

Title: PSI 2017/2018 - Machine Learning for Many Body Physics - Lecture 7

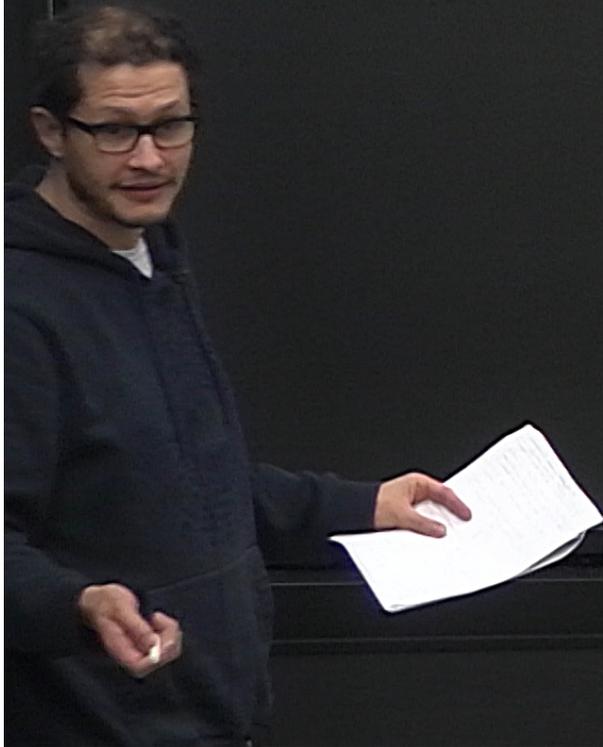
Date: Apr 17, 2018 09:00 AM

URL: <http://pirsa.org/18040060>

Abstract:

Unsupervised learning

Algorithms where the data (E) is unlabeled.



Unsupervised Learning

Algorithms where the data (E) is unlabeled.

* Learn $P(\vec{x})$

$\vec{x}_1, \vec{x}_2, \dots, \vec{x}_m$

Unsupervised Learning

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$\vec{x}_1, \vec{x}_2, \dots, \vec{x}_m$

* Learn $P(\vec{x})$ (density estimation)

Unsupervised learning

Algorithms where the data (E) is unlabeled.

$\vec{x}_1, \vec{x}_2, \dots, \vec{x}_m$

Learn $P(\vec{x})$ (density estimation)

$$|Y(\vec{x})|^2 = P(\vec{x})$$

Unsupervised Learning

Algorithms where the data (E) is unlabeled.

$\vec{x}_1, \vec{x}_2, \dots, \vec{x}_m$

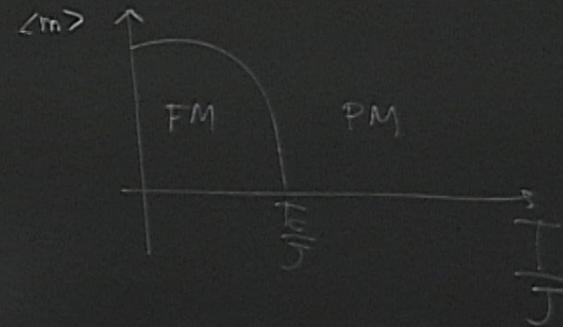
- * Learn $P(\vec{x})$ (density estimation)
- * Synthesis - Generation of samples according $P(\vec{x})$
- * Clustering

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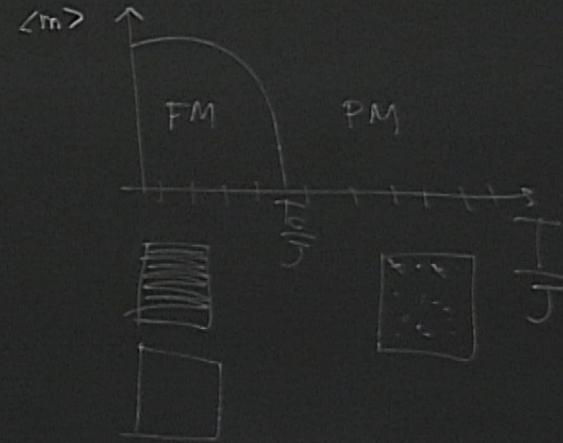


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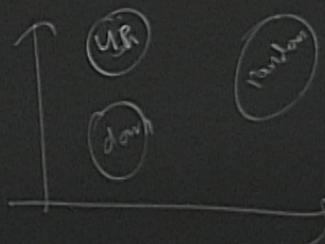


for (E) in unlabeled.

$\vec{x}_1, \vec{x}_2, \dots, \vec{x}_m$

formation)

PM



according $P(\vec{x})$

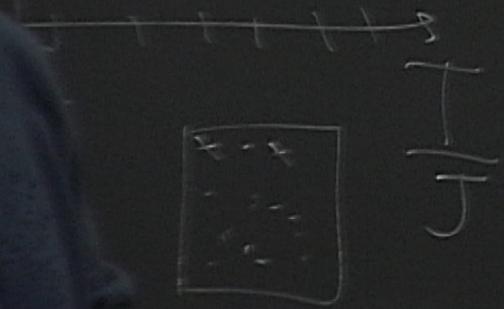
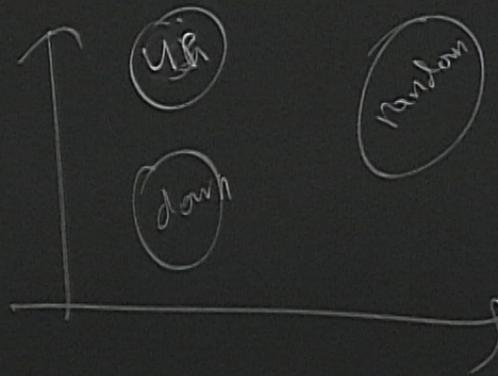


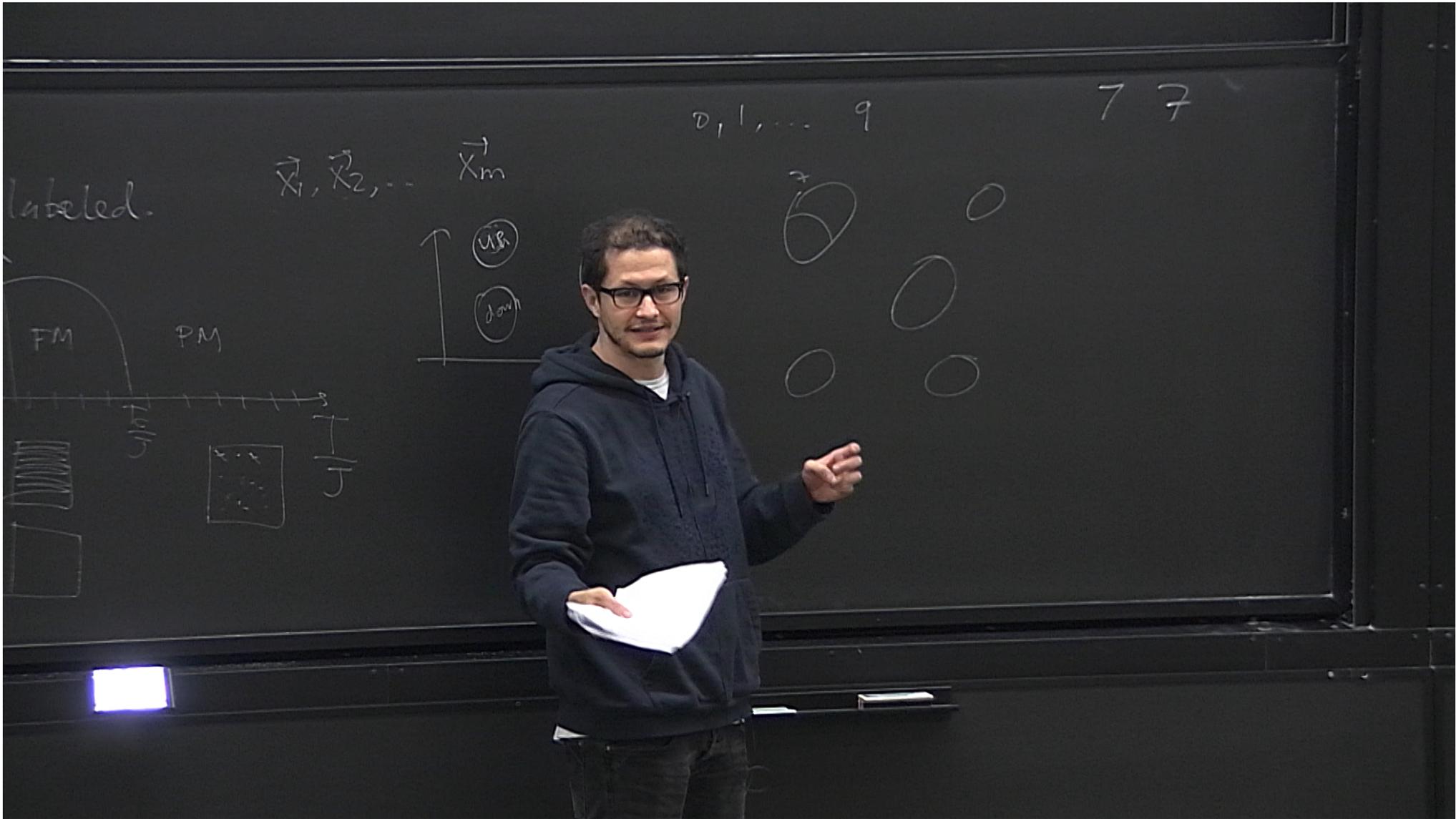
$D, 1, \dots, 9$

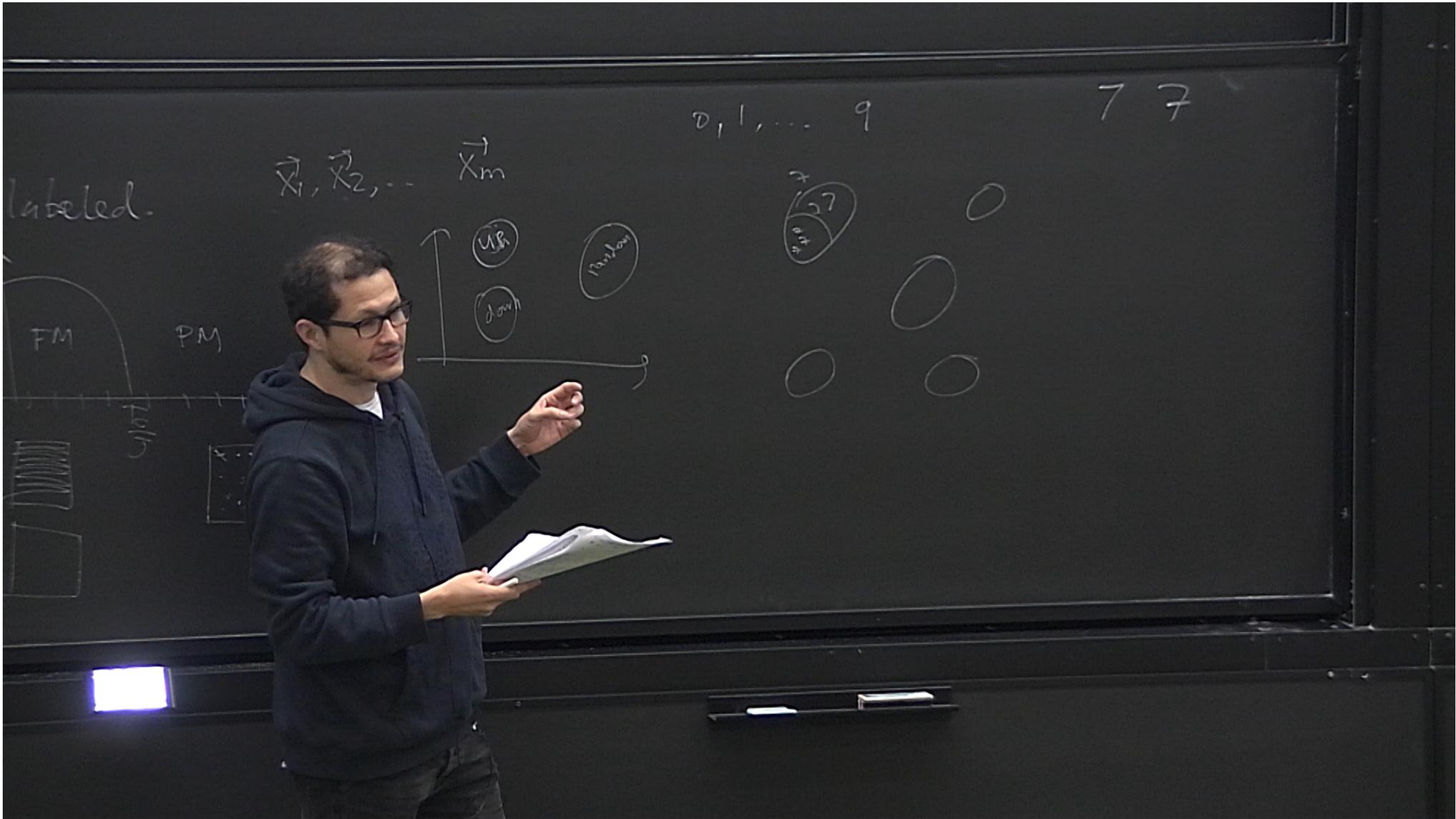
$\vec{x}_1, \vec{x}_2, \dots, \vec{x}_m$

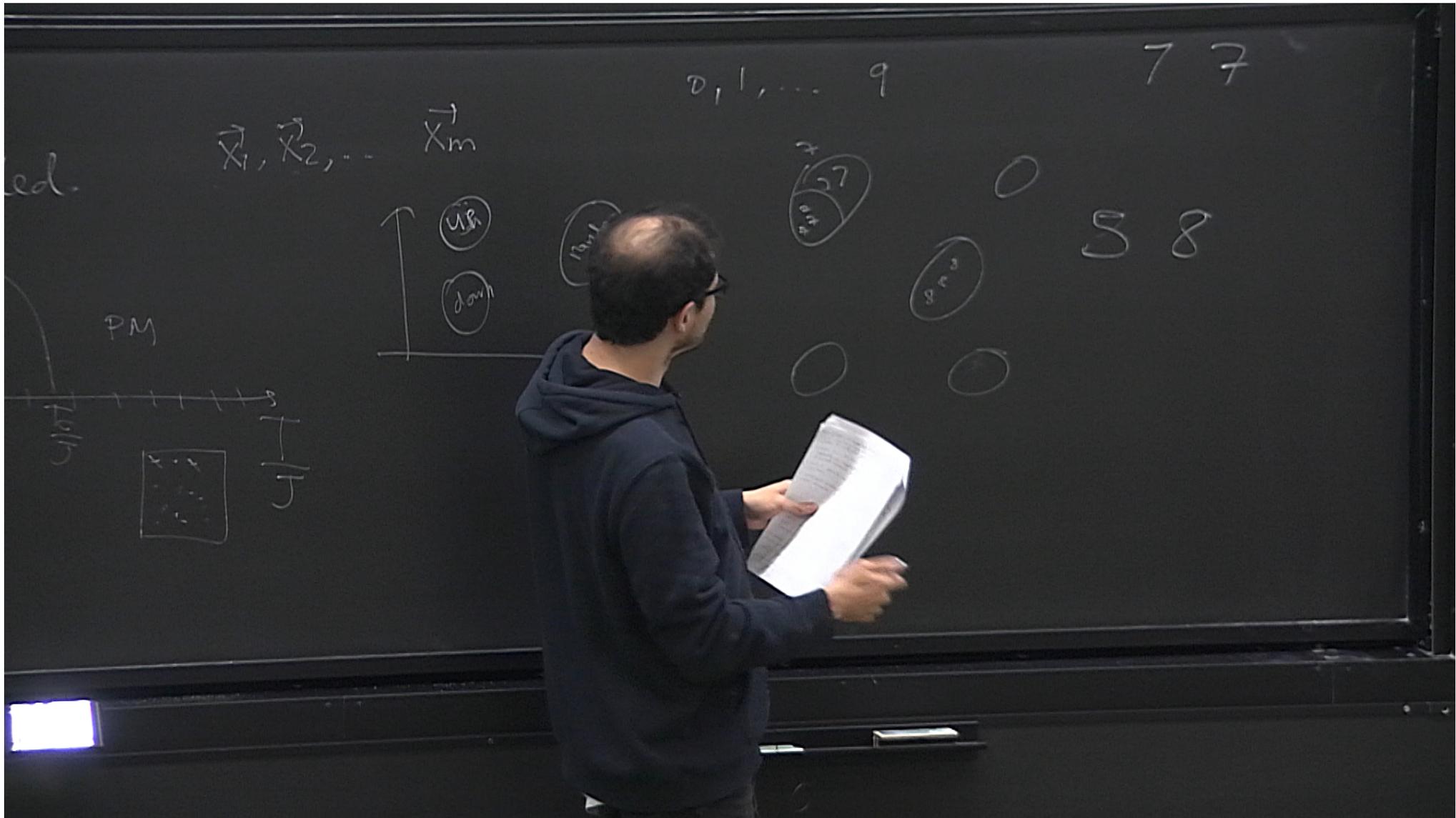
stepped.

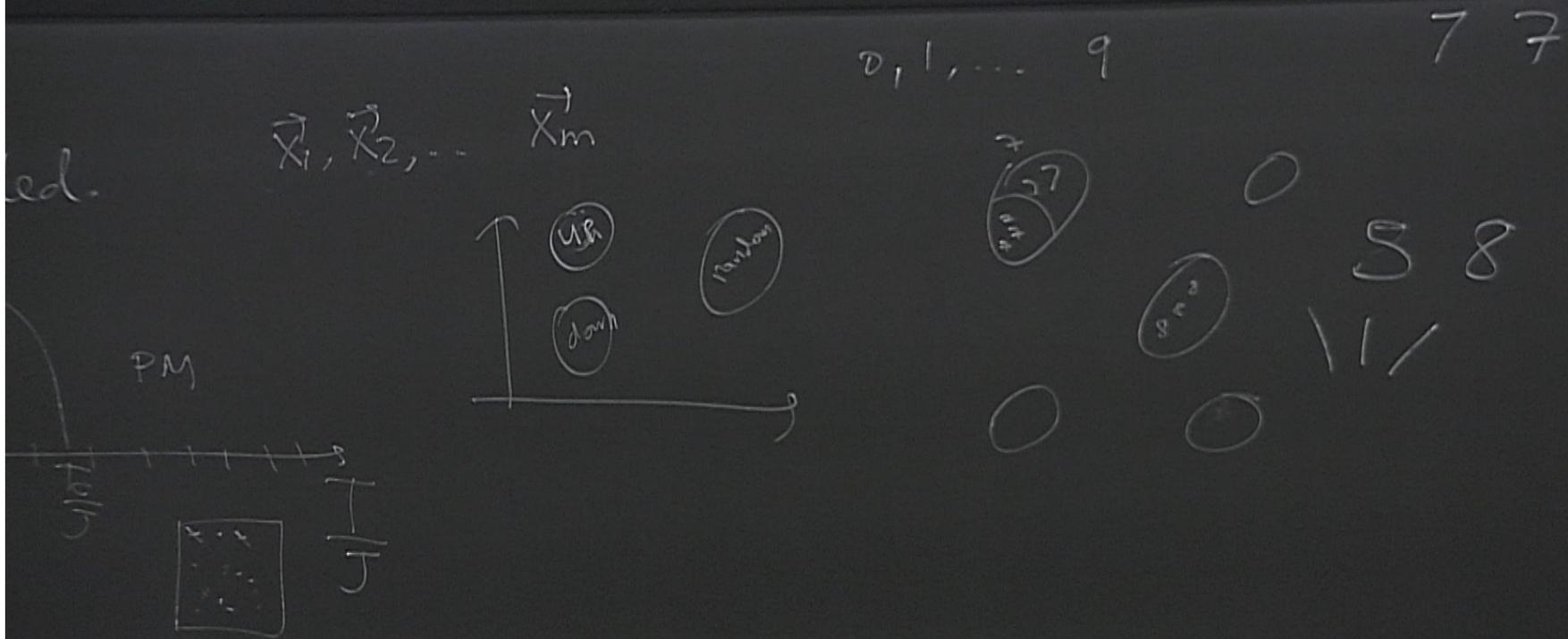
PM

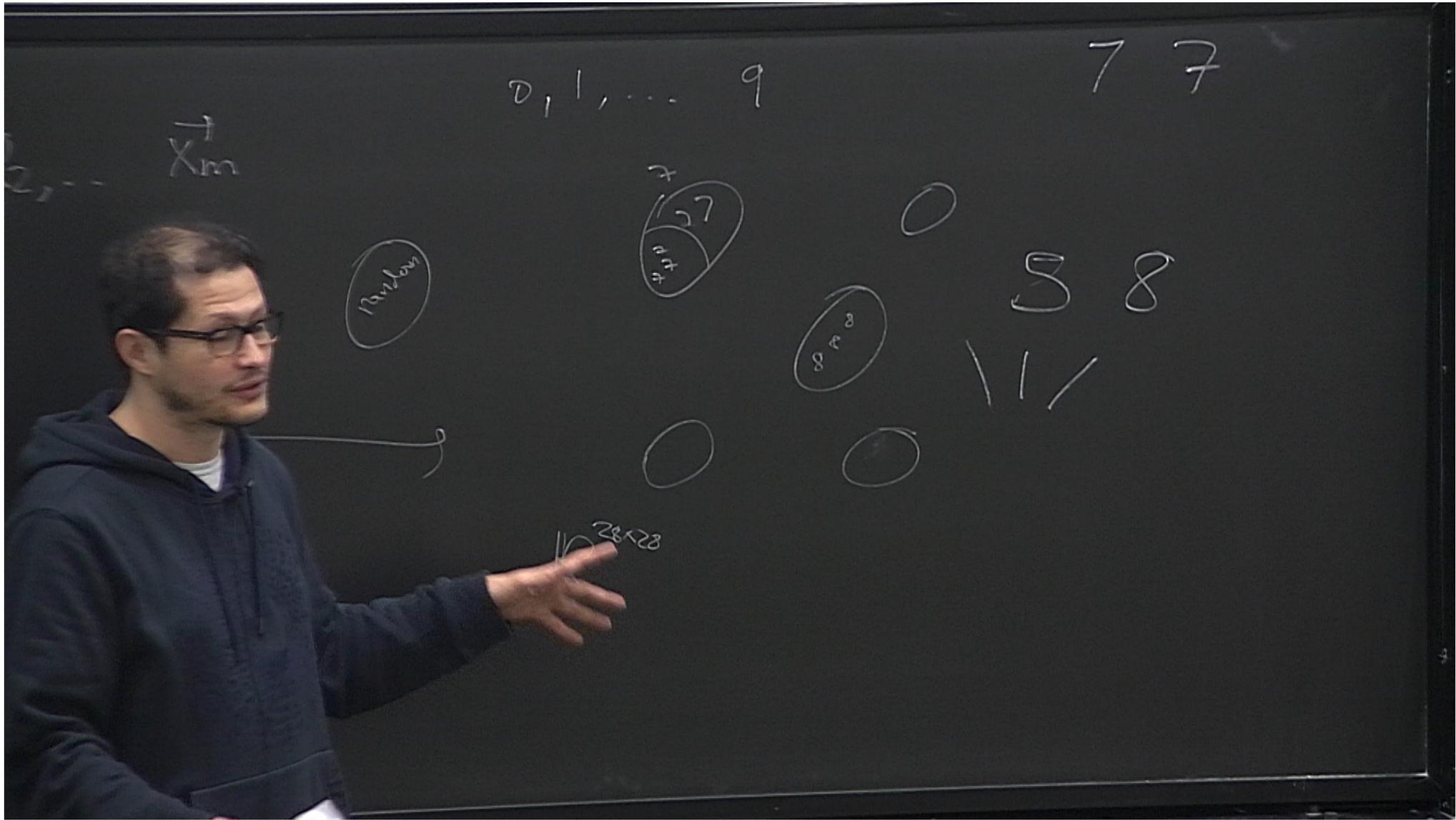


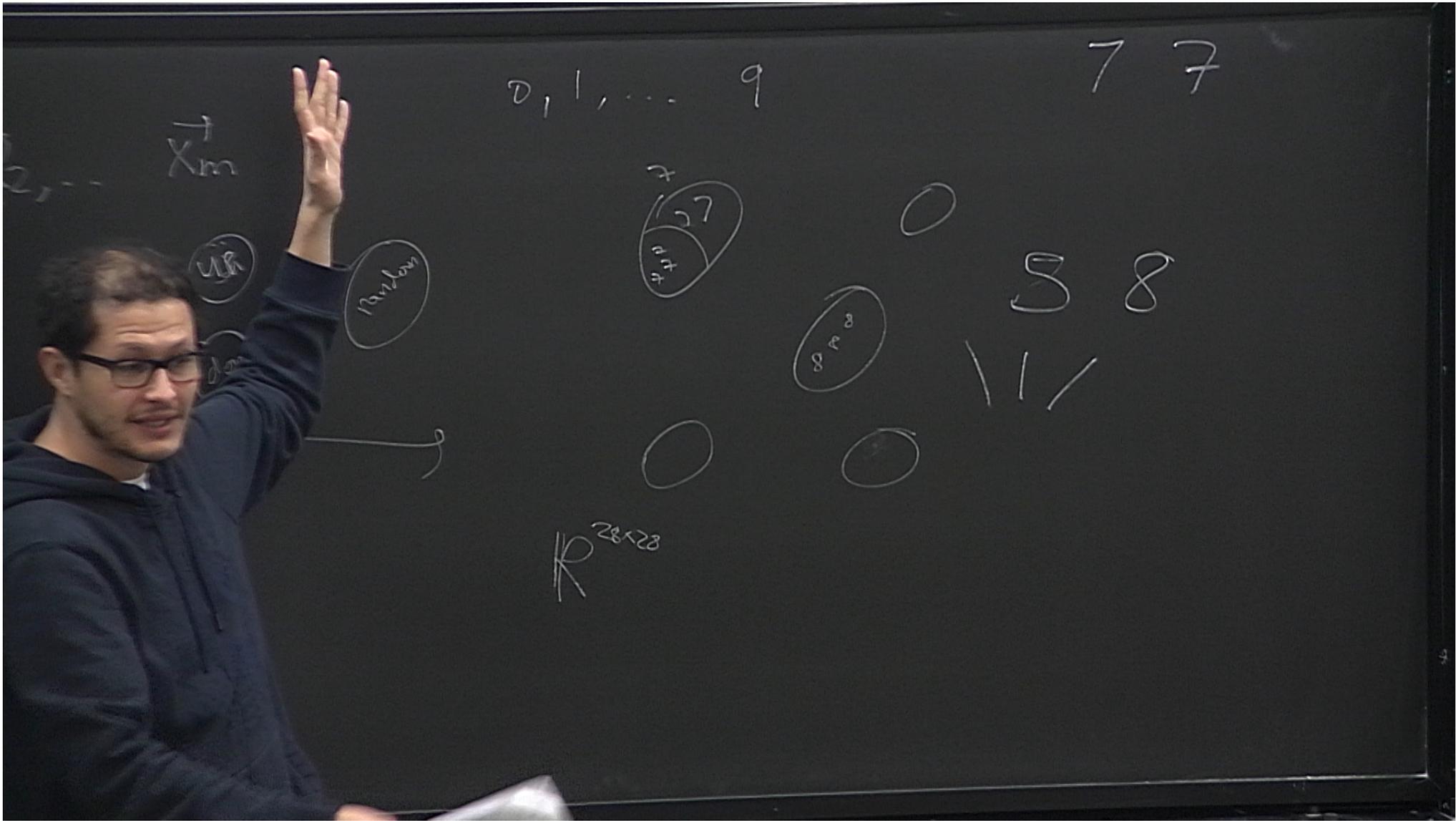












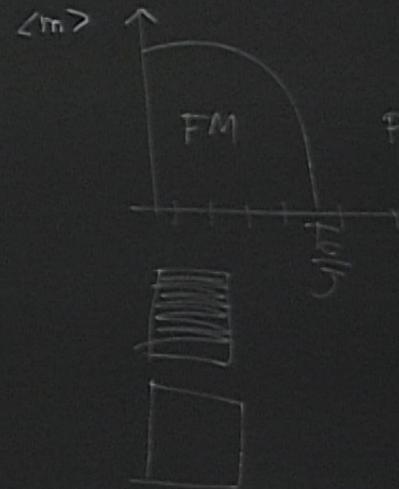
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Supervised vs Unsupervised Learning?

$$\vec{x}_1 \dots \vec{x}_m \rightarrow P(\vec{x}) \quad \vec{x} \in \mathbb{R}^n$$

Supervised vs Unsupervised Learning?

UL: $\vec{x}_1, \dots, \vec{x}_m \rightarrow P(\vec{x}) \quad \vec{x} \in \mathbb{R}^n$

SL: $\vec{x}_1, \dots, \vec{x}_m + \vec{y}_1, \vec{y}_2, \dots, \vec{y}_m$

Supervised vs Unsupervised Learning?

$$UL: \vec{x}_1, \dots, \vec{x}_m \rightarrow P(\vec{x}) \quad \vec{x} \in \mathbb{R}^n$$

$$SL: \vec{x}_1, \dots, \vec{x}_m + \vec{y}_1, \vec{y}_2, \dots, \vec{y}_m \quad P(\vec{y} | \vec{x})$$

UL and SL are not formally different

$$P(\vec{x}) = \prod_{i=1}^n P(x_i | x_1, \dots, x_{i-1})$$

$$\vec{x} = (x_1, x_2, \dots, x_n)$$

used learning?

$\vec{x} \in \mathbb{R}^n$

$P(\vec{y}|\vec{x})$

like wise: $P(\vec{x}, \vec{y})$
 $P(\vec{y}|\vec{x}) = \frac{P(\vec{x}, \vec{y})}{\sum_{\vec{y}} P(\vec{x}, \vec{y})}$

ally different

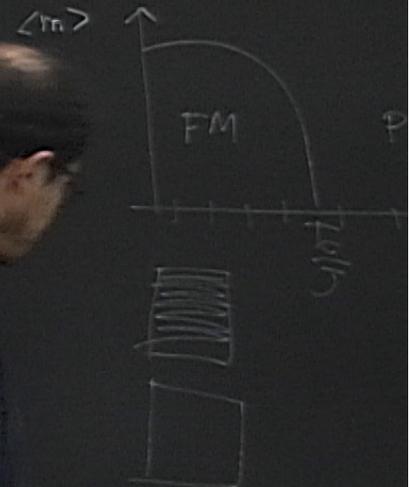
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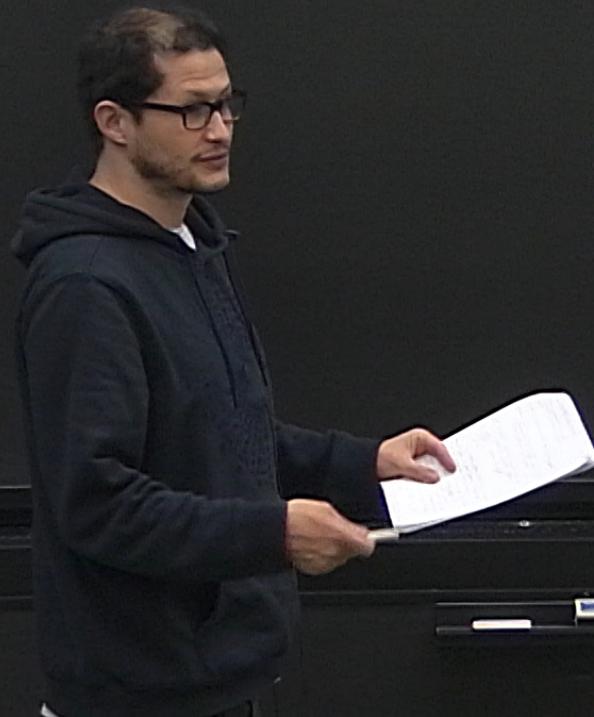
* Synthesis. Generation of samples accord

* Clustering



Principal component analysis (PCA)

We want to generate a low-dimensional representation of the data.



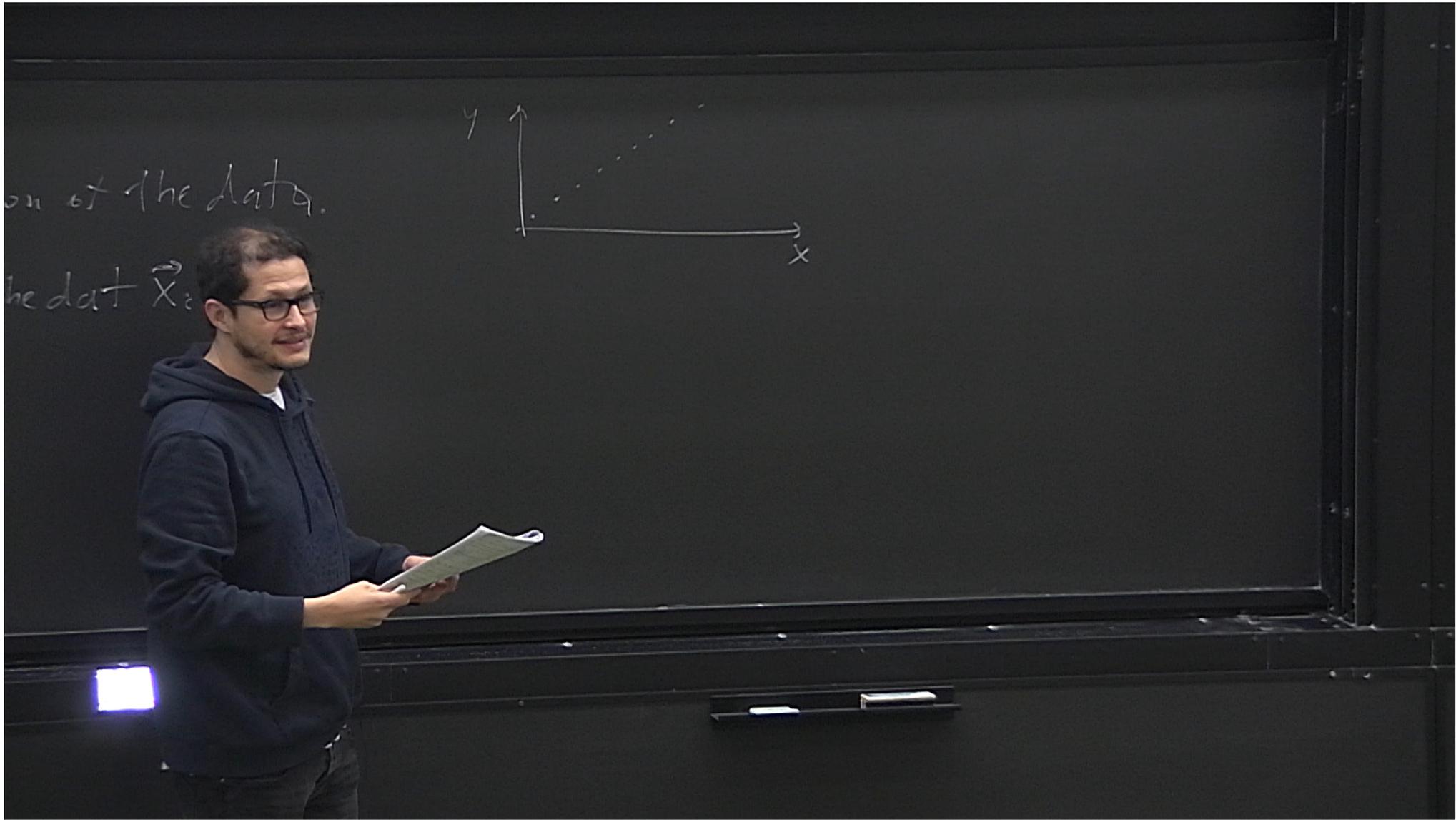
Principal component analysis (PCA)

We want to generate a low-dimensional representation of the data.

$$\vec{X} = \begin{matrix} \vec{X}_1 \\ \vec{X}_2 \\ \vec{X}_3 \\ \vdots \\ \vec{X}_m \end{matrix}$$

How? Perform a linear transformation on the data \vec{X}_i

The principal components



Principal component analysis (PCA)

We want to generate a low-dimensional representation of the data.

How? Perform a linear transformation on the data \vec{X}_i

The principal components

$$\vec{a} = (a_1, \dots, a_n)$$

$$\vec{b} = (b_1, \dots, b_n)$$

$$\sigma_{1k}^2 = \frac{1}{n-1} \vec{a} \vec{b}^T$$

$$S_X = \frac{1}{n-1} X X^T$$

$$\vec{X} =$$

$$\begin{pmatrix} \vec{X}_1 \\ \vec{X}_2 \\ \vec{X}_3 \\ \vdots \\ \vec{X}_m \end{pmatrix}$$

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$m \times n$

on of the data.

the data \vec{X}_i

$$\bar{x} = \frac{1}{n}$$



x diagonal \rightarrow variance of components of \vec{X}

x off diagonal \rightarrow covariances in the variables
correlation among components in \vec{X}

rotation of the data.

on the data \vec{X}

$$S_X = \frac{1}{n-1} X X^T$$

We want a new representation $Y = P X$ such that (S_Y)



x diagonal \rightarrow variance of components of \vec{X}

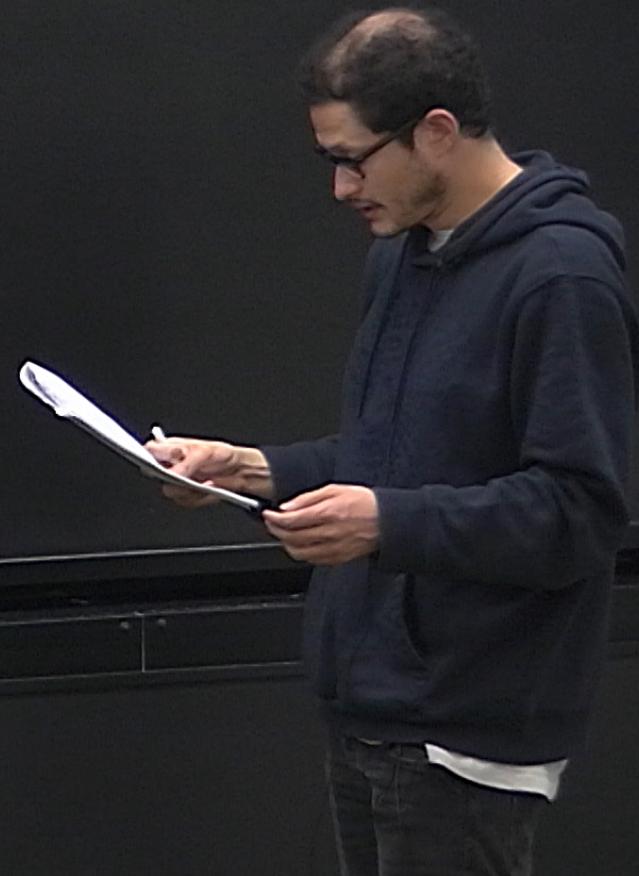
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Idea of PCA

$$Y = PX$$

such that $S_Y = \frac{1}{n-1} Y Y^T$ is diagonal.

P are the principal components of X .



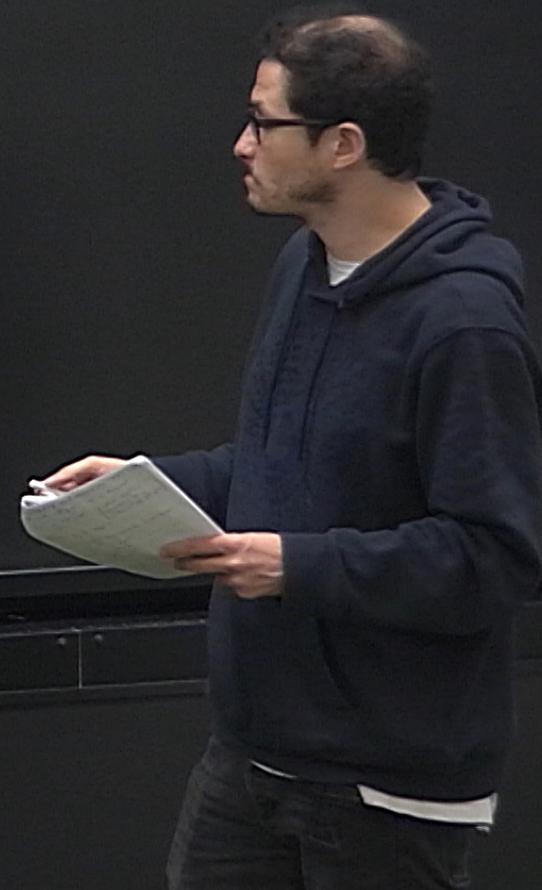
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$$S_Y = \frac{1}{m-1} P X (P X)^T = \frac{P X X^T P^T}{m-1}$$



A)
original representation of the data.



transformation on the data \vec{X}_i

$$S_X = \frac{1}{n-1} X X^T$$

$$\frac{1}{n-1} \vec{a} \vec{b}^T$$

We want a new representation $Y = P X$ such that S_Y

x diagonal \rightarrow variance of components

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$$S_y = \frac{1}{n-1} P X (P X)^T = \frac{P X X^T P^T}{n-1} = P S_x P^T$$

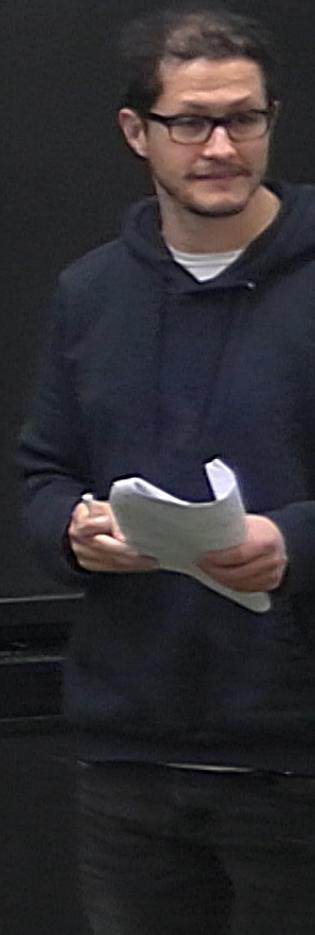
Idea of PCA

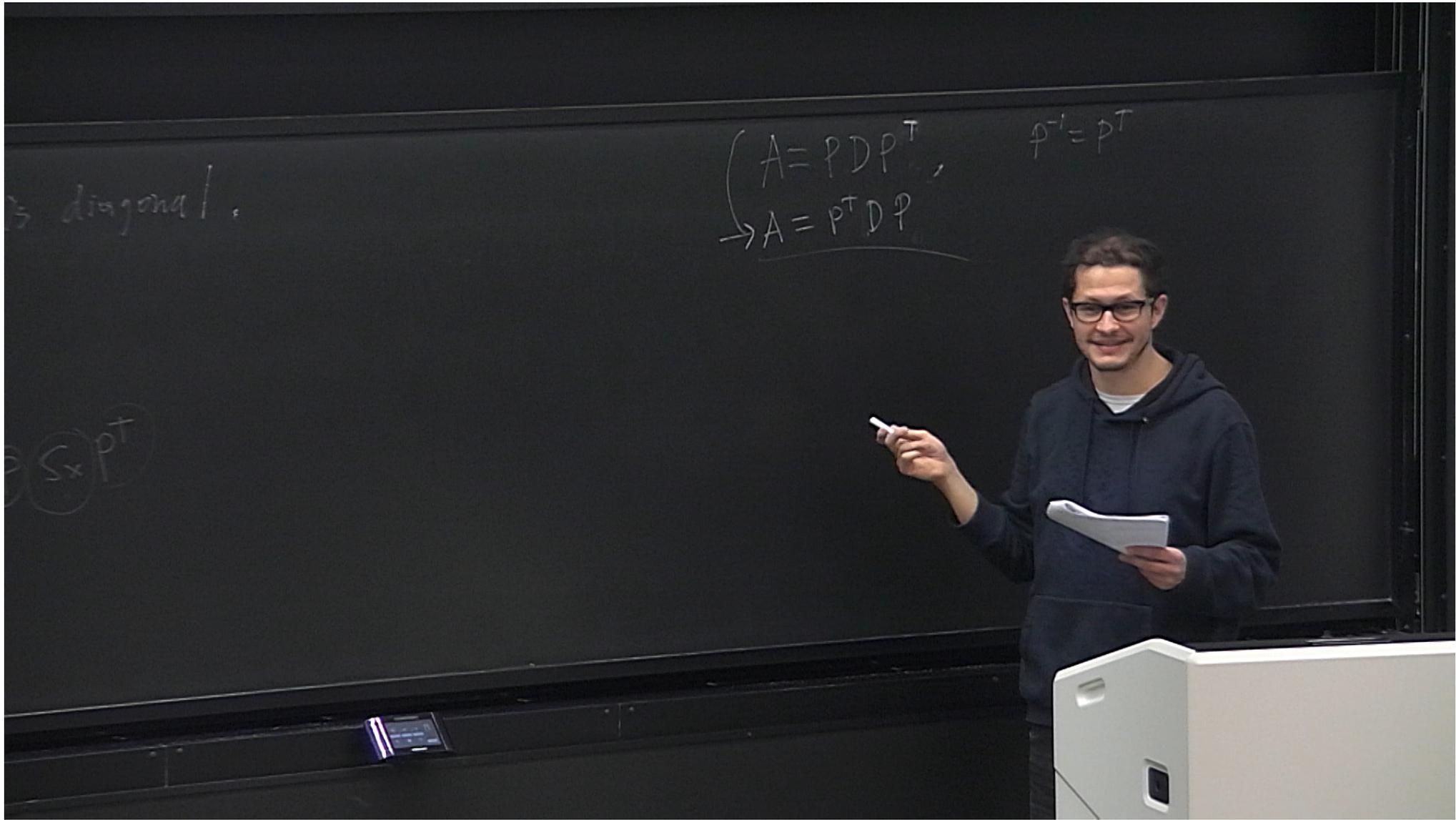
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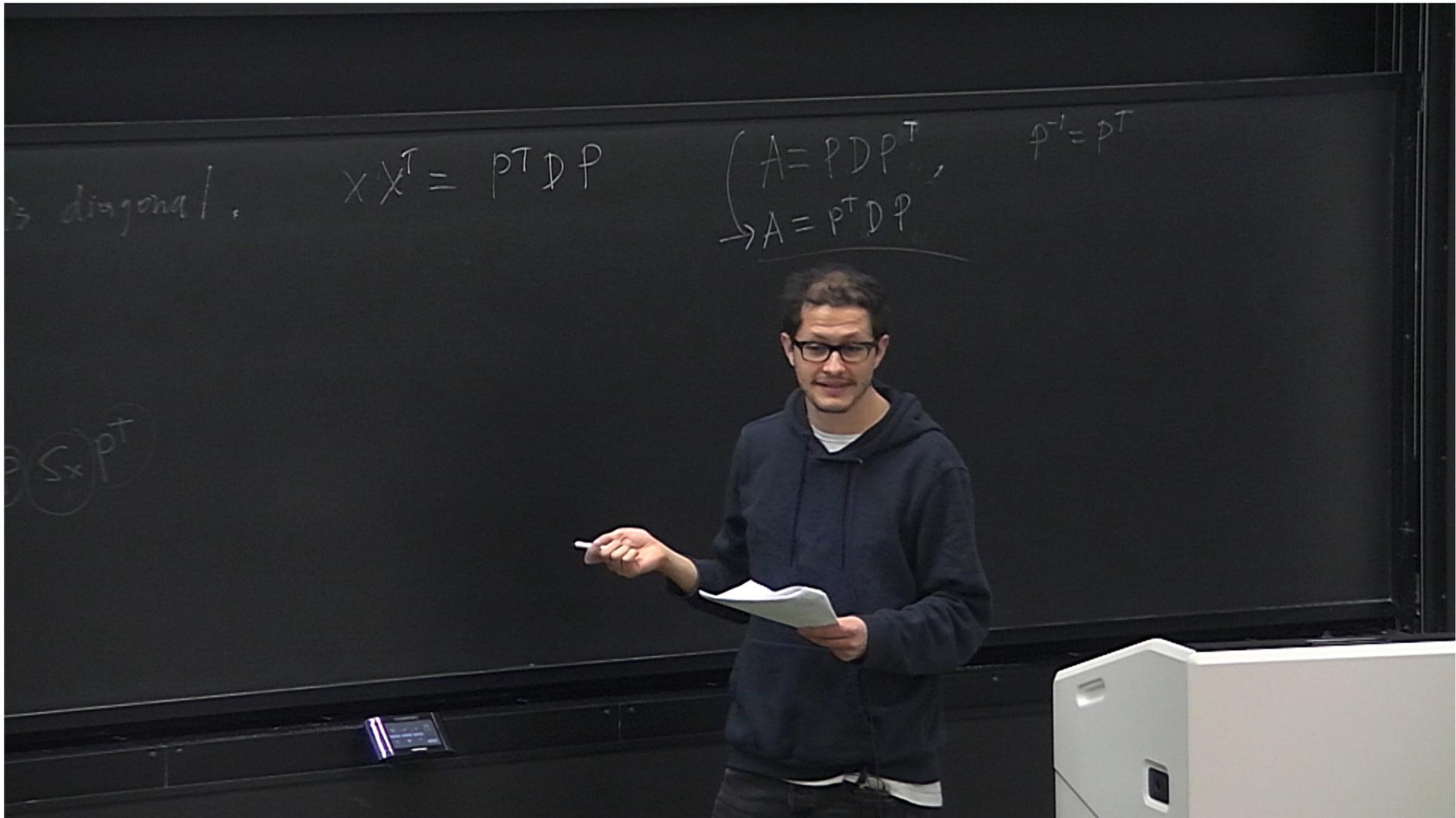
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$$S_y = \frac{1}{n-1} P X (P X)^T = \frac{P X X^T P^T}{n-1} = P S_x P^T$$







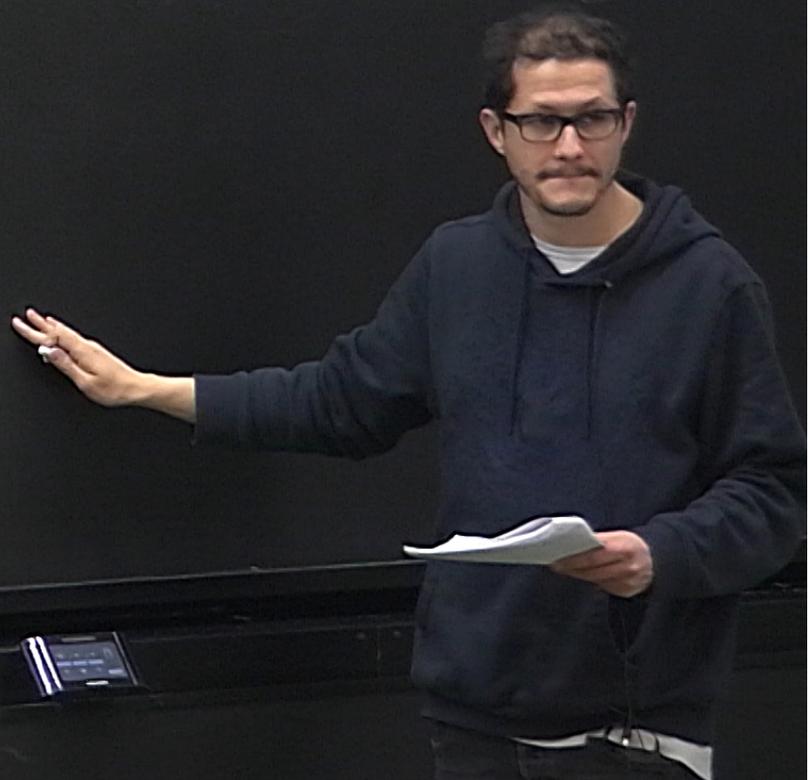
such that $S_y = \frac{1}{n-1} \cdot Y Y^T$ is diagonal.

principal components of X .

$P X (P X)^T = \frac{P X X^T P^T}{n-1} = P S_x P^T = \frac{1}{n-1} D$

$X X^T = P^T D P$

$A = P D P$
 $\rightarrow A = P^T D P$



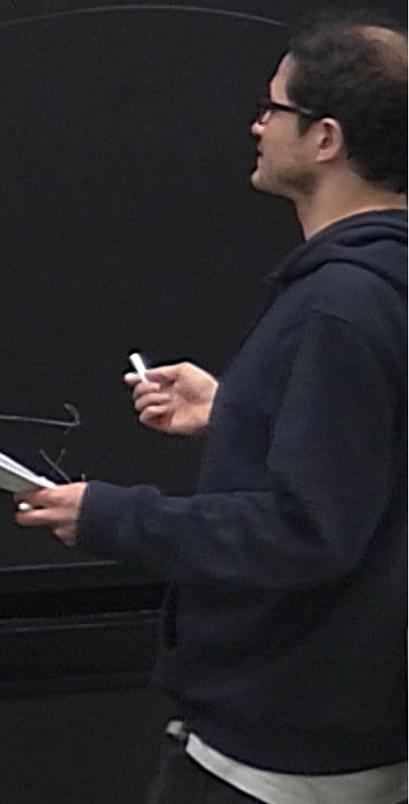
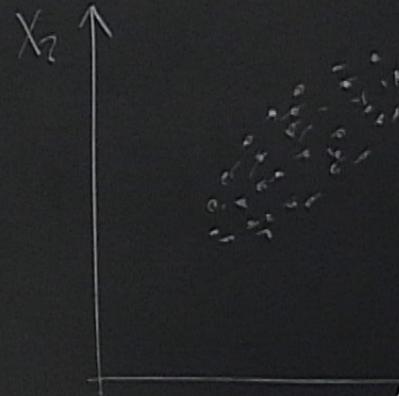
that $S_y = \frac{1}{n-1} Y Y^T$ is diagonal.

$$X X^T = P^T D P$$

$$\begin{aligned} A &= P D P^T \\ \rightarrow A &= P^T D P \end{aligned}$$

components of X .

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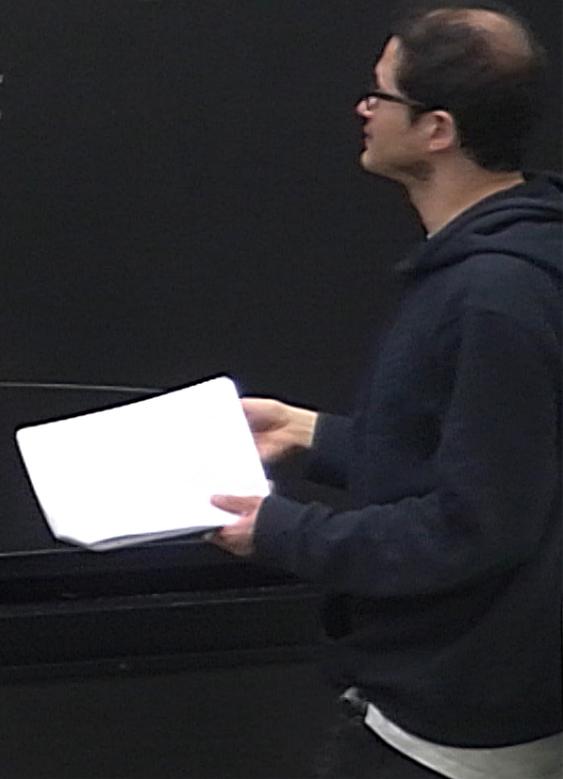
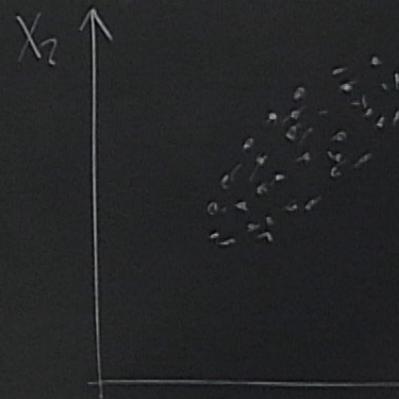
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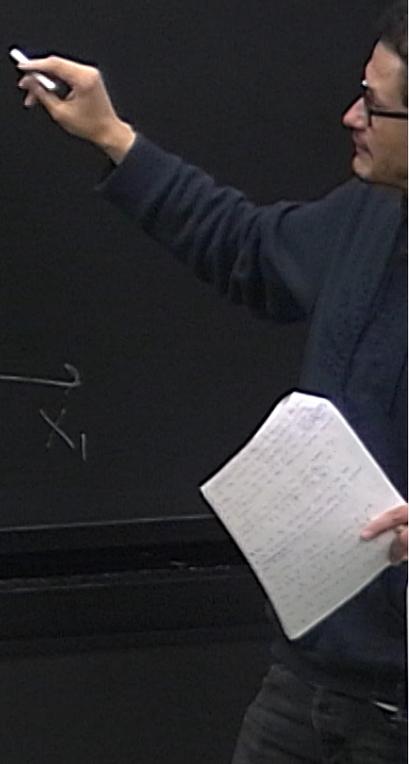
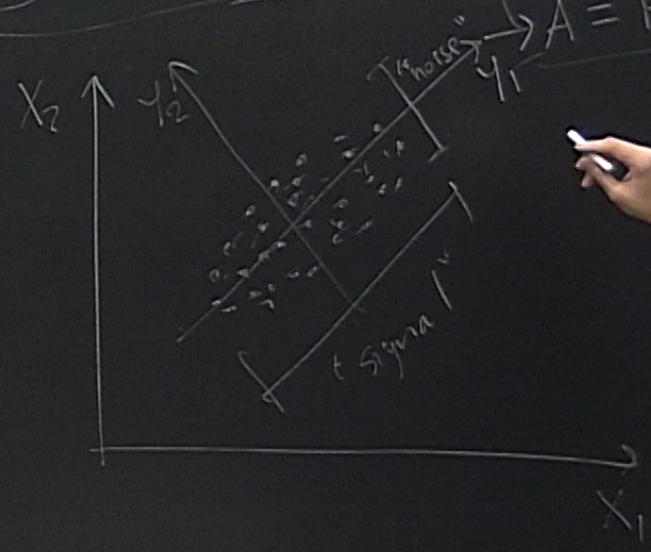
but $S_y = \frac{1}{n-1} Y Y^T$ is diagonal.

$$X X^T = P^T D P$$

$$A = P D P^T$$

components of X .

$$X X^T = \frac{P X X^T P^T}{n-1} = P S_x P^T = \frac{1}{n-1} D$$

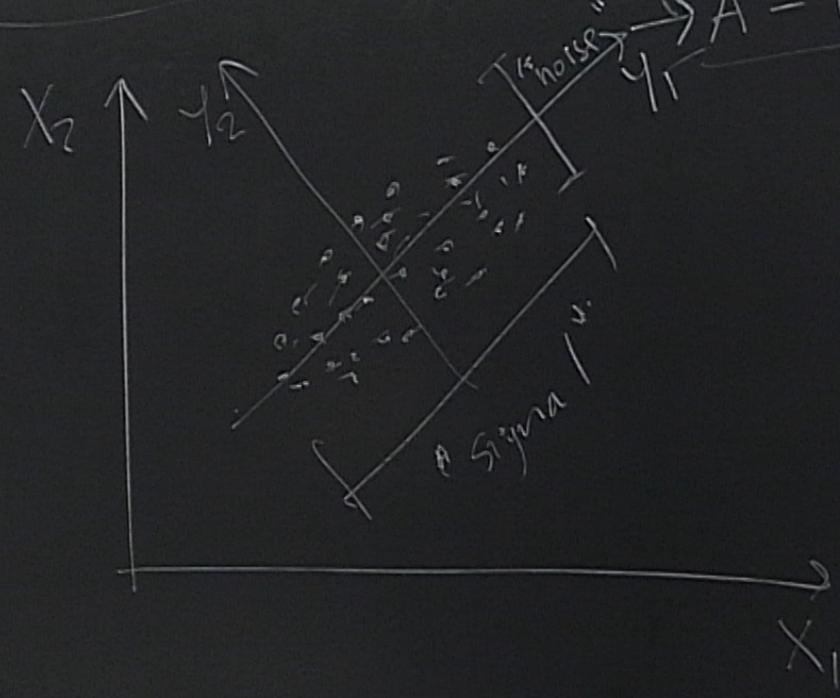


diagonal

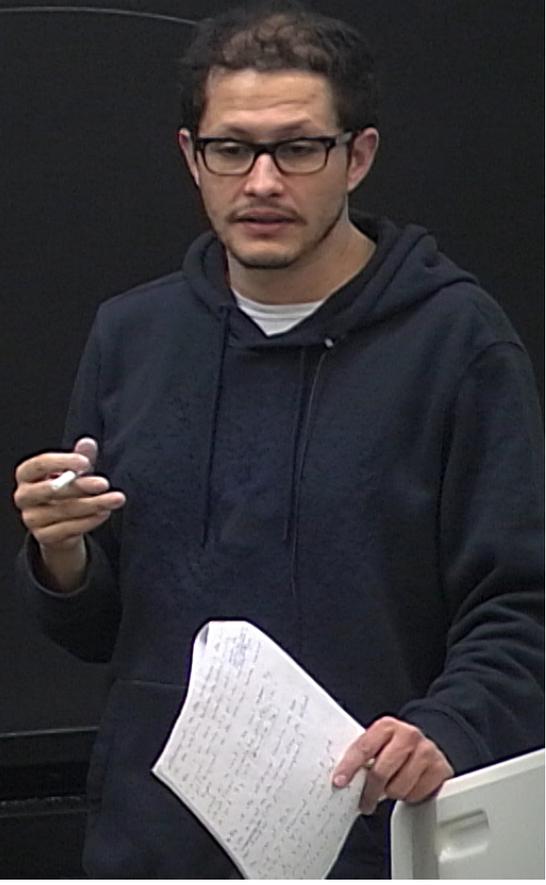
$$X^T X = P^T D P$$

$$A = P D P^T, \quad P^{-1} = P^T$$

$$A = P^T D P$$



$$S_x P^T = \frac{1}{n-1} D$$

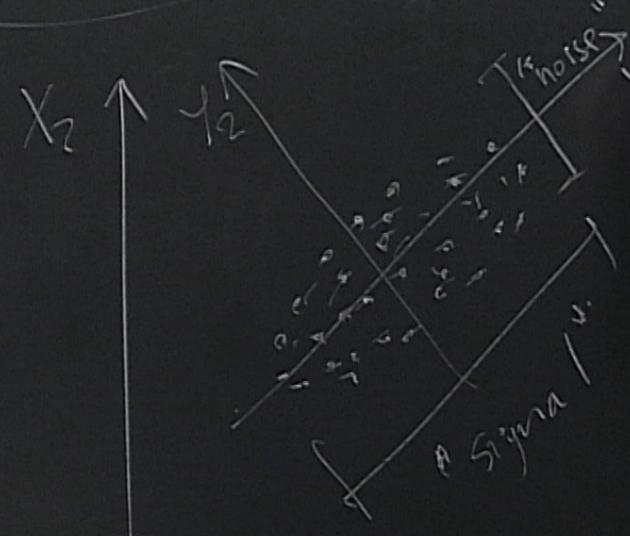


diagonal

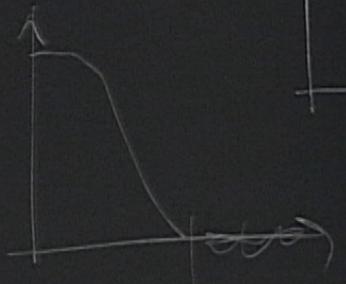
$$X X^T = P^T D P$$

$$A = P D P^T, \quad P^{-1} = P^T$$

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$$S_x P^T = \frac{1}{h-1} D$$



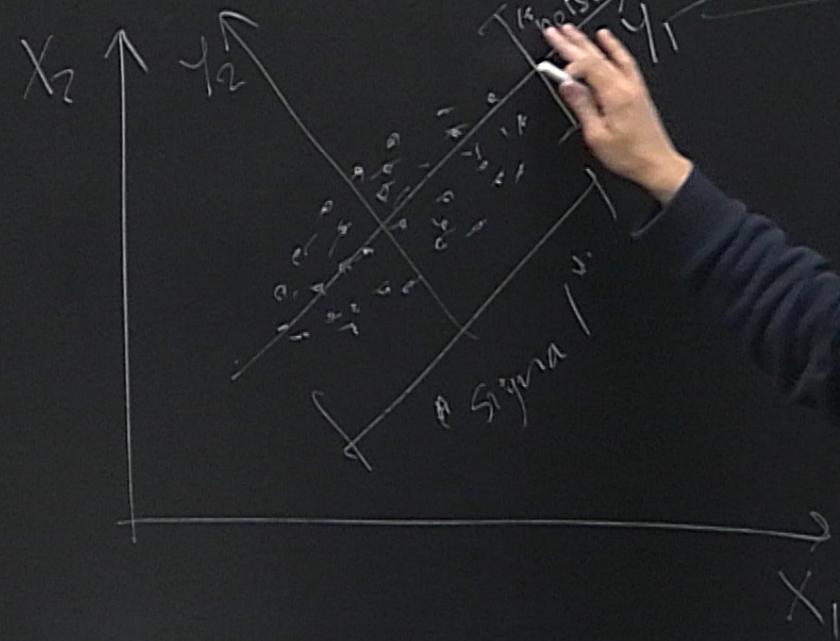
diagonal

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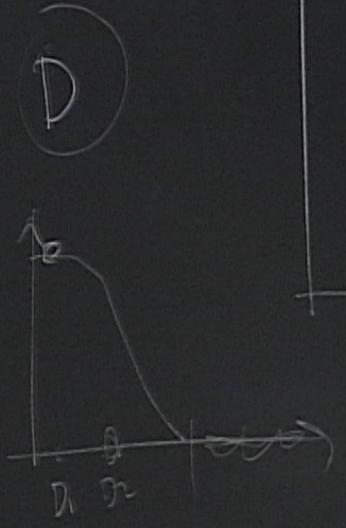
$$A = P D P^T$$

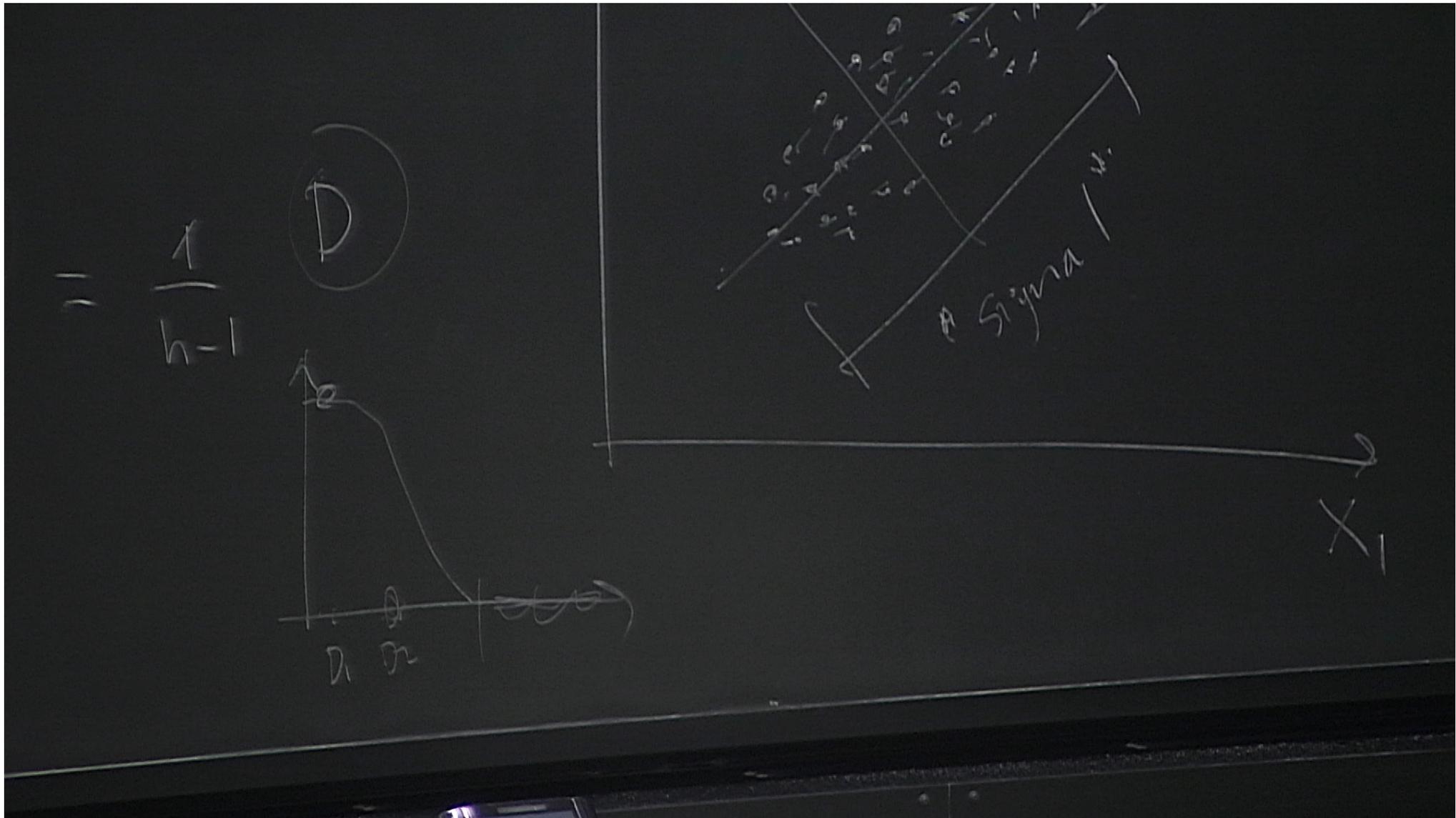
$$P^{-1} = P^T$$

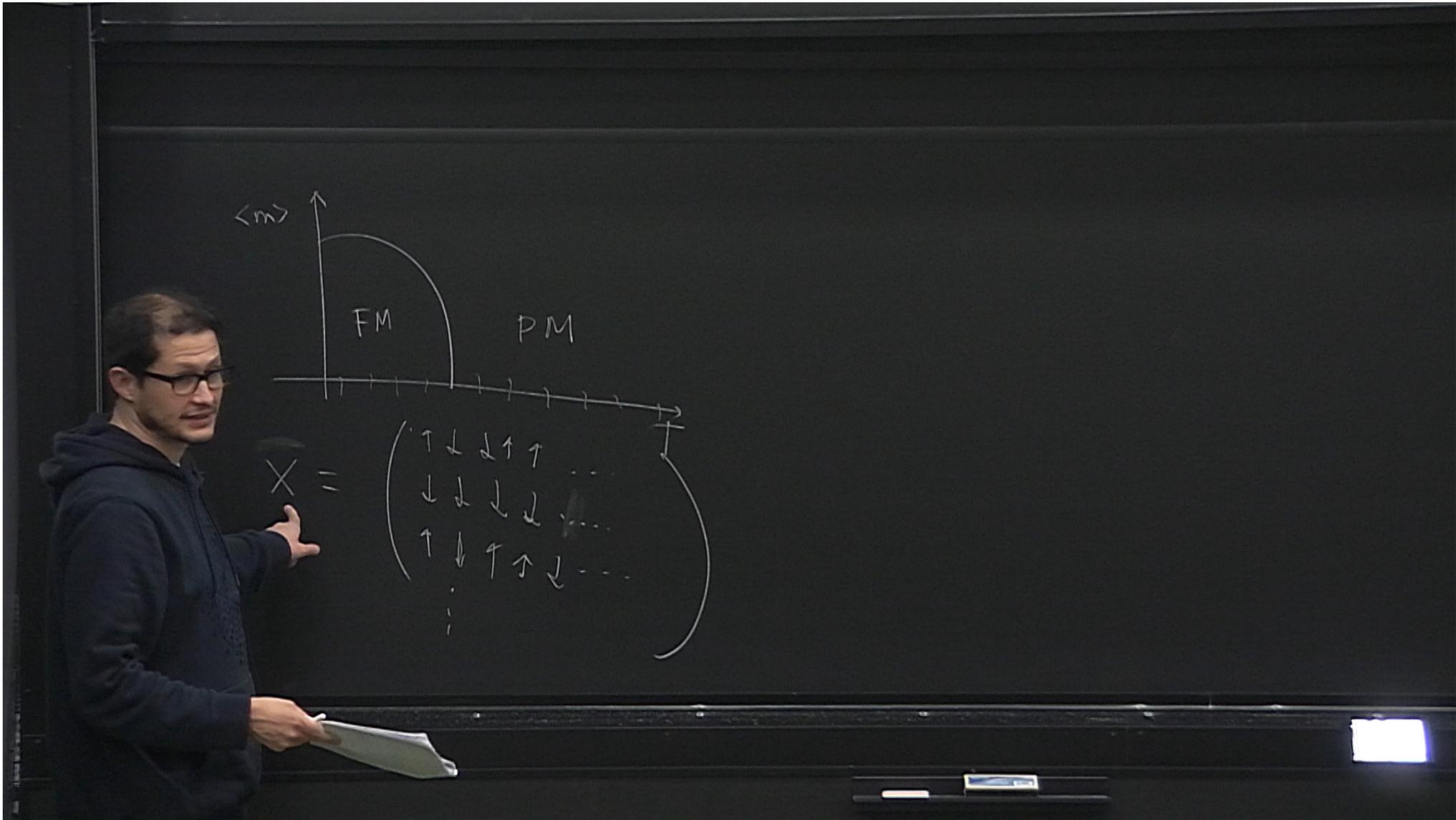
$$A = P^T D P$$



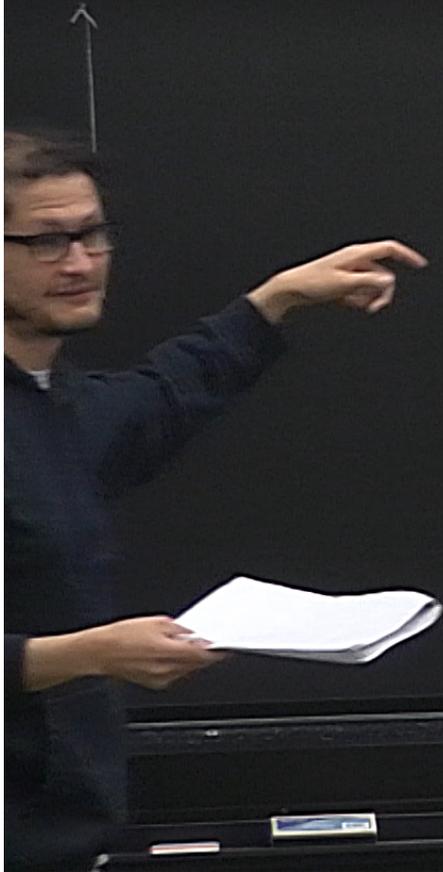
$$S_x P^T = \frac{1}{h-1} D$$



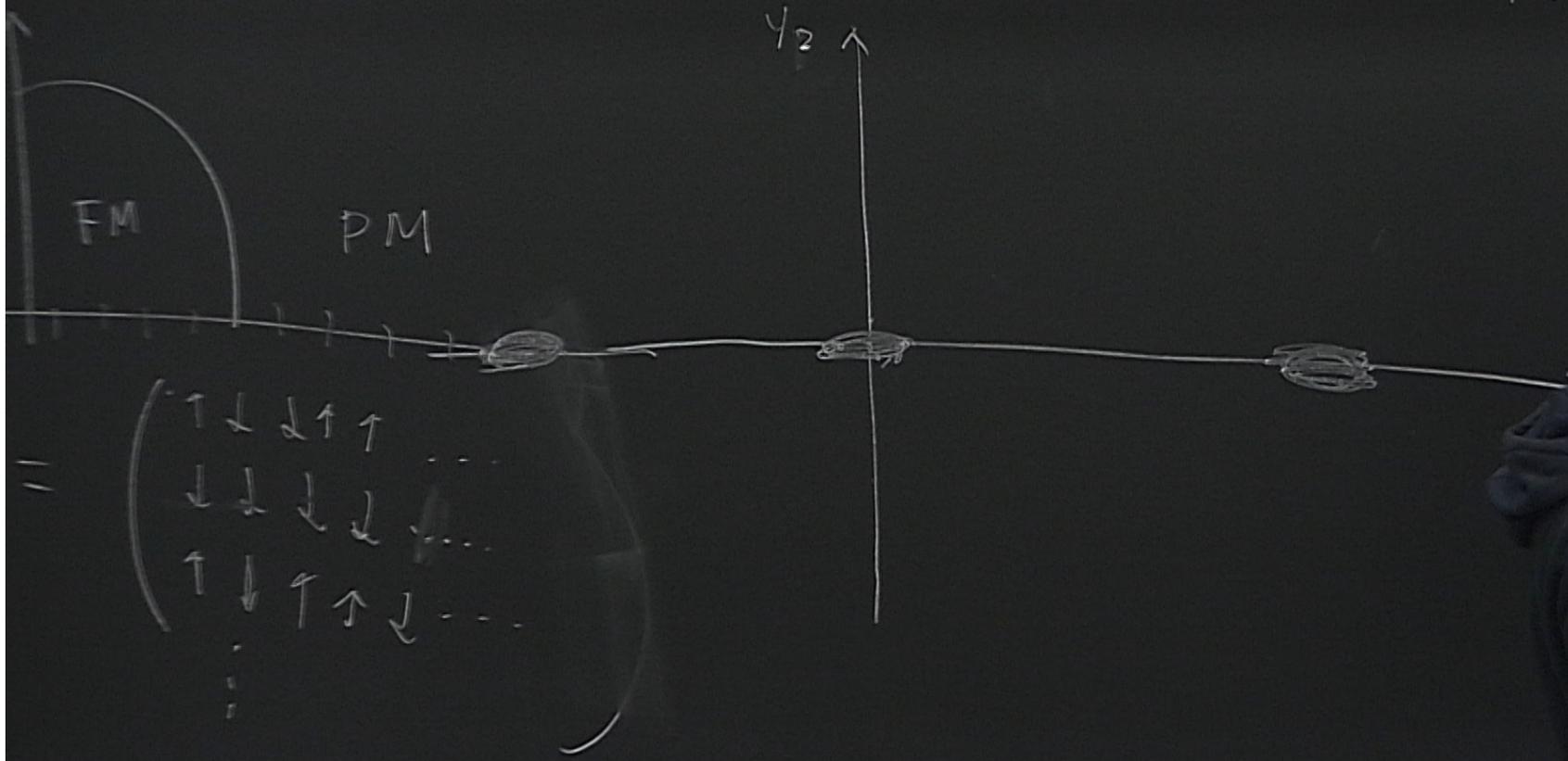




ArXiv: 1606.00318 Lei Wang



ArXiv: 1606.

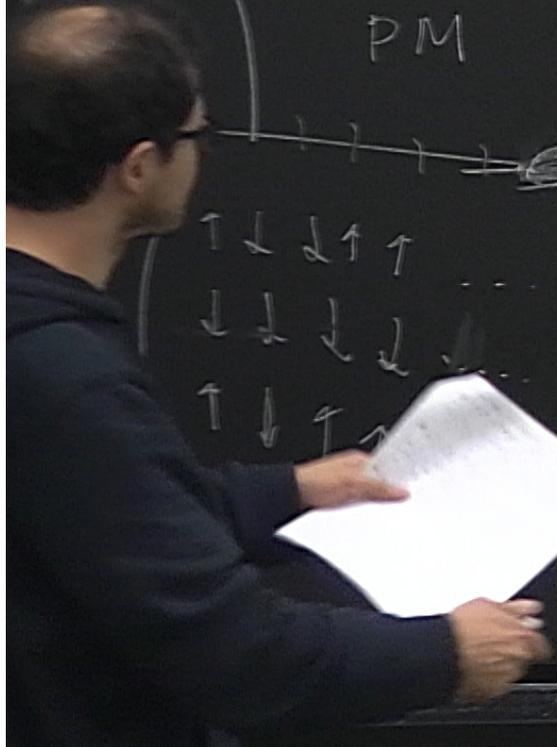


ArXiv: 1606.

PM

y_2 ↑

y_1



ArXiv: 1606.

PM

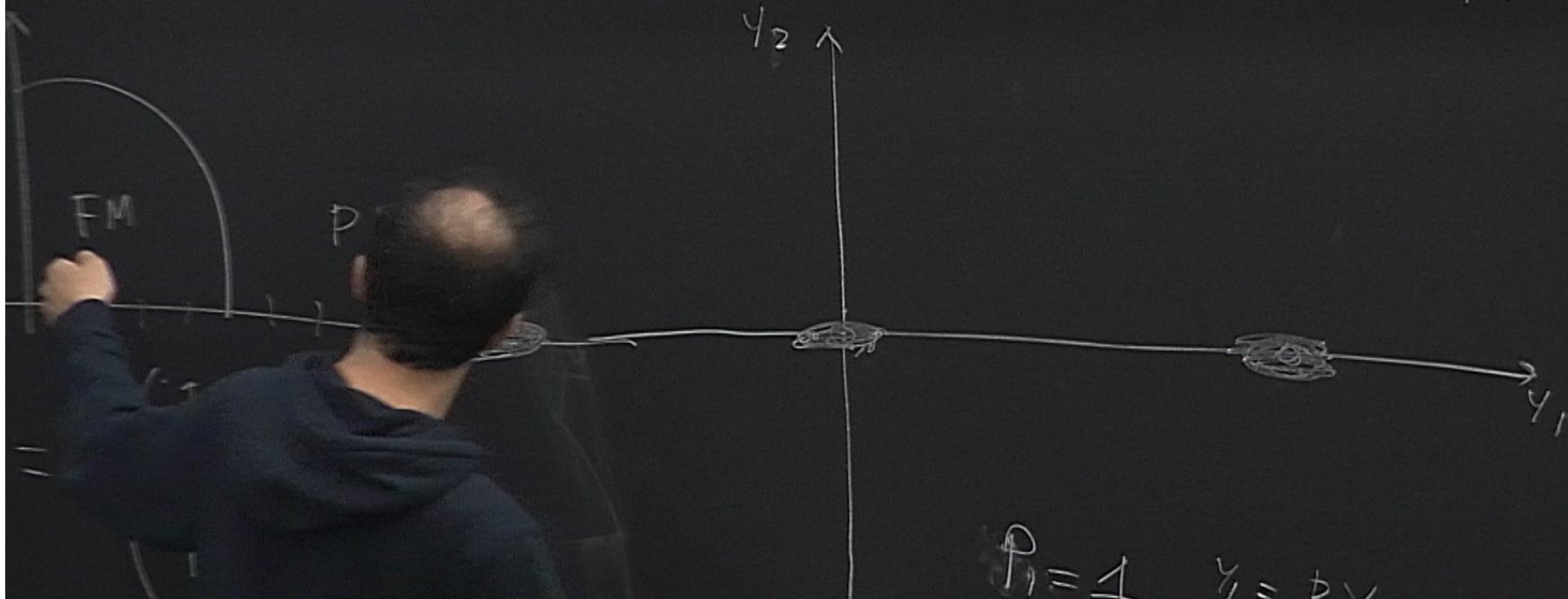
y_2

y_1

$$P_i = \frac{1}{N}$$

$$P_i X = \frac{1}{N} \sum_c \sigma_c$$

ArXiv: 1606.



$$p_i = \frac{1}{N} \quad y_i = p_i X = \frac{1}{N} \sum_c \sigma_c$$

ArXiv: 1606.00318 Lei Wang

D



$$P_i = \frac{1}{N} \quad y_i = P_i$$

