

Title: PSI 2018/2019 - Explorations in Quantum Gravity - Lecture 7

Speakers: Wolfgang Wieland

Collection: PSI 2018/2019 - Explorations in Quantum Gravity (Dupuis)

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LAST TIME:

$$H = - \int d^2x \quad N^0 \mathcal{F}_j + \Lambda^j G_j$$

INTERPRET CONSTRAINTS.

$$(\mathcal{F}[N] = \int d^2x N^0 \mathcal{F}_j, \quad G[\Lambda] = \int d^2x \Lambda^j G_j)$$

$$\{A_a^j(x), E_k^b(y)\} = \delta_k^j \delta_a^b \delta(x-y)$$

$$\delta_\Lambda E = \{E, G[\Lambda]\} = \epsilon_{jnk} E^{am} \Lambda^k(x)$$

$$\delta_\Lambda A = -(\partial \Lambda + \epsilon \Lambda A)$$

$$\delta_N E_j^a = \tilde{\epsilon}^{ca} D_c N_j(x)$$

$$\delta_N A = 0$$

Λ : ROTATIONS

N : TRANSLATIONS

$$\delta_N A = -(\partial \Lambda + \epsilon \Lambda A)$$

$$\delta_N E_j^i = \tilde{\epsilon}^{ca} D_c N_j^i(x)$$

$$\delta_N A = 0$$

Λ : ROTATIONS

N : TRANSLATIONS

$$\text{DIFFEO: } (\delta_{A(v)}^R + \delta_{\epsilon(v)}^T) A = \delta_v^D e_\mu^j + T_{\mu\nu}^j v^\nu$$

$$(\delta_{A(v)}^R + \delta_{\epsilon(v)}^T) A = \delta_v^P A_\mu^j + F_{\mu\nu}^j v^\nu$$

CONSTRAINT ALGEBRA

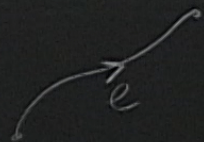
$$\{G[\Lambda], G[\Lambda']\} = G([\Lambda, \Lambda'])$$

$$\{F[N], G[\Lambda]\} = F([N, \Lambda])$$

$$\{F[N], F[N']\} = 0$$

Configuration variables - holonomies

• $A_a^d(x) \rightarrow h_e[A] = \text{P exp} - \int_e A \in \text{SU}(2)$



• Transformation under a finite rotation in terms of a $\text{SU}(2)$ gp elt.

$$\rightarrow R_k^l(g) T_l = g^{-1} \cdot T_k \cdot g \quad g \in SU(2)$$

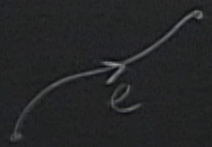
T_i are $SU(2)$ generators.

\rightarrow Lie-algebra valued objects:

$$E^a = E_0^a T_i, \quad A_a = A_a^d T_i, \quad F_{ab} = F_{ab}^d T_i$$

$$E_0^a = \hat{\epsilon}^{ab} e_{bj}$$

• $T_a(x)$... T_e



• Transformation under a finite rotation in terms of a $SU(2)$ gp elt. → $R_k^l(g) T_e$
inbred vector → Lie-algebra

$$\underbrace{N^k R_k^l(g) T_e}_{(R(g) \cdot N)^l T_e} = \bar{g} \cdot (N^k T_k) \cdot g \Rightarrow (R(g) \cdot N)^l T_l = g \cdot \underbrace{(N^k T_k)}_{g^{-1}}$$

\Rightarrow of a $su(2)$ gp elt. $\rightarrow R_k^l(g) T_l = g^{-1} \cdot T_k \cdot g \quad g \in su(2)$ T^j are $su(2)$ generators.
 \rightarrow Lie-algebra valued objects: $E^a = E_0^a T^j, A_a = A_a^d T_j, F_{ab} = F_{ab}^d T_j$
 $E_0^a = \hat{E}^{ab} e_{ab}$
 $\Rightarrow (R(g) \cdot N)^d T_j = g \cdot (N^k T_k) \cdot g^{-1}$
 $\Rightarrow E^a \rightarrow g E^a g^{-1}$
 $F_{ab} \rightarrow g F_{ab} g^{-1}$

$$\rightarrow h_e[A] = \text{P exp} - \int_e A \in \text{SU}(2)$$

rotation under a finite rotation in terms of a SU(2) gp elt.
 input vector

$$\rightarrow R_k^l(g) T_l = \bar{g} \cdot T_k \cdot g$$

→ Lie-algebra valued objects: E^a

$$\underbrace{\sum^k R_k^l(g) T_l}_{(R(g) \cdot N)^l} T_e = \bar{g} \cdot (N^k T_k) \cdot g \Rightarrow (R(g) \cdot N)^l T_l = g \cdot (N^k T_k) \cdot \bar{g}$$

$$\Rightarrow E^a \rightarrow g E^a g^{-1}$$

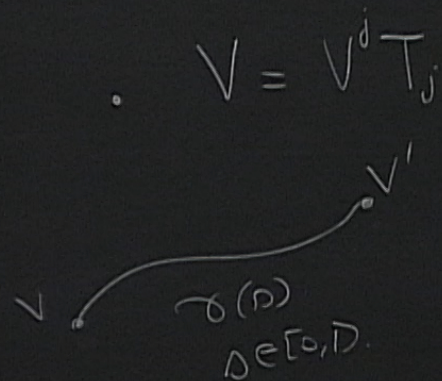
$$F_{ab} \rightarrow g F_{ab} g^{-1}$$

connection: $A_a \rightarrow g A_a g^{-1} + g \partial_a g^{-1}$

Ex: check this last transformation rule.

connection: $A_a \rightarrow g A_a g^{-1} + g \partial_a g^{-1}$

Ex check



tangent vector
 $\dot{\gamma}(s) = \frac{d}{ds} \gamma(s)$

parallel transport
 $V(s) = h(s) V(0) h(s)^{-1}$

\hookrightarrow holonomy from $\gamma(0)$ to $\gamma(0)$

Ex: check this last transformation rule.

under gauge transf. $V(o) \rightarrow g(o) V(o) g(o)^{-1} = V'(o)$

$$V(s) \rightarrow g(s) V(s) g(s)^{-1} = V'(s)$$

gauge transf. for a holonomy?

$$V'(s) = h'(s) V(o) h'(s)^{-1}$$

$$= \underbrace{h'(s) g(o)}_{g(s)} V(o) g(o)^{-1} h'(s)^{-1} = \underbrace{g(s) h(s)}_{g(s)} V(o) h(s)^{-1} g(s)^{-1}$$

$$\left[h(s) \rightarrow h'(s) = g(s) h(s) g(o)^{-1} = \underbrace{g(\sigma(s))}_{g(s)} h(s) \underbrace{g(\sigma(o))^{-1}}_{g(o)^{-1}} \right]$$

Definition of the holonomy

V parallel transported along γ :

$$0 = \ddot{\gamma}^a D_a V(s)$$

$$D_a V = \partial_a V + [A_a, V]$$

$$\dot{\gamma}^a \partial_a = \frac{d}{ds}$$

$$\hookrightarrow = \left(\frac{d}{ds} h(s) \right) V(s) h^{-1}(s) - h(s) V(s) h^{-1}(s) \frac{dh(s)}{ds} h^{-1}(s)$$

$\{G(N)\} = \epsilon_{nk} E^k$ N TRANSLATIONS

$\{F(N), F(N')\} = 0$

Definition of the holonomy

V parallel transported along γ :

$0 = \dot{\gamma}^a D_a V(s)$

$D_a V = \partial_a V + [A_a, V]$

$\dot{\gamma}^a \partial_a = \frac{d}{ds}$
 $\hookrightarrow = \left(\frac{d}{ds} h(s)\right) V(s) h^{-1}(s) - h(s) V(s) h^{-1}(s) \frac{d h(s)}{ds} h^{-1}(s) + \dot{\gamma}^a A_a h(s) V(s) h^{-1}(s) - h(s) V(s) h^{-1}(s) \dot{\gamma}^a A_a$
 $= 0$

$\frac{d}{ds} (h h^{-1}) = 0$

Defining differential eq for the holonomy

$\frac{d}{ds} h(s) = -\dot{\gamma}^a A_a^{(n(s))} h(s)$

$h(s) = 1$

$$D_a V = \partial_a V + [A_a, V]$$

$$V(\sigma) h'(\sigma) - h(\sigma) V(\sigma) h'(\sigma) \frac{d h(\sigma)}{d \sigma} h^{-1}(\sigma) + \dot{\gamma}^a A_a h(\sigma) V(\sigma) h(\sigma)^{-1} - h(\sigma) V(\sigma) h(\sigma)^{-1} \dot{\gamma}^a A_a \rightarrow \frac{d}{d \sigma} (h h^{-1}) = 0$$

$$\dot{\gamma}^a A_a(\gamma(\sigma)) h(\sigma)$$

$$h(0) = \mathbb{1}$$

\Rightarrow

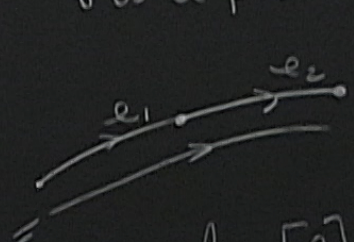
well-known solution:

$$h_{\gamma}(\sigma) = P \exp\left(-\int_{\gamma} A\right)$$

$$A(\sigma) = \dot{\gamma}(\sigma) A_a(\gamma(\sigma))$$

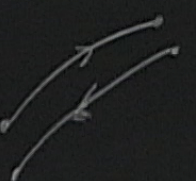
Important properties of holonomy

- i) definition $h_\gamma[A]$ independent of parametrization of path γ
- ii) γ is a point $h_\gamma = \mathbb{1}$.



The diagram shows a path consisting of two segments, e_1 and e_2 , connected end-to-end. Arrows indicate the direction of the path. Below this, the holonomy of the concatenated path is given as the product of the holonomies of the individual segments.

$$h_e[A] = h_{e_1}[A] h_{e_2}[A]$$



The diagram shows a path with an arrow pointing in the opposite direction to the previous one, representing the inverse path.

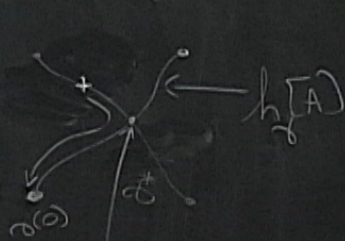
$$h_{e^{-1}}[A] = h_e[A]^{-1}$$

TODAY: Bivariant
- holonomy
- flux

Definition of the holonomy

∇ parallel transport

Conjugated variables - fluxes



flux sitting at $\sigma(\omega)$.

$$E_{\sigma} = \int_{\sigma^*} h_{\sigma\sigma^*}(\omega) e_a(\sigma^*(\omega)) (h_{\sigma\sigma^*}(\omega))^{-1}$$

↳ // transport from $\sigma^*(\omega)$ to $\sigma(\omega)$

• $\delta = \delta' = \frac{1}{2}$
 • $\det(\delta^a, \delta^{*b}) > 0$

Rmk $E_\gamma \rightarrow g(x(0)) E_\alpha g(x(0))^{-1}$

$$h_{\gamma^{-1}} = h_{\alpha}^{-1}, \quad E_{\alpha^{-1}} = -h_\alpha E_\alpha h_\alpha^{-1}$$

to extract component

$$\text{tr}(T_j T_k) = \frac{1}{2} \delta_{jk}$$

$$T_j = \frac{i}{2} \sigma_j$$

$$E_{\alpha_j} = -2 \text{TR}(E_\gamma T_j)$$

$$\{(E_\alpha)_j, h_\alpha\} = h_\alpha T_j$$

$$\{(h_\alpha)_{MN}, (h_\alpha)_{MN}\} = 0$$

$$\{E_\alpha^i, E_\alpha^j\} = \epsilon^{ijk} E_\alpha^k$$

$T^*SU(2)$