

Title: Lecture 3: Bootstrapping spinning correlators

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Collection: Mini-Course of Numerical Conformal Bootstrap

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References

- Counting Conformal Correlators
[Kravchuk, Simmons-Duffin '16] arXiv:1612.08987
- Recursion relation for general 3d blocks
[Erramilli, Iliesiu, Kravchuk '19] arXiv:1907.11247
- blocks_3d: Software for general 3d conformal blocks
[Erramilli, Iliesiu, Kravchuk, Landry, Poland, Simmons-Duffin '20] arXiv:2011.01959
- The Gross-Neveu-Yukawa archipelago
[Erramilli, Iliesiu, Kravchuk, AL, Poland, Simmons-Duffin '22]
arXiv:2210.02492

General Blocks

$$\begin{aligned} & \langle \mathcal{O}_i(x_1) \mathcal{O}_j(x_2) \mathcal{O}_k(x_3) \mathcal{O}_l(x_4) \rangle \\ &= \sum_I g_{ijkl}^I(u, v) T_{I,ijkl}(x_1, x_2, x_3, x_4) \\ &\sim \sum_{\mathcal{O}} \frac{\langle \mathcal{O}_i(x_1) \mathcal{O}_j(x_2) | \mathcal{O} \rangle \langle \mathcal{O} | \mathcal{O}_k(x_3) \mathcal{O}_l(x_4) \rangle}{\langle \mathcal{O} | \mathcal{O} \rangle} \end{aligned}$$

$$g_{ijkl}^I(u, v) = \sum_{\Delta, \rho} \sum_{a,b} \lambda_{ij\mathcal{O}}^a \lambda_{kl\mathcal{O}}^b G_{ijkl, \Delta, \rho}^{ab, I}(u, v), \quad \text{conformal blocks}$$

Spinning Operators $d = 3$

$$\langle \phi_1 \phi_2 \phi_3 \phi_4 \rangle \rightarrow \langle \mathcal{O}_1 \mathcal{O}_2 \mathcal{O}_3 \mathcal{O}_4 \rangle$$

We consider Hermitian local primary operators \mathcal{O} with (Δ, j) , represented with $2j$ spinor indices,

$$\mathcal{O}^{(\alpha_1 \cdots \alpha_{2j})}(x).$$

where each index $\alpha_i = 1, 2$, e.g. ψ^α and $V^\mu \rightarrow V^{(\alpha_1 \alpha_2)}$.

Index-free notation, contract each index with a single real polarization spinor

$$\mathcal{O}(x, s) = \mathcal{O}^{(\alpha_1 \cdots \alpha_{2j})}(x) s_{\alpha_1} \cdots s_{\alpha_{2j}}, \quad s_{\alpha_i} \equiv \begin{pmatrix} \xi \\ \bar{\xi} \end{pmatrix}.$$

Spinning Operators $d = 3$

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$$\mathcal{O}(x, s) = \mathcal{O}^{(\alpha_1 \cdots \alpha_{2j})}(x) s_{\alpha_1} \cdots s_{\alpha_{2j}} \quad s_{\alpha_i} \equiv \begin{pmatrix} \xi \\ \bar{\xi} \end{pmatrix}.$$

The time-ordered two-point function for space-like separated x_1, x_2 is given by

$$\langle \mathcal{O}(x_1, s_1) \mathcal{O}(x_2, s_2) \rangle = c_{\mathcal{O}} \frac{i^{2j} (s_1^\alpha \gamma_{\alpha\beta}^\mu s_2^\beta x_{12,\mu})^{2j}}{x_{12}^{2\Delta+2j}},$$

where $x_{12} = x_1 - x_2$, $c_{\mathcal{O}}$ is a positive constant.

Three-point and Four-point functions

- Three-point function, OPE coefficients $\lambda_{ijk}^{(a)}$.

$$\begin{aligned} & \langle \mathcal{O}_i(x_1, s_1) \mathcal{O}_j(x_2, s_2) \mathcal{O}_k(x_3, s_3) \rangle \\ &= \sum_{a \in \mathcal{I}_{ijk}} \lambda_{ijk}^{(a)} \mathbf{T}_{(a),ijk}(x_1, s_1; x_2, s_2; x_3, s_3), \end{aligned}$$

- Four-point function, function coefficients $g_{ijkl}^{(I)}(z, \bar{z})$.

$$\begin{aligned} & \langle \mathcal{O}_i(x_1, s_1) \mathcal{O}_j(x_2, s_2) \mathcal{O}_k(x_3, s_3) \mathcal{O}_l(x_4, s_4) \rangle \\ &= \sum_{I \in \mathcal{I}_{ijkl}} g_{ijkl}^{(I)}(z, \bar{z}) \mathbf{T}_{(I),ijkl}(x_1, s_1; x_2, s_2; x_3, s_3; x_4, s_4), \end{aligned}$$

- Block decomposition of each function coefficient.

$$g_{ijkl}^I(z, \bar{z}) = \sum_{\Delta, j} \sum_{a,b} \lambda_{ij\mathcal{O}}^a \lambda_{kl\mathcal{O}}^b G_{ijkl, \Delta, j}^{ab, I}(z, \bar{z})$$

Crossing symmetry

$$\sum \begin{array}{c} 1 \\ \diagup \quad \diagdown \\ \textcircled{\mathcal{O}} \\ \diagdown \quad \diagup \\ 2 \qquad 3 \end{array} = \sum \begin{array}{c} 1 \\ \diagup \quad \diagdown \\ \textcircled{\mathcal{O}} \\ \diagup \quad \diagdown \\ 2 \qquad 3 \end{array}$$

$$\langle \mathcal{O}_i(x_1, s_1) \mathcal{O}_j(x_2, s_2) | \mathcal{O}_k(x_3, s_3) \mathcal{O}_l(x_4, s_4) \rangle$$

$$= \pm \langle \mathcal{O}_k(x_3, s_3) \mathcal{O}_j(x_2, s_2) | \mathcal{O}_i(x_1, s_1) \mathcal{O}_l(x_4, s_4) \rangle.$$

Factor out the tensor structures,

$$g_{ijkl}^I(z, \bar{z}) \mp \sum_J M_J^I g_{kjil}^J(1-z, 1-\bar{z}) = 0.$$

$$g_{ijkl}^I(z, \bar{z}) = \sum_{\Delta, \rho} \sum_{a,b} \lambda_{ij\mathcal{O}}^a \lambda_{kl\mathcal{O}}^b G_{ijkl, \Delta, \rho}^{ab, I}(z, \bar{z})$$

Blocks_3d

↳

$$G_{\Delta,j}^{ab,I}(z, \bar{z}) \propto r^\Delta h_{\Delta,j}^{ab,I}(z, \bar{z})$$

$$h_{\Delta,j}^{ab,I}(z, \bar{z}) = h_{\infty,j,I}^{ab}(z, \bar{z}) + \sum_{i \in \mathcal{P}_j} \frac{(a_0 r)^{\eta_{j,i}}}{\Delta - \Delta_{j,i}} (\mathcal{L}_{j,i})_{a'}^a (\mathcal{R}_{j,i})_{b'}^b h_{\Delta'_{j,i}, j'_{j,i}, I}^{a'b'}(z, \bar{z}).$$

Blocks_3d computes blocks assuming that

- the three-point structures are defined in $SO(3)$ basis,
 $a = (j_{12}, j_{12}\mathcal{O})$, $b = (j_{43}, j_{43}\mathcal{O})$.
- the four-point structures defined in q -basis,
 $I = [q_1 q_2 q_3 q_4]$

Three-Point Structures: q -basis

Given quantum numbers (Δ_i, j_i) , the q -basis structures are

$$T_{a=[q_1, q_2, q_3]}^{ijk}, q_i \in \{-j_i, -j_i + 1, \dots, j_i\}, q_1 + q_2 + q_3 = 0.$$

The structures $T_{[q_1, q_2, q_3]}^{ijk}(x_1, s_1; x_2, s_2; x_3, s_3)$ are defined by requiring that in the following configuration,

$$x_1 = (0, 0, 0), x_2 = (0, 0, 1), x_3(L) = (0, 0, L),$$

the following identity holds

$$\lim_{L \rightarrow +\infty} L^{2\Delta_3} T_{[q_1, q_2, q_3]}^{ijk}(x_1, s_1; x_2, s_2; x_3, s_3) = \prod_{i=1}^3 ((s_i)_1)^{j_i+q_i} ((s_i)_2)^{j_i-q_i}.$$

Three-Point Structures: q -basis

Given quantum numbers (Δ_i, j_i) , the q -basis structures are

$$T_{a=[q_1, q_2, q_3]}^{ijk}, \quad q_i \in \{-j_i, -j_i + 1, \dots, j_i\}, \quad q_1 + q_2 + q_3 = 0.$$

$T_{[q_1, q_2, q_3]}^{ijk}$ transform nicely under space parity

$$T_{[q_1, q_2, q_3]}^{ijk}(x_1, s_1; x_2, s_2; x_3, s_3) \rightarrow T_{[-q_1, -q_2, -q_3]}^{ijk}(x_1, s_1; x_2, s_2; x_3, s_3)$$

and similarly under other permutations.

If we want structures invariant under some transformations, we can construct them easily in q -basis.

Example : $\langle \sigma\psi\mathcal{O} \rangle$

Start from q-basis $[q_1, q_2, q_3]$, $j_1 = 0, j_2 = 1/2, q_3 = -q_1 - q_2$,
 $[q_1 q_2 q_3] = [0, 1/2, -1/2], [0, -1/2, 1/2]$.

Assuming that σ is odd and ψ is even under parity, then \mathcal{O} and T_a have opposite parity,

$$\langle \sigma\psi\mathcal{O} \rangle \sim \lambda^a T_a$$

$$[q_1, q_2, q_3] \rightarrow [-q_1, -q_2, -q_3].$$

We then define the parity-definite structures

$$[q_1 q_2 q_3]^{\pm} = [q_1 q_2 q_3] \pm [-q_1, -q_2, -q_3].$$

$$[0, 1/2, -1/2]^+, \quad [0, 1/2, -1/2]^-. \quad \text{Navigation icons: back, forward, search, etc.}$$

Bootstrap Spinning Operators

└ Blocks3d + Examples (σ, ψ)

└ Three-Point Structures

$SO(3)$ -basis

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The $SO(3)$ basis structures are labeled by pairs (j_{12}, j_{123})

$$j_{12} \in \{|j_1 - j_2|, |j_1 - j_2| + 1, \dots, j_1 + j_2\},$$

$$j_{123} \in \{|j_3 - j_{12}|, |j_3 - j_{12}| + 1, \dots, j_3 + j_{12}\}.$$

Want to relate $T_{(j_{12}, j_{123})}^{ijk}(x_1, s_1; x_2, s_2; x_3, s_3)$ with

$T_{[q_1, q_2, q_3]}^{ijk}(x_1, s_1; x_2, s_2; x_3, s_3)$

Example : $\langle \sigma \psi \mathcal{O} \rangle$

Then we use CG coefficient to write them in $SO(3)$ basis. For example

$$[0, 1/2, -1/2] = \frac{(-1)^{j-1/2}}{\sqrt{2 \binom{2j}{j+\frac{1}{2}}}} \left(\left| \frac{1}{2}, j - \frac{1}{2} \right\rangle + \left| \frac{1}{2}, j + \frac{1}{2} \right\rangle \right).$$

$$[0, -1/2, 1/2] = \frac{(-1)^{j-1/2}}{\sqrt{2 \binom{2j}{j+\frac{1}{2}}}} \left(\left| \frac{1}{2}, j - \frac{1}{2} \right\rangle + \left| \frac{1}{2}, j - \frac{1}{2} \right\rangle \right).$$

$$[0, 1/2, -1/2]^+ = \frac{(-1)^{j-1/2}}{\sqrt{2 \binom{2j}{j+\frac{1}{2}}}} \left| \frac{1}{2}, j - \frac{1}{2} \right\rangle \Rightarrow (-1)^{j-1/2} \left| \frac{1}{2}, j - \frac{1}{2} \right\rangle$$

$$[0, 1/2, -1/2]^- = \frac{(-1)^{j-1/2}}{\sqrt{2 \binom{2j}{j+\frac{1}{2}}}} \left| \frac{1}{2}, j + \frac{1}{2} \right\rangle \Rightarrow (-1)^{j-1/2} \left| \frac{1}{2}, j + \frac{1}{2} \right\rangle$$

Example : $\langle \sigma \psi \mathcal{O} \rangle$

Then we use CG coefficient to write them in $SO(3)$ basis. For example

$$[0, 1/2, -1/2] = \frac{(-1)^{j-1/2}}{\sqrt{2 \binom{2j}{j+\frac{1}{2}}}} \left(\left| \frac{1}{2}, j - \frac{1}{2} \right\rangle + \left| \frac{1}{2}, j + \frac{1}{2} \right\rangle \right).$$

$$[0, -1/2, 1/2] = \frac{(-1)^{j-1/2}}{\sqrt{2 \binom{2j}{j+\frac{1}{2}}}} \left(\left| \frac{1}{2}, j - \frac{1}{2} \right\rangle + \left| \frac{1}{2}, j - \frac{1}{2} \right\rangle \right).$$

$$[0, 1/2, -1/2]^+ = \frac{(-1)^{j-1/2}}{\sqrt{2 \binom{2j}{j+\frac{1}{2}}}} \left| \frac{1}{2}, j - \frac{1}{2} \right\rangle \Rightarrow (-1)^{j-1/2} \left| \frac{1}{2}, j - \frac{1}{2} \right\rangle$$

$$[0, 1/2, -1/2]^- = \frac{(-1)^{j-1/2}}{\sqrt{2 \binom{2j}{j+\frac{1}{2}}}} \left| \frac{1}{2}, j + \frac{1}{2} \right\rangle \Rightarrow (-1)^{j-1/2} \left| \frac{1}{2}, j + \frac{1}{2} \right\rangle$$

Four-Point Structures: q -basis

The q -basis four-point structures are

$$T_{I=[q_1 q_2 q_3 q_4]}^{ijkl}, \quad q_i \in \{-j_i, -j_i + 1, \dots, j_i\}. \quad (1)$$

Similar to three-point structures, we require that when

$$x_1 = (0, 0, 0), \quad x_2 = (\frac{\bar{z}-z}{2}, \frac{\bar{z}+z}{2}, 0), \quad x_3 = (0, 1, 0), \quad x_4(L) = (0, L, 0),$$

$$\begin{aligned} & \lim_{L \rightarrow +\infty} L^{2\Delta_4} T_{[q_1 q_2 q_3 q_4]}^{ijkl}(x_1, s_1; x_2, s_2; x_3, s_3; x_4, s_4) \\ &= \prod_{i=1}^4 ((s_i)_1)^{j_i+q_i} ((s_i)_2)^{j_i-q_i}. \end{aligned}$$

Parity: $T_{[q_1, q_2, q_3, q_4]} \rightarrow (-1)^{\sum_i j_i - q_i} T_{[q_1, q_2, q_3, q_4]}$.

Four-Point Structures: Stabilizer

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Given $\langle \mathcal{O}_1 \mathcal{O}_2 \mathcal{O}_3 \mathcal{O}_4 \rangle$, we call a permutation a stabilizer if it changes neither the ordering of the operators nor the cross-ratios.

For four identical operators, such as $\langle \psi \psi \psi \psi \rangle$, the stabilizers are

$$\{e, (12)(34), (13)(24), (14)(23)\} = \mathbb{Z}_2 \times \mathbb{Z}_2$$

For a pair of identical operators, such as $\langle \sigma \sigma \psi \psi \rangle$, the stabilizer group is just $\{e, (12)(34)\} = \mathbb{Z}_2$.

Bootstrap Spinning Operators

└ Blocks3d + Examples (σ, ψ)

└ Four-Point Structures

Given

$$\langle \psi_1 \psi_2 \psi_3 \psi_4 \rangle = \sum g_{\psi\psi\psi\psi}^{[q_1 q_2 q_3 q_4]}(z, \bar{z}) T_{[q_1 q_2 q_3 q_4]}.$$

Under (13)(24),

$$\langle \psi_3 \psi_4 \psi_1 \psi_2 \rangle = \sum g_{\psi\psi\psi\psi}^{[q_1 q_2 q_3 q_4]}(z, \bar{z}) \cdot n(z, \bar{z}) T_{[q_3 q_4 q_1 q_2]}.$$

Comparing with

$$\langle \psi_3 \psi_4 \psi_1 \psi_2 \rangle = \sum g_{\psi\psi\psi\psi}^{[q_3 q_4 q_1 q_2]}(z, \bar{z}) T_{[q_3 q_4 q_1 q_2]}.$$

This implies that some function coefficients are linearly dependent of each other

$$n(z, \bar{z}) g_{\psi\psi\psi\psi}^{[q_1 q_2 q_3 q_4]}(z, \bar{z}) = g_{\psi\psi\psi\psi}^{[q_3 q_4 q_1 q_2]}$$

For example, we have $g_{[\uparrow\uparrow\uparrow\uparrow]}$, but for $g_{[\uparrow\uparrow\downarrow\downarrow]}$ and $g_{[\downarrow\downarrow\uparrow\uparrow]}$, we should choose only one of them to parameterize the four-point function.

Four-Point Structures: q -basis

The q -basis four-point structures are

$$T_{I=[q_1 q_2 q_3 q_4]}^{ijkl}, \quad q_i \in \{-j_i, -j_i + 1, \dots, j_i\}. \quad (1)$$

Similar to three-point structures, we require that when

$$x_1 = (0, 0, 0), \quad x_2 = (\frac{\bar{z}-z}{2}, \frac{\bar{z}+z}{2}, 0), \quad x_3 = (0, 1, 0), \quad x_4(L) = (0, L, 0),$$

$$\begin{aligned} & \lim_{L \rightarrow +\infty} L^{2\Delta_4} T_{[q_1 q_2 q_3 q_4]}^{ijkl}(x_1, s_1; x_2, s_2; x_3, s_3; x_4, s_4) \\ &= \prod_{i=1}^4 ((s_i)_1)^{j_i+q_i} ((s_i)_2)^{j_i-q_i}. \end{aligned}$$

$$\text{Parity: } T_{[q_1, q_2, q_3, q_4]} \rightarrow (-1)^{\sum_i j_i - q_i} T_{[q_1, q_2, q_3, q_4]}.$$

Four-Point Structures: Example

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$$\langle\sigma\sigma\psi\psi\rangle, \quad \langle\psi\sigma\sigma\psi\rangle, \quad \langle\psi\sigma\psi\sigma\rangle.$$

Parity = $(-1)^{\sum_i j_i - q_i}$, so the parity-even structures are

$$[0, 0, \frac{1}{2}, \frac{1}{2}], \quad [0, 0, -\frac{1}{2}, -\frac{1}{2}], \dots$$

Besides parity and stabilizers,

$$(13) : \quad T_{[q_1, q_2, q_3, q_4]} \rightarrow (-1)^{q_1 + q_2 + q_3 - q_4} T_{[q_3, q_2, q_1, q_4]}$$

$$(z \leftrightarrow \bar{z}) : \quad T_{[q_1, q_2, q_3, q_4]}(z, \bar{z}) \rightarrow (-1)^{\sum_i j_i} T_{[-q_1, -q_2, -q_3, -q_4]}(\bar{z}, z)$$

Bootstrap Spinning Operators

└ Blocks3d + Examples (σ, ψ)

└ Crossing Equations

Crossing Equations

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$$\langle \mathcal{O}_i(x_1, s_1) \mathcal{O}_j(x_2, s_2) | \mathcal{O}_k(x_3, s_3) \mathcal{O}_l(x_4, s_4) \rangle \\ = \pm \langle \mathcal{O}_k(x_3, s_3) \mathcal{O}_j(x_2, s_2) | \mathcal{O}_i(x_1, s_1) \mathcal{O}_l(x_4, s_4) \rangle.$$

$$\sum_{[q_i]} g_{ijkl}^{[q_1, q_2, q_3, q_4]}(z, \bar{z}) T_{[q_1, q_2, q_3, q_4]}^{ijkl}(x_1, s_1, \dots) \\ = \pm \sum_{[q_i]} g_{kjl}^{[q_3, q_2, q_1, q_4]}(1-z, 1-\bar{z}) T_{[q_3, q_2, q_1, q_4]}^{kjl}(x_3, s_3, \dots) \\ = \pm \sum_{[q_i]} (-1)^{q_1+q_2+q_3-q_4} g_{kjl}^{[q_3, q_2, q_1, q_4]}(1-z, 1-\bar{z}) T_{[q_1, q_2, q_3, q_4]}^{ijkl}(x_1, s_1, \dots)$$

$$g_{ijkl}^{[q_1, q_2, q_3, q_4]}(z, \bar{z}) = \pm (-1)^{q_1+q_2+q_3-q_4} g_{kjl}^{[q_3, q_2, q_1, q_4]}(1-z, 1-\bar{z})$$



Bootstrap Spinning Operators

└ Blocks3d + Examples (σ, ψ)

└ Crossing Equations

Crossing Equations: Example

$$\langle \psi\sigma | \psi\sigma \rangle = -\langle \psi\sigma | \psi\sigma \rangle,$$

$$\langle \sigma\sigma | \psi\psi \rangle = \langle \psi\sigma | \sigma\psi \rangle.$$

$$g_{ijkl}^{[q_1, q_2, q_3, q_4]}(z, \bar{z}) = \pm (-1)^{q_1+q_2+q_3-q_4} g_{kjl}^{[q_3, q_2, q_1, q_4]}(1-z, 1-\bar{z})$$

Crossing even

$$g_{[\frac{1}{2}0\frac{1}{2}0]}^{\psi\sigma\psi\sigma}(z, \bar{z}) = g_{[\frac{1}{2}0\frac{1}{2}0]}^{\psi\sigma\psi\sigma}(1-z, 1-\bar{z}),$$

$$g_{[-\frac{1}{2}0-\frac{1}{2}0]}^{\psi\sigma\psi\sigma}(z, \bar{z}) = g_{[-\frac{1}{2}0-\frac{1}{2}0]}^{\psi\sigma\psi\sigma}(1-z, 1-\bar{z}), \quad \Rightarrow \quad g_{[00\pm\frac{1}{2}\pm\frac{1}{2}]}^{\sigma\sigma\psi\psi}(z, \bar{z}) + g_{[\pm\frac{1}{2}00\pm\frac{1}{2}]}^{\psi\sigma\sigma\psi}(z, \bar{z}),$$

$$g_{[00\frac{1}{2}\frac{1}{2}]}^{\sigma\sigma\psi\psi}(z, \bar{z}) = g_{[\frac{1}{2}00\frac{1}{2}]}^{\psi\sigma\sigma\psi}(1-z, 1-\bar{z}),$$

$$g_{[00-\frac{1}{2}-\frac{1}{2}]}^{\sigma\sigma\psi\psi}(z, \bar{z}) = g_{[-\frac{1}{2}00-\frac{1}{2}]}^{\psi\sigma\sigma\psi}(1-z, 1-\bar{z}).$$

Crossing odd

$$g_{[00\pm\frac{1}{2}\pm\frac{1}{2}]}^{\sigma\sigma\psi\psi}(z, \bar{z}) - g_{[\pm\frac{1}{2}00\pm\frac{1}{2}]}^{\psi\sigma\sigma\psi}(z, \bar{z}).$$

Functional: Derivative Basis (z, \bar{z})

$$\alpha^i[f] = \sum_{m+n \leq 2n_{\max}-1} a_{mn}^i \partial_z^m \partial_{\bar{z}}^n f(z, \bar{z}) \Big|_{(z=\frac{1}{2}, \bar{z}=\frac{1}{2})}$$

Definite parity under the transformation $z \leftrightarrow \bar{z}$,

$$(z \leftrightarrow \bar{z}) : T_{[q_1, q_2, q_3, q_4]}(z, \bar{z}) \rightarrow (-1)^{\sum_i j_i} T_{[-q_1, -q_2, -q_3, -q_4]}(\bar{z}, z)$$

$$T_{[q_1, q_2, q_3, q_4]^{\pm}} \rightarrow T_{[q_1, q_2, q_3, q_4]^{\pm}} \pm (-1)^{\sum_i j_i} T_{[-q_1, -q_2, -q_3, -q_4]^{\pm}}$$

In our examples, these are

$$[00 \pm \frac{1}{2} \pm \frac{1}{2}]^{\pm} = [00 \frac{1}{2} \frac{1}{2}] \mp [00 - \frac{1}{2} - \frac{1}{2}]$$

Functional: Derivative Basis (x, t)

$$x = \frac{z + \bar{z} - 1}{2}, \quad y = \frac{z - \bar{z}}{2}, \quad t = \left(\frac{z - \bar{z}}{2}\right)^2.$$

The crossing-symmetric point becomes $x = t = 0$.

Crossing acts by

$$z \rightarrow 1 - z, \quad \bar{z} \rightarrow 1 - \bar{z} \quad \text{or}$$

$$x \rightarrow -x, \quad y \rightarrow -y \quad (\text{xy-parity})$$

crossing-even $g(z, \bar{z})$: xy-even.

crossing-odd $g(z, \bar{z})$: xy-odd.

crossing-even $g(x, t)$: $\partial_x^m \partial_y^n g = 0, m + n = \text{odd}$.

crossing-odd $g(x, t)$: $\partial_x^m \partial_y^n g = 0, m + n = \text{even}$.

Functional: Derivative Basis (x, t)

Similarly for $z \leftrightarrow \bar{z}$, $x \rightarrow x$, $y \rightarrow -y$ (t-parity),

$g_{[q_1 q_2 q_3 q_4]^+}(z, \bar{z})$: t-parity even, y-even.

$g_{[q_1 q_2 q_3 q_4]^-}(z, \bar{z})$: t-parity odd, y-odd.

Convention in Hyperion, $\partial_x^m \partial_y^n$ has the same t-parity/y-parity as g , and opposite xy-parity to g .

$$\begin{aligned} & \left. \partial_t^m \partial_x^n g^{[q_3, q_2, q_1, q_4]^+}(x, t) \right|_{x=t=0} \\ & \left. \partial_t^m \partial_x^n \left(\frac{2}{(z - \bar{z})} g^{[q_3, q_2, q_1, q_4]^-}(x, t) \right) \right|_{x=t=0} \end{aligned}$$

$$2m + n \leq 2n_{\max} - 1.$$

Bootstrap Spinning Operators

└ Blocks3d + Examples (σ, ψ)

└ Crossing Equations

Functional: Derivative Basis (x, t)

$$\partial_x^m \partial_y^n$$

$$g_{[00\frac{1}{2}\frac{1}{2}]^+}^{\sigma\sigma\psi\psi}(x, t) + g_{[\frac{1}{2}00\frac{1}{2}]^+}^{\psi\sigma\sigma\psi}(x, t), \text{xy-odd, y-even} \rightarrow \text{x-odd, y-even}$$

$$g_{[00\frac{1}{2}\frac{1}{2}]^-}^{\sigma\sigma\psi\psi}(x, t) + g_{[\frac{1}{2}00\frac{1}{2}]^-}^{\psi\sigma\sigma\psi}(x, t), \text{xy-odd, y-odd} \rightarrow \text{x-even, y-odd}$$

$$g_{[\frac{1}{2}0\frac{1}{2}0]^+}^{\psi\sigma\psi\sigma}(x, t), \text{xy-odd, y-even} \rightarrow \text{x-odd, y-even}$$

$$g_{[\frac{1}{2}0\frac{1}{2}0]^-}^{\psi\sigma\psi\sigma}(x, t), \text{xy-odd, y-odd} \rightarrow \text{x-even, y-odd}$$

$$g_{[00\frac{1}{2}\frac{1}{2}]^+}^{\sigma\sigma\psi\psi}(x, t) - g_{[\frac{1}{2}00\frac{1}{2}]^+}^{\psi\sigma\sigma\psi}(x, t), \text{xy-even, y-even} \rightarrow \text{x-even, y-even}$$

$$g_{[00\frac{1}{2}\frac{1}{2}]^-}^{\sigma\sigma\psi\psi}(x, t) - g_{[\frac{1}{2}00\frac{1}{2}]^-}^{\psi\sigma\sigma\psi}(x, t), \text{xy-even, y-odd} \rightarrow \text{x-odd, y-odd}$$

Smoothness of $g(t = 0)$

4

When we expand the four-point function in conformal blocks, we will find that the result is smooth (as a function of x_i). But it turns out that not any choice of $g_{[q_1 q_2 q_3 q_4]}(z, \bar{z})$ leads to a smooth correlator, and a finite number of boundary conditions need to be imposed on derivatives of $g_{[q_1 q_2 q_3 q_4]}(z, \bar{z})$ at $z = \bar{z}$ or $t = 0$.

$$\partial_t^{2n} \partial_x^{2m+1} g_{[\frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2}]^+}^{\psi\psi\psi\psi}(x, t) \quad n \geq 1, m \geq 0$$

Reference: Counting Conformal Correlators

Bootstrap Spinning Operators

└ Blocks3d + Examples (σ, ψ)

└ Blocks3d Software

Blocks_3d Software

$$g_{[q_1 q_2 q_3 q_4], \pm}^{ijkl}(x, t) = \sum_{\Delta j} \sum_{(j_{12}, j_{12O})} \sum_{(j_{43}, j_{43O})} \lambda_{ijO}^{(j_{12}, j_{12O})} \lambda_{klO}^{(j_{43}, j_{43O})} G_{\Delta j, [q_1 q_2 q_3 q_4], \pm}^{(j_{12}, j_{12O}), (j_{43}, j_{43O})}(x, t)$$

$$i^{-\# \text{fermions}} \partial_x^m \partial_t^n \left(p_{\pm}(x, t) G_{\Delta j, [q_1 q_2 q_3 q_4], \pm}^{(j_{12}, j_{12O}), (j_{43}, j_{43O})}(x, t) \right) \Big|_{x=t=0}$$

```
./blocks_3d --help
./blocks_3d --j-external 0.5,0,0.5,0 --j-internal
0.5,1.5,2.5,3.5,4.5,5.5,6.5,7.5,8.5,9.5,10.5,11.5,12.5,13.5,14.5,15.5,16.5
--j-12 0.5 --j-43 0.5 --delta-12 0.4176 --delta-43 -0.4176
--delta-1-plus-2 1.7196 --four-pt-struct 0.5,0,0.5,0 --four-pt-sign -1
--order 60 --lambda 11 --coordinates xt --kept-pole-order 8
--num-threads 6 --debug 1 --precision 768 -o output/derivs.json
```

Functional: Derivative Basis (x, t)

Similarly for $z \leftrightarrow \bar{z}$, $x \rightarrow x$, $y \rightarrow -y$ (t-parity),

$g_{[q_1 q_2 q_3 q_4]^+}(z, \bar{z})$: t-parity even, y-even.

$g_{[q_1 q_2 q_3 q_4]^-}(z, \bar{z})$: t-parity odd, y-odd.

Convention in Hyperion, $\partial_x^m \partial_y^n$ has the same t-parity/y-parity as g , and opposite xy-parity to g .

$$\begin{aligned} & \left. \partial_t^m \partial_x^n g^{[q_3, q_2, q_1, q_4]^+}(x, t) \right|_{x=t=0} \\ & \left. \partial_t^m \partial_x^n \left(\frac{2}{(z - \bar{z})} g^{[q_3, q_2, q_1, q_4]^-}(x, t) \right) \right|_{x=t=0} \end{aligned}$$

$$2m + n \leq 2n_{\max} - 1.$$

Bootstrap Spinning Operators

└ Blocks3d + Examples (σ, ψ)

└ Blocks3d Software

Blocks_3d Software

$$g_{[q_1 q_2 q_3 q_4], \pm}^{ijkl}(x, t) = \sum_{\Delta j} \sum_{(j_{12}, j_{12O})} \sum_{(j_{43}, j_{43O})} \lambda_{ijO}^{(j_{12}, j_{12O})} \lambda_{kIO}^{(j_{43}, j_{43O})} G_{\Delta j, [q_1 q_2 q_3 q_4], \pm}^{(j_{12}, j_{12O}), (j_{43}, j_{43O})}(x, t)$$

$$i^{-\# \text{fermions}} \partial_x^m \partial_t^n \left(p_{\pm}(x, t) G_{\Delta j, [q_1 q_2 q_3 q_4], \pm}^{(j_{12}, j_{12O}), (j_{43}, j_{43O})}(x, t) \right) \Big|_{x=t=0}$$

```
./blocks_3d --help
./blocks_3d --j-external 0.5,0,0.5,0 --j-internal
0.5,1.5,2.5,3.5,4.5,5.5,6.5,7.5,8.5,9.5,10.5,11.5,12.5,13.5,14.5,15.5,16.5
--j-12 0.5 --j-43 0.5 --delta-12 0.4176 --delta-43 -0.4176
--delta-1-plus-2 1.7196 --four-pt-struct 0.5,0,0.5,0 --four-pt-sign -1
--order 60 --lambda 11 --coordinates xt --kept-pole-order 8
--num-threads 6 --debug 1 --precision 768 -o output/derivs.json
```



Blocks_3d

$$G_{\Delta,j}^{ab,I}(z, \bar{z}) \propto r^\Delta h_{\Delta,j}^{ab,I}(z, \bar{z})$$

$$h_{\Delta,j}^{ab,I}(z, \bar{z}) = h_{\infty,j,I}^{ab}(z, \bar{z}) + \sum_{i \in \mathcal{P}_j} \frac{(a_0 r)^{\eta_{j,i}}}{\Delta - \Delta_{j,i}} (\mathcal{L}_{j,i})_{a'}^a (\mathcal{R}_{j,i})_{b'}^b h_{\Delta'_{j,i}, j'_{j,i}, I}^{a'b'}(z, \bar{z}).$$

Blocks_3d computes blocks assuming that

- the three-point structures are defined in $SO(3)$ basis,
 $a = (j_{12}, j_{12}\mathcal{O})$, $b = (j_{43}, j_{43}\mathcal{O})$.
- the four-point structures defined in q -basis,
 $I = [q_1 q_2 q_3 q_4]$

The Model

The 3-dimensional $O(N)$ Gross-Neveu-Yukawa (GNY) theories with N Majorana fermions ψ_i , interacting with a pseudoscalar ϕ

$$\mathcal{L}_{\text{GNY}} = \frac{1}{2}(\partial\phi)^2 + i\psi_i\bar{\partial}\psi_i - \frac{1}{2}m^2\phi^2 - \frac{\lambda}{4}\phi^4 + g\phi\psi_i\psi_i.$$

Global $O(N)$ symmetry and invariant under parity transformation.

- One of the simplest models for scalar-fermion interaction.

Condensed Matter Applications

The universality class of the GNY model is used to describe a variety of quantum phase transitions in condensed matter systems.

- $N = 8$: Quantum Phase Transitions in graphene [[Phys. Rev. Lett. 85 \(2000\) 4940–4943](#)].
- $N = 4$: Spinless fermions on honeycomb lattice [[1703.08801](#)].

CFT scaling dimensions \Rightarrow critical exponents.

N = 1: Emergent Supersymmetry

- N = 1:

$$\mathcal{L}_{\text{GNY}} = \frac{1}{2}(\partial\phi)^2 + i\bar{\psi}\not{\partial}\psi - \frac{1}{2}m^2\phi^2 - \frac{\lambda}{4}\phi^4 + g\phi\bar{\psi}\psi.$$

Emergent supersymmetry arising at criticality, $\lambda = g^2$.

Emergent supersymmetry on the boundary of topological superconductors [Science 344, 280 (2014)].

Bootstrap Setup

$$\mathcal{O} : (\ell, P, \mu_{\mathcal{O}(N)})$$

$$\mathcal{L}_{\text{GNY}} = \frac{1}{2}(\partial\phi)^2 + i\psi_i\bar{\partial}\psi_i - \frac{1}{2}m^2\phi^2 - \frac{\lambda}{4}\phi^4 + g\phi\psi_i\psi_i.$$

We consider the mixed system of the lowest-dimension operators ψ_i , ϵ and σ , where their quantum numbers are,

$$\begin{aligned}\sigma &\sim \phi : (0, \text{odd}, \bullet) \\ \epsilon &\sim \phi^2 : (0, \text{even}, \bullet) \\ \psi_i &: (\tfrac{1}{2}, \text{even}, \square).\end{aligned}$$

Bootstrap Spinning Operators

└ GNY

└ Three-point Structures

Counting Three-point Conformal Structures

OPE	$\mathcal{O} \in (l, P, \mu)$	$\langle \mathcal{O}_a \mathcal{O}_b \mathcal{O}_c \rangle$	Structures
$\sigma \times \sigma$	($l \in 2\mathbb{Z}$, even, \bullet)	$\langle \sigma \sigma \mathcal{O} \rangle$	
$\epsilon \times \epsilon$		$\langle \epsilon \epsilon \mathcal{O} \rangle$	[000]
$\sigma \times \epsilon$	($l \in 2\mathbb{Z}$, odd, \bullet)	$\langle \sigma \epsilon \mathcal{O} \rangle$	[000]
		$\langle \epsilon \sigma \mathcal{O} \rangle$	$(-1)^j [000]$
	($l \in \mathbb{Z} + \frac{1}{2}$, even, \square)	$\langle \sigma \psi^i \mathcal{O}^j \rangle$	$-\delta^{ij} [0, \frac{1}{2}, -\frac{1}{2}]^-$
		$\langle \psi^i \sigma \mathcal{O}^j \rangle$	$(-1)^{j-\frac{1}{2}} \delta^{ij} [\frac{1}{2}, 0, -\frac{1}{2}]^-$
$\sigma \times \psi$	($l \in \mathbb{Z} + \frac{1}{2}$, odd, \square)	$\langle \sigma \psi^i \mathcal{O}^j \rangle$	$\delta^{ij} [0, \frac{1}{2}, -\frac{1}{2}]^+$
		$\langle \psi^i \sigma \mathcal{O}^j \rangle$	$(-1)^{j-\frac{1}{2}} \delta^{ij} [\frac{1}{2}, 0, -\frac{1}{2}]^+$
	($l \in \mathbb{Z} + \frac{1}{2}$, even, \square)	$\langle \epsilon \psi^i \mathcal{O}^j \rangle$	$\delta^{ij} [0, \frac{1}{2}, -\frac{1}{2}]^+$
		$\langle \psi^i \epsilon \mathcal{O}^j \rangle$	$(-1)^{j-\frac{1}{2}} \delta^{ij} [\frac{1}{2}, 0, -\frac{1}{2}]^+$
$\epsilon \times \psi$	($l \in 2\mathbb{Z} + \frac{1}{2}$, odd, \square)	$\langle \epsilon \psi^i \mathcal{O}^j \rangle$	$-\delta^{ij} [0, \frac{1}{2}, -\frac{1}{2}]^-$
		$\langle \psi^i \epsilon \mathcal{O}^j \rangle$	$(-1)^{j-\frac{1}{2}} \delta^{ij} [\frac{1}{2}, 0, -\frac{1}{2}]^-$

OPE	$\mathcal{O} \in (l, P, \mu)$	$\langle \psi^i \psi^j \mathcal{O}^a \rangle$ Structures
$\psi \times \psi$	($l \in 2\mathbb{Z}$, even, $\mu \in \{\bullet, \square\square\}$)	$T_{\mu}^{ija} [\frac{1}{2}, -\frac{1}{2}, 0]^+$ $T_{\mu}^{ija} [\frac{1}{2}, \frac{1}{2}, -1]^+$
		$T_{\mu}^{ija} [\frac{1}{2}, -\frac{1}{2}, 0]^+$ $T_{\mu}^{ija} [\frac{1}{2}, \frac{1}{2}, -1]^+$
$\psi \times \psi$	($l \in 2\mathbb{Z} + 1$, even, $\mu = \square$)	$T_{\mu}^{ija} [\frac{1}{2}, -\frac{1}{2}, 0]^+$ $T_{\mu}^{ija} [\frac{1}{2}, \frac{1}{2}, -1]^+$
		$T_{\mu}^{ija} [\frac{1}{2}, -\frac{1}{2}, 0]^-$ $T_{\mu}^{ija} [\frac{1}{2}, \frac{1}{2}, -1]^-$
$\psi \times \psi$	($l \in 2\mathbb{Z}$, odd, $\mu \in \{\bullet, \square\square\}$)	$T_{\mu}^{ija} [\frac{1}{2}, -\frac{1}{2}, 0]^-$ $T_{\mu}^{ija} [\frac{1}{2}, \frac{1}{2}, -1]^-$
		$T_{\mu}^{ija} [\frac{1}{2}, -\frac{1}{2}, 0]^-$ $T_{\mu}^{ija} [\frac{1}{2}, \frac{1}{2}, -1]^-$
$\psi \times \psi$	($l \in (2\mathbb{Z})_{\geq 2}$, odd, $\mu = \square$)	$T_{\mu}^{ija} [\frac{1}{2}, -\frac{1}{2}, 0]^-$ $T_{\mu}^{ija} [\frac{1}{2}, \frac{1}{2}, -1]^-$
		$T_{\mu}^{ija} [\frac{1}{2}, -\frac{1}{2}, 0]^-$ $T_{\mu}^{ija} [\frac{1}{2}, \frac{1}{2}, -1]^-$

Four-point Structures

Conformal structures with nice symmetry properties,

$$\langle \psi\psi|\psi\psi\rangle = -\langle \psi\psi|\psi\psi\rangle,$$

$$(-1)^{\sum_i j_i - q_i} \Rightarrow 8 \text{ parity even structures.}$$

$[\uparrow\uparrow\uparrow\uparrow], [\downarrow\downarrow\downarrow\downarrow], [\uparrow\uparrow\downarrow\downarrow], [\downarrow\downarrow\uparrow\uparrow], [\uparrow\downarrow\uparrow\downarrow], [\downarrow\uparrow\downarrow\uparrow], [\downarrow\uparrow\uparrow\downarrow], [\uparrow\downarrow\downarrow\uparrow]$

Invariant under $(12)(34), (13)(24), (14)(23)$,

$$\langle \uparrow\uparrow\uparrow\uparrow \rangle, \langle \downarrow\downarrow\downarrow\downarrow \rangle, \langle \uparrow\uparrow\downarrow\downarrow \rangle, \langle \uparrow\downarrow\uparrow\downarrow \rangle, \langle \downarrow\uparrow\uparrow\downarrow \rangle.$$

t-parity or parity under $z \rightarrow \bar{z}$ (in this case $[\uparrow] \leftrightarrow [\downarrow]$)

$$\langle \uparrow\uparrow\uparrow\uparrow \rangle^+, \langle \uparrow\uparrow\uparrow\uparrow \rangle^-, \langle \uparrow\uparrow\downarrow\downarrow \rangle^+, \langle \uparrow\downarrow\uparrow\downarrow \rangle^+, \langle \downarrow\uparrow\uparrow\downarrow \rangle^+.$$

Four-point Structures

Conformal structures with nice symmetry properties,

$$\begin{aligned}\langle \epsilon\epsilon|\psi^i\psi^j\rangle &= \langle \psi^i\epsilon|\epsilon\psi^j\rangle, \\ \langle \psi^i\epsilon|\psi^j\epsilon\rangle &= -\langle \psi^j\epsilon|\psi^i\epsilon\rangle \\ \langle \sigma\epsilon|\psi^i\psi^j\rangle &= \langle \psi^i\epsilon|\sigma\psi^j\rangle, \\ \langle \psi^i\sigma|\psi^j\epsilon\rangle &= -\langle \psi^j\sigma|\psi^i\epsilon\rangle.\end{aligned}$$

Parity odd structures $[\uparrow\downarrow]$, $[\downarrow\uparrow]$.

Definite t-parity structures,

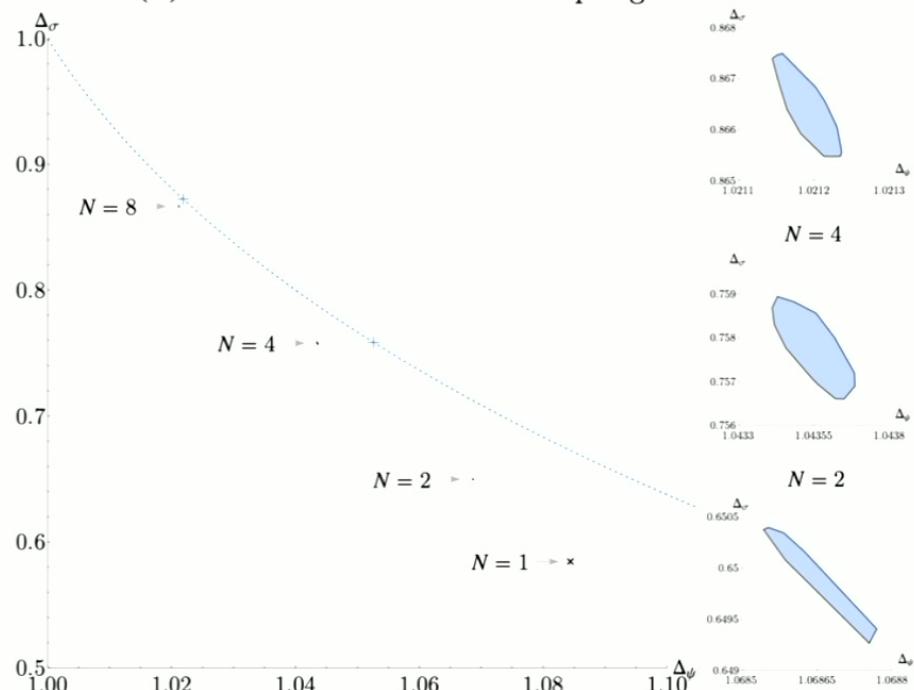
$$[\uparrow\downarrow]^\pm = [\uparrow\downarrow] \mp [\downarrow\uparrow]$$

Bootstrap Spinning Operators

└ GNY

└ Four-point Structures

Results: Archipelago

The $O(N)$ Gross–Neveu–Yukawa Archipelago

Bootstrap Spinning Operators

└ GNY

└ Four-point Structures

Results: Archipelago

The $O(N)$ Gross–Neveu–Yukawa Archipelago