Title: Deformations of General Relativity, Geometrodynamics and reality conditions

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Series: Quantum Gravity

Date: March 11, 2021 - 2:30 PM

URL: http://pirsa.org/21030029

Abstract: A remarkable aspect of 4-dimensional complexified General Relativity (GR) is that it can be non-trivially deformed: there exists an infinite-parameter set of modifications with the same degree of freedom count. It is trivial to impose reality conditions that lead to real theories with Euclidean or split signature, but the situation is more complicated and not yet fully understood in the Lorentzian case, which is the subject of this talk. I will first show that the choice of potentially consistent reality conditions is essentially unique and boils down to the reality of the underlying 3-metric at the canonical level, as in the case of GR. For simplicity, I will focus on a subset of modified theories that correspond to a natural extension of Ashtekar's Hamiltonian constraint, namely, a linear combination of EEE, EEB, EBB and BBB. Interestingly, the evolution equations for the 3-metric and its first time-derivative take the same form as in GR, but with an effective stress tensor source which cannot be expressed in terms of these two fields. Modified theories therefore appear as essentially "non-metric" in that they do not admit a closed geometrodynamics form. In particular, this obstructs the conservation of the reality conditions, because the effective source remains complex. Alternatively, if we insist on reality, we obtain extra reality conditions which then leave no room for degrees of freedom. I will finally argue that this should be a generic feature of the Lorenzian modified theories, in stark contrast to their Euclidean and split-signature counterparts.

Deformations of GR, geometrodynamics and reality conditions

[2012.05706, accepted in CQG]

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11.03.2021, Perimeter Institute QG seminar

- Complexified GR
- Reality conditions
- Deformations (Lorentzian signature problem)
- A natural subclass
- Geometrodynamics
- Obstruction to reality
- Take away

Plebanski SO(3, \mathbb{C}) action

Plebanski (1977)

$$egin{aligned} S &= \int \left[B_i \wedge F^i - rac{1}{2} \, \psi^{ij} B_i \wedge B_j - \phi \left(\lambda + \mu_{ij} \psi^{ij}
ight)
ight] \ F^i &:= \mathrm{d} \mathcal{A}^i + rac{1}{2} \, \mu^{ij} arepsilon_{ikl} \mathcal{A}^k \wedge \mathcal{A}^l \end{aligned}$$

2

if <u>real</u> fields

$$B_i = \mu_{ij} e^0 \wedge e^j + rac{1}{2} \varepsilon_{ijk} e^j \wedge e^k , \qquad \phi = e^0 \wedge e^1 \wedge e^2 \wedge e^3$$

 \Rightarrow real Palatini-Holst action (real GR)

$$- \mu_{ij} = \delta_{ij} \implies SO(3) \simeq self-dual SO(4)$$

-
$$\mu_{ij} = \eta_{ij}$$
 \Rightarrow SO(1,2) \simeq self-dual SO(2,2)

but $\mathfrak{so}(1,3) \simeq \mathfrak{sl}(2,\mathbb{C}) \quad \Rightarrow \quad \text{Lorentzian self-dual is complex}$

 \Rightarrow complex fields + <u>non-linear</u> reality conditions

$$\operatorname{Re}\left[\delta^{ij}B_i \wedge B_j\right] = 0 \qquad B_i \wedge \bar{B}_j = 0$$

underlying real metric

[Urbantke (1984)]

 $g_{\mu
u} \propto \varepsilon_{ijk} \varepsilon^{lphaeta\gamma\delta} B^{i}_{\mulpha} B^{j}_{
ueta} B^{k}_{\gamma\delta} \qquad \sqrt{-g} = rac{\mathrm{i}}{4} \,\delta^{ij} \varepsilon^{\mu
u
ho\sigma} B_{i\mu
u} B_{j
ho\sigma}$

$$B_i = \mathrm{i} \delta_{ij} e^{0} \wedge e^{j} + rac{1}{2} \, arepsilon_{ijk} e^{j} \wedge e^{k} \,, \qquad \phi = e^{0} \wedge e^{1} \wedge e^{2} \wedge e^{3}$$

 \Rightarrow Lorentzian Palatini-Holst action

 \Rightarrow <u>real Lorentzian GR</u>

Back to the complex theory: deformation

$$egin{aligned} S &= & \int \left[B_i \wedge F^i - rac{1}{2} \, \psi^{ij} B_i \wedge B_j - \phi \left(\lambda + \mu_{ij} \psi^{ij}
ight)
ight] \ & o & \int \left[B_i \wedge F^i - rac{1}{2} \, \psi^{ij} B_i \wedge B_j - \phi \mathcal{H}(\psi)
ight] \end{aligned}$$

[Capovilla ++ (1989), Bengtsson (1991), Krasnov (2006)]

- same degree of freedom count!
- dynamical internal metric

$$rac{1}{2} \, B_i \wedge B_j = - \phi \mathcal{H}_{ij} \qquad \mathcal{H}_{ij} := rac{\partial \mathcal{H}}{\partial \psi^{ij}} \qquad \mathcal{H}^{\mathrm{GR}}_{ij} := \mu_{ij}$$

- pure-connection form

[Krasnov (2011)]

$$S = \int f\left(F^i \wedge F^j\right) \qquad S_{\mathrm{GR}} = \int \left[\mathrm{Tr}\,\sqrt{F^i \wedge F^j}\right]^2$$

Reality conditions for <u>deformed theories</u>?

GR: Re
$$\left[\delta^{ij}B_i \wedge B_j\right] = 0$$
 $B_i \wedge \bar{B}_j = 0$

<u>Scalar constraint</u>: generalization $\operatorname{Re} [f (B_i \wedge B_j)] = 0$ amounts to changing $\mathcal{H}(\psi) \Rightarrow$ no new direction in theory space

<u>Tensor constraint:</u> too rigid

reality of conformal class of metrics $\overline{[g_{\mu
u}]}$

 $g_{\mu
u}\proptoarepsilon_{ijk}arepsilon^{lphaeta\gamma\delta}B^i_{\mulpha}B^j_{
ueta}B^j_{\gamma\delta}B^k_{\gamma\delta} \qquad rac{1}{2}$

$$\varepsilon \varepsilon^{\mu
u
ho\sigma}B_{i
ho\sigma}\equiv \mathrm{i}\sqrt{-g}g^{\mu
ho}g^{
u\sigma}B_{i
ho\sigma}$$

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ho\sigma}B_{i
ho\sigma}\equiv{
m i}\sqrt{-g}g^{\mu
ho}g^{
u\sigma}B_{i
ho\sigma}$$

 \Rightarrow unique reality constraints (up to redef. of \mathcal{H})

$$\Rightarrow \quad \operatorname{Re}\left[\mathcal{H}^{ij}(\psi) B_i \wedge B_j\right] = 0 \qquad \mathcal{H}_{ij} := \frac{\partial \mathcal{H}}{\partial \psi^{ij}} \qquad \mathcal{H}_{ik} \mathcal{H}^{kj} \equiv \delta_i^j$$

we implement at the action level: $S = S_h + S_c$

$$S_{h} = \int \left[\frac{1}{i} \left(B_{i} \wedge F^{i} - \frac{1}{2} \psi^{ij} B_{i} \wedge B_{j} \right) - \phi \mathcal{H}(\psi) \right]$$
$$S_{c} = \int \left[\chi \operatorname{Re} \left(\mathcal{H}^{ij} B_{i} \wedge B_{j} \right) + \chi^{ij} B_{i} \wedge \overline{B}_{j} \right]$$

Important action structure: holomorphic + reality constraints

- \Rightarrow equations of conjugate fields $\bar{B}_i \quad \chi, \chi^{ij} = 0$
- \Rightarrow S_c does not affect holomorphic equations of motion

$$egin{aligned} \mathcal{S} = \int \left[rac{1}{\mathrm{i}}\left(B_i \wedge F^i - rac{1}{2}\,\psi^{ij}B_i \wedge B_j
ight) - \phi\mathcal{H}(oldsymbol{\psi}) + \chi^{ij}B_{oldsymbol{\psi}} \wedge ar{B}_j
ight] & \phi \in \mathbb{R} \end{aligned}$$

compatibility? \Rightarrow canonical formulation : $x^{\mu} \rightarrow \{t, x^{\alpha}\}$

$$E_i^{\alpha} := \psi_{ij} B^{j\alpha} \qquad B_i^{\alpha} := \frac{1}{2} \varepsilon^{\alpha\beta\gamma} F_{\beta\gamma}^i \qquad \psi^{ij} \equiv E_{\alpha}^i B^{j\alpha}$$

canonical action

$$S = \int d^4x \left[\frac{1}{i} \left(E_i^{\alpha} \dot{A}_{\alpha}^i - \theta^i \mathcal{G}_i - N^{\alpha} \mathcal{D}_{\alpha} \right) - N \mathcal{H}(\psi) - \xi_{\alpha\beta} \operatorname{Im}[\tilde{q}^{\alpha\beta}] \right]$$

with $\mathit{N}, \mathit{N}^lpha \in \mathbb{R}$ and

$$\widetilde{q}^{lphaeta} \coloneqq \mathcal{H}^{ij}(\psi) \, E^{lpha}_i E^{eta}_i$$

3-metric density from Urbantke 4-metric

 $\mathcal{H}, \mathcal{D}_{\alpha}, \mathcal{G}_{i}$ first-class algebra (3-metric again $\tilde{q}^{\alpha\beta}$)

simple subset of theories

 $\mathcal{H} = \lambda_0 \left(E, E, \overline{E} \right) + \lambda_1 \left(E, \overline{E}, B \right) + \lambda_2 \left(E, \overline{B}, \overline{B} \right) + \lambda_3 \left(B, \overline{B}, \overline{B} \right)$

 $(X, Y, Z) := \frac{\varepsilon_{\alpha\beta\gamma}\varepsilon^{ijk}X_i^{\alpha}Y_j^{\beta}Z_k^{\gamma}}{n_X!n_Y!n_Z!}$

 $\Rightarrow \quad \tilde{q}^{\alpha\beta} = \lambda_E E_i^{\alpha} E_i^{\beta} + \lambda_S E_i^{\alpha} B^{i\beta} + \lambda_B B^{i\alpha} B^{i\beta}$ $\lambda_E := \lambda_1^2 - \lambda_0 \lambda_2 \qquad \lambda_S := \lambda_1 \lambda_2 - \lambda_0 \lambda_3 \qquad \lambda_B := \lambda_2^2 - \lambda_1 \lambda_3$

- natural extension of Ashtekar formulation [Ashtekar (1986)]

- arise from 7D 3-form theories [Krasnov ++ (2017-18)]
- redundancy: canonical transformation $E_i^{\alpha} \rightarrow E_i^{\alpha} + cB_i^{\alpha}$ invariant coupling: $\Delta := \lambda_S^2 - 4\lambda_E\lambda_B$

reality conditions?
$$q_{\alpha\beta} \in \mathbb{R} \implies K_{\alpha\beta} \in \mathbb{R}$$

 $(\partial_t - \mathcal{L}_N) K_{\alpha\beta} = \begin{bmatrix} 2K_{\alpha\gamma}K_{\beta}^{\gamma} - KK_{\alpha\beta} - R_{\alpha\beta} + \nabla_{\alpha}\nabla_{\beta} + q_{\alpha\beta}V + \Delta S_{\alpha\gamma\delta}S_{\beta}^{\gamma\delta} \end{bmatrix} N$
in general $V, S_{\alpha\beta\gamma} \in \mathbb{C} \implies$ not conserved
imposing $T_{\alpha\beta} \in \mathbb{R} \implies$ zero degrees of freedom
exception: if $\Delta = 0 \implies V = \text{constant}$
 \Rightarrow closed GR geometrodynamics, and also GR constraints
 \Rightarrow conserved reality constraints (if $V \in \mathbb{R}$)

what theories have $\Delta = 0$?

 $\Delta := \lambda_S^2 - 4\lambda_E\lambda_B$ is discriminant of 3-metric

$$\tilde{q}^{\alpha\beta} = \lambda_E E^{\alpha}_i E^{\beta}_i + \lambda_S E^{\alpha}_i B^{i\beta} + \lambda_B B^{i\alpha} B^{i\beta}$$

$$\Rightarrow \quad \Delta = 0$$
 are exact square 3-metrics
 $ilde{q}^{lphaeta} = E^{lpha}_i E^{eta}_i \quad \Rightarrow \qquad \mathcal{H} = \lambda + \delta_{ij} \psi^{ij} \quad \Rightarrow \qquad \mathsf{GR}$

or

$$\tilde{q}^{lphaeta} = B^{lpha}_i B^{eta}_i \quad \Rightarrow \quad \mathcal{H} = \lambda + \delta^{ij} \psi_{ij} \quad \Rightarrow \quad \text{Self-Dual GR}$$

$$S_{\rm SDG} = \int \psi_{ij} F^i \wedge F^j + \text{reality conditions}$$

[Krasnov (2017)]

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or

$$\tilde{q}^{lphaeta} = B^{lpha}_i B^{eta}_i \quad \Rightarrow \quad \mathcal{H} = \lambda + \delta^{ij} \psi_{ij} \quad \Rightarrow \quad \text{Self-Dual GR}$$

 $S_{\rm SDG} = \int \psi_{ij} F^i \wedge F^j$ + reality conditions [Krasnov (2017)]

(A)dS connection + linear chiral field ψ

unbounded energy

what about the generic theory?

obstructing term

$$S_{\gamma}^{\ lphaeta} = -rac{1}{2\Delta}\,arepsilon_{\gamma\delta\epsilon}\,\{q^{lpha\delta},q^{eta\epsilon}\}$$

generic 3-metric

$$\widetilde{q}^{lphaeta} = f_E(\psi) E^{lpha}_i E^{eta}_i + f_S(\psi) E^{lpha}_i B^{ieta} + f_B(\psi) B^{ilpha} B^{ieta}$$

$\overline{\{q,q\}} \neq 0$

٩.

 \Rightarrow 3-metric cannot be a phase space coordinate

- \Rightarrow no canonical 3-metric formulation
- \Rightarrow no closed geometrodynamics
- \Rightarrow no conserved reality conditions

Take away

- complexified GR admits an infinite-parameter family of deformations
- trivial real versions in Euclidean and split signature
- Lorentzian signature requires non-linear reality conditions
- generically not compatible with dynamics
 - \Rightarrow no deformed Lorentzian theories \otimes
- better understanding of geometrodynamics for Euclidean/split

