

Title: Special Topics in Astrophysics - Numerical Hydrodynamics - Lecture 19

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Collection: Special Topics in Astrophysics - Numerical Hydrodynamics

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6.1 Roe's Riemann solver

Idea: replace actual Riemann problem by an approximate linearized problem defined locally at each cell

Def: (Riemann solver of Roe):

$$\text{Replace } u_t + f(u)_x = 0$$

$$u(x,0) = \begin{cases} u_L = u_{i-1}^n & x < 0 \\ u_R = u_i^n & x > 0 \end{cases}$$

by the linear problem

$$w_t + A_{LR} w_x = 0$$

$$w(x,0) = \begin{cases} w_L & x < 0 \\ w_R & x \geq 0 \end{cases}$$

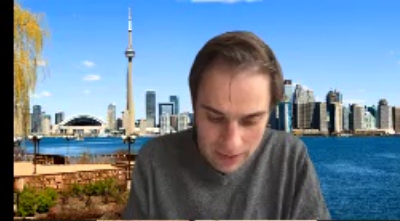




where $A_{Lr} = A(u_L, u_R) \in \text{Mat}(\mathbb{R}^{m \times m})$
satisfies the conditions

- (i) $f(v) - f(w) = A(v, w)(v - w)$
(conservation across discontinuities)
- (ii) $\|A(v, w) - Df(v)\| \rightarrow 0$ as $\|w - v\| \rightarrow 0$
(consistency with the exact Jacobian)
- (iii) $A(v, w)$ has only real eigenvalues
and a complete set of eigenvectors

The Roe scheme is defined by replacing the exact solution to the local RP in Godunov's method by the exact solution to (i).





Motivation:

- linearized problem justified at most cell interfaces

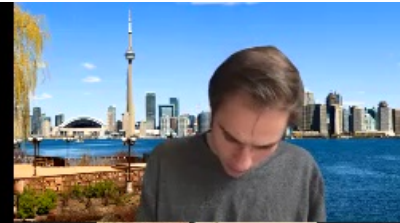
$$\|u_{i+1}^n - u_i^n\| \sim \mathcal{O}(\Delta x)$$

$$Df(u_{i+1}) \approx Df(u_i)$$

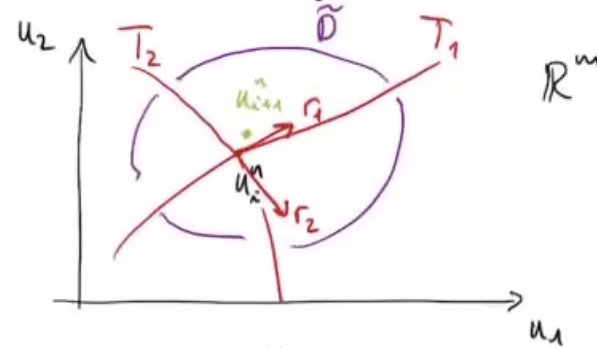
$$u_t + f(u)_x = 0 \quad \leadsto \quad u_t + \overbrace{Df(\bar{u})}^A u_x = 0$$

\uparrow const. matrix \bar{u} : some average state
 $\bar{u} = \bar{u}(u_{i+1}, u_i)$

State space: integral & shock sets
 need to connect u_{i+1}^n, u_i^n
 are nearly straight lines

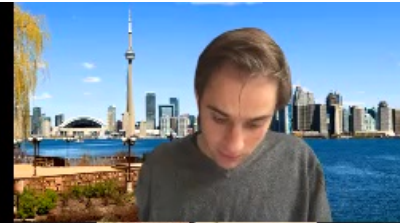


State space: integral & shock sets
 need to connect u_{i+1}^n, u_i^n
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$$u_{i+1}^n - u_i^n = \sum_{k=1}^m \alpha_k r_k$$

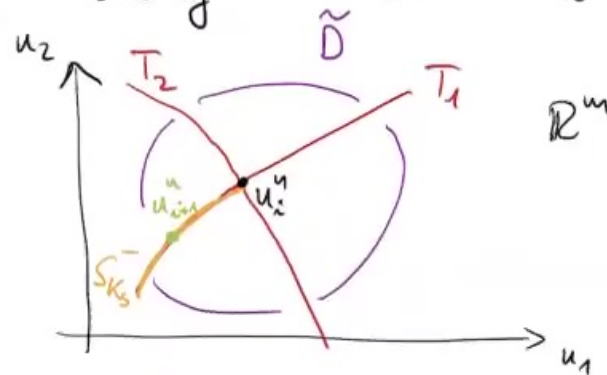
r_k eigenvectors of $Df(u_i^n)$
 (infinitesimal Riemann problem)
 linearized



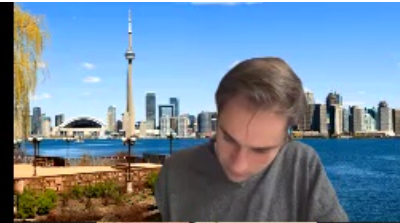


linearized

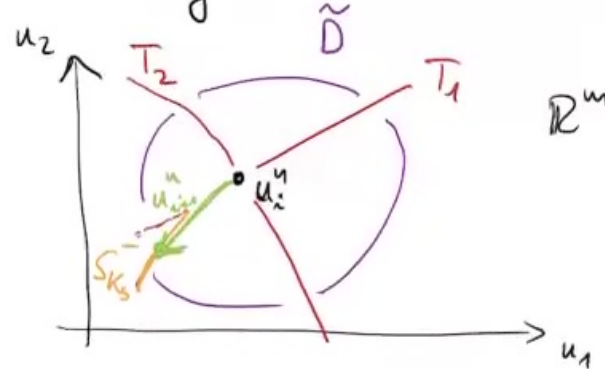
- near shocks: u_{i+1}^n, u_i^n may be separated for in state space at least in one direction $k=k_3$ along a shock set S_k^-



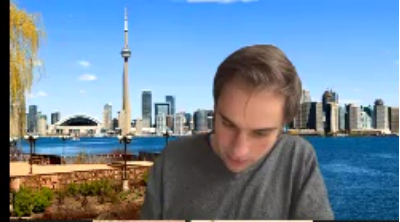
→ need to make sure that the corresponding single shock wave $w = u_{i+1}^n - u_i^n$ is an eigenvector of $A(u_i^n, u_{i+1}^n)$, so



- near success. u_{i+1}^n, u_i^n moving in separation for in state space at least in one direction $k = k_s$ along a shock set S_k^-



→ need to make sure that the corresponding single shock wave $w = u_{i+1}^n - u_i^n$ is an eigenvector of $A(u_i^n, u_{i+1}^n)$, so that the linearized problem "captures" the shock





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RH jump conditions: $f(v) - f(w) = s(v-w)$

Require $A(v,w)(v-w) \stackrel{!}{=} s(v-w) = f(v) - f(w)$

⇒ requirement (i)

Construction of $A(v,w)$:



Construction of $A(v,w)$:

- Considers the line integral along the path

$$u(\xi) = u_i^n + \underbrace{(u_{i+1}^n - u_i^n)}_{\text{change}} \xi, \quad 0 \leq \xi \leq 1$$

$$f(u_{i+1}) - f(u_i) = \int_0^1 \frac{df(u(\xi))}{d\xi} d\xi$$

$$= \int_0^1 Df(u(\xi)) u'(\xi) d\xi$$

$$= (u_{i+1}^n - u_i^n) \underbrace{\int_0^1 Df(u(\xi)) d\xi}_{= A(u_i, u_{i+1})}$$

→ satisfy





$$= (u_{i+1}^u - u_i^v) \int_0^1 Df(u(\xi)) d\xi$$

$$= A(u_i, u_{i+1})$$

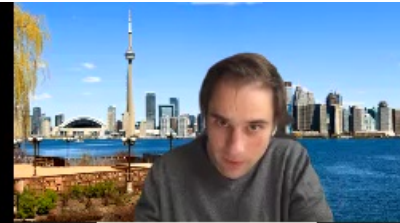
→ satisfy (i) & (ii), but (iii)
 is not necessarily guaranteed

- Roe (1981): introduce coordinate transform.
 $z(u)$

$$\text{path: } z(\xi) = z_i + (z_{i+1} - z_i)\xi, \quad z_i \equiv z(u_i)$$

$$\text{so } f(u_{i+1}) - f(u_i) = \int_0^1 \frac{df(z(\xi))}{d\xi} d\xi$$

=





$$\text{and } f(u_{i+1}) - f(u_i) = \int_0^1 \frac{df(z(\xi))}{d\xi} d\xi$$

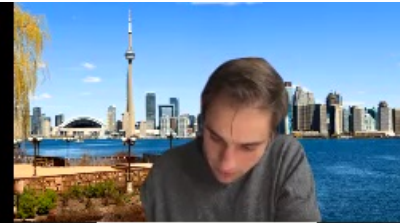
$$= (z_{i+1} - z_i) \int_0^1 \underbrace{Df_z(z(\xi))}_{\uparrow \text{wrt. to } z} d\xi$$

$$\equiv C(u_i, u_{i+1})$$

$$u_{i+1} - u_i = \int_0^1 \frac{du(z(\xi))}{d\xi} d\xi$$

$$= \int_0^1 \frac{du(z(\xi))}{dz} z'(\xi) d\xi$$

$$= (z_{i+1} - z_i) \underbrace{\int_0^1 \frac{du(z(\xi))}{dz} d\xi}_{\equiv B}$$



$$\begin{aligned}
 u_{i+1} - u_i &= \int_0^1 \frac{du(z(\zeta))}{d\zeta} d\zeta && \equiv C(u_i, u_{i+1}) \\
 &= \int_0^1 \frac{du(z(\zeta))}{dz} z'(\zeta) d\zeta \\
 \rightarrow &= (z_{i+1} - z_i) \underbrace{\int_0^1 \frac{du(z(\zeta))}{dz} d\zeta}_{\equiv B(u_i, u_{i+1})}
 \end{aligned}$$

$$\rightarrow A(u_i, u_{i+1}) \equiv C(u_i, u_{i+1}) B(u_i, u_{i+1})$$



$$\rightarrow = (z_{i+1} - z_i) \int_0^1 \frac{w(\zeta)}{dz} d\zeta$$

$$\equiv B(u_i, u_{i+1})$$

$$\Rightarrow A(u_i, u_{i+1}) \equiv C(u_i, u_{i+1}) B(u_i, u_{i+1})$$

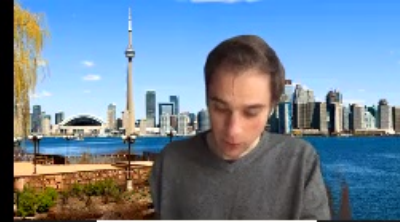
Harten, Lax, van Leer (1983): this procedure guarantees (iii) if the system has a entropy function $\bar{\Phi}$

$$\Rightarrow \text{choose } z(u) = \nabla \bar{\Phi}(u)$$

\uparrow wrt u

$\Rightarrow A = A_{HLL}$ is symmetric
 \rightarrow real eigenvalues

Proposition: Assume that there exists a matrix $A(u, w)$ as in the previous





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a matrix $A(v,w)$ as in the previous definition.
Then the Roe scheme as defined above
can be written in conservative form

$$w_i^{n+1} = w_i^n - \frac{\Delta t}{\Delta x} [g(w_i^n, w_{i+1}^n) - g(w_{i-1}^n, w_i^n)]$$



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$$w_i^{n+1} = w_i^n - \frac{\Delta t}{\Delta x} [g(w_i^n, w_{i+1}^n) - g(w_{i-1}^n, w_i^n)]$$

where the numerical flux g is given by

$$g(v,w) = \frac{1}{2} [f(v) + f(w)] - \frac{1}{2} \sum_{k=1}^m |\lambda_k| \alpha_k r_k$$

with (λ_k, r_k) being the eigenvalues and
eigenvectors of $A(v,w)$. The coefficients
("wave strengths") α_k are determined

$$w - v = \sum_{k=1}^m \alpha_k r_k$$

Proof: Toro Sec. 11.1





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Proof: Toro Sec. 11.1

Remarks: 1) Note that the exact solution to the linearized RP can be easily written down:

$$w(x,t) = \begin{cases} u_l & \frac{x}{t} < \lambda_1 \\ u_k & \lambda_k \leq \frac{x}{t} < \lambda_{k+1}, \\ u_r & \lambda_m \leq \frac{x}{t} \end{cases} \quad k = \{1, \dots, m-1\}$$





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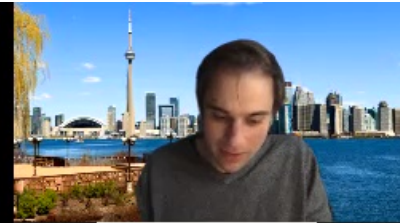
Proof: Toro Sec. 11.1

Remarks: 1) Note that the exact solution to the linearized RP can be easily written down:

$$w(x, t) = \begin{cases} u_e & \frac{x}{t} < \lambda_1 \\ u_k & \lambda_k \leq \frac{x}{t} < \lambda_{k+1}, \\ u_r & \lambda_m \leq \frac{x}{t} \end{cases} \quad k = \{1, \dots, m-1\}$$

where $u_k \equiv u_e + \sum_{j=1}^k \alpha_j r_j$, and α_j

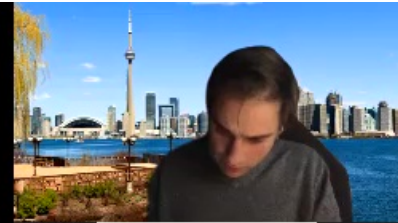
are given by $u - u_e = \sum_{j=1}^m \alpha_j r_j$





$$j=1$$

- 2) In general, the Roe scheme does not approximate the entropy solution
 → additional entropy "fixes" required (see Toro Sec. 11.4 Leveque 15.3)
- 3) Construction of $A(v,w)$ is complicated and expensive
 → Roe-Pike method (Toro Sec. 11.3) offer approach to compute all quantities needed for flux computation etc. without actually constructing $A(v,w)$



Roe's scheme for the Euler equations:

Consider $u_t + f(u)_x = 0$

Roe (1981): $z = \frac{u}{\sqrt{\beta}}$ and find that

$$A(u_l, u_r) = Df(\bar{u}), \quad \text{where}$$

$$\bar{u} = \begin{pmatrix} \bar{s} \\ \bar{s}\bar{u} \\ \bar{e} \end{pmatrix} \quad \text{and}$$

$$\bar{s} = \sqrt{\beta_l \beta_r}$$

$$\bar{u} = \frac{\sqrt{\beta_l} u_l + \sqrt{\beta_r} u_r}{\sqrt{\beta_l} + \sqrt{\beta_r}}$$

$$\bar{H} = \frac{\sqrt{\beta_l} H_l + \sqrt{\beta_r} H_r}{\sqrt{\beta_l} + \sqrt{\beta_r}}$$

$$H \equiv \frac{e+p}{s} \quad \text{specific enthalpy}$$

then $A(u_l, u_r)$ satisfies (i) - (iii).





then $A(u_{\epsilon}, u_r)$ satisfies (i) - (iii).

Remark: The Roe-scheme does not guarantee positive pressure and densities
 no cases in which $s < 0, p < 0$
 disadvantages for problems where low densities are expected

- additional fixed (Einfeldt et al. 1991)
- Einfeldt show that for certain Riemann problems there is no linearization that preserves positivity of s, e, p

