Title: From observers to physics via algorithmic information theory I

Date: Apr 03, 2018 10:30 AM

URL: http://pirsa.org/18040078

Abstract: Motivated by the conceptual puzzles of quantum theory and related areas of physics, I describe a rigorous and minimal "proof of principle― theory in which observers are fundamental and in which the physical world is a (provably) emergent phenomenon. This is a reversal of the standard view, which holds that physical theories ought to describe the objective evolution of a unique external world, with observers or agents as derived concepts that play no fundamental role whatsoever.

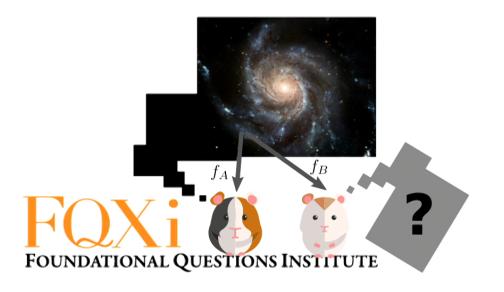
Using insights from algorithmic information theory (AIT), I show that this approach admits to address several foundational puzzles that are difficult to address via standard approaches. This includes the measurement and Boltzmann brain problems, and problems related to the computer simulation of observers. Without assuming the existence of an external world from the outset, the resulting theory actually predicts that there is one as a consequence of AIT â€" in particular, a world with simple, computable, probabilistic laws on which different observers typically (but not always) agree. This approach represents a consistent but highly unfamiliar picture of the world, leading to a new perspective from which to approach some questions in the foundations of physics.

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From observers to physics via algorithmic information theory

Markus P. Müller

Institute for Quantum Optics and Quantum Information, Vienna Perimeter Institute for Theoretical Physics, Waterloo





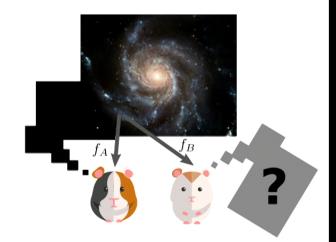
Philosophy aspects with Mike Cuffaro

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Outline for this talk (10:30 - 11:30)

1. Motivation

2. Postulates of the theory



3. How does an external world emerge?

4. What about more than one observer?

1. Motivation

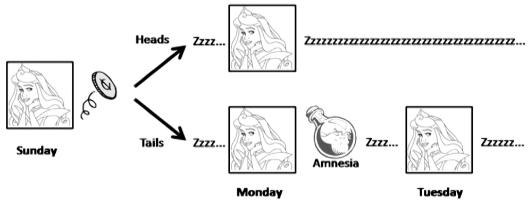
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The talk later today (14:30 - 15:30)

1. Illustration of formalism via the Sleeping Beauty Problem



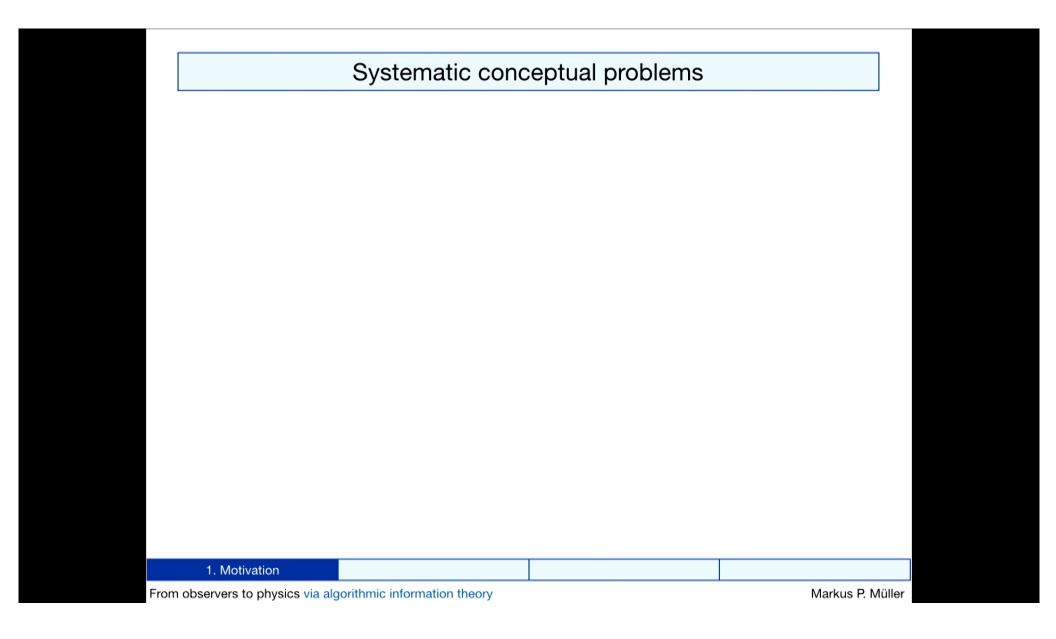
- 2. Quantum theory: Bell violation and no-signalling as generic predictions
- 3. Conceptual comments and conclusions

In large parts independent from this earlier talk.

From observers to physics via algorithmic information theory

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- Quantum theory: measurement problem, Bell's Theorem, "no-go results for facts of the world"
- Cosmology: probabilities in a "big" universe (Boltzmann brains), why low-entropic initial conditions, measure problem

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Claim: These all point in a particular direction: an approach where not a "world", but observers/observations are fundamental.

Fundamental: **P**(future observations | past observations).

1. Motivation

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Induction: P(future observations | past observations).

1. Motivation

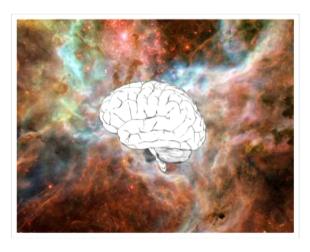
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Boltzmann brain problem

Cosmologists argue about this:



"Wow! I hope I'm not, like, a disembodied brain randomly formed complete with false memories of an existence I never really had, floating in a sea of chaos and disorder. That would really ruin my day...

https://wallacegsmith.wordpress.com/ 2013/06/10/invasion-of-the-boltzmannbrains/

1. Motivation

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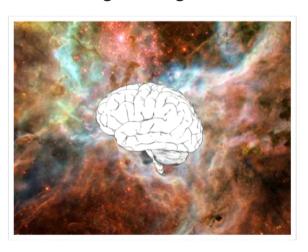
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Sketch of argumentation:

- Fix a cosmological model X that predicts a very large universe.
- Count N_{BB} (# of Boltzmann brains) and compare to N_{nat} (# of naturally evolved brains).
- If $N_{BB} \gg N_{nat}$ then a "BB-observation" should be highly probable: "What the...? I'm in space?! Aargh..."
- That's not what we see, hence X is falsified.

1. Motivation

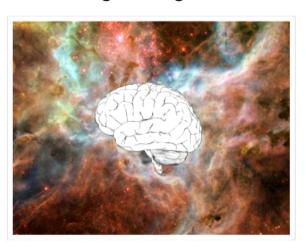
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Is this argumentation valid?

→ seems to rely on *more* than statements about "the world"

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Approach:

Drop any assumption of an "external world".

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Approach:

- Drop any assumption of an "external world".
- Start with the first-person conditional probabilities

P(future observations | past observations),

privately for every single observer.

1. Motivation

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P(next state of observer | previous states of observer), privately for every single observer.

1. Motivation

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 Postulate P=algorithmic probability, motivated by structural arguments. See what follows, and compare with actual physics.

1. Motivation

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Disclaimer



- "Observer" is a technical / informationtheoretic notion. Not (directly) related to "consciousness" etc.
- Not meant as a "TOE". Predicts its own limitation. Useless for most things.
- "Reality" of world is not denied, but only its fundamentality. Reproduces standard view to good approximation.

1. Motivation

From observers to physics via algorithmic information theory

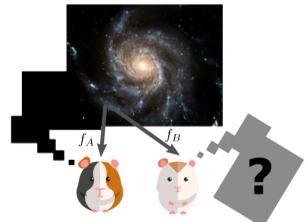
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Outline

1. Motivation





- 3. How does an external world emerge?
- 4. What about more than one observer?

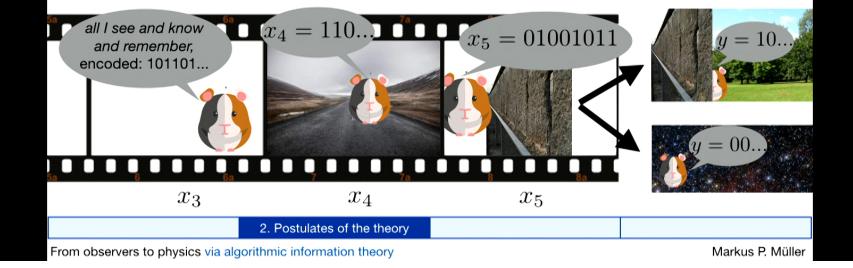
2. Postulates of the theory

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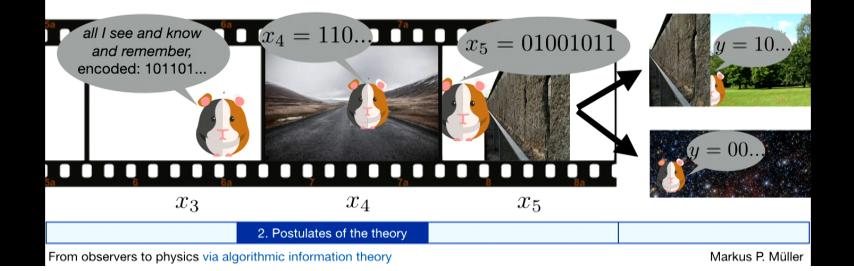
Absolutely minimal ingredients:



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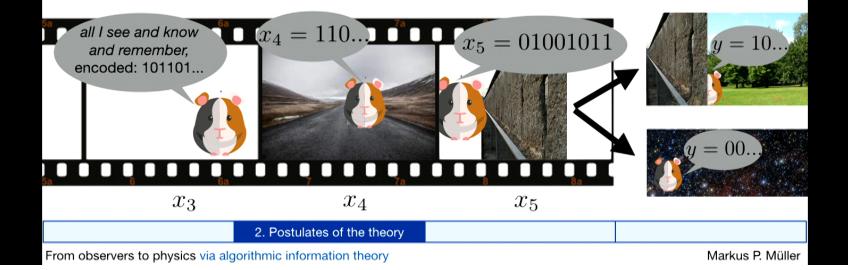
- An observer is in some state *x* (at any given moment).
- It will be in some other state y next.
- Some future states y are more probable than others.



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Absolutely minimal ingredients:

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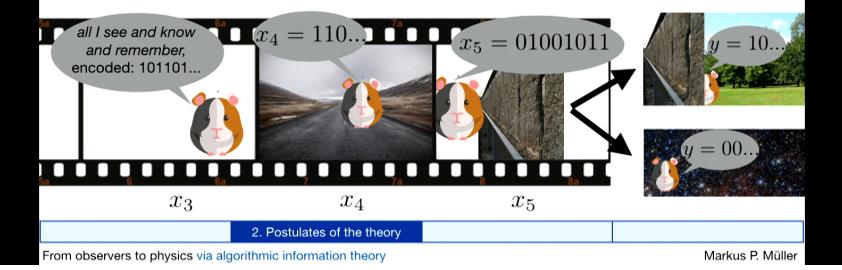


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Absolutely minimal ingredients:

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Agency, quantumness, a "world": not postulated, but (partially) derived.

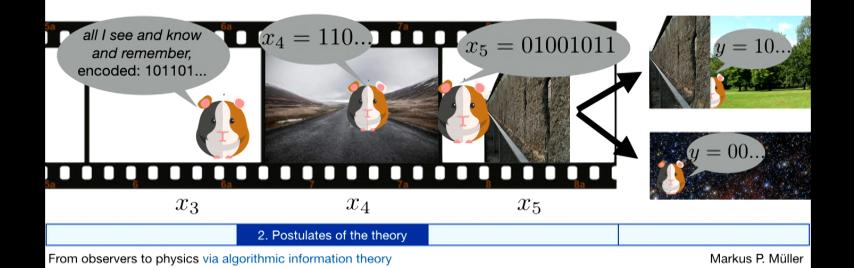


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An observer's **state** can be represented by a binary string (like $x_1=011010$). One (subjective) moment after the other, this yields a sequence $\mathbf{x}=(x_1,x_2,\ldots,x_n)$, and the probability of the next state y is

$$\mathbf{P}(y|x_1,x_2,\ldots,x_n),$$

where P is conditional algorithmic probability.



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 No assumption that this comes from incomplete knowledge / quantum state /... of any "external world".

The P describes fundamental irreducible chances.

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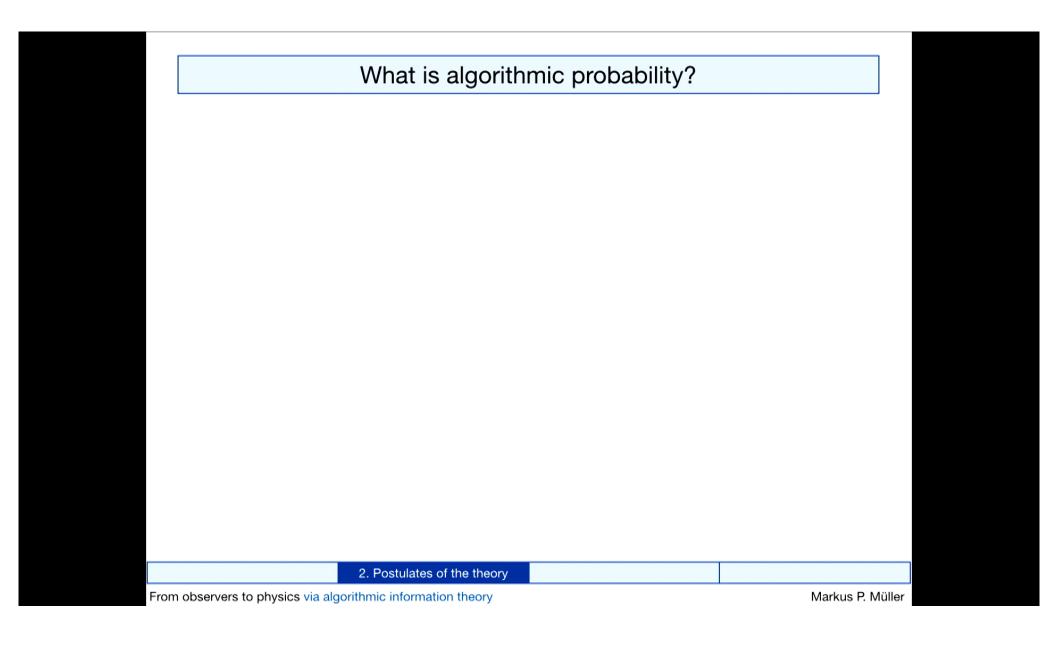
where P is conditional algorithmic probability.

- No assumption that this comes from incomplete knowledge / quantum state /... of any "external world".
 The P describes fundamental irreducible chances.
- Not the actual 0-1-sequence is relevant, but the computability structure that relates the different strings. Analogy: in GR, the actual coordinates don't matter, but the differentiable structure.

2. Postulates of the theory

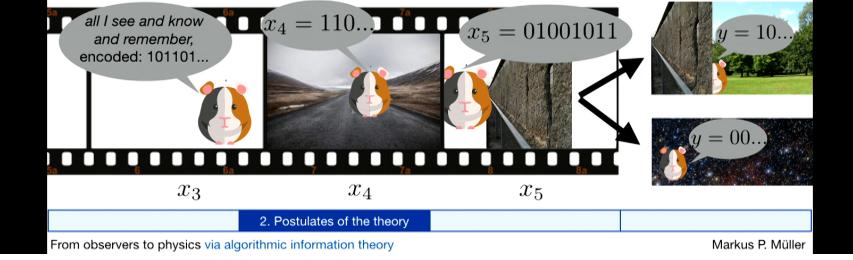
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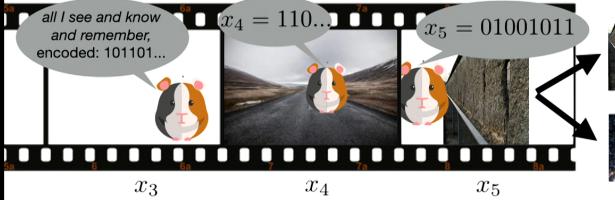
Probability measures on "histories": $\mathbf{P}(x_1, \dots, x_n) = ?$

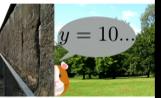


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Probability measures on "histories": $\mu(x_1, \ldots, x_n) = ?$

(Boring) example: $\mu(x_1) := 2^{-2\ell(x_1)-1}$, e.g. $\mu(1011) = 2^{-2\cdot 4-1} = 2^{-9}$,







2. Postulates of the theory

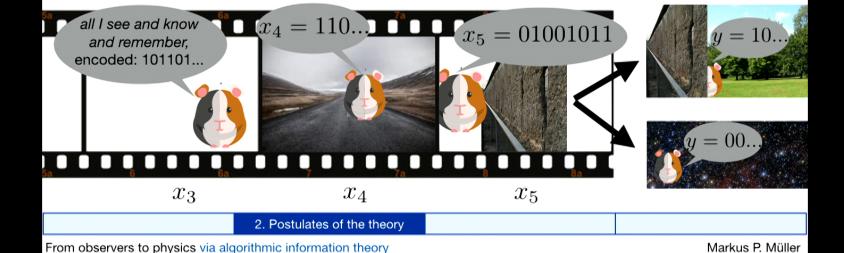
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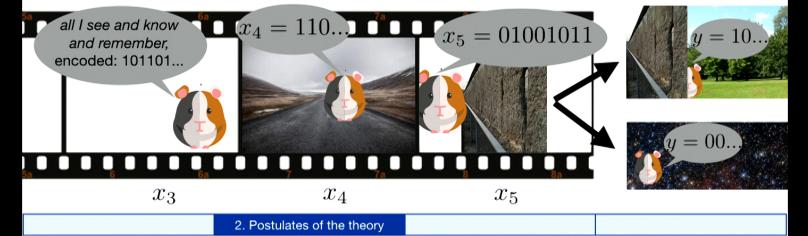
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$$\mu(x_1,\ldots,x_n):=\mu(x_1)\cdot\mu(x_2)\cdot\ldots\cdot\mu(x_n).$$

Measure: $\sum_{x_1} \mu(x_1) = 1$, $\sum_{x_{n+1}} \mu(x_1, \dots, x_n, x_{n+1}) = \mu(x_1, \dots, x_n)$.

Semimeasure: Same with "≤" instead of "=".



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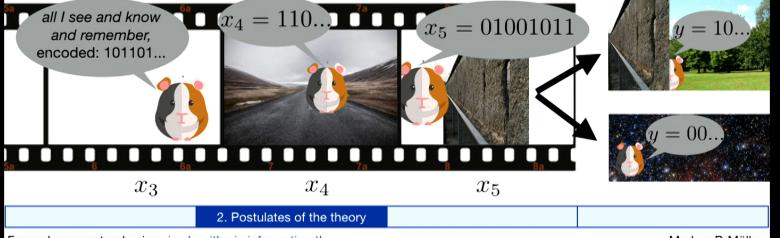
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A (semi)measure is **computable** if there is a computer program that, on input x_1, \ldots, x_n and $m \in \mathbb{N}$ outputs an (1/m)-approximation to $\mu(x_1, \ldots, x_n)$.



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A (semi)measure is **enumerable** if there is a computer program that, on input x_1, \ldots, x_n and $m \in \mathbb{N}$ outputs some approximation $\mu^{(m)}(x_1, \ldots, x_n)$ such that $\mu^{(m)} \leq \mu$ and $\lim_{m \to \infty} \mu^{(m)} = \mu$.

2. Postulates of the theory

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A universal enumerable semimeasure **M** is an enumerable semimeasure such that for every enumerable semimeasure μ there exists some constant c>0 such that $\mathbf{M}(x_1,\ldots,x_n)\geq c\cdot \mu(x_1,\ldots,x_n)$.

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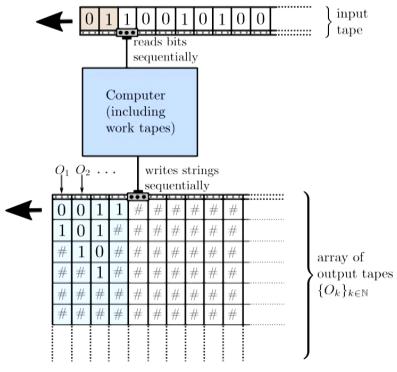
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From observers to physics via algorithmic information theory

Alternative definition:



Universal monotone Turing machine *U*

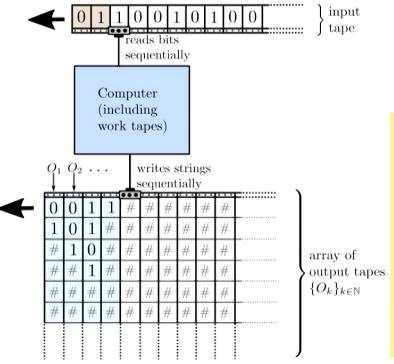
2. Postulates of the theory

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Alternative definition:



 \mathbf{M}_U :=distribution of outputs if input is chosen at random. Is universal enumerable.

"Occam's razor":

$$\mathbf{M}_{U}(x_{1},...,x_{n}) \geq 2^{-K(x_{1},...,x_{n})},$$

where $K(\mathbf{x})$ is the length of the shortest computer program that outputs \mathbf{x} .

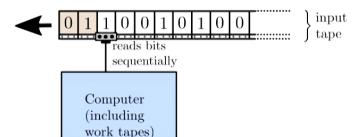
Favors compressibility!

Universal monotone Turing machine *U*

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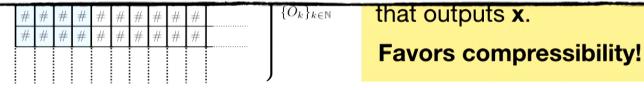
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Q: Won't the resulting theory depend on the choice of universal machine *U* / univ. enum. semimeasure **M**? **A: No,** but non-trivial why not. Maybe ask me later.



Universal monotone Turing machine *U*

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From observers to physics via algorithmic information theory

An observer's **state** can be represented by a binary string (like $x_1 = 011010$). One (subjective) moment after the other, this yields a sequence $\mathbf{x} = (x_1, x_2, \dots, x_n)$, and the probability of the next state y is $\mathbf{P}(y|x_1,\ldots,x_n):=rac{\mathbf{P}(x_1,\ldots,x_n,y)}{\mathbf{P}(x_1,\ldots,x_n)},$

where P is conditional algorithmic probability.

Conceptually, it would be more consequential to define **P** only to depend on the present, not the past. In some sense, the "past" is only what an observer presently remembers...

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Conceptually (much) clearer, but consequences much harder to work out. Don't know how to do it (yet).

2. Postulates of the theory

From observers to physics via algorithmic information theory

Why algorithmic probability? Several possible arguments: 2. Postulates of the theory Markus P. Müller From observers to physics via algorithmic information theory

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Several possible arguments:

1. Extrapolating Solomonoff induction



2. Postulates of the theory

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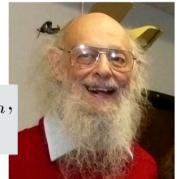
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Sol. Induction (1964): after seeing bits b_1, \ldots, b_n , predict the next bit b with prob. $\mathbf{P}(b|b_1 \ldots b_n)$.



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From observers to physics via algorithmic information theory

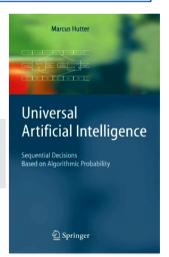
Markus P. Müller

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Several possible argumen Gives quickly the correct probabilities in all computable probabilistic environments.

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2. Postulates of the theory

From observers to physics via algorithmic information theory

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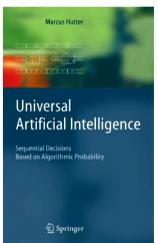
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Given a description of an experiment as input,

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2. Postulates of the theory

From observers to physics via algorithmic information theory

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- This is enough to guarantee: Solomonoff induction will do at least as good as our best physical theories in prediction (in principle, asymptotically, for many observations).

2. Postulates of the theory

From observers to physics via algorithmic information theory

Markus P. Müller

Marcus Hutter

Artificial Intelligence

Universal

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 Given a description of an experiment as input,

 an algorithm can compute the expected outcome statistics.
- This is enough to guarantee: Solomonoff induction will do at least as good as our best physical theories in prediction (in principle, asymptotically, for many observations).
- Idea: postulate that Solomonoff induction is "the law"!

 This will then have to be consistent with physics (given our data).

2. Postulates of the theory

From observers to physics via algorithmic information theory

Markus P. Müller

Marcus Hutter

Artificial Intelligence

Universal

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2. A structural motivation

Physics is nothing but what makes some future observations more likely than others.

Algorithmic probability is an essentially unique "canonical propensity structure".

2. Postulates of the theory

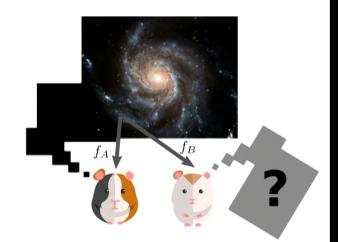
From observers to physics via algorithmic information theory

Markus P. Müller

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Outline

- 1. Motivation
- 2. Postulates of the theory



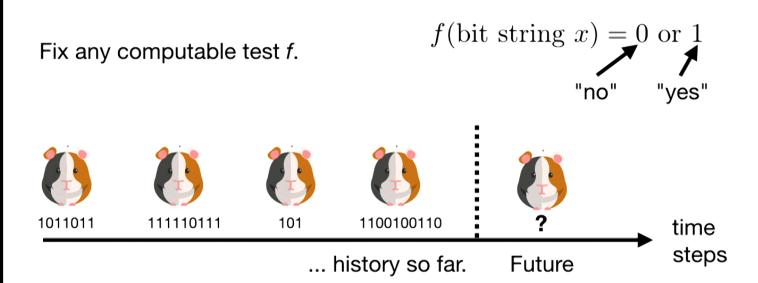
- 3. How does an external world emerge?
- 4. What about more than one observer?

3. How does physics emerge?

From observers to physics via algorithmic information theory

Markus P. Müller

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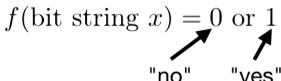
3. How does physics emerge?

From observers to physics via algorithmic information theory

Markus P. Müller

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Fix any computable test f.



Suppose the answer has been "yes" all along:



3. How does physics emerge?

From observers to physics via algorithmic information theory

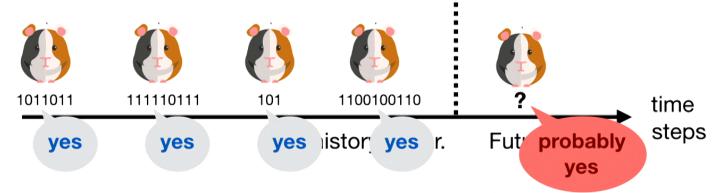
Markus P. Müller

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Fix any computable test f.

f(bit string x) = 0 or 1"no" "ves"

Suppose the answer has been "yes" all along:



Theorem: Then, with probability close to one, answer will be "yes" in the future.

3. How does physics emerge?

From observers to physics via algorithmic information theory

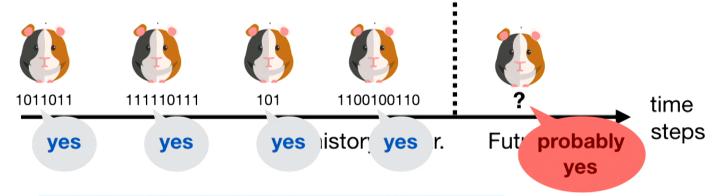
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Theorem: Then, with probability close to one, answer will be "**yes**" in the future.

Intuitive reason: This makes sequence of strings **more compressible**.

3. How does physics emerge?

From observers to physics via algorithmic information theory

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Rigorous mathematical formulation:

Theorem 8.3 (Persistence of regularities). Let A be a deadend free observer graph, and f an open computable A-test. For bits $a_1, \ldots, a_n, b \in \{0, 1\}$, define the measure p as

$$p(b|a_1a_2...a_n) := \mathbf{P}\{f(\mathbf{x}_1^{n+2}) = b \mid f(\mathbf{x}_1^2) = a_1,..., f(\mathbf{x}_1^{n+1}) = a_n\},$$

and similarly define the semimeasure m with \mathbf{P} replaced by \mathbf{M} . Then we have 38 $m(0|1^n) \leq 2^{-K(n)+\mathcal{O}(1)}$, and for the measure p we have the slightly less explicit statement

$$p(1|1^n) \stackrel{n \to \infty}{\longrightarrow} 1, \tag{10}$$

but the convergence is rapid since $\sum_{n=0}^{\infty} p(0|1^n) < \infty$. Thus, e.g., $p(1|1^n) > 1 - \frac{1}{n}$ for all but finitely many n. Moreover, the probability that $f(\mathbf{x}_1^{n+1}) = 1$ for all $n \in \mathbb{N}$ is non-zero.

3. How does physics emerge?

From observers to physics via algorithmic information theory

This is already indicates how **Boltzmann brains** are exorcized:

3. How does physics emerge?

From observers to physics via algorithmic information theory

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This is already indicates how **Boltzmann brains** are exorcized:

f := computable test whether observations are typical for a planet-like environment.

Suppose the answer has been "yes" all along:



3. How does physics emerge?

From observers to physics via algorithmic information theory

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But it is not quite enough — cf. Goodman's **New Riddle** of Induction:

3. How does physics emerge?

From observers to physics via algorithmic information theory

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3. How does physics emerge?

From observers to physics via algorithmic information theory

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But it is not quite enough — cf. Goodman's **New Riddle** of Induction:

f := computable test whether observations are typical for a planet-like environment.

$$\tilde{f} := \begin{cases} f & \text{if observed calendar shows year } \leq 2050 \\ \text{NOT } f & \text{if observed calendar shows year } > 2050. \end{cases}$$

(cf. Goodman's green/blue versus bleen/grue).

3. How does physics emerge?

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(cf. Goodman's green/blue versus bleen/grue).

Theorem applies to both f and \tilde{f} . Contradiction?! **No.**

Resolution: Since $K(f) < K(\tilde{f})$, the f-regularity stabilizes **earlier** than the \tilde{f} -regularity.

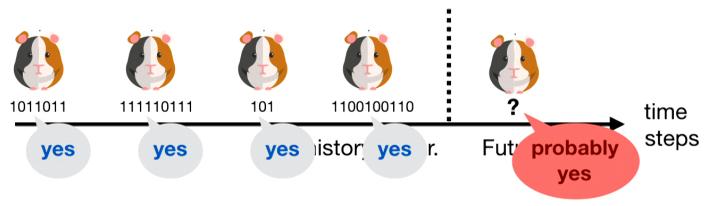
3. How does physics emerge?

From observers to physics via algorithmic information theory

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Suppose the answer has been "yes" all along:



Boltzmann brain experience ("what the... I'm suddenly in space... argh!!") is highly unlikely.

3. How does physics emerge?

From observers to physics via algorithmic information theory

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Will the different regularities "fit together" coherently? Yes!



3. How does physics emerge?

From observers to physics via algorithmic information theory

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Prediction 2: Simple, computable, probabilistic "world"

Theorem. Consider any **computable probabilistic process** that has description length L on a universal computer. Suppose it generates outputs x_1, x_2, x_3, \ldots according to the (computable) distribution $\mu(x_1, \ldots, x_n)$. Then, with **P**-probability at least 2^{-L} we have

$$\mathbf{P}(y|x_1,\ldots,x_n) \stackrel{n\to\infty}{\longrightarrow} \mu(y|x_1,\ldots,x_n),$$

i.e. the outputs of this process will asymptotically be a perfect description of the observer's states.

3. How does physics emerge?

From observers to physics via algorithmic information theory

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observer state, **P**-distributed

looks as if it came from



computational process, output μ -distributed.

3. How does physics emerge?

From observers to physics via algorithmic information theory

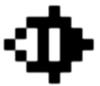
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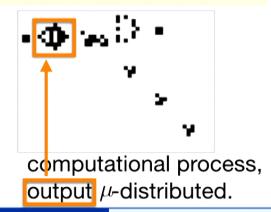
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From observers to physics via algorithmic information theory

Markus P. Müller

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- It is **contingent** which process (and thus μ) will emerge, but **simpler** ones are highly preferred (simpler = smaller L = higher probability)
- Thus, observer's probabilities will equal the marginal distribution of some random variable that's part of a probabilistic process with computable laws of short description (a simple algorithm).

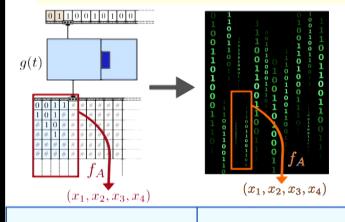
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Don't think too naively of "tapes", "bits", discreteness etc. — it's an abstract computational process.

3. How does physics emerge?

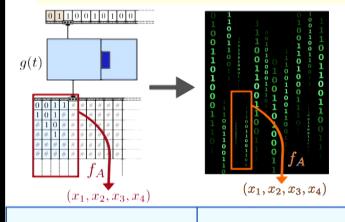
From observers to physics via algorithmic information theory

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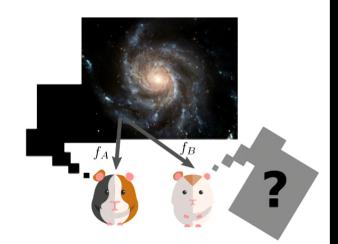
• There are generic features of (simple) computational processes, e.g. that they **start in some simple initial state**. This seems to be consistent with what we see in physics ("low-entropic initial conditions").

3. How does physics emerge?

From observers to physics via algorithmic information theory

Outline

- 1. Motivation
- 2. Postulates of the theory



- 3. How does an external world emerge?
- 4. What about more than one observer?

3. How does physics emerge?

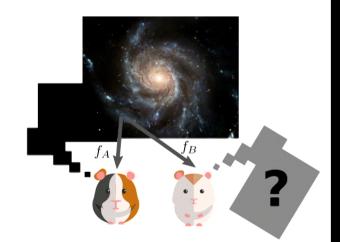
From observers to physics via algorithmic information theory

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4. More than one observer?

From observers to physics via algorithmic information theory

Markus P. Müller

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Apriori, different observers make their own "private" observations.





$$\mathbf{P}(y^A|x_1^A,\ldots,x_n^A)$$

Bambi



$$\mathbf{P}(y^B|x_1^B,\ldots,x_m^B)$$

3. How does physics emerge?

From observers to physics via algorithmic information theory

Apriori, different observers make their *own* "private" observations. They are completely unrelated, and live in their own "external worlds".





B-world

A-world

3. How does physics emerge?

From observers to physics via algorithmic information theory

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B-world

But suppose that **A** sees something in her external world that seems like another observer **B** to her...

3. How does physics emerge?

From observers to physics via algorithmic information theory

A-world

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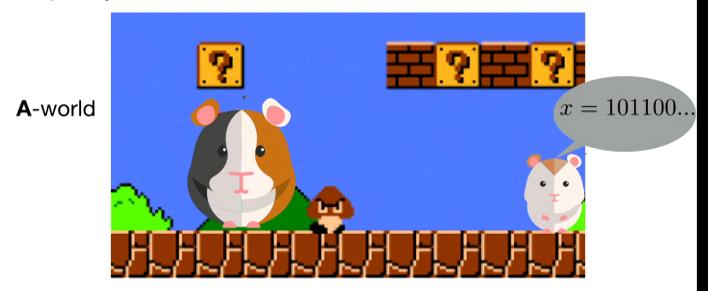
3. How does physics emerge?

From observers to physics via algorithmic information theory

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Apriori, different observers make their *own* "private" observations. They are completely unrelated, and live in their own "external worlds".



But suppose that **A** sees something in her external world that seems like another observer **B** to her...

Does what **A** sees really correspond to the first-person perspective of another observer?

3. How does physics emerge?

From observers to physics via algorithmic information theory

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How to formalize this:

A-world

Choose some (simple) computable function f_B that, at any time step, "reads out" some binary string (interpreted as ${\bf B}$'s current state)

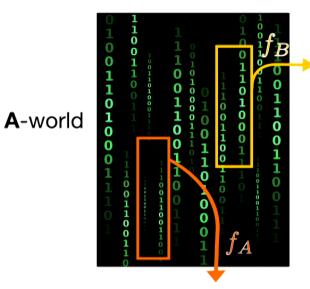
 f_B encodes "what other thing in her world **A** is looking at".

3. How does physics emerge?

From observers to physics via algorithmic information theory

Markus P. Müller

How to formalize this:



x = 101100...

Choose some (simple) computable function f_B that, at any time step, "reads out" some binary string (interpreted as \mathbf{B} 's current state)

 f_B encodes "what other thing in her world **A** is looking at".

Two probability distributions:

 $\nu(x_1,x_2,\ldots,x_n):=$ prob. that **B** is in states x_1,\ldots,x_n acc. to **A**-world

 $\mathbf{P}(x_1,\ldots,x_n)=$ algorithmic probability that **B** is in states x_1,\ldots,x_n (the real private chances for **B**!)

3. How does physics emerge?

From observers to physics via algorithmic information theory

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Let's consider a colourful example:

A-world



If Abby has a chance of about 100% of seeing Bambi see the sun rise tomorrow, then will Bambi have a chance of about 100% of seeing the sun rise tomorrow?

 $u(x_1,x_2,\ldots,x_n) := \text{prob. that } \mathbf{B} \text{ is in states } x_1,\ldots,x_n \text{ acc. to } \mathbf{A}\text{-world}$ $\mathbf{P}(x_1,\ldots,x_n) = \text{algorithmic probability that } \mathbf{B} \text{ is in states } x_1,\ldots,x_n$ (the real private chances for \mathbf{B} !)

3. How does physics emerge?

From observers to physics via algorithmic information theory

Markus P. Müller

Let's consider a colourful example:

A-world



If Abby has a chance of about 100% of seeing Bambi see the sun ν rise tomorrow, then will Bambi have a chance of about 100% of seeing the sun rise tomorrow?

Theorem: With ν -probability one,

$$\mathbf{P}(y|x_1,\ldots,x_k) \stackrel{k\to\infty}{\longrightarrow} \nu(y|x_1,\ldots,x_k).$$

So the answer is "yes", asymptotically.

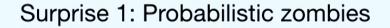
(In other words: $\mathbf{P} \approx \nu$ if **B** is "old enough" in **A**-world.)

3. How does physics emerge?

From observers to physics via algorithmic information theory

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• "Objective reality" is a theorem, not an assumption: $\mathbf{P}(y|x_1,\dots,x_k) \overset{k\to\infty}{\longrightarrow} \nu(y|x_1,\dots,x_k).$

$$\mathbf{P}(y|x_1,\ldots,x_k) \stackrel{k\to\infty}{\longrightarrow} \nu(y|x_1,\ldots,x_k).$$

Sometimes premises of theorem not satisfied ——— "zombies"!

4. Surprises

From observers to physics via algorithmic information theory

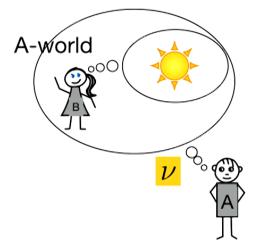
Surprise 1: Probabilistic zombies

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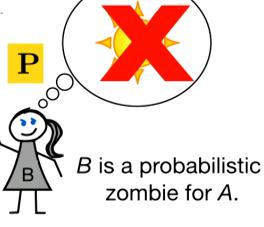
$$\mathbf{P}(y|x_1,\ldots,x_k) \stackrel{k\to\infty}{\longrightarrow} \nu(y|x_1,\ldots,x_k).$$

Sometimes premises of theorem not satisfied ——— "zombies"!

Pics borrowed from Renato Renner's slides+edited...



but



4. Surprises

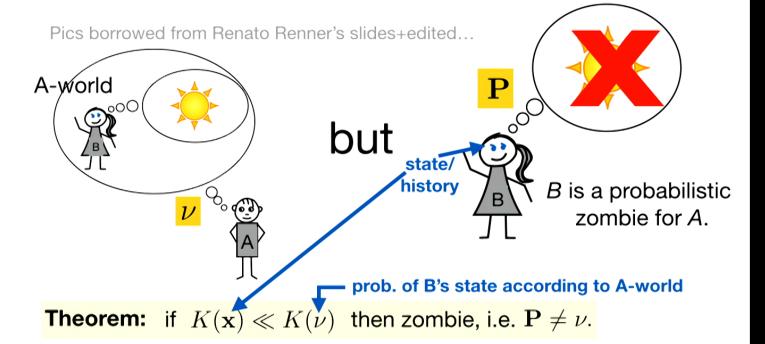
From observers to physics via algorithmic information theory

Surprise 1: Probabilistic zombies

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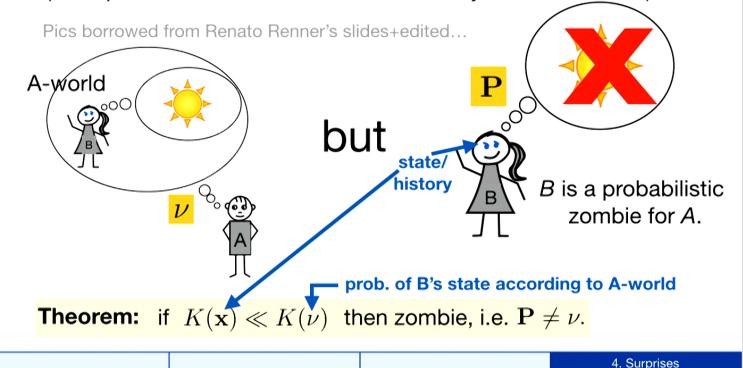
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4. Surprises

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Surprise 1: Probabilistic zombies

- $K(\mathbf{x})$ too small: **A** "points to" something in his world that is too simple (e.g. a single bit, written on a blackboard)
- $K(\nu)$ too large: **A** "points to" something in a too complicated way (example: **Boltzmann brains**, because very hard to localize.)

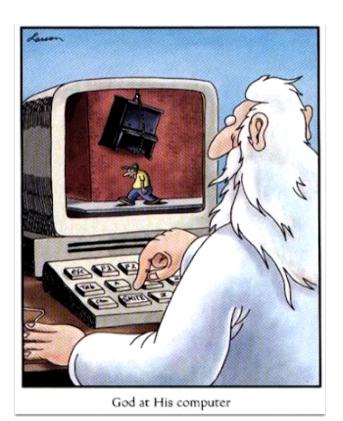


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Surprise 2: Brain emulation



Get also concrete criteria for when **simulation** of an agent corresponds to an "actual firstperson perspective" (similarly as in the zombie case).

Turns out: makes big difference if simulation is "open" or "closed" (feed in outside data or not). More details in paper.

4. Surprises

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Conclusions

- Yes, we can start with the first-person perspective, and obtain a notion of "emergent external world", consistent with known physics.
- Far from the usual regime of physics; useless for most things.
- → Allows to address fundamental problems rigorously that we tend to address with much less rigor: "why a world with simple laws at all", Boltzmann brain problem, etc.
- Not the final word (see open problem etc.), but fun.
- → Proof of principle: can have physical theory of completely new kind (first person first) that is consistent, rigorous, and has explanatory and predictive power (for some questions, but not for others).

Full version: arXiv:1712.01826
Short version (not as good, v2 soon): arXiv:1712.01816

4. Novel predictions

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Conclusions

- Yes, we can start with the first-person perspective, and obtain a notion of "emergent external world", consistent with known physics.
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- + Allows to address **fundamental problems rigorously** that we tend to address with much less rigor: "why a world with simple laws at all", Boltzmann brain problem, etc.
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Thank you!

Novel predictions

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