

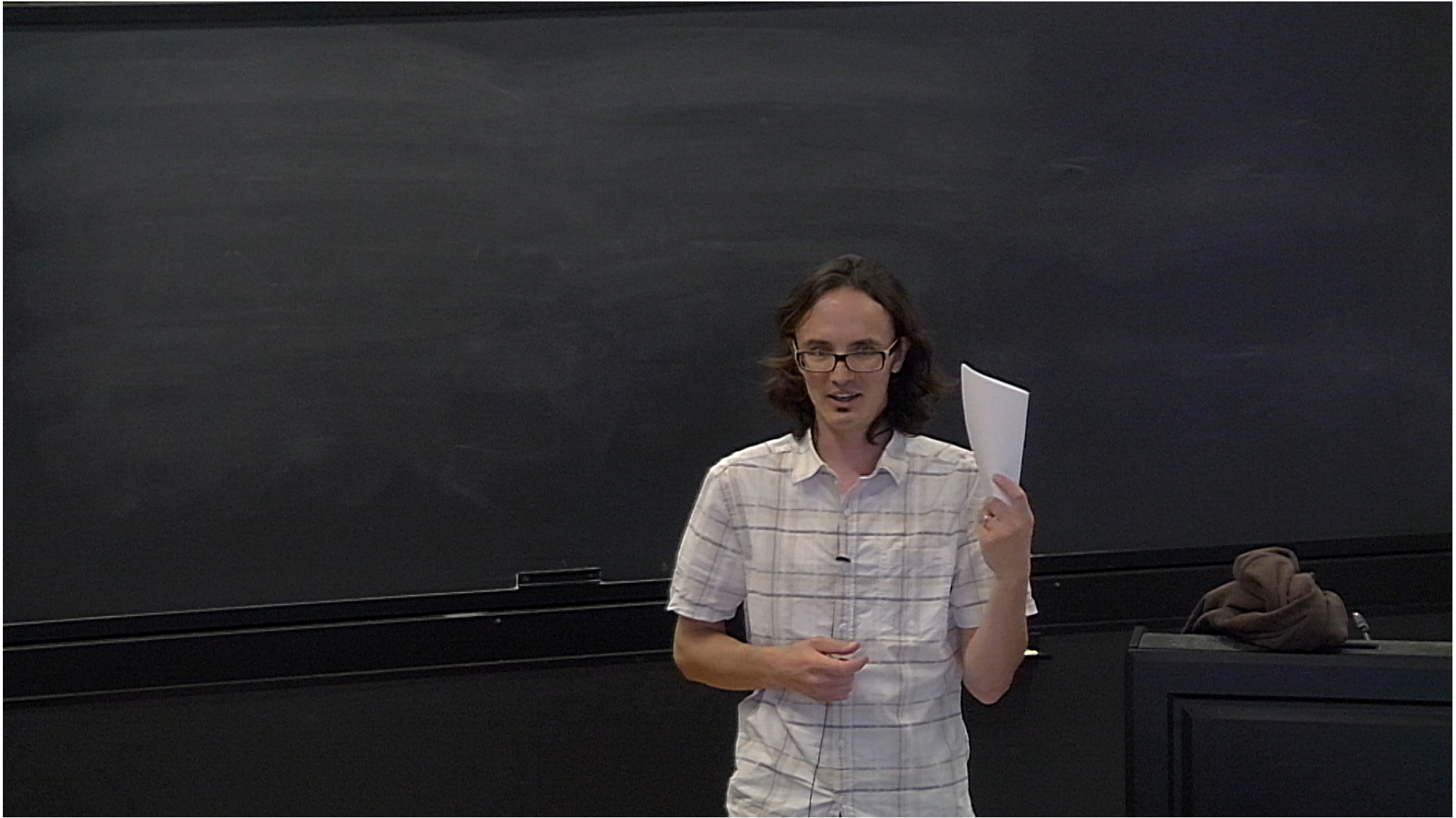
Title: Computational Physics - Lecture 7

Speakers: Erik Schnetter

Collection: Computational Physics (Schnetter)

Date: October 03, 2018 - 1:00 PM

URL: <http://pirsa.org/18100048>



arXiv 1008.4686
1205.4446

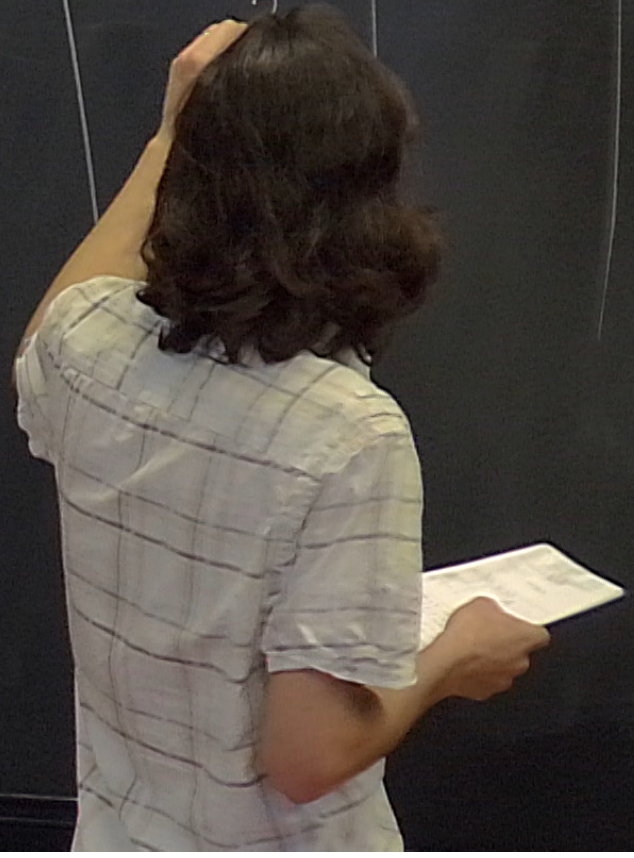
Fitting a model to data

- fitting a straight line
- magic of Gaussian

Next

- outliers
- model sel
- MCMC.

Night	Position
1	
2	



Night	Position
1	6
2	5
3	8

Model

- position y constant
- measurements $y_i = y + e_i$
- e_i drawn from a distribution
- independent

Night	Position
1	6
2	5
3	8

Model

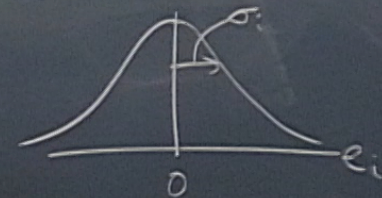
- position y constant
- measurements $y_i = y + e_i$
- e_i drawn from a distrib'n
- independent
- prob dist'n is Gaussian
with known σ_i , zero mean.

data
line

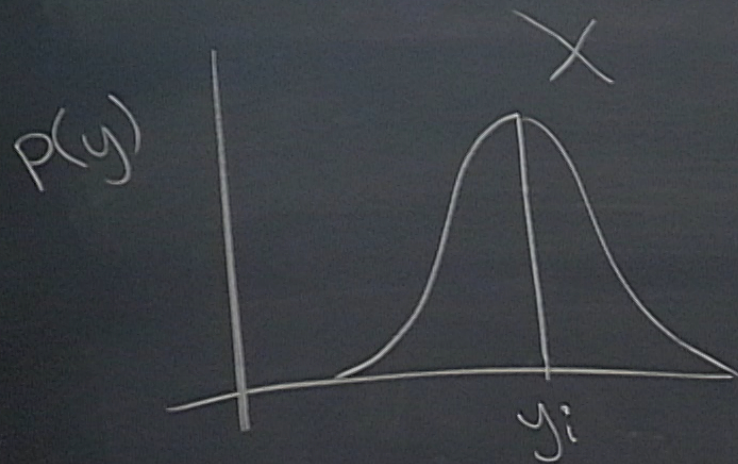
Night	Position	Uncertainty
1	6	1
2	5	1
3	8	1

Model

- position y constant
- measurements $y_i = y + e_i$
- e_i drawn from a distrib'n
- independent
- prob. dist'n is Gaussian
with known σ_i , zero mean.

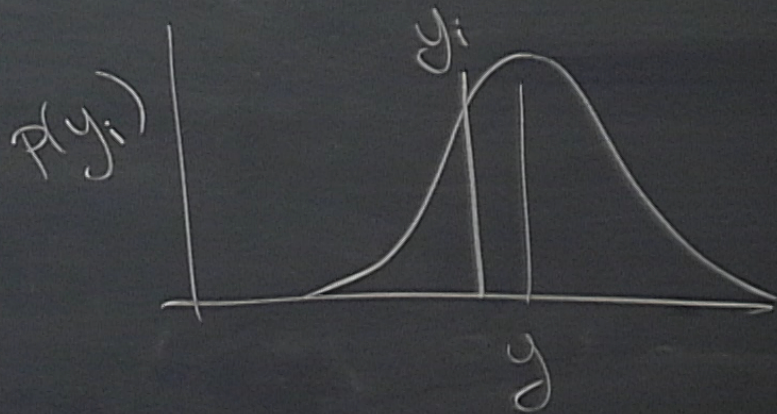


Experimentalist



"the truth is here"

Data Analyst



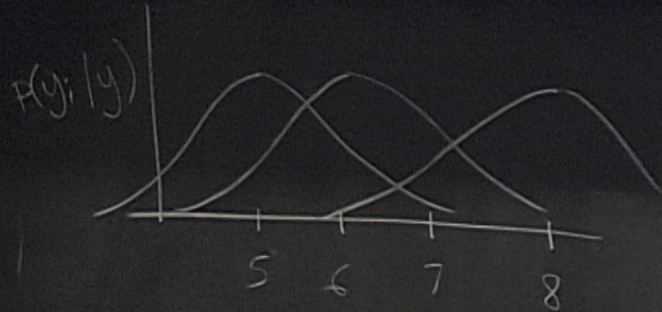
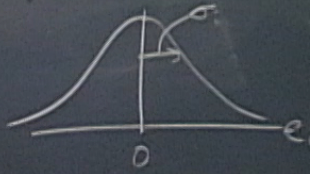
"this is what we would measure"

$$P(y_i | y) = \frac{1}{\sqrt{2\pi}\sigma_i} \exp\left(-\frac{1}{2} \frac{(y_i - y)^2}{\sigma_i^2}\right)$$

$$N(\mu, \sigma^2)$$

$$e_i \sim N(0, \sigma_i^2)$$

- outliers
- model sel
- MCMC



y_i independent

$$P(y_1, y_2, y_3 | y) = P(y_1 | y) P(y_2 | y) P(y_3 | y)$$

$$P(\{y_i\} | y) = \prod_i P(y_i | y)$$

$$= \prod_i \frac{1}{\sqrt{2\pi}\sigma_i} \exp\left(-\frac{1}{2} \frac{(y_i - y)^2}{\sigma_i^2}\right)$$

y_i independent

$$P(y_1, y_2, y_3 | y) = P(y_1 | y) P(y_2 | y) P(y_3 | y)$$

$$P(\{y_i\} | y) = \prod_i P(y_i | y)$$

$$\mathcal{L} = \prod_i \frac{1}{\sqrt{2\pi}\sigma_i} \exp\left(-\frac{1}{2} \frac{(y_i - y)^2}{\sigma_i^2}\right)$$

$$\frac{d}{dy} \log(L) = - \sum_i \frac{y_i - y}{\sigma_i^2}$$

$$0 = \sum_i \frac{1}{\sigma_i^2} - \sum_i \frac{y_i}{\sigma_i^2}$$

$$\hat{y} = \frac{\sum_i \frac{y_i}{\sigma_i^2}}{\sum_i \frac{1}{\sigma_i^2}}$$

inverse-variance weighting

"chi-squared"

Find \hat{y} that

"Maxim

σ_i^2

$$\sum \frac{y_i}{\sigma_i^2}$$

se-variance weighting

"chi-squared" $\sum \chi_i^2$

Find \hat{y} that minimizes χ^2
maximizes χ

"Maximum likelihood" analysis

$$Q = \hat{y} \sum \sigma_i^2 - \sum \sigma_i^2$$

maxim

$$L = \sum \left[-\frac{1}{2} \sum \frac{(y_i - \hat{y})^2}{\sigma_i^2} \right]$$

$$\hat{y} \frac{(\hat{y} - y)^2}{\sigma_i^2} + c = \sum \frac{(y_i - y)^2}{\sigma_i^2}$$

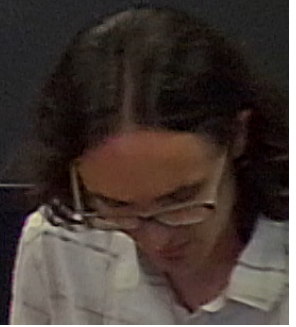
$$\sigma_i^2 = \sum \sigma_i^2$$

$$\sigma_i^2 = \frac{1}{\sum \frac{1}{\sigma_i^2}}$$

$$P(y_i | y) = \frac{1}{\sqrt{2\pi\sigma_i^2}}$$

$$N(\mu, \sigma^2)$$

e



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Fitting a model to data

- fitting a straight line
- magic of Gaussian

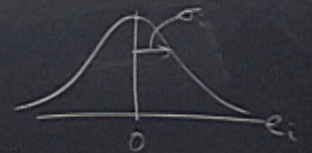
Next

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- model sel
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Night	Position	Uncertainty
1	6	1
2	5	1
3	8	1
ML	$6 \frac{1}{3}$	$\frac{1}{\sqrt{3}} \approx 0.6$

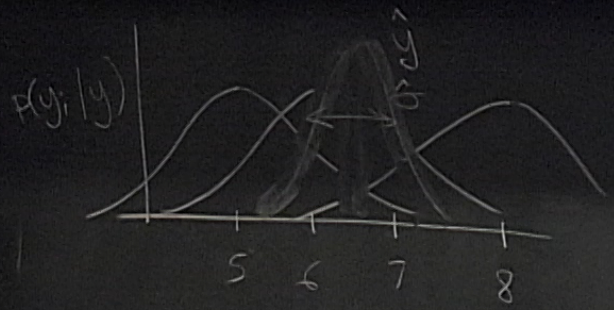
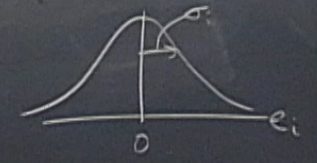
Model

- position y constant
- measurements $y_i = y + e_i$
- e_i drawn from a distribution
- independent
- prob distn is Gaussian with known σ_i , zero mean



- others
- model sel
- MCMC

with known σ_i , zero mean



y_i independent

$$P(y_1, y_2, y_3 | y) = P(y_1 | y) P(y_2 | y) P(y_3 | y)$$

$$P(\{y_i\} | y) = \prod_i P(y_i | y)$$

$$\mathcal{L} = \prod_i \frac{1}{\sqrt{2\pi}\sigma_i} \exp\left(-\frac{1}{2} \frac{(y_i - y)^2}{\sigma_i^2}\right)$$

Frequentist

Bayesian

$$P(A, B) = P(A) P(B | A) = P(B) P(A | B)$$

$$P(B | A) = \frac{P(A | B) P(B)}{P(A)}$$

B: y has the value \hat{y}

A: we measure $\{y_i\}$

$$\underbrace{P(y = \hat{y} \mid \{y_i\})}_{\text{posterior prob}} = \frac{\underbrace{P(\{y_i\} \mid y = \hat{y})}_{\text{likelihood}} \underbrace{P(y = \hat{y})}_{\text{prior}}}{\underbrace{P(\{y_i\})}_{\text{evidence}}}$$

$$\chi_i = \frac{y_i - y}{\sigma_i}$$

"chi-squared" $\sum_i \chi_i^2$

Find \hat{y} that minimizes χ^2
maximizes \mathcal{L}

"Maximum likelihood" analysis

Evidence

$$P(\{y_i\}) = \int P(\{y_i\} | y) P(y) dy$$

all the different ways you could
get $\{y_i\}$