

Title: Tutorial 1A: Introduction to simpleboot. 3D Ising Island with Delaunay search

Speakers: Ning Su

Collection: Mini-Course of Numerical Conformal Bootstrap

Date: April 24, 2023 - 1:30 PM

URL: <https://pirsa.org/23040137>

```
"VBlock$Identity"→
$$\begin{pmatrix} \text{Fp}[\text{sig}, \text{sig}, \text{eps}, \text{eps}, \theta] \\ \text{Fp}[\text{eps}, \text{eps}, \text{eps}, \text{eps}, \theta] \\ 0 \\ \text{Fp}[\text{sig}, \text{sig}, \text{eps}, \text{eps}, \theta] \\ \text{Hp}[\text{sig}, \text{sig}, \text{eps}, \text{eps}, \theta] \end{pmatrix}, (* \text{ crossing vector for } V_{\text{identity}}=(1 \ 1) \cdot V_{\text{even}}(\Delta=0, f=0) \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} *)$$

```

```
"VBlock$Deriv"→
$$\begin{pmatrix} \text{"odd"} \\ \text{"odd"} \\ \text{"odd"} \\ \text{"odd"} \\ \text{"even"} \end{pmatrix}, (* \text{ indicate the 5 components are even/odd under } u \leftrightarrow v \text{ exchange} *)$$

```

```
"VBlock$External"→{"sig", "eps"} (* the name of external operators as String *)  
};
```

Block specifications

```
In[10]:= (* conformal block specifications : spacetime dimension, derivative order, pole keeping order, r_* order, spins *)  
blockconfobj={"dim"→3, "Δmax"→11, "κ"→12, "rN"→48, "lset"→Range[0,20]~Join~{49,52}};  
  
dim = 3;  
Lambda = 27;  
AutoCB3$BlockSetting["DSD"][dim, Lambda] (* some presetting in simpleboot *)  
{dim → 3, Δmax → 27, κ → 20, rN → 80, lset → {0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11,  
12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 29, 30, 33, 34, 37, 38, 41, 42, 45, 46, 49, 50}}
```

```
"VBlock$External"→{"sig","eps"} (* the name of external operators as String *)
};
```

Block specifications

```
In[10]:= (* conformal block specifications : spacetime dimension, derivative order, pole keeping order, r_* order, spins *)
blockconfobj={ "dim"→3, "Δmax"→11, "κ"→12, "rN"→48, "lset"→Range[0,20]~Join~{49,52}};
```

```
In[30]:= dim = 3;
Lambda = 19;
AutoCB3$BlockSetting["DSD"][dim, Lambda] (* some presetting in simpleboot *)
```

```
Out[32]:= {dim → 3, Δmax → 19, κ → 14, rN → 56,
lset → {0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 49, 50}}
```

Initialize simpleboot

```
In[11]:= (* tell simpleboot about the crossing vectors and block specs *)
AutoCB3$Init[crossvecobj,blockconfobj];
```

AutoCB3\$Init[crossvecobj,blockconfobj] : this function tells simpleboot about the crossing vectors and block specs.

Gaps

`AutoCB3$Init[crossvecobj,blockconfobj]` : this function tells `simpleboot` about the crossing vectors and block specs.

Gaps

Format :

GapConfiguration is a List of element in one of the following format:

`{channel,gap,spins}` // this means demand $\alpha \cdot V_{\text{channel}} \geq 0$ for $\Delta > \text{gap}$ and L in spins. spins can be a integer or set of integers.
`{channel,IndividualOperator[Δ_0],spin}` // this means demand $\alpha \cdot (V_{\text{channel},\Delta_0,\text{spin}}) \geq 0$
`{channel,IndividualOperator[Δ_0 ,ope_List],spin}` // this means demand $\alpha \cdot (\text{ope} \cdot V_{\text{channel},\Delta_0,\text{spin}} \cdot \text{ope}) \geq 0$
`{channel,IntervalPositivity[$\Delta_{\text{min}},\Delta_{\text{max}}$],spin}` // this means demand $\alpha \cdot V_{\text{channel},\Delta,\text{spin}} \geq 0$ for $\Delta_{\text{min}} < \Delta < \Delta_{\text{max}}$

```

In[12]:= Clear@GapConfiguration;
GapConfiguration[dim_,lset_]:=
{op[op, "0", 1, 1],3,0}, (*  $\alpha \cdot V_{\text{odd}} > 0$  for  $\Delta > 3$  and  $L=0$  *)
{op[op, "E", 1, 1],3,0}, (*  $\alpha \cdot V_{\text{even}} > 0$  for  $\Delta > 3$  and  $L=0$  *)

{op[op, "E", 1, 1], $\Delta_{\text{unitary}}[dim, f]$ ,Select[lset, EvenQ[#] && # > 0 & ]}, (*  $\alpha \cdot V_{\text{even}} > 0$  for  $\Delta > \Delta_{\text{unitary}}$  and  $L=2, 4, \dots$  *)
{op[op, "0", 1, -1], $\Delta_{\text{unitary}}[dim, f]$ ,Select[lset, OddQ ]}, (*  $\alpha \cdot V_{\text{odd}} > 0$  for  $\Delta > \Delta_{\text{unitary}}$  and  $L=1, 3, \dots$  *)
{op[op, "0", 1, 1], $\Delta_{\text{unitary}}[dim, f]$ ,Select[lset, EvenQ[#] && # > 0 & ]} (*  $\alpha \cdot V_{\text{odd}} > 0$  for  $\Delta > \Delta_{\text{unitary}}$  and  $L=2, 4, \dots$  *)
};
    
```

`/:` place holder for spin

SDP template

Gaps

Format :

GapConfiguration is a List of element in one of the following format:

{channel,gap,spins} // this means demand $\alpha \cdot V_{\text{channel}} \geq 0$ for $\Delta > \text{gap}$ and L in spins. spins can be a integer or set of integers.

{channel,IndividualOperator[$\Delta 0$,spin]} // this means demand $\alpha \cdot (V_{\text{channel},\Delta 0,\text{spin}}) \geq 0$

{channel,IndividualOperator[$\Delta 0$,ope_List],spin} // this means demand $\alpha \cdot (\text{ope} \cdot V_{\text{channel},\Delta 0,\text{spin}} \cdot \text{ope}) \geq 0$

{channel,IntervalPositivity[$\Delta_{\text{min}},\Delta_{\text{max}}$],spin} // this means demand $\alpha \cdot V_{\text{channel},\Delta,\text{spin}} \geq 0$ for $\Delta_{\text{min}} < \Delta < \Delta_{\text{max}}$

```
In[12]:= Clear@GapConfiguration;
GapConfiguration[dim_,lset_] := {
  {op[op, "O", 1, 1],3,0}, (*  $\alpha \cdot V_{\text{odd}} > 0$  for  $\Delta > 3$  and  $L=0$  *)
  {op[op, "E", 1, 1],3,0}, (*  $\alpha \cdot V_{\text{even}} > 0$  for  $\Delta > 3$  and  $L=0$  *)

  {op[op, "E", 1, 1], $\Delta_{\text{unitary}}[dim, f]$ ,Select[lset, EvenQ[#] && # > 0 & ]}, (*  $\alpha \cdot V_{\text{even}} > 0$  for  $\Delta > \Delta_{\text{unitary}}$  and  $L=2, 4, \dots$  *)
  {op[op, "O", 1, -1], $\Delta_{\text{unitary}}[dim, f]$ ,Select[lset, OddQ ]}, (*  $\alpha \cdot V_{\text{odd}} > 0$  for  $\Delta > \Delta_{\text{unitary}}$  and  $L=1, 3, \dots$  *)
  {op[op, "O", 1, 1], $\Delta_{\text{unitary}}[dim, f]$ ,Select[lset, EvenQ[#] && # > 0 & ]} (*  $\alpha \cdot V_{\text{odd}} > 0$  for  $\Delta > \Delta_{\text{unitary}}$  and  $L=2, 4, \dots$  *)
};
```

/: place holder for spin

SDP template

normalization:

$$\alpha \cdot (V_{\text{identity}}) = 1 \text{ with } V_{\text{identity}} = (1 \ 1) \cdot V_{\text{even}}(\Delta = 0, l = 0) \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\alpha \cdot (V_{\text{identity}}) = 1 \text{ with } V_{\text{identity}} = (1 \ 1) \cdot V_{\text{even}}(\Delta = 0, l = 0) \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

positivity condition:

$$\alpha \cdot V_{\text{even}}(\Delta, l) \geq 0 \text{ for } \Delta \geq 3, l = 0$$

$$\alpha \cdot V_{\text{odd}}(\Delta, l) \geq 0 \text{ for } \Delta \geq 3, l = 0$$

$$\alpha \cdot V_{\text{even}}(\Delta, l) \geq 0 \text{ for } \Delta \geq \Delta_{\text{unitary}}, l = 2, 4, 6, \dots$$

$$\alpha \cdot V_{\text{odd}}(\Delta, l) \geq 0 \text{ for } \Delta \geq \Delta_{\text{unitary}}, l = 1, 2, 3, 4, \dots$$

$$\alpha \cdot V_{\theta} \geq 0 \text{ where } V_{\theta} = V_{\text{even}}(\Delta = \Delta_{\epsilon}, l = 0) + V_{\text{odd}}(\Delta = \Delta_{\sigma}, l = 0) \otimes \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

```
In[14]:= Clear@SDPTemplate$IsingOE;
SDPTemplate$IsingOE[]:=Module[
{BC$normalization,BC$objective,BC$condition,sdp,V$theta,
GFFnormalization},

BC$normalization=AutoCB3$Vector[CrossVec["identity"]]; (* alpha.V_identity=1 *)
BC$objective=AutoCB3$Vector[CrossVec["zero"]];
BC$condition=AutoCB3$Condition[1,CrossVec["V$theta"],0,{0}]~Join~ (* alpha.V_theta>0 *)
AutoCB3$Condition[GapConfiguration]; (* the rest positivity conditions *)

sdp=SDPData[BC$objective,BC$normalization,BC$condition];

sdp
];
```

~Join~ : see the note

Proj_IsingOE

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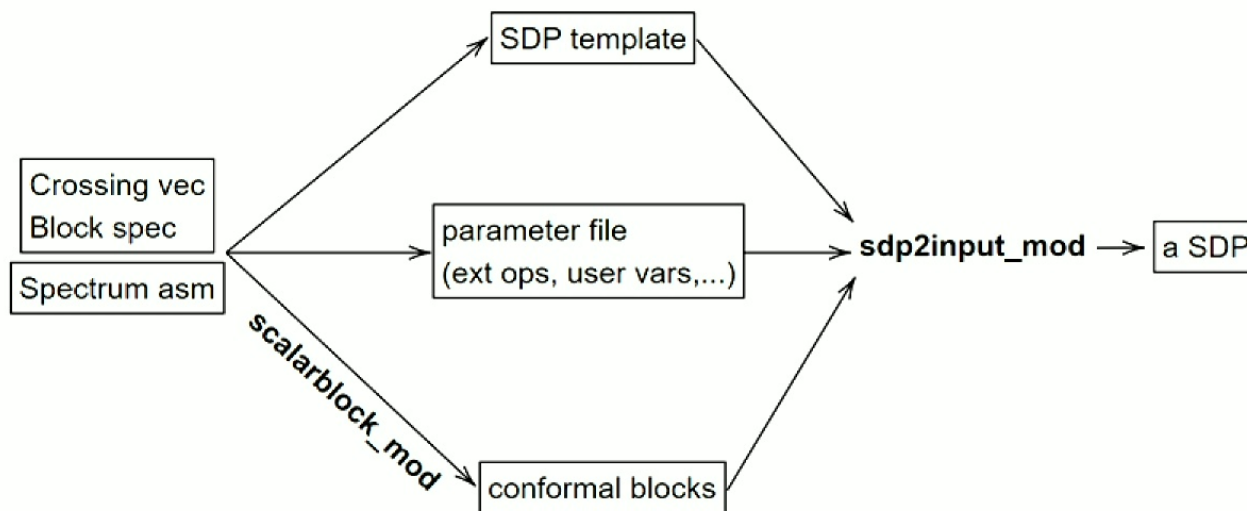
名称	状态	修改日期	类型	大小
<input checked="" type="checkbox"/> Proj_IsingOE_SDPTemplate.m... <input type="checkbox"/> project_status.txt	 	4/24/2023 7:51 PM 4/21/2023 10:33 PM	Wolfram Mathe... 文本文档	166 KB 8 KB

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simpleboot : run a SDP (high efficiency mode)



Advantage : very fast. All heavy computations are done in C++ programs

Disadvantage : simpleboot doesn't access to explicit SDP data (such as explicit crossing vectors $V_{\Delta,r}$).


```
sdp
];
```

~Join~ : see the note

```
In[33]:= (* save the template as default template for this project *)
AutoCB3$SaveSDPTemplate@SDPTemplate$IsingOE[];
```

Generate SDP

This function generate a SDP. It will be used by the Delaunay search scanner.

Input : a point to scan

Output : filename of the SDP

```
In[16]:= SDP$IsingOE[point_List, filename_:=Automatic]:=Module[
{Δσ, Δε},
{Δσ, Δε}=SetPrec[point];

AutoCB3$GenerateSDP[{Δσ, Δε}, {}, filename]
];
```

```
AutoCB3$GenerateSDP[externalOperatorList, userDefinedVariables, paramFilename]
```

AutoCB3\$GenerateSDP call C++ programs to generate blocks (if the block data is not generated) and generate an actual SDP based on the template and user-defined variables

Input:

Input:

externalOperatorList: the values of the external operators. The order should match with "VBlock\$External"

userDefinedVariables: user-defined variable in the template. Format : {"variable1"→value1, "variable2"→value2, ...}

paramFilename: SDP filename. Automatic : AutoCB3\$GenerateSDP will choose a proper name automatically.

Output:

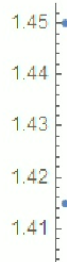
SDP filename

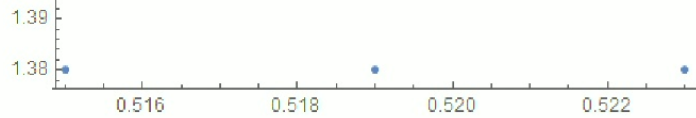
Delaunay Search

SSH\$UploadCurrentNotebook[] (* save and upload current notebook as package (.m) to the cluster *)

```
initpts = {{0.5181489, 1.412625}} ~Join~ GeneratePointsInRectangular[{0.515, 0.523}, {1.38, 1.45}, 3, 3] // SetPrec;
initpts // ListPlot
```

... N: Requested precision 16 is smaller than \$MinPrecision. Using \$MinPrecision instead.





ClusterAsyn\$Evaluate[

AutoCB3\$SaveSDPTemplate@SDPTemplate\$IsingOE[];

initpts = {{0.5181489, 1.412625}} ~ Join ~ GeneratePointsInRectangular[{0.515, 0.523}, {1.38, 1.45}, 3, 3] // SetPrec;

SB\$FeasibilityScanner[

SDP\$IsingOE, (* function that generates a SDP *)

initpts, (* initial points to scan *)

"--maxIterations=1000 --dualityGapThreshold=1e-25 --primalErrorThreshold=1e-15 --dualErrorThreshold=1e-15

--precision=765 --initialMatrixScalePrimal=1e+20 --initialMatrixScaleDual=1e+20 --maxComplementarity=1e+70

--detectPrimalFeasibleJump --detectDualFeasibleJump ", (* SDPB parameters *)

{"Delaunay"}, (* scan method *)

200, (* maximal points to scan *)

False (* initial checkpoint. False means no initial checkpoint. *)

]

]

408919

(* Check the job output. Input : job ID *)

ClusterAsyn\$JobOutput["408581"]

Quick connect...

6. login.rc.fas 2. PI_Symmet 8. PI_Symmet 11. login.rc.fas 13. PI_Symme 15. localui.pi.in 17. vpn.calleo

Terminal sidebar with file explorer:

- Quick connect...
- /gpfs/nsu2/simpleboot4_tutorial1A/Proj_IsingOE/
- Name
- btjob-409897.out
- Macros
- Stfp

```
System information as of Mon Apr 24 11:35:52 EDT 2023
System load: 0.58          Users logged in: 14
Usage of /: 41.7% of 99.94GB  IP address for eno1np0: 10.10.21.98
Memory usage: 37%         IP address for eno3: 172.16.2.250
Swap usage: 31%           IP address for ib0: 192.168.2.250
Processes: 1109           IP address for docker0: 172.17.0.1

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16 of these updates are standard security updates.
To see these additional updates run: apt list --upgradable

66 additional security updates can be applied with ESM Apps.
Learn more about enabling ESM Apps service at https://ubuntu.com/esm

Your Hardware Enablement Stack (HWE) is supported until April 2023.

Last login: Mon Apr 24 01:51:32 2023 from 10.40.1.224
nsu2@mn003:~$ squeue -u nsu2
   JOBID PARTITION   NAME   USER  ST       TIME  NODES NODELIST(REASON)
   409850   debugq  RunMMA_j  nsu2   R         48:56     1  cn070
nsu2@mn003:~$ cd /gpfs/nsu2/simpleboot4_tutorial1A/
nsu2@mn003:/gpfs/nsu2/simpleboot4_tutorial1A$ rm -r *.m
nsu2@mn003:/gpfs/nsu2/simpleboot4_tutorial1A$ squeue -u nsu2
   JOBID PARTITION   NAME   USER  ST       TIME  NODES NODELIST(REASON)
   409897   debugq  RunMMA_j  nsu2   R          0:06     1  cn071
nsu2@mn003:/gpfs/nsu2/simpleboot4_tutorial1A$
```

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Function : SB\$AddPoints

Cluster control

Function : ClusterLoginNode\$Evaluate

Function : ClusterAsyn\$Evaluate, ClusterAsyn\$JobOutput, ClusterAsyn\$JobOutput\$ToExpression

Function : ClusterAsyn\$SDPBOoutput

Function : ClusterSRUN\$ReloadJobs

Miscellaneous

Function : ObjSet, ObjGet

Function : RunShell

Function : CheckDirectory

Simpleboot operation mode

To use full functionality, simpleboot need automatic SSH login and SLURM cluster.

Automatic SSH login : SSH can be configured to passwordless login based RSA keys. See .

```

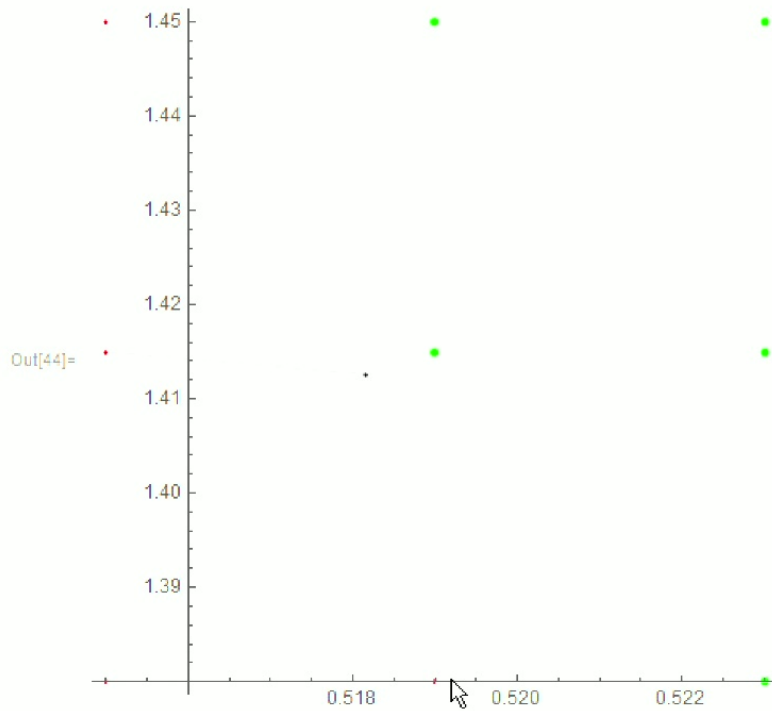
primalErrorThreshold      = 1e-15
dualErrorThreshold        = 1e-15
initialMatrixScalePrimal  = 1e+20
initialMatrixScaleDual    = 1e+20
feasibleCenteringParameter = 0.1
infeasibleCenteringParameter = 0.3
stepLengthReduction       = 0.7
maxComplementarity        = 1e+70
initialCheckpointDir      = "./Proj_IsingOE/SDPBFiles/0.518148900000_1.41262500000_Apr24_14h03m21s.ck"
checkpointDir             = "./Proj_IsingOE/SDPBFiles/0.518148900000_1.41262500000_Apr24_14h03m21s.ck"
noFinalCheckpoint        = false
writeSolution             = x,y
procsPerNode              = 64
procGranularity           = 1
verbosity                 = 1
    
```

Performing a timing run

	time	mu	P-obj	D-obj	gap	P-err	p-err	D-err	P-step	D-step	beta
1	0	1.0e+40	+0.00	+0.00	0.00	+1.00e+20	+0.00	+1.80e+24	0.446	0.383	0.300
2	0	7.1e+39	-1.29e+20	+0.00	1.00	+5.54e+19	+5.24e-195	+1.11e+24	0.366	0.398	0.300
3	1	5.5e+39	-2.27e+20	+0.00	1.00	+3.51e+19	+4.91e-195	+6.69e+23	0.292	0.257	0.300
4	1	4.6e+39	-2.84e+20	+0.00	1.00	+2.49e+19	+5.94e-195	+4.98e+23	0.323	0.358	0.300
5	2	3.7e+39	-3.22e+20	+0.00	1.00	+1.68e+19	+7.24e-195	+3.20e+23	0.355	0.291	0.300
6	2	2.9e+39	-3.84e+20	+0.00	1.00	+1.09e+19	+1.06e-194	+2.27e+23	0.439	0.339	0.300
7	3	2.1e+39	-5.00e+20	+0.00	1.00	+6.09e+18	+5.39e-195	+1.50e+23	0.371	0.324	0.300

```
In[42]:= SSH$DownloadFile@SB$Proj$FileName; (* download current project data from the cluster *)  
SB$LoadProject[]; (* load current project data *)
```

```
In[44]:= SB$DeLaunayPlot[] (* plot the scan result *)
```



Out[44]=

```
SB$RawPlot[]
```

Quick connect...

Sftp
 Macros
 Sessions

SDBPFiles
 BlockData
 project_status.txt
 Proj_IsingOE_SDPTemplate.m
 btjob-409910.out
 btjob-409897.out

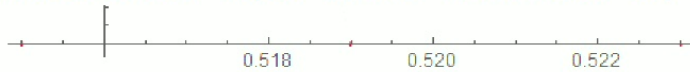
6. login.rc.fas | 2. PI_Symmet | 8. PI_Symmet | 11. login.rc.fas | 13. PI_Symmet | 15. localui.pi.in | 17. vpn.calleo

```

defq*      up 1-00:00:00 64 alloc cn[004-059,061-068]
debugq    up 1:00:00      2  resv cn[003,060]
debugq    up 1:00:00     72  alloc cn[004-059,061-076]
ehtq      up infinite    0   n/a
preq      up 1-00:00:00  2   resv cn[003,060]
preq      up 1-00:00:00  2   mix  cn[001-002]
preq      up 1-00:00:00  72  alloc cn[004-059,061-076]
reservedq up infinite    1  drain* cn095
reservedq up infinite   18  drain cn[093-094,096-110],mn004
reservedq up infinite    2   resv cn[003,060]
reservedq up infinite    2   mix  cn[001-002]
reservedq up infinite   82  alloc cn[004-059,061-076,079-086,089-090]
reservedq up infinite    6   idle cn[077-078,087-088,091-092]
sharedq   up 7-00:00:00  2   mix  cn[001-002]
gpuq      up 1-00:00:00  1   idle cn078
gpudebugq up 1:00:00      2   idle cn[077-078]
longq     up 7-00:00:00  1   resv cn060
longq     up 7-00:00:00  15  alloc cn[053-059,061-068]
amdq      up 1-00:00:00  1  drain* cn095
amdq      up 1-00:00:00  18  drain cn[093-094,096-110],mn004
amdq      up 1-00:00:00  10  alloc cn[079-086,089-090]
amdq      up 1-00:00:00  2   idle cn[087-088]
amddebugq up 1:00:00      1  drain* cn095
amddebugq up 1:00:00   18  drain cn[093-094,096-110],mn004
amddebugq up 1:00:00   10  alloc cn[079-086,089-090]
amddebugq up 1:00:00    4   idle cn[087-088,091-092]
amdpreq   up 1-00:00:00  1  drain* cn095
amdpreq   up 1-00:00:00  18  drain cn[093-094,096-110],mn004
amdpreq   up 1-00:00:00  10  alloc cn[079-086,089-090]
amdpreq   up 1-00:00:00  4   idle cn[087-088,091-092]
gpupreq   up 1-00:00:00  2   idle cn[077-078]
actq      up infinite    0   n/a
nsu2@mn003:/gpfs/nsu2/simpleboot4_tutorial1A$ squeue -u nsu2
JOBID PARTITION  NAME      USER ST  TIME  NODES NODELIST(REASON)
409910 amddebugq RunMMA_j nsu2 R    0:05  1  cn087
nsu2@mn003:/gpfs/nsu2/simpleboot4_tutorial1A$
  
```

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```
SB$RawPlot[]
```

utility codes

check job output and SDPB output

```
(* Check the job output. Input : job ID *)  
ClusterAsyn$JobOutput["407653"]  
  
(* Check the SDPB output. Input : SDP file name *)  
ClusterAsyn$SDPBOutput["0.515000000000_1.44999300000_Apr17_20h10m02s.sdp"]  
  
SB$LoadProject[];  
ClusterAsyn$SDPBOutput@ObjGet[SB$Proj$calculated$dual, 1, "LastCheckpoint"]
```

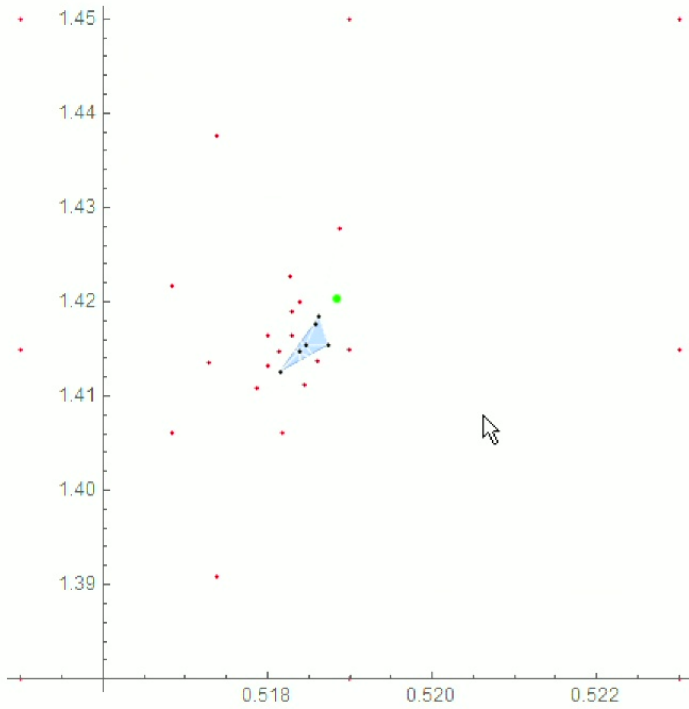
download the project data and monitor the result in real time

```
(* download the project data every 1s and plot the data *)  
Monitor[  
  While[True,  
    Pause[1];  
    SSH$DownloadFile@SB$Proj$FileName;  
  ]  
];
```



IsingOE.nb * (Running...) - Wolfram Mathematica 11.1

File Edit Insert Format Cell Graphics Evaluation Palettes Window Help
, Refresh[SB\$DelaunayPlot[], UpdateInterval -> 1]



cancel all jobs

(* ClusterLoginNode\$Evaluate: execute MMA command on the login node of the cluster *)

ClusterLoginNode\$Evaluate[

(* RunShell : execute a shell command *)

Windows taskbar showing various application icons (Windows, File Explorer, Visual Studio Code, etc.), system tray icons (network, volume, etc.), and the system clock displaying 8:11 PM on 4/24/2023. The taskbar also shows the language set to ENG and a zoom level of 120%.

Tutorial1A2

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名称	状态	修改日期	类型	大小
IsingO_test.nb	✓	4/22/2023 1:00 PM	Wolfram Noteb...	118 KB
IsingOE.m	✓	4/24/2023 8:12 PM	Wolfram Mathe...	15 KB
IsingOE.nb	✓	4/24/2023 8:12 PM	Wolfram Noteb...	232 KB
IsingOE_MMA.m	✓	4/23/2023 7:34 PM	Wolfram Mathe...	17 KB
IsingOE_MMA.nb	✓	4/23/2023 8:50 AM	Wolfram Noteb...	694 KB
IsingOE_nvg.m	✓	4/24/2023 7:36 AM	Wolfram Mathe...	17 KB
IsingOE_nvg.nb	✓	4/24/2023 7:36 AM	Wolfram Noteb...	501 KB
IsingOE_nvg_3param.m	✓	4/22/2023 11:18 PM	Wolfram Mathe...	17 KB
IsingOE_nvg_3param.nb	✓	4/22/2023 11:18 PM	Wolfram Noteb...	567 KB
IsingOE_OPEscan.m	✓	4/24/2023 7:45 AM	Wolfram Mathe...	17 KB
IsingOE_OPEscan.nb	✓	4/24/2023 7:45 AM	Wolfram Noteb...	299 KB
IsingOE_skydiving.m	✓	4/24/2023 7:49 AM	Wolfram Mathe...	17 KB
IsingOE_skydiving.nb	✓	4/24/2023 7:49 AM	Wolfram Noteb...	607 KB
normalization3.txt	✓	4/22/2023 12:41 PM	文本文档	25 KB
O3vst_OPEscan.m	✓	4/21/2023 3:23 PM	Wolfram Mathe...	503 KB
O3vst_OPEscan.nb	✓	4/21/2023 3:23 PM	Wolfram Noteb...	9,268 KB
objective3.txt	✓	4/22/2023 12:41 PM	文本文档	19 KB
run.sh	✓	4/19/2023 5:05 PM	SH 文件	1 KB
simpleboot_reference.nb	✓	4/24/2023 7:59 AM	Wolfram Noteb...	71 KB
submitMMA.m	✓	4/24/2023 7:57 AM	Wolfram Mathe...	2 KB
IsingOE_副本.nb	✓	4/24/2023 8:12 PM	Wolfram Noteb...	232 KB

52 个项目 选中 1 个项目 231 KB 同步被挂起

Windows (C:) LENOVO (D:) Applications (E:) Academia (F:)

任务栏: 设置 Sol... 8:14 PM 4/24/2023

Manually add points for Delaunay scanner to scan

```
(* ClusterLoginNode$Evaluate: execute MMA command on the login node of the cluster *)
ClusterLoginNode$Evaluate[
(* Cluster$AddPoints : add a list of point for the scanner to compute *)
Cluster$AddPoints[
  {{0.5177491433922756, 1.4069517019543976`}, {0.517380791833411, 1.4042418752442998`},
  {0.5170706010469988, 1.4008545918566775`}, {0.520560247394137, 1.4294771364820849`},
  {0.5207153427873431, 1.432864419869707}, {0.5216846889948815, 1.4352355182410423`}} // SetPrec]
]
```

Add a test region for Delaunay scanner

```
ClusterLoginNode$Evaluate[
(* Add a test region in the Delaunay scanner. The scanner will only search for new points inside the test region. *)
SB$LockProject[];
ObjSet[SB$Proj, "method"] =
  {"sampler" → "Delaunay",
   "Region" → Polygon@{{0.5171516665322581, 1.3974831977419353`}, {0.5189660012096774, 1.4049190132258063`},
   {0.5175772512096775, 1.4133332254838709`}, {0.5163900939516128, 1.4025708609677416`}}];
SB$UnlockProject[];
]

ClusterLoginNode$Evaluate[
```

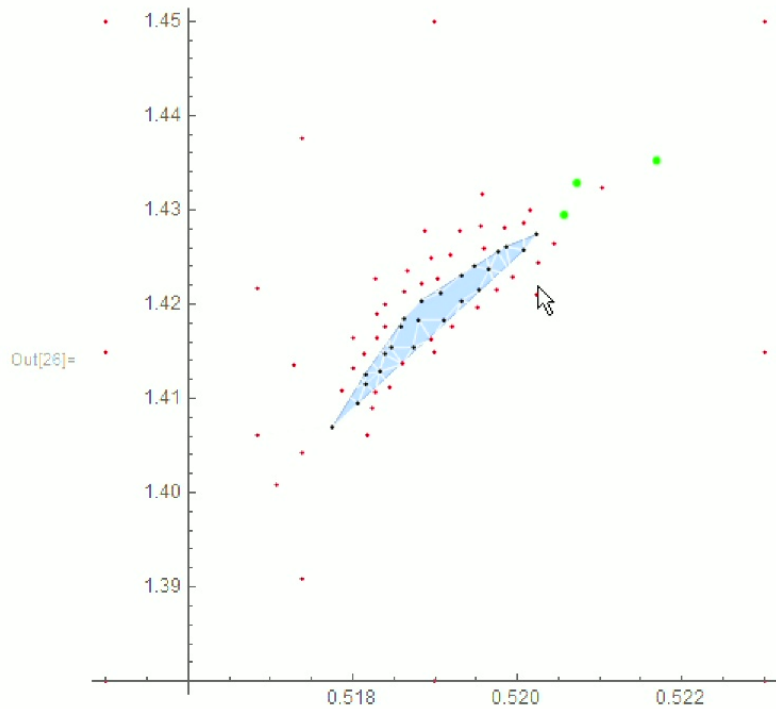
(* Check the SDPB output. Input : SDP file name *)

ClusterAsyn\$SDPBOutput["0.518148900000_1.41262500000_Apr24_14h03m21s.sdp"]

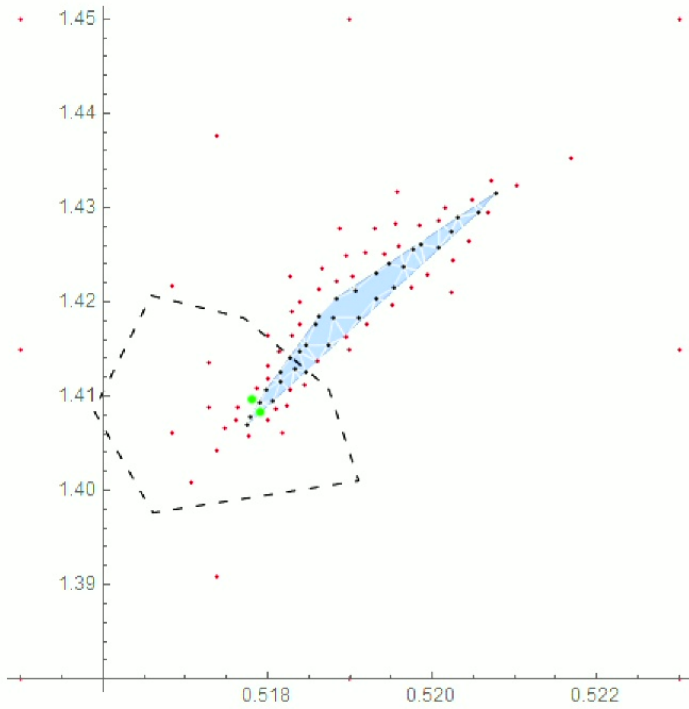
In[24]:= SSH\$DownloadFile@SB\$Proj\$FileName; (* download current project data from the cluster *)

SB\$LoadProject[]; (* load current project data *)

In[26]:= SB\$DeLaunayPlot[] (* plot the scan result *)



File Edit Insert Format Cell Graphics Evaluation Palettes Window Help
, Refresh[SB\$DelaunayPlot[], UpdateInterval -> 1]



cancel all jobs

(* ClusterLoginNode\$Evaluate: execute MMA command on the login node of the cluster *)

ClusterLoginNode\$Evaluate[

(* RunShell : execute a shell command *)

Quick connect...

Functions Sections
 Debug

- /gpfs/nsu2/simpleboot4_tutorial1A/
- Name
 - ..
 - Proj_IsingOE
 - Scripts
 - Proj_IsingOE_nvg
 - Proj_IsingOE_MMA
 - Proj_IsingOE_nvg_3param
 - Proj_IsingOE_test
 - Proj_IsingOE_OPEscan
 - Proj_IsingOE_nvg_EFM
 - Proj_IsingOE_test
 - Proj_IsingOE_skydiving
 - submitMMA.m
 - run.sh
 - test.txt
 - IsingOE2.m
 - IsingOE.m

```

GetFileDirectory[]:=If[$InputFileName==="",NotebookDirectory[],DirectoryName@$InputFileName];
$MainFileScriptQ=$InputFileName!="";
AppendTo[$Path,GetFileDirectory[]];
SetDirectory@GetFileDirectory[];

Get["./Scripts/config.m"];
Get["ReconfigCmd@"{Local.PackageDirectory}/Bootstrapper.m"];

Get["IsingOE.m"];

AutoCB3$SaveSDPTemplate@SDPTemplate$IsingOE[];

initpts={{0.5181489,1.412625}}~Join~GeneratePointsInRectangular[{0.515,0.523},{1.38,1.45}],3,3}/

SB$FeasibilityScanner[
SDP$IsingOE, {> function that generates a SDP <}
initpts, {> initial points to scan <}--maxIterations-1000 --dualityGapThreshold-1e 25 --primal:
{"Delaunay"}, {> scan method <}

```

```

amdpreq    up 1-00:00:00    4   idle cn[087-088,091-092]
gpupreq    up 1-00:00:00    2   idle cn[077-078]
actq       up infinite      0   n/a
nsu2@mn003:/gpfs/nsu2/simpleboot4_tutorial1A$

```

Follow terminal folder

UNREGISTERED VERSION - Please support MobaXterm by subscribing to the professional edition here: <http://mobaxterm.mobatek.net>

Windows taskbar showing icons for various applications and system status. System tray includes: ENG, 8:28 PM, 4/24/2023.

This is a long exercise set. But the computation is pretty quick for $\Lambda = 11$ (around 10mins to ~1 hour).

For perimeter user:

We are sharing limited computational resources among many participants. Please don't do heavy computations. For debugging, you can use debugq. Once the code runs correctly for 10mins, you can stop it and re-run it on defq. Once the feasible region have rough sharp (usually around 100 to 200 points), you can stop the computation.

Try to do Exercise 1-3 today. Try to finish Exercise 4 by Thursday (it's related to what I want to discuss on Thursday).

Exercise 1

Go through [IsingOE.nb](#) to understand how the bootstrap conditions are set up. Execute [IsingOE.nb](#) to scan a 3D Ising island.

Exercise 2

Go through [IsingO.nb](#) to understand how to use user-defined variables. Execute [IsingO.nb](#) to scan single correlator for 3D Ising.

Exercise 3

Modify [IsingO.nb](#) to scan single correlator bound for 3D O(N). You can use the crossing vector from [ArXiv:1307.6856 \(2.5\)](#).

In [simpleboot](#), the default definition of conformal block is in [ArXiv:1805.04405](#) TABLE I row 1, while the convention of [ArXiv:1307.6856](#) is in row 5. Therefore there is a $(-1)^l$ difference for $V_{A,\Delta,l}$. When you type in crossing vector, you should take minus of $V_{A,\Delta,l}$ in [ArXiv:1307.6856 \(2.5\)](#).

Exercise 4

Folder	File Name	Icon	Date Modified	File Type	Size
Applications (E:)	IsingOE_nvg.m	Green checkmark	4/24/2023 7:36 AM	Wolfram Mathe...	17 KB
Academia (F:)	IsingOE_nvg.nb	Green checkmark	4/24/2023 7:36 AM	Wolfram Noteb...	501 KB

53 个项目 选中 1 个项目 20.0 KB 在此设备上可用

8:32 PM 4/24/2023