

Title: PSI 2019/2020 - Chern-Simons Theory Part 1 - Lecture 9

Speakers: Kevin Costello

Collection: PSI 2019/2020 - Chern-Simons Theory (Part 1)

Date: March 02, 2020 - 11:30 AM

URL: <http://pirsa.org/20020032>

Last time

- Defined Kauffmann bracket

- Claim:

$$\int e^{\frac{i}{4\pi\hbar} CS(A)} W_K(A) = \langle K \rangle(x)$$

after

1) A

after.

1) A substitution of form $x = e^{\frac{c}{4\pi k}}$

2) Possibly normalizing by $x^{3wr(k)}$

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2) Possibly normalizing by $x^{3wr(K)}$



Witten remarks:

Every knot in S^3 or \mathbb{R}^3 has a canonical framing so that the self-linking vanishes.

If we use this framing, then $QFT \rightarrow$ a knot inv. (without framing worries)

Last time

- Defined Kauffmann bracket

- Claim

$$\int e^{\frac{1}{4\pi k} CS(A)} W_K(A) = \underbrace{x \langle K \rangle (x)}_{\text{normalized to be a knot invariant}}$$

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1) A s

2) Poss

Witt

Every
the set

If we

normalized to be a knot invariant if

Self-linking

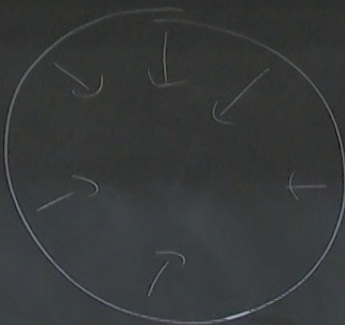
- Take a framed knot K
Displace it using normal vector,
to get K'
- Self-linking = $\text{Link}(K, K')$

normalized to be a knot invariant. If we use this for the self-linking

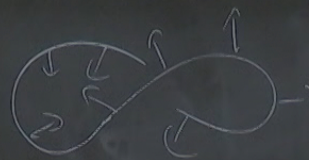
linking

can be not K
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$$\text{linking} = \text{Link}(K, K')$$



no self-linking

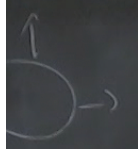


I think has
a self-linking.

invariant If we use this framing, then $QFT \rightarrow$ a knot inv. (without framing worries)

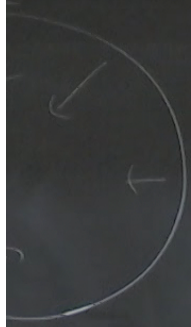
self-linking

$\langle \rangle$ is defined by

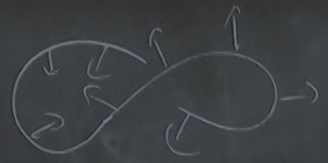
$$\langle \text{crossing} \rangle = x \langle \text{cup} \rangle + x^{-1} \langle \text{cap} \rangle$$


has self-linking

realized to be a knot invariant. If we use this framing, then $QFT \rightsquigarrow$ a knot inv. (with self-linking vanishes).



no self-linking

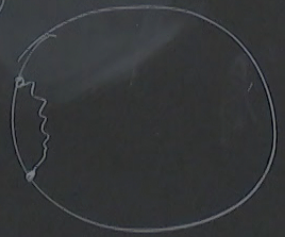


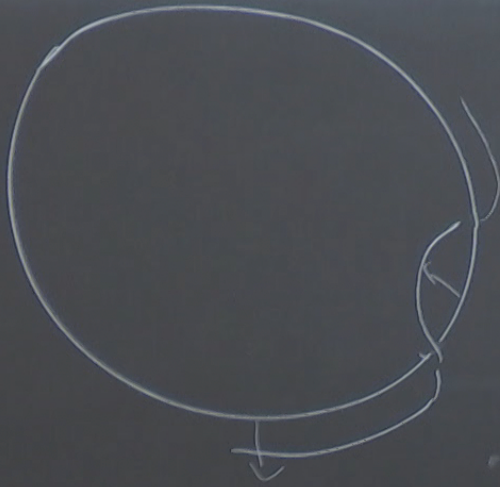
I think has a self-linking.

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Regularized version of for $U(1)$





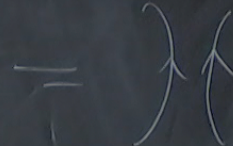


$$\frac{\Phi_m}{\Phi}$$

Why does Φ FT have any relation
(like

$$\langle \psi | \psi \rangle = x \langle \psi | \psi \rangle + x' \langle \psi | \psi \rangle ???$$

It turns out we get an equivalent knot invariant as follows.

Let $L_+ =$  $L_- =$  $L_0 =$ 

The Jones polynomial satisfies the local rule

$$t^{-1}J(L_+) - tJ(L_-) = (t^{1/2} - t^{-1/2})J(L_0)$$

This is the same as $(-x^{3wr}) \langle \rangle$ if $t^{-1/4} = x$

normalized to be a knot invariant

Every
the self
If we use

We would like to show that Φ FT increments satisfy same relation

$$\int e^{\frac{i}{4\pi k} \int \text{Tr}(S(A))} W_K(A) = x \underbrace{\langle K \rangle(x)}_{\text{normalized to be a knot invariant}}$$

Witten remarks:

Every knot in S^3 or \mathbb{R}^3 has the self-linking vanishes. If we use this framing, then

We would like to show that QFT invariants satisfy same relation
 This requires Axiomatic Topological Field Theory.
 Witten-Atiyah-Segal axioms for a 3d oriented TFT.

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- 2) If $\Sigma_1 \sqcup \Sigma_2$ is the disjoint union, $H(\Sigma_1 \sqcup \Sigma_2) = H(\Sigma_1) \otimes H(\Sigma_2)$.

Last time

- defined Kauffman bracket

$$W_K(A) = \alpha^{\text{sw}(k)} \langle K \rangle(\alpha)$$

normalized to be a knot invariant

after.

- 1) A substitution of form α
- 2) Possibly normalizing by α

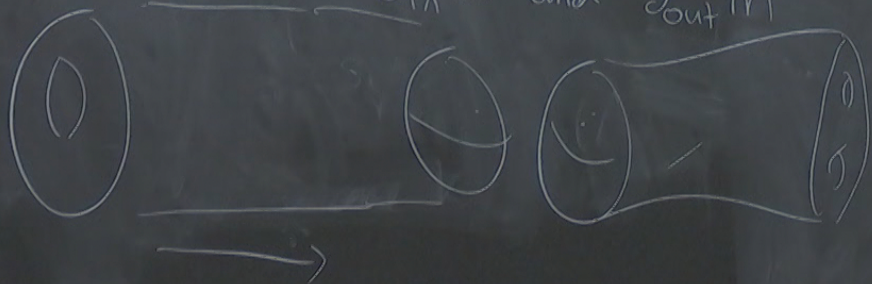
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Witten-Atiyah-Segal axioms for a 3d oriented TFT.

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3) If M is a 3-manifold
 (oriented) then,
 if $\partial M = \partial_{in} M$ and $\partial_{out} M$



then, $Z(M): H(\partial_{in} M) \rightarrow H(\partial_{out} M)$

4) Most important axiom:
 If M_1, M_2 , $\partial_{out} M_1 = \partial_{in} M_2$,
 then we can glue
 $M_1 \sqcup_{\partial_{out} M_1} M_2$

Witten-Atiyah-Segal axioms for a 3d oriented TFT.

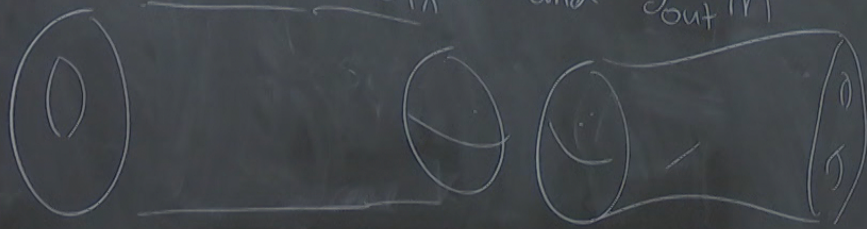
- 1) For every closed oriented surface, we have a vector space (the "Hilbert space") $H(\Sigma)$
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3) If M is a 3-manifold (oriented) then, if $\partial M = \partial_{in} M$ and $\partial_{out} M$

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4) Most important axiom: If $M_1, M_2, \partial_{out} M_1 = \partial_{in} M_2$

then we can glue $M_1 \sqcup_{\partial_{out} M_1} M_2$



Real Picture: $(D^2 \times S^1) \setminus (a \text{ ball})$

have a vector space (the "Hilbert space") $H(\Sigma)$.
 $H(\Sigma_1 \amalg \Sigma_2) = H(\Sigma_1) \otimes H(\Sigma_2)$

then, $Z(M): H(\partial_{in} M) \rightarrow H(\partial_{out} M)$

4) Most important axiom:

If $M_1 \supset M_2$, $\partial_{out} M_1 = \partial_{in} M_2$,

then we can glue
 $M_1 \amalg_{\partial_{out} M_1} M_2$ and,

$$Z(M_1 \amalg_{\partial_{out} M_1} M_2)$$

$$= Z(M_2) \circ Z(M_1)$$

$$: H(\partial_{in} M_1)$$

$$\longrightarrow H(\partial_{out} M_1) = H(\partial_{in} M_2)$$

$$\longrightarrow H(\partial_{out} M_2)$$

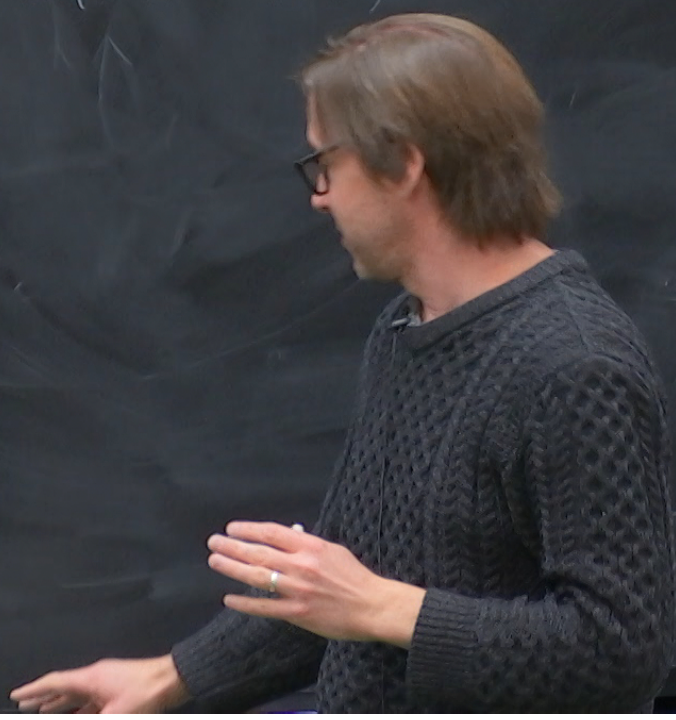
If $\bar{\Sigma} = \Sigma$ w. opposite orientations,
5) $H(\bar{\Sigma}) = H(\Sigma)^*$

If we like, can view all boundaries
as outgoing; this reverses orientation
on $\partial_{in} M$, so
 $Z(M) \in H(\partial_{in} M)^* \otimes H(\partial_{out} M)$

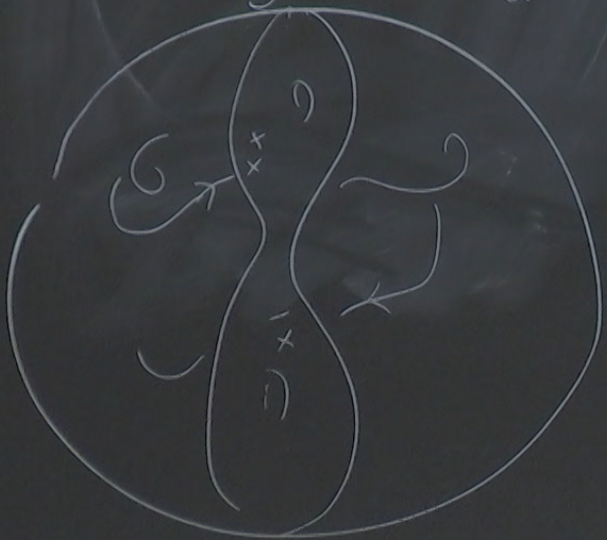
$$\sum \times I$$

w. 2 outgoing
boundaries

$$6) Z(M_1 \amalg M_2) = Z(M_1) \otimes Z(M_2)$$



Axioms for $3d$ TFT w. a $1d$ oriented defect:
Very similar except:



A link intersects Σ at points
which are labelled \pm , depending
on orientation of the link.

In this setting

effect:

- H is defined for
a surface Σ
with $n+m$ points, n +
 m -

depending

- M has a link w. boundary
on ∂M

$$Z(M, L): H(\partial_{\text{in}} M, \partial_{\text{in}} L) \rightarrow H(\partial_{\text{out}} M, \partial_{\text{out}} L)$$

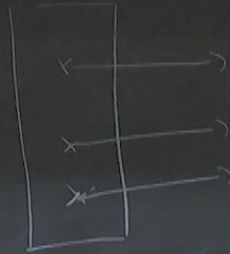
as before. All other axioms are the same,

$$H(\Sigma, \begin{matrix} n+ \\ m- \end{matrix}) = H(\overline{\Sigma}, \begin{matrix} n- \\ m+ \end{matrix})^*$$

Near b of m ,
 $m = \sum x [0, 1)$

Link looks like
 $p_1 \times [0, 1)$

\vdots
 $p_{n+m} \times [0, 1)$



$\partial \text{Link} = \text{points in } \Sigma$

Suppose we have a link in S^3 , focus near 1 crossing

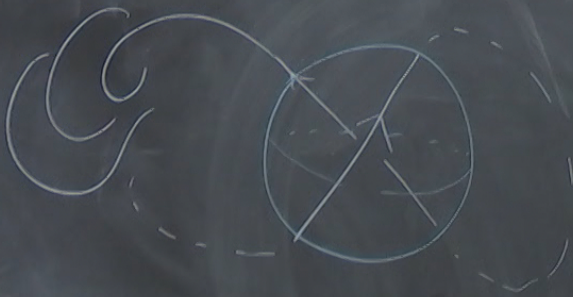
How do we understand

$Z(S^3, L)$ 'in terms of local data at crossing?'

$$S^3 = M_1 \cup M_2$$

$M_1 =$ a ball surrounding the crossing

$M_2 =$ complement of M_1



to at crossing?)

These are glued along
 $(S^2, P_+^1, P_+^2, P_-^1, P_-^2)$

$H(\Sigma_2)$

These are glued along
 $(S^2, p_+^1, p_+^2, p_-^1, p_-^2)$

at crossing?

$$Z(S^3, L) = \langle Z(M_2, L'), Z(M_1, \text{diagram}) \rangle$$

where

$$Z(M_1, \mathbb{R}) \in H(S^2, p_+^1, p_+^2, p_-^1, p_-^2)$$

$$Z(M_2, L) \in \text{dual vector space}$$

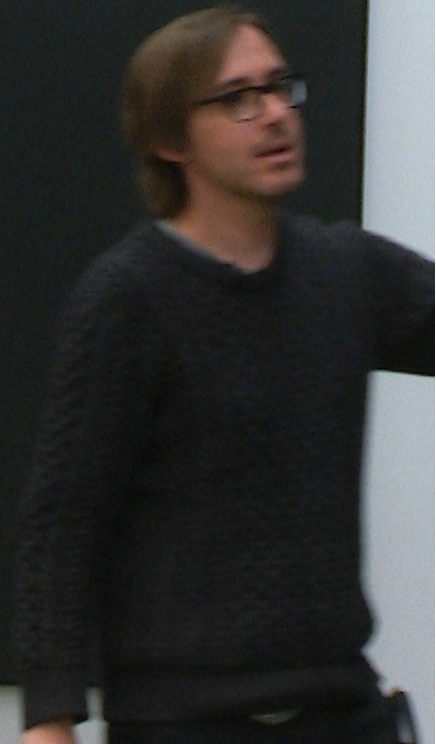
If we modify our L locally to

~~λ~~ or λf

then $Z(M, L_1), Z(M, L_0)$ has the same
expression where we replace $Z(\text{Ball}, \lambda)$
by $Z(\text{Ball}, \lambda)$ or $Z(\text{Ball}, \lambda f)$

$$Z(\phi) = \mathbb{C}$$
$$\partial M = \phi$$
$$Z(m) : \mathbb{C} \rightarrow \mathbb{C}$$

so it's a number



A Skein relation like in Jones poly. will hold.

If there are functions $F_+(h), F_-(h), F_0(h)$
so that

$$F_+(h) Z(\text{Ball}, \nearrow) + F_-(h) Z(\text{Ball}, \searrow) + F_0(h) Z(\text{Ball}, \uparrow) = 0$$
$$\in H(S^2, p_+^1, p_+^2, p_-^1, p_-^2)$$

$$6) Z(m_1 \parallel m_2)$$

Theorem

$H(S^2, P_1^+, P_2^+, P_1^-, P_2^-)$ is 2 dimensional

if $G = SU(n)$

and the defect is a Wilson line in fundamental representation