

Title: Accurately modelling extreme-mass-ratio inspirals: beyond the geodesic approximation

Speakers: Adam Pound

Series: Strong Gravity

Date: January 16, 2020 - 1:00 PM

URL: <http://pirsa.org/20010087>

Abstract: Recent observations of gravitational waves represent a remarkable success of our theoretical models of relativistic binaries. However, accurate models are largely restricted to binaries in which the two members have roughly equal masses; for binaries with more disparate masses, modelling is less mature. This is especially relevant for extreme-mass-ratio inspirals (EMRIs), in which a stellar-mass object orbits a supermassive black hole in a galactic core. EMRIs are uniquely precise probes of black hole spacetimes, and they will be key targets for the space-based detector LISA. They are best modelled by gravitational self-force theory, in which the smaller object generates a small gravitational perturbation that reacts back on it to exert a "self-force", accelerating the object away from geodesic motion. For LISA science, we must work to second order in this perturbative treatment. In this talk, I discuss the foundations of self-force theory, its application to EMRIs, and the current status of first- and second-order models.

# Accurately modelling extreme-mass-ratio inspirals: beyond the geodesic approximation

Adam Pound

Perimeter Institute

16 January 2020

UNIVERSITY OF  
Southampton





# Gravitational waves and binary systems

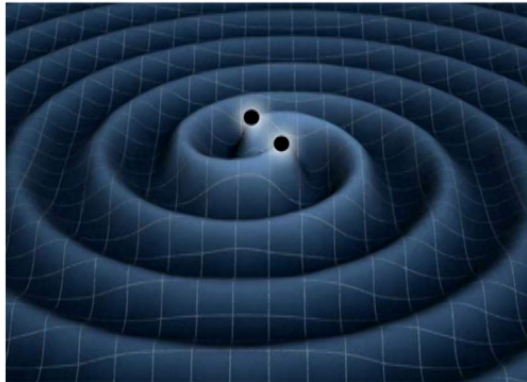


Image: NASA-GSFC/The Washington Post

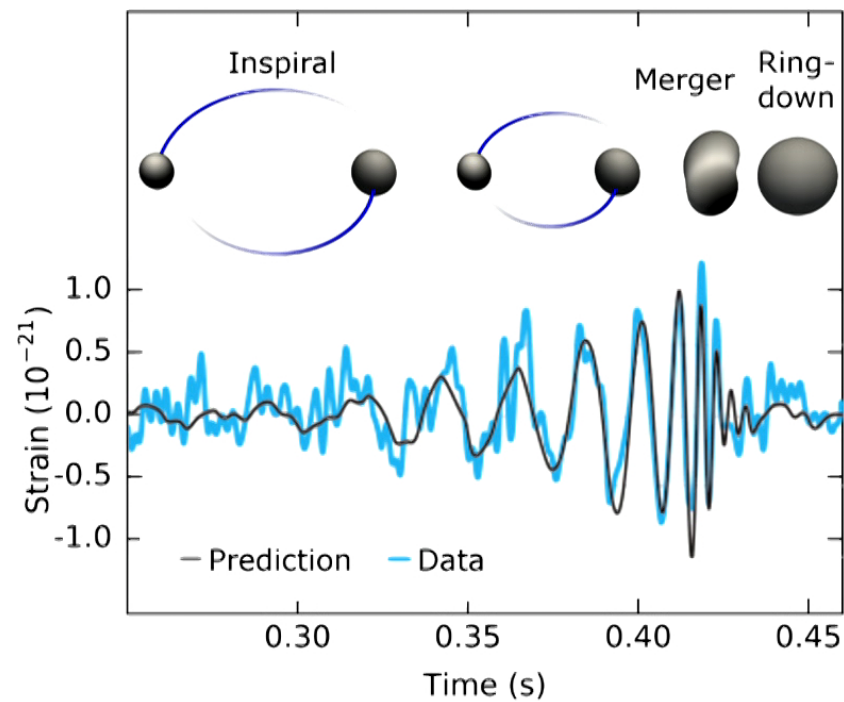
- compact objects (black holes or neutron stars) strongly curve the spacetime around them
- their motion in a binary generates gravitational waves, small ripples in spacetime

- waves propagate to detector
- to extract meaningful information from a signal, we require models that relate the waveform to the source



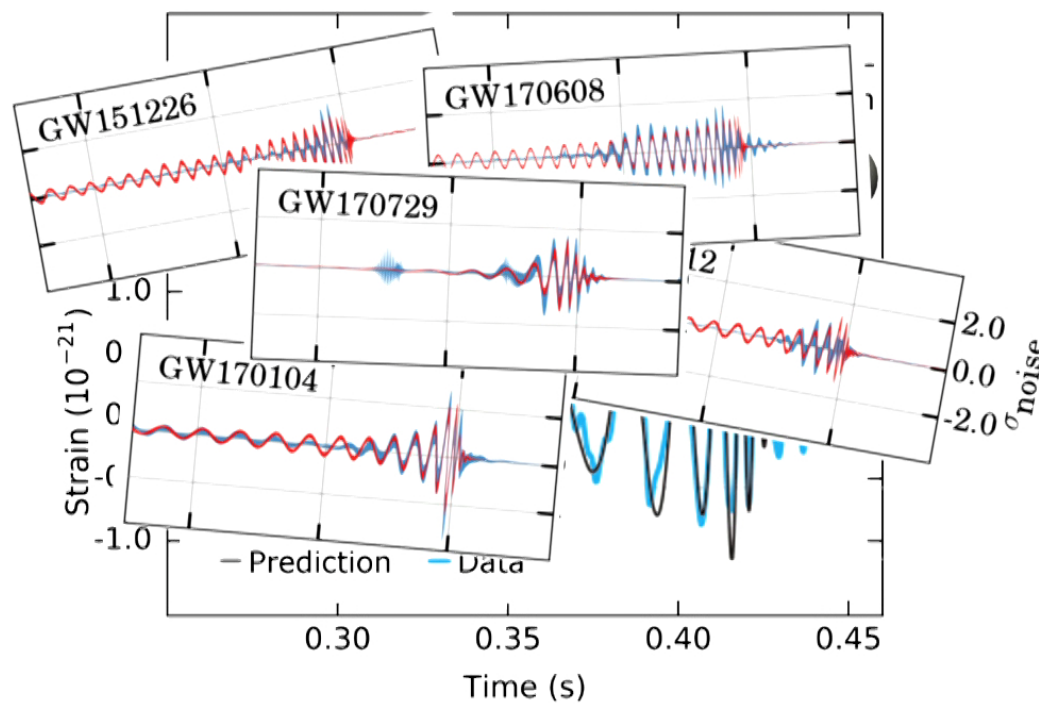
# Compact binary detections

Four years ago, LIGO first detected the gravitational waves from a black hole binary merger...



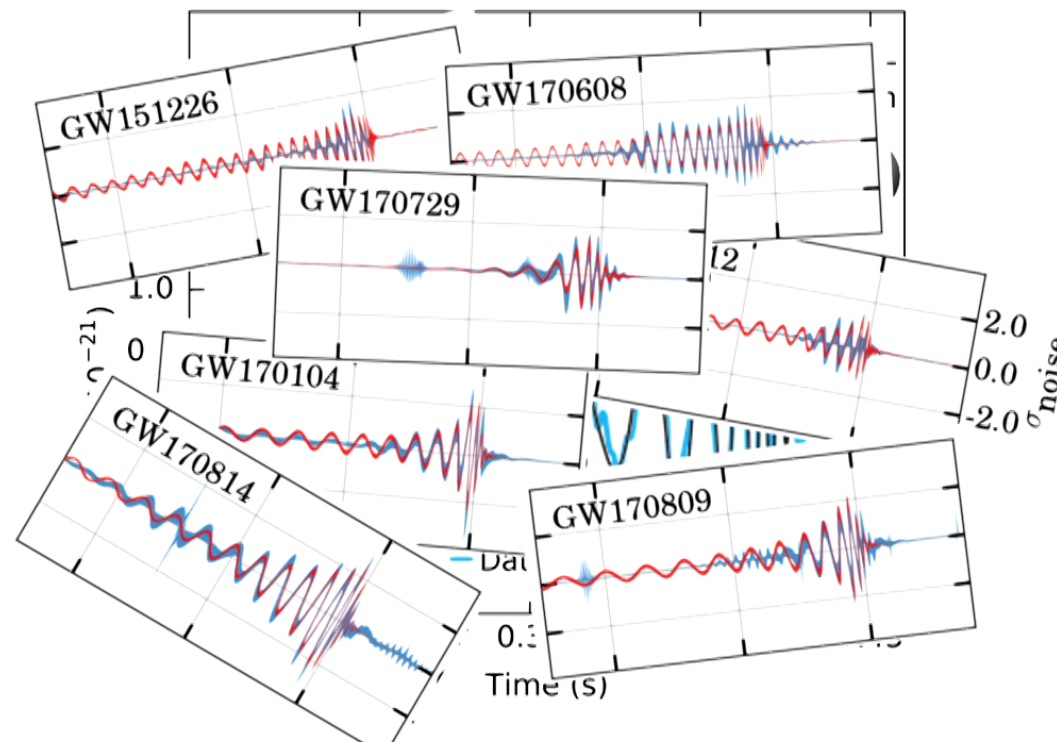
# Compact binary detections

Four years ago, LIGO first detected the gravitational waves from a black hole binary merger...



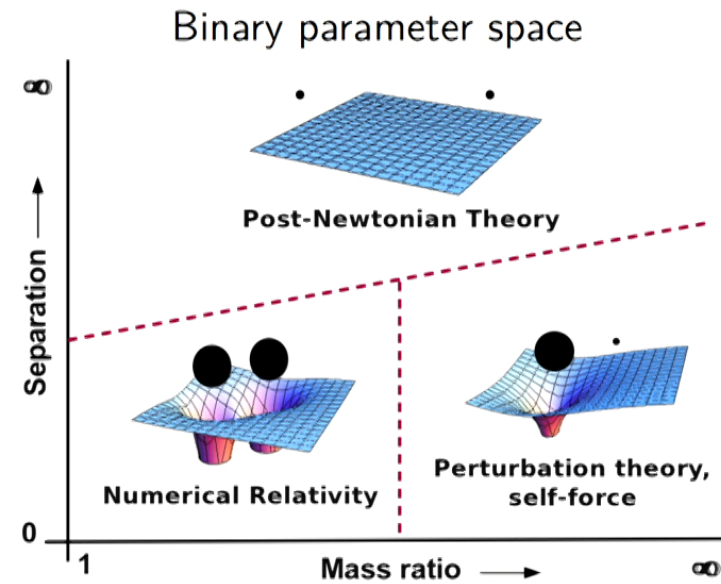
# Compact binary detections

Four years ago, LIGO first detected the gravitational waves from a black hole binary merger...



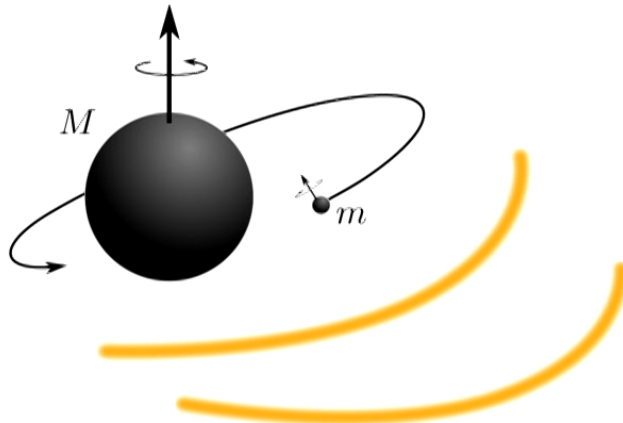
# Many types of binaries

- LIGO is only sensitive to comparable-mass binaries
- different classes of binaries will be observed by different detectors and tell us different things



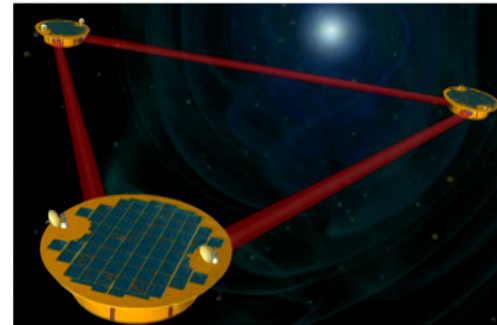
[Image courtesy of Leor Barack]

# Extreme-mass-ratio inspirals (EMRIs)

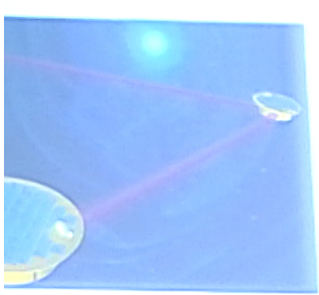


- space-based detector LISA will observe extreme-mass-ratio inspirals of stellar-mass BHs or neutron stars into massive BHs
- small object spends  $\sim M/m \sim 10^5$  orbits near BH  $\Rightarrow$  unparalleled probe of strong-field region around BH

- emitted waveforms are intricate and long-lived in the LISA band
- contain a wealth of information







16 January 2020 5 / 32

# EMRI science yield

## Fundamental physics

- measure central BH parameters: mass and spin to  $\sim .01\%$  error, quadrupole moment to  $\sim .1\%$   
 $\Rightarrow$  measure deviations from the Kerr relationship  $M_l + iS_l = M(ia)^l$   
 $\Rightarrow$  test no-hair theorem
- measure deviations from Kerr QNMs, presence or absence of event horizon, additional wave polarizations, changes to power spectrum
- constraints on modified gravity typically one or more orders of magnitude better than any other planned experiment

## Astrophysics

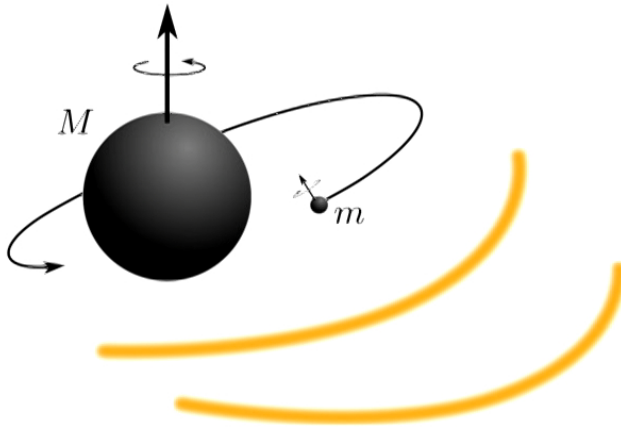
- constrain mass function  $n(M)$  (number of black holes with given mass)
- provide information about stellar environment around massive BHs

## Cosmology

- measure Hubble constant to  $\sim 1\%$

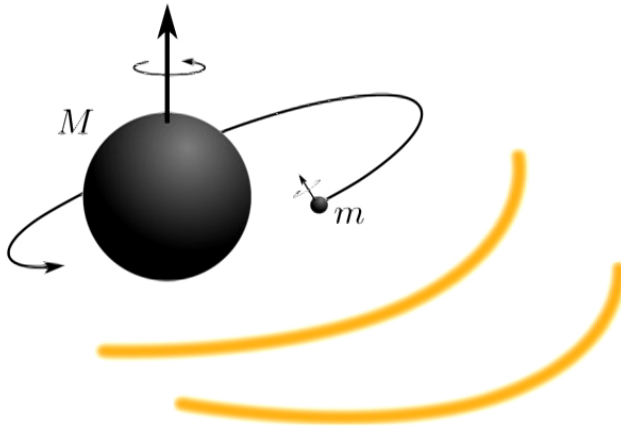


## EMRI modeling: why self-force?



- highly relativistic, strong fields
- disparate lengthscales
- long timescale: inspiral is slow, produces  $\sim \frac{M}{m} \sim 10^5$  wave cycles

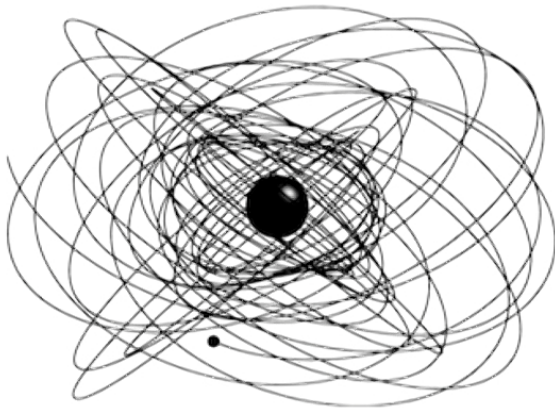
## EMRI modeling: why self-force?



- highly relativistic, strong fields  
 $\Rightarrow$  *can't use post-Newtonian theory*
- disparate lengthscales

- long timescale: inspiral is slow, produces  $\sim \frac{M}{m} \sim 10^5$  wave cycles

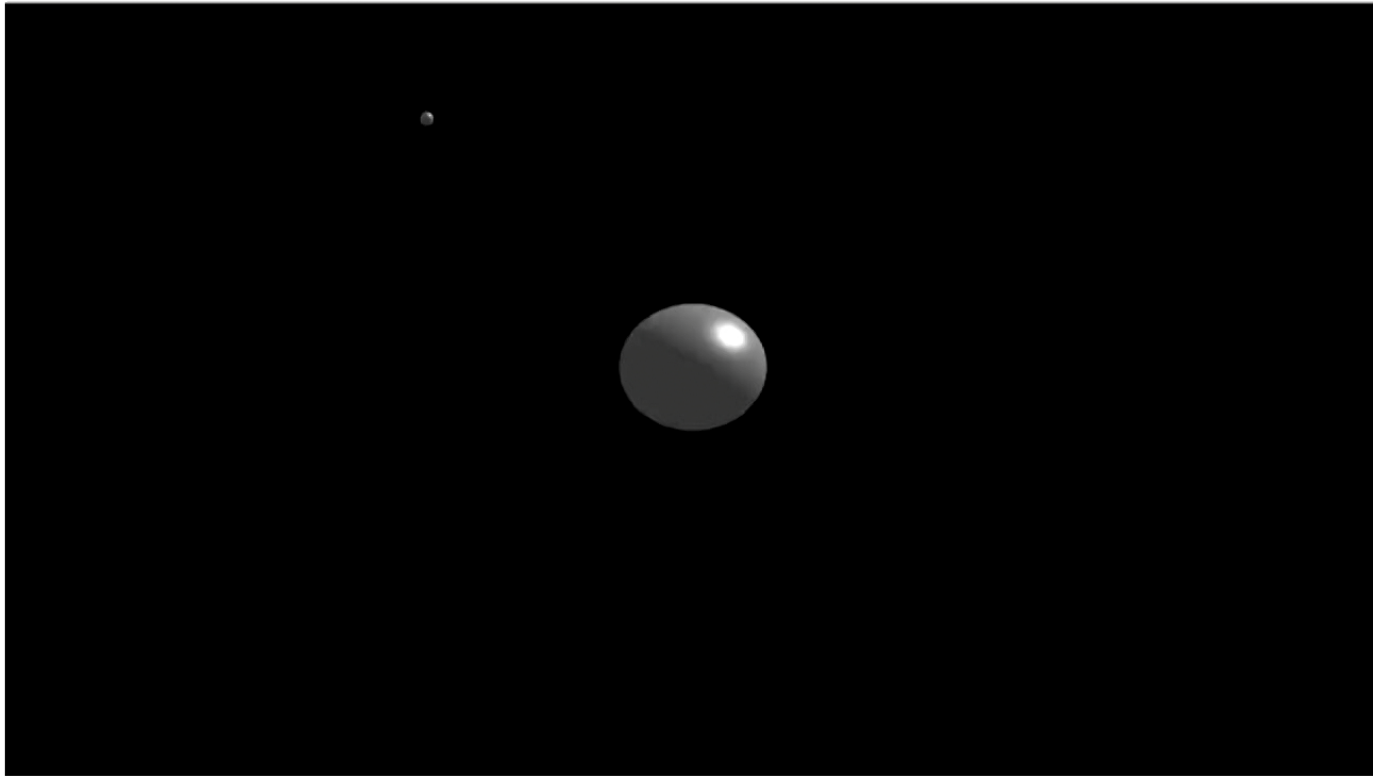
## Zeroth-order approx.: point mass on a geodesic in Kerr



[image courtesy of Steve Drasco]

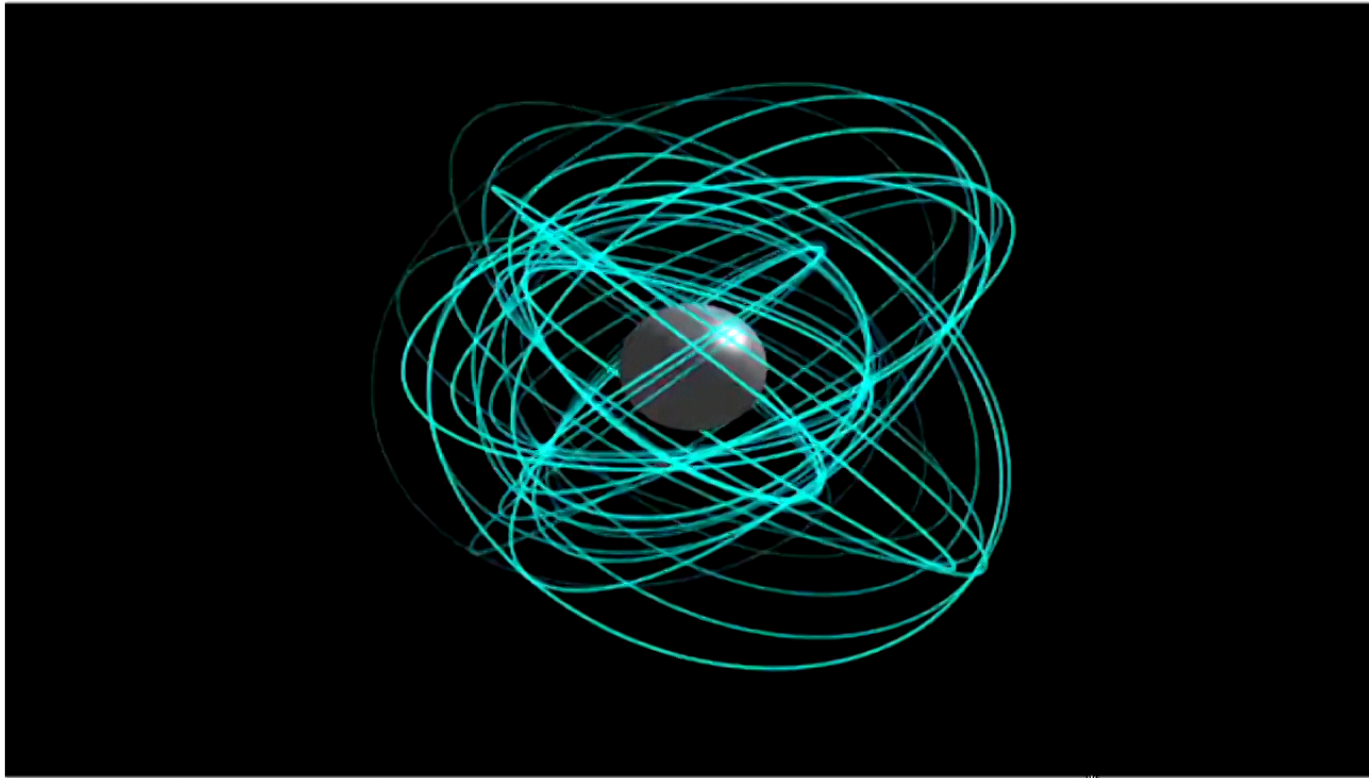
- geodesic characterized by three constants of motion:
  - ① energy  $E$
  - ② angular momentum  $L_z$
  - ③ Carter constant  $Q$ , related to orbital inclination
- $E, L_z, Q$  related to frequencies of  $r, \phi$ , and  $\theta$  motion
- emitted waveform has all harmonics of these frequencies
- (and *resonances* occur when two of the frequencies have a rational ratio)

But GWs carry off energy and ang. momentum, and the small object slowly spirals into the black hole...



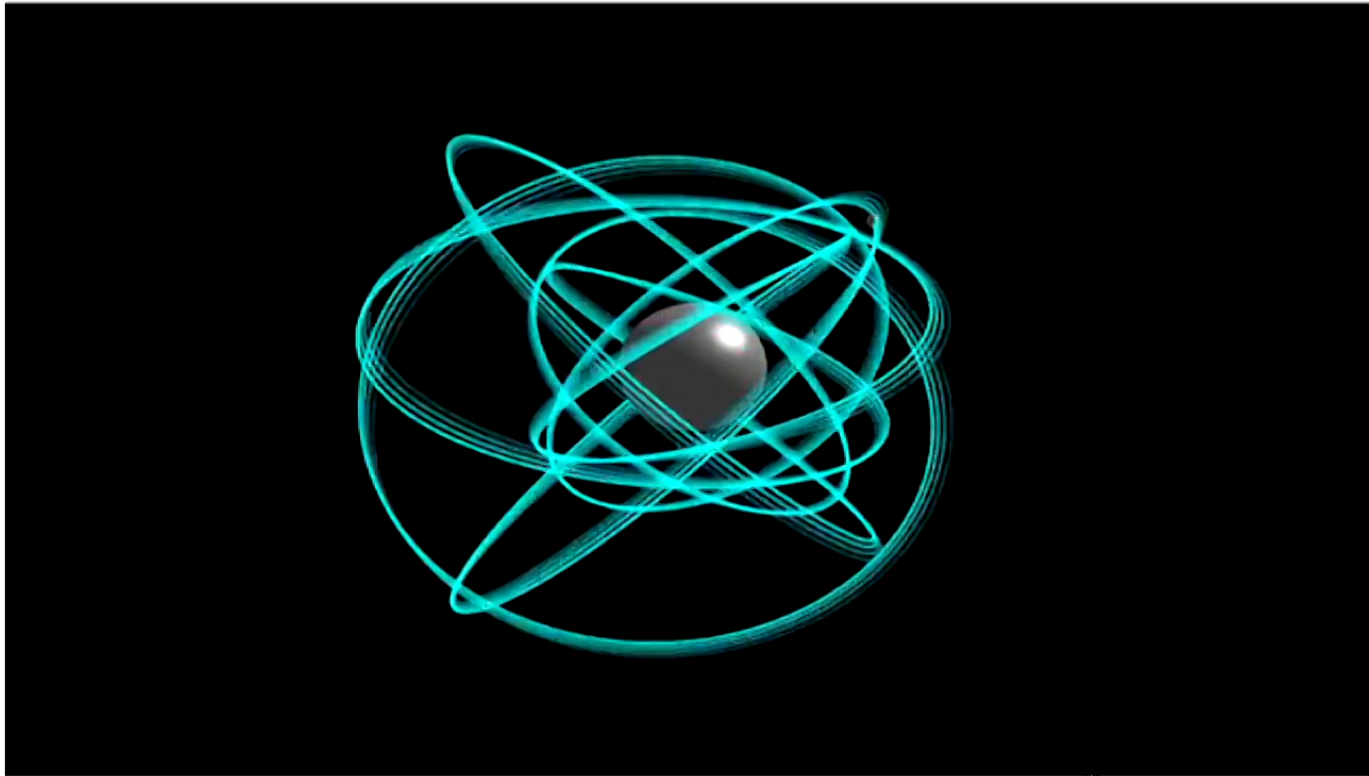
[animation courtesy of Steve Drasco]

But GWs carry off energy and ang. momentum, and the small object slowly spirals into the black hole...



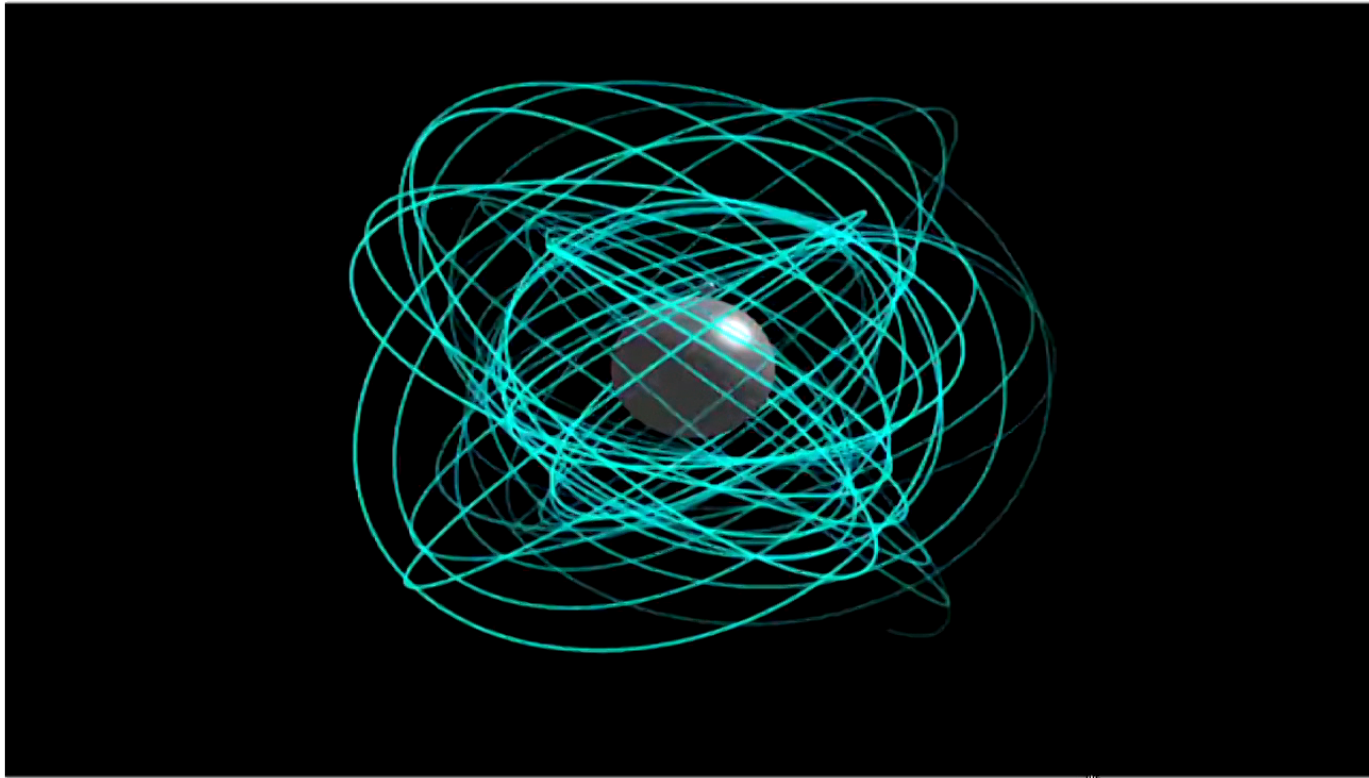
[animation courtesy of Steve Drasco]

But GWs carry off energy and ang. momentum, and the small object slowly spirals into the black hole...



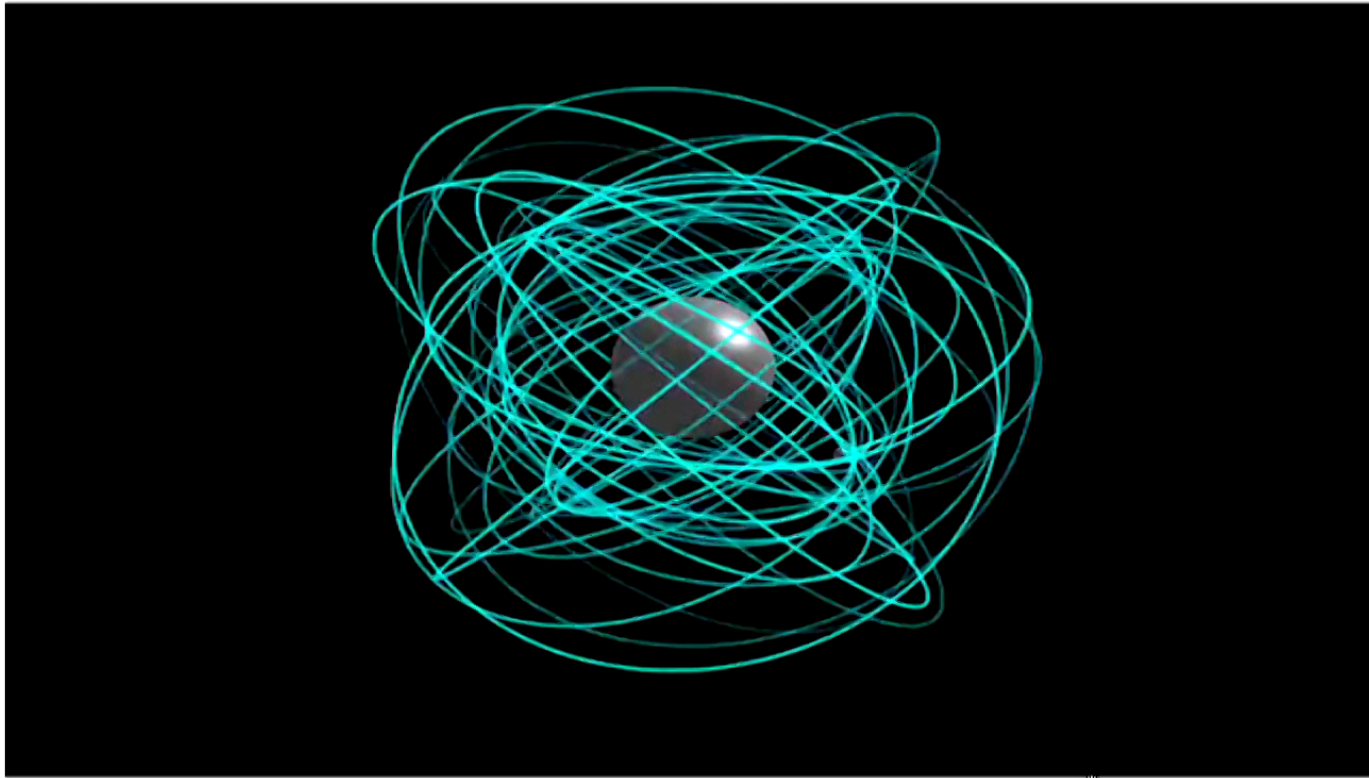
[animation courtesy of Steve Drasco]

But GWs carry off energy and ang. momentum, and the small object slowly spirals into the black hole...



[animation courtesy of Steve Drasco]

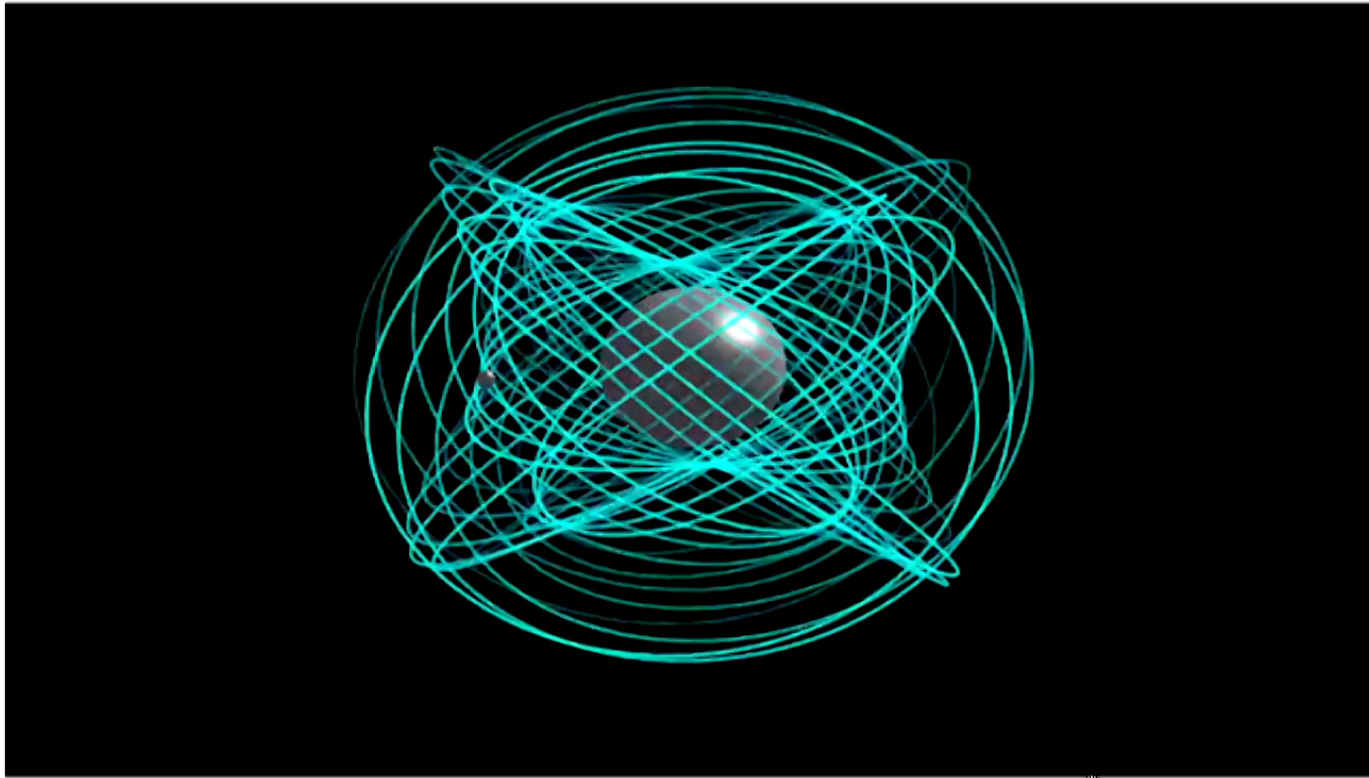
But GWs carry off energy and ang. momentum, and the small object slowly spirals into the black hole...



[animation courtesy of Steve Drasco]

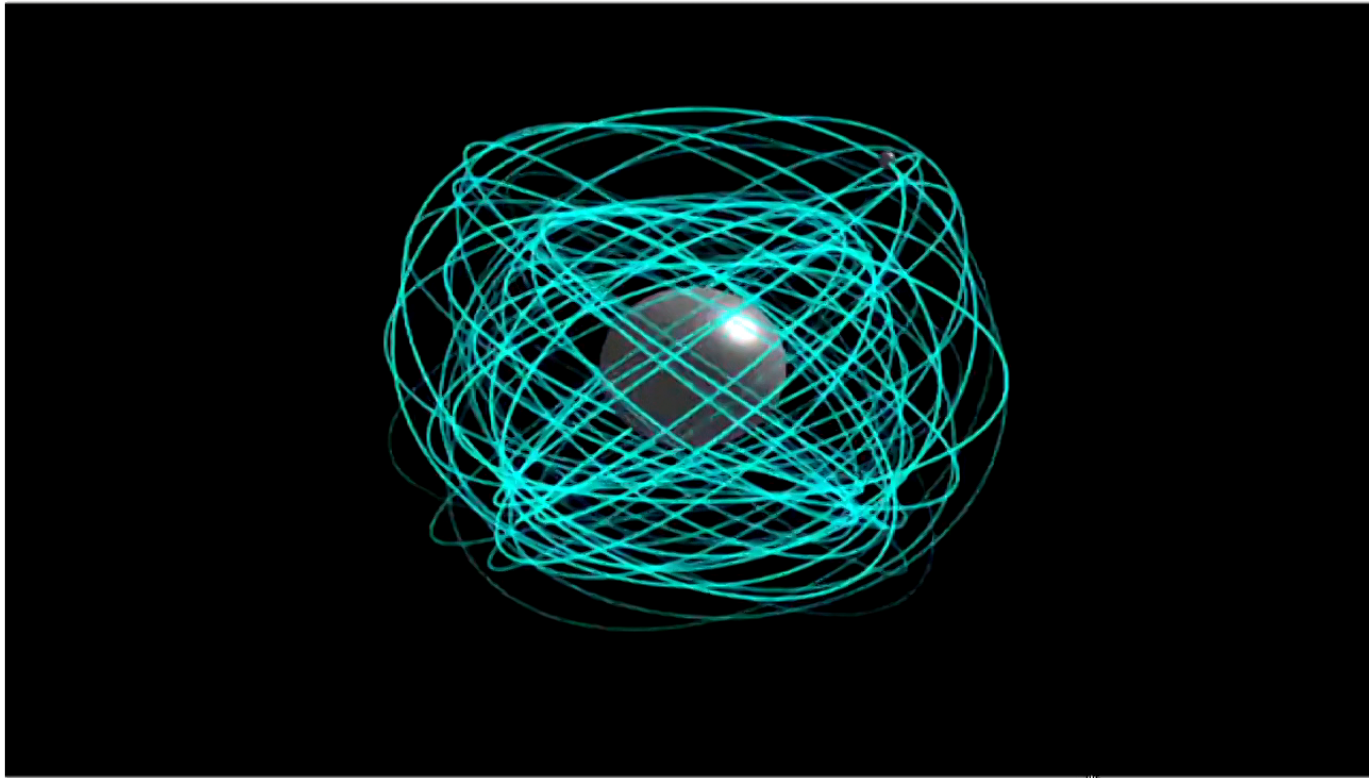


But GWs carry off energy and ang. momentum, and the small object slowly spirals into the black hole...



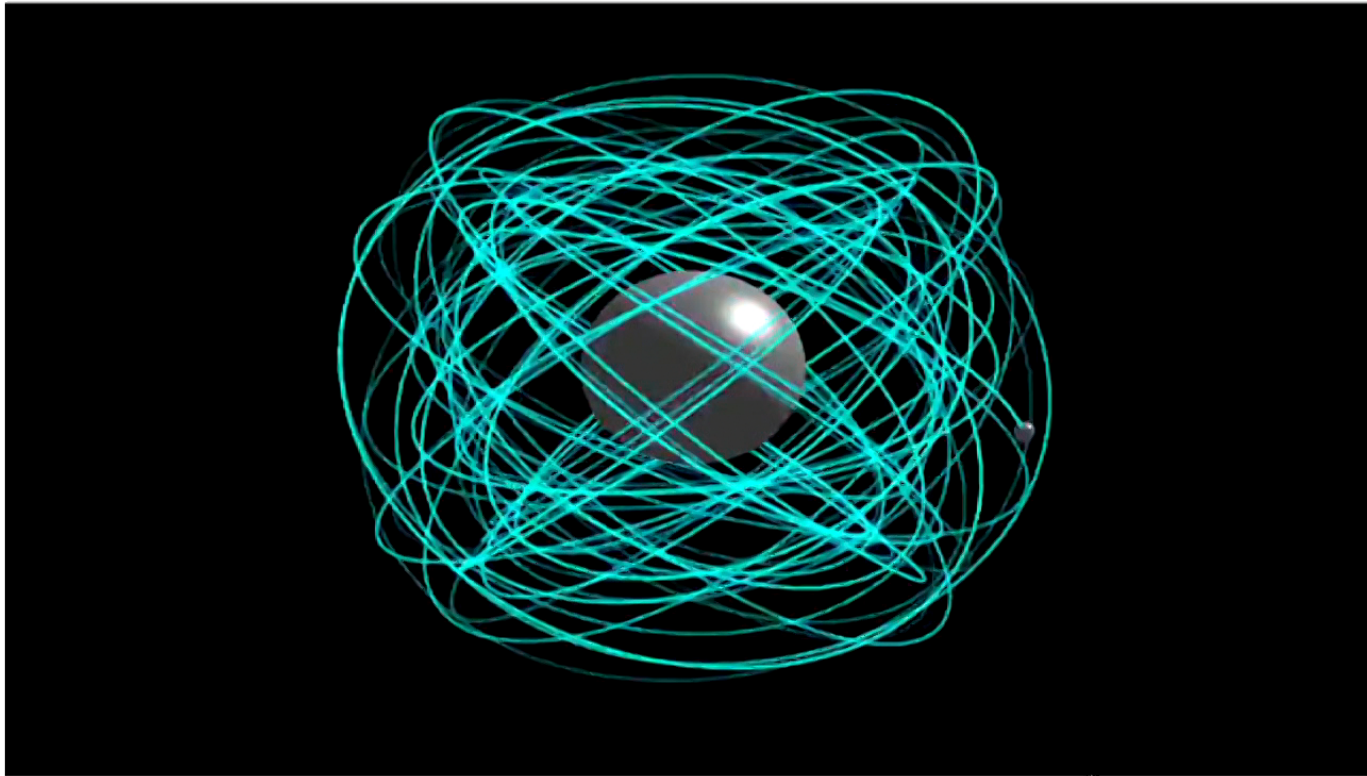
[animation courtesy of Steve Drasco]

But GWs carry off energy and ang. momentum, and the small object slowly spirals into the black hole...



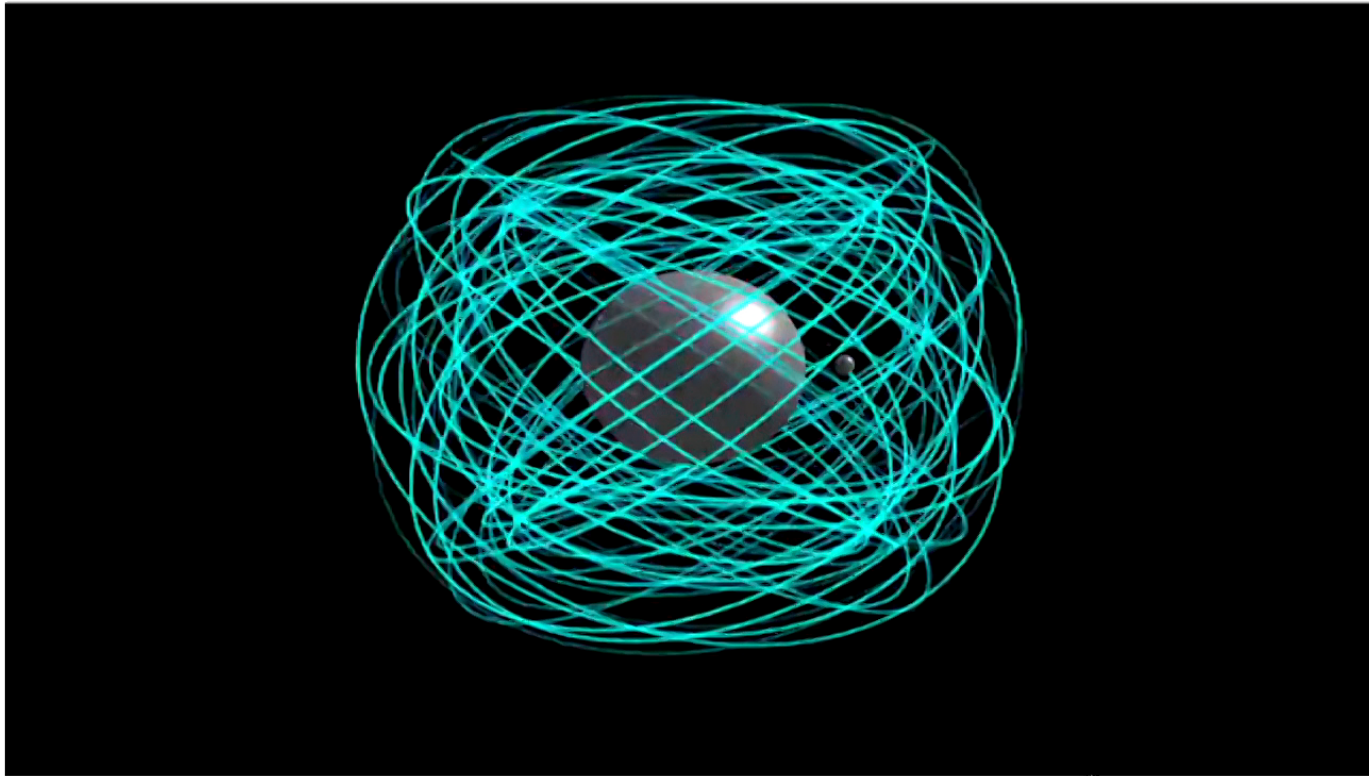
[animation courtesy of Steve Drasco]

But GWs carry off energy and ang. momentum, and the small object slowly spirals into the black hole...



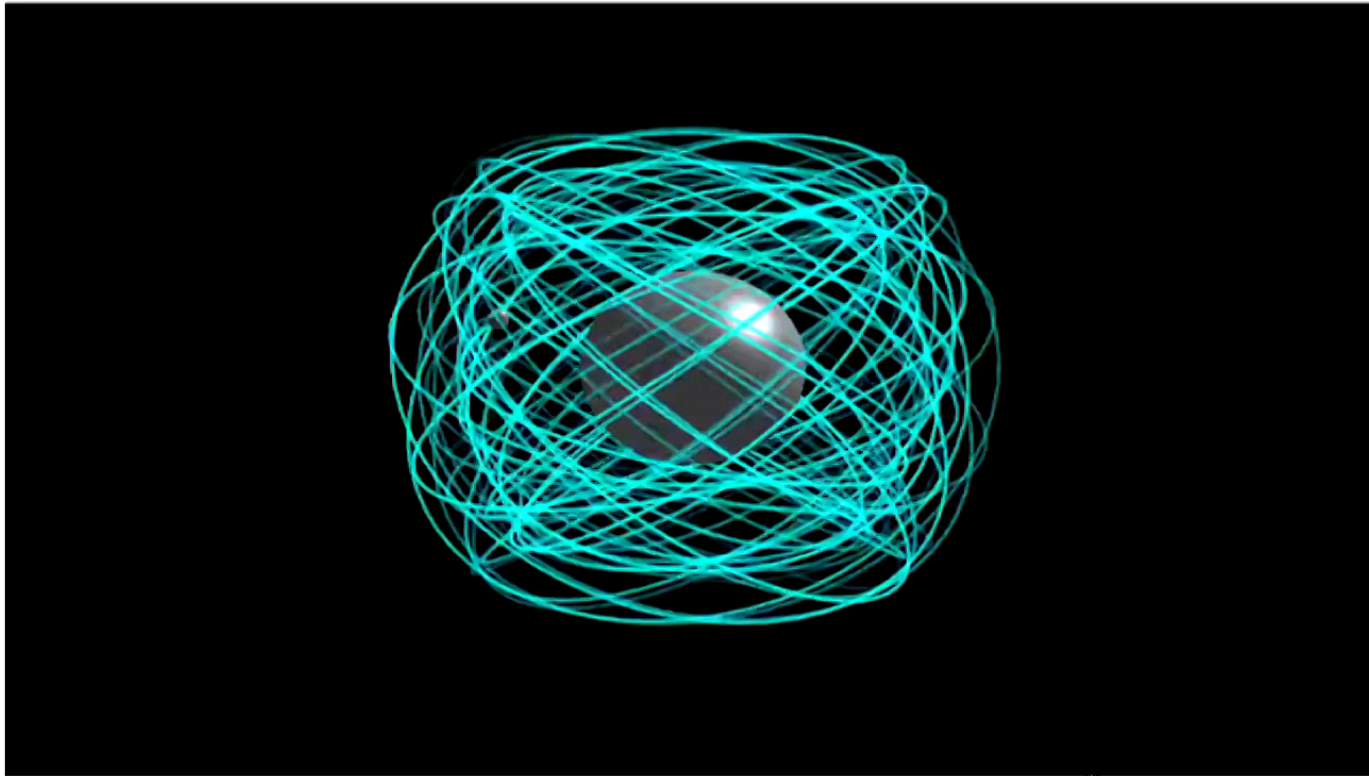
[animation courtesy of Steve Drasco]

But GWs carry off energy and ang. momentum, and the small object slowly spirals into the black hole...



[animation courtesy of Steve Drasco]

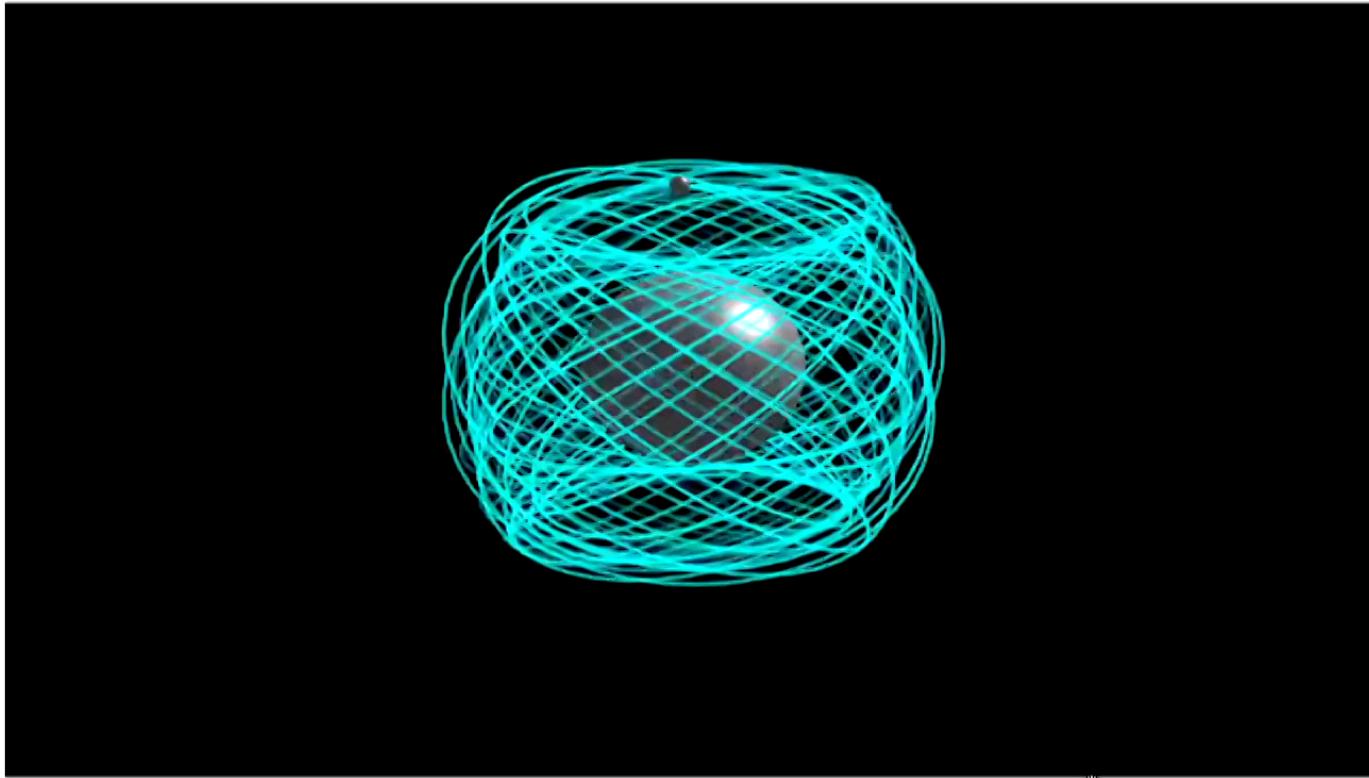
But GWs carry off energy and ang. momentum, and the small object slowly spirals into the black hole...



[animation courtesy of Steve Drasco]

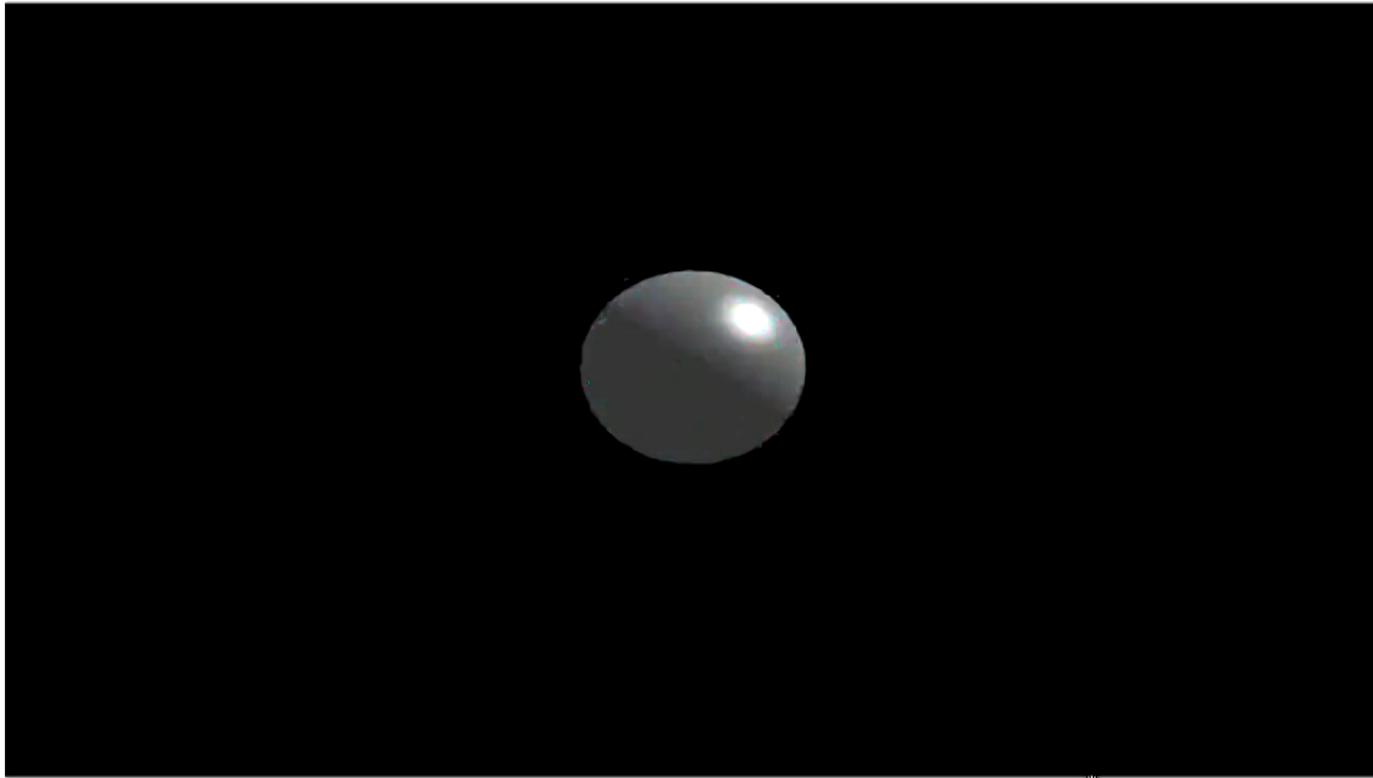


But GWs carry off energy and ang. momentum, and the small object slowly spirals into the black hole...



[animation courtesy of Steve Drasco]

But GWs carry off energy and ang. momentum, and the small object slowly spirals into the black hole...



[animation courtesy of Steve Drasco]

# Outline

- ① Intro to EMRIs
- ② EMRI model requirements
- ③ Self-force theory: the local problem
- ④ Self-force theory: the global problem
  - First order
  - Second order





# Gravitational self-force theory

- $m$  perturbs the spacetime of  $M$ :

$$\mathfrak{g}_{\mu\nu} = g_{\mu\nu} + \epsilon h_{\mu\nu}^1 + \epsilon^2 h_{\mu\nu}^2 + \dots$$

where  $\epsilon \sim m/M$

- this deformation of the geometry affects  $m$ 's motion  
 $\Rightarrow$  exerts a *self-force*

$$\frac{D^2 z^\mu}{d\tau^2} = \epsilon F_1^\mu + \epsilon^2 F_2^\mu + \dots$$



## How high order?

$$\frac{D^2 z^\mu}{d\tau^2} = \epsilon F_1^\mu + \epsilon^2 F_2^\mu + \dots$$

- force is small; inspiral occurs very slowly, on time scale  $\tau \sim 1/\epsilon$
- suppose we neglect  $F_2^\mu$ ; leads to error  $\delta\left(\frac{D^2 z^\mu}{d\tau^2}\right) \sim \epsilon^2$ 
  - $\Rightarrow$  error in position  $\delta z^\mu \sim \epsilon^2 \tau^2$
  - $\Rightarrow$  after time  $\tau \sim 1/\epsilon$ , error  $\delta z^\mu \sim 1$

$\therefore$  accurately describing orbital evolution requires second order



## Hierarchy of self-force models [Hinderer and Flanagan]

- when self-force is accounted for,  $E$ ,  $L_z$ , and  $Q$  evolve with time
- on an inspiral timescale  $t \sim 1/\epsilon$ , the phase of the gravitational wave has an expansion (excluding resonances)

$$\phi = \frac{1}{\epsilon}\phi_0 + \phi_1 + O(\epsilon)$$

- a model that gets  $\phi_0$  right should (hopefully) be enough to detect most signals
- a model that gets both  $\phi_0$  and  $\phi_1$  should be enough for precise parameter extraction



# Hierarchy of self-force models [Hinderer and Flanagan]

## Adiabatic order

determined by *adiabatic order* is accounted for,  $E$ ,  $L_z$ , and  $Q$  evolve with time

- averaged dissipative piece of  $F_1^\mu$ , the phase of the gravitational wave has an expansion (excluding resonances)

$$\phi = \frac{1}{\epsilon} \phi_0 + \phi_1 + O(\epsilon)$$

- a model that gets  $\phi_0$  right should (hopefully) be enough to detect most signals
- a model that gets both  $\phi_0$  and  $\phi_1$  should be enough for precise parameter extraction



# Hierarchy of self-force models [Hinderer and Flanagan]

## Adiabatic order

determined by

- averaged dissipative piece of  $F_1^\mu$ , the piece that is accounted for in an expansion (excluding resonances)

## Post-adiabatic order

determined by

- averaged dissipative piece of  $F_2^\mu$
- conservative piece of  $F_1^\mu$
- oscillatory dissipative piece of  $F_1^\mu$

$$\phi = \frac{1}{\epsilon} \phi_0 + \phi_1 + O(\epsilon)$$

- a model that gets  $\phi_0$  right should (hopefully) be enough to detect most signals
- a model that gets both  $\phi_0$  and  $\phi_1$  should be enough for precise parameter extraction



What is the status of these models?

- Efficient method of calculating adiabatic inspirals was developed  $\sim 15$  years ago
- Most effort over last 23 years has been on calculating full  $F_1^\mu$  —but this isn't an improvement over adiabatic approximation *if we don't also have averaged dissipative piece of  $F_2^\mu$*



# Outline

- 1 Intro to EMRIs
- 2 EMRI model requirements
- 3 Self-force theory: the local problem
- 4 Self-force theory: the global problem
  - First order
  - Second order



# What is the problem we want to solve?



A small, compact object of mass and size  $m \sim l \sim \epsilon$  moves through (and influences) spacetime

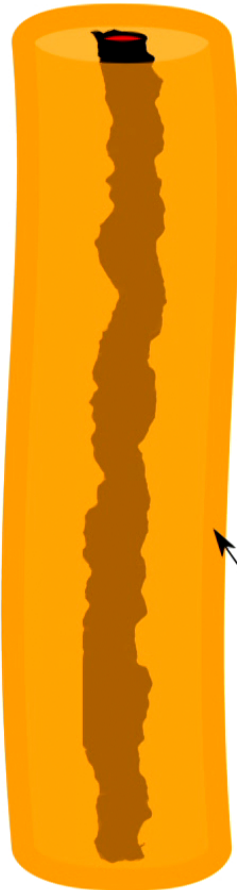
- Option 1: tackle the problem directly, treat the body as finite sized, deal with its internal composition

Need to deal with internal dynamics and strong fields near object





# What is the problem we want to solve?



A small, compact object of mass and size  $m \sim l \sim \epsilon$  moves through (and influences) spacetime

- Option 2: restrict the problem to distances  $s \gg m$  from the object, treat  $m$  as source of perturbation of external background  $g_{\mu\nu}$ :

$$g_{\mu\nu} = g_{\mu\nu} + \epsilon h_{\mu\nu}^1 + \epsilon^2 h_{\mu\nu}^2 + \dots$$

- This is a free boundary value problem

Metric here must agree with metric outside a small compact object; and "here" moves in response to field



# What is the problem we want to solve?

A small, compact object of mass and size  $m \sim l \sim \epsilon$  moves through (and influences) spacetime

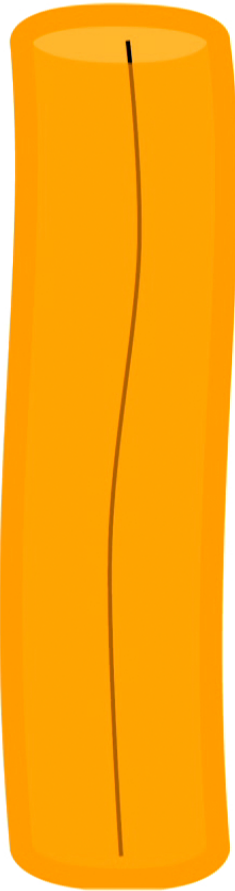
- Option 3: treat the body as a point particle
  - takes behavior of fields outside object and extends it down to a fictitious worldline
  - so  $h_{\mu\nu}^1 \sim 1/s$  ( $s$  = distance from object)
  - second-order field equation
$$\delta G[h^2] \sim -\delta^2 G[h^1] \sim (\partial h^1)^2 \sim 1/s^4$$
—no solution unless we restrict it to points off worldline, which is equivalent to FBVP



Distributionally ill defined  
source appears here!



# What is the problem we want to solve?

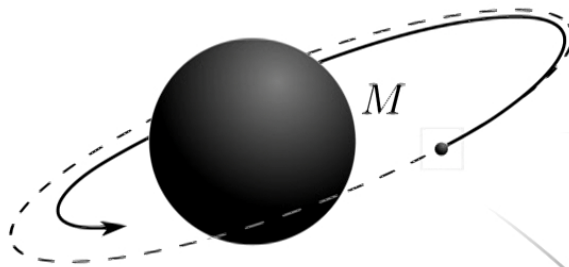


A small, compact object of mass and size  $m \sim l \sim \epsilon$  moves through (and influences) spacetime

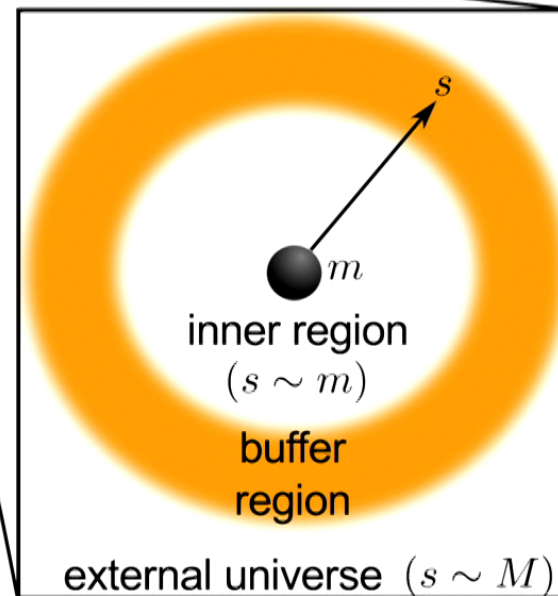
- Option 4: transform the FBVP into an *effective* problem using a *puncture*, a local approximation to the field outside the object
- This will be the method emphasized here [Mino, Sasaki, Tanaka 1996; Quinn & Wald 1996; Detweiler & Whiting 2002-03; Gralla & Wald 2008-2012; Pound 2009-2017; Harte 2012]



# Matched asymptotic expansions

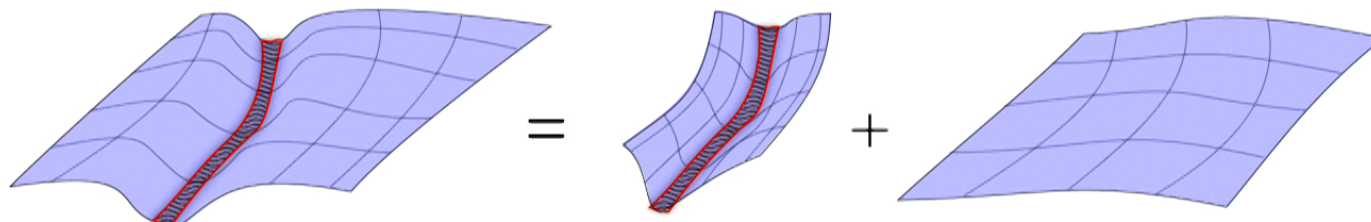


- *outer expansion*: in external universe, treat field of  $M$  as background
- *inner expansion*: in inner region, treat field of  $m$  as background
- in buffer region, feed information from inner expansion into outer expansion



## Self-field and effective field

- based on local solution to EFE in buffer region, we split local metric into a “self-field” and an effective metric



The diagram shows three 3D surface plots representing metrics. The first plot on the left, labeled 'full metric  $g_{\mu\nu}$ ', shows a surface with a sharp, deep crease. This is followed by an equals sign. The second plot, labeled '"self field"  $h_{\mu\nu}^S$ ', shows a similar surface but with a much shallower, smoother crease. This is followed by a plus sign. The third plot, labeled 'effective metric  $g_{\mu\nu} + h_{\mu\nu}^R$ ', shows a surface that is smooth and flat, representing the metric after the self-field has been removed.

full metric  $g_{\mu\nu}$  = "self field"  $h_{\mu\nu}^S$  + effective metric  $g_{\mu\nu} + h_{\mu\nu}^R$

- $h_{\mu\nu}^S$  directly determined by object's multipole moments
- $g_{\mu\nu} + h_{\mu\nu}^R$  is a *smooth vacuum metric* determined by global boundary conditions



# Equation of motion

Solving EFE in buffer region yields equations of motion for object's effective center of mass

1st order, arbitrary compact object [MiSaTaQuWa 1996]:

$$\frac{D^2 z^\mu}{d\tau^2} = -\frac{1}{2} (g^{\alpha\delta} + u^\alpha u^\delta) (2h_{\delta\beta;\gamma}^{\text{R1}} - h_{\beta\gamma;\delta}^{\text{R1}}) u^\beta u^\gamma + \frac{1}{2m} R^\alpha{}_{\beta\gamma\delta} u^\beta S^{\gamma\delta} + O(m^2)$$

(motion of spinning test body in  $g_{\mu\nu} + h_{\mu\nu}^{\text{R1}}$ )

2nd-order, nonspinning, spherical compact object [Pound 2012]:

$$\frac{D^2 z^\mu}{d\tau^2} = -\frac{1}{2} (g^{\mu\nu} + u^\mu u^\nu) (g_\nu{}^\rho - h_\nu{}^\rho) (2h_{\rho\sigma;\lambda}^{\text{R}} - h_{\sigma\lambda;\rho}^{\text{R}}) u^\sigma u^\lambda + O(m^3)$$

(geodesic motion in  $g_{\mu\nu} + h_{\mu\nu}^{\text{R}}$ )



# Equation of motion

Solving EFE in buffer region yields equations of motion for object's effective center of mass

1st order, arbitrary compact object [MiSaTaQuWa 1996]:

$$\frac{D^2 z^\mu}{d\tau^2} = -\frac{1}{2} (g^{\alpha\delta} + u^\alpha u^\delta) (2h_{\delta\beta;\gamma}^{\text{R1}} - h_{\beta\gamma;\delta}^{\text{R1}}) u^\beta u^\gamma + \frac{1}{2m} R^\alpha{}_{\beta\gamma\delta} u^\beta S^{\gamma\delta} + O(m^2)$$

(motion of spinning test body in  $g_{\mu\nu} + h_{\mu\nu}^{\text{R1}}$ )

2nd-order, nonspinning, spherical compact object [Pound 2012]:

$$\frac{D^2 z^\mu}{d\tau^2} = -\frac{1}{2} (g^{\mu\nu} + u^\mu u^\nu) (g_\nu{}^\rho - h_\nu{}^\rho) (2h_{\rho\sigma;\lambda}^{\text{R}} - h_{\sigma\lambda;\rho}^{\text{R}}) u^\sigma u^\lambda + O(m^3)$$

(geodesic motion in  $g_{\mu\nu} + h_{\mu\nu}^{\text{R}}$ )





# Equation of motion

Solving EFE in buffer region yields equations of motion for object's effective center of mass

1st order, arbitrary compact object [MiSaTaQuWa 1996]:

$$\frac{D^2 z^\mu}{d\tau^2} = -\frac{1}{2} (g^{\alpha\delta} + u^\alpha u^\delta) (2h_{\delta\beta;\gamma}^{R1} - h_{\beta\gamma;\delta}^{R1}) u^\beta u^\gamma + \frac{1}{2m} R^\alpha{}_{\beta\gamma\delta} u^\beta S^{\gamma\delta} + O(m^2)$$

(motion of spinning test body in  $g_{\mu\nu} + h_{\mu\nu}^{R1}$ )

2nd-order, nonspinning, spherical compact object [Pound 2012]:

$$\frac{D^2 z^\mu}{d\tau^2} = -\frac{1}{2} (g^{\mu\nu} + u^\mu u^\nu) (g_\nu{}^\rho - h_\nu{}^\rho) (2h_{\rho\sigma;\lambda}^R - h_{\sigma\lambda;\rho}^R) u^\sigma u^\lambda + O(m^3)$$

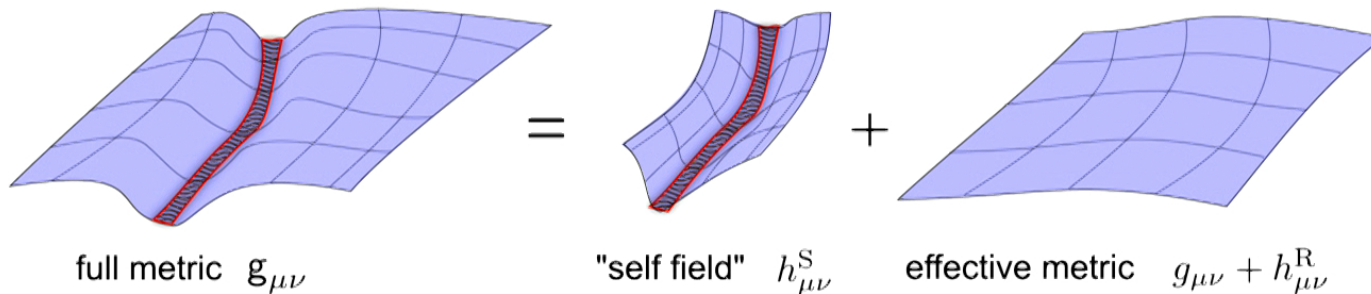
(geodesic motion in  $g_{\mu\nu} + h_{\mu\nu}^R$ )

- these results are derived *directly from EFE outside the object*; there's no regularization of infinities, and no assumptions about  $h_{\mu\nu}^R$



# Point particles and punctures

- replace “self-field” with “singular field”



- at 1st order, can use this to *replace object with a point particle*

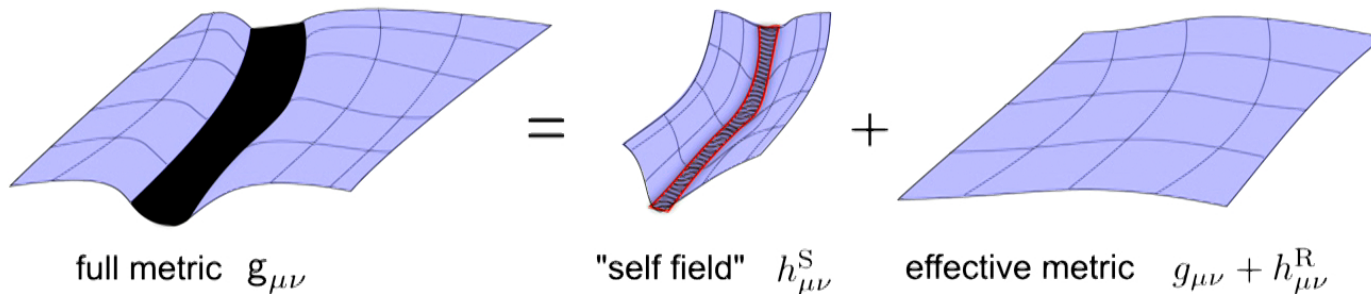
$$T_{\mu\nu}^1 := \frac{1}{8\pi} \delta G_{\mu\nu}[h^1] \sim m \delta(x - z)$$

- beyond 1st order, point particles not well defined—but can replace object with a *puncture*, a local singularity in the field, moving on  $z^\mu$ , equipped with the object's multipole moments



# Point particles and punctures

- replace “self-field” with “singular field”



- at 1st order, can use this to *replace object with a point particle*

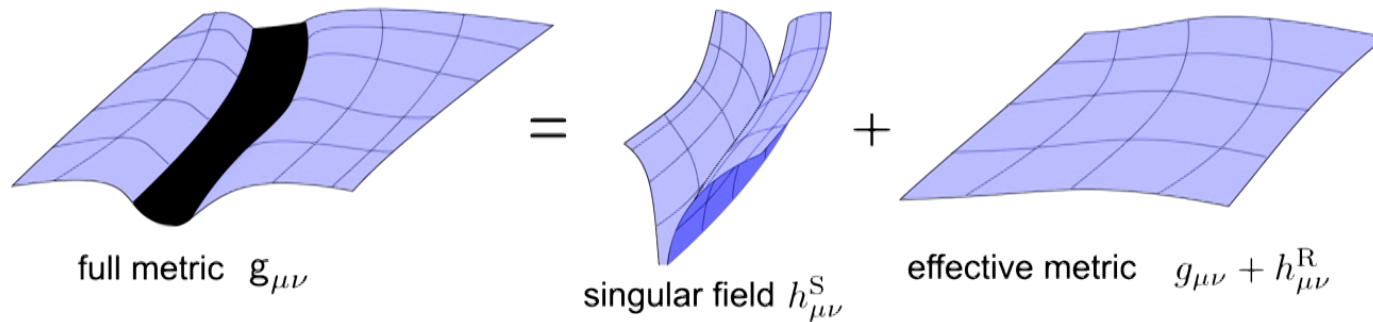
$$T_{\mu\nu}^1 := \frac{1}{8\pi} \delta G_{\mu\nu}[h^1] \sim m \delta(x - z)$$

- beyond 1st order, point particles not well defined—but can replace object with a *puncture*, a local singularity in the field, moving on  $z^\mu$ , equipped with the object's multipole moments



## Point particles and punctures

- replace “self-field” with “singular field”



- at 1st order, can use this to *replace object with a point particle*

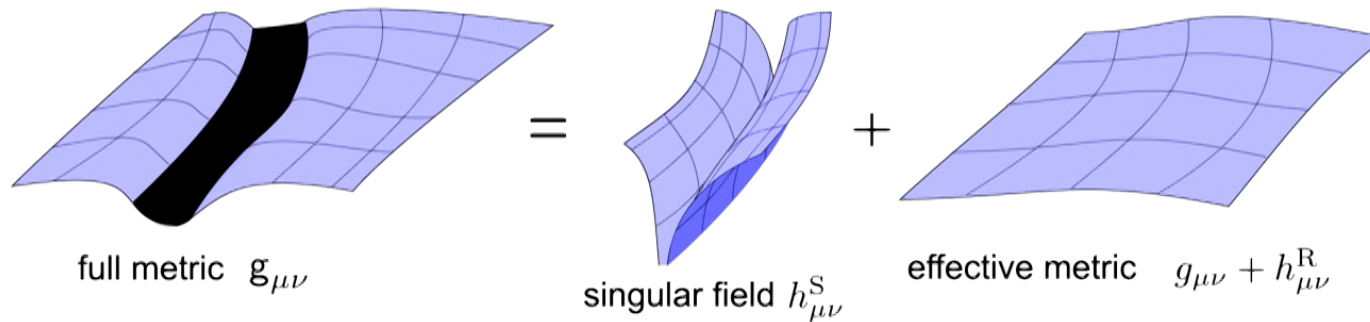
$$T_{\mu\nu}^1 := \frac{1}{8\pi} \delta G_{\mu\nu}[h^1] \sim m\delta(x - z)$$

- beyond 1st order, point particles not well defined—but can replace object with a *puncture*, a local singularity in the field, moving on  $z^\mu$ , equipped with the object's multipole moments



## Point particles and punctures

- replace “self-field” with “singular field”



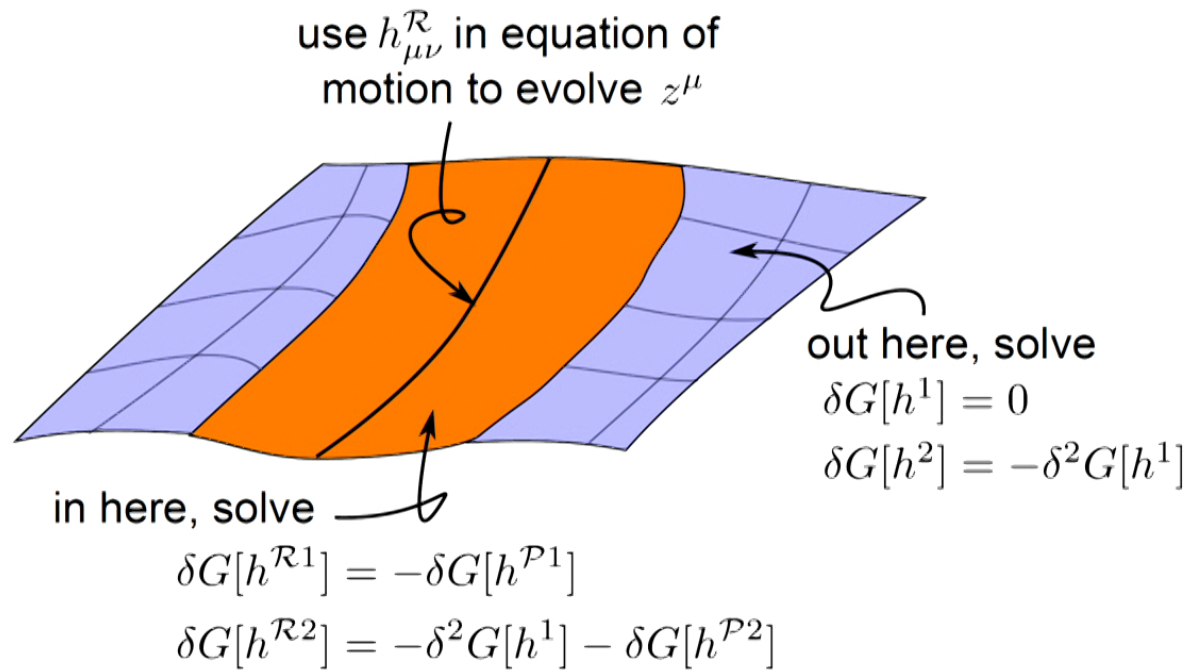
- at 1st order, can use this to *replace object with a point particle*

$$T_{\mu\nu}^1 := \frac{1}{8\pi} \delta G_{\mu\nu}[h^1] \sim m\delta(x - z)$$

- beyond 1st order, point particles not well defined—but can replace object with a *puncture*, a local singularity in the field, moving on  $z^\mu$ , equipped with the object’s multipole moments



## How you replace an object with a puncture



# Solving the Einstein equations globally

- solving the local problem told us how to replace the small object with a moving puncture in the field equations:

$$\delta G_{\mu\nu}[h^{\mathcal{R}1}] = -\delta G_{\mu\nu}[h^{\mathcal{P}1}]$$

$$\delta G_{\mu\nu}[h^{\mathcal{R}2}] = -\delta^2 G_{\mu\nu}[h^1, h^1] - \delta G_{\mu\nu}[h^{\mathcal{P}2}]$$

$$\frac{D^2 z^\mu}{d\tau^2} = -\frac{1}{2}(g^{\mu\nu} + u^\mu u^\nu)(g_\nu^\delta - h_\nu^{\mathcal{R}\delta})(2h_{\delta\beta;\gamma}^{\mathcal{R}} - h_{\beta\gamma;\delta}^{\mathcal{R}})u^\beta u^\gamma$$

where  $\delta G_{\mu\nu}[h] \sim \square h_{\mu\nu}$ ,  $\delta^2 G_{\mu\nu}[h, h] \sim \partial h \partial h + h \partial^2 h$

- the global problem: how do we solve these equations in practice?





# Solving the Einstein equations globally

- solving the local problem told us how to replace the small object with a moving puncture in the field equations:

$$\delta G_{\mu\nu}[h^{\mathcal{R}1}] = -\delta G_{\mu\nu}[h^{\mathcal{P}1}]$$

$$\delta G_{\mu\nu}[h^{\mathcal{R}2}] = -\delta^2 G_{\mu\nu}[h^1, h^1] - \delta G_{\mu\nu}[h^{\mathcal{P}2}]$$

$$\frac{D^2 z^\mu}{d\tau^2} = -\frac{1}{2}(g^{\mu\nu} + u^\mu u^\nu)(g_\nu^\delta - h_\nu^{\mathcal{R}\delta})(2h_{\delta\beta;\gamma}^{\mathcal{R}} - h_{\beta\gamma;\delta}^{\mathcal{R}})u^\beta u^\gamma$$

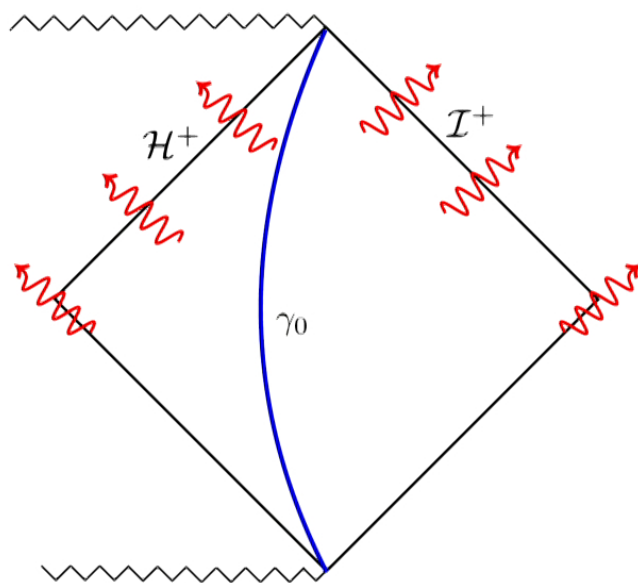
where  $\delta G_{\mu\nu}[h] \sim \square h_{\mu\nu}$ ,  $\delta^2 G_{\mu\nu}[h, h] \sim \partial h \partial h + h \partial^2 h$

- the global problem: how do we solve these equations in practice?



# Typical calculation at first order

[Barack et al, Evans et al, van de Meent, many others]

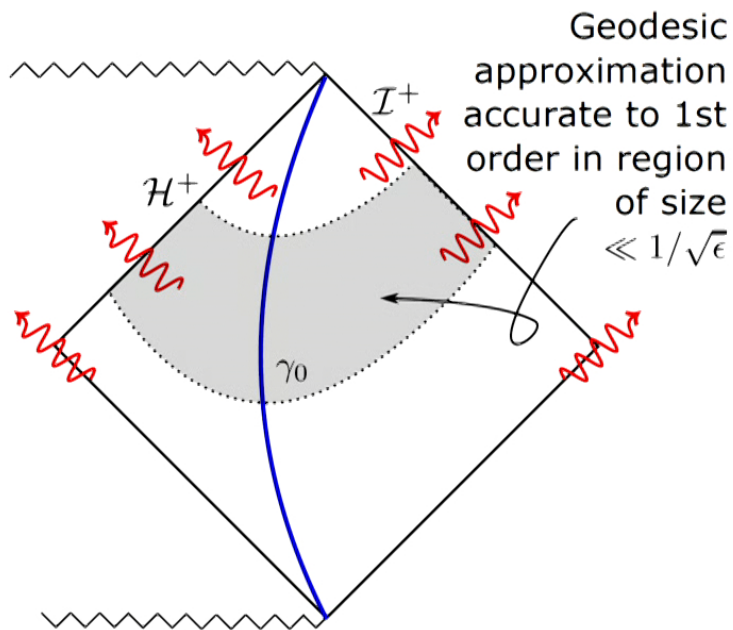


- approximate the source orbit as a bound geodesic
- impose outgoing-wave BCs at  $\mathcal{I}^+$  and  $\mathcal{H}^+$
- solve field equation numerically, compute self-force from solution
- breaks down on *dephasing time*  $\sim 1/\sqrt{\epsilon}$ , when  $|z^\mu - z_0^\mu| \sim M$



# Typical calculation at first order

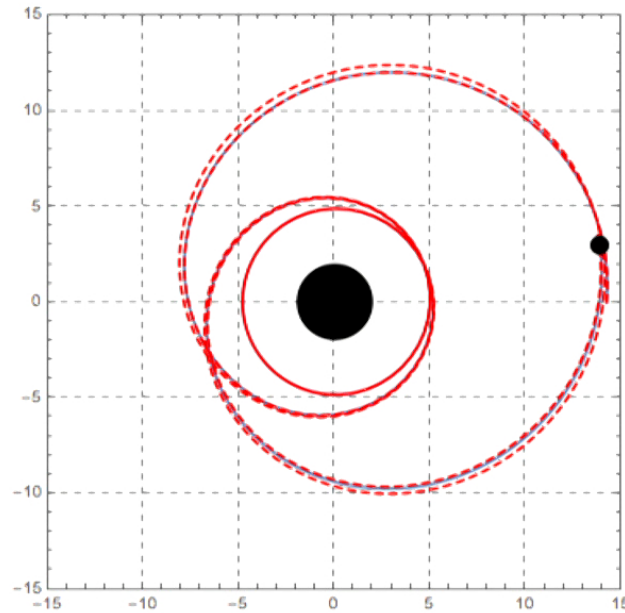
[Barack et al, Evans et al, van de Meent, many others]



- approximate the source orbit as a bound geodesic
- impose outgoing-wave BCs at  $\mathcal{I}^+$  and  $\mathcal{H}^+$
- solve field equation numerically, compute self-force from solution
- breaks down on *dephasing time*  $\sim 1/\sqrt{\epsilon}$ , when  $|z^\mu - z_0^\mu| \sim M$



# First-order force

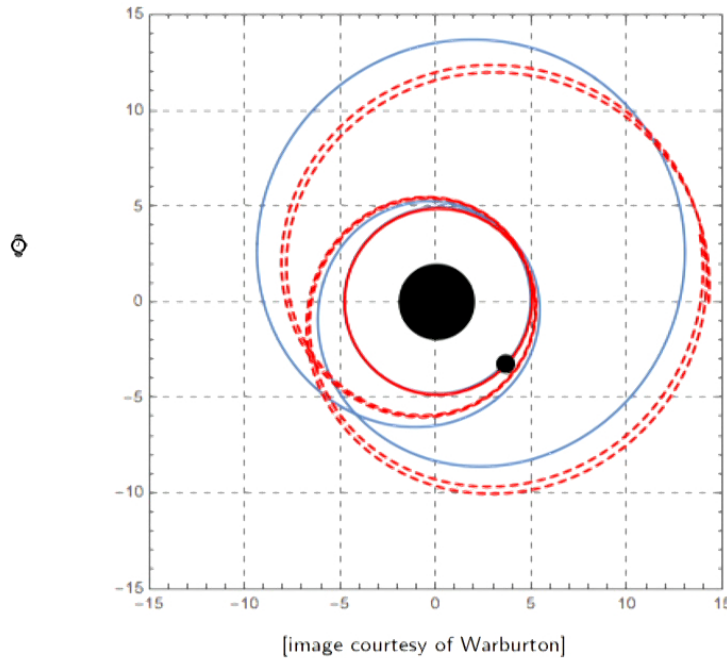


[image courtesy of Warburton]

- complete inspirals simulated in Schwarzschild using full  $F_1^\mu$  (including spin force) [Warburton et al]
- and  $F_1^\mu$  has been computed on generic orbits in Kerr [van de Meent]
- but still need  $F_2^\mu$  for post-adiabatic inspiral

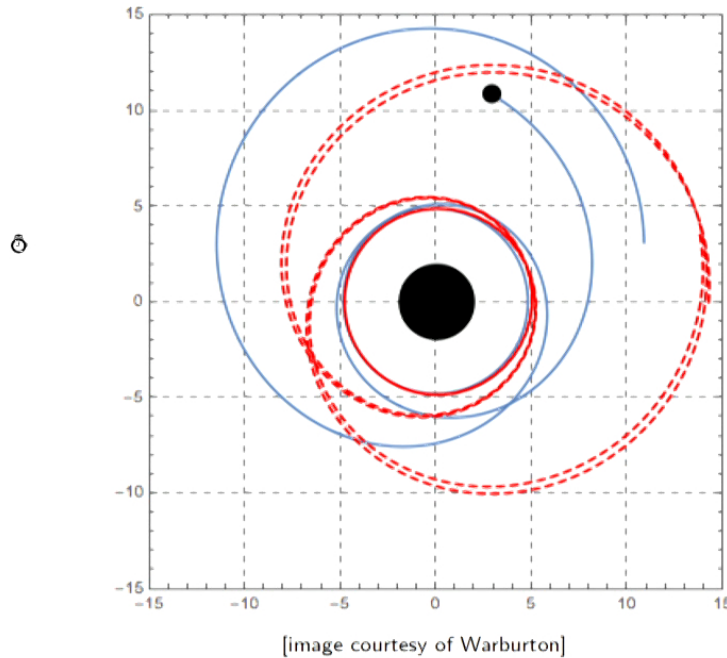


# First-order force



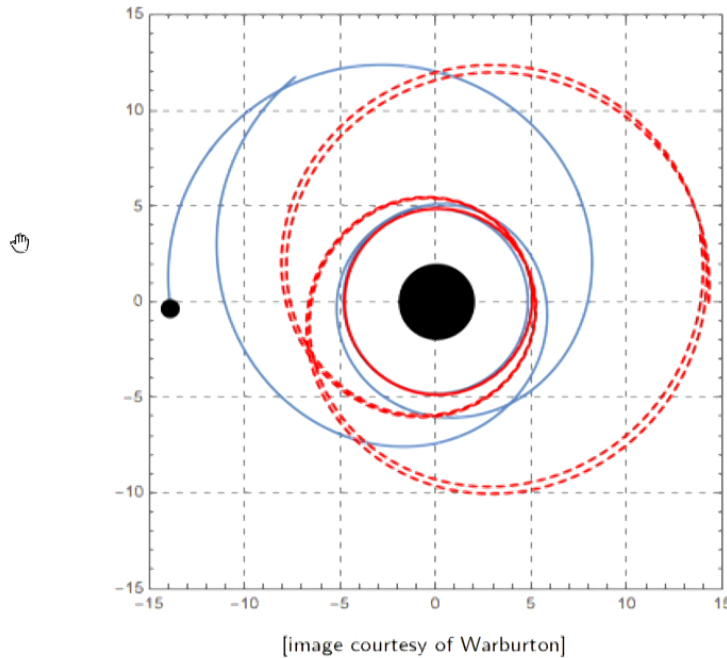
- complete inspirals simulated in Schwarzschild using full  $F_1^\mu$  (including spin force) [Warburton et al]
- and  $F_1^\mu$  has been computed on generic orbits in Kerr [van de Meent]
- but still need  $F_2^\mu$  for post-adiabatic inspiral

# First-order force



- complete inspirals simulated in Schwarzschild using full  $F_1^\mu$  (including spin force) [Warburton et al]
- and  $F_1^\mu$  has been computed on generic orbits in Kerr [van de Meent]
- but still need  $F_2^\mu$  for post-adiabatic inspiral

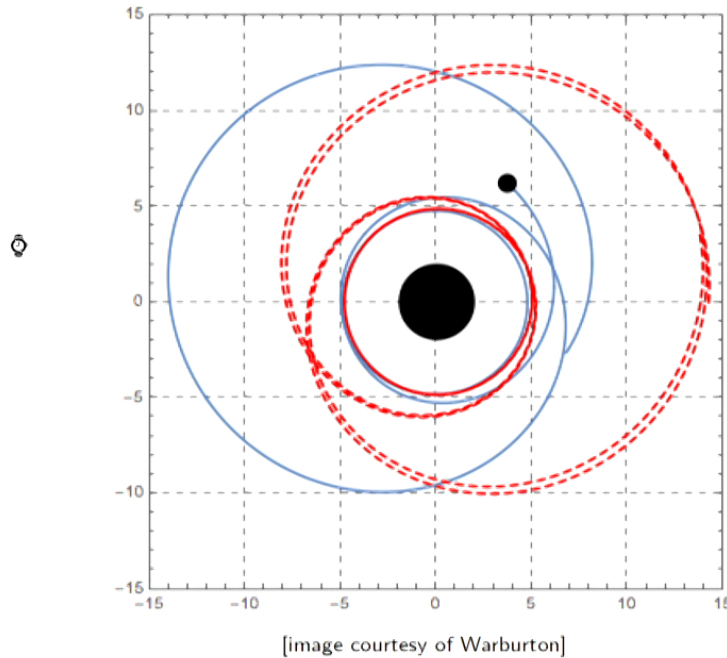
# First-order force



- complete inspirals simulated in Schwarzschild using full  $F_1^\mu$  (including spin force) [Warburton et al]
- and  $F_1^\mu$  has been computed on generic orbits in Kerr [van de Meent]
- but still need  $F_2^\mu$  for post-adiabatic inspiral

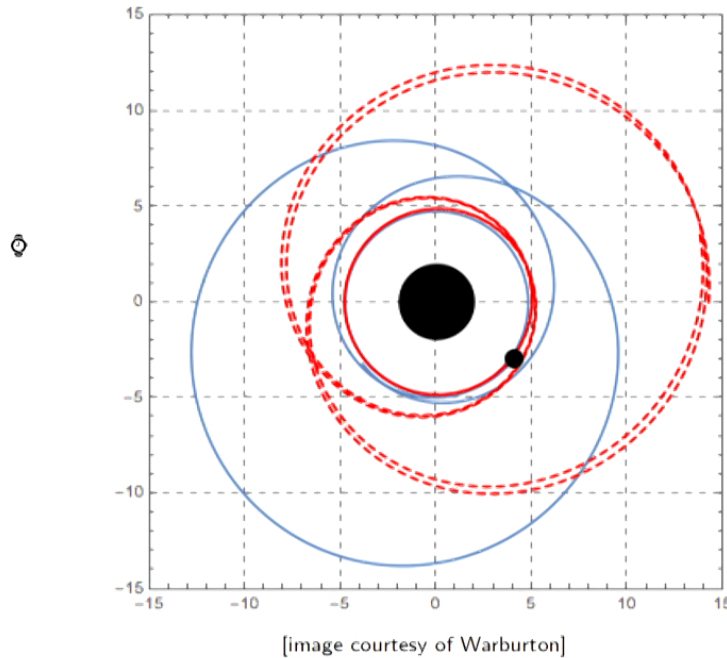


# First-order force



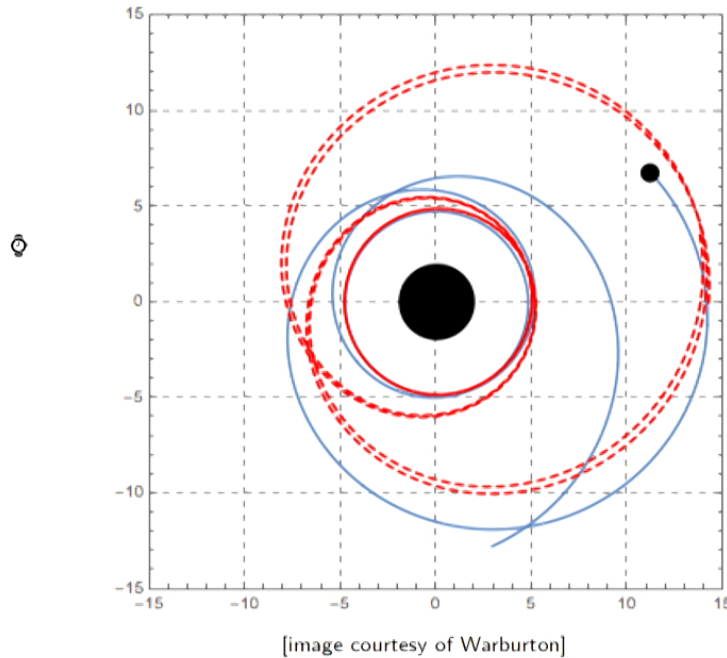
- complete inspirals simulated in Schwarzschild using full  $F_1^\mu$  (including spin force) [Warburton et al]
- and  $F_1^\mu$  has been computed on generic orbits in Kerr [van de Meent]
- but still need  $F_2^\mu$  for post-adiabatic inspiral

# First-order force



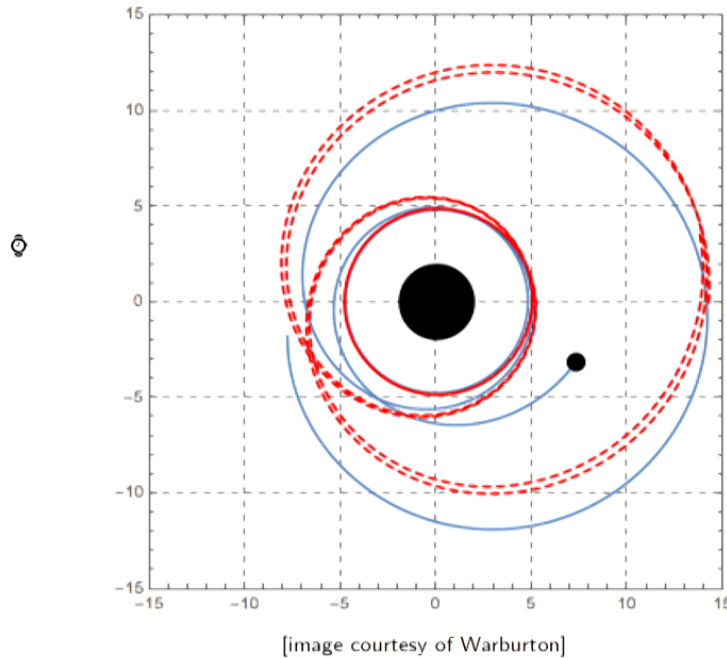
- complete inspirals simulated in Schwarzschild using full  $F_1^\mu$  (including spin force) [Warburton et al]
- and  $F_1^\mu$  has been computed on generic orbits in Kerr [van de Meent]
- but still need  $F_2^\mu$  for post-adiabatic inspiral

# First-order force



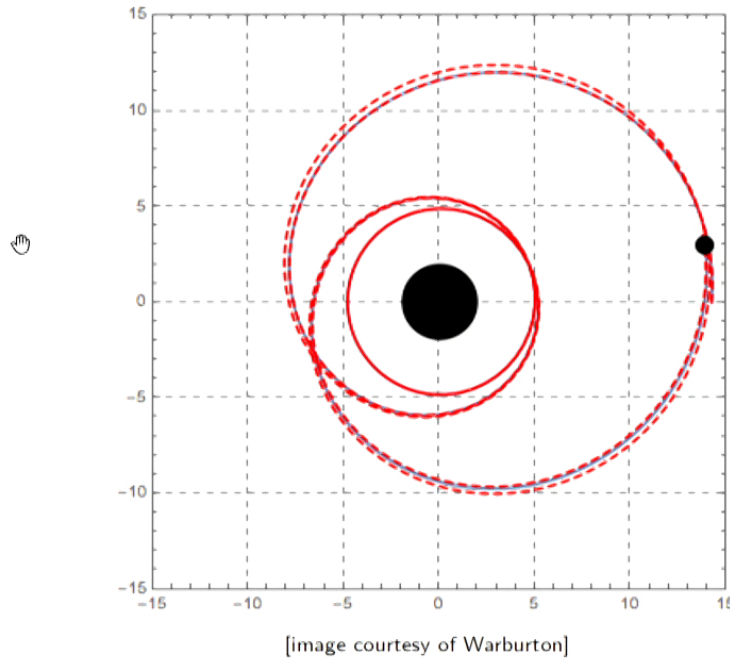
- complete inspirals simulated in Schwarzschild using full  $F_1^\mu$  (including spin force) [Warburton et al]
- and  $F_1^\mu$  has been computed on generic orbits in Kerr [van de Meent]
- but still need  $F_2^\mu$  for post-adiabatic inspiral

# First-order force



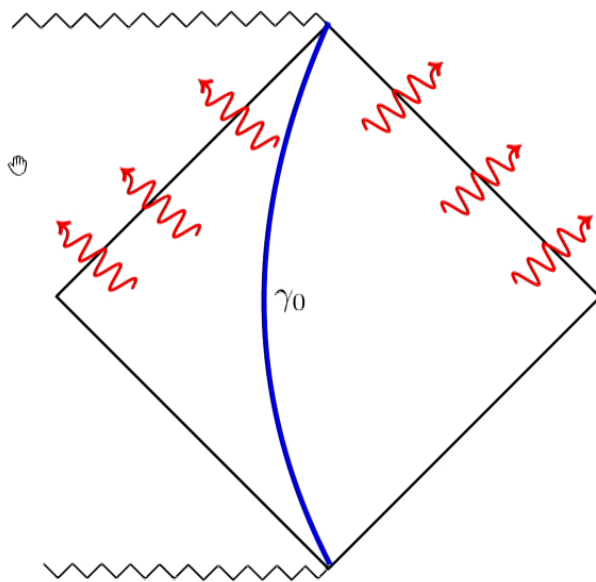
- complete inspirals simulated in Schwarzschild using full  $F_1^\mu$  (including spin force) [Warburton et al]
- and  $F_1^\mu$  has been computed on generic orbits in Kerr [van de Meent]
- but still need  $F_2^\mu$  for post-adiabatic inspiral

# First-order force



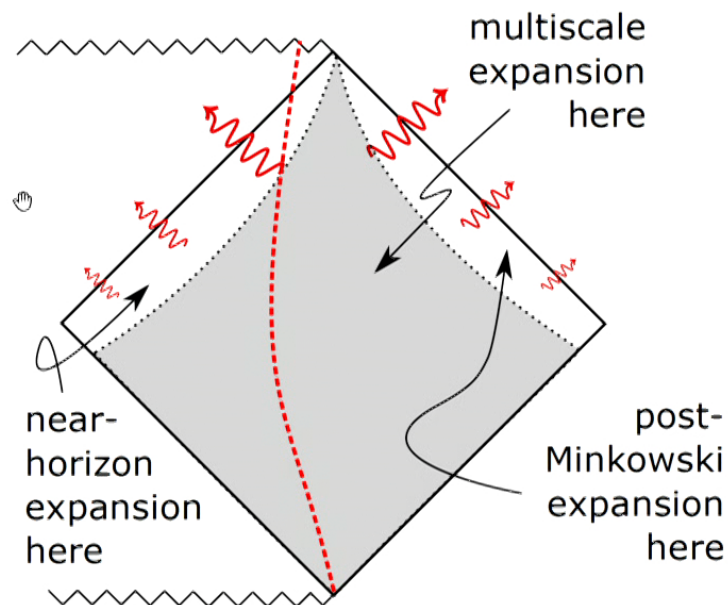
- complete inspirals simulated in Schwarzschild using full  $F_1^{\mu}$  (including spin force) [Warburton et al]
- and  $F_1^{\mu}$  has been computed on generic orbits in Kerr [van de Meent]
- but still need  $F_2^{\mu}$  for post-adiabatic inspiral

## Infrared problems at second order [Pound 2015]



- suppose we try to use “typical”  $h_{\mu\nu}^1$  to construct source for  $h_{\mu\nu}^2$
- because  $|z^\mu - z_0^\mu|$  blows up with time,  $h_{\mu\nu}^2$  does likewise
- because  $h_{\mu\nu}^1$  contains outgoing waves at all past times, the source  $\delta^2 R_{\mu\nu}[h^1]$  decays too slowly, and *its retarded integral does not exist*
- instead, we must construct a uniform approximation
  - $h_{\mu\nu}^1$  must include evolution of orbit
  - radiation must decay to zero in infinite past

# Matched expansions [Pound, Miller, Moxon, Flanagan, Hinderer, Yamada, Isoyama, Tanaka]



## Multiscale expansion

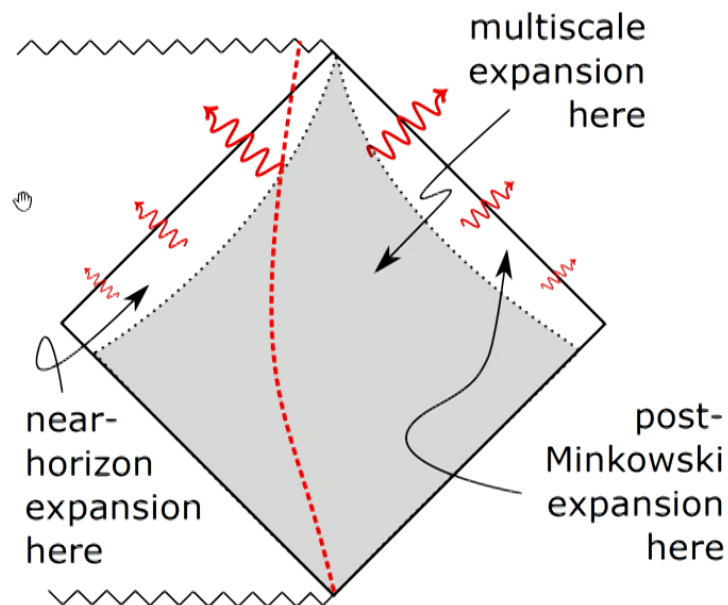
$$J^\alpha = J_0^\alpha(\tilde{t}) + \epsilon J_1^\alpha(\tilde{t}) + \dots$$

$$h_{\mu\nu}^n \sim \sum_{k^\alpha} h_{k^\alpha}^n(\tilde{t}) e^{-ik^\alpha q_\alpha(\tilde{t})}$$

- $(J^\alpha, q_\alpha)$  are action-angle variables for  $z^\mu$ , and  $\tilde{t} \sim \epsilon t$  is a “slow time”
- solve for  $h_{k^\alpha}^n$  at fixed  $\tilde{t}$  with standard frequency-domain techniques



# Matched expansions [Pound, Miller, Moxon, Flanagan, Hinderer, Yamada, Isoyama, Tanaka]



## Multiscale expansion

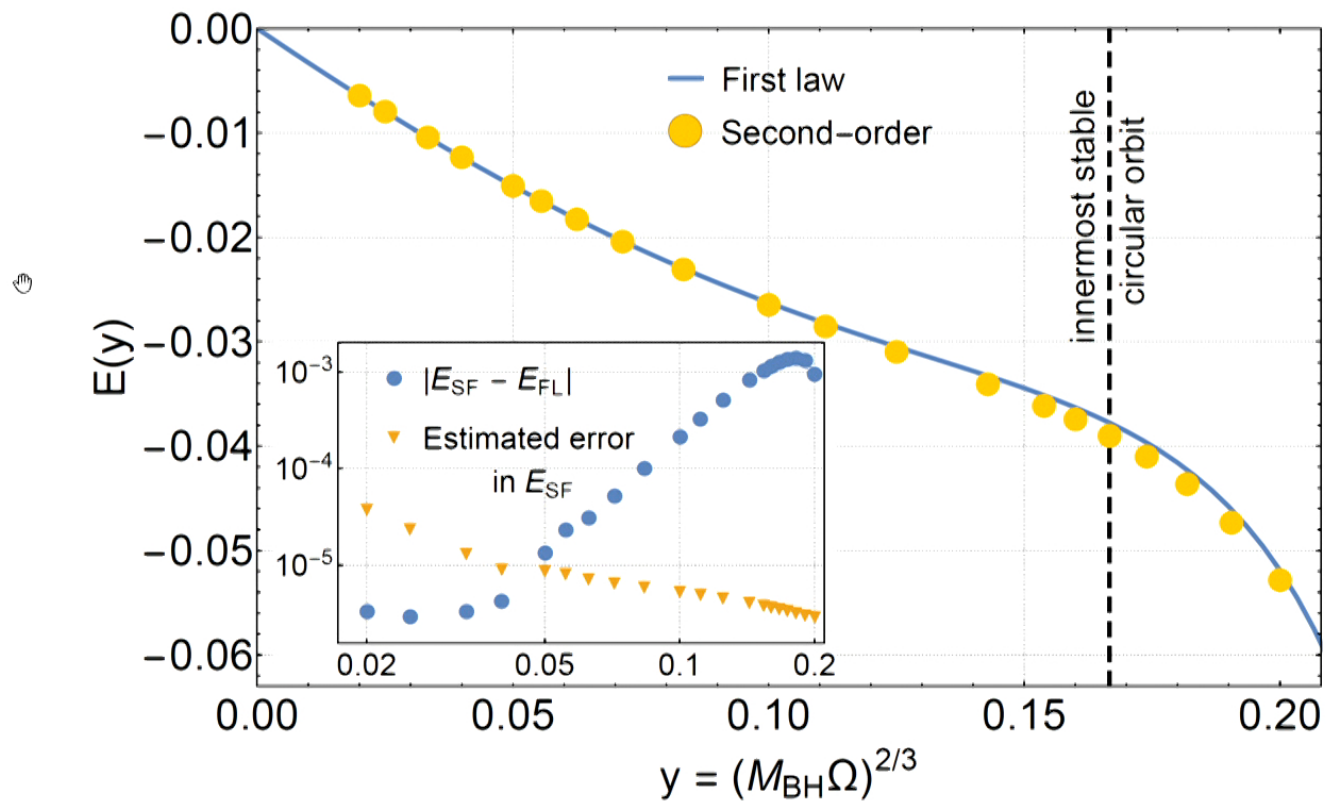
$$J^\alpha = J_0^\alpha(\tilde{t}) + \epsilon J_1^\alpha(\tilde{t}) + \dots$$

$$h_{\mu\nu}^n \sim \sum_{k^\alpha} h_{k^\alpha}^n(\tilde{t}) e^{-ik^\alpha q_\alpha(\tilde{t})}$$

- $(J^\alpha, q_\alpha)$  are action-angle variables for  $z^\mu$ , and  $\tilde{t} \sim \epsilon t$  is a "slow time"
- solve for  $h_{k^\alpha}^n$  at fixed  $\tilde{t}$  with standard frequency-domain techniques

# Binding energy [Pound, Wardell, Warburton, Miller]

Second-order piece of  $E_{\text{bind}} = M_{\text{Bondi}} - m - M_{\text{BH}}$



## Calculations performed as of 2005

		Adiabatic	1st order	2nd order
Schwarz.	circular	✓		
	generic	✓		
Kerr	circular	✓		
	generic			<b>holy grail</b>

## Calculations performed as of 2019

		Adiabatic	1st order	2nd order
Schwarz.	circular	✓	✓	✓
	generic	✓	✓	
Kerr	circular	✓	✓	
	generic	✓	✓	<b>holy grail</b>

# Conclusion

## Challenge

- accurate (post-adiabatic) model requires second-order self-force calculations for generic bound orbits in Kerr

## Prospects

- adiabatic inspirals should suffice for signal detection in most cases. Templates are on the way.
- post-adiabatic inspirals should enable high-precision parameter estimation. Lots of work to do.

For more information, see recent review by Barack and Pound (arXiv:1805.10385)

# Equation of motion

Solving EFE in buffer region yields equations of motion for object's effective center of mass

1st order, arbitrary compact object [MiSaTaQuWa 1996]:

$$\frac{D^2 z^\mu}{d\tau^2} = -\frac{1}{2} (g^{\alpha\delta} + u^\alpha u^\delta) (2h_{\delta\beta;\gamma}^{R1} - h_{\beta\gamma;\delta}^{R1}) u^\beta u^\gamma + \frac{1}{2m} R^\alpha{}_{\beta\gamma\delta} u^\beta S^{\gamma\delta} + O(m^2)$$

<sup>I</sup>  
(motion of spinning test body in  $g_{\mu\nu} + h_{\mu\nu}^{R1}$ )

2nd-order, nonspinning, spherical compact object [Pound 2012]:

$$\frac{D^2 z^\mu}{d\tau^2} = -\frac{1}{2} (g^{\mu\nu} + u^\mu u^\nu) (g_\nu{}^\rho - h_\nu{}^\rho) (2h_{\rho\sigma;\lambda}^R - h_{\sigma\lambda;\rho}^R) u^\sigma u^\lambda + O(m^3)$$

(geodesic motion in  $g_{\mu\nu} + h_{\mu\nu}^R$ )

# Equation of motion

Solving EFE in buffer region yields equations of motion for object's effective center of mass

1st order, arbitrary compact object [MiSaTaQuWa 1996]:

$$\frac{D^2 z^\mu}{d\tau^2} = -\frac{1}{2} (g^{\alpha\delta} + u^\alpha u^\delta) (2h_{\delta\beta;\gamma}^{R1} - h_{\beta\gamma;\delta}^{R1}) u^\beta u^\gamma + \frac{1}{2m} R^\alpha{}_{\beta\gamma\delta} u^\beta S^{\gamma\delta} + O(m^2)$$

I  
(motion of spinning test body in  $g_{\mu\nu} + h_{\mu\nu}^{R1}$ )

2nd-order, nonspinning, spherical compact object [Pound 2012]:

$$\frac{D^2 z^\mu}{d\tau^2} = -\frac{1}{2} (g^{\mu\nu} + u^\mu u^\nu) (g_\nu{}^\rho - h_\nu{}^\rho) (2h_{\rho\sigma;\lambda}^R - h_{\sigma\lambda;\rho}^R) u^\sigma u^\lambda + O(m^3)$$

(geodesic motion in  $g_{\mu\nu} + h_{\mu\nu}^R$ )

- these results are derived *directly from EFE outside the object*; there's no regularization of infinities, and no assumptions about  $h_{\mu\nu}^R$