

Title: Emergent classicality for large channels and states

Speakers: Daniel Ranard

Series: Perimeter Institute Quantum Discussions

Date: November 18, 2020 - 4:00 PM

URL: <http://pirsa.org/20110059>

Abstract: In a quantum measurement process, classical information about the measured system spreads through the environment. In contrast, quantum information about the system becomes inaccessible to local observers. In this talk, I will present a result about quantum channels indicating that an aspect of this phenomenon is completely general. We show that for any evolution of the system and environment, for everywhere in the environment excluding an $O(1)$ -sized region we call the "quantum Markov blanket," any locally accessible information about the system must be approximately classical, i.e. obtainable from some fixed measurement. The result strengthens the earlier result of arXiv:1310.8640 in which the excluded region was allowed to grow with total environment size. I will also discuss applications to many-body physics.

Emergent classicality and a bound on the spread of quantum information

Speaker: Daniel Ranard

Joint work with Xiao-Liang Qi

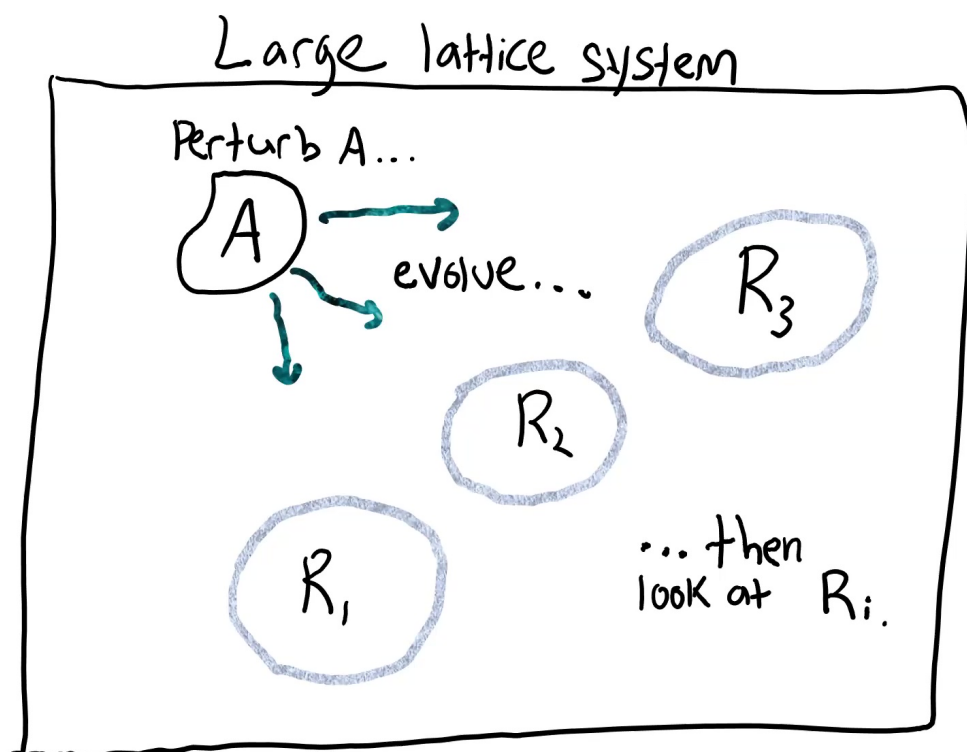
arXiv: 2001.01507

Builds on: Brandão, Piani, Horodecki (2015, *Nat. comm.* 6:7908)

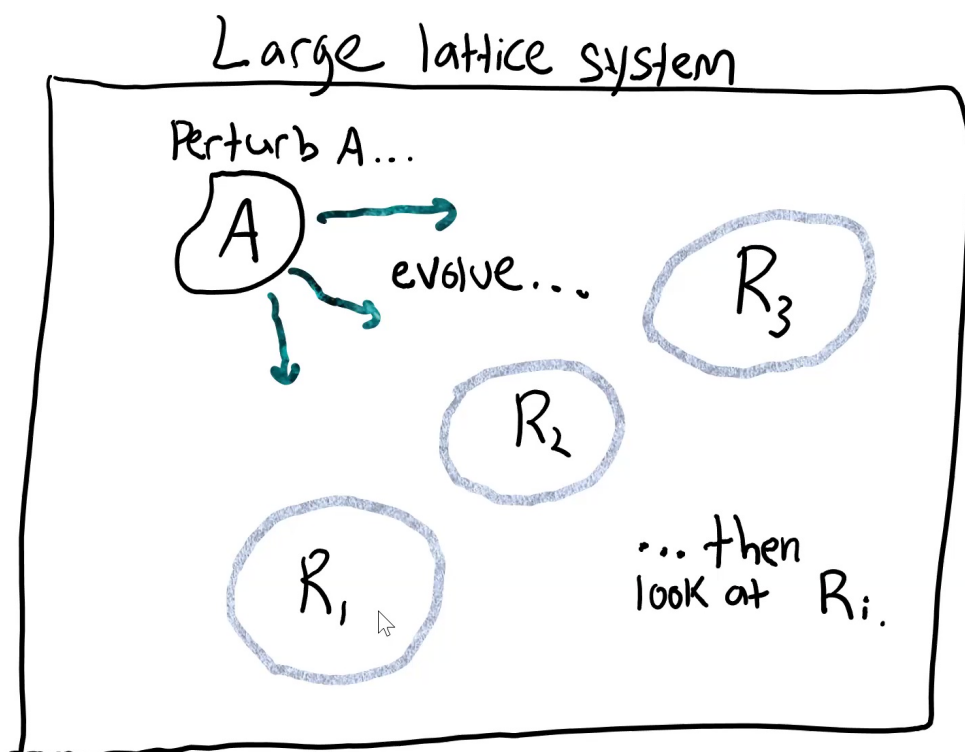
Outline

- Examples of information spreading in different systems
- General constraint on spreading in *all* systems
- Precise theorem statement
- Implications for many-body systems

How can information spread during evolution?



How can information spread during evolution?

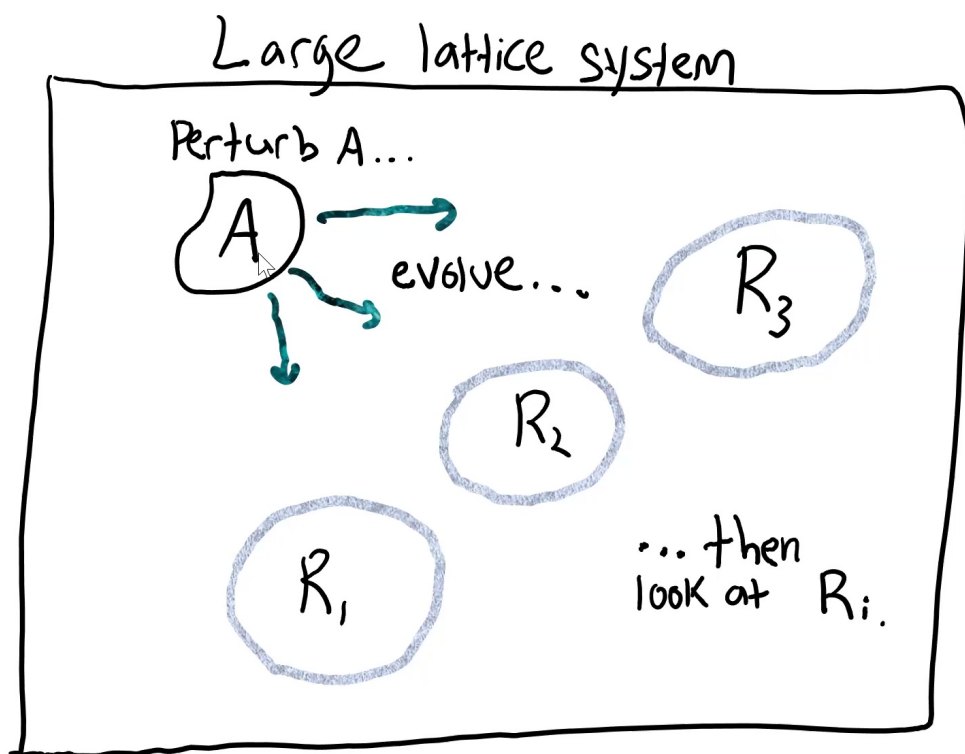


What can we learn about input perturbation at A , just looking at some R_i ?

Example situations:

- Global thermalization

How can information spread during evolution?

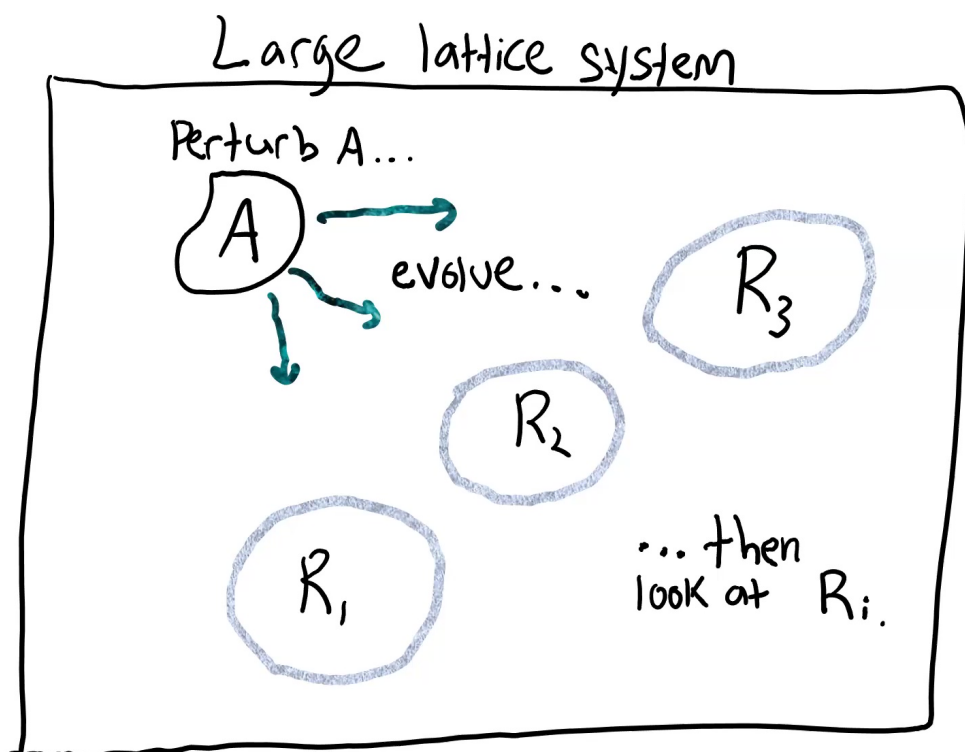


What can we learn about input perturbation at A , just looking at some R_i ?

Example situations:

- Global thermalization
- Chaotic tub of water
- Direct transport $A \rightarrow R_1$

How can information spread during evolution?

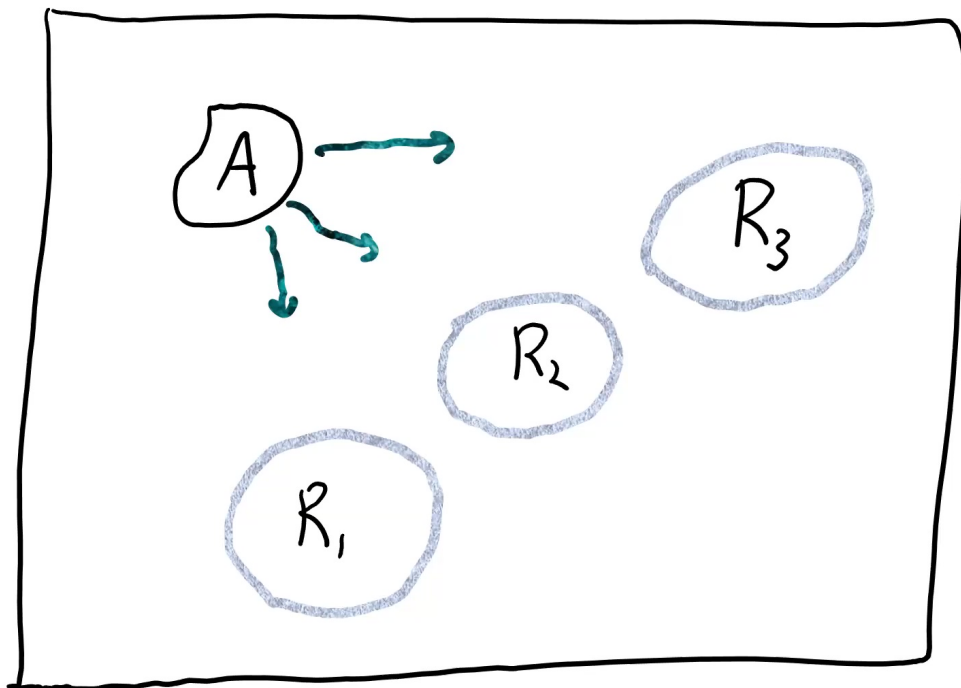


What can we learn about input perturbation at A , just looking at some R_i ?

Example situations:

- Global thermalization
- Chaotic tub of water
- Direct transport $A \rightarrow R_1$ and ~~$A \rightarrow R_2$~~

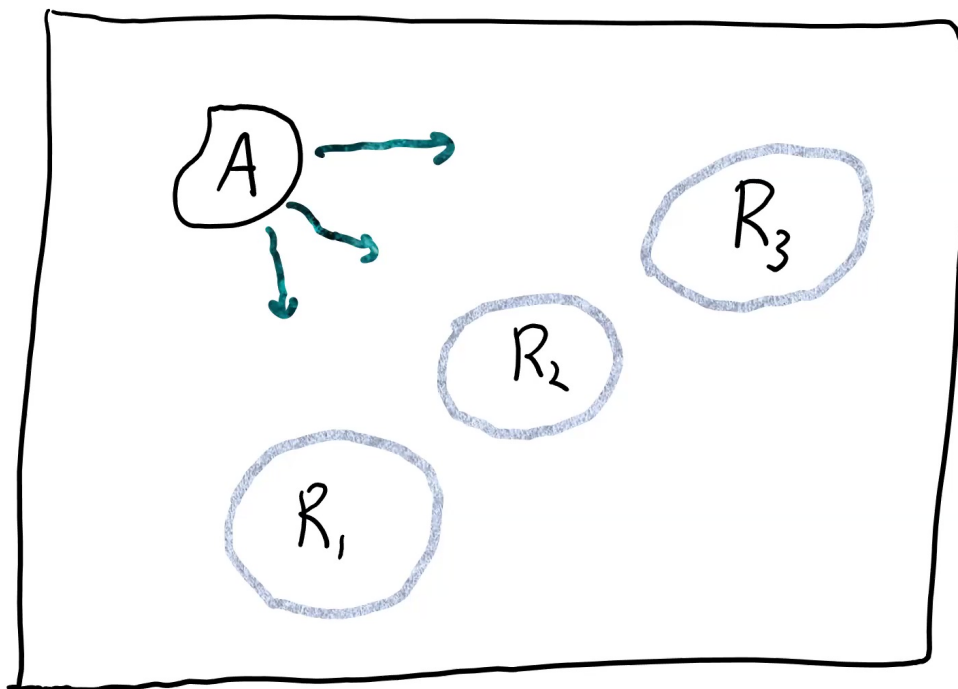
Decoherence example



A in superposition

$$|\psi_0\rangle = (c_0|0\rangle_A + c_1|1\rangle_A)|0\rangle_{R_1}|0\rangle_{R_2}|0\rangle_{R_3}$$

Decoherence example



A in superposition

$$|\psi_0\rangle = (c_0|0\rangle_A + c_1|1\rangle_A)|0\rangle_{R_1}|0\rangle_{R_2}|0\rangle_{R_3}$$

evolve

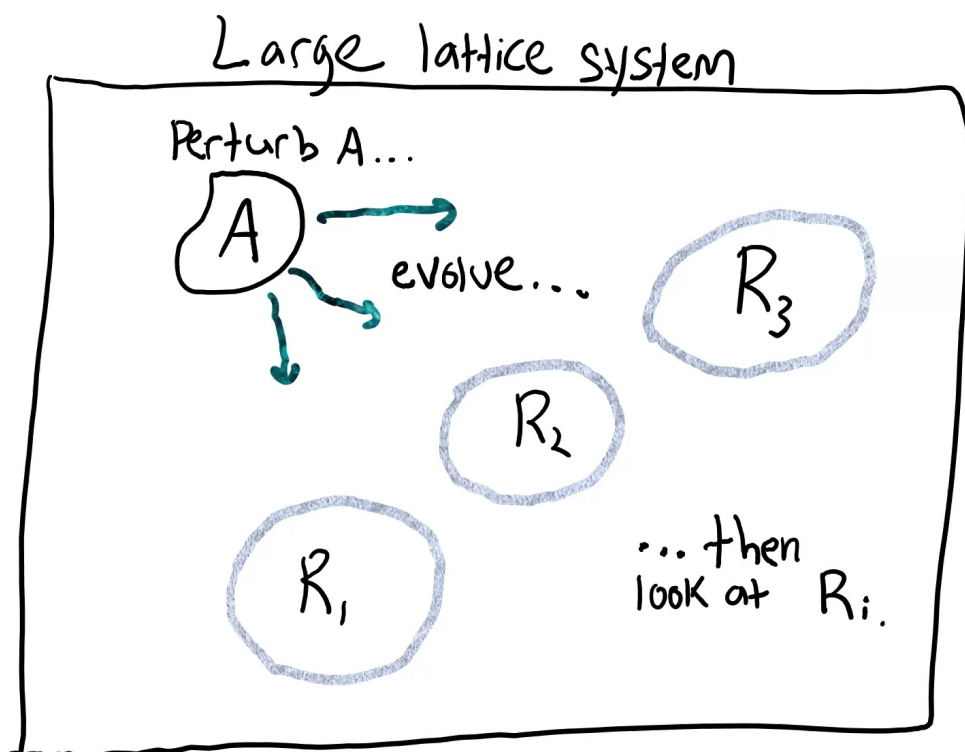
$$|\psi_t\rangle = c_0|0\rangle_A|0\rangle_{R_1}|0\rangle_{R_2}|0\rangle_{R_3} + c_1|1\rangle_A|1\rangle_{R_1}|1\rangle_{R_2}|1\rangle_{R_3}$$

Each R_i records state of A in 0,1 basis

$$\rho_{R_i} = |c_0|^2|0\rangle\langle 0| + |c_1|^2|1\rangle\langle 1|$$

Phase info. about original state on A is lost when just looking at A or R_i .

How can information spread during evolution?



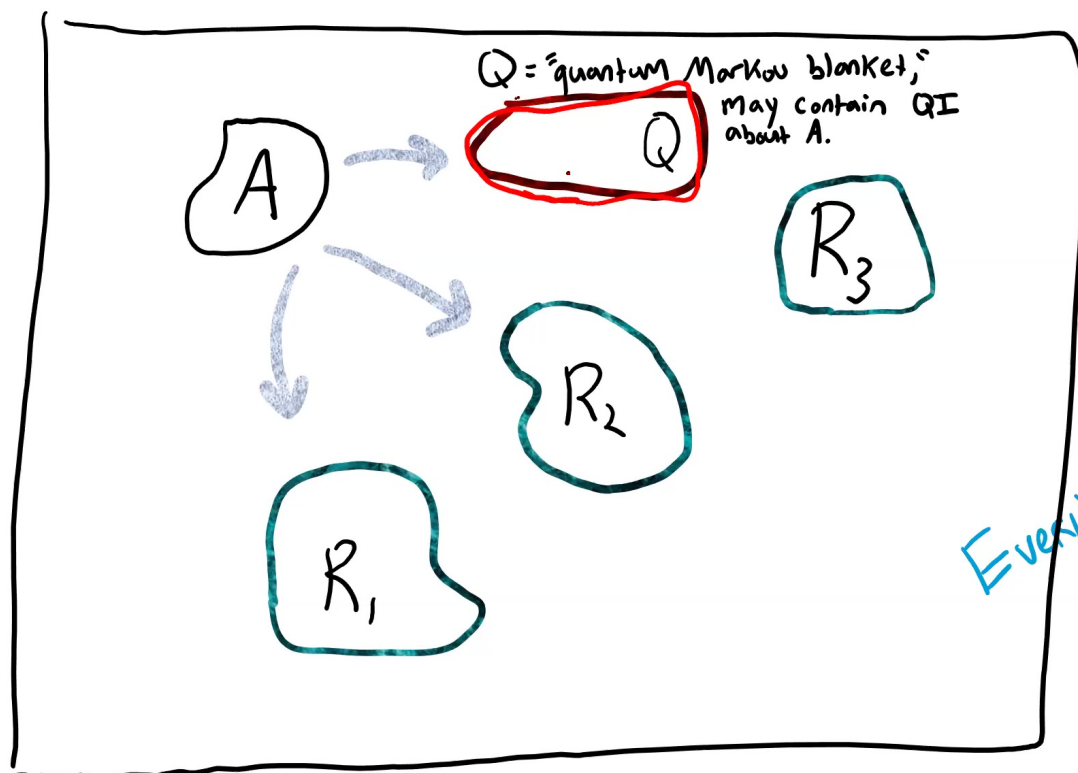
What can we learn about input perturbation at A , just looking at some R_i ?

Example situations:

- Global thermalization
- Chaotic tub of water
- Direct transport $A \rightarrow R_1$ and ~~$A \rightarrow R_2$~~
- "Measurement" of A by its environment, results passed to each R_i

Decoherence

How can information spread during evolution?

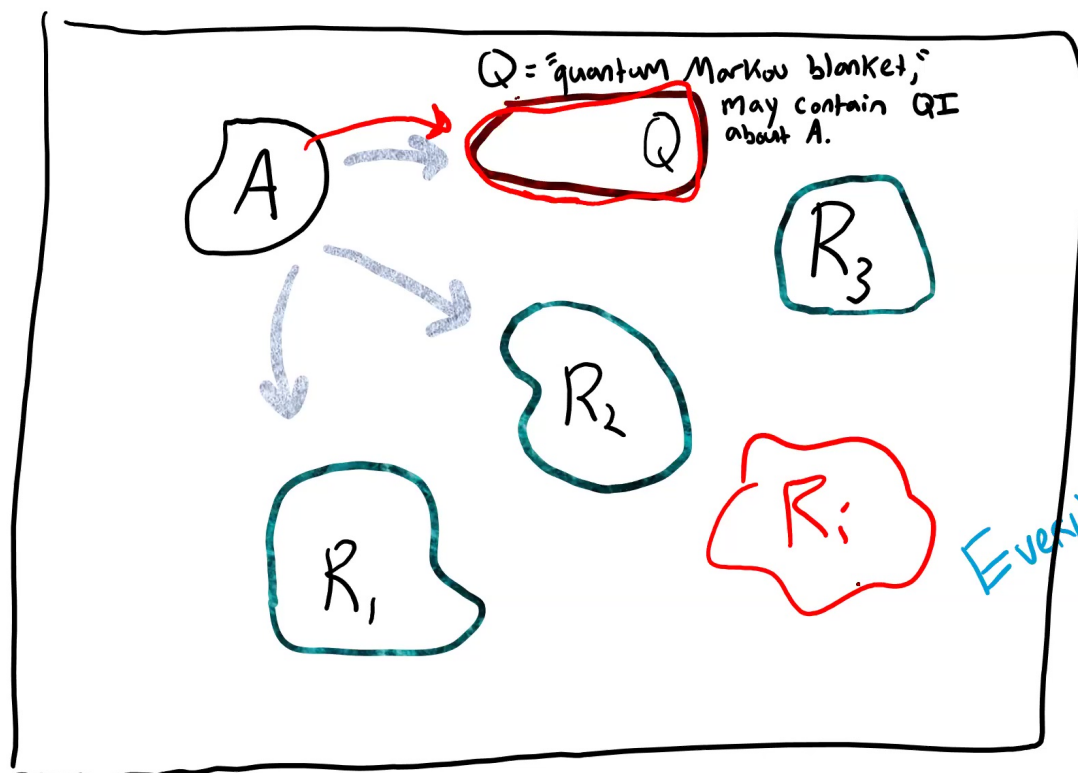


What can we learn about input perturbation at A , just looking at some R_i ?

Example situations:

- Global thermalization
- Chaotic tub of water
- Direct transport $A \rightarrow R_1$ and ~~$A \rightarrow R_2$~~
- "Measurement" of A by its environment, results passed to each R_i

How can information spread during evolution?



What can we learn about input perturbation at A , just looking at some R_i ?

Example situations:

- Global thermalization
- Chaotic tub of water

- Direct transport $A \rightarrow R_1$ and ~~$A \rightarrow R_2$~~
- "Measurement" of A by its environment, results passed to each R_i

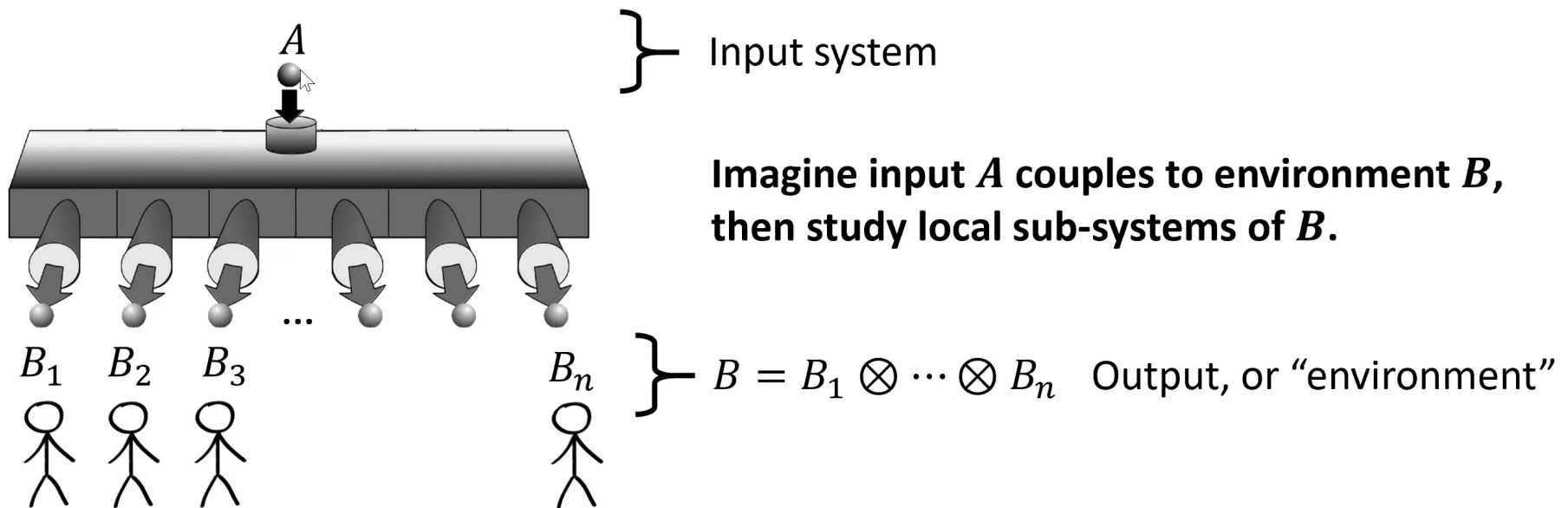
Earlier work

Inspired by very similar ideas in the excellent paper:

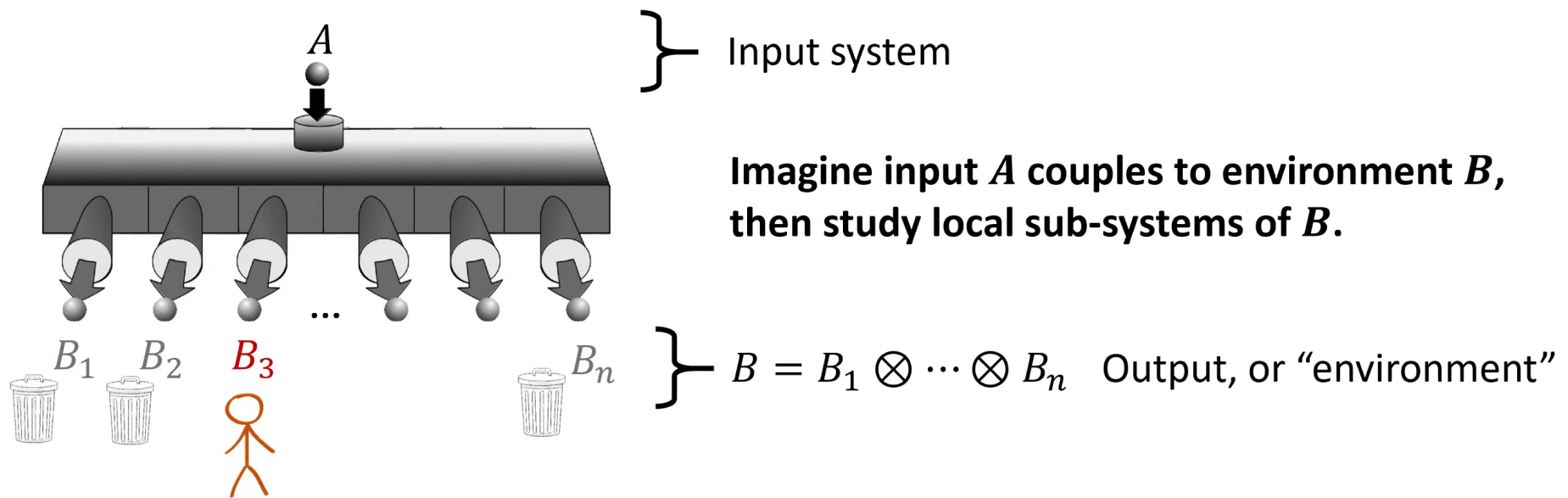
Generic emergence of classical features in quantum Darwinism,
Brandão, Piani, Horodecki.

The present work proves a stronger statement, with a simple + constructive argument.

Studying local sub-systems of the environment

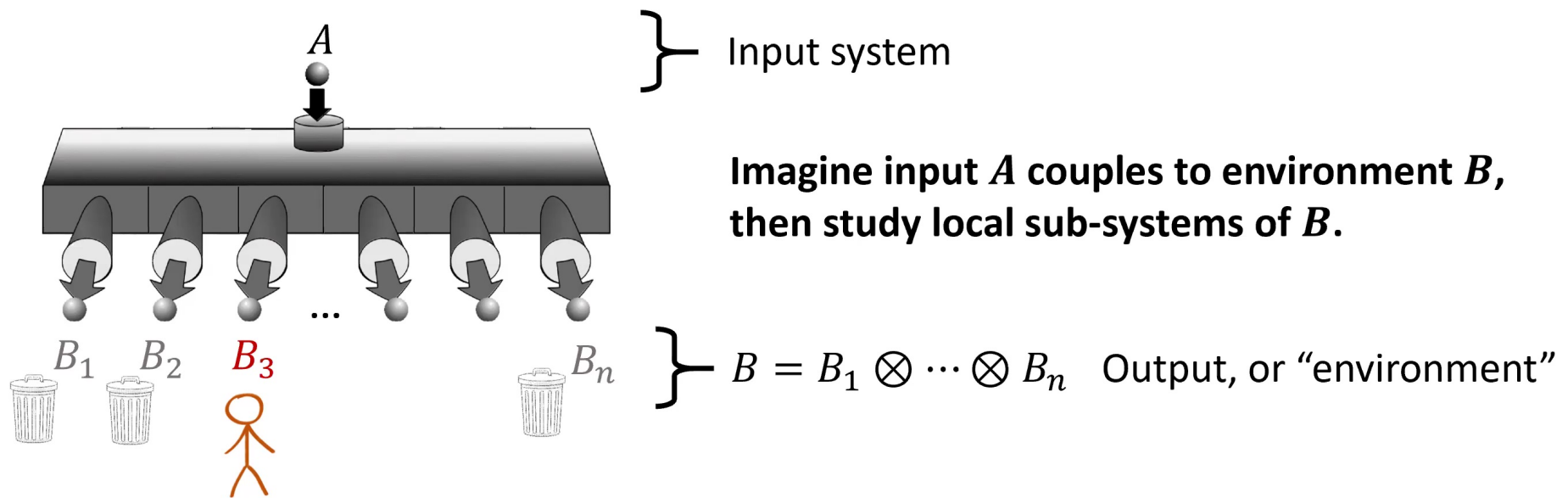


Studying local sub-systems of the environment



What can **Bob** learn about A ? For most B_i , only classical information! (Our result)

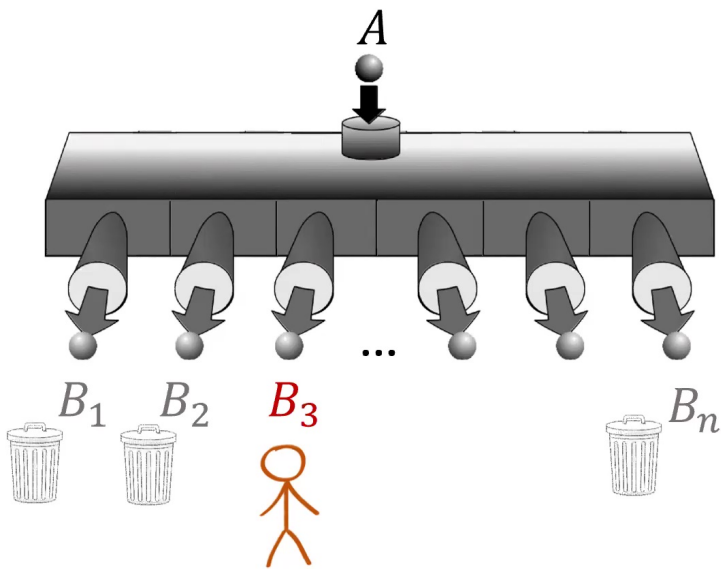
Studying local sub-systems of the environment



What can **Bob** learn about A ? For most B_i , only classical information! (Our result)

Almost everywhere in the environment B , the locally accessible information about A looks *classical*, i.e. can be obtained from a measurement of A in some fixed basis.

Studying local sub-systems of the environment



ρ_A

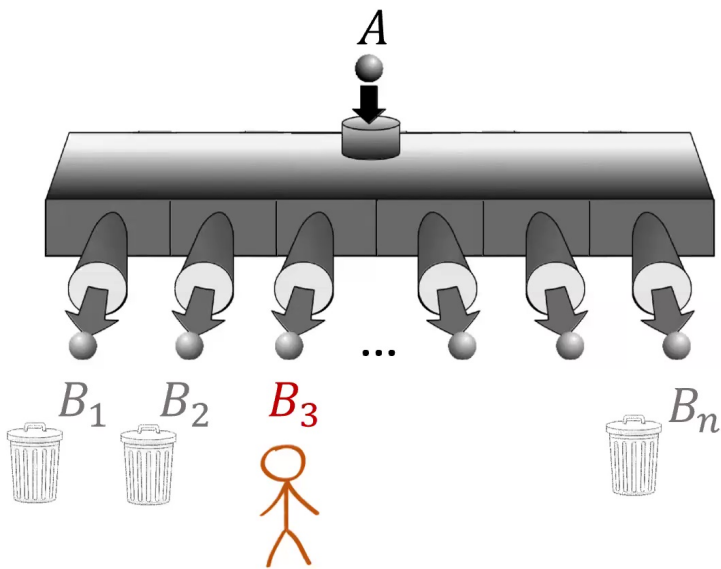
Model evolution as coupling to environment, evolving, then tracing out all except B_i

$$\rho_{B_i} = \text{Tr}_{A \bar{B}_i} (U_{AB} (\rho_A \otimes \tau_B) U_{AB}^+)$$

Environment starts in state τ_B

Then both systems evolve by unitary U_{AB}

Studying local sub-systems of the environment



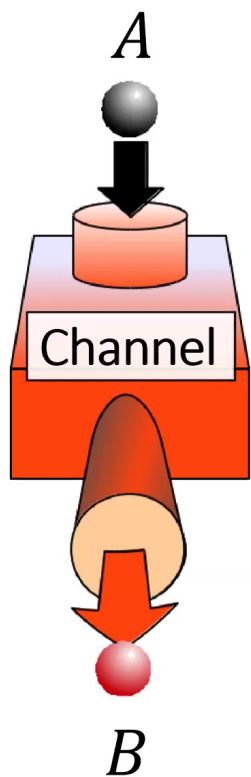
ρ_A

Model evolution as coupling to environment, evolving, then tracing out all except B_i

$$\rho_{B_i} = \text{Tr}_{A \bar{B}_i} (U_{AB} (\rho_A \otimes \tau_B) U_{AB}^\dagger)$$

Environment starts in state τ_B
Then both systems evolve by unitary U_{AB}

Interlude: Measure-and-prepare channels



Quantum channels $A \rightarrow B$ are maps from the space of density operators on system A to density operators on B , i.e.

$$\rho_A \mapsto \rho_B$$

“Measure-and-prepare” channel: Special type of channel that takes the form

$$\rho_A \mapsto \rho_B = \sum_{\alpha} \text{Tr}(M^{\alpha} \rho_A) \sigma_B^{\alpha}.$$

for some measurement operators $\{M^{\alpha}\}_{\alpha}$ and states $\{\sigma_B^{\alpha}\}_{\alpha}$ (e.g. orthogonal projectors $M^{\alpha} = |\alpha\rangle\langle\alpha|$)

Interlude: Measure-and-prepare channels

Evolutions of the form

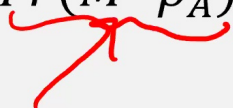
$$\rho_A \mapsto \rho_B = \sum_{\alpha} \text{Tr}(M^{\alpha} \rho_A) \sigma_B^{\alpha},$$

represent measuring A in the basis associated to M^{α} and then preparing the state σ_B^{α} contingent on classical outcome α .

For Alice and Bob are at different labs A and B , they can implement such a map by sending only classical information: Alice measures A and then sends the outcome label α to Bob, who then prepares a state σ_B^{α} .

Interlude: Measure-and-prepare channels

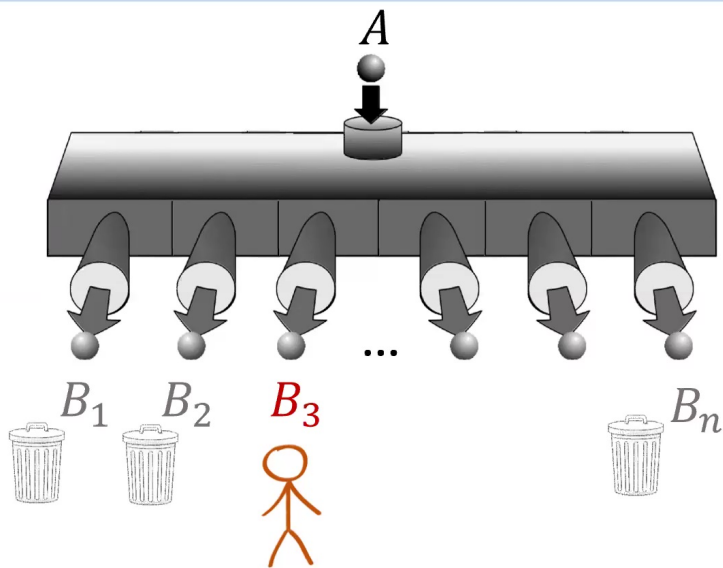
Evolutions of the form

$$\rho_A \mapsto \rho_B = \sum_{\alpha} \text{Tr}(M^{\alpha} \rho_A) \sigma_B^{\alpha},$$


represent measuring A in the basis associated to M^{α} and then preparing the state σ_B^{α} contingent on classical outcome α .

For Alice and Bob are at different labs A and B , they can implement such a map by sending only classical information: Alice measures A and then sends the outcome label α to Bob, who then prepares a state σ_B^{α} .

Our result: For any evolution $A \rightarrow B \dots$



ρ_A

Model evolution as coupling to environment, evolving, then tracing out all except B_i

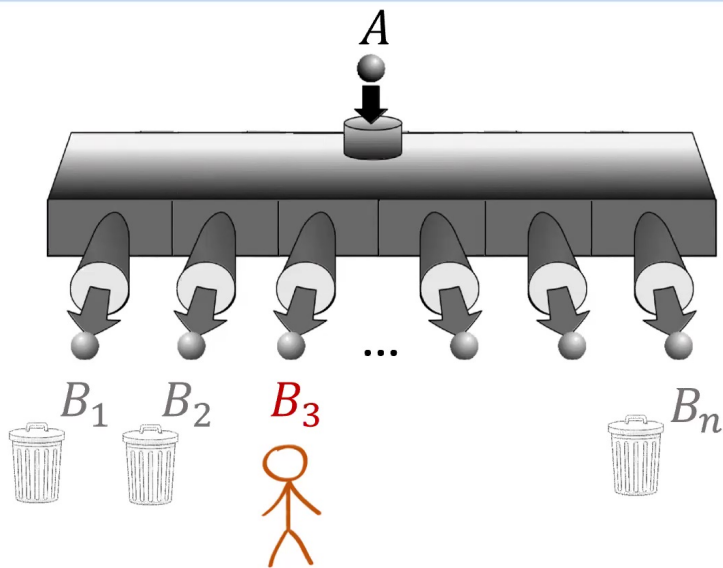
$$\rho_{B_i} = \text{Tr}_{A \bar{B}_i} (U_{AB} (\rho_A \otimes \tau_B) U_{AB}^\dagger)$$

$$\approx \sum_{\alpha} \text{Tr}(M^{\alpha} \rho_A) \sigma_{B_i}^{\alpha} \quad \text{"measure-and-prepare"}$$

for almost all B_i

for some choice of measurement operators $\{M^{\alpha}\}$
(independent of B_i)

Our result: For any evolution $A \rightarrow B \dots$



ρ_A

Model evolution as coupling to environment, evolving, then tracing out all except B_i

$$\rho_{B_i} = \text{Tr}_{A \bar{B}_i} (U_{AB} (\rho_A \otimes \tau_B) U_{AB}^\dagger)$$

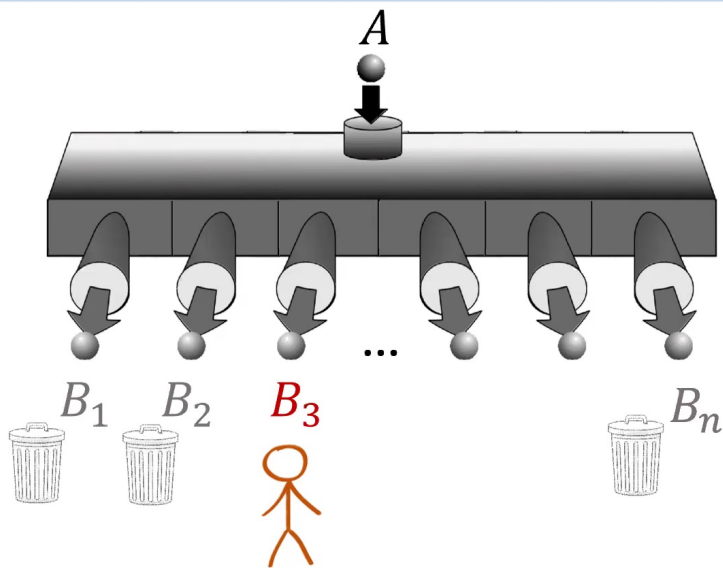
$$\approx \sum_{\alpha} \text{Tr}(M^{\alpha} \rho_A) \sigma_{B_i}^{\alpha} \quad \text{“measure-and-prepare”}$$

for almost all B_i

for some choice of measurement operators $\{M^{\alpha}\}$
(independent of B_i)

For almost all B_i (all but $O(1)$ -many), the evolution $\rho_A \rightarrow \rho_{B_i}$ looks like performing a fixed classical measurement on A , followed by preparing some state on B_i based on the outcome.

Our result: For any evolution $A \rightarrow B \dots$



ρ_A

Model evolution as coupling to environment, evolving, then tracing out all except B_i

$$\rho_{B_i} = \text{Tr}_{A \bar{B}_i} (U_{AB} (\rho_A \otimes \tau_B) U_{AB}^\dagger)$$

$$\approx \sum_{\alpha} \text{Tr}(M^{\alpha} \rho_A) \sigma_{B_i}^{\alpha} \quad \text{"measure-and-prepare"}$$

for almost all B_i

for some choice of measurement operators $\{M^{\alpha}\}$
(independent of B_i)

For almost all B_i (all but $O(1)$ -many), the evolution $\rho_A \rightarrow \rho_{B_i}$ looks like performing a fixed classical measurement on A , followed by preparing some state on B_i based on the outcome.

Examples of applying theorem to evolutions

ρ_A



Model evolution as coupling input A to environment B ,
evolving both, then tracing out all except B_i

$$\rho_{B_i} = \text{Tr}_{A \overline{B_i}} (U_{AB} (\rho_A \otimes \tau_B) U_{AB}^+)$$

Example: Direct transport $A \rightarrow B_1$

ρ_A



Model evolution as coupling input A to environment B ,
evolving both, then tracing out all except B_i

$$\rho_{B_i} = \text{Tr}_{A \bar{B}_i} (U_{AB} (\rho_A \otimes \tau_B) U_{AB}^\dagger)$$

$$\tau_B = |0\rangle^{\otimes n} \langle 0|^{\otimes n}$$

$$U_{AB} |0\rangle_A |0 \dots 0\rangle_B = |0\rangle_A |0 \dots 0\rangle_B$$

$$U_{AB} |1\rangle_A |0 \dots 0\rangle_B = |1\rangle_A |00 \dots 0\rangle_B$$

$$\rho_A \rightarrow \rho_{B_1} = \rho_A$$

$$\rho_A \rightarrow \rho_{B_i} = \text{Tr}(\rho_A) |0\rangle \langle 0|_{B_i} \quad (\text{for } i > 1)$$

Example:

Input system A sent faithfully to B_1

Other B_i sent to $|0\rangle$ (for $i > 1$)

Not measure-and-prepare **X**

Measure-and-prepare **✓** (Trivial prep.)

Example: Direct transport $A \rightarrow B_1$

ρ_A



Model evolution as coupling input A to environment B ,
evolving both, then tracing out all except B_i

$$\rho_{B_i} = \text{Tr}_{A \bar{B}_i} (U_{AB} (\rho_A \otimes \tau_B) U_{AB}^\dagger)$$

$$\tau_B = |0\rangle^{\otimes n} \langle 0|^{\otimes n}$$

$$U_{AB} |0\rangle_A |0 \dots 0\rangle_B = |0\rangle_A |0 \dots 0\rangle_B$$

$$U_{AB} |1\rangle_A |0 \dots 0\rangle_B = |1\rangle_A |00 \dots 0\rangle_B$$

$$\rho_A \rightarrow \rho_{B_1} = \rho_A$$

$$\rho_A \rightarrow \rho_{B_i} = \text{Tr}(\rho_A) |0\rangle \langle 0|_{B_i} \quad (\text{for } i > 1)$$

Example:

Input system A sent faithfully to B_1
Other B_i sent to $|0\rangle$ (for $i > 1$)

Not measure-and-prepare **X**

Measure-and-prepare **✓**

(Trivial prep.)

B_i

Example: Spin chain evolution

ρ_A



Model evolution as coupling input A to environment B ,
evolving both, then tracing out all except B_i

$$\rho_{B_i} = \text{Tr}_{A \bar{B}_i} (U_{AB} (\rho_A \otimes \tau_B) U_{AB}^\dagger)$$



τ_B = Groundstate of spin chain B

U_{AB} = Evolution of extended chain AB

Example:

Couple qubit A onto end of spin chain B ,
then evolve extended chain

$$\rho_A \rightarrow \rho_{B_i} = \text{????}$$

Numerical examples work!

Measure-and-prepare



Example: Spin chain evolution

ρ_A



Model evolution as coupling input A to environment B , evolving both, then tracing out all except B_i

\uparrow
 e^{-iHt}

$$\rho_{B_i} = \text{Tr}_{A \bar{B}_i} (U_{AB}(\rho_A \otimes \tau_B) U_{AB}^\dagger)$$



τ_B = Groundstate of spin chain B

U_{AB} = Evolution of extended chain AB

Example:

Couple qubit A onto end of spin chain B , then evolve extended chain

$$\rho_A \rightarrow \rho_{B_i} = \text{????}$$

Numerical examples work!

Measure-and-prepare



Example: Spin chain evolution

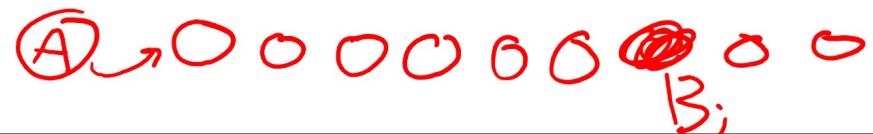
ρ_A



Model evolution as coupling input A to environment B , evolving both, then tracing out all except B_i

$\uparrow e^{-iHt}$

$$\rho_{B_i} = \text{Tr}_{A \bar{B}_i} (U_{AB} (\rho_A \otimes \tau_B) U_{AB}^\dagger)$$



τ_B = Groundstate of spin chain B

U_{AB} = Evolution of extended chain AB

Example:

Couple qubit A onto end of spin chain B , then evolve extended chain

$$\rho_A \rightarrow \rho_{B_i} = \text{????}$$

Measure-and-prepare



Numerical examples work!

Example: Decoherence

ρ_A



Model evolution as coupling input A to environment B ,
evolving both, then tracing out all except B_i

$$\rho_{B_i} = \text{Tr}_{A \bar{B}_i} (U_{AB} (\rho_A \otimes \tau_B) U_{AB}^\dagger)$$

$$\tau_B = |0\rangle^{\otimes n} \langle 0|^{\otimes n}$$

$$U_{AB} |0\rangle_A |0\rangle_B^{\otimes n} = |0\rangle_A |0\rangle_B^{\otimes n}$$

$$U_{AB} |1\rangle_A |0\rangle_B^{\otimes n} = |1\rangle_A |1\rangle_B^{\otimes n}$$

Example:

Input system A is measured/decohered
in $|0\rangle, |1\rangle$ basis

Outcome recorded on each B_i

$$\rho_A \rightarrow \rho_{B_i} = \text{Tr}(|0\rangle\langle 0| \rho_A) |0\rangle\langle 0|_{B_i} + \text{Tr}(|1\rangle\langle 1| \rho_A) |1\rangle\langle 1|_{B_i}$$

Measure-and-prepare ✓

Example: Decoherence

ρ_A



Model evolution as coupling input A to environment B ,
evolving both, then tracing out all except B_i

$$\rho_{B_i} = \text{Tr}_{A \bar{B}_i} (U_{AB} (\rho_A \otimes \tau_B) U_{AB}^\dagger)$$

$$\tau_B = |0\rangle^{\otimes n} \langle 0|^{\otimes n}$$

$$U_{AB} |0\rangle_A |0\rangle_B^{\otimes n} = |0\rangle_A |0\rangle_B^{\otimes n}$$

$$U_{AB} |1\rangle_A |0\rangle_B^{\otimes n} = |1\rangle_A |1\rangle_B^{\otimes n}$$

$$\rho_A \rightarrow \rho_{B_i} = \text{Tr}(|0\rangle\langle 0| \rho_A) |0\rangle\langle 0|_{B_i} + \text{Tr}(|1\rangle\langle 1| \rho_A) |1\rangle\langle 1|_{B_i}$$

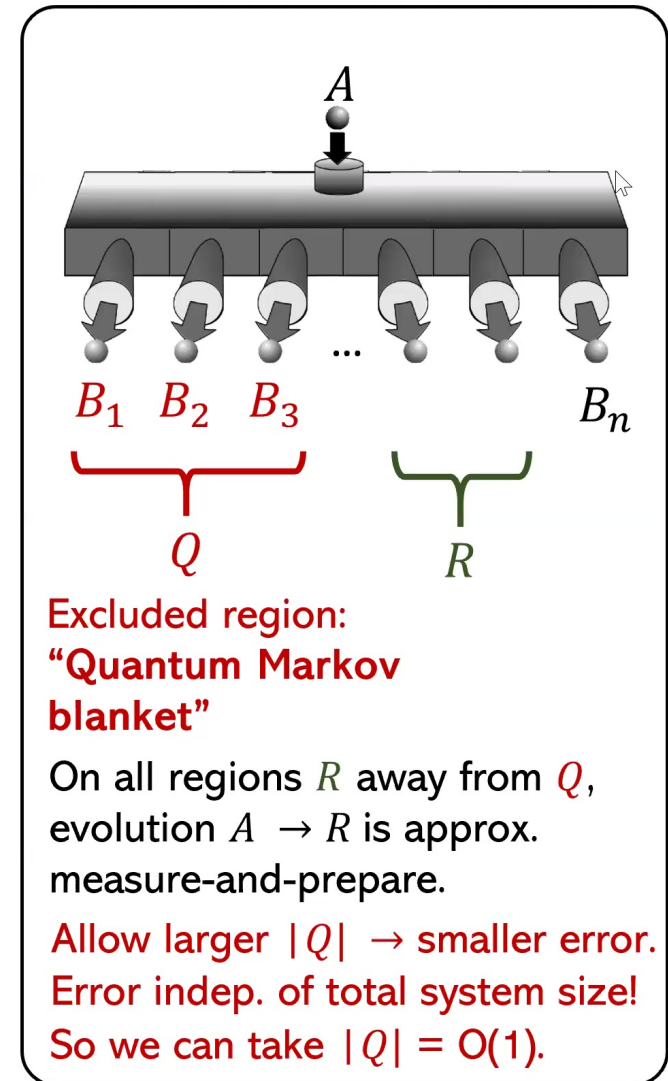
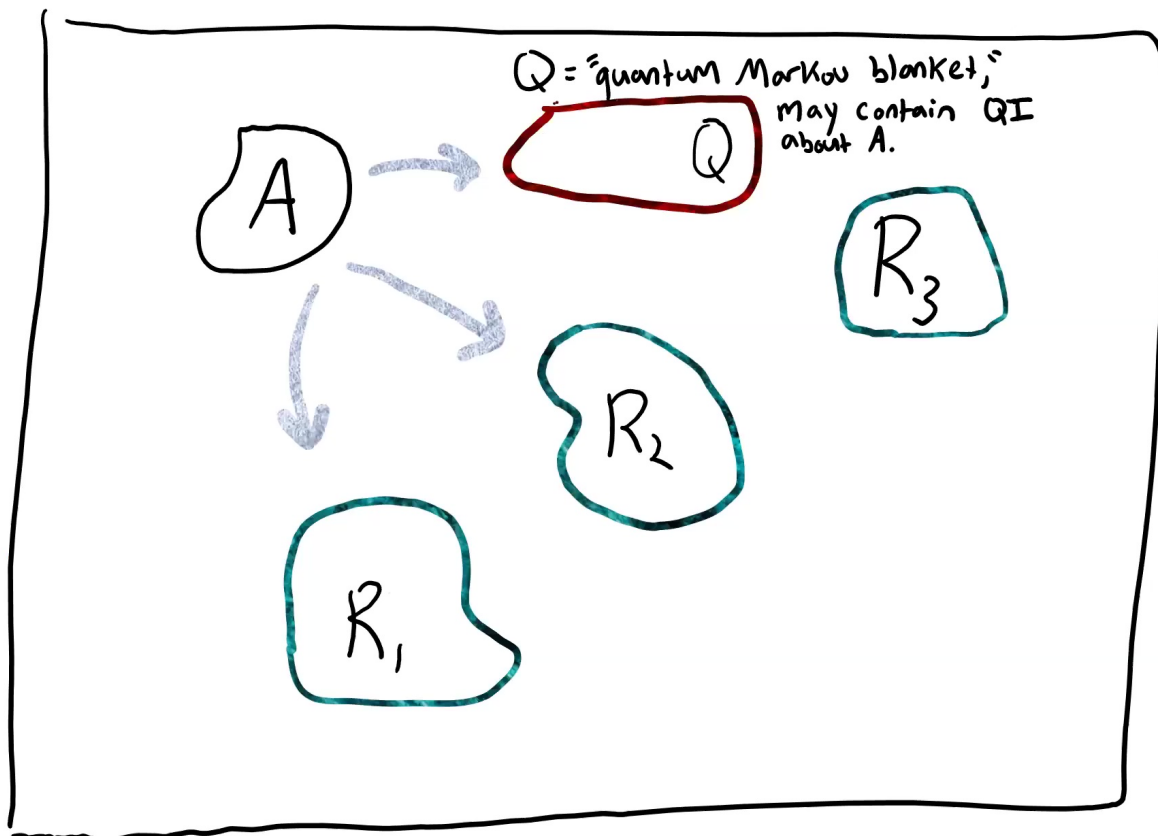
Example:

Input system A is measured/decohered
in $|0\rangle, |1\rangle$ basis

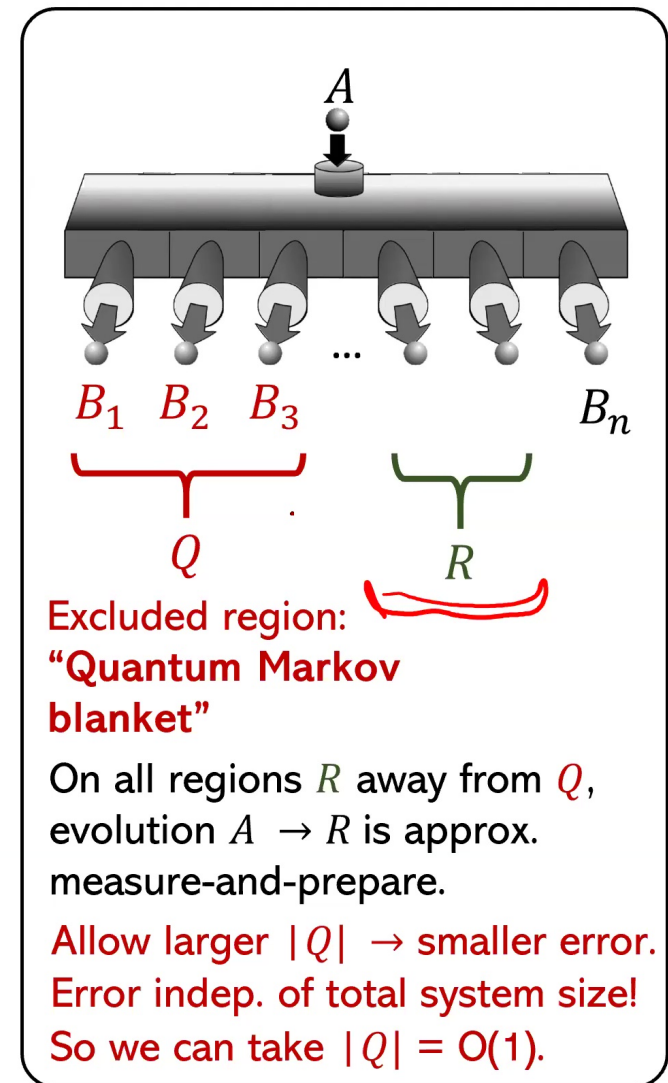
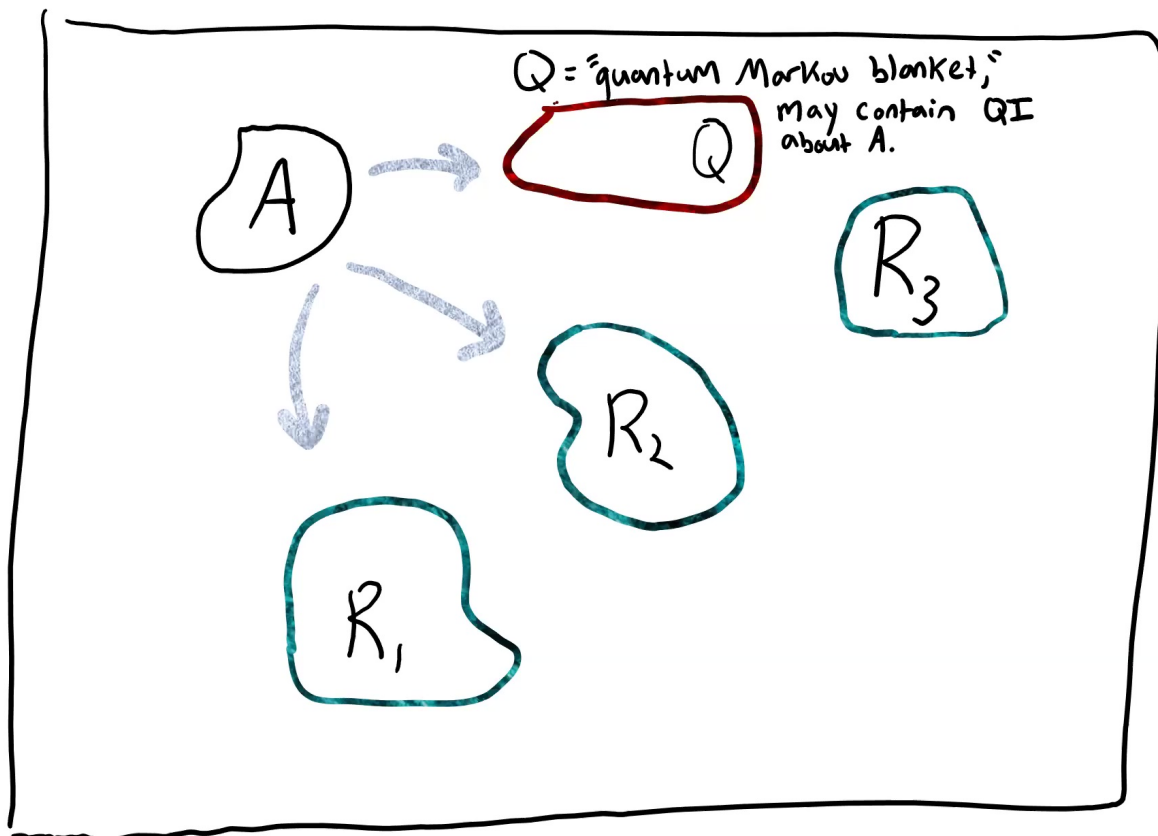
Outcome recorded on each B_i

Measure-and-prepare ✓

Theorem statement (almost)



Theorem statement (almost)



Quantum Markov blanket, Q

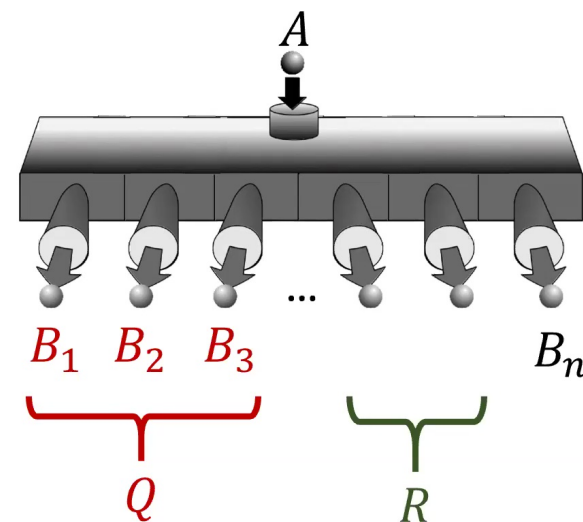
Q roughly includes outputs B_i with most information about A

Q “blankets” A :

Any information about A that’s accessible on small regions R outside Q can be obtained from a classical measurement on just Q .

Q includes, at least, any region with locally accessible *quantum* information about A .

For arbitrarily large environments, you can still “cover” A with an $O(1)$ -sized blanket Q !



Excluded region:
“Quantum Markov
blanket”

On all regions R away from Q ,
evolution $A \rightarrow R$ is approx.
measure-and-prepare.

Allow larger $|Q| \rightarrow$ smaller error.
Error indep. of total system size!
So we can take $|Q| = O(1)$.

Theorem statement

Consider a quantum channel

$$N : \mathcal{D}(A) \rightarrow \mathcal{D}(B_1 \otimes \cdots \otimes B_n)$$

$\mathcal{D}(X)$ = density operators on X

For general output subset R , let N

$$N_R \equiv \text{Tr}_{\bar{R}} \circ N : \mathcal{D}(A) \rightarrow \mathcal{D}(R)$$

denote the *reduced channel* obtained by tracing out the complement \bar{R} .

Theorem: For any $|Q|, |R| \in \{1, \dots, n\}$, there exists a POVM $\{M_\alpha\}$ and an “excluded” output subset Q of size $|Q|$, such that for all output subsets R of size $|R|$ disjoint from Q ,

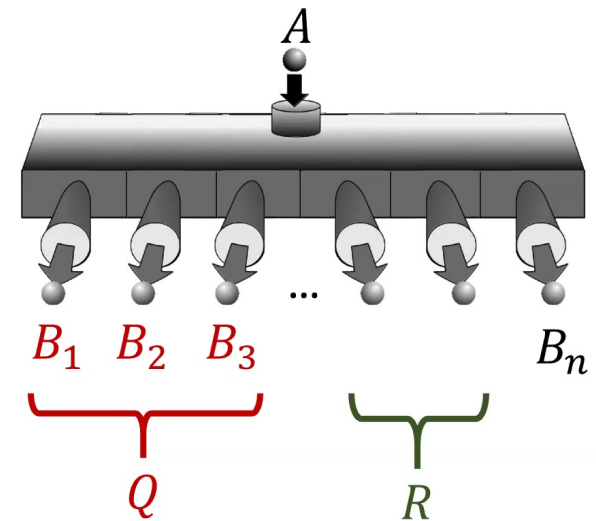
$$\|N_R - \mathcal{E}_R\|_\diamond \leq d_A^3 \sqrt{2 \ln d_A \frac{|R|}{|Q|}}$$

Take $|R| < |Q|$
 $d_A = \dim(A)$

where \mathcal{E}_R is *measure-and-prepare*,

$$\mathcal{E}_R(\rho) \equiv \sum_{\alpha} \text{Tr}(M_{\alpha} \rho) \sigma_R^{\alpha}$$

for some choice of states σ_R^{α} on R . Note $\{M_{\alpha}\}$ chosen independent of R .



Excluded region:
“Quantum Markov blanket”

On all regions R away from Q , evolution $A \rightarrow R$ is approx. measure-and-prepare.

Allow larger $|Q| \rightarrow$ smaller error.
Error indep. of total system size!
So we can take $|Q| = O(1)$.

Theorem statement

Consider a quantum channel

$$N: \mathcal{D}(A) \rightarrow \mathcal{D}(B_1 \otimes \cdots \otimes B_n)$$

$\mathcal{D}(X)$ = density operators on X

For general output subset R , let N

$$N_R \equiv \text{Tr}_{\bar{R}} \circ N: \mathcal{D}(A) \rightarrow \mathcal{D}(R)$$

$$R = \{B_1, B_2, B_5\}$$

denote the *reduced channel* obtained by tracing out the complement \bar{R} .

Theorem: For any $|Q|, |R| \in \{1, \dots, n\}$, there exists a POVM $\{M_\alpha\}$ and an “excluded” output subset Q of size $|Q|$, such that for all output subsets R of size $|R|$ disjoint from Q ,

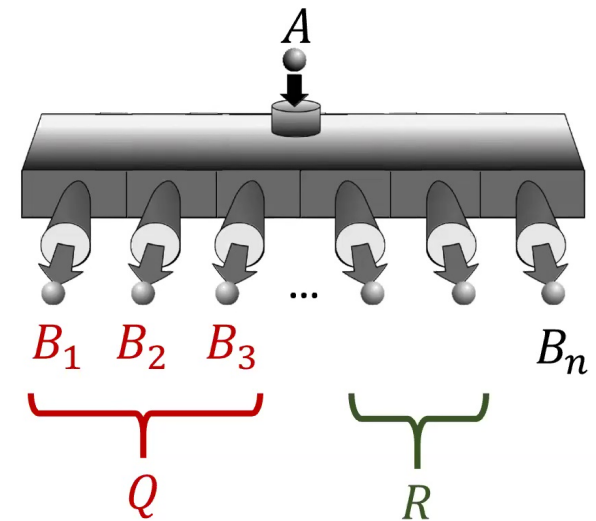
$$\|N_R - \mathcal{E}_R\|_\diamond \leq d_A^3 \sqrt{2 \ln d_A \frac{|R|}{|Q|}}$$

Take $|R| < |Q|$
 $d_A = \dim(A)$

where \mathcal{E}_R is *measure-and-prepare*,

$$\mathcal{E}_R(\rho) \equiv \sum_{\alpha} \text{Tr}(M_{\alpha} \rho) \sigma_R^{\alpha}$$

for some choice of states σ_R^{α} on R . Note $\{M_{\alpha}\}$ chosen independent of R .



Excluded region:
“Quantum Markov blanket”

On all regions R away from Q , evolution $A \rightarrow R$ is approx. measure-and-prepare.

Allow larger $|Q| \rightarrow$ smaller error.
 Error indep. of total system size!
 So we can take $|Q| = O(1)$.

Theorem statement

Consider a quantum channel

$$N: \mathcal{D}(A) \rightarrow \mathcal{D}(B_1 \otimes \cdots \otimes B_n)$$

$\mathcal{D}(X)$ = density operators on X

For general output subset R , let N

$$N_R \equiv \text{Tr}_{\bar{R}} \circ N: \mathcal{D}(A) \rightarrow \mathcal{D}(R)$$

$$R = \{B_1, B_2, B_5\}$$

denote the *reduced channel* obtained by tracing out the complement \bar{R} .

Theorem: For any $|Q|, |R| \in \{1, \dots, n\}$, there exists a POVM $\{M_\alpha\}$ and an “excluded” output subset Q of size $|Q|$, such that for all output subsets R of size $|R|$ disjoint from Q ,

$$R \cap Q = \emptyset$$

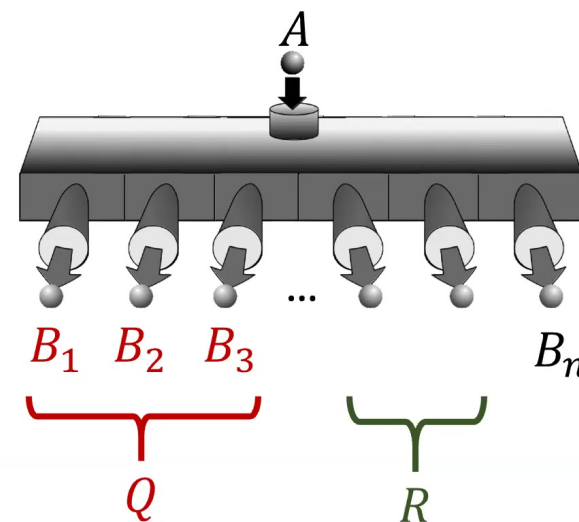
$$\|N_R - \mathcal{E}_R\|_\diamond \leq d_A^3 \sqrt{2 \ln d_A \frac{|R|}{|Q|}}$$

Take $|R| < |Q|$
 $d_A = \dim(A)$

where \mathcal{E}_R is *measure-and-prepare*,

$$\mathcal{E}_R(\rho) \equiv \sum_{\alpha} \text{Tr}(M_{\alpha} \rho) \sigma_R^{\alpha}$$

for some choice of states σ_R^{α} on R . Note $\{M_{\alpha}\}$ chosen independent of R .



Excluded region:
“Quantum Markov blanket”

On all regions R away from Q , evolution $A \rightarrow R$ is approx. measure-and-prepare.

Allow larger $|Q| \rightarrow$ smaller error.
 Error indep. of total system size!
 So we can take $|Q| = O(1)$.

Theorem statement

Consider a quantum channel

$$N: \mathcal{D}(A) \rightarrow \mathcal{D}(B_1 \otimes \cdots \otimes B_n)$$

$\mathcal{D}(X)$ = density operators on X

For general output subset R , let N

$$N_R \equiv \text{Tr}_{\bar{R}} \circ N: \mathcal{D}(A) \rightarrow \mathcal{D}(R)$$

$$R = \{B_1, B_2, B_5\}$$

denote the *reduced channel* obtained by tracing out the complement \bar{R} .

Theorem: For any $|Q|, |R| \in \{1, \dots, n\}$, there exists a POVM $\{M_\alpha\}$ and an “excluded” output subset Q of size $|Q|$, such that for all output subsets R of size $|R|$ disjoint from Q ,

$$R \cap Q = \emptyset$$

$$\|N_R - \mathcal{E}_R\|_\diamond \leq d_A^3 \sqrt{2 \ln d_A \frac{|R|}{|Q|}}$$

Take $|R| < |Q|$

$d_A = \dim(A)$

where \mathcal{E}_R is *measure-and-prepare*,

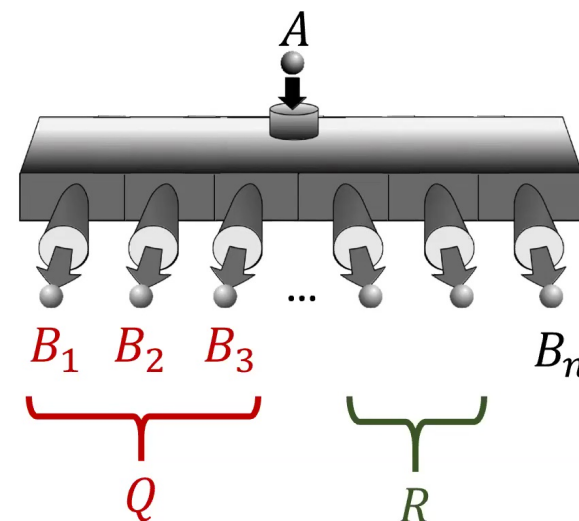
$$\mathcal{E}_R(\rho) \equiv \sum_{\alpha} \text{Tr}(M_{\alpha} \rho) \sigma_R^{\alpha}$$

for some choice of states σ_R^{α} on R . Note $\{M_{\alpha}\}$ chosen independent of R .

$$n = 10^{23}$$

$$|R| = 1$$

$$|Q| < 10, 100, 1000$$



Excluded region:
“Quantum Markov
blanket”

On all regions R away from Q ,
evolution $A \rightarrow R$ is approx.
measure-and-prepare.

Allow larger $|Q| \rightarrow$ smaller error.
Error indep. of total system size!
So we can take $|Q| = O(1)$.

Theorem statement

Consider a quantum channel

$$N: \mathcal{D}(A) \rightarrow \mathcal{D}(B_1 \otimes \cdots \otimes B_n)$$

$\mathcal{D}(X)$ = density operators on X

For general output subset R , let N

$$N_R \equiv \text{Tr}_{\bar{R}} \circ N: \mathcal{D}(A) \rightarrow \mathcal{D}(R)$$

$$R = \{B_1, B_2, B_5\}$$

denote the *reduced channel* obtained by tracing out the complement \bar{R} .

Theorem: For any $|Q|, |R| \in \{1, \dots, n\}$, there exists a POVM $\{M_\alpha\}$ and an “excluded” output subset Q of size $|Q|$, such that for all output subsets R of size $|R|$ disjoint from Q ,

$$R \cap Q = \emptyset$$

$$\|N_R - \mathcal{E}_R\|_\diamond \leq d_A^3 \sqrt{2 \ln d_A \frac{|R|}{|Q|}}$$

Take $|R| < |Q|$
 $d_A = \dim(A)$

where \mathcal{E}_R is *measure-and-prepare*,

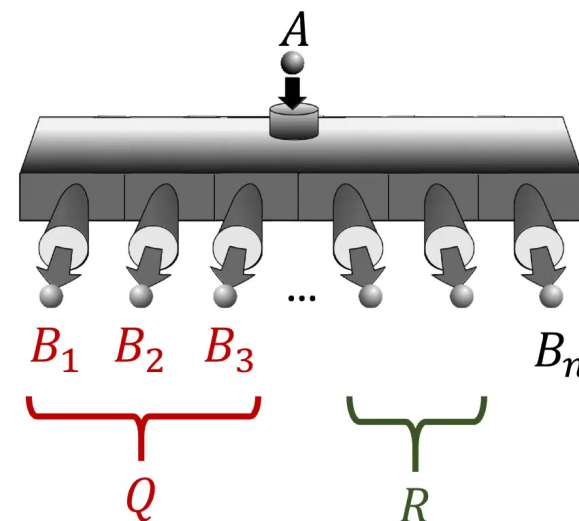
$$\mathcal{E}_R(\rho) \equiv \sum_{\alpha} \text{Tr}(M_{\alpha} \rho) \sigma_R^{\alpha}$$

for some choice of states σ_R^{α} on R . Note $\{M_{\alpha}\}$ chosen independent of R .

$$n = 10^{23}$$

$$|R| = 1$$

$$|Q| < 10, 100, 1000$$



Excluded region:
“Quantum Markov blanket”

On all regions R away from Q , evolution $A \rightarrow R$ is approx. measure-and-prepare.

Allow larger $|Q| \rightarrow$ smaller error.
 Error indep. of total system size!
 So we can take $|Q| = O(1)$.

Theorem statement

Consider a quantum channel

$$N: \mathcal{D}(A) \rightarrow \mathcal{D}(B_1 \otimes \cdots \otimes B_n)$$

$\mathcal{D}(X)$ = density operators on X

For general output subset R , let N

$$N_R \equiv \text{Tr}_{\bar{R}} \circ N: \mathcal{D}(A) \rightarrow \mathcal{D}(R)$$

$$R = \{B_1, B_2, B_5\}$$

denote the *reduced channel* obtained by tracing out the complement \bar{R} .

Theorem: For any $|Q|, |R| \in \{1, \dots, n\}$, there exists a POVM $\{M_\alpha\}$ and an “excluded” output subset Q of size $|Q|$, such that for all output subsets R of size $|R|$ disjoint from Q ,

$$R \cap Q = \emptyset$$

$$\|N_R - \mathcal{E}_R\|_\diamond \leq d_A^3 \sqrt{2 \ln d_A \frac{|R|}{|Q|}}$$

Take $|R| < |Q|$
 $d_A = \dim(A)$

where \mathcal{E}_R is *measure-and-prepare*,

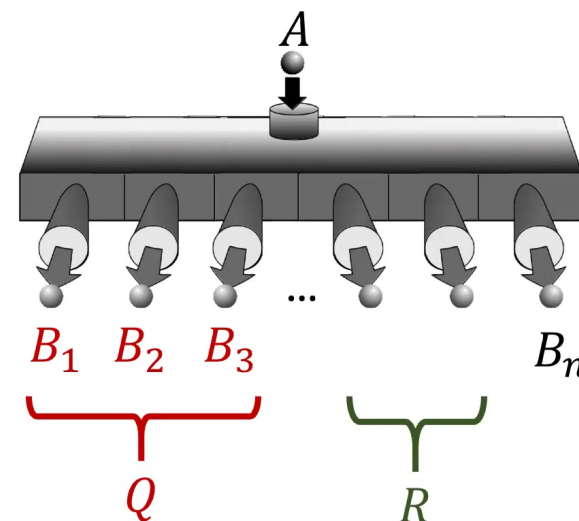
$$\mathcal{E}_R(\rho) \equiv \sum_{\alpha} \text{Tr}(M_{\alpha} \rho) \sigma_R^{\alpha}$$

for some choice of states σ_R^{α} on R . Note $\{M_{\alpha}\}$ chosen independent of R .

$$n = 10^{23}$$

$$|R| = 1$$

$$|Q| < 10, 100, 1000$$



Excluded region:
“Quantum Markov blanket”

On all regions R away from Q , evolution $A \rightarrow R$ is approx. measure-and-prepare.

Allow larger $|Q| \rightarrow$ smaller error.
 Error indep. of total system size!
 So we can take $|Q| = O(1)$.

Theorem statement

$d_A = \dim \mathcal{H}_A$
 $|Q| = \# \text{ qubits in } Q$

Consider a quantum channel

$$N: \mathcal{D}(A) \rightarrow \mathcal{D}(B_1 \otimes \cdots \otimes B_n)$$

$\mathcal{D}(X)$ = density operators on X

For general output subset R , let N

$$N_R \equiv \text{Tr}_{\bar{R}} \circ N: \mathcal{D}(A) \rightarrow \mathcal{D}(R)$$

$R = \{B_1, B_2, B_5\}$

denote the *reduced channel* obtained by tracing out the complement \bar{R} .

Theorem: For any $|Q|, |R| \in \{1, \dots, n\}$, there exists a POVM $\{M_\alpha\}$ and an “excluded” output subset Q of size $|Q|$, such that for all output subsets R of size $|R|$ disjoint from Q ,

$$R \cap Q = \emptyset$$

$$\|N_R - \mathcal{E}_R\|_\diamond \leq d_A^3 \sqrt{2 \ln d_A \frac{|R|}{|Q|}}$$

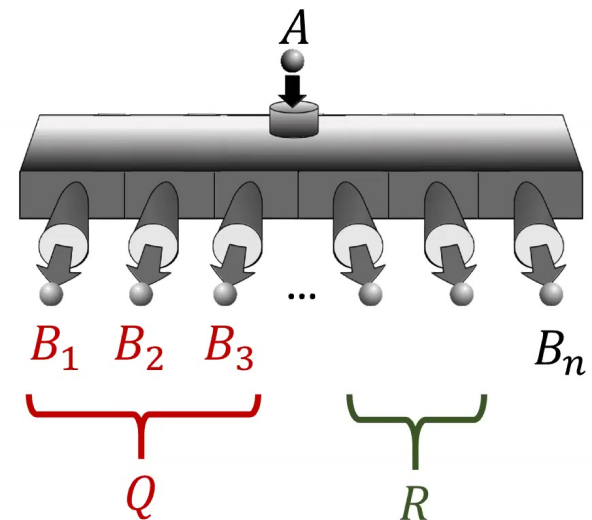
Take $|R| < |Q|$
 $d_A = \dim(A)$

where \mathcal{E}_R is *measure-and-prepare*,

$$\mathcal{E}_R(\rho) \equiv \sum_\alpha \text{Tr}(M_\alpha \rho) \sigma_R^\alpha$$

for some choice of states σ_R^α on R . Note $\{M_\alpha\}$ chosen independent of R .

$n = 10^{23}$
 $|R| = 1$
 $|Q| < 10, 100, 1000$



Excluded region:
“Quantum Markov blanket”

On all regions R away from Q , evolution $A \rightarrow R$ is approx. measure-and-prepare.

Allow larger $|Q| \rightarrow$ smaller error.
 Error indep. of total system size!
 So we can take $|Q| = O(1)$.

Supplementary interlude: proof sketch

Theorem statement (for states)

Consider any quantum state $\rho_{AB_1 \dots B_n}$ on $A \otimes B_1 \otimes \dots \otimes B_n$.

Theorem: For any $|Q|, |R| \in \{1, \dots, n\}$, there exist states ρ_α^A , probabilities p_α , and an “excluded” subset $Q \subset \{B_1, \dots, B_n\}$ of size $|Q|$, such that for all subsets $R \subset \{B_1, \dots, B_n\}$ of size $|R|$ disjoint from Q ,

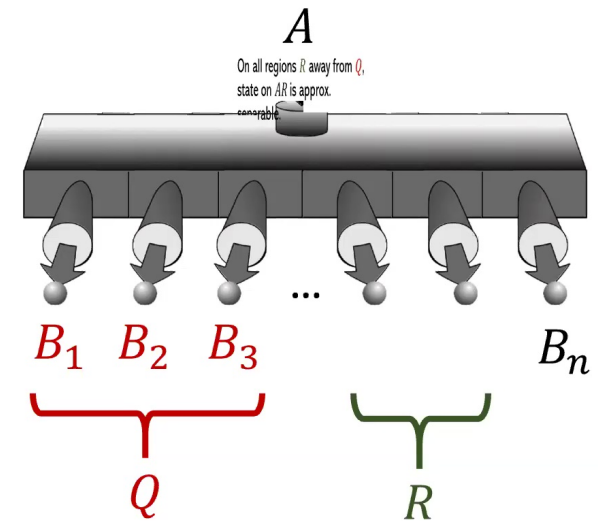
$$\left\| \rho_{AR} - \sum_{\alpha} p_{\alpha} \rho_{\alpha}^A \otimes \sigma_{\alpha}^R \right\|_{LOCC_{\leftarrow}} \leq \sqrt{2 \ln d_A \frac{|R|}{|Q|}} \quad d_A = \dim(A)$$

for some choice of states σ_R^{α} on R .

Note $\rho_{\alpha}^A, p_{\alpha}$ chosen independently of R .

We used “one-way LOCC norm,”

$$\|\rho_{AR}\|_{LOCC_{\leftarrow}} \equiv \max_{M_R \in QC} \|(1 \otimes M_R)(\rho_{AR})\|_1$$



Excluded region:
“Quantum Markov
blanket”

On all regions R away from Q ,
state on AR is approx.
separable.

Allow larger $|Q| \rightarrow$ smaller error.
Error indep. of total system size!
So we can take $|Q| = O(1)$.

Theorem statement (for states)

Consider any quantum state $\rho_{AB_1 \dots B_n}$ on $A \otimes B_1 \otimes \dots \otimes B_n$.

Theorem: For any $|Q|, |R| \in \{1, \dots, n\}$, there exist states ρ_α^A , probabilities p_α , and an “excluded” subset $Q \subset \{B_1, \dots, B_n\}$ of size $|Q|$, such that for all subsets $R \subset \{B_1, \dots, B_n\}$ of size $|R|$ disjoint from Q ,

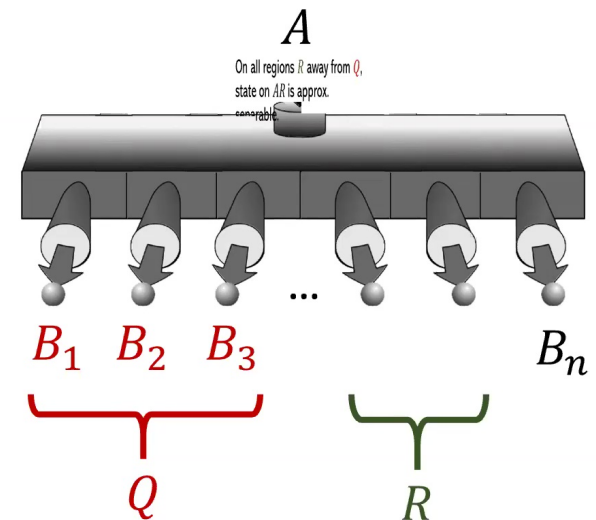
$$\left\| \rho_{AR} - \sum_{\alpha} p_{\alpha} \rho_{\alpha}^A \otimes \sigma_{\alpha}^R \right\|_{LOCC_{\leftarrow}} \leq \sqrt{2 \ln d_A \frac{|R|}{|Q|}} \quad d_A = \dim(A)$$

for some choice of states σ_R^{α} on R .

Note $\rho_{\alpha}^A, p_{\alpha}$ chosen independently of R .

We used “one-way LOCC norm,”

$$\|\rho_{AR}\|_{LOCC_{\leftarrow}} \equiv \max_{M_R \in QC} \|(1 \otimes M_R)(\rho_{AR})\|_1$$



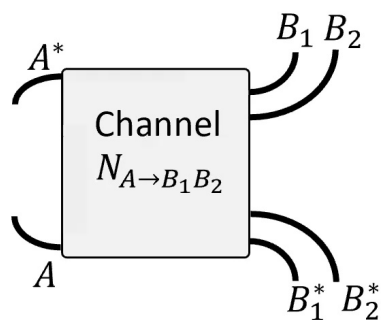
Excluded region:
“Quantum Markov
blanket”

On all regions R away from Q ,
state on AR is approx.
separable.

Allow larger $|Q| \rightarrow$ smaller error.
Error indep. of total system size!
So we can take $|Q| = O(1)$.

Channel-state duality

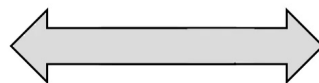
The main result may be formulated as a result about either (1) channels with multiple outputs, or (2) multipartite states.



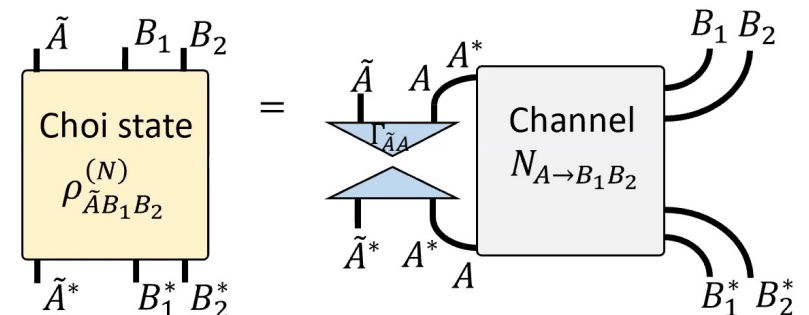
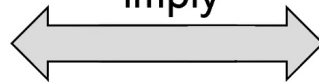
Constraints on **dynamical** properties of channels (e.g. no cloning)

Reduced channels are measure-and-prepare?

Channel-state duality



imply



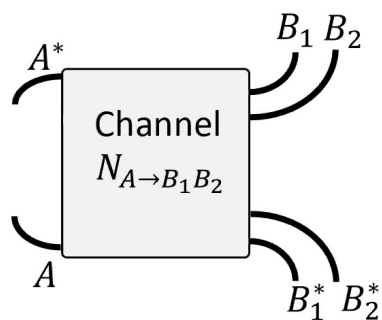
Constraints on **static** correlation properties of states (e.g. monogamy)

Reduced states are separable?

Channel-state duality

The main result may be formulated as a result about either (1) channels with multiple outputs, or (2) multipartite states.

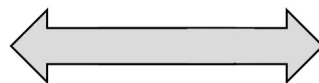
m.p. ← Sep. St.



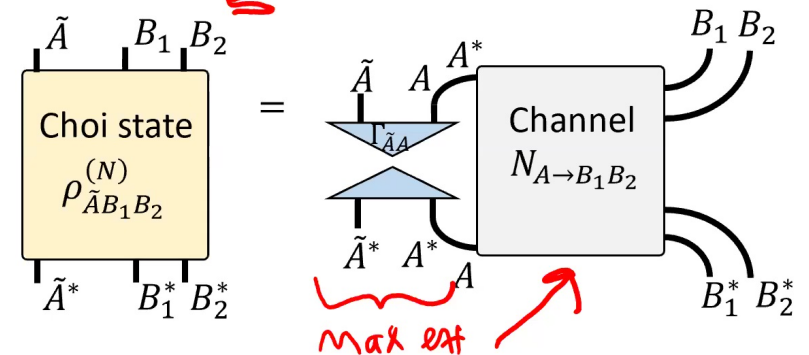
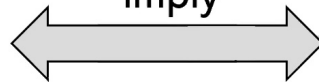
Constraints on **dynamical** properties of channels (e.g. no cloning)

Reduced channels are measure-and-prepare?

Channel-state duality



imply



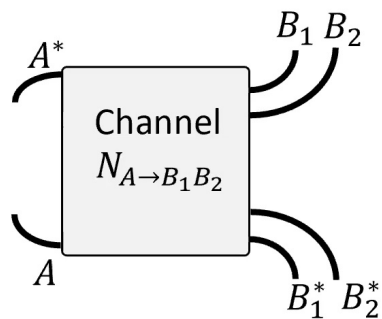
Constraints on **static** correlation properties of states (e.g. monogamy)

Reduced states are separable?

Channel-state duality

The main result may be formulated as a result about either (1) channels with multiple outputs, or (2) multipartite states.

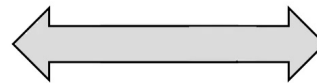
m.p. \longleftrightarrow *sep. state*



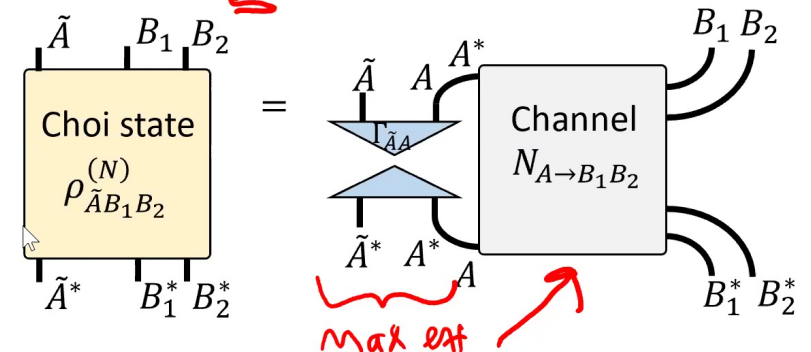
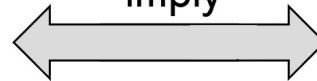
Constraints on **dynamical** properties of channels (e.g. no cloning)

Reduced channels are measure-and-prepare?

Channel-state duality



imply



Constraints on **static** correlation properties of states (e.g. monogamy)

Reduced states are separable?

Sketch of argument: Warm-up result

$$S(X) = -\text{Tr}(\rho_X \log \rho_X)$$

(entropy)

(how much there is to know about X)

$$I(X, Y) = S(X) + S(Y) - S(XY)$$

(mutual information)

(how much knowing Y tells you about X)

$$I(X, Y|Z) = I(X, YZ) - I(X, Z)$$

(conditional mutual information)

(how much more knowing YZ tells you about X than just knowing Y)

Sketch of argument: Warm-up result

$$S(X) = -\text{Tr}(\rho_X \log \rho_X)$$

(entropy)

(how much there is to know about X)

$$I(X, Y) = S(X) + S(Y) - S(XY)$$

(mutual information)

(how much knowing Y tells you about X)

$$I(X, Y|Z) = I(X, YZ) - I(X, Z)$$

(conditional mutual information)

(how much more knowing YZ tells you about X than just knowing Y)

For any state $\rho_{AB_1 \dots B_n}$, for any size q :

There exists region $Q \subset \{B_1, \dots, B_n\}$ of size $|Q| \leq q$ such that for all $B_i \notin Q$,

$$I(A, B_i|Q) \leq \frac{1}{|Q|} 2 \log(d_A).$$

$$I(X, Y|Z) = I(X, YZ) - I(X, Z) \quad (\text{conditional mutual information})$$

For any state $\rho_{AB_1 \dots B_n}$, for any size q :

There exists region $Q \subset \{B_1, \dots, B_n\}$ of size $|Q| \leq q$ such that for all $B_i \notin Q$,

$$I(A, B_i|Q) \leq \frac{1}{|Q|} 2 \log(d_A).$$

Constructive proof: Build up Q by expanding it one by one.

- 1) Choose region B_{i_1} that maximizes $I(A, B_{i_1})$
- 2) Choose region B_{i_2} that maximizes $I(A, B_{i_2}|B_{i_1})$
- 3) Choose region B_{i_3} that maximizes $I(A, B_{i_3}|B_{i_1} B_{i_2})$
- \vdots
- $|Q|$) Choose region $B_{i_{|Q|}}$ that maximizes $I(A, B_{i_{|Q|}}|B_{i_1} \dots B_{i_{|Q|-1}})$

By chain rule of mutual information,

$$I(A, B_{i_1}) + I(A, B_{i_2}|B_{i_1}) + \dots + I(A, B_{i_q}|B_{i_1} \dots B_{i_{q-1}}) = I(A, B_{i_1} \dots B_{i_q}) \leq 2 \log(d_A)$$

And by strong subadditivity, all terms are positive. So at least one term is small, i.e.

there is some value q' s.t. $I(A, B_{i_{q'}}|B_{i_1} \dots B_{i_{q'-1}}) \leq |Q|^{-1} 2 \log(d_A)$. Take $Q = B_{i_1} \dots B_{i_{q'-1}}$.

$$I(X, Y|Z) = I(X, YZ) - I(X, Z) \quad (\text{conditional mutual information})$$

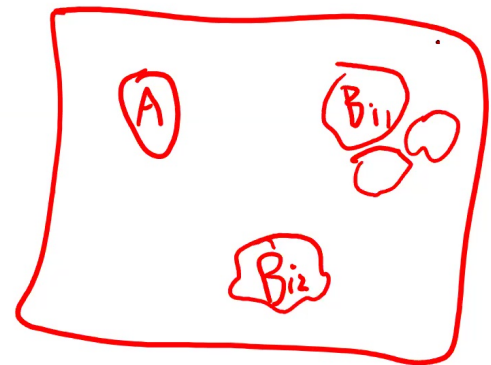
For any state $\rho_{AB_1 \dots B_n}$, for any size q :

There exists region $Q \subset \{B_1, \dots, B_n\}$ of size $|Q| \leq q$ such that for all $B_i \notin Q$,

$$I(A, B_i|Q) \leq \frac{1}{|Q|} 2 \log(d_A).$$

Constructive proof: Build up Q by expanding it one by one.

- 1) Choose region B_{i_1} that maximizes $I(A, B_{i_1})$
- 2) Choose region B_{i_2} that maximizes $I(A, B_{i_2}|B_{i_1})$
- 3) Choose region B_{i_3} that maximizes $I(A, B_{i_3}|B_{i_1} B_{i_2})$
- \vdots
- $|Q|$) Choose region $B_{i_{|Q|}}$ that maximizes $I(A, B_{i_{|Q|}}|B_{i_1} \dots B_{i_{|Q|-1}})$



By chain rule of mutual information,

$$I(A, B_{i_1}) + I(A, B_{i_2}|B_{i_1}) + \dots + I(A, B_{i_q}|B_{i_1} \dots B_{i_{q-1}}) = I(A, B_{i_1} \dots B_{i_q}) \leq 2 \log(d_A)$$

And by strong subadditivity, all terms are positive. So at least one term is small, i.e.

there is some value q' s.t. $I(A, B_{i_{q'}}|B_{i_1} \dots B_{i_{q'-1}}) \leq |Q|^{-1} 2 \log(d_A)$. Take $Q = B_{i_1} \dots B_{i_{q'-1}}$.



Diagram illustrating a quantum communication setup. A Bell pair is distributed between two parties. The left party has a system labeled "Identity" and a receiver labeled A' which is connected to a box labeled $\rho_{A's}$. The right party has a system labeled $N_{A=0}$ and a receiver labeled B .

$S(X) = -\text{Tr}(\rho_X \log \rho_X)$	(entropy) (how much there is to know about X)
$I(X, Y) = S(X) + S(Y) - S(XY)$	(mutual information) (how much knowing Y tells you about X)
$I(X, Y Z) = I(X, YZ) - I(X, Z)$	(conditional mutual information) (how much more knowing Y tells you about X than just knowing Y)

$S(X) = -\text{Tr}(\rho_X \log \rho_X)$	(entropy) (how much there is to know about X)
$I(X, Y) = S(X) + S(Y) - S(XY)$	(mutual information) (how much knowing Y tells you about X)
$I(X, Y Z) = I(X, YZ) - I(X, Z)$	(conditional mutual information) (how much more knowing Y tells you about X than just knowing Y)

For any state $\rho_{AB_1 \dots B_n}$, for any size q :

There exists region $Q \subset \{B_1, \dots, B_n\}$ of size $|Q| \leq q$ such that for all $B_i \in Q$:

$$I(A, B_i|Q) \leq \frac{1}{q} 2 \log(d_A).$$

Constructive proof: Build up Q by expanding it one by one.

- 1) Choose region B_1 that maximizes $I(A, B_1 | B_2)$
- 2) Choose region B_2 that maximizes $I(A, B_1 | B_2)$
- 3) Choose region B_3 that maximizes $I(A, B_1 | B_2 | B_3)$

⋮

Ⓚ) Choose region $B_{|Q|}$ that maximizes $I(A, B_1 | B_2 | \dots | B_{|Q|})$

By chain rule of mutual information.

$$I(A, B_1) + I(A, B_2 | B_1) + \dots + I(A, B_{|Q|} | B_1, \dots, B_{|Q|-1}) = I(A, B_1 - B_{|Q|}) \leq 2 \log(d_A)$$

And by strong subadditivity, all terms are positive. So at least one term is small, i.e. there is some value of $i \leq I(A, B_i | B_1, \dots, B_{i-1}) \leq |Q|^{-1} 2 \log(d_A)$. Take $Q = B_1 - B_{i-1}$.

For any state ρ_{A_1, \dots, A_n} , for any size q :
 There exists region $Q \subset \{B_1, \dots, B_n\}$ of size $|Q| \leq q$ such that for all $B_i \in Q$,

$$I(A_i, B_i | Q) \leq \frac{q}{n-2} \log(d_{A_i})$$

Visual constructive proof: To find the region Q , optimize over paths below:

Implications for many-body dynamics?

For any state $\rho_{AB_1 \dots B_n}$, for any size q :

There exists region $Q \subset \{B_1, \dots, B_n\}$ of size $|Q| \leq q$ such that for all $B_i \notin Q$,

$$I(A, B_i | Q) \leq \frac{1}{|Q|} 2 \log(d_A).$$

Constructive proof: Build up Q by expanding it one by one.

- 1) Choose region B_{i_1} that maximizes $I(A, B_{i_1})$
- 2) Choose region B_{i_2} that maximizes $I(A, B_{i_2} | B_{i_1})$
- 3) Choose region B_{i_3} that maximizes $I(A, B_{i_3} | B_{i_1}, B_{i_2})$

-
-
-

$|Q|$) Choose region $B_{i_{|Q|}}$ that maximizes $I(A, B_{i_q} | B_{i_1} \dots B_{i_{q-1}})$

By chain rule of mutual information,

$$I(A, B_{i_1}) + I(A, B_{i_2}|B_{i_1}) + \dots + I(A, B_{i_q}|B_{i_1} \dots B_{i_{q-1}}) = I(A, B_{i_1} \dots B_{i_q}) \leq 2 \log(d_A)$$

And by strong subadditivity, all terms are positive. So at least one term is small, i.e.

there is some value q' s.t. $I(A, B_{i_{q'}} | B_{i_1} \dots B_{i_{q'-1}}) \leq |Q|^{-1} 2 \log(d_A)$. Take $Q = B_{i_1} \dots B_{i_{q'-1}}$.

$$I(X, Y|Z) = I(X, YZ) - I(X, Z) \quad (\text{conditional mutual information})$$

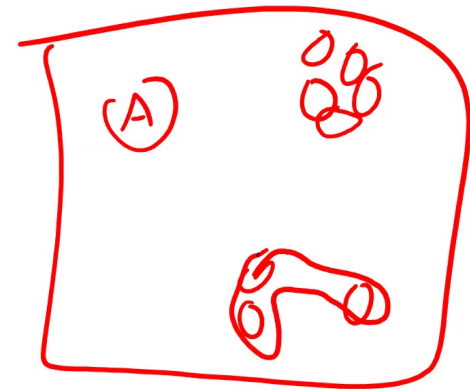
For any state $\rho_{AB_1 \dots B_n}$, for any size q :

There exists region $Q \subset \{B_1, \dots, B_n\}$ of size $|Q| \leq q$ such that for all $B_i \notin Q$,

$$I(A, B_i|Q) \leq \frac{1}{|Q|} 2 \log(d_A).$$

Constructive proof: Build up Q by expanding it one by one.

- 1) Choose region B_{i_1} that maximizes $I(A, B_{i_1})$
- 2) Choose region B_{i_2} that maximizes $I(A, B_{i_2}|B_{i_1})$
- 3) Choose region B_{i_3} that maximizes $I(A, B_{i_3}|B_{i_1} B_{i_2})$
- \vdots
- $|Q|$) Choose region $B_{i_{|Q|}}$ that maximizes $I(A, B_{i_q}|B_{i_1} \dots B_{i_{q-1}})$



By chain rule of mutual information,

$$I(A, B_{i_1}) + I(A, B_{i_2}|B_{i_1}) + \dots + I(A, B_{i_q}|B_{i_1} \dots B_{i_{q-1}}) = I(A, B_{i_1} \dots B_{i_q}) \leq 2 \log(d_A)$$

And by strong subadditivity, all terms are positive. So at least one term is small, i.e.

there is some value q' s.t. $I(A, B_{i_{q'}}|B_{i_1} \dots B_{i_{q'-1}}) \leq |Q|^{-1} 2 \log(d_A)$. Take $Q = B_{i_1} \dots B_{i_{q'-1}}$.

$$I(X, Y|Z) = I(X, YZ) - I(X, Z) \quad (\text{conditional mutual information})$$

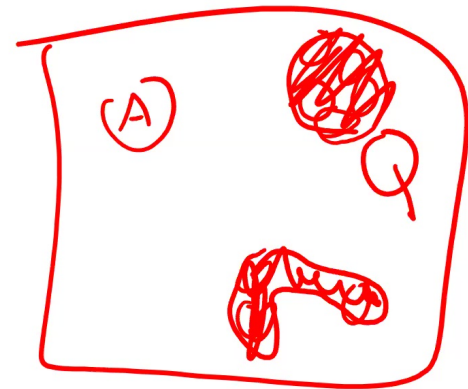
For any state $\rho_{AB_1 \dots B_n}$, for any size q :

There exists region $Q \subset \{B_1, \dots, B_n\}$ of size $|Q| \leq q$ such that for all $B_i \notin Q$,

$$I(A, B_i|Q) \leq \frac{1}{|Q|} 2 \log(d_A).$$

Constructive proof: Build up Q by expanding it one by one.

- 1) Choose region B_{i_1} that maximizes $I(A, B_{i_1})$
- 2) Choose region B_{i_2} that maximizes $I(A, B_{i_2}|B_{i_1})$
- 3) Choose region B_{i_3} that maximizes $I(A, B_{i_3}|B_{i_1} B_{i_2})$
- \vdots
- $|Q|$) Choose region $B_{i_{|Q|}}$ that maximizes $I(A, B_{i_q}|B_{i_1} \dots B_{i_{q-1}})$



By chain rule of mutual information,

$$I(A, B_{i_1}) + I(A, B_{i_2}|B_{i_1}) + \dots + I(A, B_{i_q}|B_{i_1} \dots B_{i_{q-1}}) = I(A, B_{i_1} \dots B_{i_q}) \leq 2 \log(d_A)$$

And by strong subadditivity, all terms are positive. So at least one term is small, i.e. there is some value q' s.t. $I(A, B_{i_{q'}}|B_{i_1} \dots B_{i_{q'-1}}) \leq |Q|^{-1} 2 \log(d_A)$. Take $Q = B_{i_1} \dots B_{i_{q'-1}}$.

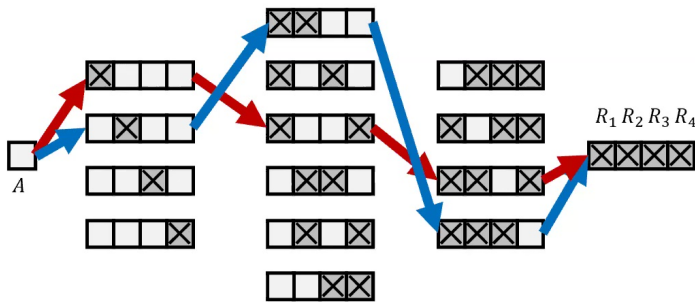
$$I(X, Y|Z) = I(X, YZ) - I(X, Z) \quad (\text{conditional mutual information})$$

For any state $\rho_{AB_1 \dots B_n}$, for any size q :

There exists region $Q \subset \{B_1, \dots, B_n\}$ of size $|Q| \leq q$ such that for all $B_i \notin Q$,

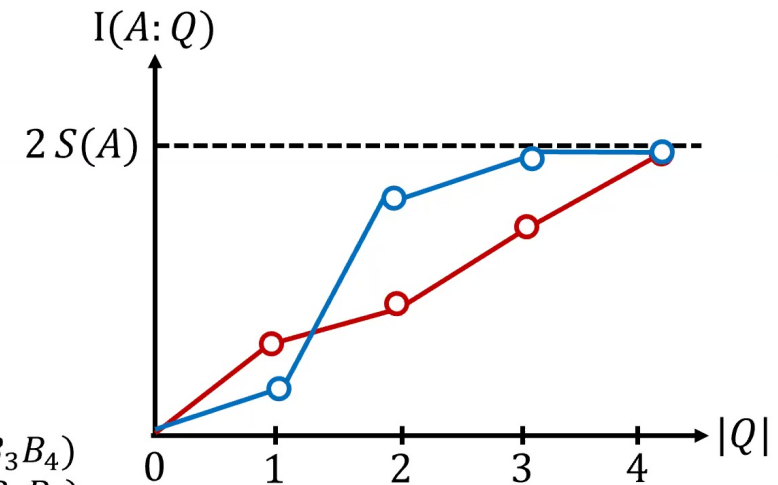
$$I(A, B_i|Q) \leq \frac{1}{|Q|} 2 \log(d_A).$$

Visual constructive proof: To find the region Q , optimize over paths below.



$$\begin{aligned} I(A: B_1) + I(A: B_4|B_1) + I(A: B_2|B_1 B_4) + I(A: B_3|B_1 B_4 B_2) &= I(A: B_1 B_2 B_3 B_4) \\ I(A: B_2) + I(A: B_1|B_2) + I(A: B_3|B_2 B_1) + I(A: B_4|B_2 B_1 B_3) &= I(A: B_1 B_2 B_3 B_4) \\ &= 2 S(A) \text{ (if pure)} \end{aligned}$$

Each node is a candidate region Q . Arrows indicate inclusions. Each path is an expanding subset of outputs. Strategy: **Gradually expand Q to learn as much as possible about A , until further expansion yields no further knowledge. Stop there to obtain final Q .**



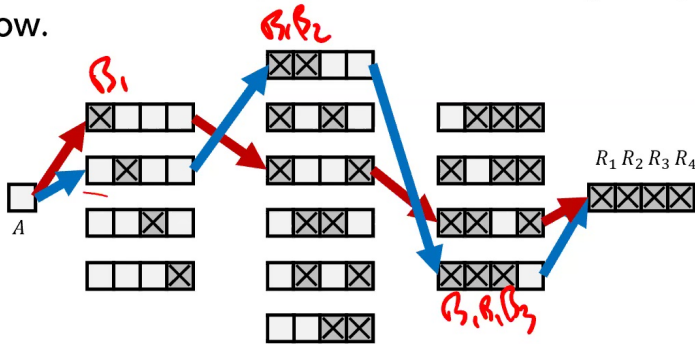
$$I(X, Y|Z) = I(X, YZ) - I(X, Z) \quad (\text{conditional mutual information})$$

For any state $\rho_{AB_1 \dots B_n}$, for any size q :

There exists region $Q \subset \{B_1, \dots, B_n\}$ of size $|Q| \leq q$ such that for all $B_i \notin Q$,

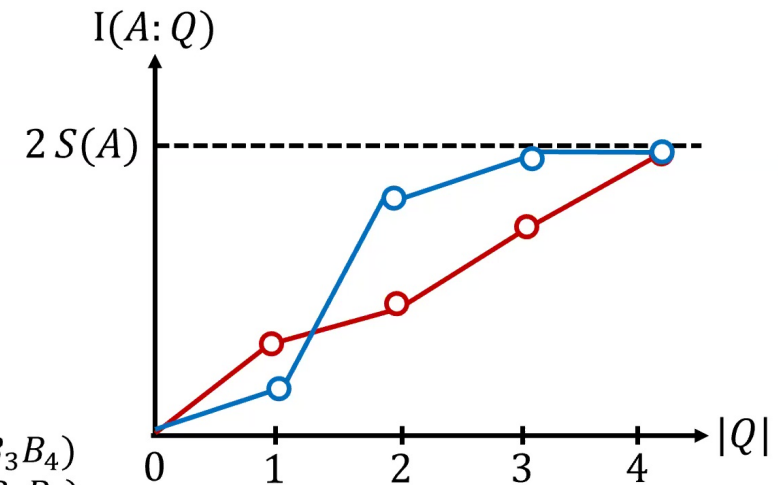
$$I(A, B_i|Q) \leq \frac{1}{|Q|} 2 \log(d_A).$$

Visual constructive proof: To find the region Q , optimize over paths below.



$$\begin{aligned} I(A: B_1) + I(A: B_4|B_1) + I(A: B_2|B_1B_4) + I(A: B_3|B_1B_4B_2) &= I(A: B_1B_2B_3B_4) \\ I(A: B_2) + I(A: B_1|B_2) + I(A: B_3|B_2B_1) + I(A: B_4|B_2B_1B_3) &= I(A: B_1B_2B_3B_4) \\ &= 2S(A) \text{ (if pure)} \end{aligned}$$

Each node is a candidate region Q . Arrows indicate inclusions. Each path is an expanding subset of outputs. Strategy: **Gradually expand Q to learn as much as possible about A , until further expansion yields no further knowledge. Stop there to obtain final Q .**



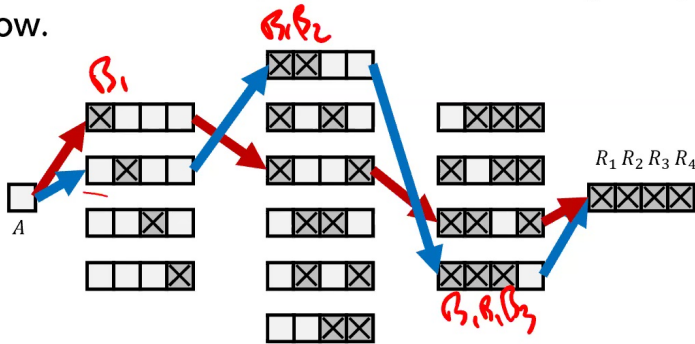
$$I(X, Y|Z) = I(X, YZ) - I(X, Z) \quad (\text{conditional mutual information})$$

For any state $\rho_{AB_1 \dots B_n}$, for any size q :

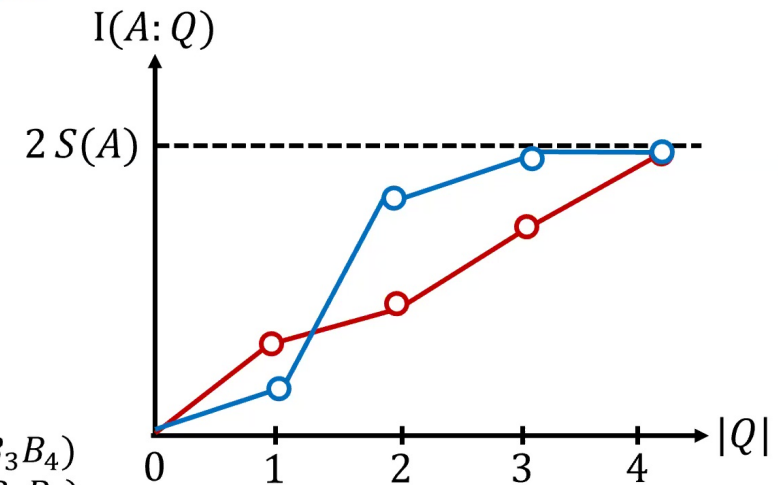
There exists region $Q \subset \{B_1, \dots, B_n\}$ of size $|Q| \leq q$ such that for all $B_i \notin Q$,

$$I(A, B_i|Q) \leq \frac{1}{|Q|} 2 \log(d_A).$$

Visual constructive proof: To find the region Q , optimize over paths below.



$$\begin{aligned} I(A: B_1) + I(A: B_4|B_1) + I(A: B_2|B_1 B_4) + I(A: B_3|B_1 B_4 B_2) &= I(A: B_1 B_2 B_3 B_4) \\ I(A: B_2) + I(A: B_1|B_2) + I(A: B_3|B_2 B_1) + I(A: B_4|B_2 B_1 B_3) &= I(A: B_1 B_2 B_3 B_4) \\ &= 2 S(A) \text{ (if pure)} \end{aligned}$$

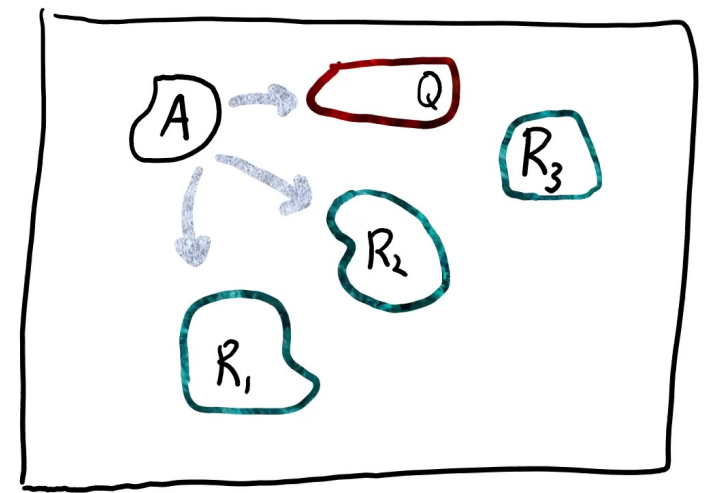


Each node is a candidate region Q . Arrows indicate inclusions. Each path is an expanding subset of outputs. Strategy: **Gradually expand Q to learn as much as possible about A , until further expansion yields no further knowledge. Stop there to obtain final Q .**

Implications for many-body dynamics?

Constructive method identifies “basis” $\{M^\alpha\}$ on A that is effectively measured/decohered by the rest of the system.

Helps identify emergent classical variables in many-body systems?

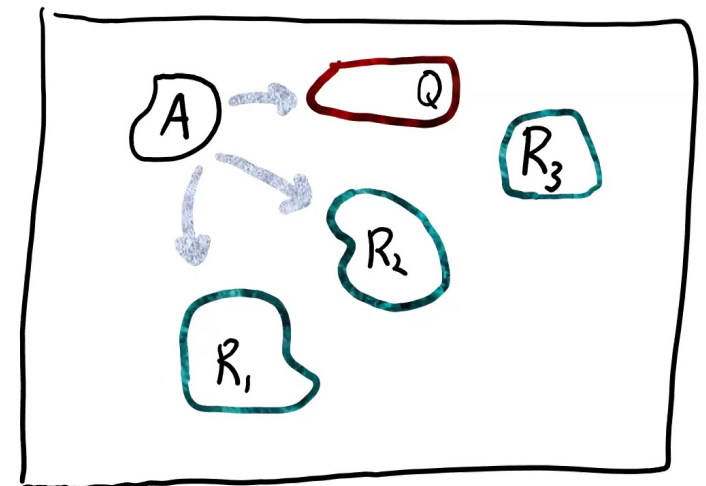


Implications for many-body dynamics?

Example: Hydrodynamics

In charge-conserving random circuits, the observable “measured” on A roughly coincides with the charge (confirmed numerically).

Explore more examples? Apply analysis where we don't already understand what's going on?



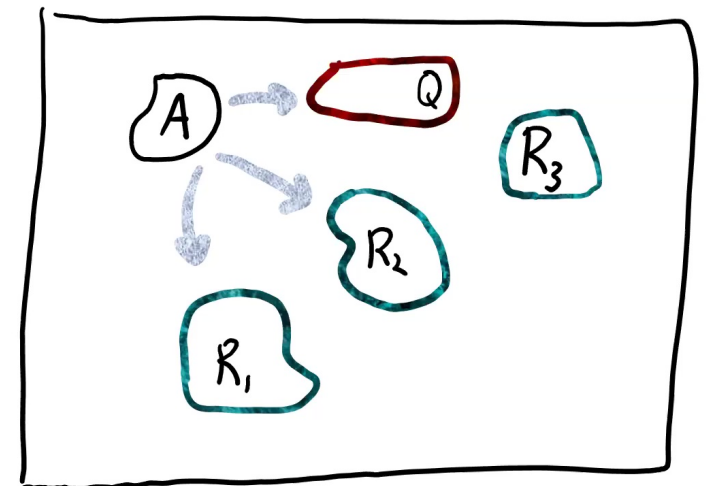
Implications for many-body dynamics?

Example: Hydrodynamics



In charge-conserving random circuits, the observable “measured” on A roughly coincides with the charge (confirmed numerically).

Explore more examples? Apply analysis where we don't already understand what's going on?



Future work

- How tight is the bound? How can it be improved when assuming additional structure to the dynamics, like spatial geometry or local conserved quantities?
- Compatibility theory
- What many-body examples can we explore?
- Use algorithm to identify emergent classical variables in many-body systems?

Future work

- How tight is the bound? How can it be improved when assuming additional structure to the dynamics, like spatial geometry or local conserved quantities?

- Compatibility theory

$$\begin{array}{l} N_1: A \longrightarrow B_1 \\ N_2: A \longrightarrow B_2 \end{array}$$

- What many-body examples can we explore?
- Use algorithm to identify emergent classical variables in many-body systems?

Future work

- How tight is the bound? How can it be improved when assuming additional structure to the dynamics, like spatial geometry or local conserved quantities?

- Compatibility theory

$$\begin{array}{l} N_1: A \longrightarrow B_1 \\ N_2: A \longrightarrow B_2 \end{array}$$

- What many-body examples can we explore?

$$N: A \longrightarrow B_1 B_2$$

- Use algorithm to identify emergent classical variables in many-body systems?

Thank you!