

Title: PSI 2019/2020 - Quantum Gravity Part 1 - Lecture 6

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Collection: PSI 2019/2020 - Quantum Gravity Part 1

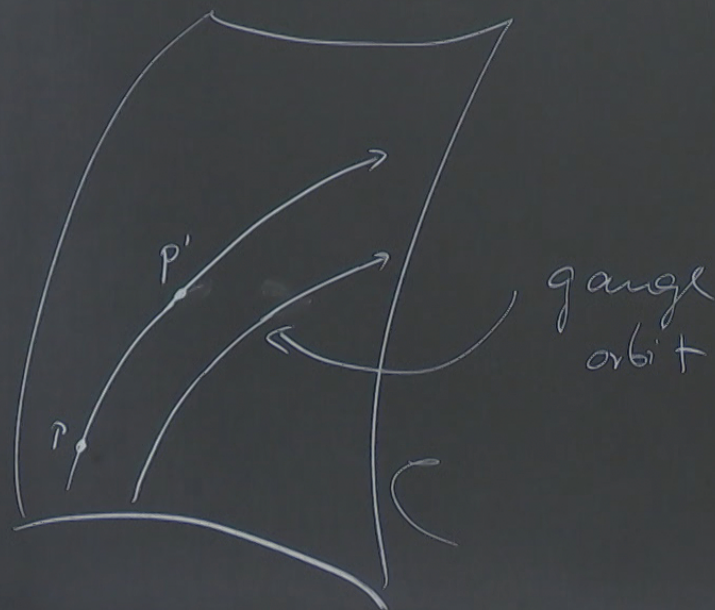
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Phase space for systems with

(First class) constraints

a) $\Rightarrow$ need to



for systems with (first class) constraints

$$\{C_I, C_J\} = f_{IJ}{}^K C_K$$

(First class) constraint

a) $\Rightarrow$ need to reduce to the constraint hypersurface

b) $\Rightarrow$ gauge symmetry: gauge orbits along hypersurface

constraints

$$f_I \partial^k C_k$$

$2n$ dim phase space

constant hypersurface $(2n - N)$ dim

gauge orbits along hypersurface N dim orbit. Need to quotient by gauge action.

(Reduced) phase space, $\Rightarrow (2n - 2N)$ dim

Physical

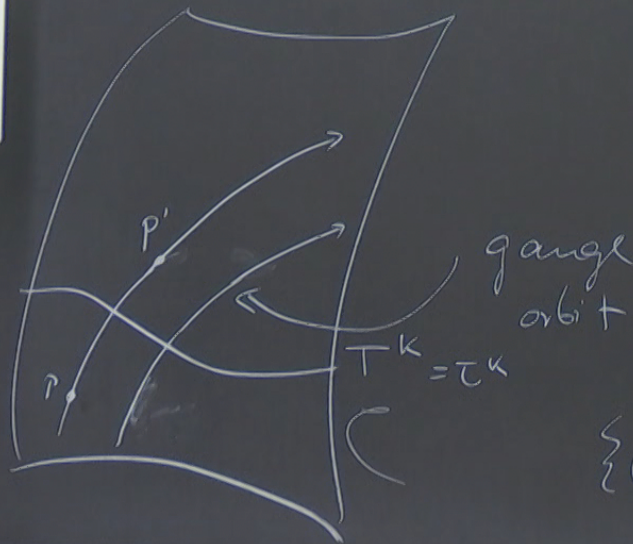
Phase space for systems with (first class)

$$\{C_I, C_J\}$$

(First class) constraints N

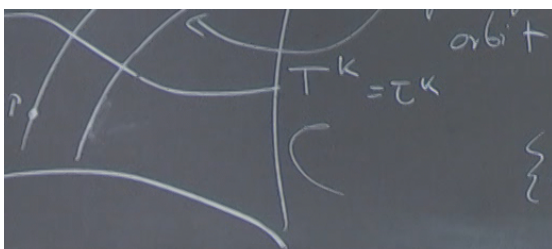
a) $\Rightarrow$ need to reduce to f

b) $\Rightarrow$ gauge symmetry:



$$\{C_K, T^J\} \neq 0$$

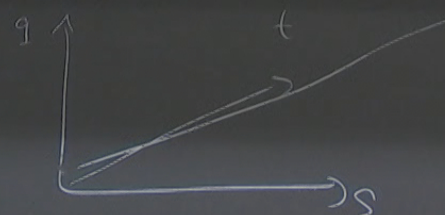
$$\begin{array}{l}
 \text{Physical} \\
 \text{Dirac}
 \end{array}
 \left\{ \begin{array}{l}
 \text{Observables } \mathcal{O}: \\
 \mathcal{O}, C_f
 \end{array} \right.
 \begin{array}{l}
 \{f, C_f\} \neq 0 \\
 \{ \mathcal{O}, C_f \} \approx 0
 \end{array}$$



$$\{C_k, T^k\} \neq 0$$

(Reduced) phase space,
Physical

7 Quantization of Gauge System



7.1 Example: The parametrized particle

Usual action: $S = \int L(q, \dot{q}) dt$

$$L = \frac{m}{2} \dot{q}^2 - V(q)$$

Configurations: $(t(s), q(s))$ s : evolution parameter

$$\mathbb{R} \\ (t(f(s)), q(f(s)))$$

$$S_p = \int L(q, \frac{q'}{t'}) t' ds$$

$$q' = \frac{dq}{ds} = \frac{dq(t(s))}{dt} \frac{dt(s)}{ds} = \dot{q} t'$$

$$dt = t' ds$$

• invariant under reparametrization s .

$$s \mapsto \tilde{s} = f(s)$$

Canonical Analysis

$$L_p = L(q, \frac{q'}{t'}) t', \quad (q, t)$$

Hamiltonian
for L
↓

$$P_t = \frac{\partial L_p}{\partial t'} = L - \frac{\partial L}{\partial \dot{q}} \left(\frac{q'}{t'} \right) = -(p_q \dot{q} - L) = -h(p_q, q)$$

$$P_q = \frac{\partial L_p}{\partial q'} = \frac{\partial L}{\partial \dot{q}} \frac{1}{t'} t' = m \frac{q'}{t'}$$

$$P_t = -h(p_q, q) \Rightarrow \text{constraint} \quad C = p_t + h(p_q, q)$$

$$P_q = m \frac{q'}{t'}$$

$$H = p_t t' + p_q q' - \underbrace{L}_{L_p} t' = \underbrace{t'}_N \underbrace{(p_t + h(p_q, q))}_C$$

$$t' = \{t, NC\}$$

$$q' = \{q, NC\}$$

$$= N \frac{\partial h(p_q, q)}{\partial p_q}$$

"Time" evolution is a gauge transformation

- Physical observables

$$\{F, C\} \approx 0$$

- Relational observables:

$F_f(\tau)$

parameter τ

phase space fct f

: value of f

• Time evolution

• Physical observables

$$\{F, C\} \approx 0$$

• Relational observables

$F_f(\tau)$: value of
 parameter
 phase space fct

$$F_f(\tau)_{p'} = f(p')$$

$$F_q(\tau) =$$

"Time" evolution is a gauge transformation

• Physical observables $\{F, C\} \approx 0$

• Relational observables

$F_f(\tau)$
 $\uparrow$ parameter
 $\uparrow$ phase space fct

: value of f for s where $t(s) = \tau$

$$\begin{array}{c} t(s) = \tau \rightarrow p' \\ (t) \rightarrow p = f(p') \end{array}$$

(free particle) $\rightarrow F_q(\tau) = q + \frac{p_q}{m}(\tau - t)$ $\{F_q(\tau), C\}$
 $F_{p_q}(\tau) = p_q$

$$F_t(\tau) = \tau$$

$$F_R(\tau) = -h(p_{q, \dot{q}})$$

$$= -\frac{p_q^2}{m}$$

s where $t(s) = \tau$

$$\{F_q(\tau), (\cdot)\}$$