

Title: PSI 2017/2018 - Cosmology - Lecture 14

Date: Apr 26, 2018 10:15 AM

URL: <http://pirsa.org/18040026>

Abstract:

TIME DEPENDENT SHO

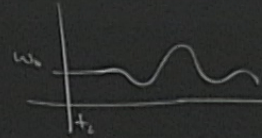
$$\hat{H}(t) = \frac{1}{2} p^2 + \frac{1}{2} \omega(t)^2 x^2$$

As $t \rightarrow t_0$ $\omega(t) \rightarrow \omega_0$

$| \psi(t) \rangle \rightarrow | 0 \rangle$

$$\hat{x}_H(t) = u(t) a + u(t)^* a^\dagger$$

$$\hat{p}_H(t) = \dot{u}(t) a + \dot{u}(t)^* a^\dagger$$



$$\begin{aligned}
 | a \rangle &= | a(t_0) \rangle = \sqrt{\frac{\omega_0}{2}} \left(\hat{x}_S + i \frac{1}{\omega_0} \hat{p}_S \right) \\
 &\neq | a_S(t) \rangle = \sqrt{\frac{\omega(t)}{2}} \left(\hat{x}_S + i \frac{1}{\omega(t)} \hat{p}_S \right) \\
 &\neq | a_H(t) \rangle = U(t, t_0)^\dagger | a_S(t) \rangle U(t, t_0)
 \end{aligned}$$

TIME DEPENDENT SHG

$$\hat{H}(t) = \frac{1}{2} p^2 + \frac{1}{2} \omega(t)^2 x^2$$

As $t \rightarrow t_0$ $\omega(t) \rightarrow \omega_0$

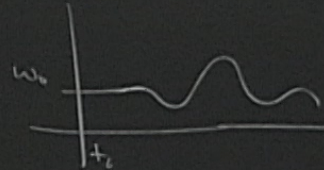
$|\psi(t)\rangle \rightarrow |0\rangle$

$$\hat{X}_H(t) = u(t)a + u(t)^* a^\dagger$$

$$\hat{p}_H(t) = \dot{u}(t)a + \dot{u}(t)^* a^\dagger$$

WHERE $\ddot{u}(t) = -\omega(t)^2 u(t)$

$$u(t) \rightarrow \frac{1}{(2\omega_0)^{1/2}} e^{-i\omega_0 t}$$



$$a = a(t_0) = \frac{1}{\sqrt{2}} \left(\hat{X}_S + i \hat{p}_S \right)$$

$$\neq a_S(t) = \frac{1}{\sqrt{2}} \left(\hat{X}_S + i \hat{p}_S \right)$$

$$\neq a_H(t) = \dots$$

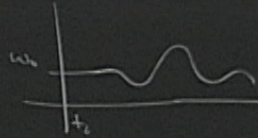
$$\begin{aligned}
\langle x^2(t) \rangle &= \langle \psi(t) | \hat{x}_S^2 | \psi(t) \rangle \\
&= \langle 0 | \hat{x}_H(t)^2 | 0 \rangle \\
&= \langle 0 | (u(t)a + u^*(t)a^\dagger)(u(t)a + u^*(t)a^\dagger) | 0 \rangle \\
&= u(t)u(t)^* \underbrace{\langle 0 | a a^\dagger | 0 \rangle}_{=1} \\
&= |u(t)|^2
\end{aligned}$$

TIME DEPENDENT SHC

$$\hat{H}(t) = \frac{1}{2} p^2 + \frac{1}{2} u(t)^2 x^2$$

As $t \rightarrow t_0$ $u(t) \rightarrow u_0$

$|u(t)\rangle \rightarrow |0\rangle$



$$\begin{aligned} \hat{x}_H(t) &= u(t)a + u(t)^* a^\dagger \\ \hat{p}_H(t) &= \dot{u}(t)a + \dot{u}(t)^* a^\dagger \end{aligned}$$

LAGRANGE $\ddot{u}(t) = -\omega(t)^2 u(t)$

$$u(t) \rightarrow \frac{1}{(2u_0)^{1/2}} e^{-i\omega_0 t}$$

$$\begin{aligned} |a\rangle &= |a(t_0)\rangle = \sqrt{\frac{u_0}{2}} (\hat{x}_S + i u_0 \hat{p}_S) \\ &\neq |a_S(t)\rangle = \sqrt{\frac{u(t)}{2}} (\hat{x}_S + i u(t) \hat{p}_S) \\ &\neq |a_H(t)\rangle = (u(t/t_0))^{1/2} |a_S(t/t_0)\rangle \end{aligned}$$

$$\langle x^2(t) \rangle = \langle$$

$$\begin{aligned}
\langle X^2(t) \rangle &= \langle \psi(t) | \hat{x}_S^2 | \psi(t) \rangle \\
&= \langle 0 | \hat{x}_H(t)^2 | 0 \rangle \\
&= \langle 0 | (u(t)a + u^*(t)a^\dagger)(u(t)a + u^*(t)a^\dagger) | 0 \rangle \quad [a, a^\dagger] = 1 \\
&= u(t)u^*(t) \langle 0 | \underbrace{aa^\dagger}_{=1} | 0 \rangle \\
&= |u(t)|^2
\end{aligned}$$

CANONICAL COMMUTATOR:

$$\hat{i} = [\hat{x}_H(t), \hat{p}_H(t)]$$

$$= u(t) \dot{u}(t) - u(t) \dot{u}(t)$$

CANONICAL COMMUTATOR

$$\begin{aligned} \hat{i} &= [\hat{x}_H(t), \hat{p}_H(t)] \\ &= \boxed{u(t) \dot{u}(t)^* - u(t)^* \dot{u}(t)} \end{aligned}$$

$$\frac{d}{dt} > 0$$

CANONICAL COMMUTATOR:

$$\hat{i} = [\hat{x}_H(t), \hat{p}_H(t)]$$

$$i = u(t) \dot{u}(t)^{\dagger} - u(t)^{\vee} \dot{u}(t)$$

$$\begin{pmatrix} \hat{q}_H(t) \\ \hat{p}_H(t) \end{pmatrix} = \begin{pmatrix} u(t) & u(t)^{\dagger} \\ \dot{u}(t) & \dot{u}(t)^{\vee} \end{pmatrix} \begin{pmatrix} a \\ a^{\dagger} \end{pmatrix}$$

$$\begin{pmatrix} \hat{Q}_H(t) \\ \hat{P}_H(t) \end{pmatrix} = \begin{pmatrix} u(t) & u(t)^* \\ \dot{u}(t) & \dot{u}(t)^* \end{pmatrix} \begin{pmatrix} a \\ a^\dagger \end{pmatrix}$$

$$\textcircled{a} | \psi(t_0) \rangle = 0$$

↳

INVERT
⇒

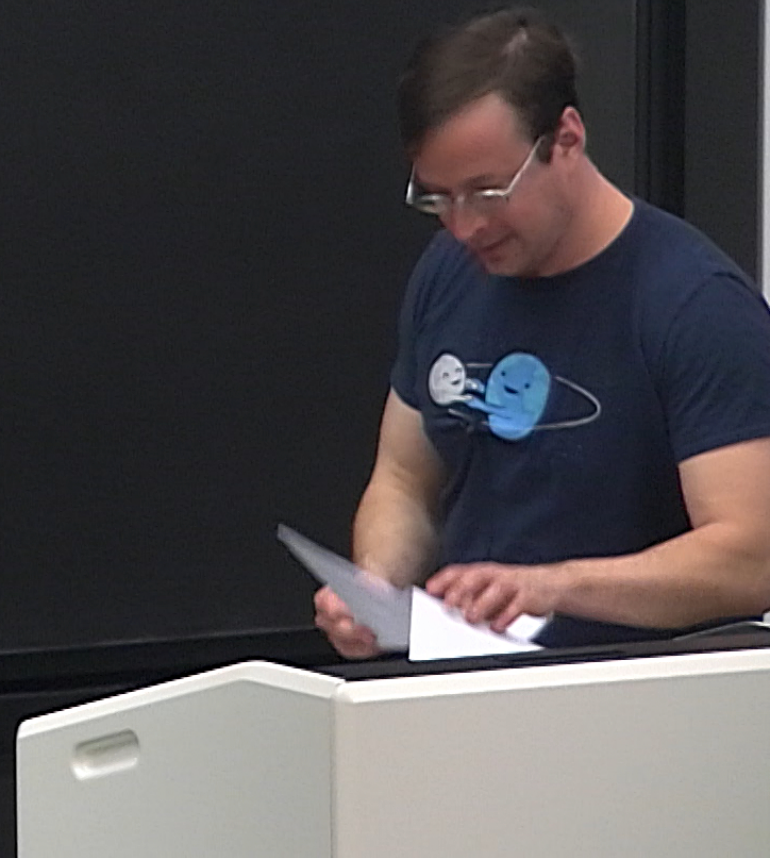
$$a = \dot{u}(t)^* \hat{X}_H(t) + u(t)^* \hat{P}_H(t)$$

$$\begin{aligned} 0 &= a | \psi(t_0) \rangle \\ &= \left(\dot{u}(t)^* \hat{X}_H(t) + u(t)^* \hat{P}_H(t) \right) | \psi(t_0) \rangle \\ &= \cancel{U(t, t_0)} + \left(\dot{u}(t)^* \hat{X}_S + u(t)^* \hat{P}_S \right) \underbrace{U(t, t_0)}_{= | \psi(t) \rangle} | \psi(t_0) \rangle \end{aligned}$$

$$\textcircled{a} \langle \psi(t_0) | \psi(t_0) \rangle = 1$$

$$\left[\dot{u}(t)^* x + u(t)^* \left(-i \frac{\partial}{\partial x} \right) \right] \psi(t, x) = 0$$

$$\begin{aligned} & \langle \psi(t_1) | \psi(t_0) \rangle \\ &= \langle \hat{P}_S \psi(t_1, t_0) | \psi(t_0) \rangle \\ &= \langle \psi(t_1) | \psi(t_0) \rangle \end{aligned}$$



$$\textcircled{a} \psi(t_0) = 0$$

$$\left[\dot{u}(t)^* x + u(t)^* \left(-i \frac{\partial}{\partial x} \right) \right] \psi(t, x) = 0$$

$$\Rightarrow \psi(x, t) = A(t) \exp\left(\frac{i \dot{u}(t)^*}{2 u(t)^*} x^2 \right)$$

$$i \frac{\partial}{\partial t} \psi = \left(-\frac{1}{2} \frac{\partial^2}{\partial x^2} + u(t)^2 x^2 \right) \psi$$

=

$$\begin{aligned} & \psi(t) | \psi(t) \rangle \\ & \int \psi(t, x) \psi(t, x) | \psi(t) \rangle \\ & = | \psi(t) \rangle \end{aligned}$$

$$\left[\dot{u}(t)^* x + u(t)^* \left(-i \frac{\partial}{\partial x} \right) \right] \psi(t, x) = 0$$

$$\Rightarrow \psi(x, t) = A(t) \exp\left(\frac{i \dot{u}(t)^*}{2 u(t)^*} x^2 \right) \quad i \frac{\partial}{\partial t} \psi = \left(-\frac{1}{2} \frac{\partial^2}{\partial x^2} + u(t)^2 x^2 \right) \psi$$

$$= \frac{1}{(2\pi)^{1/4} (u(t)^*)^{1/2}} \exp\left(\frac{i \dot{u}(t)^*}{2 u(t)^*} x^2 \right)$$

$$\left[\dot{u}(t)^* x + u(t)^* \left(-i \frac{\partial}{\partial x} \right) \right] \psi(t, x) = 0$$

$$\Rightarrow \psi(x, t) = A(t) \exp\left(\frac{i \dot{u}(t)^*}{2 u(t)^*} x^2 \right) \quad i \frac{\partial}{\partial t} \psi = \left(-\frac{1}{2} \frac{\partial^2}{\partial x^2} + u(t)^2 x^2 \right) \psi$$

$$= \frac{1}{(2\pi)^{1/4} (u(t)^*)^{1/2}} \exp\left(\frac{i \dot{u}(t)^*}{2 u(t)^*} x^2 \right)$$

$$= \frac{1}{(2\pi)^{1/4} (u(t))^{1/4}} \exp\left(\frac{i}{2} \frac{\dot{u}(t)}{u(t)^3} x^2\right)$$

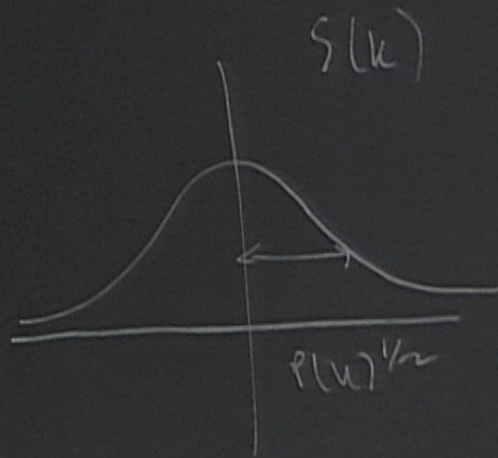
$$\psi(x) = \exp((A+iB)x^2)$$

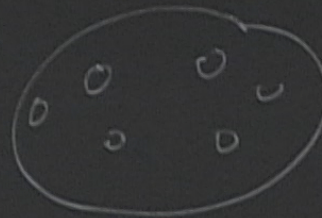
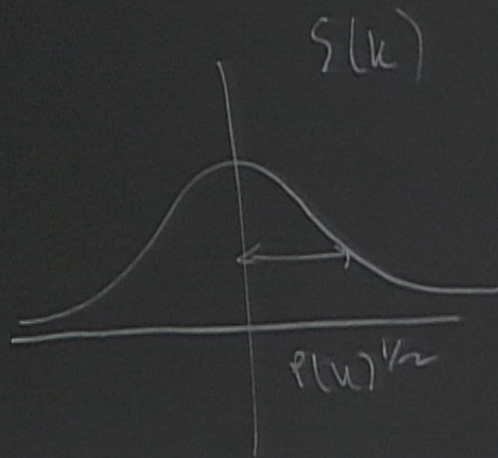
$$|\psi|^2 = \exp(2Ax^2)$$

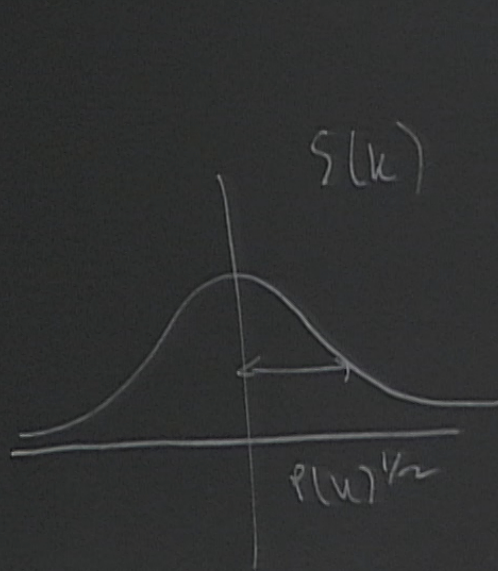
$$= \frac{1}{(2\pi)^{1/4} (u(t))^{1/2}} \exp\left(\frac{i \dot{u}(t)}{2 u(t)^2} x^2\right)$$

$$\psi(x) = \exp((A+iB)x^2)$$

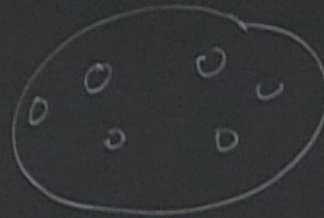
$$|\psi|^2 = \exp(2Ax^2) \quad \text{GAUSSIAN!}$$







$$e^{-x^2}$$



MASSLESS SCALAR FIELD IN NONDYNAMICAL DE SITTER

$$H = \text{CONSTANT}$$

$$ds^2 = -dt^2 + e^{2Ht} dx^2 \quad (-\infty < t < \infty)$$

$$ds^2 = \frac{1}{(H\tau)^2} (-d\tau^2 + dx^2) \quad (-\infty < \tau < 0)$$

MASSLESS SCALAR FIELD IN NONDYNAMICAL DE SITTER

$$H = \text{CONSTANT}$$

$$ds^2 = -dt^2 + e^{2Ht} dx^2 \quad (-\infty < t < \infty)$$

✓ $ds^2 = \frac{1}{(H\tau)^2} (-d\tau^2 + dx^2) \quad (-\infty < \tau < 0)$

$$S = \int d^4x \sqrt{g} \left(-\frac{1}{2} g^{\mu\nu} (\partial_\mu \phi) (\partial_\nu \phi) \right)$$

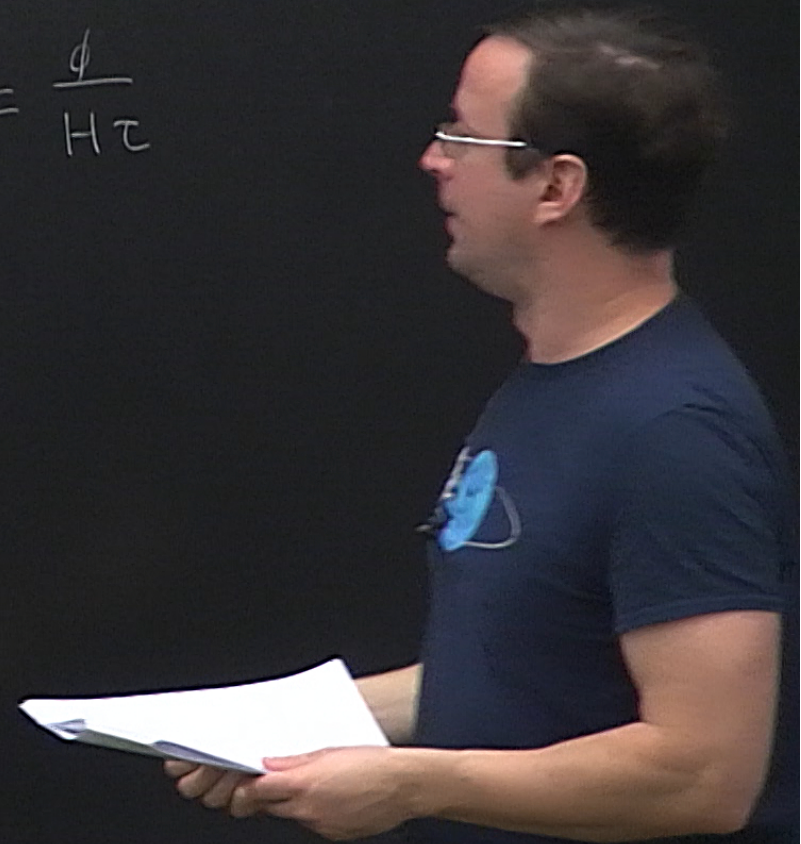
$$S = \int d\tau \frac{d^3k}{(2\pi)^3} \frac{1}{(V\tau)^2} \left(\frac{1}{2} \frac{\partial \phi_k^+}{\partial \tau} \frac{\partial \phi_k}{\partial \tau} - \frac{k^2}{2} \phi_k^+ \phi_k \right)$$



$$S = \int d\tau \frac{d^3k}{(2\pi)^3} \frac{1}{(V\tau)^2} \left[\frac{1}{2} \frac{\partial \phi_k^+}{\partial \tau} \frac{\partial \phi_k}{\partial \tau} - \frac{k^2}{2} \phi_k^+ \phi_k \right]$$

CANONICALLY NORMALIZE: $\psi = \frac{\phi}{\sqrt{H\tau}}$

$$S =$$



$$S = \int d\tau \frac{d^3k}{(2\pi)^3} \frac{1}{(H\tau)^2} \left[\frac{1}{2} \frac{\partial \psi_k^+}{\partial \tau} \frac{\partial \psi_k}{\partial \tau} - \frac{k^2}{2} \psi_k^+ \psi_k \right]$$

CANONICALLY NORMALIZE: $\psi = \frac{\phi}{H\tau}$

$$S = \int d\tau \frac{d^3k}{(2\pi)^3} \frac{1}{(H\tau)^2} \left[\frac{1}{2} \left(H\tau \frac{\partial \psi_k^+}{\partial \tau} + H\psi_k^+ \right) \left(H\tau \frac{\partial \psi_k}{\partial \tau} + H\psi_k \right) - \frac{k^2}{2} (H\tau)^2 \psi_k^+ \psi_k \right]$$

$$= \int d\tau \frac{d^3k}{(2\pi)^3} \left[\frac{1}{2} \left(\frac{\partial \psi_k^+}{\partial \tau} \right)^+ \left(\frac{\partial \psi_k}{\partial \tau} \right) + \frac{1}{2\tau} \left(\frac{\partial \psi_k^+}{\partial \tau} \psi_k + \psi_k^+ \frac{\partial \psi_k}{\partial \tau} \right) - \frac{1}{2} \left(k^2 - \frac{1}{\tau} \right) \psi_k^+ \psi_k \right]$$

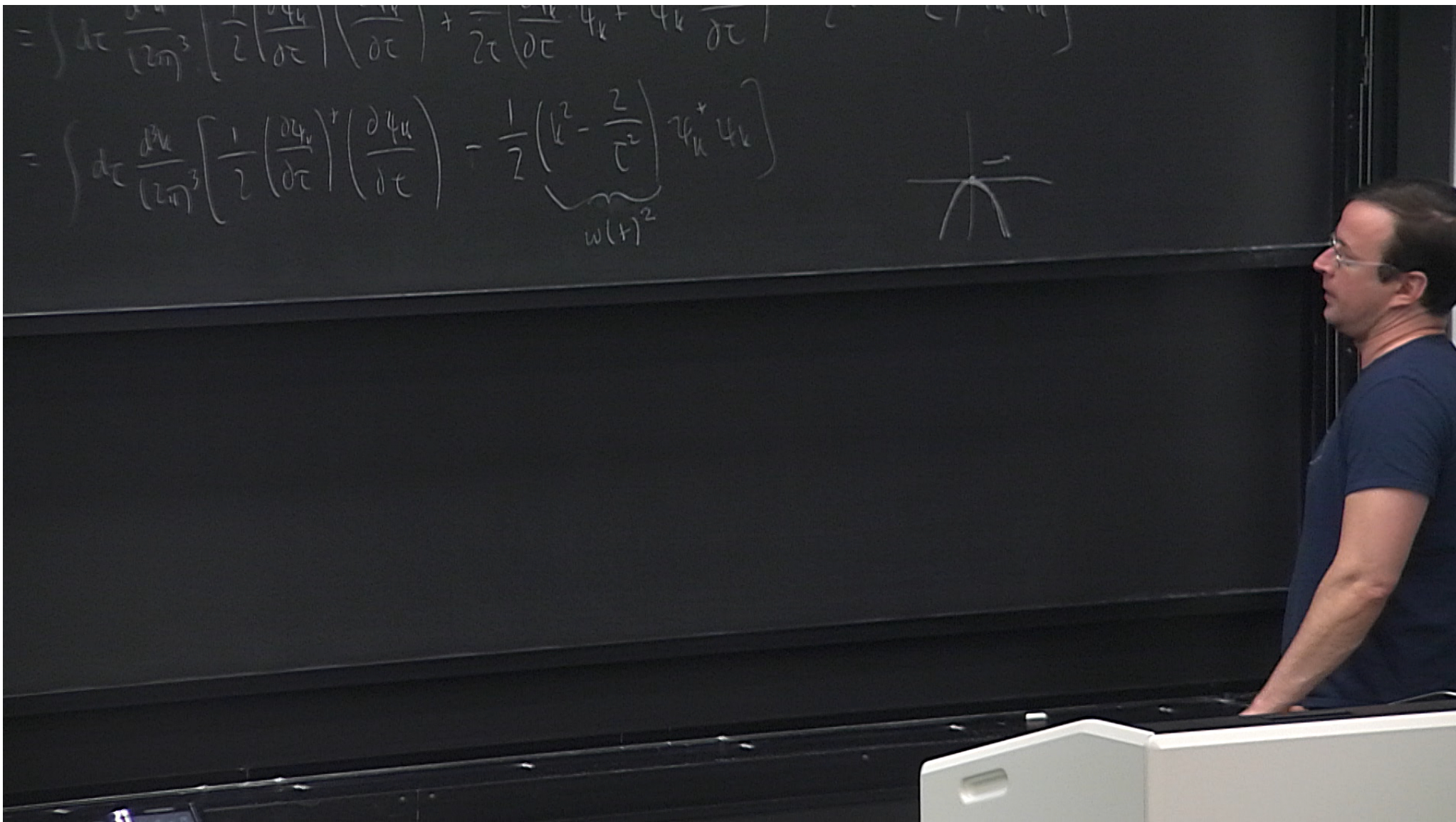
$$S = \int d\tau \frac{d^3k}{(2\pi)^3} \frac{1}{(1/\tau)^2} \left[\frac{1}{2} \frac{\partial \phi_k^*}{\partial \tau} \frac{\partial \phi_k}{\partial \tau} - \frac{k^2}{2} \phi_k^* \phi_k \right]$$

CANONICALLY NORMALIZE: $\psi = \frac{\phi}{H\tau}$

$$S = \int d\tau \frac{d^3k}{(2\pi)^3} \frac{1}{(H\tau)^2} \left[\frac{1}{2} \left(H\tau \frac{\partial \psi_k^*}{\partial \tau} + H\psi_k^* \right) \left(H\tau \frac{\partial \psi_k}{\partial \tau} + H\psi_k \right) - \frac{k^2}{2} (1/\tau)^2 \psi_k^* \psi_k \right]$$

$$= \int d\tau \frac{d^3k}{(2\pi)^3} \left[\frac{1}{2} \left(\frac{\partial \psi_k^*}{\partial \tau} \right)^* \left(\frac{\partial \psi_k}{\partial \tau} \right) + \frac{1}{2\tau} \left(\frac{\partial \psi_k^*}{\partial \tau} \psi_k + \psi_k^* \frac{\partial \psi_k}{\partial \tau} \right) - \frac{1}{2} \left(k^2 - \frac{1}{\tau^2} \right) \psi_k^* \psi_k \right]$$

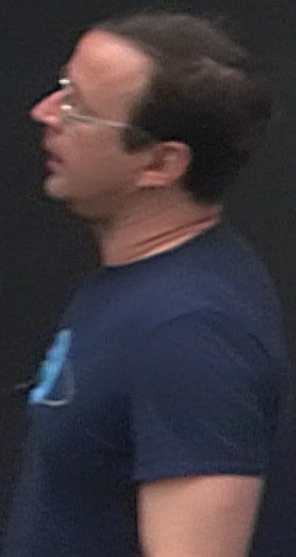
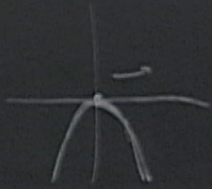
$$= \int d\tau \frac{d^3k}{(2\pi)^3} \left[\frac{1}{2} \left(\frac{\partial \psi_k^*}{\partial \tau} \right)^* \left(\frac{\partial \psi_k}{\partial \tau} \right) - \frac{1}{2} \underbrace{\left(k^2 - \frac{2}{\tau^2} \right)}_{\omega(k)^2} \psi_k^* \psi_k \right]$$



$$= \int d\tau \frac{d^3k}{(2\pi)^3} \left[\frac{1}{2} \left(\frac{\partial \phi_k}{\partial \tau} \right)^* \left(\frac{\partial \phi_k}{\partial \tau} \right) + \frac{1}{2\tau} \left(\frac{\partial \phi_k}{\partial \tau} \phi_k + \phi_k \frac{\partial \phi_k}{\partial \tau} \right) - \frac{1}{2} \left(k^2 - \frac{1}{\tau} \right) \phi_k^* \phi_k \right]$$

$$= \int d\tau \frac{d^3k}{(2\pi)^3} \left[\frac{1}{2} \left(\frac{\partial \phi_k}{\partial \tau} \right)^* \left(\frac{\partial \phi_k}{\partial \tau} \right) - \frac{1}{2} \underbrace{\left(k^2 - \frac{1}{\tau} \right)}_{\omega(k)^2} \phi_k^* \phi_k \right]$$

$\omega \rightarrow k$ AT EARLY TIMES

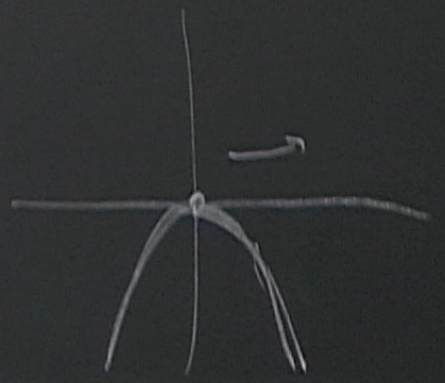


$$2\tau \left(\frac{\partial \tau}{\partial k} \right)$$

$$= \frac{1}{2} \left(k^2 - \frac{2}{\tau^2} \right) \left[\begin{matrix} \tau_k^+ \\ \tau_k \end{matrix} \right]$$

$w(t)^2$

$w \rightarrow k$ AT EARLY TIMES



STARTING IN VACUUM STATE

$$\hat{H} \psi_k(\tau) = u_{\psi}(k, \tau) a_k + u_{\psi}(k, \tau)^* a_{-k}^{\dagger}$$

WHERE $\ddot{u}_{\psi}(k, \tau) = -\left(k^2 - \frac{2}{\tau^2}\right) u_{\psi}(k, \tau)$

AND $u_{\psi}(k, \tau) \rightarrow \frac{1}{(2k)^{1/2}} e^{-ik\tau}$ AS $\tau \rightarrow -\infty$

STARTING IN VACUUM STATE

$$\hat{H}_{\psi}(k, \tau) = u_{\psi}(k, \tau) a_k + u_{\psi}^*(k, \tau) a_{-k}^\dagger$$

WHERE

$$\ddot{u}_{\psi}(k, \tau) = -\left(k^2 - \frac{2}{\tau^2}\right) u_{\psi}(k, \tau)$$

AND

$$u_{\psi}(k, \tau) \rightarrow \frac{1}{(2k)^{1/2}} e^{-ik\tau} \quad \text{AS } \tau \rightarrow -\infty$$

SOLUTION:

$$u_{\psi}(k, \tau) = \frac{1}{(2k)^{1/2}} \left(1 - \frac{i}{k\tau}\right) e^{-ik\tau}$$

[NOT EASY!]

STARTING IN VACUUM STATE

$$\hat{H}_\psi(k, \tau) = u_\psi(k, \tau) a_k + u_\psi^*(k, \tau) a_{-k}^\dagger$$

WHERE $\ddot{u}_\psi(k, \tau) = -\left(k^2 - \frac{2+\epsilon}{\tau^2}\right) u_\psi(k, \tau)$

AND $u_\psi(k, \tau) \rightarrow \frac{1}{(2k)^{1/2}} e^{-ik\tau}$ AS $\tau \rightarrow -\infty$

SOLUTION: $u_\psi(k, \tau) = \frac{1}{(2k)^{1/2}} \left(1 - \frac{i}{k\tau}\right) e^{-ik\tau}$

[NOT EASY!]

STARTING IN VACUUM STATE

$$\hat{H}_k(\tau) = u_\psi(k, \tau) a_k + u_\psi(k, \tau)^* a_{-k}^\dagger$$

WHERE

$$\ddot{u}_\psi(k, \tau) = -\left(k^2 - \frac{2}{\tau^2}\right) u_\psi(k, \tau)$$

AND

$$u_\psi(k, \tau) \rightarrow \frac{1}{(2k)^{1/2}} e^{-ik\tau} \quad \text{AS } \tau \rightarrow -\infty$$

SOLUTION:

$$u_\psi(k, \tau) = \frac{1}{(2k)^{1/2}} \left(1 - \frac{i}{k\tau}\right) e^{-ik\tau}$$

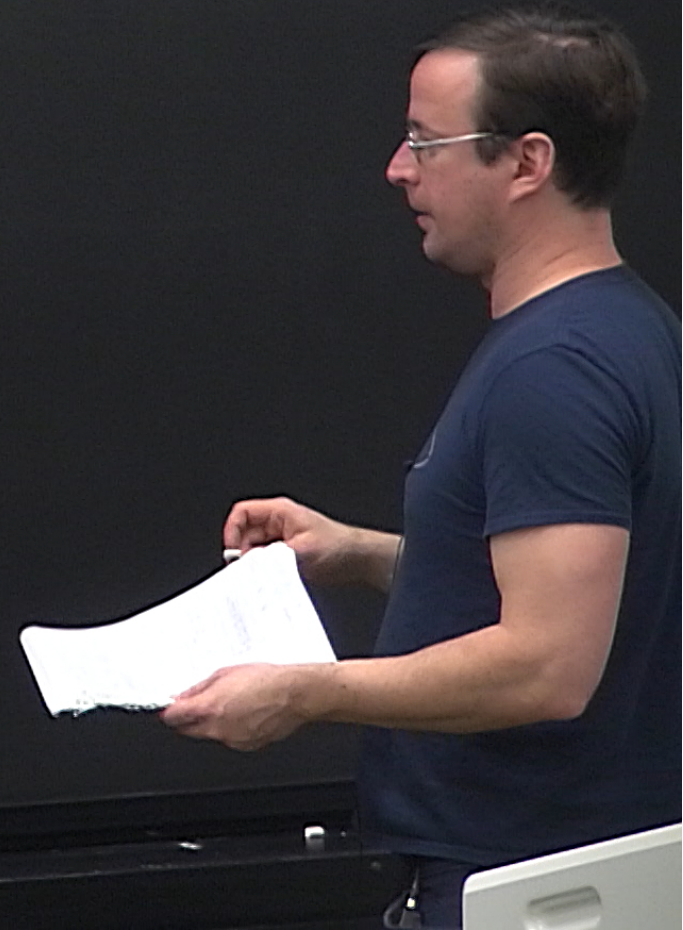
[NOT EASY!]

IN ORIGINAL FIELD VARIABLE $\phi = (H\tau)\psi$

$$\hat{\phi}_k^H(\tau) = u_\phi(k, \tau) \hat{a}_k + u_\phi(k, \tau)^* \hat{a}_{-k}^\dagger$$

$$u_\phi(k, \tau) = H\tau u_\psi(k, \tau)$$

$$= \frac{H}{2k^{3/2}} (1 + ik\tau) e^{-ik\tau}$$



IN ORIGINAL FIELD VARIABLE $\phi = (H\tau) \psi$

$$\hat{\phi}_k^H(\tau) = u_\phi(k, \tau) \hat{a}_k + u_\phi(k, \tau)^* \hat{a}_{-k}^\dagger$$

$$u_\phi(k, \tau) = H\tau u_\psi(k, \tau)$$

$$= \frac{H}{2k^{3/2}} (1 + ik\tau) e^{-ik\tau}$$

"DE SITTER MODE FUNCTION"

POWER SPECTRUM: $\langle \hat{\phi}_k^H(\tau) \hat{\phi}_k^H(\tau) \rangle$

IN ORIGINAL FIELD VARIABLE $\phi = (H\tau) \psi$

$$\hat{\phi}_k^H(\tau) = u_\phi(k, \tau) a_k + u_\phi(k, \tau)^* a_{-k}^\dagger$$

$$u_\phi(k, \tau) = H\tau u_\psi(k, \tau)$$

$$= \frac{H}{2k^{3/2}} (1 + ik\tau) e^{-ik\tau}$$

"DE SITTER MODE FUNCTION"

POWER SPECTRUM:

$$\langle \phi_k^H(\tau)^* \phi_{k'}(\tau) \rangle$$

IN ORIGINAL FIELD VARIABLE $\phi = (H\tau) \psi$

$$\hat{\phi}_k^H(\tau) = u_\phi(k, \tau) \hat{a}_k + u_\phi(k, \tau)^* \hat{a}_{-k}^\dagger$$

$$u_\phi(k, \tau) = H\tau u_\psi(k, \tau)$$

$$= \frac{H}{2k^{3/2}} (1 + ik\tau) e^{-ik\tau}$$

"DE SITTER MODE FUNCTION"

POWER SPECTRUM: $\langle \hat{\phi}_k^H(\tau)^* \hat{\phi}_{k'}^H(\tau) \rangle = \langle 0 | \hat{\phi}_k^H(\tau)^* \hat{\phi}_{k'}^H(\tau) | 0 \rangle$

$$= \frac{4\pi}{2k^{3/2}} (1+ik\tau) e^{-ik\tau}$$

"DE SITTER MODE FUNCTION"

ENERGY SPECTRUM:

$$\begin{aligned} \langle \phi_k^*(\tau) \phi_{k'}(\tau) \rangle &= \langle 0 | \phi_k^H(\tau)^\dagger \phi_{k'}^H(\tau) | 0 \rangle \\ &= \langle 0 | (u_\phi(k,\tau)^* a_k^\dagger + u_\psi(k,\tau) a_{-k}) (u_\phi(k',\tau) a_{k'} + u_\psi(k',\tau) a_{-k'}^\dagger) | 0 \rangle \end{aligned}$$

$$= \frac{4\pi}{2k^{3/2}} (1+ik\tau) e^{-ik\tau}$$

"DE SITTER MODE FUNCTION"

ENERGY SPECTRUM:

$$\begin{aligned} \langle \phi_k(\tau) \phi_{k'}(\tau) \rangle &= \langle 0 | \phi_k^H(\tau)^\dagger \phi_{k'}^H(\tau) | 0 \rangle \\ &= \langle 0 | (u_\phi(k,\tau)^* a_k^\dagger + u_\phi(k,\tau) a_{-k}) (u_\phi(k',\tau) a_{k'} + u_\phi(k',\tau)^* a_{-k}') | 0 \rangle \\ &= u_\phi(k,\tau) u_\phi(k',\tau)^* \langle 0 | a_{-k} a_{-k'}^\dagger | 0 \rangle \end{aligned}$$

EX SPECTRUM:

$$\begin{aligned} \langle \phi_k^*(\tau) \phi_{k'}(\tau) \rangle &= \langle 0 | \phi_k^*(\tau) \phi_{k'}(\tau) | 0 \rangle \\ &= \langle 0 | \left(u_\phi(k, \tau)^* a_k^\dagger + u_\phi(k, \tau) a_k \right) \left(u_\phi(k', \tau) a_{k'} + u_\phi(k', \tau)^* a_{-k'}^\dagger \right) | 0 \rangle \\ &= u_\phi(k, \tau) u_\phi(k', \tau)^* \langle 0 | a_{-k} a_{-k'}^\dagger | 0 \rangle \end{aligned}$$

$$\begin{aligned} &= u_\phi(k, \tau) u_\phi(k', \tau)^* (2\pi)^3 \delta^3(k - k') \\ &[a_k, a_{k'}^\dagger] = (2\pi)^3 \delta^3(k - k') \end{aligned}$$



$$= u_{\varphi}(k, \tau) u_{\varphi}(k', \tau)^* (2\pi)^3 \delta^3(k-k')$$

$$[a_k, a_{k'}^{\dagger}] = (2\pi)^3 \delta^3(k-k')$$

$$= \frac{H}{2k^3} (1 + k^2 \tau^2) (2\pi)^3 \delta^3(k-k')$$

$$P_k(\tau)$$

$$= u_{\phi}(k, \tau) u_{\phi}(k', \tau)^* (2\pi)^3 \delta^3(k - k')$$

$$[a_k, a_{k'}^{\dagger}] = (2\pi)^3 \delta^3(k - k')$$

$$= \frac{H^2}{2k^3} (1 + k^2 \tau^2) (2\pi)^3 \delta^3(k - k')$$

$$P_k(\tau)$$

$$\text{At } \tau=0 \Rightarrow P_{\phi}(k) = \frac{H^2}{2k^3}$$

$$[a_k, a_{k'}^\dagger] = (2\pi)^3 \delta^3(k-k')$$

$$= \frac{H^2}{2k^3} (1+k^2\tau^2) (2\pi)^3 \delta^3(k-k')$$

$$P_k(\tau)$$

$$\text{At } \tau=0 \Rightarrow P_\sigma(k) = \frac{H^2}{2k^3} \rightarrow \text{SCALE INVARIANT}$$

$$[a_k, a_{k'}^\dagger] = (2\pi)^3 \delta^3(k-k')$$

$$= \frac{H^2}{2k^3} (1+k^2\tau^2) (2\pi)^3 \delta^3(k-k')$$

$P_k(\tau)$

At $\tau=0 \Rightarrow$

$$P_\sigma(k) = \frac{H^2}{2k^3}$$

\rightarrow SCALE INVARIANT

$$[a_k, a_{k'}^\dagger] = (2\pi)^3 \delta^3(k-k')$$

$$= \frac{H^2}{2k^3} (1 - k^2 \tau^2) (2\pi)^3 \delta^3(k-k')$$

$$\Delta_\varphi^2(k) = \frac{k^3}{2\pi^2} P_\varphi(k)$$

$$P_k(\tau)$$

At $\tau=0 \Rightarrow$

$$P_\varphi(k) = \frac{H^2}{2k^3}$$

→ SCALE INVARIANT
"SIZE" OF FLUCTUATION

$$[a_k, a_{k'}^\dagger] = (2\pi)^3 \delta^3(k - k')$$

$$= \frac{H^2}{2k^3} (1 - k^2 \tau^2) (2\pi)^3 \delta^3(k - k')$$

$$\Delta_\phi^2(k) = \frac{k^3}{2\pi^2} P_\phi(k)$$

$$P_k(\tau)$$

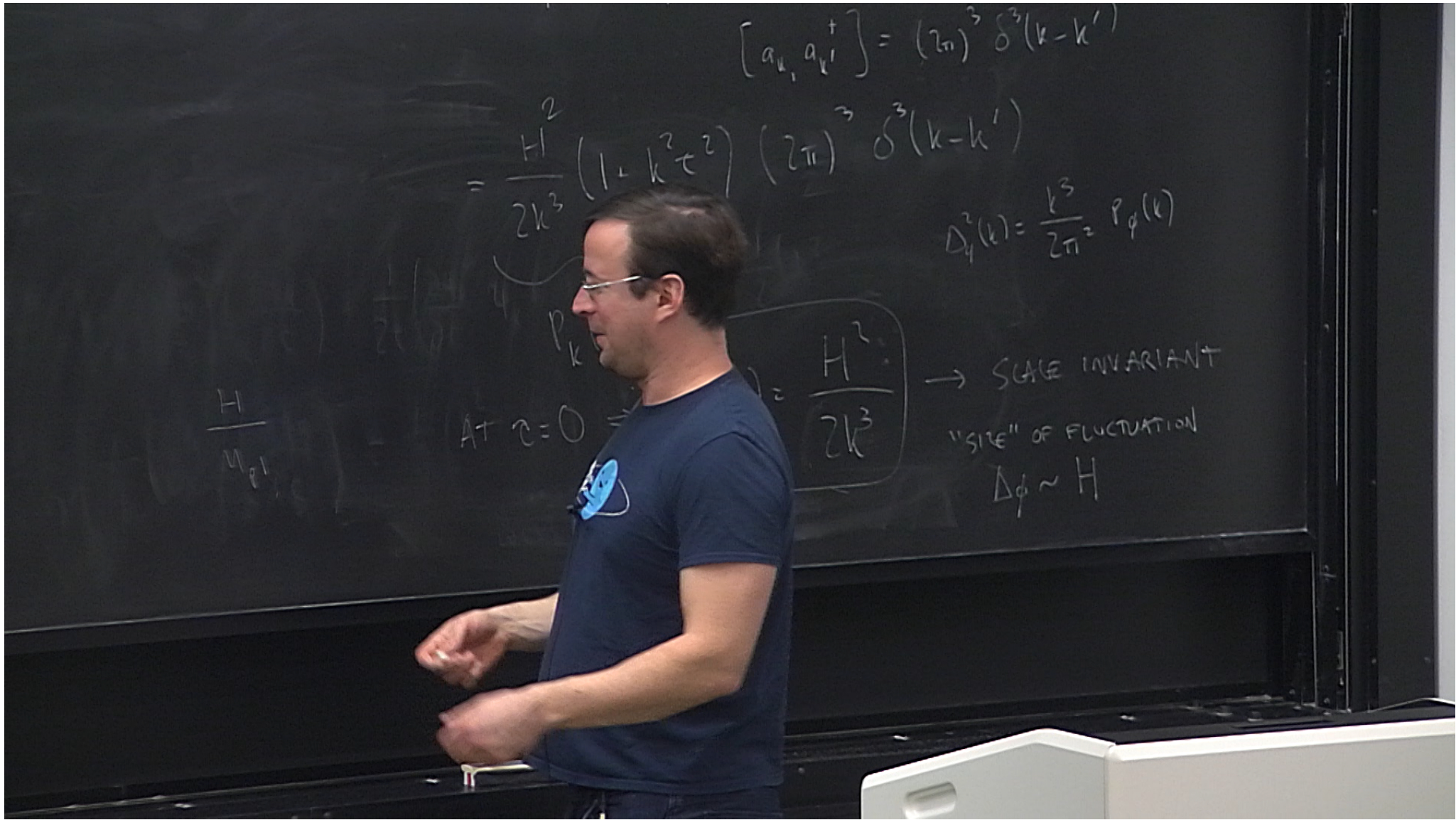
At $\tau=0 \Rightarrow$

$$P_\phi(k) = \frac{H^2}{2k^3}$$

→ SCALE INVARIANT

"SIZE" OF FLUCTUATION

$$\Delta\phi \sim H$$



$$[a_k, a_{k'}^\dagger] = (2\pi)^3 \delta^3(k - k')$$

$$= \frac{H^2}{2k^3} (1 - k^2 \tau^2) (2\pi)^3 \delta^3(k - k')$$

$$\Delta_\phi^2(k) = \frac{k^3}{2\pi^2} P_\phi(k)$$

$$\frac{H}{M_{pl}}$$

$$P_k = \frac{H^2}{2k^3}$$

→ SCALE INVARIANT
"SIZE" OF FLUCTUATION
 $\Delta\phi \sim H$

$$\psi_k(z) = u_p(k, \tau) a_k + u_p(k, \tau) a_k^+$$

$$\frac{\partial}{\partial \tau} \left(\frac{1}{(1+k)^2} \frac{\partial u_p}{\partial \tau} \right) + k^2 u_p = 0$$

$$u_p(k, \tau) \rightarrow$$

$$\psi_k(z) = u_p(k, \tau) a_k + u_p(k, \tau) a_k^\dagger$$

$$\frac{\partial}{\partial \tau} \left(\frac{1}{(1+k\tau)^2} \frac{\partial u_p}{\partial \tau} \right) + k^2 u_p = 0$$

$$u_p(k, \tau) \rightarrow A(k) e^{-k\tau} \quad \text{AS } \tau \rightarrow -\infty$$

$$\psi_k(z) = u_p(k, \tau) a_k + u_p(k, \tau) a_k^\dagger$$

$$\frac{\partial}{\partial \tau} \left(\frac{1}{(H\tau)^2} \frac{\partial u_p}{\partial \tau} \right) + k^2 u_p = 0$$

$$u_p(k, \tau) \rightarrow \underbrace{A(k)}_{\text{AS } \tau \rightarrow -\infty} e^{-ik\tau}$$

$$i = [k, p_p] \quad p_p = \frac{\delta S}{\delta \dot{\phi}} = \frac{1}{(H\tau)^2} \frac{\partial \phi}{\partial \tau}$$

$$= \frac{1}{(H\tau)^2} (u \dot{u}^\dagger - \dot{u} u^\dagger)$$

$$\psi_k(\tau) = u_\phi(k, \tau) a_k + u_\phi^*(k, \tau) a_k^\dagger$$

$$\frac{\partial}{\partial \tau} \left(\frac{1}{(H\tau)^2} \frac{\partial u_\phi}{\partial \tau} \right) + k^2 u_\phi = 0$$

$$u_\phi(k, \tau) \rightarrow \underbrace{A(k)}_{\text{AS } \tau \rightarrow -\infty} e^{-ik\tau}$$

$$i = [k, p_\phi] \quad p_\phi = \frac{\delta S}{\delta \dot{\phi}} = \frac{1}{(H\tau)^2} \frac{\partial \phi}{\partial \tau}$$

$$= \frac{1}{(H\tau)^2} (u \dot{u}^\dagger - u^\dagger \dot{u}) \Rightarrow |A|^2 = \frac{H^2}{2k^3}$$

$$\psi_k(\tau) = u_\phi(k, \tau) a_k + u_\phi^*(k, \tau) a_k^\dagger$$

$$\frac{\partial}{\partial \tau} \left(\frac{1}{(Hc)^2} \frac{\partial u_\phi}{\partial \tau} \right) + k^2 u_\phi = 0$$

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$$\phi_k(\tau) = u_\phi(k, \tau) a_k + u_\phi^*(k, \tau) a_k^\dagger$$

$S \rightarrow \lambda S$

$$\frac{\partial}{\partial \tau} \left(\frac{1}{(H\tau)^2} \frac{\partial u_\phi}{\partial \tau} \right) + k^2 u_\phi = 0$$

$$u_\phi(k, \tau) \rightarrow A(k) e^{-ik\tau} \quad \text{AS } \tau \rightarrow -\infty$$

$$i = [k, p_\mu] \quad p_\mu = \frac{\delta S}{\delta \dot{\phi}} = \frac{1}{(H\tau)^2} \frac{\partial \phi}{\partial \tau}$$

$$= \frac{1}{(H\tau)^2} (u \dot{u}^\dagger - u^* \dot{u}) \Rightarrow |A|^2 = \frac{H^2}{2k^3}$$

MASSLESS SCALAR IN NONDYNAMICAL FRW SPACETIME

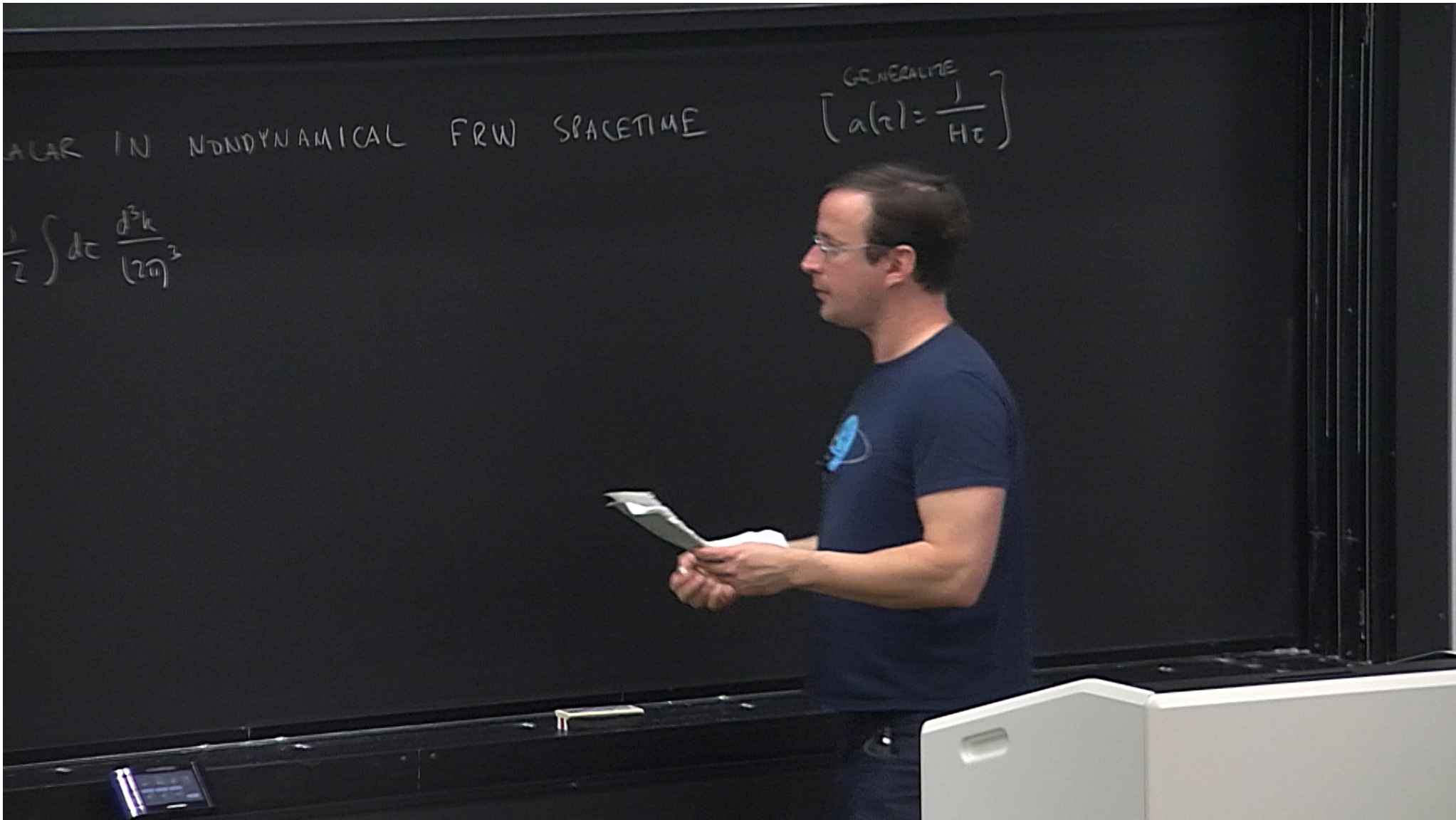
$[a(\tau) = -$

$$S = \frac{1}{2} \int d\tau \frac{d^3k}{(2\pi)^3}$$

ALAN IN NONDYNAMICAL FRW SPACETIME

GENERALISE
$$\left[a(\tau) = \frac{1}{H\tau} \right]$$

$$\frac{1}{2} \int d\tau \frac{d^3k}{(2\pi)^3}$$



MASSLESS SCALAR IN NONDYNAMICAL FRW SPACETIME

GENERALIZE
 $\left[a(\tau) = \frac{1}{H\tau} \right]$

$$S = \frac{1}{2} \int d\tau \frac{d^3k}{(2\pi)^3} a(\tau)^2 \left((\partial_\tau \phi)^2 - (\partial_i \phi)^2 \right)$$

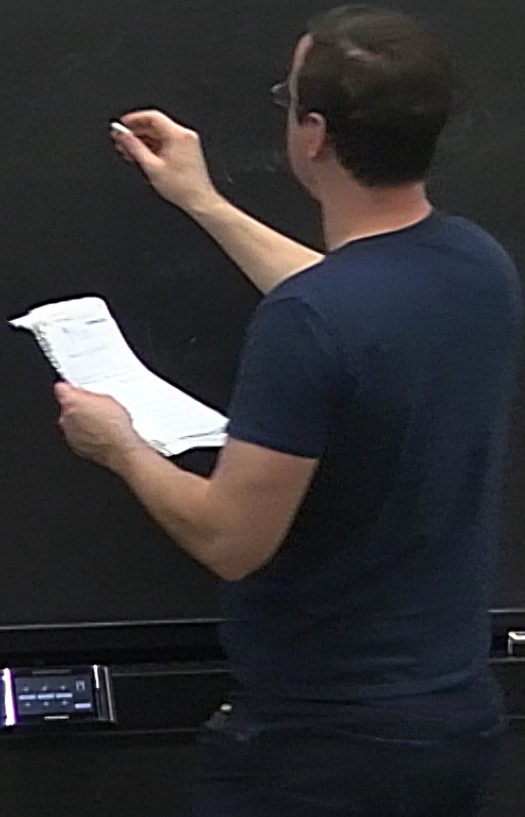
$$\frac{d}{d\tau} \left(a^2 \frac{du_\mu}{d\tau} \right) + k^2 u_\mu = 0$$

$$S = -\frac{1}{2} \int d\tau d^3x a(\tau)^2 \left[(\partial_\tau \phi)^2 - (\partial_i \phi)^2 \right]$$

$$\frac{d}{d\tau} \left(a^2 \frac{du_\psi}{d\tau} \right) + \hbar^2 a^2 u_\psi = 0$$

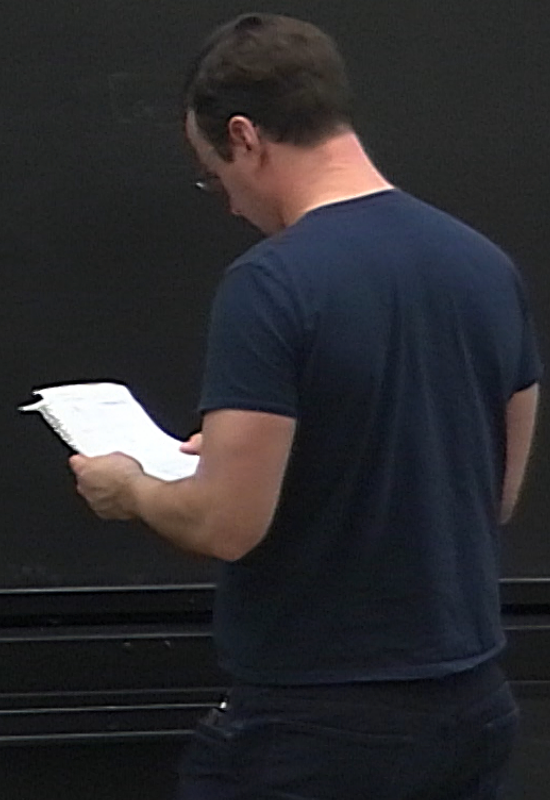
$$\psi = a \phi$$

$$\psi = a\phi \Rightarrow S = \frac{1}{2} \int d\tau d^3x \left[(\partial_\tau \psi)^2 - (\partial_i \psi)^2 + \frac{(\partial_\tau a)^2}{a} \psi^2 \right]$$



$$\psi = a\phi \Rightarrow S = \frac{1}{2} \int d\tau d^3x \left[(\partial_\tau \psi)^2 - (\partial_i \psi)^2 + \frac{(\partial_\tau a)^2}{a} \psi^2 \right]$$

$$\frac{d^2 u_\psi}{d\tau^2} + k^2 u_\psi - \frac{\partial_\tau^2 a}{a} = 0$$



$$\psi = a\phi \Rightarrow S = \frac{1}{2} \int d\tau d^3x \left[(\partial_\tau \psi)^2 - (\partial_i \psi)^2 + \frac{(\partial_\tau a)^2}{a} \psi^2 \right] \quad a(t)$$

$$\frac{d^2 u_\psi}{d\tau^2} + k^2 u_\psi - \frac{\partial_\tau^2 a}{a} = 0$$

$$u_\psi(k) \rightarrow \frac{1}{(2k)^{1/2}} e^{-ik\tau} \quad \text{AT EARLY TIMES}$$

$$S = \frac{1}{2} \int d\tau d^3x a(\tau)^2 \left[(\partial_\tau \phi)^2 - (\partial_i \phi)^2 \right]$$

$$\frac{d}{d\tau} \left(a^2 \frac{du_\phi}{d\tau} \right) + \hbar^2 a^2 u_\phi = 0$$

$$u_\phi(k, \tau) \rightarrow \frac{a(\tau)^{-1}}{(2k)^{1/2}} e^{-ik\tau}$$

$$\psi = a\phi \Rightarrow S = \frac{1}{2} \int$$

$$\frac{d^2 u_\psi}{d\tau^2} +$$

$$u_\psi(k) \rightarrow$$

$$\psi = a\phi \Rightarrow S = \frac{1}{2} \int d\tau d^3x \left[(\partial_\tau \psi)^2 - (\partial_i \psi)^2 + \frac{(\partial_\tau a)^2}{a} \psi^2 \right] \quad a(\tau)$$

$$\frac{d^2 u_\psi}{d\tau^2} + k^2 u_\psi - \frac{\partial_\tau^2 a}{a} = 0$$

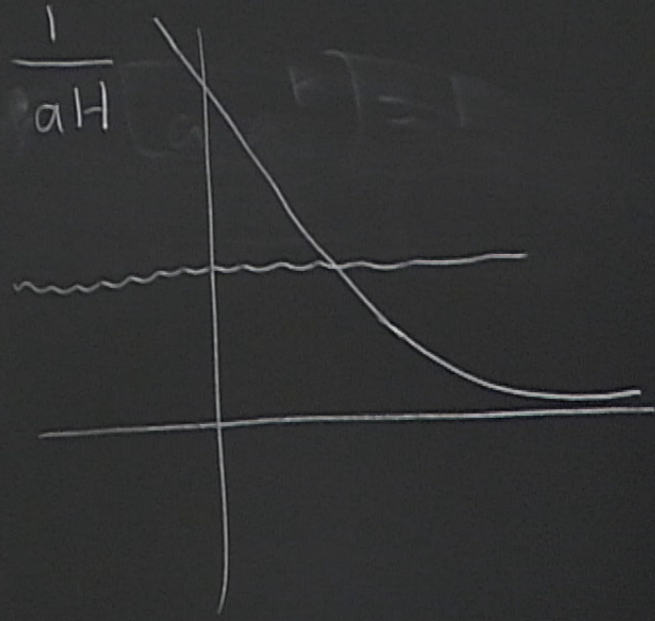
$$u_\psi(k) \rightarrow \frac{1}{(2k)^{1/2}} e^{-ik\tau}$$

AT EARLY TIMES



$$\left[(\delta_{\psi})^2 + \frac{(\delta_{\tau \alpha})^2}{a} \psi^2 \right] \quad \text{also}$$

COMMUNING
DISTANCE



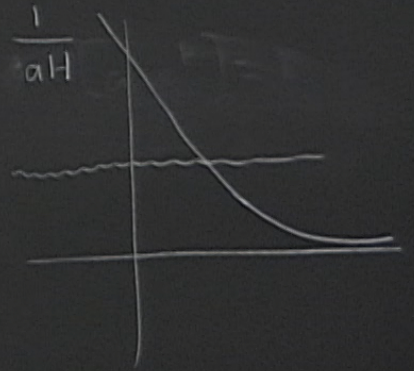
$k=1$

AT EARLY TIMES

$$\psi = a\phi \Rightarrow S = \frac{1}{2} \int d\tau d^3x \left[(\partial_\tau \psi)^2 - (\partial_i \psi)^2 + \frac{(\partial_\tau a)^2}{a} \psi^2 \right] \quad \text{a.c.}$$

$$\frac{d^2 u_\psi}{d\tau^2} + k^2 u_\psi - \frac{\partial_\tau^2 a}{a} = 0$$

COMOVING DISTANCE



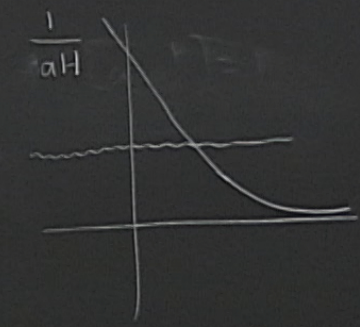
$$u_\psi(k) \rightarrow \frac{1}{(2k)^{1/2}} e^{-ik\tau}$$

AT EARLY TIMES

$$\Rightarrow S = \frac{1}{2} \int d\tau d^3x \left[(\partial_\tau \psi)^2 - (\partial_i \psi)^2 + \frac{(\partial_\tau a)^2}{a} \psi^2 \right] \quad \text{a/c)$$

$$\frac{d^2 u_\psi}{d\tau^2} + k^2 u_\psi - \frac{\partial_\tau^2 a}{a} = 0$$

COMPARING DISTANCE



AT EARLY TIMES

$$u_\psi(k) \rightarrow \frac{1}{(2k)^{1/2}} e^{-ik\tau}$$

$$S = -\frac{1}{2} \int d\tau d^3x a(\tau)^2 \left[(\partial_\tau \phi)^2 - (\partial_i \phi)^2 \right]$$

$$\frac{d}{d\tau} \left(a^2 \frac{du_\psi}{d\tau} \right) + k^2 a^2 u_\psi = 0$$

$$u_\psi(k, \tau) \rightarrow \frac{a(\tau)^{-1}}{(2k)^{1/2}} e^{-ik\tau}$$

$u_p(\tau) \rightarrow$ CONSTANT AT LATE TIMES

$$\psi = a\phi \Rightarrow S = \frac{1}{2} \int$$

$$\frac{d^2 u_\psi}{d\tau^2} +$$

$$u_\psi(k) \rightarrow$$

$$\psi_k(\tau) = u_\phi(k, \tau) a_k + u_\phi^*(k, \tau) a_k^\dagger$$

$$\frac{\partial}{\partial \tau} \left(\frac{1}{(H\tau)^2} \frac{\partial u_\phi}{\partial \tau} \right) + k^2 u_\phi = 0$$

$$u_\phi(k, \tau) \rightarrow A(k) e^{-ik\tau} \quad \text{AS } \tau \rightarrow -\infty$$

$$i = [p_i, p_j] \quad p_j = \frac{\delta S}{\delta \dot{\phi}} = \frac{1}{(H\tau)^2} \frac{\partial \phi}{\partial \tau}$$

$$= \frac{1}{(H\tau)^2} (u \dot{u}^\dagger - \dot{u} u^\dagger) \Rightarrow |A|^2 = \frac{H^2}{2k^3}$$

$$(1+ik\tau) e^{-ik\tau}$$

S →

MASSLESS SCALAR IN NONDYN

$$S = \frac{1}{2} \int d\tau \frac{d^3 k}{(2\pi)^3} a(\tau)^2$$

$$\frac{d}{d\tau} \left(a^2 \frac{du_\phi}{d\tau} \right) + k^2$$

$$(1 - ik\tau) e^{-ik\tau}$$

$$u_{\phi}(k, \tau) a_k^{\dagger}$$

$$S \rightarrow \lambda S$$

$$S = \frac{1}{2} \int d\tau d^3x a(\tau)^2 \left[(\partial_\tau \phi)^2 - (\partial_i \phi)^2 \right]$$

$$\frac{d}{d\tau} \left(a^2 \frac{du_\phi}{d\tau} \right) + k^2 a^2 u_\phi = 0$$

$$u_\phi(k, \tau) \rightarrow \frac{a(\tau)^{-1}}{(2k)^{1/2}} e^{-k\tau}$$

$u_\phi(\tau) \rightarrow$ CONSTANT AT LATE TIMES

$$|u_\phi(k, \tau)|^2 \rightarrow \frac{H^2}{2k^3} + [\text{SLOW-ROLL CORRECTIONS}]$$

$$H_x = H(a) \Big|_{k=aH}$$

$$\psi = a\phi \Rightarrow S = \frac{1}{2} \int d\tau d^3x \left[(\partial_\tau \psi)^2 - (\partial_i \psi)^2 \right]$$

$$\frac{d^2 u_\psi}{d\tau^2} +$$

$$u_\psi(k) \rightarrow$$

$$S = -\frac{1}{2} \int d\tau d^3x a(\tau)^2 \left[(\partial_\tau \phi)^2 - (\partial_i \phi)^2 \right]$$

$$\frac{d}{d\tau} \left(a^2 \frac{du_\phi}{d\tau} \right) + k^2 a^2 u_\phi = 0$$

$$u_\phi(k, \tau) \rightarrow \frac{a(\tau)^{-1}}{(2k)^{1/2}} e^{-ikt}$$

$u_\phi(\tau) \rightarrow$ CONSTANT AT LATE TIMES

$$|u_\phi(k, \tau)|^2 \rightarrow \frac{H^2}{2k^3} + [\text{SLOW-ROLL CORRECTIONS}]$$

$$H_x = H(a) \Big|_{k=aH}$$

$$\psi = a\phi \Rightarrow$$

$$S = -\frac{1}{2} \int d\tau d^3x a(\tau)^2 \left[(\partial_\tau \phi)^2 - (\partial_i \phi)^2 \right]$$

$$\frac{d}{d\tau} \left(a^2 \frac{du_\phi}{d\tau} \right) + k^2 a^2 u_\phi = 0$$

$$u_\phi(k, \tau) \rightarrow \frac{a(\tau)^{-1}}{(2k)^{1/2}} e^{-ikt}$$

$u_\phi(\tau) \rightarrow$ CONSTANT AT LATE TIMES

$$|u_\phi(k, \tau)|^2 \rightarrow \frac{H^2}{2k^3} + [\text{SLOW-ROLL CORRECTIONS}]$$

$$H_x = H(\omega) \Big|_{k=aH}$$

$$\psi = a\phi \Rightarrow$$