

Title: Talk 7

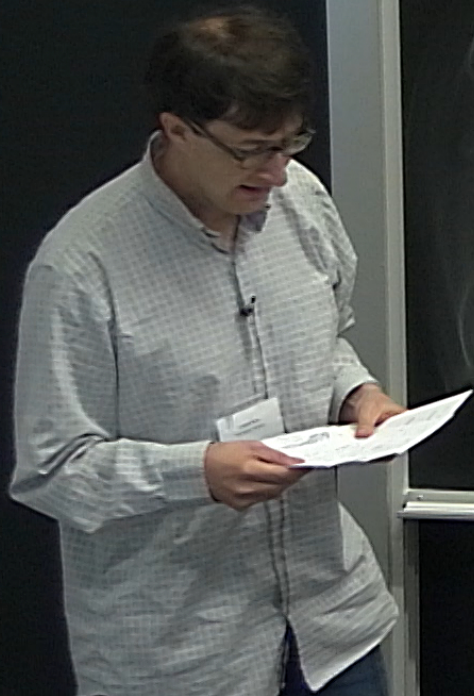
Speakers:

Collection: Simplicity III

Date: September 10, 2019 - 11:00 AM

URL: <http://pirsa.org/19090074>

The Standard Model From A Jordan Algebra



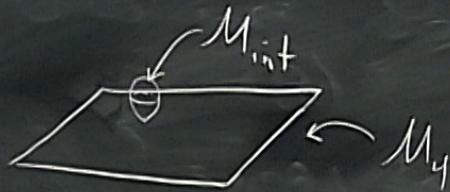
The Standard Model From A Jordan Algebra

- Two goals:

- (1) unify grav w/ other fields

- (2) unify grav w/ QM

Soln (1a): Kaluza-Klein (S.T.)

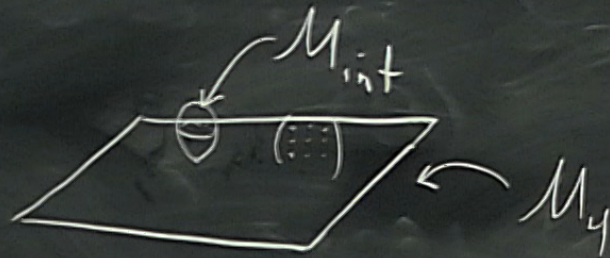


- Problems:
- too many fields
 - stabilize M_{int} (KKLT, landscape)

Reason: M_{int} are a manifold
 A_{int} is ∞ -dimensional

Soln(1b): replace M_{int} by discrete/finite space

Soln (1a): Kaluza-Klein (S.T.)



- Problems:
 - too many fields
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Reason: M_{int} are a manifold
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Soln(1b): replace M_{int} by discrete/finite space
 A_{int} finite-dimensional

$$\text{Aut}[C_\infty(M)] = \text{Diff}(M_4)$$

$$\text{Aut}[C_\infty(M) \otimes A_{int}] = \text{Diff}(M) \ltimes \text{Map}(M_4, \underbrace{\text{Aut}(A_{int})}_{SU(3) \times SU(2) \times U(1)})$$

$$\text{Aut}[C_\infty(M_4 \times M_{int})]$$

(2) "Quantum geometry"

• Soln (2a): NCG

• 1st attemp: (1b) also assumed (2a)

Dubois-Violette, Kerner, Madore, Connes

• NCG is for phase space $[q, p] \neq 0$ (symplectic geom.)
not spacetime $[q, q'] = 0$ (pseudo-Riemann)

• Soln (2b): replace NCG by Jordan geometry
 $A_{int} = \text{Jordan algebra}$

$$(H_1, H_2) = H_2 H_1$$

$$\{H_1, H_2\} \quad \text{Jordan}$$

$$[A_1, A_2] \quad \text{Lie}$$

$$\{\{H_1, H_2\}, H_3\} = \{H_1, H_2\}$$

$$[a, b] = ab - ba \neq 0$$

$$[a, b, c] = (ab)c - a(bc) \neq 0$$

Jordan + von Neumann + Wigner

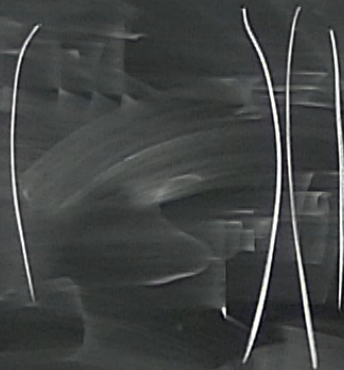
$$\underline{JSpin(n)}, J_n(\mathbb{R}), J_n(\mathbb{C}), J_n(\mathbb{H}), J_3(\mathbb{O})$$

$$(q, p) \rightarrow q$$

$$\begin{aligned} \circ &\rightarrow H = \frac{1}{2}(O + O^\dagger) \leftarrow \\ A &= \frac{1}{2}(O - O^\dagger) \end{aligned}$$

$$\text{NCG: } \{M, g\} \rightarrow \{A, H, D\} \rightarrow \boxed{A \oplus H = B}$$

Barrett:



$$\text{NCG: } \{M, g\} \rightarrow \{A, H, D\} \rightarrow \boxed{A \oplus H = B}$$

$$SU(3) \times SU(2) \times U(1)$$

Barrett:

$$\left(\begin{array}{c|c} 4 \times 4 & \\ \hline & 4 \times 4 \end{array} \right) \left(\begin{array}{c|c} & \psi_{4 \times 4} \\ \hline \psi_{4 \times 4}^+ & \end{array} \right)$$

$$\left(\begin{array}{c|c} J_2(\mathbb{C}) & \\ \hline J_{Spin(2)} & J_3(\mathbb{C}) \\ & \mathbb{R} \end{array} \right)$$

	$SU(3)$	$SU(2)$	$U(1)$	$U(1)_{B-L}$
q_L	3	2	0 ($\frac{1}{6}$)	$\frac{1}{3}$
u_R	3	1	$\frac{1}{2}$ ($\frac{2}{3}$)	$\frac{1}{3}$
d_R	3	1	$-\frac{1}{2}$ ($-\frac{1}{3}$)	$\frac{1}{3}$
ℓ_L	1	2	0 ($-\frac{1}{2}$)	-1
ν_R	1	1	$\frac{1}{2}$ (0)	-1
e_R	1	1	$-\frac{1}{2}$ (-1)	-1