u yEven - g u s s u yEven ) -- ^
```

$$g_{[00\frac{1}{2}\frac{1}{2}]^+}^{\sigma\sigma\psi\psi}(x, t) + g_{[\frac{1}{2}00\frac{1}{2}]^+}^{\psi\sigma\sigma\psi}(x, t), \text{xy-odd, y-even} \rightarrow \text{x-odd, y-even}$$

$$g_{[00\frac{1}{2}\frac{1}{2}]^+}^{\sigma\sigma\psi\psi}(x, t) - g_{[\frac{1}{2}00\frac{1}{2}]^+}^{\psi\sigma\sigma\psi}(x, t), \text{xy-even, y-even} \rightarrow \text{x-even, y-even}$$

Add flavor structures

Concatenate All Crossing Equations

```
crossingEqsGNY
:: forall n s a b . (Ord b, Fractional a, Eq a)
=> FourPointFunctionTerm (ExternalOp s) (B3d.Q4Struct, ON4PtStruct n) b a
-> V [22] (Taylors 'XT, FreeVect b a)
crossingEqsGNY g =
    FFFF.crossingEqsWithFlavorSign xEven (map0ps (const Psi) (map4pt (,QPlus) g)) L.++
    FFFF.crossingEqsWithFlavorSign xEven (map0ps (const Psi) (map4pt (,Q3) g)) L.++
    FFFF.crossingEqsWithFlavorSign xOdd (map0ps (const Psi) (map4pt (,QMinus) g)) L.++
    crossingEqsFFSS (map4pt (,Unique) g) L.++
    crossingEqSSSS (map4pt (,Unique) g)
```

```
g qs sgn = g0 Psi Psi Psi Psi (B3d.Q4Struct qs sgn)
g Sig Sig Sig Sig (B3d.Q4Struct (0,0,0,0) yEven))
```

```
map4pt f g o1 o2 o3 o4 s = g o1 o2 o3 o4 (f s)
( , QPlus) structure = (structure, QPlus)
```

$$T_{I_{\text{conf}}, a_{\text{flavor}}}^{ijkl} = t_{I_{\text{conf}}}^{ijkl} Q_{I_{\text{flavor}}}^{ijkl}.$$

Crossing Equations

```
crossingEqsGNY
:: forall n s a b . (Ord b, Fractional a, Eq a)
=> FourPointFunctionTerm (ExternalOp s) (B3d.Q4Struct, ON4PtStruct n) b a
-> V 22 (Taylors 'XT, FreeVect b a)
crossingEqsGNY g =
    FFFF.crossingEqsWithFlavorSign xEven (mapOps (const Psi) (map4pt (,QPlus) g)) L.++
    FFFF.crossingEqsWithFlavorSign xEven (mapOps (const Psi) (map4pt (,Q3) g)) L.++
    FFFF.crossingEqsWithFlavorSign xOdd (mapOps (const Psi) (map4pt (,QMinus) g)) L.++
    crossingEqsFFSS (map4pt (,Unique) g) L.++
    crossingEqSSSS (map4pt (,Unique) g)
```

g qs sgn = g0 Psi Psi Psi Psi (B3d.Q4Struct qs sgn)

mapOps f g o1 o2 o3 o4 s = g (f o1) (f o2) (f o3) (f o4) s

const Psi operator = Psi

```

crossingMatGNY
  :: forall j n s a. (Reifies n Rational, KnownNat j, Fractional a, Eq a)
  => V j (OPECoefficient (ExternalOp s) (B3d.S03Struct Rational Rational Delta, ON3PtStruct n) a)
  -> Tagged '(n,s) (CrossingMat j 22 B3d.Block3d a)
crossingMatGNY channel =
  pure $ mapBlocksFreeVect evalFlavorCoeff . unzipBlock) $
  crossingMatrix channel ((crossingEqsGNY @n @s))
  where
    evalFlavorCoeff (b,f) = evalONBlock f *^ vec (B3d.Block3d b)

```

evalFlavorCoeff (b,f) = evalONBlock f *^ vec (B3d.Block3d b)

Conformal Block Flavor Block

src/Bounds/Scalars3d/ONRep.hs

Evaluate O(N) flavor blocks, the result is a number

```
evalONBlock :: (Reifies n Rational, Fractional a, Eq a) => Block (ON3PtStruct n) (ON4PtStruct n) -> a
evalONBlock (Block (ON3PtStruct r1 r2 r) (ON3PtStruct r4 r3 r')) f
| r /= r' = 0
| otherwise = case ((r1, r2, r3, r4), r, f) of
  ((ONVector, ONVector, ONVector, ONVector), _, _) -> FV.coeff f (onVectorBlock r)
  ((ONSinglet, ONSinglet, ONSinglet, ONSinglet), ONSinglet, Unique) -> 1
  ((ONVector, ONVector, ONSinglet, ONSinglet), ONSinglet, Unique) -> 1
  ((ONSinglet, ONSinglet, ONVector, ONVector), ONSinglet, Unique) -> 1
  ((ONVector, ONSinglet, ONVector, ONSinglet), ONSinglet, Unique) -> 1
```

Coefficient of f, a ON4PtStruct, in the vector (onVectorBlock r)

onVectorBlock

```
:: forall n a . (Reifies n Rational, Fractional a, Eq a)
=> ONRep
```

```
-> FreeVect (ON4PtStruct n) a
```

onVectorBlock r = case r of

```
ONSinglet      -> v12_34
```

```
ONSymTensor   -> 1/2 *^ (v13_24 + v23_14) - 1/nGroup *^ v12_34
```

```
ONAntiSymTensor -> 1/2 *^ (v23_14 - v13_24)
```

```
_              -> 0
```

where

ON4PtStruct's are invariant under crossing

ONRep's are representations of operators

```

bulkConstraints :: GNY -> [BulkConstraint]
bulkConstraints f = do
    parity <- [minBound .. maxBound]
    oNRep <- [minBound .. maxBound]
    l <- case (parity, oNRep) of
        (_, ONVector)           -> filter (not . HI.isInteger) (spins f)
        (B3d.ParityEven, ONSinglet) -> filter HI.isEvenInteger (spins f)
        (B3d.ParityOdd, ONSinglet) -> filter HI.isInteger (spins f)
        (B3d.ParityEven, ONSymTensor) -> filter HI.isEvenInteger (spins f)
        (B3d.ParityOdd, ONSymTensor) -> filter HI.isInteger (spins f)
        (B3d.ParityEven, ONAntiSymTensor) -> filter HI.isOddInteger (spins f)
        (B3d.ParityOdd, ONAntiSymTensor) -> filter (\x -> (x/=0) && (HI.isInteger x)) (spins f)
    (delta, range) <- listDeltas (ChannelType l parity oNRep) (spectrum f)
    let iConformalRep = B3d.ConformalRep delta l
    pure $ case (parity, HI.isEvenInteger l, l, oNRep) of
        (B3d.ParityEven, True, 0, ONSinglet)      -> BulkConstraint range $ Scalar_ParityEven_Singlet delta
        (B3d.ParityEven, True, _, ONSinglet)       -> BulkConstraint range $ SpinEven_ParityEven_Singlet iConformalRep
        (B3d.ParityOdd, True, _, ONSinglet)        -> BulkConstraint range $ SpinEven_ParityOdd_Singlet iConformalRep
        (B3d.ParityOdd, False, _, ONSinglet)       -> BulkConstraint range $ SpinOdd_ParityOdd_Singlet iConformalRep
        (B3d.ParityEven, True, 0, ONSymTensor)     -> BulkConstraint range $ Scalar_ParityEven_TensorSym delta
        (B3d.ParityEven, True, _, ONSymTensor)      -> BulkConstraint range $ SpinEven_ParityEven_TensorSym iConformalRep
        (B3d.ParityOdd, True, _, ONSymTensor)       -> BulkConstraint range $ SpinEven_ParityOdd_TensorSym iConformalRep
        (B3d.ParityOdd, False, _, ONSymTensor)      -> BulkConstraint range $ SpinOdd_ParityOdd_TensorSym iConformalRep
        (B3d.ParityEven, False, _, ONAntiSymTensor) -> BulkConstraint range $ SpinOdd_ParityEven_TensorAntiSym iConformalRep
        (B3d.ParityOdd, False, _, ONAntiSymTensor)   -> BulkConstraint range $ SpinOdd_ParityOdd_TensorAntiSym iConformalRep
        (B3d.ParityOdd, True, _, ONAntiSymTensor)    -> BulkConstraint range $ SpinEven_ParityOdd_TensorAntiSym iConformalRep
        (B3d.ParityEven, False, _, ONVector)         -> BulkConstraint range $ ParityEven_Vector iConformalRep
        (B3d.ParityOdd, False, _, ONVector)          -> BulkConstraint range $ ParityOdd_Vector iConformalRep
    _ -> error $ "Internal representation disallowed: " ++ show((parity,l,oNRep))

```

Practice

1. Take

- Bounds/Fermions3d/GNY.hs

and rewrite them into codes that bootstrap

- (ε, ψ)
- or all three operators $(\sigma, \varepsilon, \psi)$