

Title: PSI 2019/2020 - Standard Model and Beyond part 2 - Lecture 7

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Collection: PSI 2019/2020 - Standard Model and Beyond - Part 2

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SM+B #25

Grand Unification ($SO(10)$, $SU(5)$, Pati-Salam)

Baez + Huerta arXiv:0904.1556

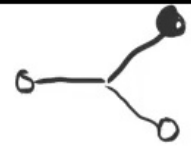
H. Freudenthal: "Lie Groups + Foundations of Geom." (1964)

J. Baez: "The Octonions" arXiv:math/0105155

P. Ramond: "Intro to Exceptional Lie Groups +
Lie Alg." (1978)

Barton + Sudbery: arXiv:math/0203010

Dubois-Violette + Todorov: arXiv:1808.08110

Triality: $SO(8)$


V, S^+, S^-

$g_1 \in SO(8) \begin{matrix} \nearrow g_1 V \\ \rightarrow g_2 S^+ \\ \searrow g_3 S^- \end{matrix}$

$IK \rightarrow \text{Tri}(IK)$:

$\text{Der}(IK): \underline{D}(xy) = \underline{D}(x)y + x\underline{D}(y) \leftarrow 0 \quad \forall x, y \in IK$

$\text{Tri}(IK): \underline{\underline{A}}(xy) = \underline{\underline{B}}(x)y + x\underline{\underline{C}}(y) \leftarrow \overbrace{(A, B, C)}^{(D, D, D)} \quad \forall x, y \in IK$

$(A, B, C) \quad (A', B', C')$

$(A+A', B+B', C+C') \quad ([A, A'], [B, B'], [C, C'])$

	$IK \neq \mathbb{R}$	$\mathbb{C}$	$\mathbb{H}$	$\mathbb{O}$
der IK	0	0	$su(2)$	$g_2 \leftarrow 14$
tri IK	0	$so(2)^2$	$su(2)^3$	$so(8) \leftarrow 28$

$$L(K_A, K_B) = \text{Der}(K_A) \oplus \text{Der}(K_B) \oplus A_3'(K_A \otimes K_B)$$

$$= \text{Tri}(K_A) \oplus \text{Tri}(K_B) \oplus \underbrace{(K_A \otimes K_B)}_{133} \oplus \underbrace{(K_A \otimes K_B)}_{H \otimes \mathbb{D}} \oplus \underbrace{(K_A \otimes K_B)}_{H \otimes \mathbb{D}}$$

	R	C	H	D
R				F_4
C				E_6
H				E_7
O	F_4	E_6	E_7	E_8

$\begin{pmatrix} 133 & H \otimes \mathbb{D} \end{pmatrix}$
 $9 + 28 + 32 \times 3$

$$\begin{aligned}
L(K_A, K_B) &= \text{Der}(K_A) \oplus \text{Der}(K_B) \oplus A'_3(K_A \otimes K_B) \\
&= \underbrace{\text{Tr}_i(K_A)}_{\psi} \oplus \underbrace{\text{Tr}_i(K_B)}_{\psi} \oplus \underbrace{(K_A \otimes K_B)}_1 \oplus \underbrace{(K_A \otimes K_B)}_2 \oplus \underbrace{(K_A \otimes K_B)}_3 \\
&\quad T_A = (\underline{T_{A_1}}, T_{A_2}, T_{A_3}) \quad T_B = (T_{B_1}, T_{B_2}, T_{B_3})
\end{aligned}$$

$$[T_A, (a \otimes b)_i] = ((T_{A_i} a) \otimes b)_i$$

$$[T_B, (a \otimes b)_i] = (a \otimes T_{B_i} b)_i$$

$$[(a \otimes b)_i, (a' \otimes b')_j] = (\bar{a}' \bar{a} \otimes \bar{b}' \bar{b})_k$$



$$H_3(1) \quad F_4 \begin{cases} \rightarrow \text{Spin}(9) \\ \rightarrow \frac{\text{su}(3) \times \text{su}(3)}{\mathbb{Z}_3} \end{cases} \left. \vphantom{\begin{matrix} \text{Spin}(9) \\ \frac{\text{su}(3) \times \text{su}(3)}{\mathbb{Z}_3} \end{matrix}} \right\} \frac{\text{su}(3) \times \text{su}(2) \times \text{u}(1)}{\mathbb{Z}_6}$$

$$①: G_2 \rightarrow \text{SU}(3)$$

I
↓

$$\begin{aligned} x &= a_0 1 + a_1 i + a_2 j + a_3 k + a_4 l + a_5 li + a_6 lj + a_7 lk \\ &= (a_0 + a_4 l) + (a_1 + a_5 l) i + (a_2 + a_6 l) j + (a_3 + a_7 l) k \\ &= m_0 1 + m_1 i + m_2 j + m_3 k \end{aligned}$$

$$m_0 + \begin{pmatrix} m_1 \\ m_2 \\ m_3 \end{pmatrix} \rightarrow m_0 + U \begin{pmatrix} m_1 \\ m_2 \\ m_3 \end{pmatrix} \quad UC$$

$$H_3(\mathbb{O}) \ni \begin{pmatrix} s_1 & m_3 & \bar{m}_2 \\ \bar{m}_3 & s_2 & m_1 \\ m_2 & \bar{m}_1 & s_3 \end{pmatrix} = \begin{pmatrix} s_1 & m_3 & \bar{m}_2 \\ \bar{m}_3 & s_2 & m_1 \\ m_2 & \bar{m}_1 & s_3 \end{pmatrix} + \overline{\begin{pmatrix} \vec{m}_1 & \vec{m}_2 & \vec{m}_3 \end{pmatrix}}$$

$$M_i = m_i + \begin{pmatrix} M_{i1} \\ M_{i2} \\ M_{i3} \end{pmatrix} \quad \uparrow \quad H_3(\mathbb{O}) \quad \quad \quad \uparrow \quad H_3(\mathbb{C}) \quad \quad \quad \uparrow \quad M_3(\mathbb{C})$$

$$= m_i + \vec{M}_i \quad \begin{matrix} U \rightarrow e^{2\pi i/3} U \\ V \rightarrow e^{2\pi i/3} V \end{matrix} \quad \begin{matrix} (X) \\ (Y) \end{matrix}$$

$$\underline{X} \rightarrow V X V^\dagger$$

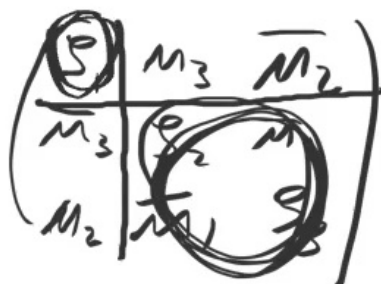
$$U, V \in SU(3)$$

$$\underline{Y} \rightarrow U Y V^\dagger$$

$$\underline{SU(3) \times SU(3)}$$

$$\begin{aligned}
 H_3(\mathbb{O}) &\ni \begin{pmatrix} s_1 & m_3 & \bar{m}_2 \\ \bar{m}_3 & s_2 & m_1 \\ m_2 & \bar{m}_1 & s_3 \end{pmatrix} = \begin{pmatrix} s_1 & m_3 & \bar{m}_2 \\ \bar{m}_3 & s_2 & m_1 \\ m_2 & \bar{m}_1 & s_3 \end{pmatrix} + \overline{\begin{pmatrix} \vec{m}_1 & \vec{m}_2 & \vec{m}_3 \end{pmatrix}} \\
 &= \begin{pmatrix} s_1 & m_3 & \bar{m}_2 \\ \bar{m}_3 & s_2 & m_1 \\ m_2 & \bar{m}_1 & s_3 \end{pmatrix} + \begin{pmatrix} \vec{m}_1 & \vec{m}_2 & \vec{m}_3 \end{pmatrix} \\
 \mu_i &= m_i + \begin{pmatrix} m_{i1} \\ m_{i2} \\ m_{i3} \end{pmatrix} \quad \uparrow \quad H_3(\mathbb{O}) \quad \uparrow \quad H_3(\mathbb{C}) \quad \uparrow \quad M_3(\mathbb{C}) \\
 &= m_i + \vec{M}_i \quad \begin{matrix} U \rightarrow e^{2\pi i/3} U \\ V \rightarrow e^{2\pi i/3} V \end{matrix} \quad \begin{matrix} (X) \\ (Y) \end{matrix} \\
 \underline{X} &\rightarrow V X V^\dagger \quad \underline{Y} \rightarrow U Y U^\dagger \\
 U, V &\in SU(3) \quad \underline{SU(3) \times SU(3)} \\
 &\quad \quad \quad \underline{\mathbb{Z}_3}
 \end{aligned}$$

$$\begin{pmatrix} s_1 & m_3 & \overline{m}_2 \\ \overline{m}_3 & s_2 & m_1 \\ m_2 & \overline{m}_1 & s_3 \end{pmatrix}$$



$$H_3(\mathbb{K}) \quad v = \dim(\mathbb{K})$$

$$H_2(\mathbb{K}) \cong J_{\text{spin}}(v+1)$$

$$H_2(\mathbb{C}) \cong J_{\text{spin}}(3)$$

$$H_2(\mathbb{O}) \cong J_{\text{spin}}(9) \rightarrow \text{spin}$$

$$X = \begin{pmatrix} s_1 & m_3 & \bar{m}_2 \\ \bar{m}_3 & s_2 & m_1 \\ m_2 & \bar{m}_1 & s_3 \end{pmatrix} \quad Y = (\vec{M}_1 \quad \vec{M}_2 \quad \vec{M}_3)$$

$$\underline{X \rightarrow VXV^\dagger} \quad \underline{Y \rightarrow UXV^\dagger}$$

$$U, V \in SU(3)$$

$$V = \begin{pmatrix} e^{-2i\alpha} & & \\ & 1 & \\ & & e^{i\alpha} \end{pmatrix} \leftarrow W$$

$$\frac{SU(3) \times SU(2) \times U(1)}{\mathbb{Z}_6}$$

$$U \rightarrow e^{2\pi i/3} U$$

$$V \rightarrow e^{2\pi i/3} V$$

$$W \rightarrow -W, e^{i\alpha} \rightarrow -e^{i\alpha}$$

$$\begin{aligned}
 H_3(\mathbb{O}) &\rightarrow \mathbb{O}P^2 \\
 H_2(\mathbb{O}) &\rightarrow M_{9,1} \\
 H_2(\mathbb{I}) &\rightarrow M_{3,1}
 \end{aligned}$$