

Title: Quantum Gravity Lecture (230403)

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Collection: Quantum Gravity (2022/2023)

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URL: <https://pirsa.org/23040026>

PLAN

1) Geometrize Mechanics
(& field theory)
→ symplectic geom.

2) Covariant Phase Space
→ in depth study of the sym of GR
→ general covariance is a phys. principle
→ GR from its sym.

→ Wald's BH mechanics
(entropy)

→ Wald's BH mechanics
(entropy as a N. ch.)

3) CPS to Canonical Ph Sp.

↳ GR constr algebra

→ WdW eq.

→ Ashtekar's variables for
GR

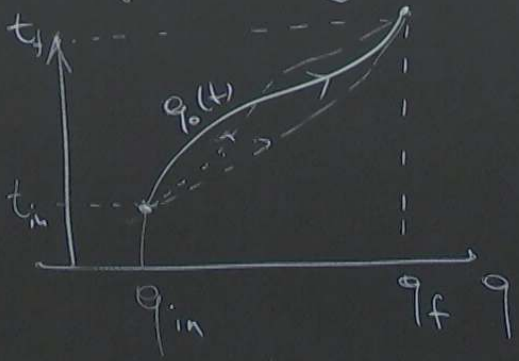
GR

principle

oies
 N, ch.)
 nical Ph Sp.
 tr algebra
 's variables for

ACTION PRINCIPLE

$$S[q(t)] = \int dt \mathcal{L}(q(t), \dot{q}(t))$$



Extremality = phys path

$$0 = \delta S|_{q_0} = \int_{t_{in}}^{t_f} \left(\frac{\partial \mathcal{L}}{\partial q} - \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}} \right) \delta q + \left[\frac{\partial \mathcal{L}}{\partial \dot{q}} \delta q \right]_{t_{in}}^{t_f}$$

$\equiv 0$
 τ

Hamiltonian

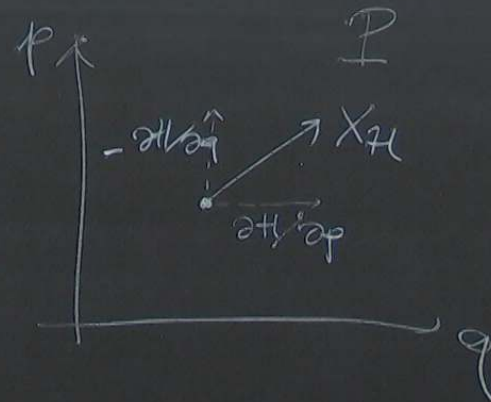
$$p = \frac{\partial L}{\partial \dot{q}} \quad \text{canonical momentum}$$

$$\hookrightarrow \dot{q} = \dot{q}(p, q)$$

$$\text{Hamilt. : } H(p, q) = p\dot{q} - L(q, \dot{q})$$

$$\text{Eom} \begin{cases} \dot{p} = -\frac{\partial H}{\partial q} \\ \dot{q} = \frac{\partial H}{\partial p} \end{cases} \rightarrow \frac{d}{dt} \begin{pmatrix} q \\ p \end{pmatrix} = X_H \in \mathcal{X}'(P)$$

"velocity in Ph Sp"
HAM V.F.



Poisson Brackets

$$\{\cdot, \cdot\} : C^\infty(P) \times C^\infty(P) \rightarrow C^\infty(P)$$
$$(f, g) \mapsto \{f, g\} = \sum_i \frac{\partial f}{\partial p_i} \frac{\partial g}{\partial q_i} - \frac{\partial g}{\partial p_i} \frac{\partial f}{\partial q_i}$$

$$P \ni (p, q)$$

$$X_H = \{H, \cdot\} = \sum_i \frac{\partial H}{\partial p_i} \frac{\partial}{\partial q_i} - \frac{\partial H}{\partial q_i} \frac{\partial}{\partial p_i}$$

Velocity in Ph Sp
HAM V.F.

Sympl. Geom

DEF (sympl. mfd)

P be $2n$ -dim.
 $\omega \in \Omega^2(P)$ s.t.
↑
SYMPLE FORM

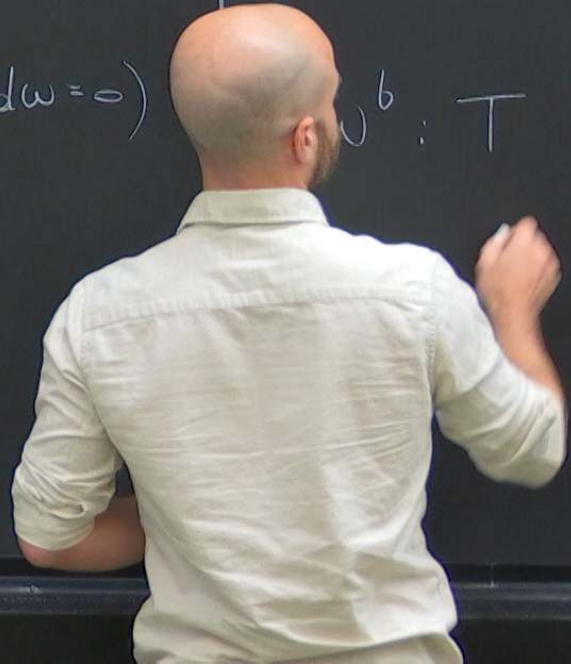
- ① ω is non deg.
- ② ω is closed ($d\omega = 0$)

① Non deg

$$\omega = \sum_{I,J} \frac{1}{2} \omega_{IJ}$$

invert as a (skew)

$\omega^b : T$



Velocity in T^*M by
HAM V.F.

① ω is non deg.

② ω is closed ($d\omega=0$)

① Non deg

$$\omega = \sum_{I,J} \frac{1}{2} \omega_{IJ}(z) dz^I \wedge dz^J$$

invertible at all z
as a $2n \times 2n$
(skew) matrix

$$\bullet \omega^b : TP \longrightarrow T^*P$$

$$(z, X) \longmapsto (z, i_X \omega(z))$$

ω is non degenerate iff ω^b is injective

(\Rightarrow surjective \Rightarrow bijective)

(finite dim)

②

DEF [Liouville]

$$d\mu_L = \frac{1}{n!} \underbrace{\omega \wedge \dots \wedge \omega}_{n\text{-times}} \in \mathcal{S}L^{(2n)}(P)$$

(vol form on P)

DEF [sympl. potential]

$$\theta \in \mathcal{S}L^1(P) \text{ s.t. } \omega := d\theta \text{ is sympl.}$$

(existence not guaranteed)

$\omega(z)$)
 ω^\flat is injective

THM $P = T^*Q$ is canonically symplectic

$$\omega := d\Theta =$$

Pf: i) T_q^*Q v. sp. with basis $\{dq^i\}$
 p_i are coords on T_q^*Q in this basis.

(i.e. $\alpha \in T_q^*Q$, $\alpha = \sum_i p_i(\alpha) dq^i$)

ii) $\{p_i, q^i\}$ coords on $T^*Q = P$

$\Rightarrow \Theta(p, q) = \sum_i p_i dq^i \in \Omega^1(P)$ CANONICAL
(TAUTOLOGICAL)
1-form

canonically symplectic

with basis $\{dq^i\}$

on $T^*_q Q$ in this basis.

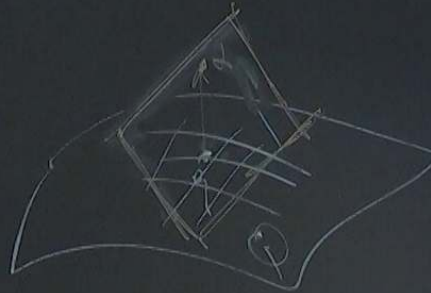
$\alpha = \sum_i p_i(q) dq^i$

α on $T^*Q = P$

$q^i \in \Omega^1(P)$ CANONICAL
(TAUTOLOGICAL)
1-form

$$\omega := d\Theta = \sum_i dp_i \wedge dq^i \quad \text{SYMPL.}$$

$$n=1 \quad \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$



THM [Darboux]

Let (P, ω) sympl.

Then, locally

\exists coords $\mathbb{Z}^I = (q^1, \dots, q^n, p_1, \dots, p_n)$
such that $\omega = \sum_i dp_i \wedge dq^i$
("canonical" or Darboux coords)

↓
in an open neighborhood

(of every pt)

Cor: $dx_L = \pm dq^1 \wedge \dots \wedge dq^n \wedge dp_1 \wedge \dots \wedge dp_n$

$$\omega = \text{Area 2-form} \\ = d\cos\theta \wedge d\phi$$

$$\mathcal{V} = \underbrace{\cos\theta}_{\uparrow} \underbrace{d\phi}_{\uparrow}$$



Back to P.B.

$$\{ \cdot, \cdot \} = \text{is a bivector} \\ = \frac{1}{2} \Pi^{IJ}(z) \frac{\partial}{\partial z^I} \wedge \frac{\partial}{\partial z^J}$$

Prop Let (P, ω) be sympl

$$\Rightarrow (P, \Pi), \quad \Pi^{IJ}(z) = (\omega_{IJ}(z))^{-1}$$

is Poisson $\begin{cases} \rightarrow \text{skewsym} \checkmark \\ \rightarrow \text{bi-derivation} \checkmark \\ \rightarrow \text{Jacobi} \iff \boxed{\text{closedness}} \end{cases}$

Back to P.B.

$$\{ \cdot, \cdot \} = \text{is a bivector} \\ = \frac{1}{2} \Pi^{IJ}(z) \frac{\partial}{\partial z^I} \wedge \frac{\partial}{\partial z^J}$$

$$\{fg, h\} = f\{g, h\} + \{f, h\}g$$

Prop Let (P, ω) be sympl

$$\Rightarrow (P, \Pi), \quad \Pi^{IJ}(z) = (\omega_{IJ}(z))^{-1}$$

is Poisson $\begin{cases} \rightarrow \text{skewsym} \checkmark \\ \rightarrow \text{bi-derivation} \checkmark \\ \rightarrow \text{Jacobi} \iff \boxed{\text{closedness}} \end{cases}$