

Title: General Relativity for Cosmology - Lecture 21

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Abstract:

GR for Cosmology, Achim Kempf, Fall 2017, Lecture 22

Note Title

A singularity theorem:

Assume that:

- (M, g) is a globally hyperbolic spacetime
- The energy-momentum tensor of matter obeys the Strong energy condition:

Notice: Since the Einstein equation can be brought in the form $8\pi G_{\mu\nu} = T_{\mu\nu} - \frac{1}{2}Tg_{\mu\nu}$, the strong energy condition is a condition on the Ricci tensor too. This will be the use of the strong energy condition.

$$\left(T_{\mu\nu} - \frac{1}{2}Tg_{\mu\nu}\right)g^{\mu}g^{\nu} \geq 0 \quad \forall \text{ timelike } \xi.$$

- There exists a C^2 spacelike Cauchy surface Σ , on which the trace of the extrinsic curvature, K , is bounded from above by a negative constant C :

$$K(p) \leq C < 0 \quad \text{for all } p \in \Sigma$$

Then:

No past-directed timelike curve from a spacelike hypersurface Σ can have eigentime, i.e., proper length, larger than $\frac{3}{c}$.

J.e.: All past-directed timelike geodesics are incomplete.

\Rightarrow There is a cosmological singularity in the finite past!
because all past-directed paths end on it.

Extrinsic curvature?

later more on this

□ The extrinsic curvature of a spacelike hypersurface describes how much curvature there is in between the spacelike hypersurface and the time dimension.

Intuitively: it is the rate of the expansion of spacetime, more precisely its negative, the rate of contraction.

Thus: Assuming $K(p) \leq G < 0$ meant that spacetime has a finite minimum expansion rate everywhere on Σ .
→ We'll define expansion below in detail.

The strong energy condition?

Recall: □ The "weak energy condition":

$$T_{\mu\nu} v^\mu v^\nu \geq 0 \text{ for all timelike } v: g(v,v) = 0$$

Meaning? For an observer with unit tangent v the local energy density is: $T_{\mu\nu} v^\mu v^\nu \geq 0$

□ The "dominant energy condition":

$$\underbrace{T_{\mu\nu} v^\mu v^\nu \geq 0}_{\text{weak energy condition}} \text{ and } K_\mu K^\mu \leq 0$$

i.e. $T_{\mu\nu} v^\nu$ is non-space-like.

where v is any timelike vector and $K_\mu := T_{\mu\nu} v^\nu$

Meaning? The local energy-momentum flow vector K may not be conserved but has to be non-space-like: Flow should be into the future ← need for causality.

□ The "strong energy condition"

Matter is said to obey the strong energy condition iff :

$$\left(T_{\mu\nu} - \frac{1}{2} T g_{\mu\nu}\right) g^{\mu} g^{\nu} \geq 0 \quad \forall \text{ timelike } \xi.$$

□ Intuition ? *Excludes matter that causes accelerated expansion.* as we will discuss below

□ Plausible ? Yes, obeyed by known matter.
(but not by dark energy)

□ Relationship ? Independent of weak and dominant energy condition.

Concretely: For known matter, $T_{\mu\nu}$ is diagonalizable to obtain:

$$T_{\mu\nu} = \begin{pmatrix} \mathfrak{s} & & \\ 0 & p_1 & 0 \\ 0 & 0 & p_3 \end{pmatrix}$$

↑ energy density observed by comoving observer
↓ principal pressures

The energy conditions then read:

Weak: $\mathfrak{s} > 0$ and $\mathfrak{s} + p_i \geq 0$ for $i \in \{1, 2, 3\}$

Dominant: $\mathfrak{s} \geq |p_i|$ for $i \in \{1, 2, 3\}$

Exercise:

Show this → Strong: $\mathfrak{s} + \sum_{i=1}^3 p_i \geq 0$ and $\mathfrak{s} + p_i \geq 0$ for $i \in \{1, 2, 3\}$

Note: could possibly be also negative.

Recall: A cosmological constant Λ can be viewed as a contribution to $T_{\mu\nu}$.

Indeed, there is no big bang singularity, e.g., if $w = -1 \forall t$,
i.e., in de Sitter spacetime inflation $a(t) = e^{Ht}$ ↗

Exercise: Show that the strong energy condition is violated in cosmology
iff $w < -\frac{1}{3}$, i.e., iff the expansion is accelerating: $\ddot{a}(t) > 0$.

Given, in particular, the strong energy condition, one can show that geodesics meet a divergence of a quantity called expansion, Θ , in finite proper time:

The "expansion", Θ :
important notion also e.g. in study of grav. collapse of stars.

□ Consider a "congruence of timelike geodesics"
through Σ , i.e., a smooth family of timelike geodesics,

exactly one through each $p \in \Sigma$. If parametrized by proper time, their tangent vector field ξ , namely

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$$\xi := \frac{d}{d\tau} \quad \text{proper time}$$

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will obey : $g(\xi, \xi) = -1 \forall p.$

□ Consider now a one-parameter subfamily of these geodesics :

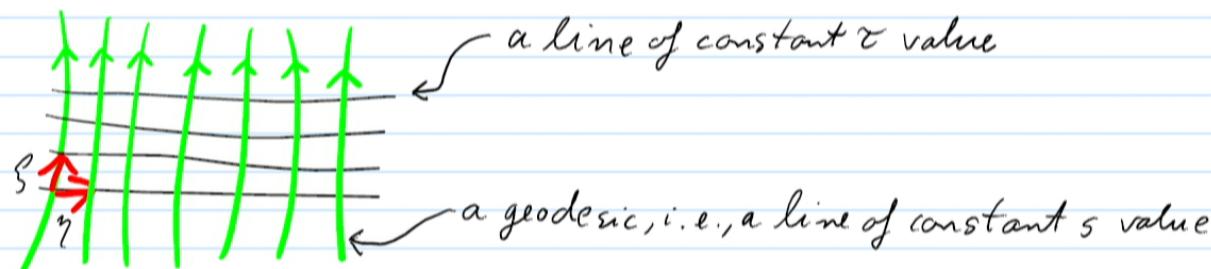
$$x(\tau, s)$$

τ parameter of family of neighboring geodesics.

↙ a "connecting vector field"

Then, we define the deviation vector :

$$\eta := \frac{d}{ds}$$



□ How does η change along a geodesic?

τ, s are Riemann normal coordinates for a geodesic traveller.

$$\Rightarrow \frac{d}{d\tau} \frac{d}{ds} = \frac{d}{ds} \frac{d}{d\tau}, \text{ i.e., } [\xi, \eta] = 0$$

□ Since the torsion vanishes: $0 = T(\xi, \eta) = \nabla_\xi \eta - \nabla_\eta \xi - [\xi, \eta]$

$$\Rightarrow \nabla_\xi \eta = \nabla_\eta \xi$$

$$\Rightarrow \xi^\nu \nabla_{e_\nu} \eta^\alpha e_\alpha = \eta^\alpha \nabla_{e_\alpha} \xi^\nu e_\nu$$

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$$\Rightarrow \xi^\nu \eta^\alpha = \eta^\alpha \xi^\nu = \eta^\alpha B^\nu_\nu \text{ for } B^\nu_\nu := \xi^\nu$$

\Rightarrow Along the geodesic's direction, ξ , the deviation vector η^ν changes its direction and length by $B^\nu_\nu \eta^\nu$.

□ The tensor B^ν_ν can be decomposed covariantly and uniquely into:

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□ The tensor $B_{\mu\nu}$ can be decomposed covariantly and uniquely into:

$$B_{\mu\nu} = \omega_{\mu\nu} + g_{\mu\nu} + t_{\mu\nu}$$

Symmetric and trace = 0
↓
anti-symmetric ↑ rest

(all 3 terms are tensors
because the split is covariant)

Cosmic ballet tensor field.

We have: $\omega_{\mu\nu} = \frac{1}{2}(B_{\mu\nu} - B_{\nu\mu})$, clearly.

But $g_{\mu\nu}, t_{\mu\nu} = ?$

In preparation: define the projector $h_{\mu\nu}$ onto $(R\xi)^\perp$ i.e.
onto the spatial components:

$$h_{\mu\nu} := g_{\mu\nu} + \xi_\mu \xi_\nu$$

$$B_{\mu\nu} = \omega_{\mu\nu} + G_{\mu\nu} + t_{\mu\nu}$$

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In preparation: define the projector $h_{\mu\nu}$ onto $(R\zeta)^\perp$ i.e.
onto the spatial components:
 ζ is timelike

$$h_{\mu\nu} := g_{\mu\nu} + \zeta_\mu \zeta_\nu$$

Check: is $h_{\mu\nu} w^\nu$ really always \perp to ζ ?

$$\text{Indeed: } \ell' h_{\mu\nu} w^\nu = (\zeta, w) + \overbrace{\ell \cdot \ell}^{\perp \zeta} (\zeta, w) = 0$$

$$B_{\mu\nu} = \omega_{\mu\nu} + \overset{\downarrow}{G_{\mu\nu}} + \overset{\uparrow}{t_{\mu\nu}} \quad \begin{matrix} \text{(all 3 terms are tensors)} \\ \text{(because the split is covariant)} \end{matrix}$$

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antisymmetric
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$$\text{Indeed: } \xi^\mu h_{\mu\nu} w^\nu = (\xi, w) + \overset{\zeta = -1}{(\xi, \xi)} (\xi, w) = 0$$

Define: The "expansion", Θ , is defined as the magnitude of the spatial part of B :

$$\Theta := B^{\mu\nu} h_{\mu\nu}$$

Claim: $\text{Tr}(B) = \Theta$

Indeed: $\Theta = B^{\mu\nu} h_{\mu\nu} = B^{\mu\nu} g_{\mu\nu} + \xi^\mu \xi_\nu B_\mu^\nu$

$$= \text{Tr}(B) + \xi^\mu \xi_\nu \underbrace{\nabla_\mu \xi^\nu}_{(=0 \text{ because } \nabla_\mu \xi^\nu = 0 \text{ for geodesics.})}$$

Therefore: $\sigma_{\mu\nu} = \frac{1}{2} (B_{\mu\nu} + B_{\nu\mu}) - \frac{1}{3} \Theta h_{\mu\nu}$ $\left(\begin{array}{l} \text{because:} \\ \text{Tr}(h_{\mu\nu}) = g^{\mu\nu} h_{\mu\nu} \\ = g^{\mu\nu} (g_{\mu\nu} + \xi_\mu \xi_\nu) \\ = g^{\mu\nu} \xi_\mu \xi_\nu \end{array} \right)$

↑ the part of $B_{\mu\nu}$ which is symmetric and traceless.

and:

$$t_{\mu\nu} = \frac{1}{3} \Theta h_{\mu\nu} \quad \leftarrow \text{the "rest term".}$$

□ Interpretation:

a.) $\omega_{\mu\nu}$ is antisymmetric: $\omega_{\mu\nu} = -\omega_{\nu\mu}$
 \Rightarrow it generates Lorentz transformation for γ .
but all γ are \perp to the time direction

$\Rightarrow \omega_{\mu\nu}$ generates spatial rotations of neighbouring geodesics around another. So, $\omega_{\mu\nu}$ is called
 ω "Twists tensor"

One can prove: (nontrivial)

If one chooses the congruence of geodesics \perp to Σ then $\omega_{\mu\nu} = 0$.

b.) $\mathcal{G}_{\mu\nu}$ is symmetric, $\mathcal{G}_{\mu\nu} = \mathcal{G}_{\nu\mu}$. (i.e. hermitian)

Consider "diagonalized", by suitable choice of cd basis.

$\Rightarrow \mathcal{G}_{\mu\nu}$ changes the relative lengths of the basis vectors, by multiplying them with its eigenvalues.

i.e. points on a sphere will under geodesic flow \rightarrow become points on an ellipsoid.

Note: Since $\text{Tr}(\mathcal{G})=0$ we have $\det(\mathcal{e}^{\omega\sigma}) = 1$

infinitesimal transport along geodesics

limit transport

\Rightarrow The volume spanned by basis vectors stays the same under the action of \mathcal{G} .

\rightsquigarrow Definition: $\mathcal{G}_{\mu\nu} =:$ "Shear tensor" $\square \rightarrow \square$

c.) While the twist and shear tensors are both traceless and therefore volume-preserving, we see that the trace part, Θ , i.e., more precisely

$$t_{\mu\nu} = \frac{1}{3} \Theta h_{\mu\nu} =: \text{"Expansion tensor"}$$

\nwarrow recall: is projector on spatial part.

is indeed generating the spatial expansion or contraction of nearby geodesics!

Evolution of Θ along a geodesic?

Recall:

Given, in particular, the strong energy condition, our singularity theorem claimed that geodesics meet a divergence of a quantity called expansion, Θ , in finite proper time in the past and this will mean a big bang singularity:

The "expansion", Θ : \checkmark important notion also e.g. in study of grav. collapse of stars.

□ Consider a "congruence of timelike geodesics"

e.g., freely falling dust.

through Σ , i.e., a smooth family of timelike geodesics,

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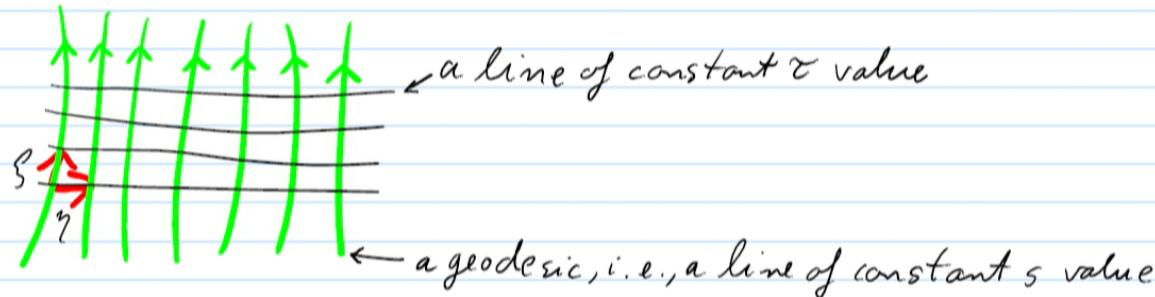
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$$y(\tau, s)$$

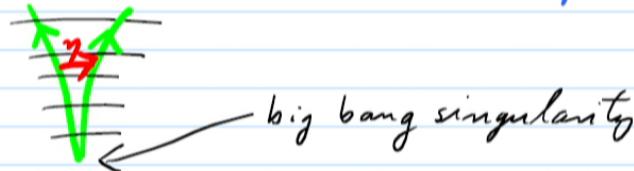
↑ τ parameter of family of neighboring geodesics.
eigentime



□ Then, we define the deviation vector to a neighboring geodesic:

$$\eta := \frac{d}{ds}$$

□ The singularity theorem claims that this happened in the past:



How does η change along a past-directed timelike geodesic with tangent ξ ?

We showed:

$$\xi^\mu \dot{\gamma}_{;\nu} = \dot{\gamma}^\mu B^\nu_\mu \text{ where } B^\nu_\mu := \dot{\gamma}^\nu_{;\mu}$$

\Rightarrow Along the geodesic, ξ , the deviation vector η' changes its direction and length by $B^\nu_\mu \eta^\mu$.

□ The tensor B^ν_μ can be decomposed covariantly and uniquely:

$$B_{\mu\nu} = \underset{\substack{\text{antisymmetric} \\ \uparrow}}{\omega_{\mu\nu}} + \underset{\downarrow}{G_{\mu\nu}} + \underset{\substack{\text{rest} \\ \uparrow}}{t_{\mu\nu}}$$

Symmetric and trace = 0

□ The tensor B^v_{μ} can be decomposed covariantly and uniquely:

$$B_{\mu\nu} = \underset{\text{antisymmetric}}{\omega_{\mu\nu}} + \underset{\text{Symmetric and trace = 0}}{\sigma_{\mu\nu}} + \underset{\text{rest}}{t_{\mu\nu}}$$

Explicitly:

$$\omega_{\mu\nu} = \frac{1}{2} (B_{\mu\nu} - B_{\nu\mu})$$

Volume preserving \rightarrow

$$\sigma_{\mu\nu} = \frac{1}{2} (B_{\mu\nu} + B_{\nu\mu}) - \frac{1}{3} \Theta h_{\mu\nu}$$

$$t_{\mu\nu} = \frac{1}{3} \Theta h_{\mu\nu}$$

Twist: $\circ \rightarrow \circ$

Shear: $\circ \rightarrow \parallel$

Expansion: $\circ \rightarrow \bigcirc$

Explicitly:

$$\omega_{\mu\nu} = \frac{1}{2} (B_{\mu\nu} - B_{\nu\mu}) \quad \text{Twist: } \circ \rightarrow \circ$$

$$\text{Volume preserving} \rightarrow \sigma_{\mu\nu} = \frac{1}{2} (B_{\mu\nu} + B_{\nu\mu}) - \frac{1}{3} \Theta h_{\mu\nu} \quad \text{Shear: } \circ \rightarrow \square$$

$$\text{Volume changing: } t_{\mu\nu} = \frac{1}{3} \Theta h_{\mu\nu} \quad \text{Expansion: } \circ \rightarrow \bigcirc$$

Here, we defined: $\Theta := B^{\mu\nu} g_{\mu\nu}$ and $h_{\mu\nu} := g_{\mu\nu} + \xi_\mu \xi_\nu$

I.e., the Expansion, Θ , is the trace of B , which we showed is also equal to the magnitude of the spatial part of B : $\Theta = B^{\mu\nu} h_{\mu\nu}$.

Key question:

What is the dynamics of Θ ?

The Raychaudhuri equation

For the derivation, we will use:

A) Definition of B is: $B_{\mu\nu} := \zeta_{\mu;\nu}$

B) The curvature tensor obeys the Ricci equation:

$$\zeta^a{}_{jbc} - \zeta^a{}_{jcb} = R^a{}_{bcd} \zeta^d$$

c) ζ is tangent to a geodesic, i.e., it obeys: $\nabla_\zeta \zeta = 0$

$$\text{i.e.: } 0 = \nabla_a \zeta^b e_b = \zeta^a \nabla_a \zeta^b e_b = \zeta^a \zeta^b{}_{;a} e_b$$

True for all e_a , thus: $\boxed{\zeta^a \zeta^b{}_{;a} = 0}$

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True for all e_a , thus: $\boxed{\xi^a \xi^b_{;a} = 0}$

Now calculate the rate of change of B along the geodesic:

$$\begin{aligned} \xi^c B_{ab;c} &\stackrel{(A)}{=} \xi^c \xi_{a;bc} \\ &\stackrel{(B)}{=} \xi^c \xi_{a;cb} + \xi^c R_{abcd} \xi^d \end{aligned}$$

$$\stackrel{\text{Leibniz rule}}{=} \underbrace{(\xi^c \xi_{a;c})}_{\parallel b} - \xi_{jb} \xi_{a;c} + R_{abcd} \xi^c \xi^d$$

$$\stackrel{(C)}{=} -\xi_{jb} \xi_{a;c} + R_{abcd} \xi^c \xi^d$$

$$\stackrel{(A)}{=} -B^c{}_b B_{ac} + R_{abcd} \xi^c \xi^d$$

In summary, we derived:

$$\xi^c B_{ab;c} = -B^c_b B_{ac} + R_{abcd} \xi^c \xi^d \quad (*)$$

The trace of (*) will be the Raychaudhuri equation.

But first, we recall:

$$\square \quad \xi = \frac{d}{dt}$$

$$\square \quad \text{Tr } B = B_{\mu\nu} g^{\mu\nu} = \Theta$$

\Rightarrow Trace(LHS) of (*) reads $\frac{d}{dt} \Theta$!

Now on the RHS of (*) use the decomposition

$$B_{\mu\nu} = \omega_{\mu\nu} + \sigma_{\mu\nu} + \frac{1}{3} \Theta h_{\mu\nu} \text{ to express } B^c_b B_{ac}:$$

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$$B^c{}_b B_{ac} = \omega^c{}_b (\underline{\omega_{ac}} + \sigma_{ac} + \frac{1}{3}\Theta h_{ac})$$

$$+ G^c{}_b (\underline{\omega_{ac}} + \underline{G_{ac}} + \frac{1}{3}\Theta h_{ac})$$

$$+ \frac{1}{3}\Theta h^c{}_b (\underline{\omega_{ac}} + \underline{G_{ac}} + \underline{\frac{1}{3}\Theta h_{ac}})$$

When taking the trace, $g^{ab} B^c{}_b B_{ac}$, only the diagonal terms survive:

$$\text{Tr}(BB) = g^{ab} B^c{}_b B_{ac} = \omega_{ab} \omega^{ab} + G_{ab} G^{ab} + \underbrace{\frac{1}{9}\Theta^2 h_{ab} h^{ab}}_{\substack{3 \\ \text{Exercise:} \\ \text{show it is 3}}}$$

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Exercise:
show it is 3

The Raychandhuri equation is then the trace of Eq. (*) :

$$\frac{d\Theta}{d\tau} = -\frac{1}{3} \Theta^2 - \underbrace{G_{ab} G^{ab}}_{\text{always positive}} - \underbrace{\omega_{ab} \omega^{ab}}_{\text{always positive (and vanishes if choose congruence } \perp \Sigma)} - \underbrace{R_{cd} \bar{\zeta}^c \bar{\zeta}^d}_{\text{pos. or neg? ?}}$$

recall: Ricci tensor is
 $\checkmark R_{cd} = R_{da}{}^a$

In summary, we derived:

$$\xi^c B_{ab;c} = -B^c_b B_{ac} + R_{abcd} \xi^c \xi^d \quad (*)$$

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Dynamics

□ Assume that

$$R_{\mu\nu}\xi^\mu\xi^\nu \geq 0 \text{ for all timelike } \xi$$

i.e., using the Einstein equation

$$R_{\mu\nu} = 8\pi G (T_{\mu\nu} - \frac{1}{2}g_{\mu\nu}T^a_a)$$

we are assuming that

$$T_{\mu\nu}\xi^\mu\xi^\nu - \frac{1}{2}\xi^\mu\xi_\mu T \geq 0 \text{ whenever } \xi^\mu\xi_\mu < 0$$

i.e. the Strong Energy Condition.

Thus, assuming the strong energy condition:

$$\frac{d\theta}{d\tau} + \frac{1}{3}\theta^2 \leq 0$$

$$\text{i.e., } -\frac{1}{\theta^2} \frac{d\theta}{d\tau} - \frac{1}{3} \geq 0$$

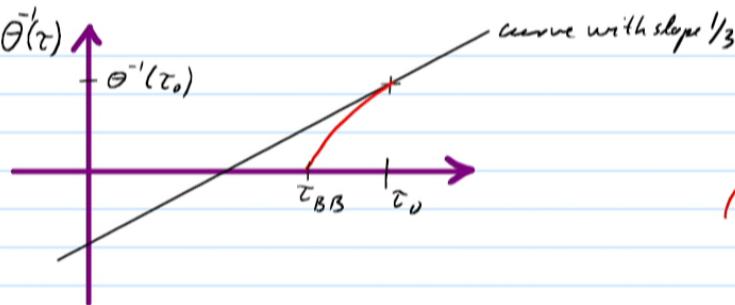
$$\text{i.e., } \boxed{\frac{d}{d\tau} \theta^{-1} \geq \frac{1}{3}} \quad (\dagger)$$

Consider the cases when the geodesics are initially all either

- a.) diverging, i.e., $\theta(\tau_0) > 0$ (expanding universe) or
- b.) converging, i.e., $\theta(\tau_0) < 0$ (contracting universe)

(This is reformulating the theorem's assumption that the extrinsic curvature (i.e. the expansion or contraction at some time exceeds a certain finite value everywhere)

a.)



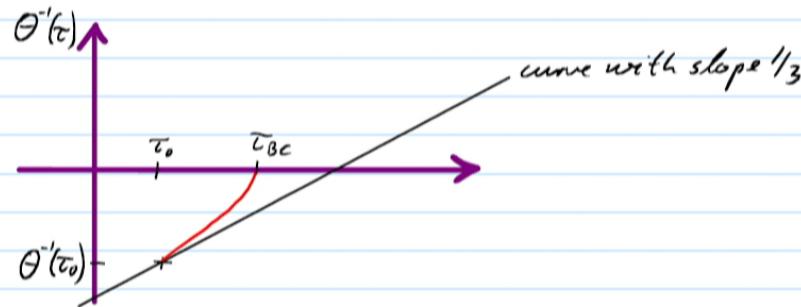
curve with slope $1/3$

τ_0 = e.g. today

red = curve $\Theta'(\tau)$ of slope $> \frac{1}{3}$

We see that $\Theta'(\tau)$ must have hit $\Theta'(\tau) = 0$ at a finite time τ_{BB} (Big Bang).

b.)



curve with slope $1/3$

τ_0 = e.g. today

red = curve of slope $< \frac{1}{3}$

We see that $\Theta'(\tau)$ will hit $\Theta'(\tau) = 0$ at a finite time τ_{BC} (Big Crunch)

Conclusion:

Eq. (+) implies that $\dot{\Theta}(\tau)$ must go through 0, i.e.:

- a.) for sufficiently early τ , have $\Theta \rightarrow +\infty$, i.e.: Big Bang
- b.) for sufficiently late τ , have $\Theta \rightarrow -\infty$, i.e.: Big Crunch

Note:

This type of reasoning leads also to further cosmological singularity theorems.

E.g., another cosmological singularity theorem does not assume global hyperbolicity, and its conclusion is weaker:

There is at least one incomplete timelike geodesic.

Results, e.g., regarding types of cosmic singularity?

- Assume a set of symmetries of matter and spacetime has been chosen.
- Assume an exact solution or at least its asymptotic properties at early times have been found.
- Assume, we choose a timelike congruence e.g. of geodesics.

⇒ We can now explicitly calculate the twist, shear and expansion along the congruence :