

Title: Reflecting scalar fields in numerical relativity

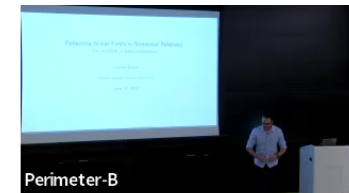
Speakers: Conner Dailey

Collection: Young Researchers Conference

Date: June 21, 2022 - 9:25 AM

URL: <https://pirsa.org/22060049>

Abstract: Black hole echoes have been considered as new probes to standard gravitational waveforms. Here, I consider reflections of scalar waves around a black hole as a model of black hole echoes arising from scalar fields. This problem is difficult due to the need for a proper understanding of the characteristic fields that propagate in numerical relativity. Using the "Einstein-Christoffel" system, I model the characteristic fields and the boundary conditions in such a way as to properly reflect scalar waves at a boundary using the full power of Einstein's equations.



Reflecting Scalar Fields in Numerical Relativity

The full IBVP in Spherical Symmetry

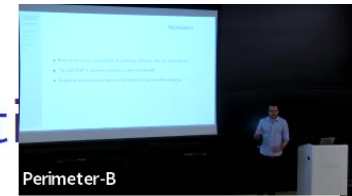
Conner Dailey



Perimeter Institute, University of Waterloo

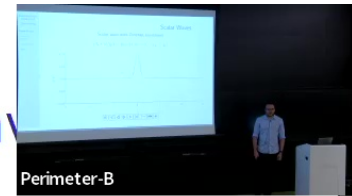
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Motivati



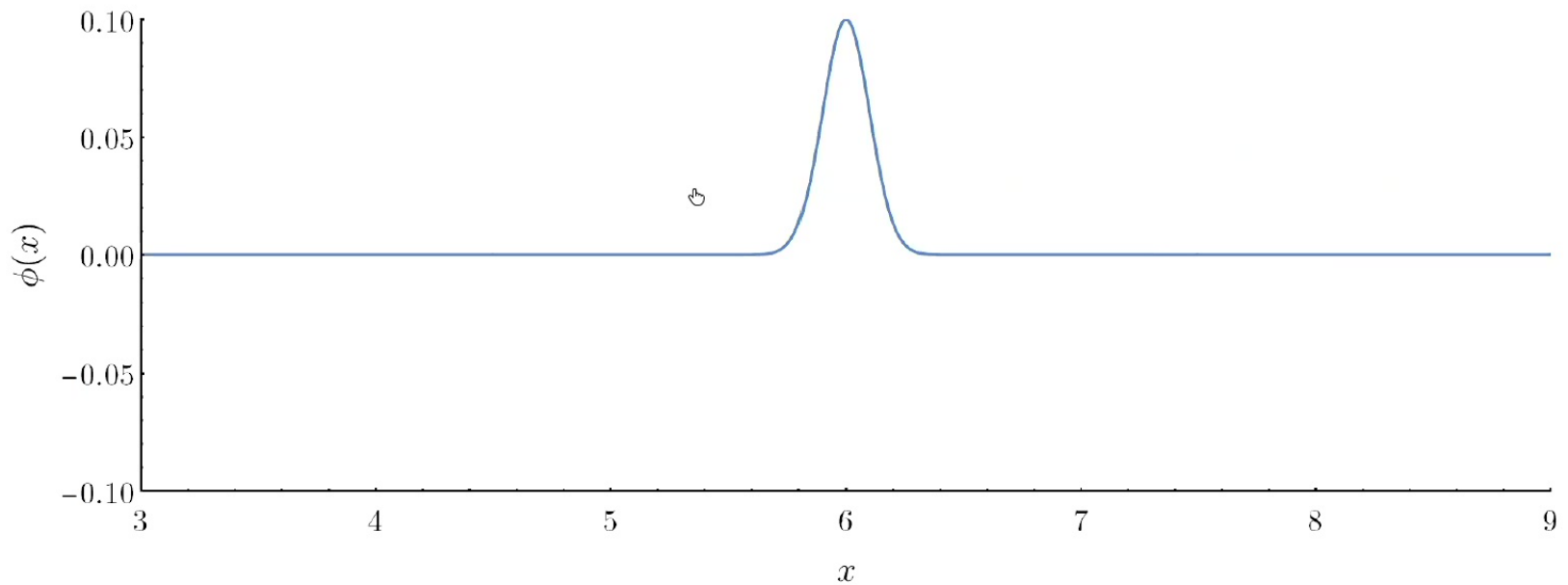
- Black hole echoes, indications of reflecting behavior near an event horizon
- The full IBVP in general relativity is often overlooked
- Simplified simulations in spherical symmetry using a modern language

Scalar Wave



Scalar wave with Dirichlet boundaries

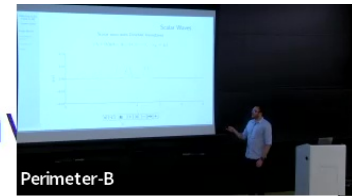
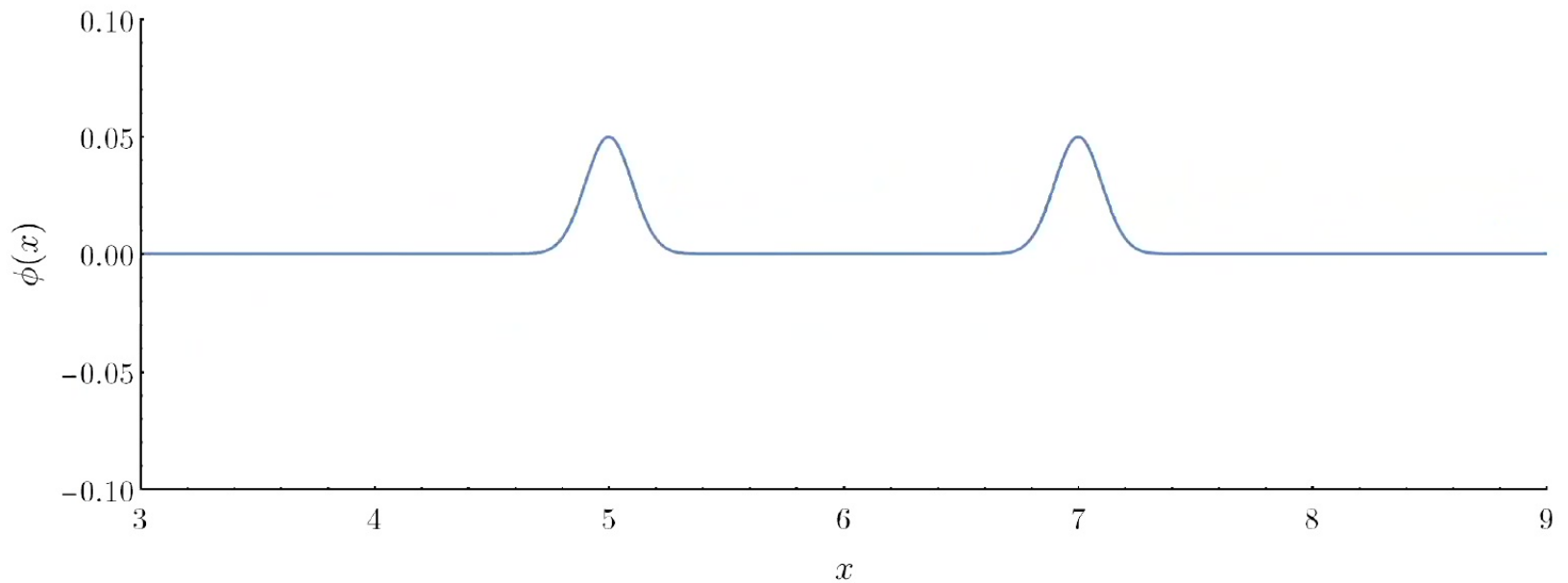
$$(\partial_t + \partial_x)(\partial_t - \partial_x)\phi(x, t) = 0, \quad c_{\pm} = \pm 1$$



Scalar Wave

Scalar wave with Dirichlet boundaries

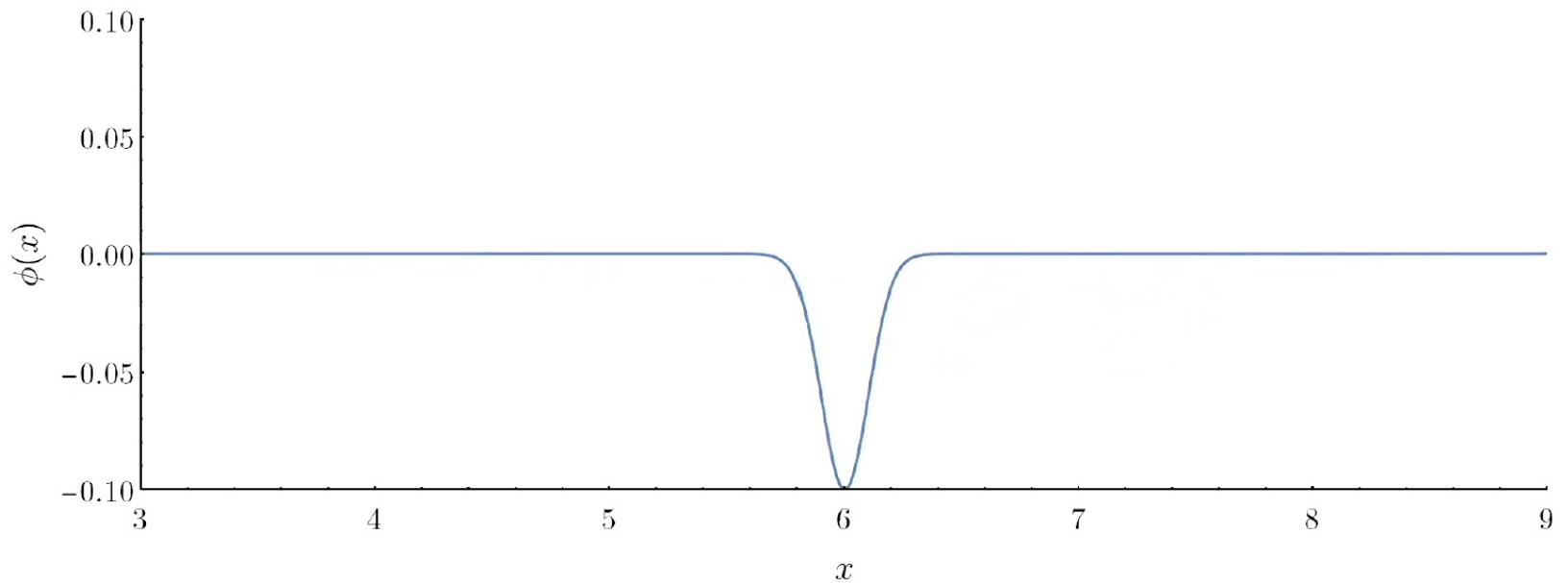
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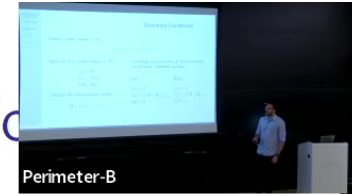
Scalar Wave

Scalar wave with Dirichlet boundaries

$$(\partial_t + \partial_x)(\partial_t - \partial_x)\phi(x, t) = 0, \quad c_{\pm} = \pm 1$$



Boundary Conditions



General scalar waves in GR

$$g^{\mu\nu} \partial_\mu \partial_\nu \phi - \Gamma^\mu \partial_\mu \phi = 0$$

Split into first order system in 1D

$$\partial_t \phi = \Pi$$

$$\partial_t \psi = \partial_r \Pi$$

$$\partial_t \Pi = \Pi_{\text{rhs}}$$

Identify the characteristic modes

$$\Pi + c_{\mp} \psi, \quad v = c_{\pm}$$

Exchange characteristics at the boundaries,
for Dirichlet reflection we have

Left

$$\partial_t \phi = 0$$

$$\partial_t \psi = \partial_r \Pi + \Pi_{\text{rhs}}/c_+$$

$$\partial_t \Pi = 0$$

Right

$$\partial_t \phi = 0$$

$$\partial_t \psi = \partial_r \Pi + \Pi_{\text{rhs}}/c_-$$

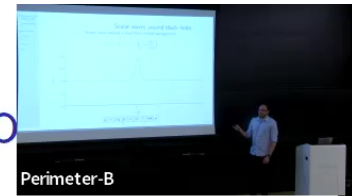
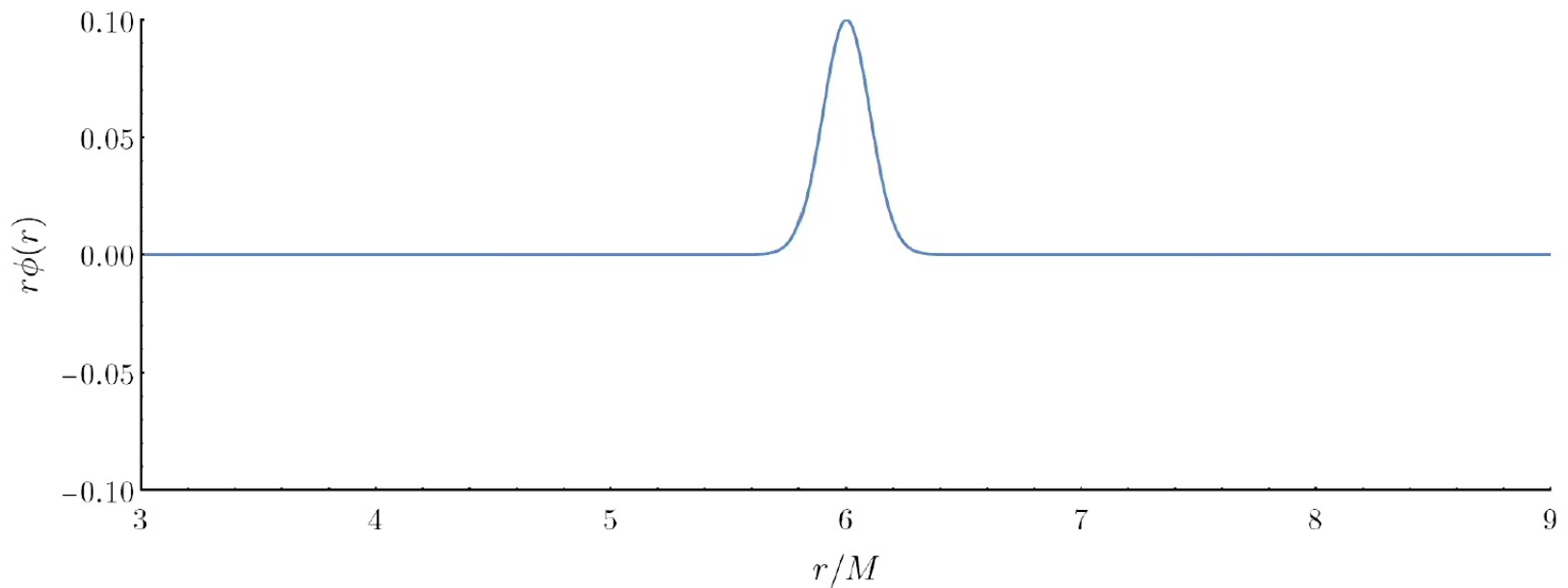
$$\partial_t \Pi = 0$$



Scalar waves around black holes

Scalar wave around a fixed Kerr-Schild background

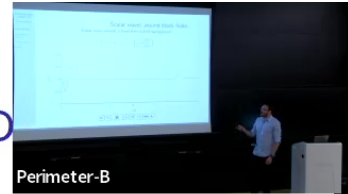
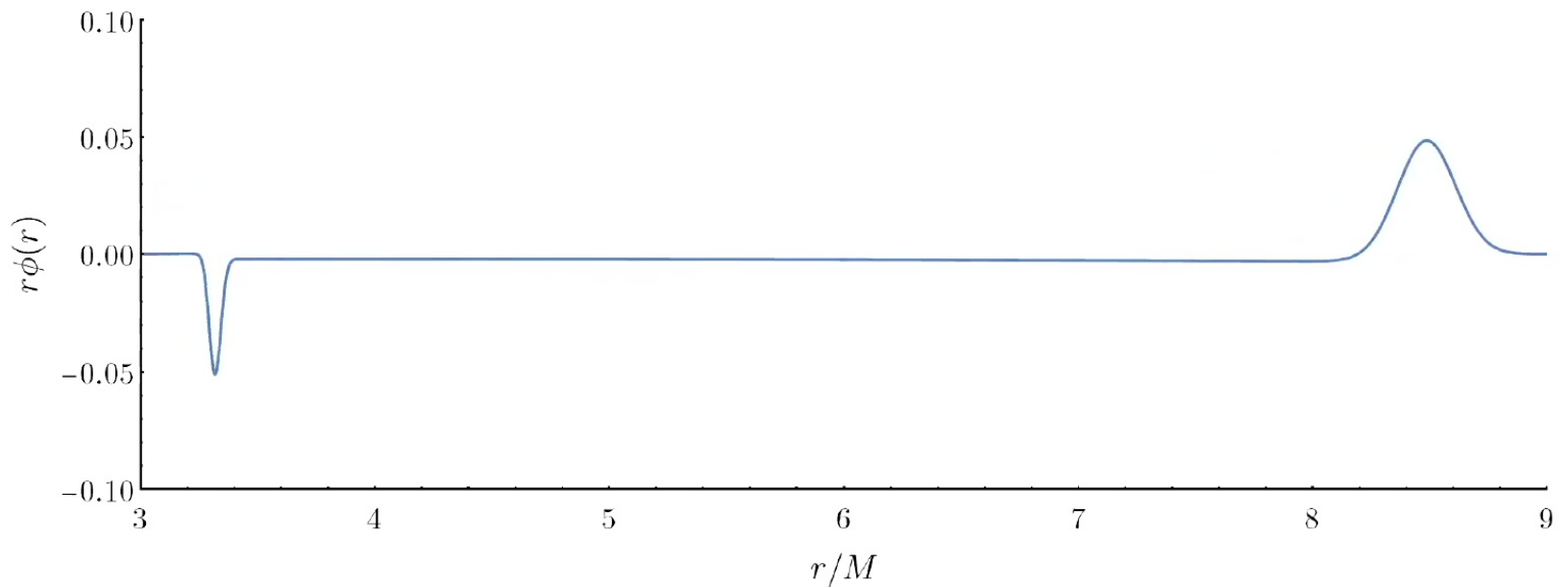
$$c_- = -1, \quad c_+ = \left(\frac{r - 2M}{r + 2M} \right)$$



Scalar waves around black holes

Scalar wave around a fixed Kerr-Schild background

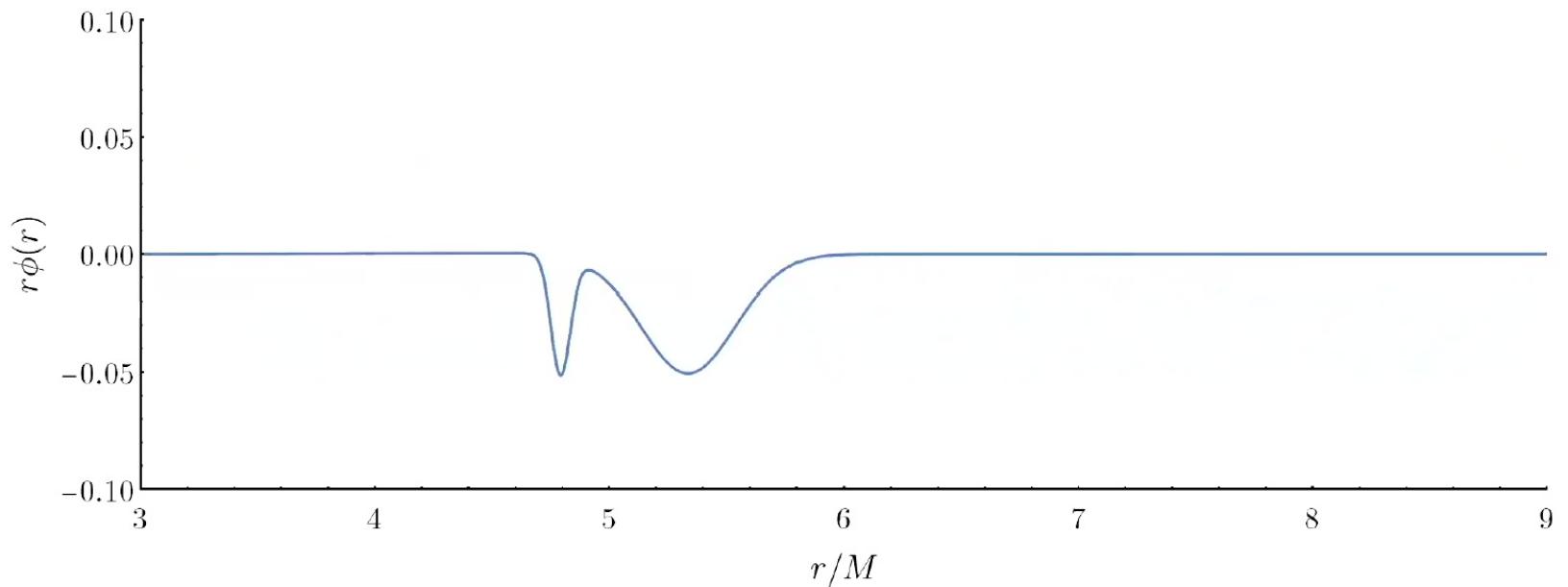
$$c_- = -1, \quad c_+ = \left(\frac{r - 2M}{r + 2M} \right)$$



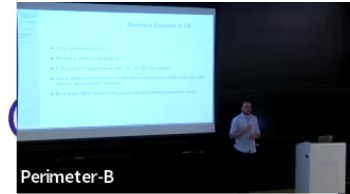
Scalar waves around black holes

Scalar wave around a fixed Kerr-Schild background

$$c_- = -1, \quad c_+ = \left(\frac{r - 2M}{r + 2M} \right)$$



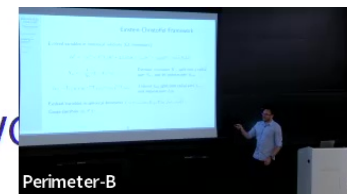
Numerical Evolution in GR



- Vector of evolved variables \vec{u}
- We need a system of equations $\partial_t \vec{u} = \dots$
- If the system is higher order in time, you can add more variables
- Lots of freedom of choice here, we just want a system that is stable numerically and correctly solves Einstein's equations
- For a proper IBVP, we would like physical and well-defined characteristic speeds



Einstein-Christoffel Framework



Evolved variables in numerical relativity (EC framework)

$$ds^2 = -(\alpha^2 - \beta^r \beta_r) dt^2 + 2\beta_r dt dr + \gamma_{rr} dr^2 + \gamma_{\theta\theta} (d\theta^2 + \sin^2(\theta) d\phi^2)$$

$$K_{ij} = -\frac{1}{2\alpha} (\partial_t - \mathcal{L}_\beta) \gamma_{ij}$$

Extrinsic curvature K_{ij} split into a radial part K_{rr} and an angular part $K_{\theta\theta}$

$$f_{kij} = \Gamma_{(ij)k} + \gamma_{ki} \gamma^{lm} \Gamma_{[lj]m} + \gamma_{kj} \gamma^{lm} \Gamma_{[li]m}$$

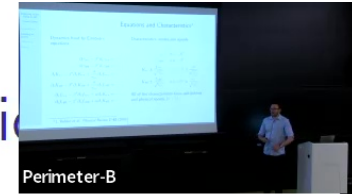
3-tensor f_{kij} split into radial part f_{rrr} and angular part $f_{r\theta\theta}$

Evolved Variables in spherical symmetry $\vec{u} = (\gamma_{rr}, \gamma_{\theta\theta}, K_{rr}, K_{\theta\theta}, f_{rrr}, f_{r\theta\theta})$

Gauge variables (α, β^r)



Equations and Characteristics



Dynamics fixed by Einstein's
equations

$$\begin{aligned}\partial_t \gamma_{rr} - \beta^r \partial_r \gamma_{rr} &= \dots, \\ \partial_t \gamma_{\theta\theta} - \beta^r \partial_r \gamma_{\theta\theta} &= \dots, \\ \partial_t K_{rr} - \beta^r \partial_r K_{rr} + \frac{\alpha}{\gamma_{rr}} \partial_r f_{rrr} &= \dots, \\ \partial_t K_{\theta\theta} - \beta^r \partial_r K_{\theta\theta} + \frac{\alpha}{\gamma_{rr}} \partial_r f_{r\theta\theta} &= \dots, \\ \partial_t f_{rrr} - \beta^r \partial_r f_{rrr} + \alpha \partial_r K_{rr} &= \dots, \\ \partial_t f_{r\theta\theta} - \beta^r \partial_r f_{r\theta\theta} + \alpha \partial_r K_{\theta\theta} &= \dots.\end{aligned}$$

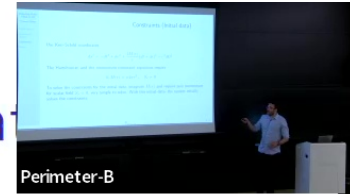
Characteristics modes and speeds

$$\begin{aligned}\gamma_{rr}, \quad v &= -\beta^r \\ \gamma_{\theta\theta}, \quad v &= -\beta^r \\ K_{rr} \pm \frac{f_{rrr}}{\sqrt{\gamma_{rr}}}, \quad v &= -\beta^r \pm \frac{\alpha}{\sqrt{\gamma_{rr}}} \\ K_{\theta\theta} \pm \frac{f_{r\theta\theta}}{\sqrt{\gamma_{rr}}}, \quad v &= -\beta^r \pm \frac{\alpha}{\sqrt{\gamma_{rr}}}\end{aligned}$$

All of the characteristics have well-defined
and physical speeds ($v \leq 1$)

¹L. Kidder *et al.*, *Physical Review D* **62** (2000).
I

Constraints (Initial data)



Use Kerr-Schild coordinates

$$ds^2 = -dt^2 + dr^2 + \frac{2M(r)}{r}(dt + dr)^2 + r^2 d\Omega^2$$

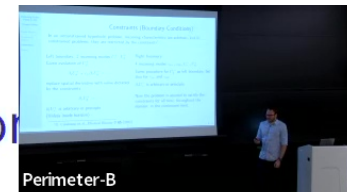
The Hamiltonian and the momentum constraint equations require

$$\partial_r M(r) = \rho 4\pi r^2, \quad S_r = 0$$

To solve the constraints for the initial data, integrate $M(r)$ and require zero momentum for scalar field $S_r = 0$, very simple to solve. With this initial data, the system initially solves the constraints.



Constraints (Boundary Conditions)



In an unconstrained hyperbolic problem, incoming characteristics are arbitrary, but in constrained problems, they are restricted by the constraints².

Left boundary: 2 incoming modes U_r^+, U_θ^+

Given evolution of U_θ^+

$$\partial_t U_\theta^+ + c_+ \partial_r U_\theta^+ = \dots$$

replace spatial derivative with value dictated by the constraints

$$\partial_r U_\theta^+ = \dots$$

$\partial_t U_r^+$ is arbitrary in principle

(Unless inside horizon)

Right boundary:

4 incoming modes $\gamma_{rr}, \gamma_{\theta\theta}, U_r^-, U_\theta^-$

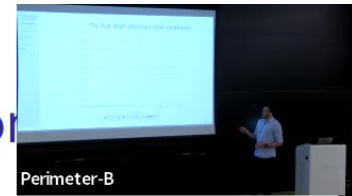
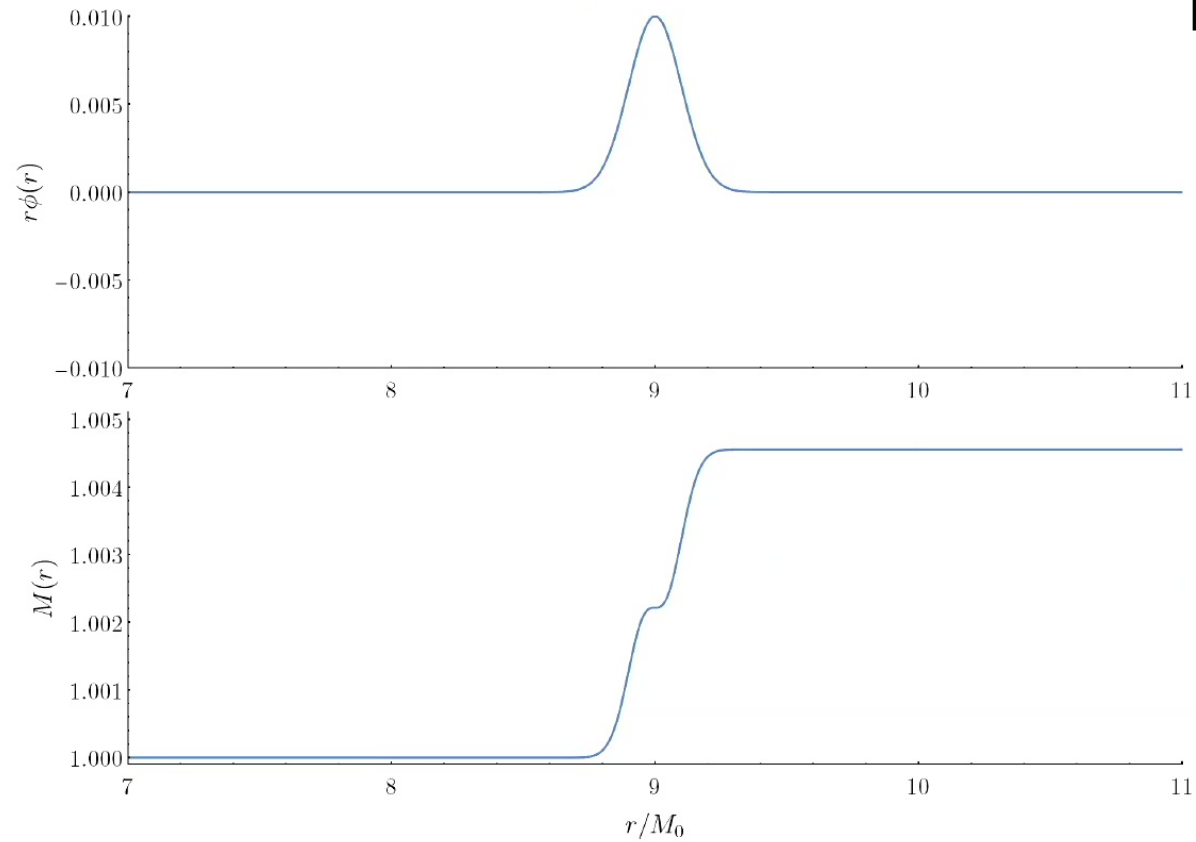
Same procedure for U_θ^- as left boundary, but also for γ_{rr} and $\gamma_{\theta\theta}$

$\partial_t U_r^-$ is arbitrary in principle

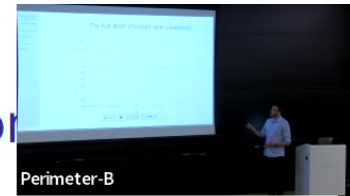
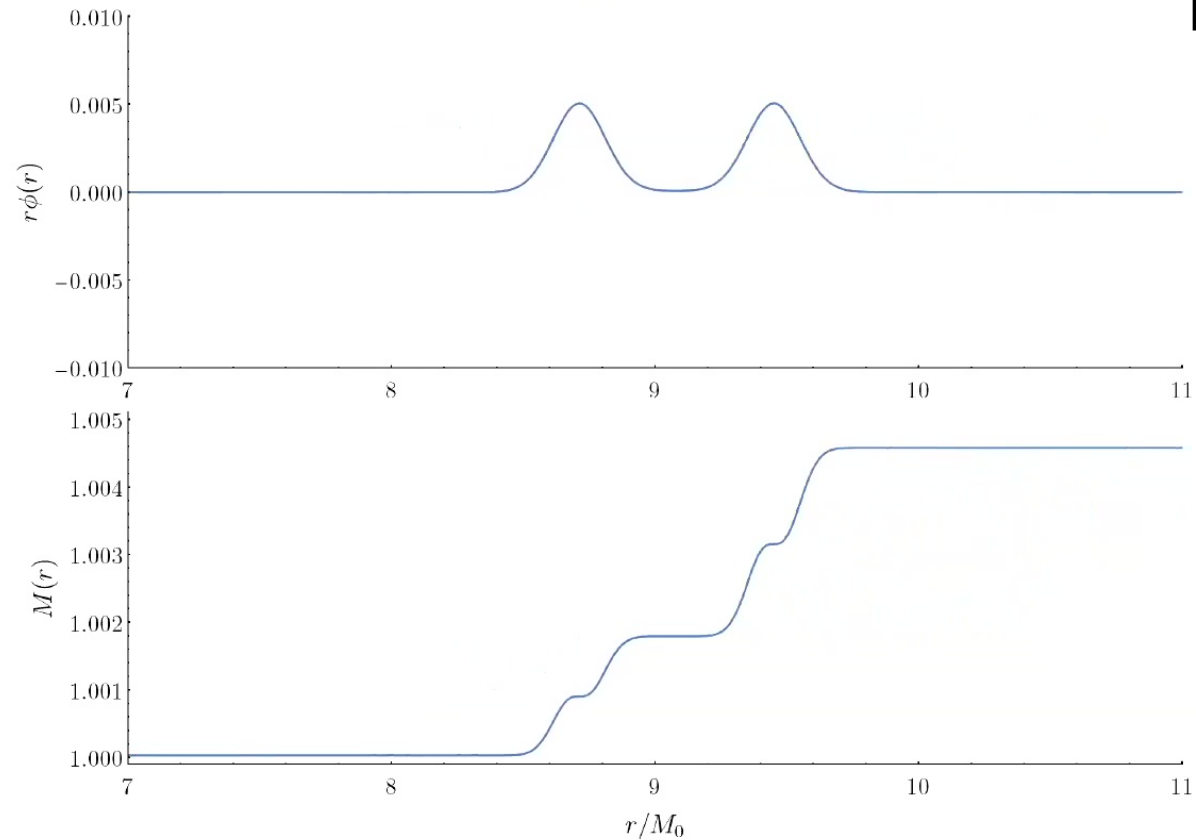
Now the problem is assured to satisfy the constraints for all time, throughout the domain, in the continuum limit.

²G. Calabrese *et al.*, *Physical Review D* **65** (2002).

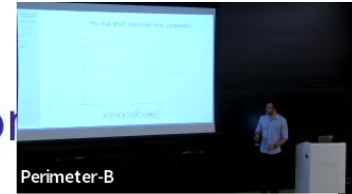
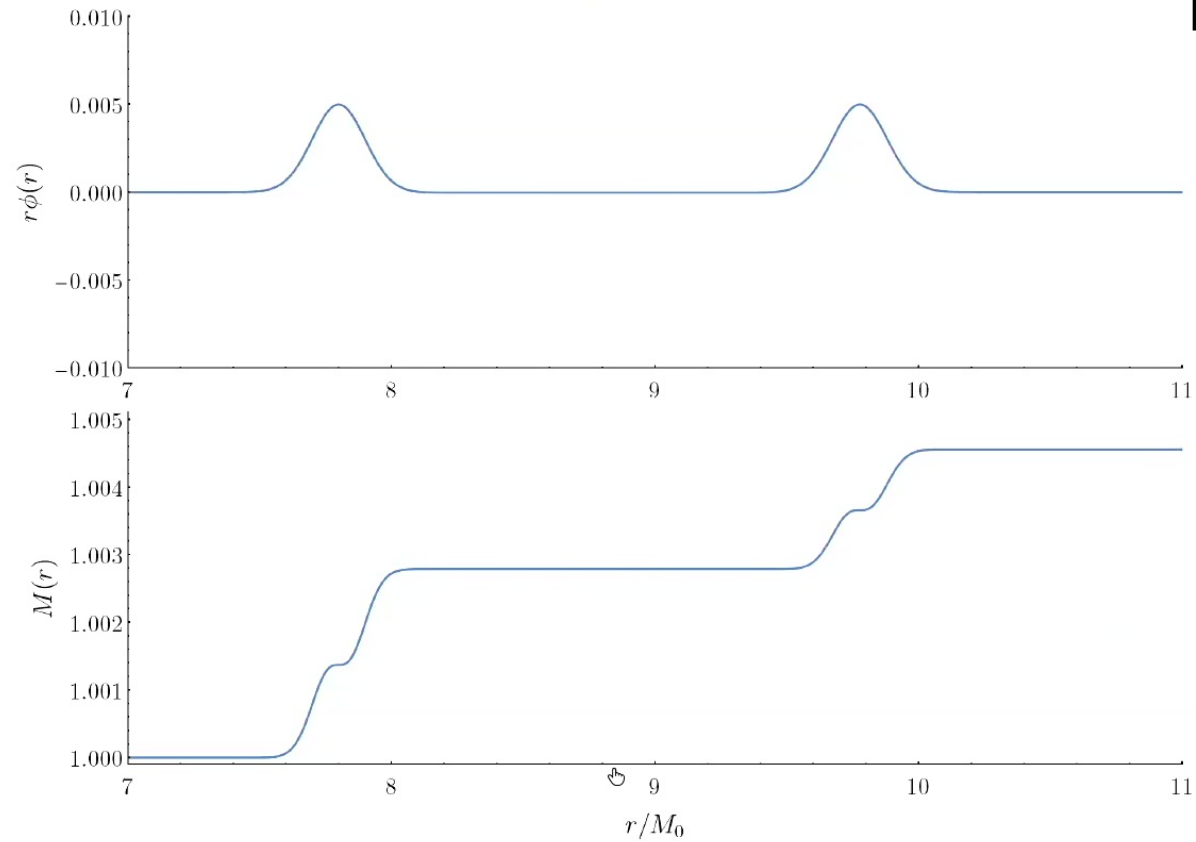
The Full IBVP (Dirichlet style condition



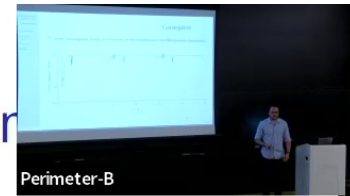
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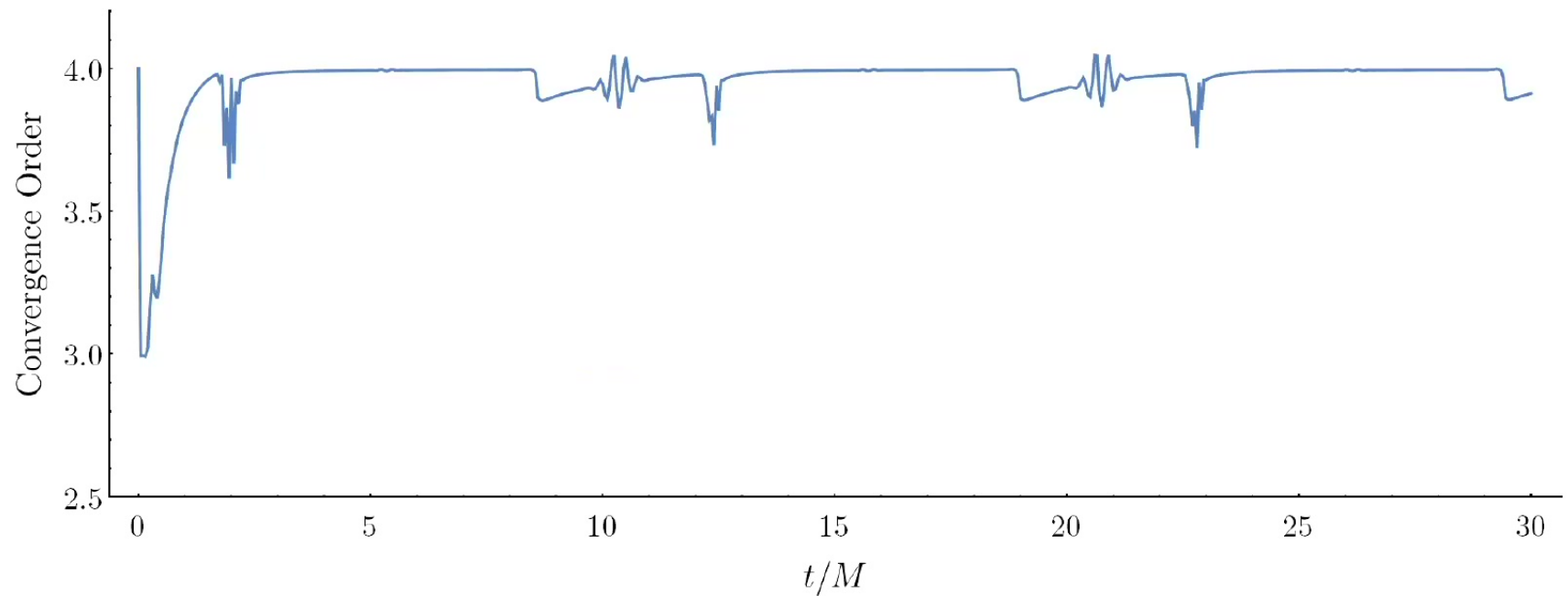
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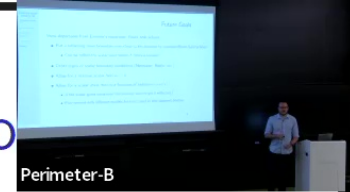


Convergence



4th order convergence based on the norm of the Hamiltonian and Momentum constraints





Show departures from Einstein's equations: Black hole echoes

- Put a reflecting inner boundary very close to the horizon to simulate Black hole echoes
 - Can we reflect the scalar wave before it forms a horizon?
- Other types of scalar boundary conditions (Neumann, Robin, etc.)
- Allow for a massive scalar field $m > 0$
- Allow for a scalar mass that is a function of radius $m \rightarrow m(r)$
 - If the scalar gains mass near the horizon, can we get a reflection?
 - Play around with different models for $m(r)$, tied to the apparent horizon



The Full IBVP (Dirichlet style condition

