Title: Detecting nonclassicality in restricted general probabilistic theories

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Abstract: The formalism of general probabilistic theories provides a universal paradigm that is suitable for describing various physical systems including classical and quantum ones as particular cases. Contrary to the often assumed no-restriction hypothesis, the set of accessible measurements within a given theory can be limited for different reasons, and this raises a question of what restrictions on measurements are operationally relevant. We argue that all operational restrictions must be closed under simulation, where the simulation scheme involves mixing and classical post-processing of measurements. We distinguish three classes of such operational restrictions: restrictions on measurements originating from restrictions on effects; restrictions on measurements that do not restrict the set of effects in any way; and all other restrictions. As a setting to detect nonclassicality in restricted theories we consider generalizations of random access codes, an intriguing class of communication tasks that reveal an operational and quantitative difference between classical and quantum information processing. We formulate a natural generalization of them, called random access tests, which can be used to examine collective properties of collections of measurements. We show that the violation of a classical bound in a random access test is a signature of either measurement incompatibility or super information storability, and that we can use them to detect differences in different restrictions.

# DETECTING NONCLASSICALITY IN RESTRICTED GENERAL PROBABILISTIC THEORIES



PI QF seminar 27.1.2022 LEEVI LEPPÄJÄRVI





# GENERAL PROBABILISTIC THEORIES (GPTs)

# INFORMATION PROCESSING IN OPERATIONAL THEORIES



State space: compact convex subset of a finite-dimensional real vector space



State space: compact convex subset of a finite-dimensional real vector space

$$\mathcal{S} = \{x \in \mathcal{V} \mid x \geq 0, \ u(x) = 1\}$$

## Effect space:

consists of <u>affine</u> functionals  $e: S \rightarrow [0, 1]$  giving probabilities on states

## $\mathcal{E}(\mathcal{S}) = \{ e \in \mathcal{V}^* \, | \, o \le e \le u \}$

 $\mathcal{V}^*$ 

NO-RESTRICTION HYPOTHESIS

2\*

 $\mathfrak{u} - \mathcal{V}^*$ 

u

 $\mathcal{E}(\mathcal{S})$ 

#### Observables

- An observable A with a finite number of outcomes is a mapping  $A: x \mapsto A_x$ from a finite outcome set  $\Omega_A$  to the set of effects  $\mathcal{E}(\mathcal{S})$  such that

 $\sum_{x\in\Omega_A}A_x(s)=1$ 

for all  $s \in S$ .

The set of observables on  ${\mathcal S}$  is denoted by  ${\mathcal O}({\mathcal S})$  .

## Other elements of an operational theory

### Channels

#### Instruments

Composite systems

#### Quantum theory

Let  $\mathcal{H}$  be a d-dimensional Hilbert space

States: 
$$\mathcal{S}(\mathcal{H}) = \{ \rho \in \mathcal{L}_s(\mathcal{H}) \mid \rho \ge 0, \ tr[\rho] = 1 \}$$

 $\texttt{Effects:} \quad \mathcal{E}(\mathcal{S}(\mathcal{H})) \simeq \mathcal{E}(\mathcal{H}) = \{ E \in \mathcal{L}_s(\mathcal{H}) \, | \, 0 \leq E \leq I \}$ 

observables = POVMs:  $A: x \mapsto A(x)$  such that  $\sum_{x \in \Omega_A} A(x) = I$ 



## SIMULATION OF MEASUREMENTS

FILIPPOV, HEINOSAARI AND LEPPÄJÄRVI, SIMULABILITY OF OBSERVABLES IN GENERAL PROBABILISTIC THEORIES, PHYS. REV. A 97, 062102 (2018).

OSZMANIEC, GUERINI, WITTEK AND ACÍN, PHYS. REV. LETT. 119, 190501 (2017) GUERINI, BAVARESCO, TERRA CUNHA AND ACÍN, J. MATH. PHYS. 58, 092102 (2017)







## Simulation of devices



## Directions of applications



## OPERATIONAL RESTRICTIONS

## JOINT WORK WITH SERGEY FILIPPOV, STAN GUDDER AND TEIKO HEINOSAARI

FILIPPOV, GUDDER, HEINOSAARI AND LEPPÄJÄRVI, OPERATIONAL RESTRICTIONS IN GENERAL PROBABILISTIC THEORIES, FOUND. PHYS. 50, 850-876 (2020).

No-restriction hypothesis

# $\mathcal{E}(\mathcal{S}) = \{e: \mathcal{S} \to [0,1] | e \text{ affine} \}$

all mathematically valid functions are taken to be physical effects in the theory

## NO OPERATION AL JUSTIFICATION

JANOTTA AND LAL, GENERALIZED PROBABILISTIC THEORIES WITHOUT THE NO-RESTRICTION HYPOTHESIS, PHYS. REV. A, 87:052131 (2013).

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Also, how about observables?



#### Simulation closed restrictions

Def: An operational restriction of measurements is a subset  $\tilde{\mathcal{O}} \subset \mathcal{O}(S)$  of observables that is simulation closed, i.e.,

# $sim(\tilde{\mathcal{O}}) = \tilde{\mathcal{O}}$

#### Simulation closed restrictions

For a subset of observables  $\tilde{\mathcal{O}} \subseteq \mathcal{O}(S)$  we denote  $\mathcal{E}_{\tilde{\mathcal{O}}} = \{ e \in \mathcal{E}(S) \mid \exists A \in \tilde{\mathcal{O}} : e \in \operatorname{ran}(A) \}$ - the set of available effects

For a subset of effects  $\tilde{\mathcal{E}} \subseteq \mathcal{E}(\mathcal{S})$  we denote  $\mathcal{O}_{\tilde{\mathcal{E}}} = \{A \in \mathcal{O}(\mathcal{S}) | \operatorname{ran}(A) \subset \tilde{\mathcal{E}}\}$ - the induced set of feasible observables

$$*\operatorname{ran}(\mathbf{A}) = \left\{\sum_{\mathbf{x}\in ilde{\mathbf{\Omega}}} \mathbf{A}_{\mathbf{x}} \mid ilde{\mathbf{\Omega}} \subseteq \mathbf{\Omega}_{\mathbf{A}}
ight\}$$

Types of restrictions
$$(R1) \quad \tilde{\mathcal{O}} = \mathcal{O}_{\tilde{\mathcal{E}}} \text{ for some } \tilde{\mathcal{E}} \subset \mathcal{E}(S)$$
restriction purely by  
effect restrictions $(R2) \quad \tilde{\mathcal{E}}_{\tilde{\mathcal{O}}} = \mathcal{E}(S) \text{ but } \tilde{\mathcal{O}} \neq \mathcal{O}(S)$ restriction purely  
on observables $(R3) \quad \mathcal{E}_{\tilde{\mathcal{O}}} \subset \mathcal{E}(S) \text{ and } \tilde{\mathcal{O}} \neq \mathcal{O}_{\tilde{\mathcal{E}}} \text{ for any } \tilde{\mathcal{E}} \subset \mathcal{E}(S)$  $(R3) \quad \mathcal{E}_{\tilde{\mathcal{O}}} \subset \mathcal{E}(S) \text{ and } \tilde{\mathcal{O}} \neq \mathcal{O}_{\tilde{\mathcal{E}}} \text{ for any } \tilde{\mathcal{E}} \subset \mathcal{E}(S)$  $(R3) \quad \mathcal{E}_{\tilde{\mathcal{O}}} \subset \mathcal{E}(S) \text{ and } \tilde{\mathcal{O}} \neq \mathcal{O}_{\tilde{\mathcal{E}}} \text{ for any } \tilde{\mathcal{E}} \subset \mathcal{E}(S)$ 

## (R1): restrictions induced by effect restrictions

For a valid effect restriction  $\tilde{\mathcal{E}} \subseteq \mathcal{E}(\mathcal{S})$  we require that E1)  $\mathbf{u} \in \tilde{\mathcal{E}}$ E2)  $\forall e \in \tilde{\mathcal{E}}, \exists A \in \mathcal{O}_{\tilde{\mathcal{E}}}: e \in \operatorname{ran}(A)$ 

Prop: An effect restriction  $\tilde{\mathcal{E}} \subseteq \mathcal{E}(\mathcal{S})$  satisfying EI) and E2) induces a simulation closed operational restriction  $\mathcal{O}_{\tilde{\mathcal{E}}}$  if and only if  $\tilde{\mathcal{E}}$  is convex.

This includes but is not limited to convex effect subalgebras of  $\mathcal{E}(\mathcal{S})$ 



(R2): restrictions only on observables  

$$(R2) \quad \mathcal{E}_{\tilde{\mathcal{O}}} = \mathcal{E}(\mathcal{S}) \quad bu \pm \quad \tilde{\mathcal{O}} \neq \mathcal{O}(\mathcal{S})$$
Effectively dichotomic observables  

$$\mathcal{O}_{2-eff} = sim(\{A \in \mathcal{O}(\mathcal{S}) \mid \#\Omega_A = 2\})$$
Prop: If  $\tilde{\mathcal{O}} \subset \mathcal{O}(\mathcal{S})$  is an operational restriction of type (R2), then  

$$\mathcal{O}_{2-eff} \subset \tilde{\mathcal{O}}$$

## (R3): restrictions on both effects and observables (not R1 nor R2)

Noisy observables (random noise)

 $\tilde{\mathcal{O}}_{t} = \{tA + (1 - t)pu | A \in \mathcal{O}(\mathcal{S}), p \in \mathcal{P}(\Omega_{A})\}$ 

Available effects

 $\mathcal{E}_{\tilde{\mathcal{O}}_{+}} = \{ \mathbf{t}e + (1-\mathbf{t})\mathbf{p}e \,|\, e \in \mathcal{E}(\mathcal{S}), \mathbf{p} \in [0,1] \}$ 



## (R3): restrictions on both effects and observables (not R1 nor R2)

Noisy observables (random noise)

 $\tilde{\mathcal{O}}_{t} = \{tA + (1 - t)pu | A \in \mathcal{O}(\mathcal{S}), p \in \mathcal{P}(\Omega_{A})\}$ 

Available effects

 $\mathcal{E}_{\tilde{\mathcal{O}}_{+}} = \{ te + (1-t)pe \, | \, e \in \mathcal{E}(\mathcal{S}), p \in [0,1] \}$ 

 $ilde{\mathcal{O}}_{ ext{t}}$  is not induced by  $\mathcal{E}_{ ilde{\mathcal{O}}_{ ext{t}}}$ 

 $\widehat{\mathcal{E}}_{+}$ 

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# DETECTING NONCLASSICALITY WITH RANDOM ACCESS TESTS

JOINT WORK WITH TEIKO HEINOSAARI

HEINOSAARI AND LEPPÄJÄRVI, RANDOM ACCESS TEST AS AN IDENTIFIER OF NONCLASSICALITY, ARXIV:2112.03781 [QUANT-PH] (2021).



Average success probability  

$$\bar{P}^{(n,d)}\left(M^{(1)},\ldots,M^{(n)};\{s_{\vec{x}}\}_{\vec{x}}\right) = \frac{1}{nd^n}\sum_{\vec{x}}\left[M^{(1)}_{x_1}+\cdots+M^{(n)}_{x_n}\right](s_{\vec{x}})$$
optimal:  

$$\bar{P}_q^{(2,d)} = \frac{1}{2}\left(1+\frac{1}{\sqrt{d}}\right) > \frac{1}{2}\left(1+\frac{1}{d}\right) = \bar{P}_c^{(2,d)}$$

$$\vec{x} \in \{0, \dots, d-1\}^n \xrightarrow{P}_{Alice} \overset{s_{\vec{x}}}{\underset{d_{op}}{\Rightarrow}} \xrightarrow{f}_{d_{op}} \underbrace{\mathcal{M}^{(j)}}_{Bob} \xrightarrow{g}_{y} \xrightarrow{f}_{y} \xrightarrow{f}_{$$

 $j \in \{1, \ldots, n\}$ 

Random access codes



Average success probability (  $\#\Omega_j = m_j$  )

$$\bar{P}\left(M^{(1)},\ldots,M^{(n)};\{s_{\vec{x}}\}_{\vec{x}}\right) = \frac{1}{nm_{1}\cdots m_{n}}\sum_{\vec{x}}\left[M^{(1)}_{x_{1}}+\cdots+M^{(n)}_{x_{n}}\right](s_{\vec{x}})$$



Maximum average success probability for fixed observables

$$\bar{P}\left(M^{(1)},\ldots,M^{(n)}\right) = \frac{1}{nm_1\cdots m_n}\sum_{\vec{x}} \|M_{x_1}^{(1)}+\cdots+M_{x_n}^{(n)}\|$$

#### Information storability

Decoding power of an observable

$$\lambda_{\max}(A) = \sum_{x \in \Omega_A} ||A_x|| = \sum_{x \in \Omega_A} \sup_{s \in S} A_x(s)$$

 $rac{\lambda_{m\,ax}(A)}{\#\Omega_A}$  is the maximal probability of decoding  $\#\Omega_A$  messages by using A

Information storability\* of a subset  $\tilde{\mathcal{O}} \subseteq \mathcal{O}(\mathcal{S})$ 

$$\lambda_{\max}(\tilde{\mathcal{O}}) = \sup_{A \in \tilde{\mathcal{O}}} \lambda_{\max}(A)$$

\*MATSUMOTO AND KIMURA, INFORMATION STORING YIELDS A POINT-ASYMMETRY OF STATE SPACE IN GENERAL PROBABILISTIC THEORIES, ARXIV:1802.01162 [QUANT-PH], (2018)

## Connecting RATs and incompatibility of observables

Def: Observables  $M^{(1)}, \ldots, M^{(n)}$  are  $\tilde{\mathcal{O}}$  -compatible if they are compatible, i.e. jointly measurable, and their joint measurement belongs to  $\tilde{\mathcal{O}} \subseteq \mathcal{O}(S)$ .

Prop.: If two observables  $M^{(1)}$  and  $M^{(2)}$  with  $m_1$  and  $m_2$  outcomes respectively are  $\tilde{\mathcal{O}}$  -compatible, then  $\bar{P}\left(M^{(1)}, M^{(2)}\right) \leq \frac{1}{2}\left(1 + \frac{\lambda_{\max}(\tilde{\mathcal{O}})}{m_1m_2}\right)$ 



then  $M^{(1)}$  and  $M^{(2)}$  are  $\tilde{\mathcal{O}}$  -incompatible

Note: the observables can still be compatible in the unrestricted theory

If  $\lambda_{max}(\tilde{\mathcal{O}}) = m_1 = m_2 = d$ , then RHS equals  $\bar{P}_c^{(2,d)}!$ 



$$\overline{Prop}: If \qquad \overline{P}\left(M^{(1)}, M^{(2)}\right) > \frac{1}{2}\left(1 + \frac{\lambda_{\max}(\tilde{\mathcal{O}})}{m_1 m_2}\right)$$

then  $M^{(1)}$  and  $M^{(2)}$  are  $\tilde{\mathcal{O}}$  -incompatible.

Note: the observables can still be compatible in the unrestricted theory.

If 
$$\lambda_{max}(\tilde{\mathcal{O}}) = m_1 = m_2 = d$$
, then RHS equals  $\bar{P}_c^{(2,d)}$ !

-> OPERATIONAL CONNECTION TO NONCLASSICALITY

Let  $\tilde{\mathcal{O}} \subseteq \mathcal{O}(\mathcal{S})$  be a restriction with an operational dimension d. Let  $M^{(1)}, M^{(2)} \in \tilde{\mathcal{O}}$  be two observables with  $m_1 = m_2 = d$  outcomes.

If 
$$\overline{P}(M^{(1)}, M^{(2)}) > \overline{P}_{c}^{(2,d)}$$
 then  
super information storability holds, i.e.,  
 $\lambda_{max}(\tilde{O}) > d$ ,  
and/or  $M^{(1)}$  and  $M^{(2)}$  are  $\tilde{O}$ -incompatible.







![](_page_41_Picture_0.jpeg)