Title: No-free-information principle in general probabilistic theories

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Abstract: In quantum theory, the no-information-without-disturbance and no-free-information principles express that those observables that do not disturb the measurement of another observable and those that can be measured jointly with any other observable must be trivial, i.e., coin tossing observables. We show that in the framework of general probabilistic theories these principles do not hold in general. In this way, we obtain characterizations of the probabilistic theories where these principles hold and we show that the two principles are not equivalent.

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# No-free-information principle in general probabilistic theories

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# The three principles

 No broadcasting You can't make two coffes out of one.



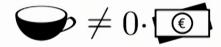
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## The three principles

 No broadcasting You can't make two coffes out of one.



2. No information without disturbance You can't have the coffee for free.



## The three principles

No broadcasting
 You can't make two coffes out of one.

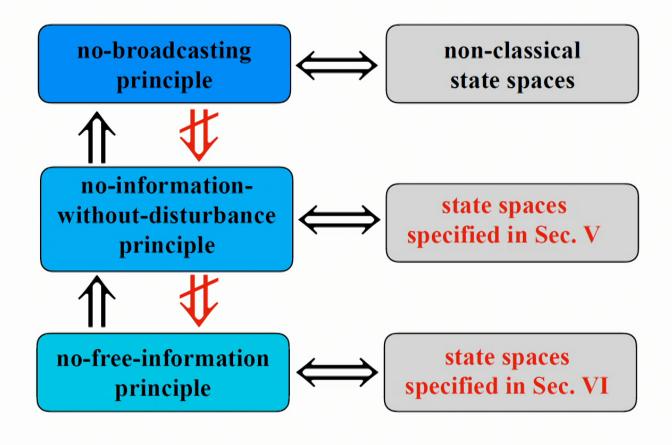


2. No information without disturbance You can't have the coffee for free.

$$\longrightarrow \neq 0.$$

3. No free information You can't have the coffee for free even if you pay for the lunch.

## The results



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## GPT refresher

- K: state space, compact convex subset of  $\mathbb{R}^n$
- A(K): linear space of affine functions  $f: K \to \mathbb{R}$
- $A(K)^+$ : cone of positive affine functions,  $f(x) \ge 0$ ,  $\forall x \in K$
- E(K): effect algebra of affine functions  $f: K \to [0,1]$
- $A(K)^*$ : dual vector space to A(K)
- $A(K)^{*+}$ : positive cone of functionals  $\langle \varphi, f \rangle \geq 0$ ,  $\forall f \in A(K)^{+}$

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### **GPT** refresher

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#### In quantum theory:

- K: density matrices over finite dimensional Hilbert space
- A(K): self-adjoint operators,  $A(\rho) = \text{Tr}(\rho A)$
- $A(K)^+$ : cone of positive semi-definite matrices,  $A \ge 0$
- E(K): set of effects,  $0 \le A \le 1$
- $A(K)^*$ : self-adjoint operators
- $A(K)^{*+}$ : cone of positive semi-definite matrices,  $A \ge 0$

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## Measurements

 $\Omega$ : sample space, finite measurable set of outcomes  $\mathcal{P}(\Omega)$ : set of probability measures on  $\Omega$ , simplex

#### **Definition**

Measurement is an affine map

$$m: K \to \mathcal{P}(\Omega)$$
.

Let  $A \subset \Omega$ , measurable m(x; A) = measure of the set A with respect to measure m(x)

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## Compatibility of measurements

 $\Omega_1$ ,  $\Omega_2$  sample spaces

#### **Definition**

Measurements

$$m_1:K\to \mathcal{P}(\Omega_1)$$

$$m_2:K\to \mathcal{P}(\Omega_2)$$

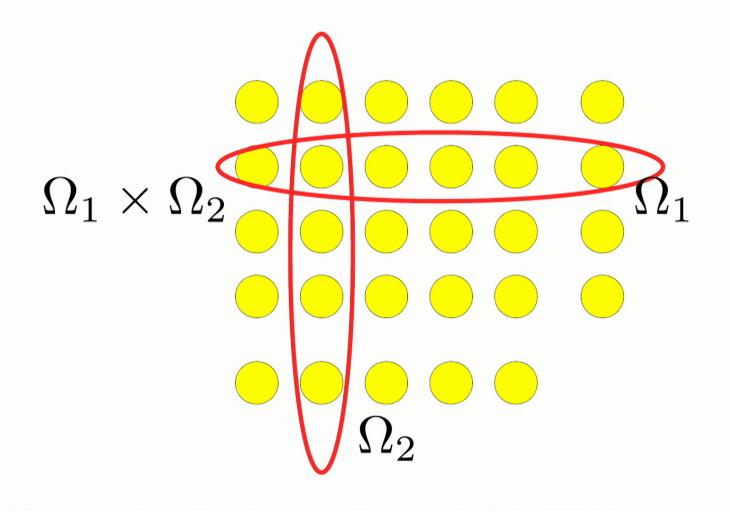
are compatible if there exists  $m: K \to \mathcal{P}(\Omega_1 \times \Omega_2)$  such that for all  $A_1 \subset \Omega_1$ ,  $A_2 \subset \Omega_2$  and  $\forall x \in K$ 

$$m_1(x; A_1) = m(x; A_1 \times \Omega_2),$$

$$m_2(x; A_2) = m(x; \Omega_1 \times A_2).$$

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# Compatibility of measurements



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## Compatibility of measurements

 $\Omega_1$ ,  $\Omega_2$  sample spaces

#### **Definition**

Measurements

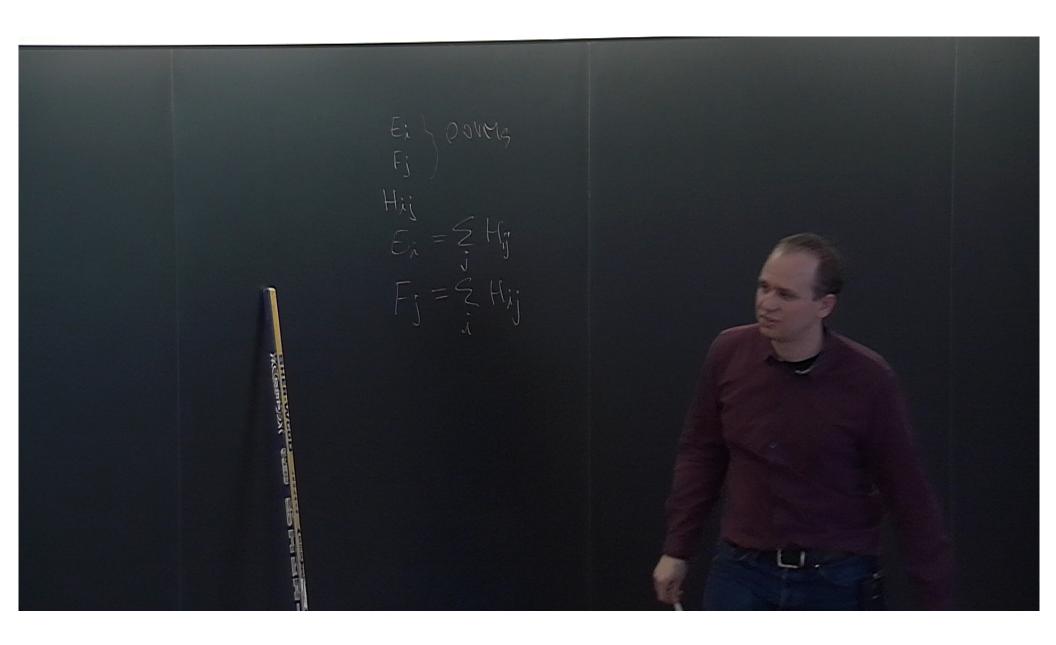
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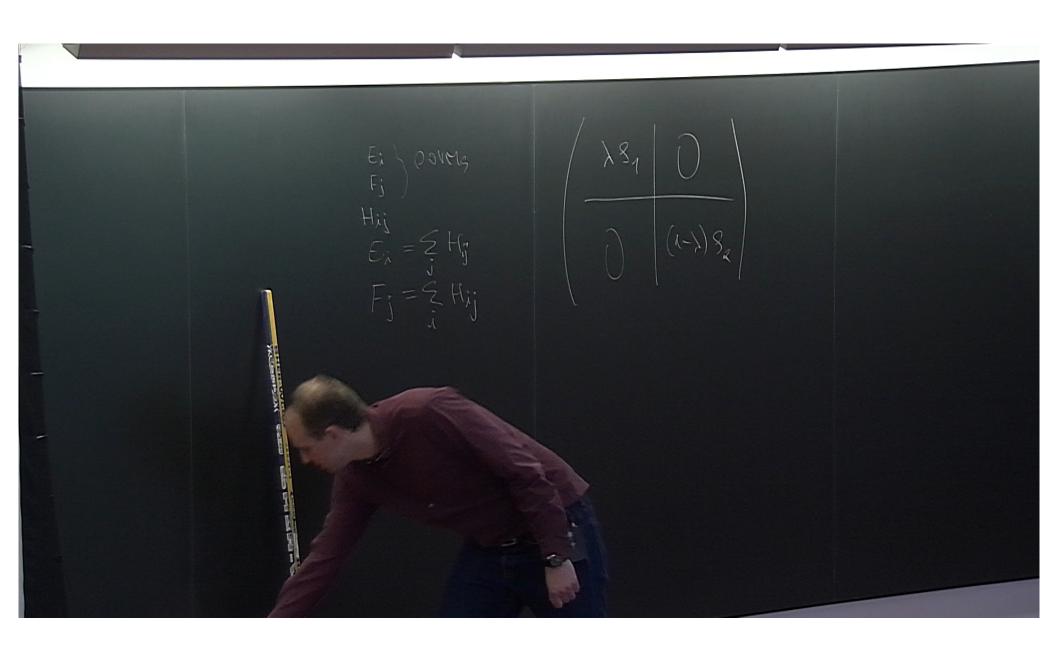
## Direct convex hull

#### **Definition**

Let  $K_A$ ,  $K_B$  be state spaces, then  $K_A \oplus K_B$  is a state space of ordered and weighted pairs of states, i.e.

$$K_A \oplus K_B = \{(\lambda x, (1 - \lambda)y) : x \in K_A, y \in K_B, \lambda \in [0, 1]\}.$$

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#### **Theorem**

There exists nontrivial observable compatible with the identity channel if and only

$$K = \bigoplus_{i=1}^n K_i$$
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The main idea of the proof is that the measurement has to be constant on the sets  $K_i$ .

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#### Corollary

Let  $\tau$  be a coin-toss measurement, then m is compatible with the identity channel if and only if  $\lambda m + (1 - \lambda)\tau$  is compatible with the identity channel for all  $\lambda \in [1,0)$ .

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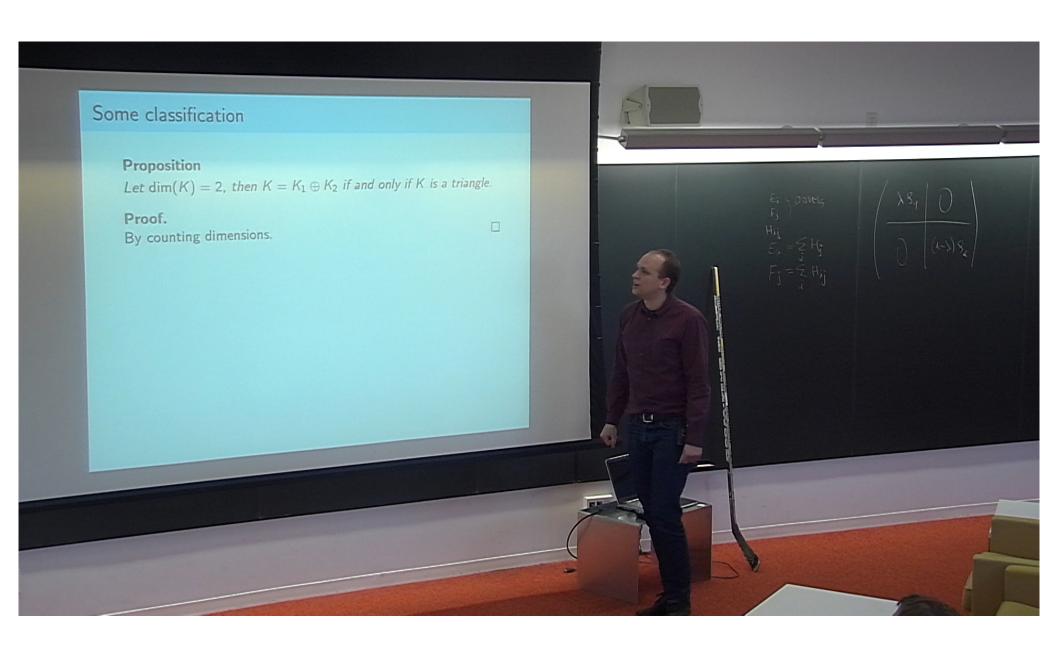
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## Noise does not help!



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## Some classification

## **Proposition**

Let  $\dim(K) = 2$ , then  $K = K_1 \oplus K_2$  if and only if K is a triangle.

#### Proof.

By counting dimensions.

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## Some classification

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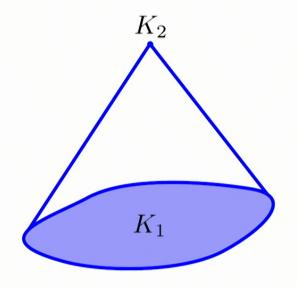
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By counting dimensions.

## **Proposition**

Let dim(K) = 3, then  $K = K_1 \oplus K_2$  if and only if  $K_2 = \{x\}$  and K is pyramid-shaped.



# Post-processings and convex combinations

Let  $m_1$ ,  $m_2$  be measurements

$$m_1: K \to \mathcal{P}(\Omega_1)$$

$$m_2:K o \mathcal{P}(\Omega_2)$$

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## Post-processings and convex combinations

Let  $m_1$ ,  $m_2$  be measurements

$$m_1:K o \mathcal{P}(\Omega_1)$$

$$m_2:K o \mathcal{P}(\Omega_2)$$

#### **Definition**

Post-processing is a map  $\nu: \mathcal{P}(\Omega_2) \to \mathcal{P}(\Omega_1)$  that allows us to construct measurement

$$m_2' = \nu \circ m_2 : K \to \mathcal{P}(\Omega_1)$$

Post-processing is a form of order that gives rise to an equivalence.

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Post-processing is a form of order that gives rise to an equivalence.

#### **Definition**

For  $\lambda \in [0,1]$  we define convex combination of measurements as the map

$$(\lambda m_1 + (1-\lambda)m_2'): K \to \mathcal{P}(\Omega_1)$$

## Simulability of measurements

#### **Definition**

Measurements  $m_1, \ldots, m_k$  simulate a measurement m if there are

- post-processing  $\nu_1, \ldots, \nu_k$
- numbers  $\lambda_1,\ldots,\lambda_k$ , s.t.  $\lambda_i\in[0,1]$  for  $i=1,\ldots,k$ ,  $\sum_{i=1}^k\lambda_i=1$

such that

$$m = \sum_{i=1}^{k} \lambda_i \nu_i \circ m_i$$

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such that

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#### Definition

We say that a measurement m is simulation irreducible if it can be simulated only by post-processing equivalent measurements.

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## No free information

#### **Theorem**

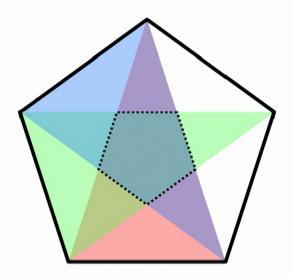
A measurement m is compatible with every other measurement on K if and only if it is compatible with every simulation irreducible measurement on K.

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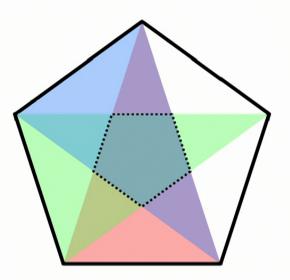


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## No free information

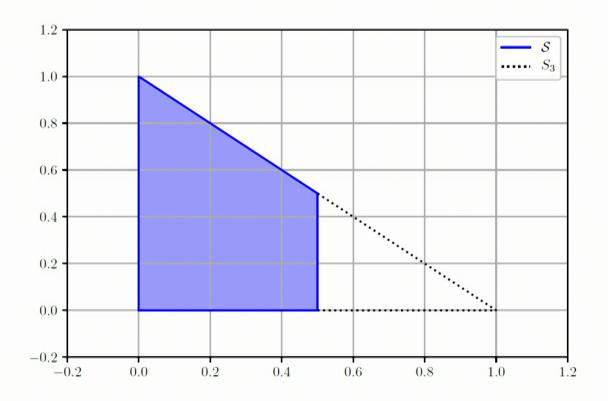
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A measurement m is compatible with every other measurement on K if and only if it is compatible with every simulation irreducible measurement on K.



Noise helps! (sometimes)

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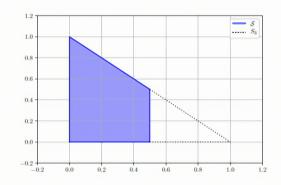
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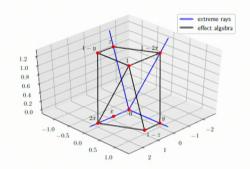
Simulation irreducible measurements:

$$m_2 = 2x \otimes \delta_1 + (1 - 2x) \otimes \delta_2$$
  

$$m_3 = x \otimes \delta_1 + y \otimes \delta_2$$
  

$$+ (1 - x - y) \otimes \delta_3$$





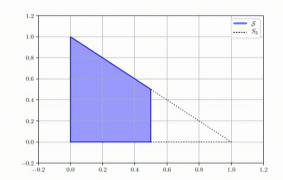
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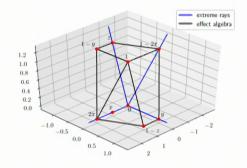
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Measurement compatible with every other measurement

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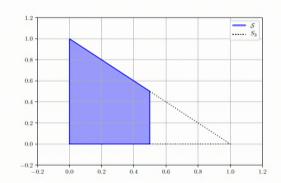
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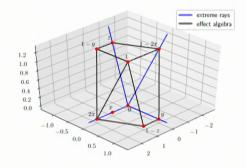


Measurement compatible with every other measurement

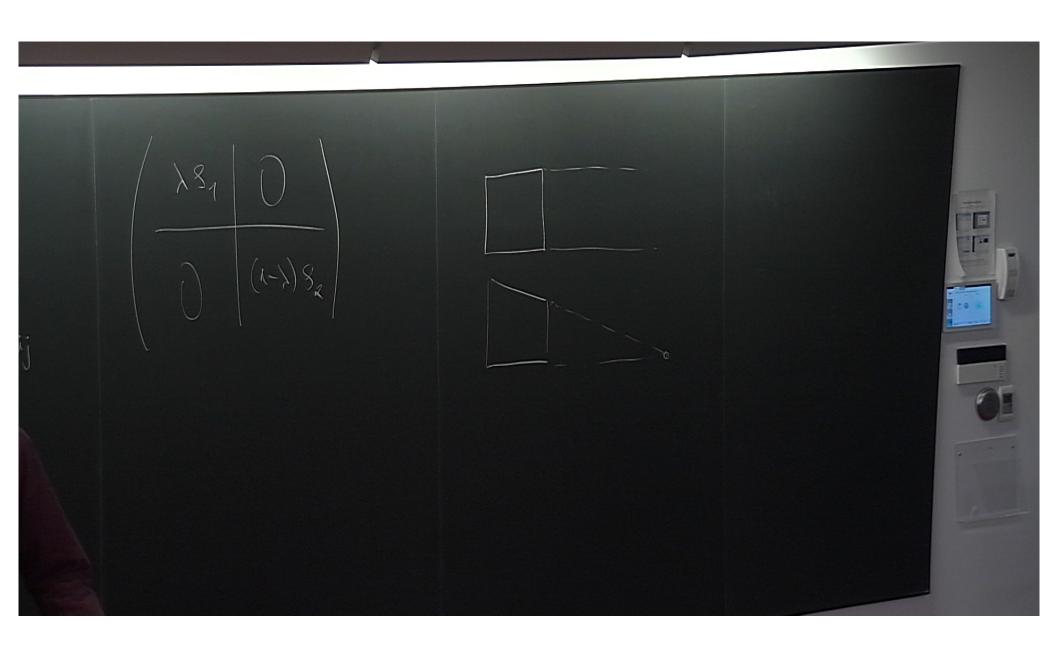
$$m = x \otimes \delta_1 + (1 - x) \otimes \delta_2$$

The joint measuremnet

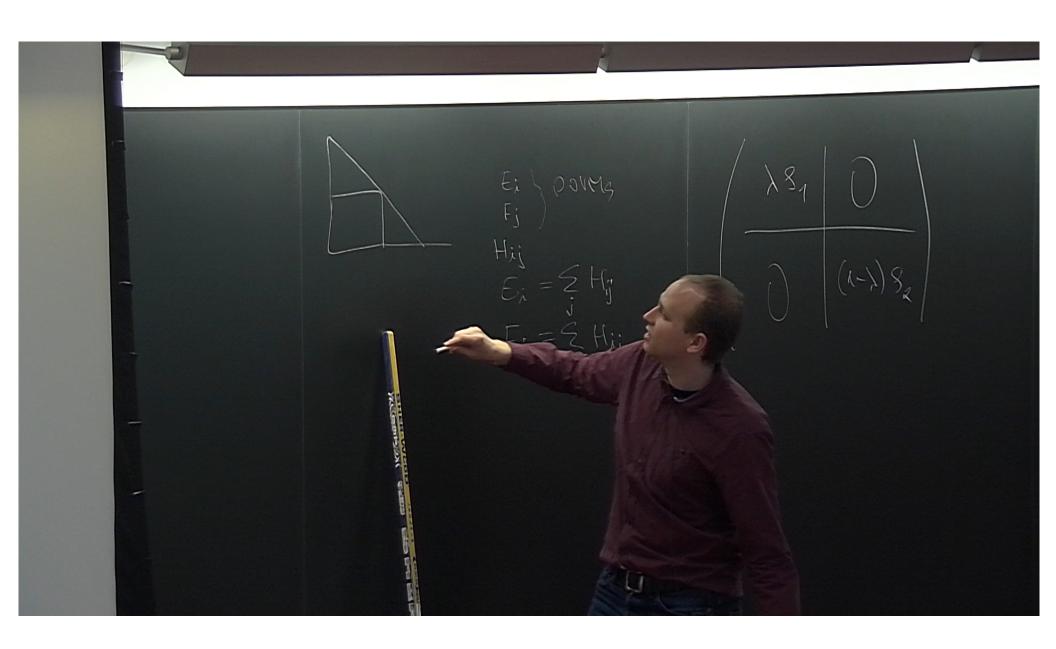
$$m_2' = x \otimes \delta_1 + x \otimes \delta_2 + (1-x) \otimes \delta_3$$



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