

Title: General Relativity for Cosmology - Lecture 22

Speakers: Achim Kempf

Collection: General Relativity for Cosmology (Kempf)

Date: November 26, 2019 - 4:00 PM

URL: <http://pirsa.org/19110007>

A singularity theorem:

Assume that:

- (M, g) is a globally hyperbolic spacetime
- The energy-momentum tensor of matter obeys the

Strong energy condition :

Notice: Since the Einstein equation can be brought in the form $R_{\mu\nu} = T_{\mu\nu} - \frac{1}{2}Tg_{\mu\nu}$, the strong energy condition is a condition on the Ricci tensor too. This will be the use of the strong energy condition.

$$(T_{\mu\nu} - \frac{1}{2}Tg_{\mu\nu})\xi^\mu\xi^\nu \geq 0 \quad \forall \text{ timelike } \xi.$$

- There exists a C^2 spacelike Cauchy surface Σ , on which the trace of the extrinsic curvature, K , is bounded from above by a negative constant C :

$$K(p) \leq C < 0 \quad \text{for all } p \in \Sigma$$

Then:

No past-directed timelike curve from a spacelike hypersurface Σ can have eigentime, i.e., proper length, larger than $\frac{3}{c}$.

J.e.: All past-directed timelike geodesics are incomplete.

\Rightarrow There is a cosmological singularity in the finite past!
 because all past-directed paths end on it.

Extrinsic curvature?

later move on this

□ The extrinsic curvature of a spacelike hypersurface describes how much curvature there is in between the spacelike hypersurface and the time dimension.

Intuitively: it is the rate of the expansion of spacetime, more precisely its negative, the rate of contraction.

Thus: Assuming $K(p) \leq C < 0$ ^{$\forall p \in \Sigma$} means that spacetime has a finite minimum expansion rate everywhere on Σ .

→ We'll define expansion below in detail.

The strong energy condition?

Recall:

□ The "weak energy condition":

$$T_{\mu\nu} v^\mu v^\nu \geq 0 \text{ for all timelike } v: g(v,v) < 0$$

Meaning? For an observer with unit tangent v the local energy density is: $T_{\mu\nu} v^\mu v^\nu \geq 0$

□ The "dominant energy condition":

$$T_{\mu\nu} v^\mu v^\nu \geq 0 \text{ and } K_\mu K^\mu \leq 0$$

weak energy condition ↑ i.e. $T_{\mu\nu} v^\nu$ is non-space-like.

where v is any timelike vector and $K_\mu := T_{\mu\nu} v^\nu$

Meaning? The local energy-momentum flow vector K may not be conserved but has to be non-space-like: Flow should be into the future to avoid for causality.

Recall:

□ The "weak energy condition":

$$T_{\mu\nu} v^\mu v^\nu \geq 0 \text{ for all timelike } v: g(v,v) < 0$$

Meaning? For an observer with unit tangent v the local energy density is: $T_{\mu\nu} v^\mu v^\nu \geq 0$

□ The "dominant energy condition":

$$\underbrace{T_{\mu\nu} v^\mu v^\nu \geq 0}_{\text{weak energy condition}} \text{ and } K_\mu K^\mu \leq 0$$

↑ i.e. $T_{\mu\nu} v^\nu$ is non-space-like.

where v is any timelike vector and $K_\mu := T_{\mu\nu} v^\nu$

Meaning? The local energy-momentum flow vector K may not be conserved but has to be non-space-like: Flow should be into the future ← need for causality.

□ The "strong energy condition"

Matter is said to obey the strong energy condition iff:

$$(T_{\mu\nu} - \frac{1}{2} T^{\sigma}{}_{\sigma} g_{\mu\nu}) \xi^{\mu} \xi^{\nu} \geq 0 \quad \forall \text{ timelike } \xi.$$

- Intuition? ^{↙ as we will discuss below} Excludes matter that causes accelerated expansion.
- Plausible? Yes, obeyed by known matter.
(but not by dark energy)
- Relationship? Independent of weak and dominant energy conditions.



Type here to search



4:20 PM
2019-11-26



$$T_{\mu\nu} = \begin{pmatrix} S & & & \\ & P & & \\ & & P & \\ & & & P \end{pmatrix}$$

$$T_{00} + \frac{1}{2}(-T_{00} + 3T_{11}) \geq 0$$

$$S + \frac{1}{2}(-S + 3P) \geq 0$$

$$P = wS$$

$$\frac{S}{2} \geq -\frac{3}{2}P$$

$$P \leq -\frac{1}{3}S$$

$$w \geq -\frac{1}{3}$$

condition iff:

$$(T_{\mu\nu} - \frac{1}{2} T^{\sigma}{}_{\sigma} g_{\mu\nu}) \xi^{\mu} \xi^{\nu} \geq 0 \quad \forall \text{ timelike } \xi.$$

- Intuition? as we will discuss below Excludes matter that causes accelerated expansion.
- Plausible? Yes, obeyed by known matter.
(but not by dark energy)
- Relationship? Independent of weak and dominant energy conditions.

Concretely: For known matter, $T_{\mu\nu}$ is diagonalizable to obtain:

$$T_{\mu\nu} = \begin{pmatrix} \rho & & & \\ & p_1 & & \\ & & p_2 & \\ & & & p_3 \end{pmatrix}$$

\swarrow energy density observed by comoving observer
 \nwarrow principal pressures

The energy conditions then read:

□ Weak: $\rho \geq 0$ and $\rho + p_i \geq 0$ for $i \in \{1, 2, 3\}$

□ Dominant: $\rho \geq |p_i|$ for $i \in \{1, 2, 3\}$

Exercise:

Show this \rightarrow

□ Strong: $\rho + \sum_{i=1}^3 p_i \geq 0$ and $\rho + p_i \geq 0$ for $i \in \{1, 2, 3\}$

\uparrow Note: could possibly be also negative.

Recall: A cosmological constant Λ can be viewed as a contribution to $T_{\mu\nu}$.

Indeed, there is no big bang singularity, e.g., if $w = -1 \forall t$,
 i.e., in de Sitter spacetime inflation $a(t) = e^{Ht}$ \downarrow

Exercise: Show that the strong energy condition is violated in cosmology
 iff $w < -\frac{1}{3}$, i.e., iff the expansion is accelerating: $\ddot{a}(t) > 0$.

Given, in particular, the strong energy condition, one can show that geodesics meet a divergence of a quantity called **expansion**, θ , in finite proper time:

The "expansion", θ : important notion also e.g. in study of grav. collapse of stars.

□ Consider a "**congruence of timelike geodesics**" e.g., freely falling dust. through Σ , i.e., a smooth family of timelike geodesics, exactly one through each $p \in \Sigma$. If parametrized by proper time, their tangent vector field ξ , namely

exactly one through each $p \in \Sigma$. If parametrized by proper time, their tangent vector field ξ , namely

$$\xi := \frac{d}{d\tau} \leftarrow \text{proper time}$$

will obey: $g(\xi, \xi) = -1 \quad \forall p$.

□ Consider now a one-parameter subfamily of these geodesics:

$$x(\tau, s) \leftarrow \text{parameter of family of neighboring geodesics.}$$

\leftarrow a "connecting vector field"

will obey : $g(\xi, \xi) = -1 \quad \forall p.$

□ Consider now a one-parameter sub family of these geodesics :

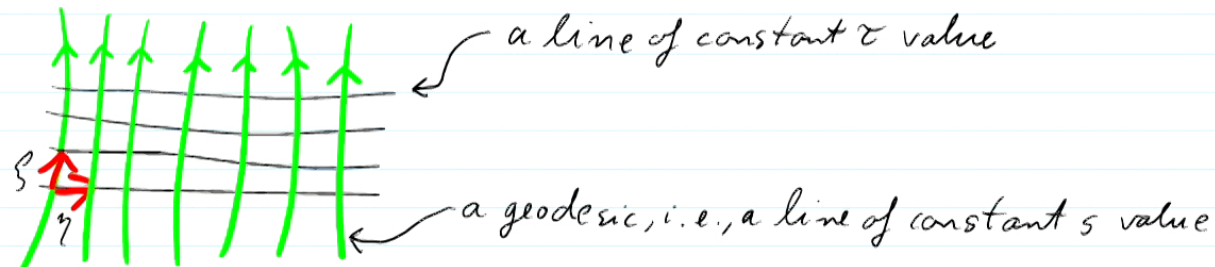
$$x(\tau, s)$$

← parameter of family of neighboring geodesics.

← a "connecting vector field"

Then, we define the deviation vector :

$$\eta := \frac{d}{ds}$$



Type here to search



4:35 PM
2019-11-26



□ How does η change along a geodesic?

τ, s are Riemann normal coordinates for a geodesic traveller.

$$\Rightarrow \frac{d}{d\tau} \frac{d}{ds} = \frac{d}{ds} \frac{d}{d\tau}, \text{ i.e., } [\xi, \eta] = 0$$

□ Since the torsion vanishes: $0 = \mathcal{T}(\xi, \eta) = \nabla_{\xi} \eta - \nabla_{\eta} \xi - [\xi, \eta]$

$$\Rightarrow \nabla_{\xi} \eta = \nabla_{\eta} \xi$$

$$\Rightarrow \xi^{\alpha} \nabla_{e_{\alpha}} \eta^{\nu} e_{\nu} = \eta^{\alpha} \nabla_{e_{\alpha}} \xi^{\beta} e_{\beta}$$

$$\Rightarrow \xi^{\alpha} \eta^{\nu}{}_{;\alpha} e_{\nu} = \eta^{\alpha} \xi^{\beta}{}_{;\alpha} e_{\beta}$$

$$\Rightarrow \xi^{\alpha} \eta^{\nu}{}_{;\alpha} = \eta^{\alpha} \xi^{\beta}{}_{;\alpha} = \eta^{\alpha} B^{\nu}{}_{\alpha} \text{ for } B^{\nu}{}_{\mu} := \xi^{\nu}{}_{;\mu}$$

\Rightarrow Along the geodesic's direction, ξ , the deviation vector η^{ν} changes its direction and length by $B^{\nu}{}_{\mu} \eta^{\mu}$.

□ The tensor $B^{\nu}{}_{\mu}$ can be decomposed covariantly and uniquely into:

$$\Rightarrow \xi^\nu \nabla_{e_\mu} \eta^\rho = \eta^\rho \nabla_{e_\mu} \xi^\nu$$

$$\Rightarrow \xi^\mu \eta^\nu{}_{;\mu} e_\nu = \eta^\mu \xi^\nu{}_{;\mu} e_\nu$$

$$\Rightarrow \xi^\mu \eta^\nu{}_{;\mu} = \eta^\mu \xi^\nu{}_{;\mu} = \eta^\mu B^\nu{}_\mu \text{ for } B^\nu{}_\mu := \xi^\nu{}_{;\mu}$$

\Rightarrow Along the geodesic's direction, ξ , the deviation vector η^ν changes its direction and length by $B^\nu{}_\mu \eta^\mu$.

□ The tensor $B^\nu{}_\mu$ can be decomposed covariantly and uniquely into:

$$B_{\mu\nu} = \omega_{\mu\nu} + \sigma_{\mu\nu} + \epsilon_{\mu\nu} \quad \left(\begin{array}{l} \text{all 3 terms are tensors} \\ \text{because the split is covariant} \end{array} \right)$$

Symmetric and trace = 0
↓
↑
anti-symmetric
rest

Cosmic ballet tensor field.

$$B_{\mu\nu} = \omega_{\mu\nu} + \sigma_{\mu\nu} + \epsilon_{\mu\nu}$$

$$B_{\mu\nu} = \omega_{\mu\nu} + G_{\mu\nu} + t_{\mu\nu}$$

Cosmic ballet tensor field.

Symmetric and trace = 0
 anti-symmetric
 rest

(all 3 terms are tensors because the split is covariant)

We have: $\omega_{\mu\nu} = \frac{1}{2}(B_{\mu\nu} - B_{\nu\mu})$, clearly.

But $G_{\mu\nu}, t_{\mu\nu} = ?$

In preparation: define the projector $h_{\mu\nu}$ onto $(\mathbb{R}\xi)^\perp$ i.e. onto the spatial components:

↑
is timelike

$$h_{\mu\nu} := g_{\mu\nu} + \xi_\mu \xi_\nu$$

Check: is $h_{\mu\nu} w^\nu$ really always \perp to ξ ?

Cosmic ballet
tensor field.

↑
antisymmetric

rest

(because we are in covariant)

We have: $\omega_{\mu\nu} = \frac{1}{2}(B_{\mu\nu} - B_{\nu\mu})$, clearly.

But $g_{\mu\nu}, t_{\mu\nu} = ?$

In preparation: define the projector $h_{\mu\nu}$ onto $(\mathbb{R}\xi)^\perp$ i.e.
onto the spatial components:

↑
is timelike

$$h_{\mu\nu} := g_{\mu\nu} + \xi_\mu \xi_\nu$$

Check: is $h_{\mu\nu} w^\nu$ really always \perp to ξ ?

$$\text{Indeed: } \xi^\mu h_{\mu\nu} w^\nu = (\xi, w) + \overbrace{(\xi, \xi)}^{-1} (\xi, w) = 0$$

Define: The "expansion", θ , is defined as the magnitude of the spatial part of B :

$$\theta := B^{\mu\nu} h_{\mu\nu}$$

Claim: $\text{Tr}(B) = \theta$

Indeed: $\theta = B^{\mu\nu} h_{\mu\nu} = B^{\mu\nu} g_{\mu\nu} + \xi^\mu \xi_\nu B_{\mu\nu}$
 $= \text{Tr}(B) + \xi^\mu \xi_\nu \nabla_\mu \xi^\nu$ (= 0 because $\nabla_\mu \xi^\mu = 0$ for geodesics.)

Therefore: $\sigma_{\mu\nu} = \frac{1}{2} (B_{\mu\nu} + B_{\nu\mu}) - \frac{1}{3} \theta h_{\mu\nu}$ (because:
 $\text{Tr}(h_{\mu\nu}) = g^{\mu\nu} h_{\mu\nu}$
 $= g^{\mu\nu} (g_{\mu\nu} + \xi_\mu \xi_\nu)$
 $= 4 - 1$)

↑ the part of $B_{\mu\nu}$ which is symmetric and traceless.

and:

$$t_{\mu\nu} = \frac{1}{3} \theta h_{\mu\nu} \quad \leftarrow \text{the "rest term"}$$

$$B_{\mu\nu} = \omega_{\mu\nu} + G_{\mu\nu} + t_{\mu\nu}$$
 (all 3 terms are tensors because the split is covariant)

Cosmic ballet tensor field.

Symmetric and trace = 0
 anti-symmetric
 rest

We have: $\omega_{\mu\nu} = \frac{1}{2}(B_{\mu\nu} - B_{\nu\mu})$, clearly.

But $G_{\mu\nu}, t_{\mu\nu} = ?$

In preparation: define the projector $h_{\mu\nu}$ onto $(\mathbb{R}\xi)^\perp$ i.e. onto the spatial components:

↑
is timelike

$$h_{\mu\nu} := g_{\mu\nu} + \xi_\mu \xi_\nu$$

Check: is $h_{\mu\nu} w^\nu$ really always \perp to ξ ?

$$\tilde{n}^{-1}$$

Define: The "expansion", θ , is defined as the magnitude of the spatial part of B :

$$\theta := B^{\mu\nu} h_{\mu\nu}$$

Claim: $\text{Tr}(B) = \theta$

Indeed: $\theta = B^{\mu\nu} h_{\mu\nu} = B^{\mu\nu} g_{\mu\nu} + \xi^\mu \xi_\nu B_\mu^\nu$
 $= \text{Tr}(B) + \xi^\mu \xi_\nu \nabla_\mu \xi^\nu$ (= 0 because $\nabla_\mu \xi^\nu = 0$ for geodesics.)

Therefore: $\sigma_{\mu\nu} = \frac{1}{2} (B_{\mu\nu} + B_{\nu\mu}) - \frac{1}{3} \theta h_{\mu\nu}$ (because:
 $\text{Tr}(h_{\mu\nu}) = g^{\mu\nu} h_{\mu\nu}$
 $= g^{\mu\nu} (g_{\mu\nu} + \xi_\mu \xi_\nu)$
 $= 4 - 1$)

↑ the part of $B_{\mu\nu}$ which is symmetric and traceless.

and:

$$t_{\mu\nu} = \frac{1}{3} \theta h_{\mu\nu} \quad \leftarrow \text{the "rest term"}$$

□ Interpretation:

a.) $\omega_{\mu\nu}$ is antisymmetric: $\omega_{\mu\nu} = -\omega_{\nu\mu}$
 \Rightarrow it generates Lorentz transformation for η .

but all η are \perp to the time direction

\Rightarrow $\omega_{\mu\nu}$ generates spatial rotations of neighboring geodesics around another. So, $\omega_{\mu\nu}$ is called

$\omega =$ "Twists tensor"

One can prove: (nontrivial)

If one chooses the congruence of geodesics \perp to Σ then $\omega_{\mu\nu} = 0$.

b.) $\sigma_{\mu\nu}$ is symmetric, $\sigma_{\mu\nu} = \sigma_{\nu\mu}$. (i.e. hermitean)


Consider "diagonalized", by suitable choice of cd basis.

\Rightarrow $\sigma_{\mu\nu}$ changes the relative lengths of the basis vectors, by multiplying them with its eigenvalues.

i.e. points on a sphere will under geodesic flow \rightarrow become points on an ellipsoid.

Note: Since $\text{Tr}(\sigma) = 0$ we have $\det(e^{\pm\sigma}) = 1$
 \swarrow infinitesimal transport along geodesics
 \nwarrow finite transport

\Rightarrow The volume spanned by basis vectors stays the same under the action of σ .

\rightsquigarrow Definition: $\sigma_{\mu\nu} =: \text{"Shear tensor"}$ 

c.) While the twist and shear tensors are both traceless and therefore volume-preserving, we see that the trace part, θ , i.e., more precisely

$$t_{\mu\nu} = \frac{1}{3} \theta h_{\mu\nu} =: \text{"Expansion tensor"}$$

↑ recall: is projector on spatial part.

is indeed generating the spatial expansion or contraction of nearby geodesics!

Evolution of θ along a geodesic?

Recall:

Given, in particular, the strong energy condition, our singularity theorem claimed that geodesics meet a divergence of a quantity called **expansion**, θ , in finite proper time in the past and this will mean a big bang singularity:

The "expansion", θ : important notion also e.g. in study of grav. collapse of stars.

□ Consider a "**congruence of timelike geodesics**" e.g., freely falling dust. through Σ , i.e., a smooth family of timelike geodesics, exactly one through each $p \in \Sigma$: (Σ is a (spatial) surface)

The "expansion", θ :

important notion also e.g. in study of grav. collaps of stars.

- Consider a "congruence of timelike geodesics" through Σ , i.e., a smooth family of timelike geodesics, exactly one through each $p \in \Sigma$: (Σ is a Cauchy surface)
 e.g., freely falling dust.

- We consider a one-parameter sub-family of these geodesics:

$\gamma(\tau, s)$

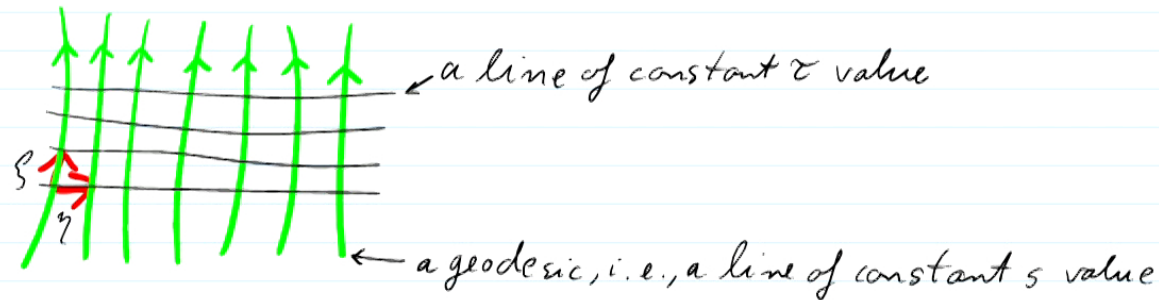
↑
proper time

↑ parameter of family of neighboring geodesics.

□ We consider a one-parameter sub-family of these geodesics:

$$x(\tau, s)$$

\uparrow \leftarrow parameter of family of neighboring geodesics.
 eigentime



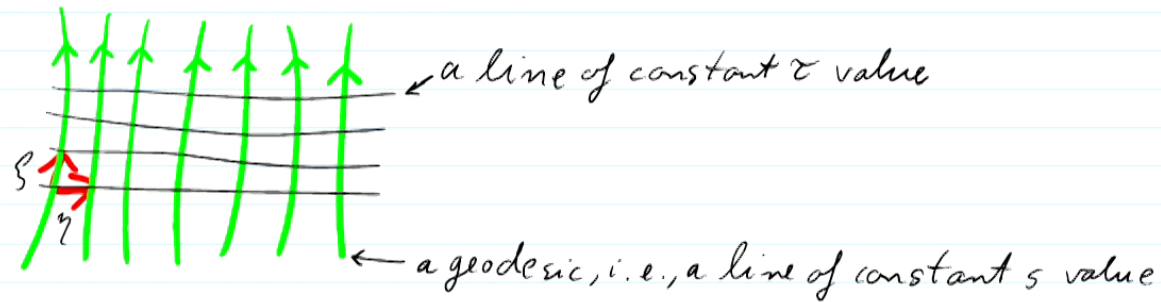
□ Then, we define the deviation vector to a neighboring geodesic:

$$\eta := \frac{d}{ds}$$

□ The singularity theorem claims that this happened in the past:



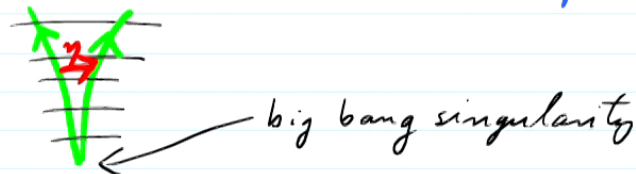
$x(\tau, s)$
 ↑ eigentime ← parameter of family of neighboring geodesics.



▢ Then, we define the deviation vector to a neighboring geodesic:

$$\eta := \frac{d}{ds}$$

▢ The singularity theorem claims that this happened in the past:



How does η change along a past-directed timelike geodesic with tangent ξ ?

We showed:

$$\xi^\nu \eta^\mu{}_{;\nu} = \eta^\mu B^\nu{}_\mu \quad \text{where} \quad B^\nu{}_\mu := \xi^\nu \eta^\mu{}_{;\nu}$$

\Rightarrow Along the geodesic, ξ , the deviation vector η^μ changes its direction and length by $B^\nu{}_\mu \eta^\mu$.

□ The tensor $B^\nu{}_\mu$ can be decomposed covariantly and uniquely:

$$B_{\mu\nu} = \omega_{\mu\nu} + \overset{\text{Symmetric and trace}=0}{G_{\mu\nu}} + \underset{\text{rest}}{t_{\mu\nu}}$$

Explicitly:

Volume preserving \rightarrow $\omega_{\mu\nu} = \frac{1}{2} (B_{\mu\nu} - B_{\nu\mu})$ Twist: $\circ \rightarrow \odot$

$\sigma_{\mu\nu} = \frac{1}{2} (B_{\mu\nu} + B_{\nu\mu}) - \frac{1}{3} \theta h_{\mu\nu}$ Shear: $\circ \rightarrow \parallel$

Volume changing: $\epsilon_{\mu\nu} = \frac{1}{3} \theta h_{\mu\nu}$ Expansion: $\circ \rightarrow \bigcirc$

Here, we defined: $\theta := B^{\mu\nu} g_{\mu\nu}$ and $h_{\mu\nu} := g_{\mu\nu} + \xi_\mu \xi_\nu$

I.e., the Expansion, θ , is the trace of B , which we showed is also equal to the magnitude of the spatial part of B : $\theta = B^{\mu\nu} h_{\mu\nu}$.

Key question:

What is the dynamics of θ ?

The Raychaudhuri equation

For the derivation, we will use:

A) Definition of B is: $B_{\mu\nu} := \xi_{\mu;\nu}$

B) The curvature tensor obeys the Ricci equation:

$$\xi^a{}_{;jbc} - \xi^a{}_{;jcb} = R^a{}_{bcd} \xi^d$$

C) ξ is tangent to a geodesic, i.e., it obeys: $\nabla_{\xi} \xi = 0$

$$\text{i.e.: } 0 = \nabla_{\xi} \xi^b e_b = \xi^a \nabla_{e_a} \xi^b e_b = \xi^a \xi^b{}_{;ja} e_b$$

True for all e_a , thus: $\xi^a \xi^b{}_{;ja} = 0$

Now calculate the rate of change of B along the geodesic:

$$\xi^c B_{ab;c} \stackrel{(A)}{=} \xi^c \xi_{a;bc}$$

$\nabla_{\xi} B$

$$\stackrel{(B)}{=} \xi^c \xi_{a;cb} + \xi^c R_{abcd} \xi^d$$

$$\stackrel{\text{Leibniz rule}}{=} \underbrace{(\xi^c \xi_{a;c})}_{=0};b - \xi^c \xi_{ib} \xi_{a;c} + R_{abcd} \xi^c \xi^d$$

$$\stackrel{(C)}{=} -\xi^c \xi_{ib} \xi_{a;c} + R_{abcd} \xi^c \xi^d$$

$$\stackrel{(A)}{=} -B^c_b B_{ac} + R_{abcd} \xi^c \xi^d$$

In summary, we derived:

$$\xi^c B_{ab;c} = -B^c_b B_{ac} + R_{abcd} \xi^c \xi^d \quad (*)$$

The trace of (*) will be the Raychaudhuri equation.

But first, we recall:

$$\square \xi = \frac{d}{d\tau}$$

$$\square \text{Tr} B = B_{\mu\nu} g^{\mu\nu} = \theta$$

$$\Rightarrow \text{Trace(LHS) of (*) reads } \frac{d}{d\tau} \theta !$$

Now on the RHS of (*) use the decomposition

$$B_{\mu\nu} = \omega_{\mu\nu} + \sigma_{\mu\nu} + \frac{1}{3} \theta h_{\mu\nu} \text{ to express } B^c_b B_{ac}:$$

$$\begin{aligned}
 B^c_b B_{ac} &= \omega^c_b (\omega_{ac} + \sigma_{ac} + \frac{1}{3} \theta h_{ac}) \\
 &+ \sigma^c_b (\omega_{ac} + \underline{G_{ac}} + \frac{1}{3} \theta h_{ac}) \\
 &+ \frac{1}{3} \theta h^c_b (\omega_{ac} + G_{ac} + \frac{1}{3} \theta h_{ac})
 \end{aligned}$$

When taking the trace, $g^{ab} B^c_b B_{ac}$, only the diagonal terms survive:

$$\text{Tr}(BB) = g^{ab} B^c_b B_{ac} = \omega_{ab} \omega^{ab} + G_{ab} G^{ab} + \frac{1}{9} \theta^2 h_{ab} h^{ab}$$

Exercise: show it is 3

The Raychaudhuri equation is then the trace of Eq. (*) :

$$\frac{d\theta}{d\tau} = -\frac{1}{3} \theta^2 - \underbrace{G_{ab} G^{ab}}_{\text{always positive}} - \underbrace{\omega_{ab} \omega^{ab}}_{\text{always positive (and vanishes if choose congruence } \perp \Sigma)} - \underbrace{R_{cd} \xi^c \xi^d}_{\text{pos. or neg. ?}}$$

recall Ricci tensor is $R_{cd} = R_{cd}{}^a{}_a$

pos. or neg. ?

$$\begin{aligned}
 & \omega_b \omega_{ac} - \omega_b \omega_{ac} + \omega_{ac} \cdot 3 \omega_{nac} \\
 & + \sigma^c_b (\omega_{ac} + \sigma_{ac} + \frac{1}{3} \theta h_{ac}) \\
 & + \frac{1}{3} \theta h^a_b (\omega_{ac} + \sigma_{ac} + \frac{1}{3} \theta h_{ac})
 \end{aligned}$$

When taking the trace, $g^{ab} B^c_b B_{ac}$, only the diagonal terms survive:

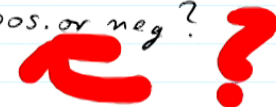
Exercise: show it is 3

$$\text{Tr}(BB) = g^{ab} B^c_b B_{ac} = \omega_{ab} \omega^{ab} + \sigma_{ab} \sigma^{ab} + \frac{1}{3} \theta^2 h_{ab} h^{ab}$$

The Raychaudhuri equation is then the trace of Eq. (*):

$$\frac{d\theta}{d\tau} = -\frac{1}{3} \theta^2 - \underbrace{\sigma_{ab} \sigma^{ab}}_{\text{always positive}} - \underbrace{\omega_{ab} \omega^{ab}}_{\text{always positive (and vanishes if choose congruence } \perp \Sigma)} - \underbrace{R_{cd} \xi^c \xi^d}_{\text{pos. or neg. ?}}$$

recall: Ricci tensor is $R_{cd} = R_{cd}{}^a{}_a$



$$T_{\mu\nu} = \begin{pmatrix} S & \\ & P_{PP} \end{pmatrix}$$

$$T_{00} + \frac{1}{2}(-T_{00} + 3T_{11}) \geq 0$$

$$\left(T_{\mu\nu} - \frac{1}{2}g_{\mu\nu}T \right) \xi^\mu \xi^\nu \geq 0$$

$$S + \frac{1}{2}(-S + 3P) \geq 0$$

$$P = wS$$

$$\frac{S}{2} \geq -\frac{3}{2}P$$

$$P \leq -\frac{1}{3}S$$

$$w \geq -\frac{1}{3}$$

Dynamics

□ Assume that

$$R_{\mu\nu} \xi^\mu \xi^\nu \geq 0 \quad \text{for all timelike } \xi$$

i.e., using the Einstein equation

$$R_{\mu\nu} = 8\pi G (T_{\mu\nu} - \frac{1}{2} g_{\mu\nu} T^a_a)$$

we are assuming that

$$T_{\mu\nu} \xi^\mu \xi^\nu - \frac{1}{2} \xi^\mu \xi_\mu T \geq 0 \quad \text{whenever } \xi^\mu \xi_\mu < 0$$

i.e. the Strong Energy Condition.



Type here to search



5:20 PM
2019-11-26

Thus, assuming the strong energy condition:

$$\frac{d\theta}{d\tau} + \frac{1}{3}\theta^2 \leq 0$$

$$\text{i.e., } -\frac{1}{\theta^2} \frac{d\theta}{d\tau} - \frac{1}{3} \geq 0$$

$$\text{i.e., } \boxed{\frac{d}{d\tau} \theta^{-1} \geq \frac{1}{3}} \quad (+)$$

Consider the cases when the geodesics are initially all either

a.) diverging, i.e., $\theta(\tau_0) > 0$ (expanding universe) or

b.) converging, i.e., $\theta(\tau_0) < 0$ (contracting universe)

(This is reformulating the theorem's assumption that the extrinsic curvature (i.e. the expansion or contraction at some time exceeds a certain finite value everywhere)

$$\frac{d\theta}{d\tau} + \frac{1}{3}\theta^2 \leq 0$$

$$\text{i.e., } -\frac{1}{\theta^2} \frac{d\theta}{d\tau} - \frac{1}{3} \geq 0$$

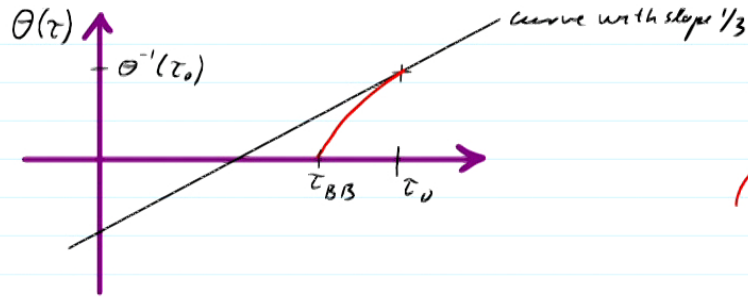
$$\text{i.e., } \boxed{\frac{d}{d\tau} \theta^{-1} \geq \frac{1}{3}} \quad (+)$$

Consider the cases when the geodesics are initially all either

- a.) diverging, i.e., $\theta(\tau_0) > 0$ (expanding universe) or
- b.) converging, i.e., $\theta(\tau_0) < 0$ (contracting universe)

(This is reformulating the theorem's assumption that the extrinsic curvature (i.e. the expansion or contraction at some time exceeds a certain finite value everywhere)

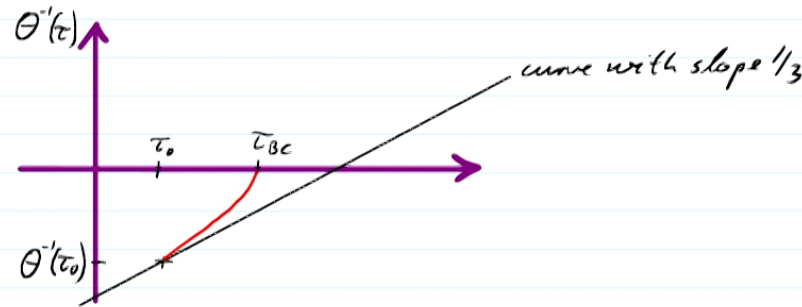
a.)



$\tau_0 = \text{e.g. today}$
 (= curve $\theta'(\tau)$ of slope $> \frac{1}{3}$

We see that $\theta'(\tau)$ must have hit $\theta'(\tau) = 0$ at a finite time τ_{BB} (Big Bang).

b.)



$\tau_0 = \text{e.g. today}$
 (= curve of slope $> \frac{1}{3}$

We see that $\theta'(\tau)$ will hit $\theta'(\tau) = 0$ at a finite time τ_{BC} (Big Crunch)

Conclusion:

Eq. (+) implies that $\theta(\tau)$ must go through 0, i.e.:

a.) for sufficiently early τ , have $\theta \rightarrow +\infty$, i.e.: Big Bang

b.) for sufficiently late τ , have $\theta \rightarrow -\infty$, i.e.: Big Crunch

Note:

This type of reasoning leads also to further cosmological singularity theorems.

E.g., another cosmological singularity theorem does not assume global hyperbolicity, and its conclusion is weaker:

There is at least one incomplete timelike geodesic.