

Title: Talk 10

Speakers:

Collection: Simplicity III

Date: September 11, 2019 - 9:45 AM

URL: <http://pirsa.org/19090079>

The ERC logo consists of a cluster of orange dots of varying sizes, with the lowercase letters 'erc' in a bold, black, sans-serif font to its right.

erc

The FNSNF logo features the letters 'FNSNF' in a bold, black, sans-serif font, with a blue square containing a white 'S' shape behind the 'N's.

FNSNF

The geometrical trinity of gravity

The ETH logo is the word 'ETH' in a large, bold, black, sans-serif font. Below it, in a smaller font, are the words 'Eidgenössische Technische Hochschule Zürich' and 'Swiss Federal Institute of Technology Zurich'.

ETH
Eidgenössische Technische Hochschule Zürich
Swiss Federal Institute of Technology Zurich

Lavinia Heisenberg
(ETH-ITP)
Institute for Theoretical Physics, Zürich
Lavinia.Heisenberg@phys.ethz.ch

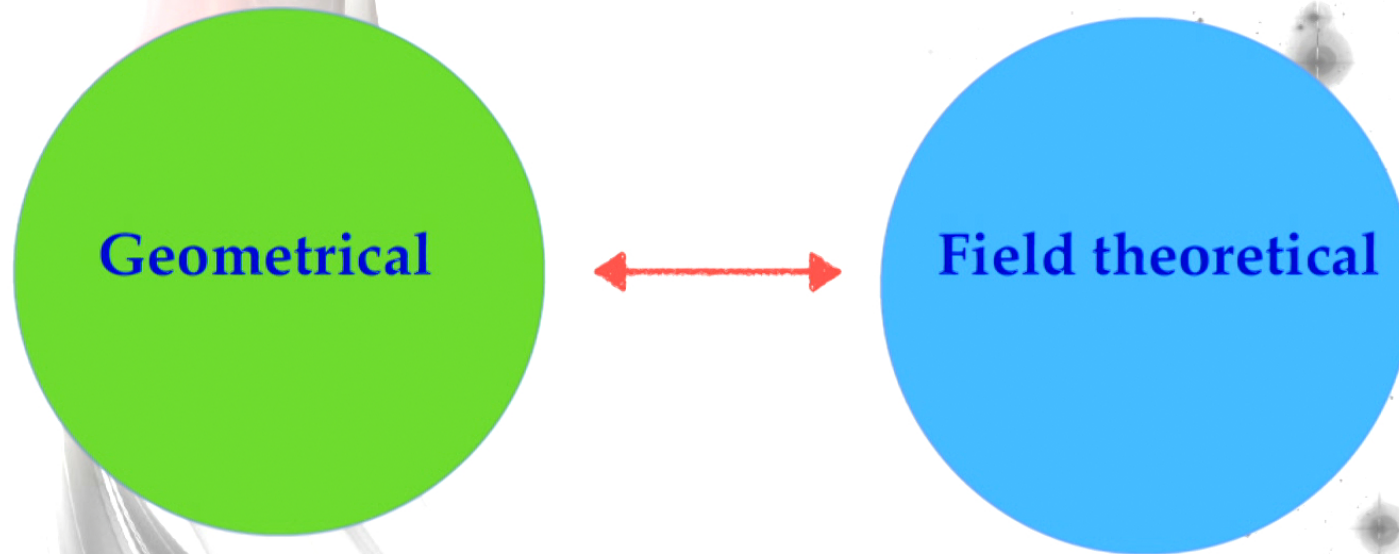
11th Sept 2019, Simplicity III, Perimeter Institute, Waterloo/Canada



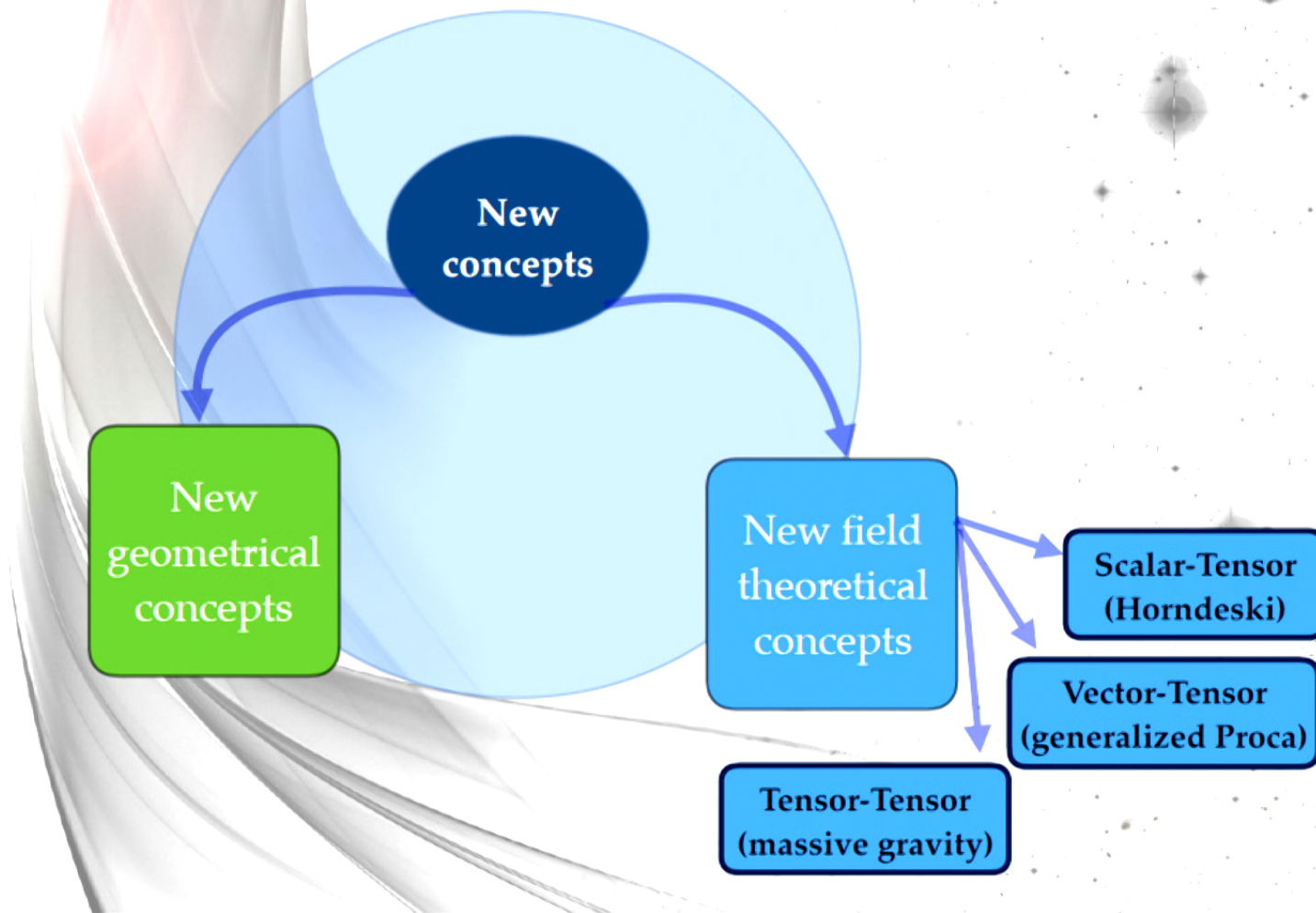
Q: Are you related to Werner Heisenberg?

LH: It is uncertain!

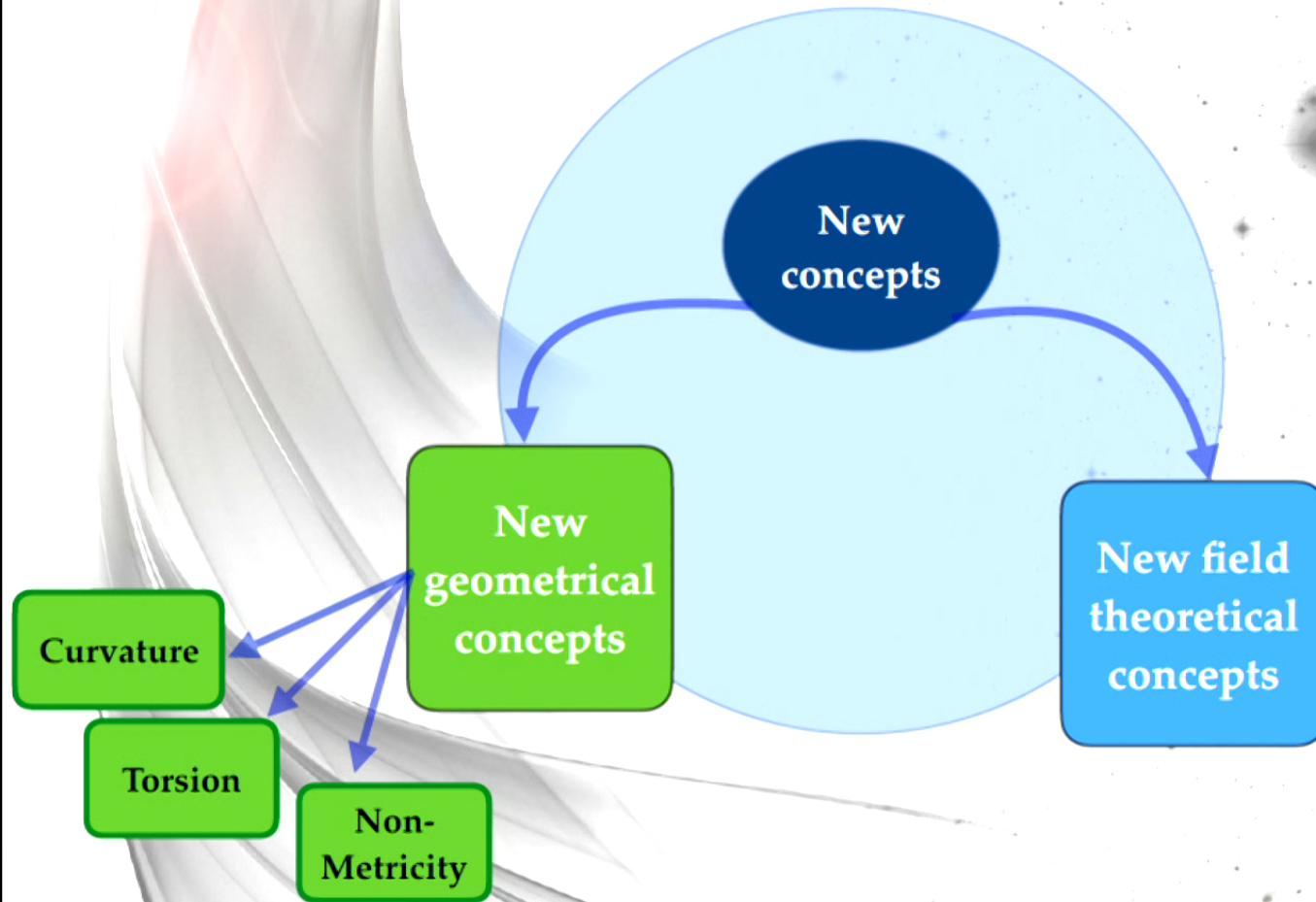
Different Interpretations of Gravity



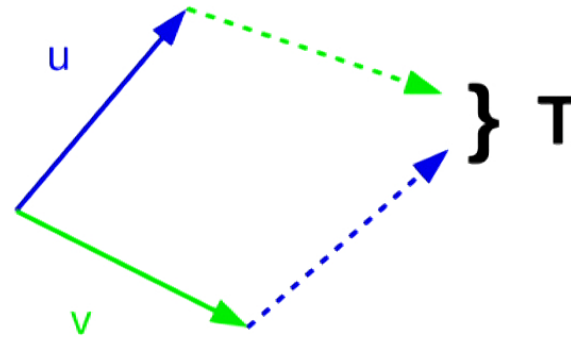
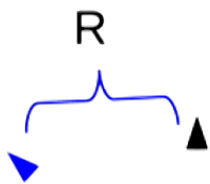
Gravity theories



Gravity theories

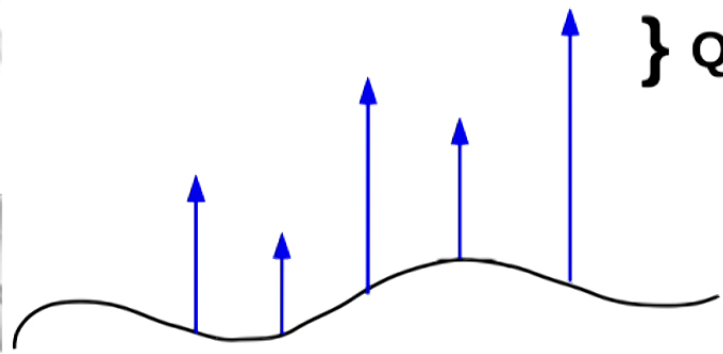


Geometrical objects



● Riemann: $R_{\beta\mu\nu}^{\alpha} \neq 0$

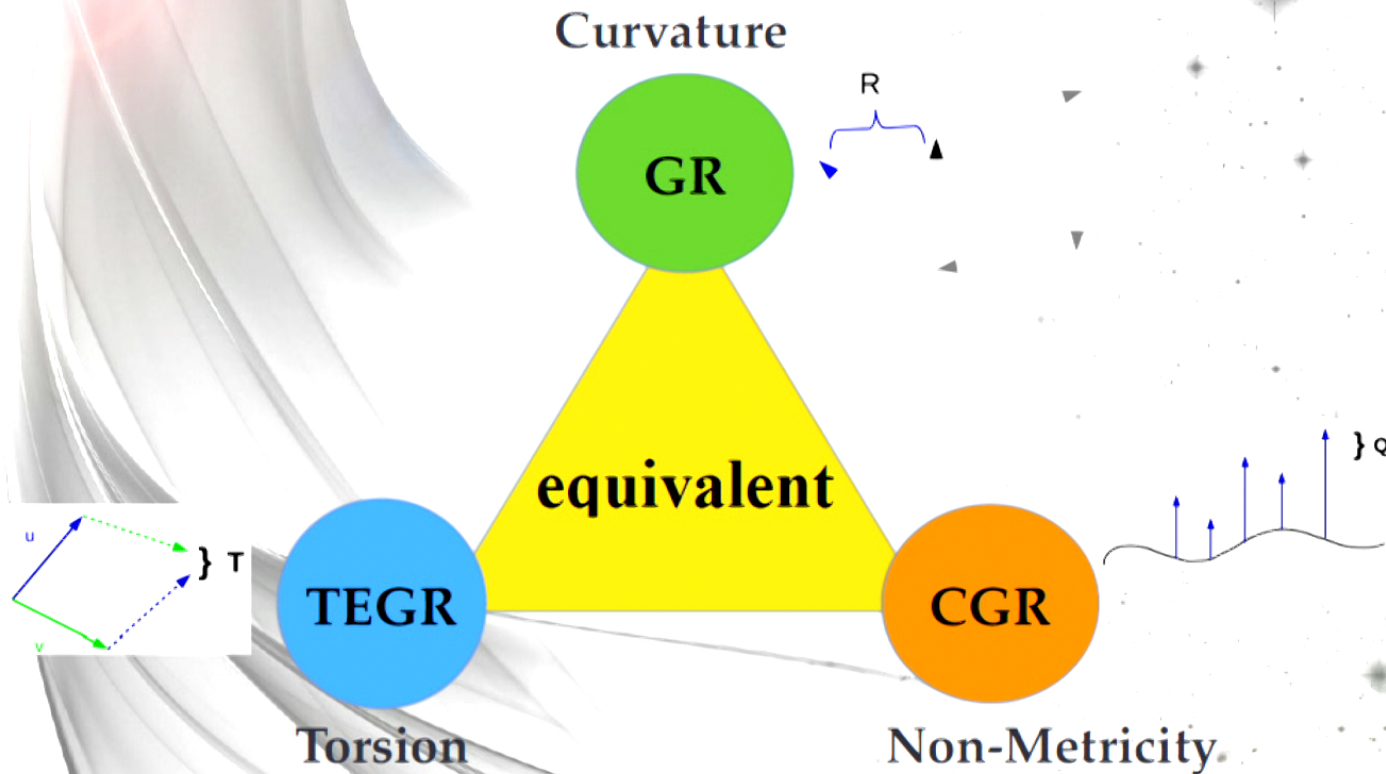
● Torsion: $T_{\mu\nu}^{\alpha} \neq 0$



● Non-metricity: $Q_{\mu\nu}^{\alpha} \neq 0$

Geometrical Trinity of GR!

L.H & J.Beltran, T.Koivisto
Universe 5 (2019) 7, 173,
arXiv:1903.06830





General Relativity (Curvature)

(pseudo-) Riemannian manifold



$$\Gamma_{\mu\nu}^{\alpha} = \{\overset{\alpha}{\underset{\mu\nu}{\}}\}$$

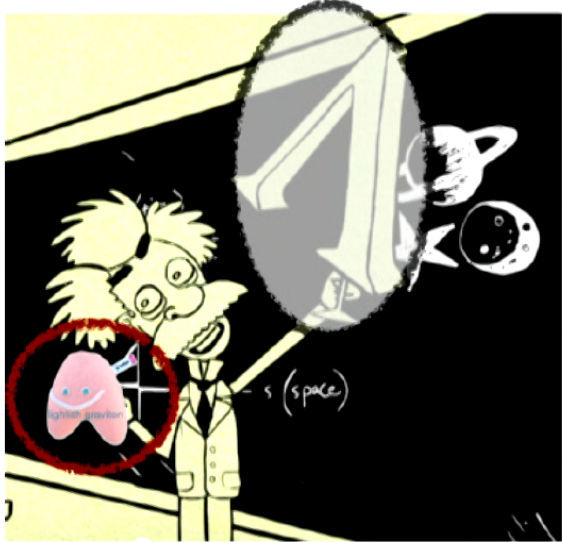
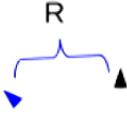
$$\{\overset{\alpha}{\underset{\mu\nu}{\}}\} = \frac{1}{2}g^{\alpha\lambda}(\partial_{\nu}g_{\lambda\mu} + \partial_{\mu}g_{\lambda\nu} - \partial_{\lambda}g_{\mu\nu})$$

● Riemann: $R_{\beta\mu\nu}^{\alpha} \neq 0$

● Torsion: $T_{\mu\nu}^{\alpha} = 0$

● Non-metricity: $Q_{\mu\nu}^{\alpha} = 0$

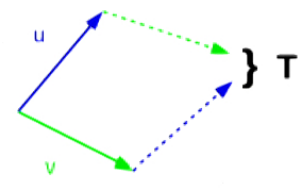
$$Q_{\mu\nu}^{\alpha} = \nabla_{\alpha}g_{\mu\nu}$$



TEGR

TEGR (Torsion)

a manifold based on torsion



$\Gamma^a_{\mu\nu}$

$$\Gamma^a_{\mu\nu} = \{^a_{\mu\nu}\} + K^a_{\mu\nu}(T)$$

$$K^a_{\mu\nu} = \frac{1}{2}T^a_{\mu\nu} + T_{(\mu}{}^a{}_{\nu)}$$

contorsion tensor

- Riemann: $R^{\alpha}_{\beta\mu\nu} = 0$

- Torsion: $T^{\alpha}_{\mu\nu} \neq 0$

- Non-metricity: $Q^{\alpha}_{\mu\nu} = 0$

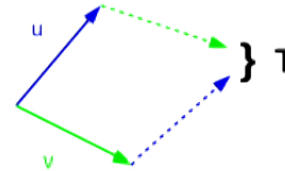
$$T^{\lambda}_{\mu\nu} = (\Gamma^{\lambda}_{\mu\nu} - \Gamma^{\lambda}_{\nu\mu})$$

↑
Torsion

TEGR

TEGR (Torsion)

a manifold based on torsion



$\Gamma^a_{\mu\nu}$

$$\Gamma^a_{\mu\nu} = \{^a_{\mu\nu}\} + K^a_{\mu\nu}(T)$$

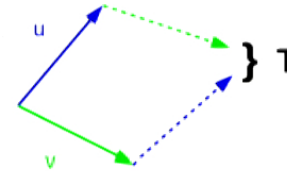
- Riemann: $R^{\alpha}_{\beta\mu\nu} = 0 \implies \Gamma^{\alpha}_{\mu\nu} = (\Lambda^{-1})^{\alpha}_{\lambda} \partial_{\mu} \Lambda^{\lambda}_{\nu}$
- Non-metricity: $Q^{\alpha}_{\mu\nu} = 0 \implies g^{\lambda(\mu} \partial_{\alpha} \Lambda^{\nu)\rho} (\Lambda^{-1})^{\rho}_{\lambda} = \frac{1}{2} \partial_{\alpha} g^{\mu\nu}$

$$T^{\alpha}_{\mu\nu} = 2(\Lambda^{-1})^{\alpha}_{\lambda} \partial_{[\mu} \Lambda^{\lambda}_{\nu]}$$

TEGR

TEGR (Torsion)

a manifold based on torsion



$\Gamma_{\mu\nu}^a$

$$\Gamma_{\mu\nu}^a = \{^a_{\mu\nu}\} + K_{\mu\nu}^a(T)$$

$$\mathcal{S} = \frac{1}{2} \sqrt{-g} (c_1 T_\alpha^{\mu\nu} T^\alpha_{\mu\nu} + c_2 T_\alpha^{\mu\nu} T_\mu^\alpha{}_\nu + c_3 T_\mu T^\mu) + \lambda_\alpha^{\beta\mu\nu} R_{\beta\mu\nu}^\alpha + \tilde{\lambda}_\alpha^{\mu\nu} Q_\alpha^{\mu\nu}$$

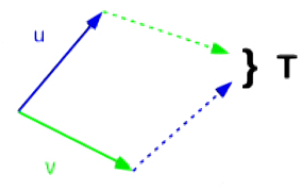
$$c_1 = \frac{1}{4}, \quad c_2 = \frac{1}{2}, \quad c_3 = -1 \quad \rightarrow \text{equivalent to GR!}$$

$$\Lambda_\mu^\alpha \text{ (16 components)} - 2 \times 4 \text{ (transl.gauge)} - 6 \text{ (Lor. rot+boosts)} = 2 \text{ dof}$$

TEGR

TEGR (Torsion)

a manifold based on torsion



$\Gamma^a_{\mu\nu}$

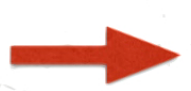
$$\Gamma^a_{\mu\nu} = \{^a_{\mu\nu}\} + K^a_{\mu\nu}(T)$$

$$\mathcal{S} = \frac{1}{2} \sqrt{-g} (c_1 T^\alpha_{\mu\nu} T^\alpha_{\mu\nu} + c_2 T^\alpha_{\mu\nu} T^\alpha_{\nu\mu} + c_3 T_\mu T^\mu) + \lambda^\beta_{\alpha} R^\alpha_{\beta\mu\nu} + \tilde{\lambda}^{\mu\nu}_\alpha Q^\alpha_{\mu\nu}$$

$c_1 = \frac{1}{4}, \quad c_2 = \frac{1}{2}, \quad c_3 = -1 \quad \rightarrow$ equivalent to GR!

$$R = \mathcal{R} + \mathring{T} + 2\mathcal{D}_\alpha T^\alpha$$

$$\uparrow = 0$$



$$-\mathcal{R} = \mathring{T} + 2\mathcal{D}_\alpha T^\alpha$$

CGR

CGR (Non-metricity)

L.H & J.Beltran, T.Koivisto

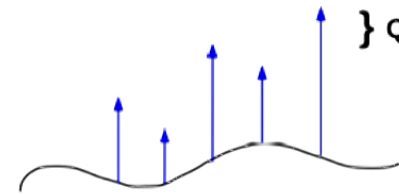
PRD98 (2018) 4, 044048,

arXiv:1803.10185

a manifold based on non-metricity

$g_{\mu\nu}, \Gamma_{\mu\nu}^a$

$$\Gamma_{\mu\nu}^a = \{^a_{\mu\nu}\} + L_{\mu\nu}^\alpha(Q)$$



$$L_{\mu\nu}^\alpha = \frac{1}{2}Q_{\mu\nu}^\alpha - Q_{(\mu}{}^\alpha{}_{\nu)}$$

disformation tensor

- Riemann: $R_{\beta\mu\nu}^\alpha = 0$
- Torsion: $T_{\mu\nu}^\alpha = 0$
- Non-metricity: $Q_{\mu\nu}^\alpha \neq 0$

$$\nabla_\alpha g_{\mu\nu} = Q_{\alpha\mu\nu}$$

↑
Non-metricity

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$g_{\mu\nu}, \Gamma_{\mu\nu}^a$

$$\Gamma_{\mu\nu}^a = \{\overset{a}{\mu\nu}\} + L_{\mu\nu}^a(Q)$$

● Riemann: $R_{\beta\mu\nu}^\alpha = 0 \quad \longrightarrow \quad \Gamma_{\mu\nu}^\alpha = (\Lambda^{-1})_{\lambda}^{\alpha} \partial_{\mu} \Lambda_{\nu}^{\lambda}$

● Torsion: $T_{\mu\nu}^{\alpha} = 0 \quad \longrightarrow \quad \Lambda_{\nu}^{\rho} = \partial_{\nu} \xi^{\rho}$

$$\Gamma_{\mu\nu}^{\alpha} = \left(\frac{\partial x^{\alpha}}{\partial \xi^{\rho}} \right) \partial_{\mu} \partial_{\nu} \xi^{\rho} \quad \text{Diffs}$$

the connection can be set to zero by means of a gauge choice

$$\Gamma_{\mu\nu}^{\alpha} = 0$$

CGR

CGR (Non-metricity)

L.H & J.Beltran, T.Koivisto

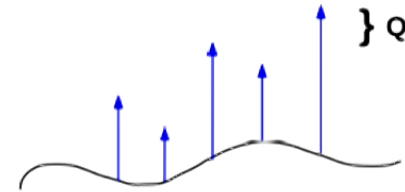
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$$\Gamma_{\mu\nu}^a = \{^a_{\mu\nu}\} + L_{\mu\nu}^a(Q)$$

$$\mathcal{S} = \int d^4x \sqrt{-g} \sum_{i=1}^5 c_i Q_i^2 + \lambda_\alpha{}^{\beta\mu\nu} R^\alpha{}_{\beta\mu\nu} + \tilde{\lambda}_\alpha{}^{\mu\nu} T^\alpha{}_{\mu\nu}$$

$$c_1 = -c_3 = -\frac{1}{2}c_2 = -\frac{1}{2}c_5 = -\frac{1}{4} \text{ and } c_4 = 0 \rightarrow \text{equivalent to GR!}$$

$$\sum_{i=1}^5 c_i Q_i^2 = \frac{1}{4} Q_{\alpha\beta\mu} Q^{\alpha\beta\mu} - \frac{1}{2} Q_{\alpha\beta\mu} Q_{\beta\mu\alpha} - \frac{1}{4} Q_\alpha Q^\alpha + \frac{1}{2} Q_\alpha \tilde{Q}^\alpha$$

$$Q_\mu = Q_{\mu\alpha}{}^\alpha \text{ and } \tilde{Q}^\mu = Q_\alpha{}^{\mu\alpha}$$

CGR

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$$\Gamma_{\mu\nu}^a = \{^a_{\mu\nu}\} + L_{\mu\nu}^a(Q)$$

$$\Gamma_{\mu\nu}^\alpha = \left(\frac{\partial x^\alpha}{\partial \xi^\rho} \right) \partial_\mu \partial_\nu \xi^\rho$$

Diffs

the connection can be set to zero by means of a gauge choice

$$\Gamma_{\mu\nu}^\alpha = 0$$

- All points are equivalent!
- No inertial effects at all!
- From the full $GL(4, \mathbb{R})$ we have reduced it to Diffs.

CGR

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PRD98 (2018) 4, 044048,

arXiv:1803.10185

a manifold based on non-metricity

$$g_{\mu\nu}, \Gamma_{\mu\nu}^a \quad \Gamma_{\mu\nu}^a = \left\{ \begin{matrix} \alpha \\ \mu\nu \end{matrix} \right\} + L_{\mu\nu}^\alpha(Q)$$

$$\mathcal{S} = \int d^4x \sqrt{-g} \sum_{i=1}^5 c_i Q_i^2 + \lambda_\alpha{}^{\beta\mu\nu} R^\alpha{}_{\beta\mu\nu} + \tilde{\lambda}_\alpha{}^{\mu\nu} T^\alpha{}_{\mu\nu}$$

$$\sum_{i=1}^5 c_i Q_i^2 = \frac{1}{4} Q_{\alpha\beta\mu} Q^{\alpha\beta\mu} - \frac{1}{2} Q_{\alpha\beta\mu} Q_{\beta\mu\alpha} - \frac{1}{4} Q_\alpha Q^\alpha + \frac{1}{2} Q_\alpha \tilde{Q}^\alpha$$

$$R = \mathcal{R} + \mathcal{Q} + \mathcal{D}_\alpha(Q^\alpha - \tilde{Q}^\alpha)$$

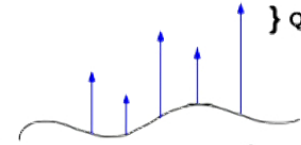
$$\uparrow \\ = 0$$

$$\longrightarrow -\mathcal{R} = \mathcal{Q} + \mathcal{D}_\alpha(Q^\alpha - \tilde{Q}^\alpha)$$

CGR

CGR (Non-metricity)

a manifold based on non-metricity



$$g_{\mu\nu}, \Gamma_{\mu\nu}^{\alpha} \quad \Gamma_{\mu\nu}^{\alpha} = \{\alpha_{\mu\nu}\} + L_{\mu\nu}^{\alpha}(Q)$$

$$\sum_{i=1}^5 c_i Q_i^2 = \frac{1}{4} Q_{\alpha\beta\mu} Q^{\alpha\beta\mu} - \frac{1}{2} Q_{\alpha\beta\mu} Q_{\beta\mu\alpha} - \frac{1}{4} Q_{\alpha} Q^{\alpha} + \frac{1}{2} Q_{\alpha} \tilde{Q}^{\alpha}$$

in the coincident gauge

$$\Gamma_{\mu\nu}^{\alpha} = \{\alpha_{\mu\nu}\} + L_{\mu\nu}^{\alpha}(Q) = 0 \quad \rightarrow \quad -\{\alpha_{\mu\nu}\} = L_{\mu\nu}^{\alpha}$$

$$\sum_{i=1}^5 c_i Q_i^2 = g^{\mu\nu} \left(\{\alpha_{\beta\mu}\} \{\nu\alpha\} - \{\beta\alpha\} \{\mu\nu\} \right)$$

the action is the $\{\}\}$ part of $R(\{\})$

$\partial_\mu h^\mu_\nu = 0$

$$F_{\mu\nu} = 0 \longrightarrow A_\mu = \partial_\mu \phi$$

$$\xi^\alpha = X^\alpha \longrightarrow \Gamma^\alpha_{\mu\nu} = 0$$

CGR

CGR (Non-metricity)

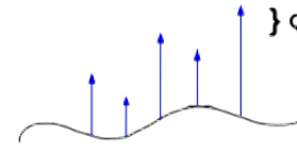
a manifold based on non-metricity

$g_{\mu\nu}, \Gamma_{\mu\nu}^a$

$$\Gamma_{\mu\nu}^a = \{^{\alpha}_{\mu\nu}\} + L_{\mu\nu}^{\alpha}(Q) = 0$$

$$\sum_{i=1}^5 c_i Q_i^2 = g^{\mu\nu} \left(\{^{\alpha}_{\beta\mu}\} \{^{\beta}_{\nu\alpha}\} - \{^{\alpha}_{\beta\alpha}\} \{^{\beta}_{\mu\nu}\} \right)$$

- No need for GHY boundary term for a well-defined variational principle
- More direct contact with (the most fundamental) field theory description (Deser's resummation approach)
- Improved and unambiguous entropy of BHs
- New tool to canonically quantize GR?



Modified gravity (geometrical perspective)

- Promote the scalars to general functions

$$\int \sqrt{-q} \mathcal{R} \quad \rightarrow \quad \int \sqrt{-q} f(\mathcal{R})$$

$$\int \sqrt{-q} \mathring{\mathbb{T}} \quad \rightarrow \quad \int \sqrt{-q} f(\mathring{\mathbb{T}})$$

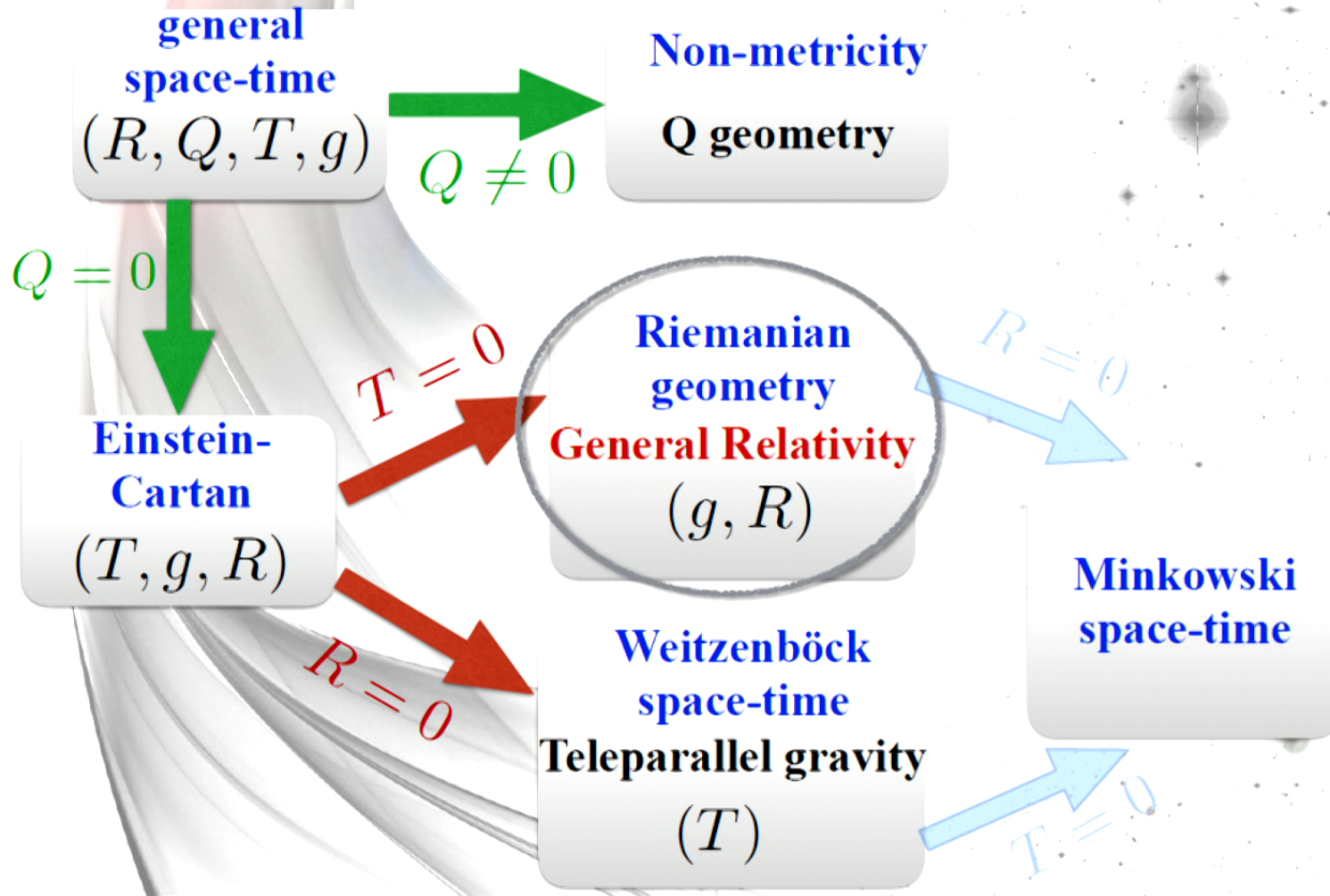
$$\int \sqrt{-q} \mathring{\mathcal{Q}} \quad \rightarrow \quad \int \sqrt{-q} f(\mathring{\mathcal{Q}})$$

- Other consistent quadratic actions? \mathcal{C}_i

$$\mathcal{S} = \int d^4x \sqrt{-g} \sum_{i=1}^5 c_i Q_i^2 + \lambda_\alpha^{\beta\mu\nu} R^\alpha{}_{\beta\mu\nu} + \tilde{\lambda}_\alpha^{\mu\nu} T^\alpha{}_{\mu\nu}$$

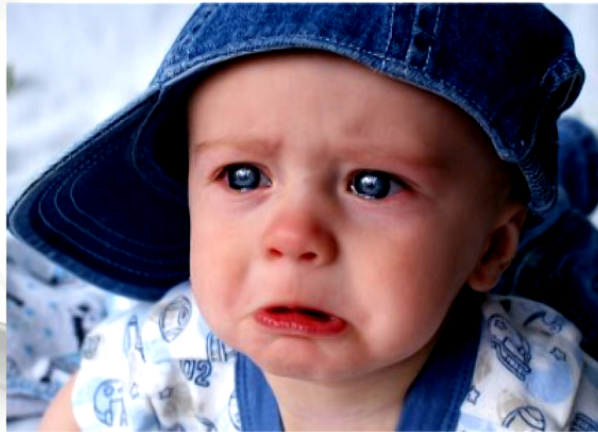
$$\mathcal{S} = \frac{1}{2} \sqrt{-g} (c_1 T_\alpha{}^{\mu\nu} T^\alpha{}_{\mu\nu} + c_2 T_\alpha{}^{\mu\nu} T_\mu{}^\alpha{}_\nu + c_3 T_\mu T^\mu) \\ + \lambda_\alpha^{\beta\mu\nu} R^\alpha{}_{\beta\mu\nu} + \tilde{\lambda}_\alpha^{\mu\nu} Q_\alpha{}^{\mu\nu}$$

Geometrical setup



General Relativity (field theory perspective)

**Imagine a universe in which
Einstein did not exist!**



General Relativity (field theory perspective)

Imagine a modern version of Einstein

Who would have learned
all the standard techniques
of field theory description



We would have eventually constructed GR from
field theory perspective, just years later

General Relativity (field theory perspective)

Imagine a modern version of Einstein

Who would have learned
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massless Spin 2 Field

In 4 dimensions the only Lovelock invariants are

- **Cosmological constant** $\sqrt{-g}$

- **Ricci scalar** R

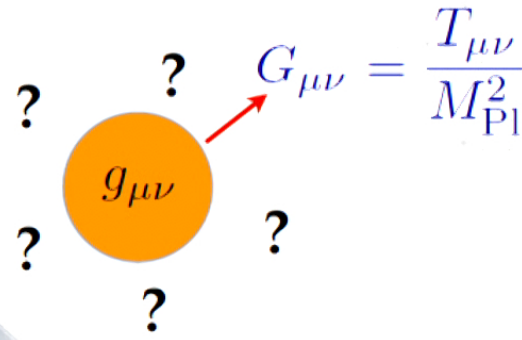
- **Gauss-Bonnet term** \mathcal{L}_{GB} $\mathcal{L}_{GB} = R_{\mu\nu\alpha\beta}R^{\mu\nu\alpha\beta} - 4R_{\mu\nu}R^{\mu\nu} + R^2$
(topological)

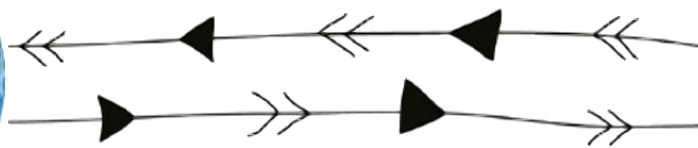


$$\mathcal{L}_g = \sqrt{-g}M_{\text{Pl}}^2 R + \sqrt{-g}\Lambda$$

GR

Modified Gravity

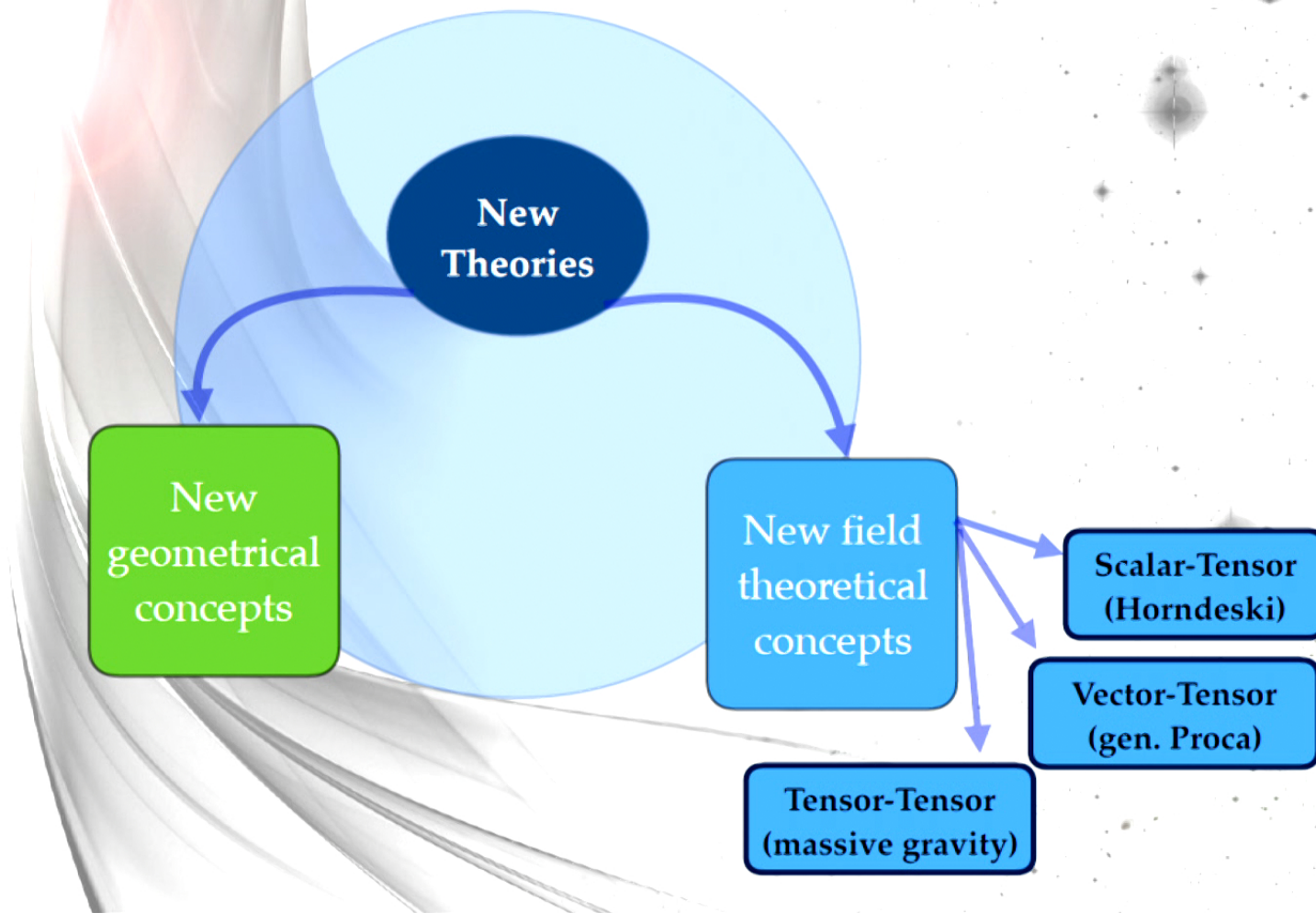
$$G_{\mu\nu} = \frac{T_{\mu\nu}}{M_{\text{Pl}}^2}$$




GRAVITON

$$\left\{ \begin{array}{l} g_{\mu\nu} \\ f_{\mu\nu} \\ A_{\mu} \\ \phi \end{array} \right\}$$

Gravity theories



Field Theoretical Trinity of Gravity

