

Title: PSI 2017/2018 - Cosmology - Lecture 9

Date: Apr 19, 2018 10:15 AM

URL: <http://pirsa.org/18040021>

Abstract:

$$g_{\mu\nu}(x,t) = \bar{g}_{\mu\nu}(t) + \delta g_{\mu\nu}(x,t)$$

$$\phi(x,t) = \bar{\phi}(t) + \delta\phi(x,t)$$

$$\bar{g}_{\mu\nu}(t) = \begin{pmatrix} -1 & \\ & a(t)^2 \delta_{ij} \end{pmatrix} \quad a(t) \sim \text{EXPERIMENTAL}$$

$\bar{\phi}(t)$ CHANGING SLOWLY

$$\xi^\mu = (\xi^0, \xi^i)$$

$$\mathcal{L}_\xi \phi = \xi^0 \dot{\bar{\phi}}$$

$$\mathcal{L}_\xi g_{00} = -2\dot{\xi}^0$$

$$\mathcal{L}_\xi g_{0i} = a^2 \dot{\xi}^i - \partial_i \xi^0$$

$$\mathcal{L}_\xi g_{ij} = 2a^2 H \xi^0 \delta_{ij} + a^2 (\partial_i \xi_j + \partial_j \xi_i)$$

$$g_{\mu\nu}(x_i, t) = \bar{g}_{\mu\nu}(t) + \delta g_{\mu\nu}(x_i, t)$$

$$\phi(x_i, t) = \bar{\phi}(t) + \delta\phi(x_i, t)$$

$$\bar{g}_{\mu\nu}(t) = \begin{pmatrix} -1 & & \\ & a(t)^2 \delta_{ij} & \\ & & \end{pmatrix}$$

$a(t) \sim \text{EXPONENTIAL}$

$\bar{\phi}(t)$

CHANGING SLOWLY

$$\xi^\mu = (\xi^0, \xi^i)$$

$$\mathcal{L}_\xi \phi = \xi^0 \dot{\phi}$$

$$\mathcal{L}_\xi g_{00} = -2\dot{\xi}^0$$

$$\mathcal{L}_\xi g_{0i} = a^2 \dot{\xi}^i - \partial_i \xi^0$$

$$\mathcal{L}_\xi g_{ij} = 2a^2 H \xi^0 \delta_{ij} + a^2 (\partial_i \xi_j + \partial_j \xi_i)$$

GAUGE FIXING

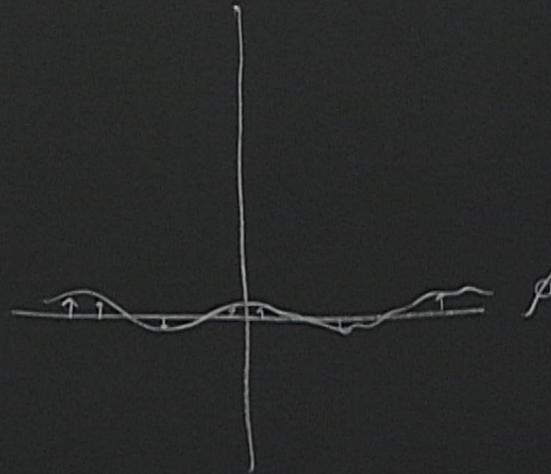
ELECTRODYNAMICS

GAUGE FIXING

$$A_{\mu} \rightarrow A_{\mu} + \partial_{\mu} \alpha(x)$$
$$\partial_{\mu} A^{\mu} = 0 \quad [\text{LORENTZ}]$$
$$A^0 = 0 \quad [\text{COULOMB}]$$

GAUGE FIXING IN SINGLE FIELD INFLATION

$$\delta\phi = 0$$



DEFINE $\delta g_{ij}(x,t) = a(t)^2 [2 \eta(x,t) \delta_{ij} + \gamma_{ij}(x,t)]$ $\delta_{kk}(x,t) = 0$

(δg)

$$\delta g_{ij} = \epsilon \partial_i \delta x_j + \epsilon (\partial_i \delta x_j + \partial_j \delta x_i)$$

FIELD INFLATION

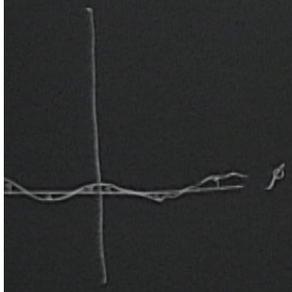
DEFINE $\delta g_{ij}(x,t) = a(t)^2 [2\zeta(x,t) \delta_{ij} + \gamma_{ij}(x,t)]$ $\gamma_{kk}(x,t) = 0$

$$(\delta g_{ij}) \leftrightarrow (\zeta, \gamma_{ij})$$

$$\zeta = \frac{1}{6} a^{-2} (\delta g_{kk})$$

$$\gamma_{ij} = a^{-2} \left(\delta g_{ij} - \frac{1}{3} \delta_{ij} (\delta g_{kk}) \right)$$

ELO INFLATION



DEFINE $\delta g_{ij}(x,t) = a(t)^2 [2\zeta(x,t)\delta_{ij} + \chi_{ij}(x,t)]$ $\chi_{kk}(x,t) = 0$

$(\delta g_{ij}) \leftrightarrow (\zeta, \chi_{ij})$

$\zeta = \frac{1}{6} a^{-2} (\delta g_{kk})$

$\chi_{ij} = a^{-2} (\delta g_{ij} - \frac{1}{3} \delta_{ij} (\delta g_{kk}))$

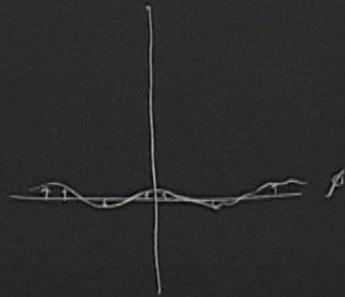
$\delta g_{ij} = \begin{pmatrix} \delta g_{11} & \\ & 0 \end{pmatrix}$

$= \underbrace{\left(\frac{1}{3} \delta g_{11}\right)}_{\zeta} \delta_{ij} + \underbrace{\begin{pmatrix} \frac{2}{3} \delta g_{11} & \\ & -\frac{1}{3} \delta g_{11} \end{pmatrix}}_{\chi_{ij}} + \underbrace{\begin{pmatrix} & \\ & -\frac{1}{3} \delta g_{11} \end{pmatrix}}_{\chi_{ij}}$

Gauge Fixing in Single Field Inflation

$$\delta\phi = 0$$

$$\partial_j \gamma_{ij} = 0$$



DEFINE $\delta g_{ij}(x) = a(x)^2 [2\gamma_{ij}(x) \delta_{ij} + \dots]$

$$(\delta g_{ij}) \leftrightarrow (\xi_i, \gamma_{ij})$$

$$\delta g_{ij} = \begin{pmatrix} \delta g_{11} & \\ & 0 \end{pmatrix}$$

$$= \underbrace{\left(\frac{1}{3} \delta g_{11}\right)}_{\xi_i} \delta_{ij} + \underbrace{\begin{pmatrix} \frac{2}{3} \delta g_{11} & \\ & -\frac{1}{3} \delta g_{11} \end{pmatrix}}_{\gamma_{ij}} \delta_{ij}$$

21

DEFINE $\delta g_{ij}(x,t) = a(t)^2 \left[2\eta(x,t) \delta_{ij} + \gamma_{ij}(x,t) \right]$ $\sum_k \gamma_{kk}(x,t) = 0$

$(\delta g_{ij}) \leftrightarrow (\xi_i, \gamma_{ij})$

$\xi = \frac{1}{6} a^{-2} (\delta g_{kk})$

$\gamma_{ij} = a^{-2} \left(\delta g_{ij} - \frac{1}{3} \delta_{ij} \sum_k \delta g_{kk} \right)$

$\delta g_{ij} = \begin{pmatrix} \delta g_{11} & \\ & 0 \end{pmatrix}$

$= \underbrace{\left(\frac{1}{3} \delta g_{11} \right)}_{\xi} \delta_{ij} + \underbrace{\begin{pmatrix} \frac{2}{3} \delta g_{11} & \\ & -\frac{1}{3} \delta g_{11} \end{pmatrix}}_{\gamma_{ij}} + \underbrace{\begin{pmatrix} & \\ & -\frac{1}{3} \delta g_{11} \end{pmatrix}}_{\gamma_{ij}}$

$(\delta g_{\mu\nu}(x, L), \delta\phi(x, t))$ ARBITRARY

\Rightarrow THERE EXISTS A GAUGE TRANSFORMATION ξ^μ

SUCH THAT $\delta\phi = \underbrace{\partial_j \chi}_{\xi^\mu} = 0$

$$\begin{aligned}
\delta\phi &\rightarrow \delta\phi + \epsilon_0 \dot{\phi} \\
\delta g_{ij} &\rightarrow (\delta g_{ij}) + 2\alpha^2 H \epsilon^0 \delta_{ij} + \alpha^2 (\partial_i \epsilon_j + \partial_j \epsilon_i) \\
\delta_{ij} &\rightarrow \delta_{ij} + \partial_i \epsilon_j + \partial_j \epsilon_i - \frac{2}{3} (\partial_k \epsilon_k) \delta_{ij} \\
\partial_j \delta_{ij} &\rightarrow \partial_j \delta_{ij} + \partial^2 \epsilon_i + \frac{1}{3} \partial_i \partial_j \epsilon^j
\end{aligned}$$

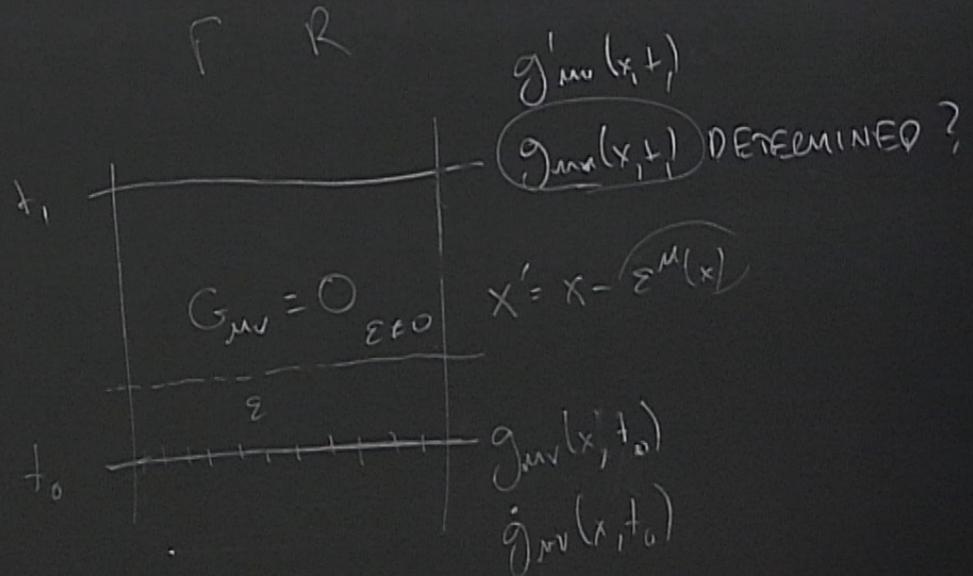
WANT TO SOLVE:

$$\left. \begin{aligned}
\dot{\phi} \epsilon_0 &= S_0 \\
\partial^2 \epsilon_i + \frac{1}{3} \partial_i \partial_j \epsilon^j &= S_i
\end{aligned} \right\} \text{"SOURCES"} (S_0, S_i)$$

EXTRINSIC CURVATURE + ADM VARIABLES

$$\mathbb{G}_{\mu\nu} = M_{\mu\nu}^{-2} T_{\mu\nu}$$

$$g_{\mu\nu}(x) \rightarrow \begin{matrix} 10 \\ \textcircled{6} \\ 2 \end{matrix}$$



- EINSTEIN'S EQS:
- UNDER-DETERMINED
 - REDUNDANT
 - WITH NONDYNAMICAL DEGREES OF FREEDOM

FOY EXAMPLES $x(t)$, $y(t)$, $z(t)$

$$\dot{x} + \dot{y} = y + z$$

$$\dot{y} + \dot{z} = x - z$$

$$\dot{x} - \dot{z} = -x + y + 2z$$

$$u = x + y$$

$$v = y + z$$



$$\dot{u} = v$$

$$\dot{v} = u - v$$

$$\dot{u} - \dot{v} = -u + 2v$$

FOY EXAMPLES $x(t)$, $y(t)$, $z(t)$

$$\dot{x} + \dot{y} = y + z$$

$$\dot{y} + \dot{z} = x - z$$

$$\dot{x} - \dot{z} = -x + y + 2z$$

$$u = x + y$$

$$v = y + z$$

$$\dot{u} = v$$

$$\dot{v} = u - v$$

$$\dot{u} - \dot{v} = -u + 2v$$

$$x(t) \rightarrow x(t) + \varepsilon(t)$$

$$y(t) \rightarrow y(t) - \varepsilon(t)$$

$$z(t) \rightarrow z(t) + \varepsilon(t)$$

$$z = 0$$

$x+y$
 $y+z$

$$\begin{aligned}\dot{u} &= v \\ \dot{v} &= u - v \\ \dot{u} - \dot{v} &= -u + 2v\end{aligned}$$

$$z = 0$$

TODAY EXAMPLE # 2

$$\begin{aligned}\dot{x} + \dot{y} &= y + z \\ \dot{y} + \dot{z} &= x - z \\ \dot{x} - \dot{z} &= z\end{aligned}$$

$$\begin{aligned}\Rightarrow 0 &= x - y - z \\ z &= x - y\end{aligned}$$

$$\begin{aligned}\dot{x} &= y \\ \Rightarrow \dot{y} &= x - y \\ \dot{x} + \dot{y} &= x\end{aligned}$$

EXTRINSIC CURVATURE

- EUCLIDEAN FOR NOW!



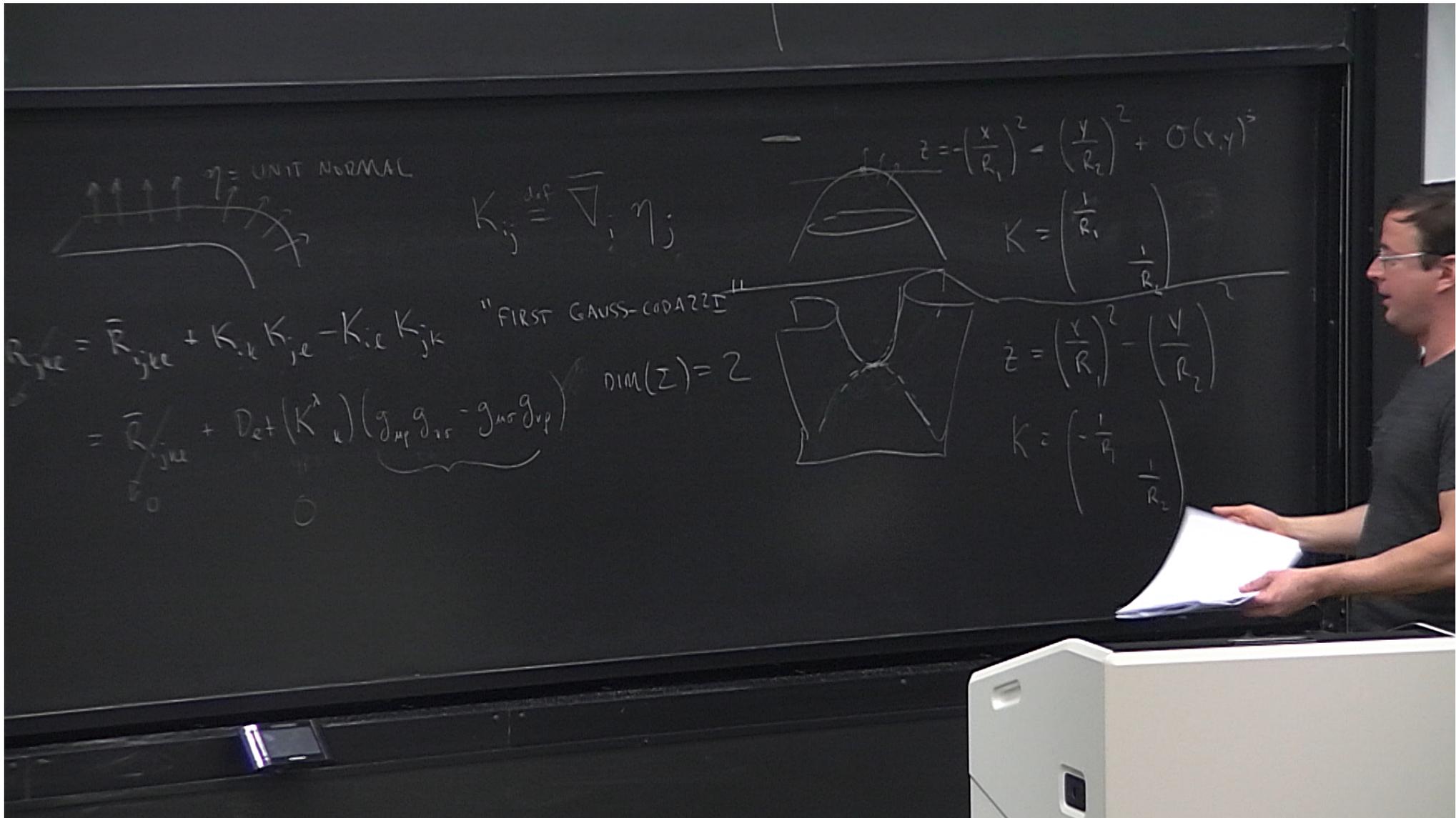
\bar{R} = AMBIENT SPACE

Σ = CODIMENSION-1 SURFACE

How is R_{ijkl} RELATED TO \bar{R}_{ijkl} ?

$$R_{ijkl} = \bar{R}_{ijkl} + K_{ik}K_{jl} - K_{il}K_{jk}$$

WHERE K_{ij} IS "EXTRINSIC CURVATURE"



$\eta = \text{UNIT NORMAL}$

$$K_{ij} \stackrel{\text{def}}{=} \nabla_i \eta_j$$

$$z = -\left(\frac{x}{R_1}\right)^2 - \left(\frac{y}{R_2}\right)^2 + O(x,y)^3$$

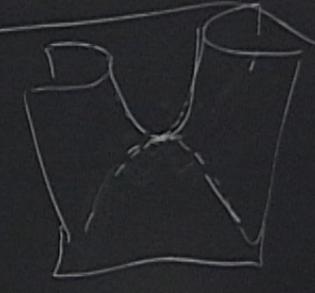
$$K = \begin{pmatrix} -\frac{1}{R_1} & 0 \\ 0 & -\frac{1}{R_2} \end{pmatrix}$$

$$\bar{R}_{jke} = \bar{R}_{jke} + K_{ik} K_{je} - K_{ie} K_{jk}$$

$$= \bar{R}_{jke} + \text{Det}(K^a_k) (g_{\mu p} g_{\nu r} - g_{\mu r} g_{\nu p})$$

"FIRST GAUSS-CODAZZI"

$$\text{DIM}(Z) = 2$$



$$\bar{z} = \left(\frac{x}{R_1}\right)^2 - \left(\frac{y}{R_2}\right)^2$$

$$K = \begin{pmatrix} \frac{1}{R_1} & 0 \\ 0 & -\frac{1}{R_2} \end{pmatrix}$$

BACK TO $(-+++)$ SIGNATURE

Σ DEFINED BY $x^0 = \text{CONSTANT}$

ADM VARIABLES: $ds^2 = -N^2 dt^2 + g_{ij}^{(3)} (dx^i + N^i dt) (dx^j + N^j dt)$

CHANGE OF VARIABLES $g_{\mu\nu}^{(4)} = (g_{00}, g_{0i}, g_{ij}^{(3)}) \leftrightarrow (N, N^i, g_{ij}^{(3)})$

"LAPSE" "SHIFT"

$$S_{EH} = \frac{M^2}{2} \int d^4x \sqrt{g^{(4)}} R^{(4)}$$

$$S_{ADM} = \frac{M^2}{2} \int d^4x \sqrt{g^{(3)}} N \left[R^{(3)} + K^i_j K_{ij} + (K^R_x)^2 \right] \text{ WHERE } K_{ij} = \frac{1}{2N} \left[\dot{g}_{ij}^{(3)} - g_{jk}^{(3)} \nabla_i N^k - g_{ik}^{(3)} \nabla_j N^k \right]$$

$$z^0 \delta_{ij} + a^2 (\partial_i \tau_j + \partial_j \tau_i)$$

$$K^j_i, N^j dt$$

$$\rightarrow (N, N^i, g^{ij})$$

"Lapse" "Shift"

$$\text{WHERE } K^j_i = \frac{1}{2N} \left[\dot{g}^{ij} - g^{jk} \nabla_i N^k - g^{lj} \nabla_l N^k \right]$$

$$\mathcal{L}[\phi, \partial\phi] \quad \left| \quad \frac{\partial \mathcal{L}}{\partial \phi} = \partial_\mu \left(\frac{\partial \mathcal{L}}{\partial \mu \phi} \right) \right.$$

EINSTEIN'S EQUATIONS
 • DIVERGENCE
 • REQUIRE
 • WITH AN

EXTRINSIC CURVATURE

• EUCLIDEAN



How is R_{ijkl} related to R_{ij} ?
 $R_{ijkl} =$

$$\mathcal{L}[\phi, \partial\phi]$$

$$\frac{\partial \mathcal{L}}{\partial \phi} = \dots$$

$$(dx^i + N^i dt)(dx^j + N^j dt)$$

$$N^2 + g_{ij}^{(3)} N^i N^j$$

$$(g_{0i}, g_{ij}^{(3)}) \leftrightarrow (N, N^i, g_{ij}^{(3)})$$

\downarrow "LAPSE" \downarrow "SHIFT"

$$K_{ij} + (K^k{}_k)^2 \quad \text{WHERE } K_{ij} = \frac{1}{2N} \left[\dot{g}_{ij}^{(3)} - g_{jk}^{(3)} \nabla_i^{(3)} N^k - g_{ik}^{(3)} \nabla_j^{(3)} N^k \right]$$