

Title: Numerical Methods Lecture - 230202

Speakers: Erik Schnetter

Collection: Numerical Methods (2022/2023)

Date: February 02, 2023 - 9:15 AM

URL: <https://pirsa.org/23020000>

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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Julia 1.8.5

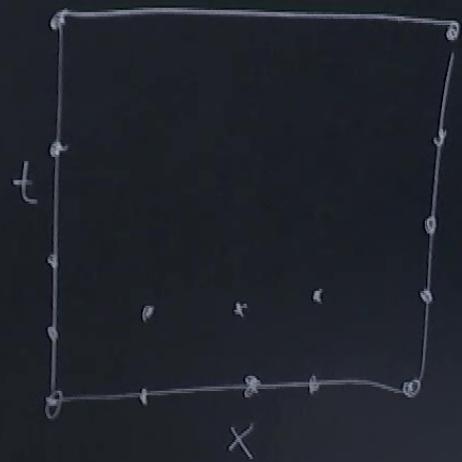
[10]: `using CairoMakie`

[11]: `fig = Figure(resolution = (300, 300))  
ax = Axis(fig[1, 1])  
contourf!(vec(x), vec(t), vec(u))  
fig`

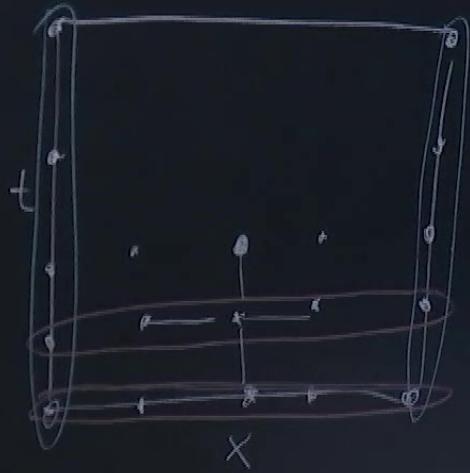
[11]:

Simple 0 \$ 1 Julia 1.8.5 | Idle Mem: 1.08 GB Saving completed Mode: Command Ln 1, Col 1 Wave Equation 2023.ipynb

Wave equation:  $\partial_t^2 u = \partial_x^2 u$



Wave equation:  $\partial_t^2 u = \partial_x^2 u$



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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Julia 1.8.5

## Solve the wave equation

```
[1]: # Define two grid functions `t`, `x` holding the c
function coords(nn, ni, dt, dx)
    t = [n * dt for i in 0:ni, n in 0:nn]
    x = [i * dx for i in 0:ni, n in 0:nn]
    return t, x
end

[1]: coords (generic function with 1 method)

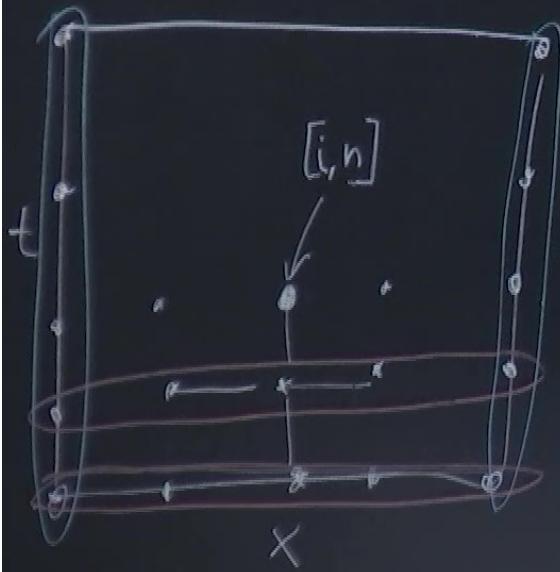
[7]: t, x = coords(101, 101, 1/100, 1/100);

[8]: function standing(t, x)
    ni, nn = size(t)
    u = zeros(ni, nn)
    # Initial conditions for first two points in time
    for n in 1:2, i in 1:ni
        u[i, n] = cos(2π * t[n, i]) * sin(2π * x[n, i])
    end
    return u
end
```

Simple 0 \$ 1 Julia 1.8.5 | Idle Mem: 1.08 GB Saving completed Mode: Edit Ln 1, Col 51 Wave Equation 2023.ipynb

Wave equation:  $\partial_t^2 u = \partial_x^2 u$

$$f''_i := \frac{f_{i-1} - 2f_i + f_{i+1}}{h^2}$$



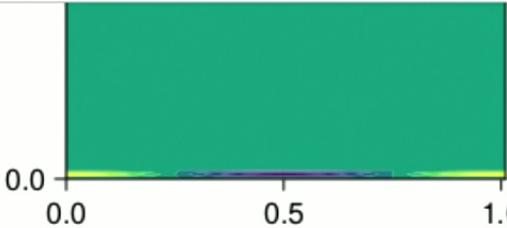
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Code git



```
[ ]: # Find the solution at one interior point u[i,n]
function evolve_point!(u, dt, dx, n, i)
    ni, nn = size(u)
    # Finite difference for second derivative in x direction at point [i,n-1]
    uxx = (u[i-1,n-1] - 2*u[i,n-1] + u[i+1,n-1]) / dx^2
    # Time derivative
    utt = (u[i,n-2] - 2*u[i,n-1] + u[i,n]) / dt^2
```

Simple 0 \$ 1 Julia 1.8.5 | Idle Mem: 1.22 GB Saving completed Mode: Command Ln 1, Col 49 Wave Equation 2023.ipynb

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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Julia 1.8.5

[15]: # Find the solution at one interior point  $u[i,n]$   
function evolve\_point!(u, dt, dx, n, i)  
 ni, nn = size(u)  
 # Finite difference for second derivative in x direction at point [i,n-1]  
 uxx = (u[i-1,n-1] - 2\*u[i,n-1] + u[i+1,n-1]) / dx^2  
 # Time derivative  
 # utt = (u[i,n-2] - 2\*u[i,n-1] + u[i,n]) / dt^2  
 # Wave equation  
 # utt = uxx  
 # Solve for  $u[i,n]$   
 u[i,n] = uxx \* dt^2 - u[i,n-2] + 2\*u[i,n-1]  
 return  
end

[15]: evolve\_point! (generic function with 1 method)

[ ]:

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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Julia 1.8.5

```
uxx = (u[i-1,n-1] - 2*u[i,n-1] + u[i+1,n-1]) / dx^2
# Time derivative
# utt = (u[i,n-2] - 2*u[i,n-1] + u[i,n]) / dt^2
# Wave equation
# utt = uxx
# Solve for u[i,n]
u[i,n] = uxx * dt^2 - u[i,n-2] + 2*u[i,n-1]
return
end

[16]: evolve_point! (generic function with 1 method)

[ ]: # Find the solution for one point in time `n`
function evolve_step!(u, dt, dx, n)
    ni, nn = size(u)
    # Apply boundary condition at left boundary
    u[1,n] = 0
    # Evolve interior
    for i in 2:ni-1
        evolve_point!(u, dt, dx, n, i)
    end
    # Apply boundary condition at right boundary
    u[ni,n] = 0
    return
end
```

Simple 0 \$ 1 Julia 1.8.5 | Idle Mem: 1.14 GB Saving completed Mode: Edit Ln 13, Col 4 Wave Equation 2023.ipynb

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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Julia 1.8.5

## Solve the wave equation

```
[12]: # Define two grid functions `t`, `x` holding the coordinates
function coords(nn, ni, dt, dx)
    t = [n * dt for i in 0:ni, n in 0:nn]
    x = [i * dx for i in 0:ni, n in 0:nn]
    return t, x
end

[12]: coords (generic function with 1 method)

[7]: nn = 101
ni = 101
dt = 1 / (nn-1)
dx = 1 / (ni-1)
t, x = coords(101, 101, 1/100, 1/100);

[13]: # Define initial conditions for a standing wave
function standing(t, x)
    ni, nn = size(t)
    u = zeros(ni, nn)
    # Initial conditions for first two points in time
    for n in 1:2, i in 1:ni
```

Simple 0 \$ 1 Julia 1.8.5 | Idle Mem: 1.36 GB Saving completed Mode: Edit Ln 5, Col 15 Wave Equation 2023.ipynb

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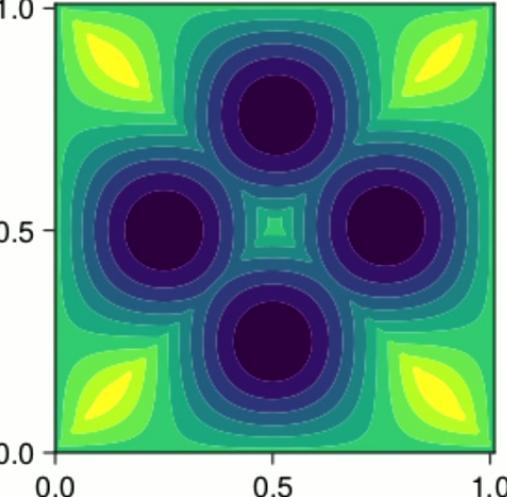
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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Julia 1.8.5

[20]: evolve!(u, dt, dx)

[21]: fig = Figure(resolution = (300, 300))  
ax = Axis(fig[1, 1])  
contourf!(vec(x), vec(t), vec(u))  
fig

[21]:



Simple 0 \$ 1 Julia 1.8.5 | Idle Mem: 1.22 GB Saving completed Mode: Edit Ln 1, Col 1 Wave Equation 2023.ipynb

A screenshot of a Mac OS X desktop environment. At the top, the Dock shows various icons like Safari, Mail, and Finder. The system status bar at the top right displays the date (Thu Feb 2 09:46), battery level (100%), signal strength, and other system info. The main window is a JupyterLab interface. The title bar says "symmetry.pi.local" and "JupyterLab". The menu bar includes File, Edit, View, History, Bookmarks, Develop, Window, Help, and a Calculating... progress indicator. The toolbar has icons for file operations like New, Open, Save, and Run, along with a Git icon. The tabs show "Untitled10.ipynb", "Convergence 2023 b.ipynb", and "Wave Equation 2023.ipynb" (which is currently active). The notebook area contains Julia code for a standing wave simulation. The bottom status bar shows "Simple" mode, keyboard shortcuts (0, \$, 1), the kernel (Julia 1.8.5 | Idle), memory usage (Mem: 1.08 GB), a saving message ("Saving completed"), mode ("Mode: Command"), line and column numbers ("Ln 3, Col 34"), and the notebook name ("Wave Equation 2023.ipynb").

```
dx = 1 / (ni-1)
t, x = coords(nn, ni, dt, dx);

[3]: # Define initial conditions for a standing wave
function standing(t, x)
    ni, nn = size(t)
    u = zeros(ni, nn)
    # Initial conditions for first two points in time
    for n in 1:2, i in 1:ni
        u[i, n] = cos(2π * t[n, i]) * sin(2π * x[n, i])
    end
    return u
end

[3]: standing (generic function with 1 method)

[4]: u = standing(t, x);

[5]: using CairoMakie

[6]: fig = Figure(resolution = (300, 300))
ax = Axis(fig[1, 1])
contourf!(vec(x), vec(t), vec(u))
fig
```

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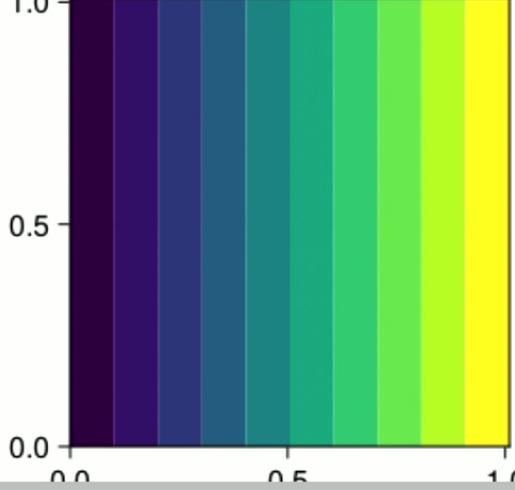
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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Julia 1.8.5

[14]: `using CairoMakie`

[21]: `fig = Figure(resolution = (300, 300))  
ax = Axis(fig[1, 1])  
# contourf!(vec(x), vec(t), vec(u))  
contourf!(vec(x), vec(t), vec(x))  
fig`

[21]: 

Simple 0 \$ 1 Julia 1.8.5 | Idle Mem: 1.10 GB Saving completed Mode: Command Ln 1, Col 51 Wave Equation 2023.ipynb

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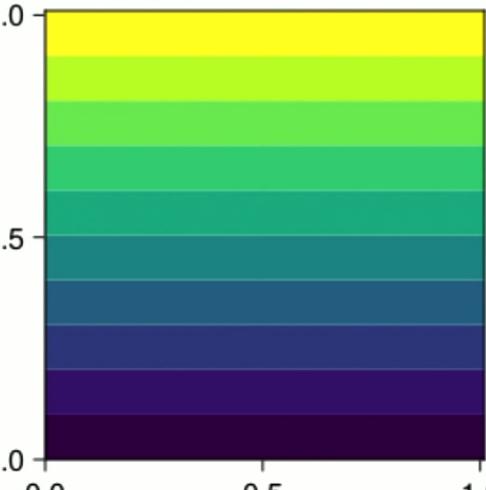
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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Julia 1.8.5

[14]: `using CairoMakie`

[22]: `fig = Figure(resolution = (300, 300))  
ax = Axis(fig[1, 1])  
# contourf!(vec(x), vec(t), vec(u))  
contourf!(vec(x), vec(t), vec(t))  
fig`

[22]: 

Simple 0 \$ 1 Julia 1.8.5 | Idle Mem: 1.10 GB Saving completed Mode: Command Ln 1, Col 51 Wave Equation 2023.ipynb

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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Julia 1.8.5

[14]: `using CairoMakie`

[23]: `fig = Figure(resolution = (300, 300))  
ax = Axis(fig[1, 1])  
contourf!(vec(x), vec(t), vec(u))  
fig`

[23]:

Simple 0 \$ 1 Julia 1.8.5 | Idle Mem: 1.10 GB Saving completed Mode: Command Ln 1, Col 51 Wave Equation 2023.ipynb

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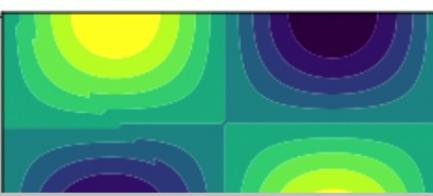
```
[30]: # Find the solution everywhere
function evolve!(u, dt, dx)
    ni, nn = size(u)
    # Loop over all times
    for n in 3:nn
        evolve_step!(u, dt, dx, n)
    end
    return
end

[30]: evolve! (generic function with 1 method)

[31]: evolve!(u, dt, dx)

[32]: fig = Figure(resolution = (300, 300))
ax = Axis(fig[1, 1])
contourf!(vec(x), vec(t), vec(u))
fig
```

[32]:



Simple 0 \$ 1 Julia 1.8.5 | Idle Mem: 1.10 GB Saving completed Mode: Command Ln 2, Col 21 Wave Equation 2023.ipynb

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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Julia 1.8.5

```
[34]: t1, x1 = coords(2nn-1, 2ni-1, dt/2, dx/2);

[35]: u1 = standing(t1, x1);

[37]: evolve!(u1, dt/2, dx/2)

[42]: fig = Figure(resolution = (300, 300))
ax = Axis(fig[1,1])
contourf!(fig[1,1], vec(x), vec(t), vec(u))
contourf!(fig[1,2], vec(x1), vec(t1), vec(u1))
fig
```

There needs to be a single axis-like object at GridLayoutBase.Span(1:1, 2:2), GridLayoutBase.Inner() to plot in to.  
Use a non-mutating plotting command to create an axis implicitly.

Stacktrace:

```
[1] error(s::String)
    @ Base ./error.jl:35
[2] plot!(::Type{Combined{Makie.contourf}}, ::GridPosition, ::Vector{Float64}, ::Vararg{Vector{Float64}}; kwargs::Base.Pairs{Symbol, Union{}, Tuple{}, NamedTuple{(), Tuple{}}})
    @ Makie ~/.julia/packages/Makie/Za3LL/src/figureplotting.jl:112
[3] plot!(::Type{Combined{Makie.contourf}}, ::GridPosition, ::Vector{Float64}, ::Vector{Float64})
```

Simple 0 \$ 1 ⚡ Julia 1.8.5 | Idle Mem: 1.27 GB Saving completed Mode: Edit ⚡ Ln 4, Col 1 Wave Equation 2023.ipynb

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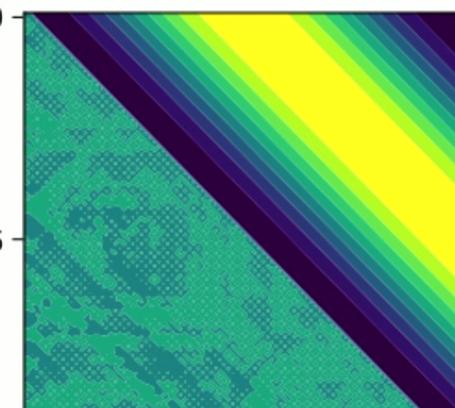
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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Julia 1.8.5

Code git

[44]: # Show error  
fig = Figure(resolution = (300, 300))  
ax = Axis(fig[1, 1])  
contourf!(vec(x), vec(t), vec(u - cos.(2π .\* t) .\* sin.(2π \* x)))  
fig

[44]:



Simple 0 \$ 1 Julia 1.8.5 | Idle Mem: 1.23 GB Saving completed Mode: Edit Ln 1, Col 1 Wave Equation 2023.ipynb

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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Julia 1.8.5

[48]: 

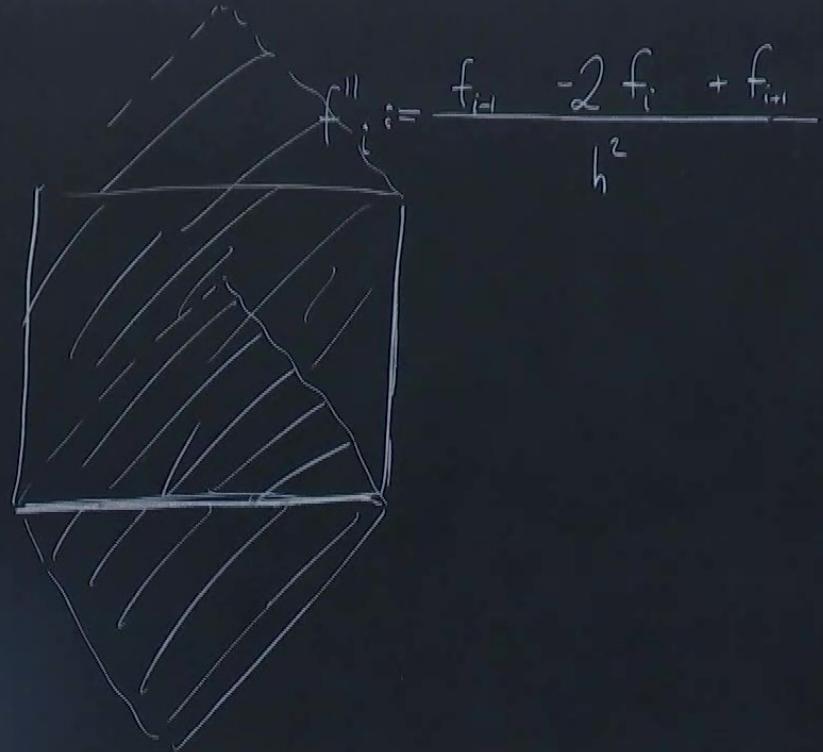
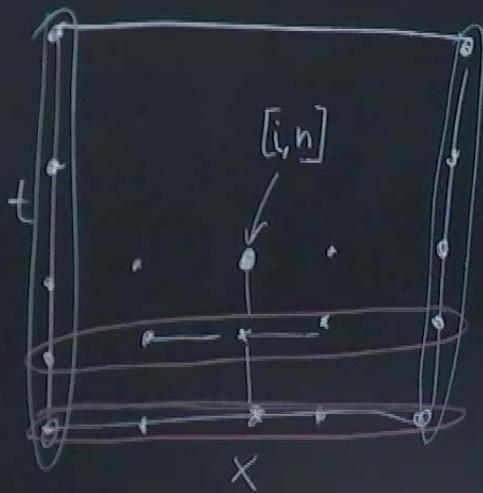
```
# Show error
fig = Figure(resolution = (300, 300))
ax = Axis(fig[1, 1])
contourf!(vec(x), vec(t), vec(u - cos.(2π * t) .* sin.(2π * x)))
fig
```

[48]:

Simple 0 \$ 1 Julia 1.8.5 | Idle Mem: 1.24 GB Saving completed Mode: Command Ln 4, Col 4 Wave Equation 2023.ipynb

Wave equation:

$$\partial_t^2 u = \partial_x^2 u$$



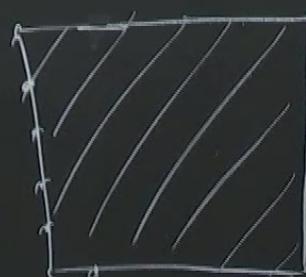
Poisson Equation

$$(\partial_x^2 + \partial_y^2) u = g$$

$$\Delta u = g$$

$$u = \Delta^{-1} g$$

$$u|_{\partial\Omega} = 0$$

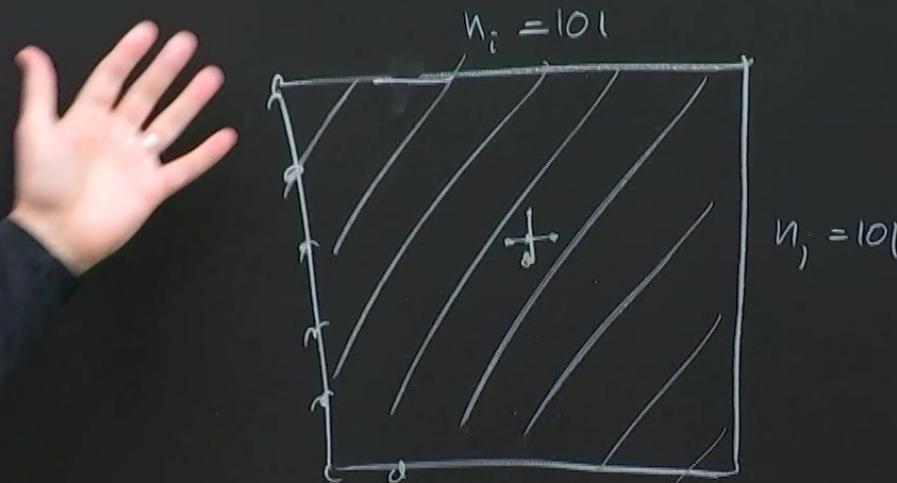


Equation

$$(\partial_x^2 + \partial_y^2) u = g$$

$$\Delta u =$$

$$u|_{\partial\Omega} =$$



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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Poisson Equation 2023.ipynb Julia 1.8.5

## Solve Poisson equation

```
[2]: # ( $\partial_t^2 + \partial_x^2$ ) u = p
# u = 0 on boundary (Dirichlet boundary conditions)

# Using finite differencing

[4]: # Choose problem size
ni = 5
nj = 5
dx = 1/(ni-1)
dy = 1/(nj-1);

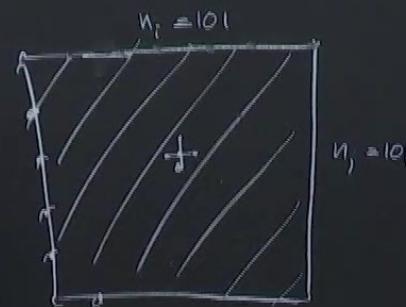
[6]: # Choose RHS (right hand side)
p = zeros(ni, nj)
p[2,2] = 1;

[ ]:
```

Simple 0 \$ 2 Julia 1.8.5 | Idle Mem: 1.67 GB Saving completed Mode: Command Ln 1, Col 1 Poisson Equation 2023.ipynb

## Poisson Equation

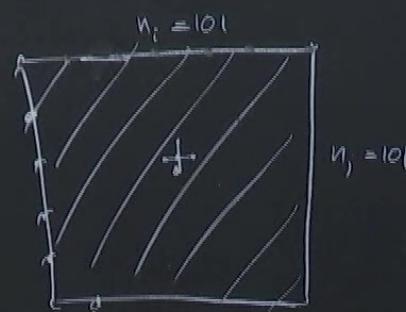
$$(\partial_x^2 + \partial_y^2) u = g$$



$$A \begin{cases} \Delta u = g \\ u|_{\partial\Omega} = 0 \end{cases} \quad u = \Delta^{-1} g$$
$$A \cdot x = b$$

Poisson Equation

$$(\partial_x^2 + \partial_y^2) u = g$$



$$\begin{aligned} A \left\{ \begin{array}{l} \Delta u = g \\ u|_{\partial\Omega} = 0 \end{array} \right. \quad u = \Delta^{-1} g \\ A^{-1} g \end{aligned}$$

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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Poisson Equation 2023.ipynb Julia 1.8.5

```
using SparseArrays

[9]: # Define the non-zero elements
I = Int[]
J = Int[]
V = Float64[];

[13]: # Boundary conditions (the easy part)

# left boundary
# A[1,1] = 1
push!(I, 1)
push!(J, 1)
push!(V, 1)

# right boundary
# A[ni,ni] = 1
push!(I, ni)
push!(J, ni)
push!(V, 1)
;

[ ]: # Interior: Laplace operator
for i in 2:ni-1
end
```

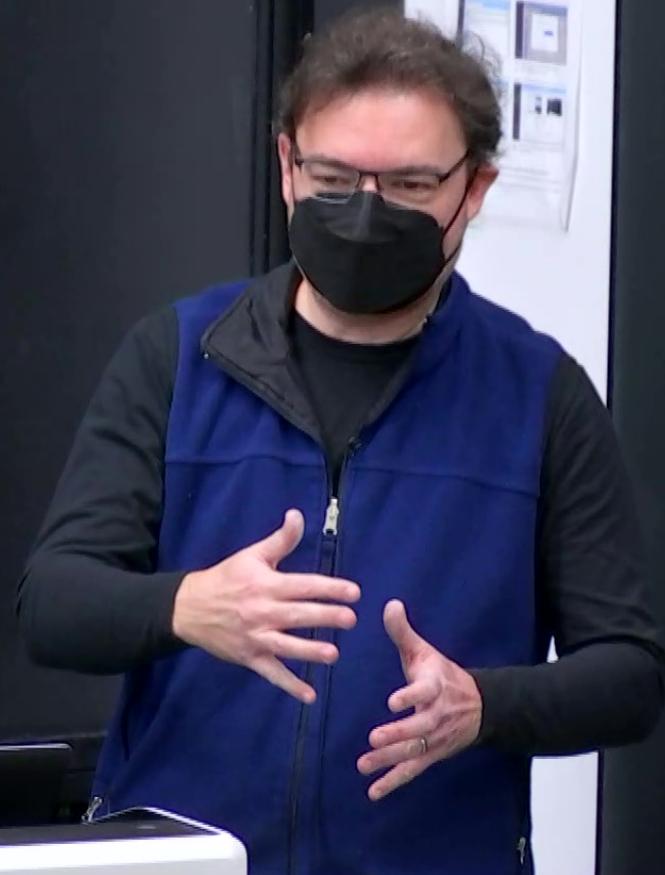
Simple 0 \$ 2 Julia 1.8.5 | Idle Mem: 1.56 GB Saving completed Mode: Command Ln 3, Col 19 Poisson Equation 2023.ipynb

$$f''_{i,i} := \frac{f_{i+1} - 2f_i + f_{i-1}}{h^2}$$

$$\partial_x^2 u$$

$$A \cdot u$$

$$u''_i = \frac{1}{h^2} \begin{bmatrix} & & \\ & 1 & -2 & 1 \\ & & & \end{bmatrix} \cdot \begin{bmatrix} u_{i-1} \\ u_i \\ u_{i+1} \\ \vdots \end{bmatrix}$$



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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Poisson Equation 2023.ipynb Julia 1.8.5

[21]: # Define RHS  
b = [0; ρ[2:ni-1]; 0]

[21]: 5-element Vector{Float64}:

0.0  
1.0  
1.0  
1.0  
0.0

[22]: u = A \ b

[22]: 5-element Vector{Float64}:

0.0  
-1.5  
-2.0  
-1.5  
0.0

[ ]:

Simple 0 \$ 2 Julia 1.8.5 | Idle Mem: 1.60 GB Saving completed Mode: Edit Ln 1, Col 1 Poisson Equation 2023.ipynb

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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Poisson Equation 2023.ipynb Julia 1.8.5

0.0

```
[23]: using CairoMakie
```

```
[26]: fig = Figure(resolution=(400, 200))
ax = Axis(fig[1, 1])
plot!(u; color=:red)
fig
```

0.0  
-0.5  
-1.0  
-1.5  
-2.0

1 2 3 4 5

[ ]:

Simple 0 \$ 2 Julia 1.8.5 | Idle Mem: 2.04 GB Saving completed Mode: Command Ln 1, Col 1 Poisson Equation 2023.ipynb

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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Poisson Equation 2023.ipynb Julia 1.8.5

```
# right stencil point
push!(I, i)      # row
push!(J, i+1)    # column
push!(V, 1/dx^2)  # value
end

[39]: A = sparse(I, J, V, ni, ni)

[39]: 51×51 SparseMatrixCSC{Float64, Int64} with 149 stored entries:
      ⋮
      ⋮
      ⋮
      ⋮
      ⋮
      ⋮
      ⋮
      ⋮

[40]: # Define RHS
b = [0; p[2:ni-1]; 0]
```

Simple 0 \$ 2 Julia 1.8.5 | Idle Mem: 2.00 GB Saving completed Mode: Command Ln 1, Col 10 Poisson Equation 2023.ipynb

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Untitled10.ipynb Convergence 2023 b.ipynb Wave Equation 2023.ipynb Poisson Equation 2023.ipynb Julia 1.8.5

[53]: `using CairoMakie`

[54]: `fig = Figure(resolution=(400, 200))  
ax = Axis(fig[1, 1])  
plot!(u; color=:red)  
fig`

[54]:

[ ]:

Simple 0 \$ 2 Julia 1.8.5 | Idle Mem: 1.99 GB Saving completed Mode: Command Ln 1, Col 32 Poisson Equation 2023.ipynb