Title: SDP approaches for quantum polynomial optimization

Speakers: Laurens Ligthart

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Abstract: "Many relevant tasks in Quantum Information processing can be expressed as polynomial optimization problems over states and operators. In the earlier talk by David, we saw that this is also the case for certain (quantum) causal compatibility and causal optimization problems.

This talk will focus on several closely related semidefinite programming (SDP) hierarchies that have recently been shown to be complete for such polynomial optimization problems [arxiv:2110.14659, 2212.11299, 2301.12513]. We give a high-level overview of the techniques and mathematics that are needed for proving such statements. In particular, we will see a version of a Quantum De Finetti theorem, as well as a sketch of a constructive proof of convergence for the SDP hierarchies. Afterwards, these results are linked back to the causal compatibility problem to conclude that such SDP hierarchies are complete for a certain type of causal structures known as tree networks."

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Semidefinite optimization approaches for quantum polynomial optimization

Laurens Ligthart

Joint work with Mariami Gachechiladze & David Gross

Institute for Theoretical Physics, University of Cologne, Germany

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Outline

Introduction

Causal compatibility (non-linear) Bell inequalities

Quantum Polynomial Optimization

SDP approaches

NPO

Polarization

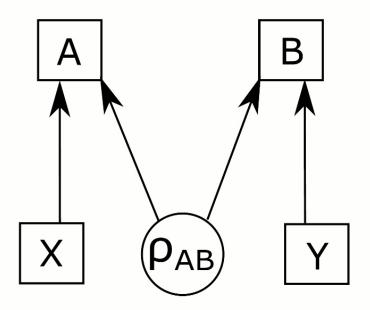
Convergence

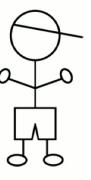
Conclusion



Bell scenario







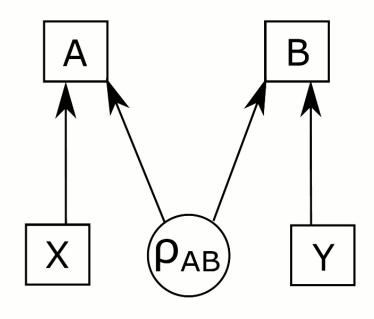


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Bell scenario

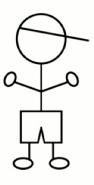


$$\{\mathcal{A}_{lpha|x}\}_{lpha,x} \ \mathcal{A}_{lpha|x} \succeq \mathbf{0} \ \sum_{lpha} \mathcal{A}_{lpha|x} = \mathbb{I}$$



$$P(a, b|x, y) = \rho_{AB}(A_{\alpha|x}B_{\beta|y})$$

 $\rho_{AB}(\mathbb{I}) = 1, \rho_{AB} \ge 0$



$$egin{aligned} \{B_{eta|y}\}_{eta,y}\ B_{eta|y} \succeq 0\ \sum_{eta} B_{eta|y} = \mathbb{I} \end{aligned}$$





The causal compatibility problem

Causal compatibility

Given a (conditional) probability distribution P(a, b, c, ... | x, y, z, ...) and a causal structure (in the form of a DAG), determine whether P can be produced in this causal structure.

This is dependent on the physical model:

- Classical probability
- Quantum mechanics
- GPT





(non-linear) Bell inequalities

For binary observables we have

The CHSH expression

$$\rho(A_1B_1+A_1B_2+A_2B_1-A_2B_2).$$

Tsirelson bound for quantum systems is $2\sqrt{2}$.

The expression

$$\rho(A_1B_2+A_2B_1)^2+\rho(A_1B_1-A_2B_2)^2.$$

Classical bound is 4¹. Quantum bound is matching².

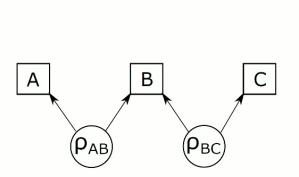
Many more complicated expressions...



¹Uffink (2002)

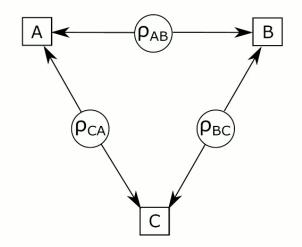
²Klep *et al.* (2023)

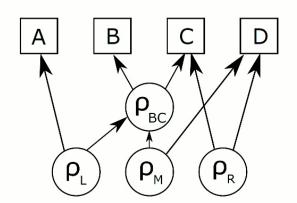
Causal structures



Introduction

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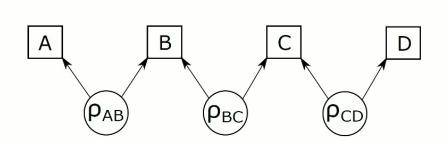


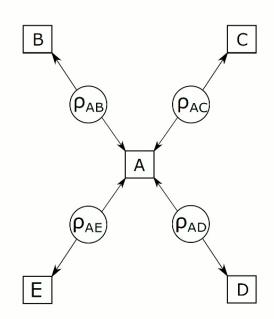


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Introduction ○○ ○○●

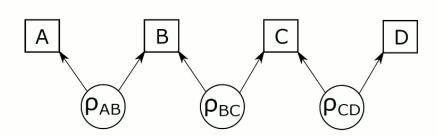
Tree networks





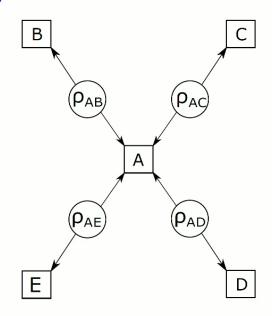


Tree networks



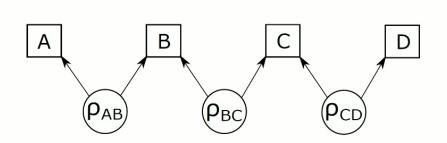
$$A \perp C, D$$

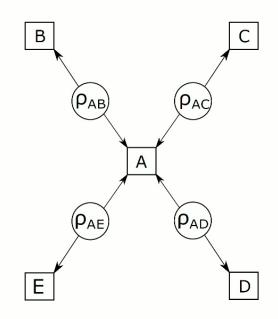
 $A, B \perp D$



$$B \perp C, D, E$$
 $C \perp B, D, E$
 $D \perp B, C, E$

Tree networks





$$\rho(\mathsf{acd}) = \rho(\mathsf{a})\rho(\mathsf{cd})$$

$$\rho(\mathsf{abd}) = \rho(\mathsf{ab})\rho(\mathsf{d})$$

$$\rho(bcde) = \rho(b)\rho(c)\rho(d)\rho(e)$$



Polynomials

Such expressions are polynomials in two ways:

- In the operators
- But also in the state

$$ho(abcd) =
ho(a)
ho(b)
ho(c)
ho(d) =
ho^{\otimes 4}(a\otimes b\otimes c\otimes d)$$

We call such expressions state polynomials



Optimization

Quantum Polynomial Optimization

Introduction

Given a set of generators \mathcal{G} and relations \mathcal{R} , defining a C^* -algebra $\mathcal{A} = C^*(\mathcal{G}|\mathcal{R})$, and a set of state polynomials $p_i : (A, S(A)) \to \mathbb{C}$, solve

$$\min_{
ho \in \mathcal{S}(\mathcal{A})} \quad p_0(\mathcal{A},
ho)$$
s. t. $p_i(\mathcal{A},
ho) = 0 \quad \forall i$.

For example, A could be the algebra generated by the measurements and the p_i could be the factorization constraints.



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We would like to use convex optimization:

$$\min_{X} \quad \langle C, X \rangle$$
s.t. $\langle A_i, X \rangle = b_i$
 $X \succeq 0$

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angle \ & ext{s.t.} & \langle A_i, X
angle = b_i \ & X \succeq 0 \end{array}$$

However

• The set of product states is not convex: For ρ , σ product states $(1 - \lambda)\rho + \lambda\sigma$ is mixed unless $\lambda = 0$ or 1.



We would like to use convex optimization:

$$\min_{X} \quad \langle C, X \rangle$$
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However

- The set of product states is not convex: For ρ , σ product states $(1 \lambda)\rho + \lambda\sigma$ is mixed unless $\lambda = 0$ or 1.
- The polynomials (in the state) can be non-convex
- The dimension grows exponentially quickly



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So that seems pretty bad...





NPO

- Non-commutative Polynomial Optimization³⁴ can optimize over objective functions and constraints that are linear in the state and polynomial in the operators
- Hierarchy of relaxations that converges in the limit via a monotonically increasing sequence of lower bounds
- Can be formulated independent of the dimension!



Introduction

³Navascués, Pironio, Acín (2008)

⁴Pironio, Navascués, Acín (2010)



NPO: How does it (roughly) work?

Construct a functional that is only positive on a subspace of the algebra A.

• Choose a basis $\{a_i\}$ of A, with $a_0 = \mathbb{I}$.

Introduction

• Choose an integer k and construct a $k \times k$ matrix $M^{(k)}$, where

$$M_{i,j}^{(k)} =
ho(a_i^*a_j)$$



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A matrix N is PSD iff $v^*Nv \ge 0$ for all vectors v



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A matrix N is PSD iff $v^*Nv \ge 0$ for all vectors v

$$v^*Mv = \sum_{i,j} v_i^* M_{i,j} v_j$$

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A matrix N is PSD iff $v^*Nv \ge 0$ for all vectors v

Introduction

$$v^*Mv = \sum_{i,j} v_i^* M_{i,j} v_j$$

$$= \sum_{i,j} v_i^* \rho(a_i^* a_j) v_j$$

$$= \rho(\sum_i v_i^* a_i^* \sum_j v_j a_j)$$

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$$= \rho(\sum_i v_i^* a_i^* \sum_j v_j a_j)$$

$$= \rho(X^*X) \ge 0$$

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NPO: How does it (roughly) work?

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- Choose an integer k and construct a $k \times k$ matrix $M^{(k)}$, where

$$M_{i,j}^{(k)} = \rho(a_i^* a_j)$$

Solve the SDP

$$\begin{aligned} & \min_{M^{(k)}} & & \sum_{i,j} \rho_{ij}^0 M_{i,j}^{(k)} \\ & \text{s.t.} & & M_{0,0}^{(k)} = 1 \\ & & & \sum_{i,j} (\rho^\ell)_{ij} M_{i,j}^{(k)} = 0 \quad \text{when } \sum_{i,j} (\rho^\ell)_{ij} \rho(a_i^* a_j) = 0 \\ & & & M^{(k)} \succeq 0 \end{aligned}$$



- The set of product states is not convex: For ρ, σ product states $(1 \lambda)\rho + \lambda \sigma$ is mixed unless $\lambda = 0$ or 1.
- The polynomials (in the state) can be non-convex NPO can handle any polynomial in operators $\frac{1}{2}\sqrt{}$
- The dimension grows exponentially quickly
 NPO can deal with that √



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Independence implies symmetry

Idea:

If $\rho(AB) = \rho(A)\rho(B)$, then

$$\rho(AB) = \rho^{\otimes 2}(AB \otimes \mathbb{I}) = \rho^{\otimes 2}(A \otimes B) = \rho^{\otimes 2}(B \otimes A).$$

More generally, for *n* copies:

$$\rho(AB) = \rho^{\otimes n} \Big(\pi_1(A \otimes \mathbb{I}^{\otimes (n-1)}) \pi_2(B \otimes \mathbb{I}^{\otimes (n-1)}) \Big)$$

for all n and $\pi_1, \pi_2 \in S_n$.



⁵Wolfe, Spekkens, Fritz (2019)

⁶Wolfe *et al.* (2021)

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for all n and $\pi_1, \pi_2 \in S_n$.

This is also (partly) the motivation behind the inflation technique.⁵



⁵Wolfe, Spekkens, Fritz (2019)

⁶Wolfe *et al.* (2021)

Relaxations via symmetry

Instead of solving our difficult problem

$$egin{array}{ll} \min_{
ho \in \mathcal{S}(\mathcal{A})} & p_0(\mathcal{A},
ho) \ & s.t. & p_i(\mathcal{A},
ho) = 0 & orall i \end{array}$$

solve the hierarchy of NPO problems

$$egin{array}{ll} \min_{\omega \in S(\mathcal{A}^{\otimes n})} & \omega(y_0) \ & s.t. & \omega(y_i) = 0 & orall i \ & \omega ext{ is symmetric on } \mathcal{A}^{\otimes n}, \end{array}$$

where y_0 , y_i are the polarizations of p_0 , p_i .



Polarization example

SDP approaches

Suppose

Introduction

$$p_i(A, \rho) = \rho(AB) - \rho(A)\rho(B) = 0.$$

Then the polarization of p_i is

$$\omega(\mathbf{y}_i) := \omega(\mathbf{A}_1 \mathbf{B}_1 - \mathbf{A}_1 \mathbf{B}_2) = \mathbf{0},$$

which is now linear in the state



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Relaxations via symmetry

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where y_0, y_i are the polarizations of p_0, p_i .



- The set of product states is not convex: For ρ, σ product states $(1 \lambda)\rho + \lambda\sigma$ is mixed unless $\lambda = 0$ or 1. the set of symmetric states is convex \checkmark
- The polynomials (in the state) can be non-convex
 We linearized those polynomials √
- The dimension grows exponentially quickly
 NPO can deal with that √



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- The set of product states is not convex: For ρ, σ product states $(1 \lambda)\rho + \lambda\sigma$ is mixed unless $\lambda = 0$ or 1. the set of symmetric states is convex \checkmark
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Quantum de Finetti Theorem

Theorem: Max tensor product Quantum de Finetti⁷

Let $\omega \in S(A^{\infty})$ be a symmetric state on an infinite maximal tensor product

$$\mathcal{A}^{\infty} = \lim_{n \to \infty} \mathcal{A}^{\otimes_{\max} n}.$$

Then there exists a unique probability measure μ over states on \mathcal{A} such that for all $x \in \mathcal{A}^{\infty}$,

$$\omega(\mathbf{x}) = \int_{\mathcal{S}(\mathcal{A})} \Pi_{\sigma}^{\infty}(\mathbf{x}) \, \mathrm{d}\mu(\sigma),$$

where Π_{σ}^{∞} is the infinite symmetric product state on \mathcal{A}^{∞} associated with the state σ on \mathcal{A} .



⁷L, Gachechiladze, Gross (2021)

Convergence proof sketch

- Each step in the hierarchy is a relaxation \implies each solution is a lower bound
- NPO converges⁸
- The Quantum de Finetti Theorem shows that for $n \to \infty$ the optimal state converges to a <u>separable</u> state that obeys all the polarization constraints. It looks like

$$\omega(\mathbf{x}) = \int_{\mathcal{S}(\mathcal{A})} \Pi_{\sigma}^{\infty}(\mathbf{x}) \, \mathrm{d}\mu(\sigma),$$

where "each" Π_{σ}^{∞} obeys all the polynomial constraints!

• Choose one such Π_{σ}^{∞} . This state gives an upper bound that matches the lower bound in the limit.



⁸Pironio, Navascués, Acín (2008)

⁹L, Gross (2022)

SDP approaches

Closely related SDP hierarchy

Recent paper on state polynomial optimization¹⁰

- Extends the algebra \mathcal{A} by including <u>commuting</u> generators g_i " = " $\rho(a_i)$ for a basis $\{a_i\}_i$ of \mathcal{A}
- Now polynomials in states also become linear:

$$ho(\mathbf{a}_i \mathbf{a}_j) =
ho(\mathbf{a}_i)
ho(\mathbf{a}_j) =
ho(\mathbf{a}_i
ho(\mathbf{a}_j)) =
ho(\mathbf{a}_i \mathbf{g}_j)$$

They prove a Positivstellensatz to show that this converges
 Resembles scalar extension¹¹



Introduction

¹⁰Klep *et al.* (2023)

¹¹Pozas-Kerstjens *et al.* (2019)

Conclusion & outlook

There are several closely related converging hierarchies of SDP relaxations to the state polynomial optimization problem

$$\min_{
ho \in \mathcal{S}(\mathcal{A})} \quad p_0(\mathcal{A},
ho)$$
s. t. $p_i(\mathcal{A},
ho) = 0 \quad \forall i$.

This has many applications in QIT, e.g. (non-linear) Bell inequalities and the causal compatibility problem (cf David's talk)

- Which hierarchy has faster convergence? And how are they related?
- For which causal structures is state polynomial optimization complete?



Introduction

Introduction

Thanks for listening!



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