Title: Spekkensâ $€^{\text {TM }}$ toy model in all dimensions and its relationship with stabiliser quantum mechanics
Date: Jul 04, 2017 03:30 PM
URL: http://pirsa.org/17070000
Abstract: < $\mathrm{p}>$ In this talk I am going to describe Spekkensâ $€^{\mathrm{TM}} \& \mathrm{nbsp}$;toy model, a non-contextual hidden variable model with an epistemic restriction, a\ constraint on what an observer can know about reality. The aim of the model, developed for\ continuous and discrete prime degrees of freedom, is to advocate the epistemic view of quantum\ theory, where quantum states are states of incomplete knowledge about a deeper underlying reality. In spite of its classical flavour, many aspects that were thought to belong only to quantum mechanics can be reproduced in\ the model.\ </p>
<p>I am\ going to describe our results regarding the<em>\ formulation of\ rules for the update of states after measurement</em> I will do it for systems of discrete prime dimensions and I will then give the idea on how to proceed in the non-prime dimensional case.\ </p>
$<p>I$ will also depict the relationship between Spekkensâ $€^{\mathrm{TM}}$ model, stabiliser quantum mechanics and Gross' theory of discrete Wigner functions (they are equivalent theories in odd dimensions) in terms of measurement update rules.</p>
$<\mathrm{p}>\mathrm{I}$ will conclude by briefly discussing a project we have been recently working on that consists of characterising sub theories of\ Spekkensâ $€^{\mathrm{TM}}$ model that are operationally equivalent to\ sub theories of QM (in particular in the case of qubits) and use them to represent the non-contextual classically simulable part\ of state-injection schemes of computation with contextuality as a resource.</p>

# Spekkens' toy model in all dimensions and its relationship with stabiliser quantum mechanics 

arXiv:1701.07801 (2017).

Lorenzo Catani, Dan Browne
University College London

- Motivations
- Introduction to Spekkens' toy model
- Bit case (d=2)
- General case
- Measurement update rules
- Prime dimensions
- Non-prime dimensions
- Relationship with stabiliser quantum mechanics
- Spekkens' sub-theories compatible with QM
- Conclusions
- Future directions
- What does a quantum state describe?
- What does a quantum state describe?
- Classify the inherent non-classical features.


## Spekkens' Toy Model

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## Spekkens toy model

Model to support the epistemic view of QT.

Quantum mechanics


Elementary system: 1 bit


## Spekkens' Toy Model

## Epistemic restriction

## Knowledge balance principle:

When the observer has the maximum knowledge about reality, his amount of knowledge has to equal his ignorance.


The observer can at maximum answer one of the two questions.

## Spekkens' Toy Model

## Elementary system: 1 bit



Ontic states $=$ states of reality


Epistemic states $=$ states of (incomplete) knowledge


## Spekkens＇Toy Model

## Epistemic states of one bit



## Spekkens' Toy Model

Transformations
Permutations of the ontic states


## Spekkens' Toy Model

## Epistemic states of couple of bits

Maximal knowledge states

Uncorrelated state


Perfectly correlated state


## Spekkens' Toy Model

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## Epistemic states of couple of bits

Maximal knowledge states

Uncorrelated state


Maximum knowledge of the individual ontic states.

Perfectly correlated state

$\longleftrightarrow$ Maximum knowledge of
trade-off
-

No classical analogue

## Epistemic states of couple of bits

Maximal knowledge states



Perfectly correlated state


## Spekkens' Toy Model

## Phase-space formalism

- Phase space $\Omega \equiv \mathbb{Z}_{d}^{2 n} ; \quad \mathrm{d}=$ dimension, $\mathrm{n}=$ number of systems.
- Quadrature variables $X_{j}, P_{j}$
- Ontic states $\lambda \in \Omega . \longrightarrow$ Vectorial representation: $\lambda=\left(x_{0}, p_{0}, \ldots, x_{n-1}, p_{n-1}\right)$.
- Observables $\Sigma=\sum_{m}\left(a_{m} X_{m}+b_{m} P_{m}\right) . \longrightarrow$ Vec. representation: $\boldsymbol{\Sigma}=\left(a_{0}, b_{0}, \ldots, a_{n-1}, b_{n-1}\right)$
- Outcomes $\sigma=\boldsymbol{\Sigma}^{T} \lambda=\sum_{j}\left(a_{j} x_{j}+b_{j} p_{j}\right)$. Inner product.


## Spekkens' Toy Model

## Epistemic restriction

## Classical complementarity (C.C.) principle

The observer can at maximum jointly know the values of a set of variables that Poisson commute.

Poisson commute means that the symplectic inner product is zero:

$$
\left\langle\boldsymbol{\Sigma}_{\mathbf{1}}, \boldsymbol{\Sigma}_{\mathbf{2}}\right\rangle \equiv \boldsymbol{\Sigma}_{\mathbf{1}}^{T} J \boldsymbol{\Sigma}_{\mathbf{2}}=0, \text { where } J=\bigoplus_{j=1}^{n}\left[\begin{array}{cc}
0 & 1 \\
-1 & 0
\end{array}\right]_{j} .
$$

## Spekkens' Toy Model

## Epistemic states

- Defined by $(V, \mathbf{w})$.
- $V=\operatorname{span}\left\{\Sigma_{1}, \ldots, \Sigma_{n}\right\} \subseteq \Omega$. Isotropic subspace of known variables.
- $\mathbf{w}$ is such that $\boldsymbol{\Sigma}_{j}^{T} \mathbf{w}=\sigma_{j}$. Evaluation vector.
- The set of ontic states consistent with the epistemic state $(V, \mathbf{w})$ is $V^{\perp}+\mathbf{w}$.


## Spekkens' Toy Model

## Epistemic states

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- The set of ontic states consistent with the epistemic state $(V, \mathbf{w})$ is $V^{\perp}+\mathbf{w}$.
- The associated uniform probability distribution is

$$
P_{(V, \mathbf{w})}(\lambda)=\frac{1}{d^{n}} \delta_{V^{\perp}+\mathbf{w}}(\lambda)
$$

## Spekkens' Toy Model

## Valid Transformations

Symplectic affine transformations: $\lambda \rightarrow S \lambda+\mathbf{a}$

Epistemic restriction preserved: $(S \lambda)^{T} J\left(S \lambda^{\prime}\right)=\lambda^{T} J \lambda^{\prime}, \forall \lambda, \lambda^{\prime} \in \Omega$.

Associated probability distribution: $\Gamma_{S, \mathbf{a}}\left(\lambda \mid \lambda^{\prime}\right)=\delta_{S \lambda^{\prime}+\mathbf{a}}(\lambda)$.

## Spekkens' Toy Model

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## Valid Measurements

The elements of a measurement are represented as epistemic states.

Example: One trit - measure of the observable $\Pi=X$.


## Spekkens' Toy Model

## Operational statistics

Probability of obtaining outcome $k \in V_{\Pi}$ :

$$
P(k)=\sum_{\lambda, \lambda^{\prime} \in \Omega} P_{\left(V_{\Pi}, \mathbf{r}_{k}\right)}(k \mid \lambda) \Gamma_{(S, \mathbf{a})}\left(\lambda \mid \lambda^{\prime}\right) P_{(V, \mathbf{w})}\left(\lambda^{\prime}\right)
$$



TABLE II: Categorization of quantum phenomena.

Quasi-quantization: classical statistical theories with an epistemic restriction, R. W. Spekkens Fund. TheoryPhys,181(2016)

## Result

Spekkens' model is operationally equivalent to SQM in odd dimensions.

## $\downarrow$ <br> Proven through Gross' Wigner functions.

## Contents

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- Prime dimensions
- Non-prime dimensions
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- Spekkens' subtheories compatible with QM
- Conclusions
- Future directions


## Measurement update rules - prime case

$$
\begin{aligned}
& \text { State } \\
& (V, \mathbf{W}),(\sqrt{\Pi}, \mathbf{r}) \rightarrow\left(\nabla^{\prime}, \mathbf{W}^{\prime}\right)
\end{aligned}
$$

## Measurement update rules - prime case



Classical complementarity implies that we can learn only the generators of the state that commute with the measurement.


State after measurement given by the generators of the measurement and the generators of the original state that commute with them.

## Measurement update rules - prime case

## Adding/Removing generators

- Adding a generator $\Sigma^{\prime}$ to $V=\operatorname{span}\left\{\Sigma_{1}, \Sigma_{2}, \ldots, \Sigma_{n}\right\}$ :

$$
V^{\prime}=V \oplus \operatorname{span}\left\{\Sigma^{\prime}\right\} \quad \longrightarrow \quad V^{\prime \perp}=V^{\perp} \cap\left(\operatorname{span}\left\{\Sigma^{\prime}\right\}\right)^{\perp}
$$

- Removing a generator, say $\Sigma_{n}$, from $V=\operatorname{span}\left\{\Sigma_{1}, \Sigma_{2}, \ldots, \Sigma_{n}\right\}$ :
$V^{\prime}=\operatorname{span}\left\{\Sigma_{1}, \ldots, \Sigma_{n-1}\right\}$


## Measurement update rules - prime case

## Adding/Removing generators

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$$
V^{\prime}=\operatorname{span}\left\{\Sigma_{1}, \ldots, \Sigma_{n-1}\right\} \quad \Longrightarrow \quad V^{\prime \perp}=V^{\perp} \oplus V_{n}
$$

Proof.
$V^{\prime \perp}$ given by all $\lambda$ such that $\boldsymbol{\Sigma}_{j}^{T} \lambda=0$ for all $j<n$, but $\boldsymbol{\Sigma}_{n}^{T} \lambda \neq 0$.
Need to add $\lambda^{\prime}=c \gamma$ to $V^{\perp}$, where $c \in \mathbb{Z}_{d} \neq 0$ and $\gamma$ such that $\Sigma_{n}^{T} \gamma=1$.
$\Sigma_{n}^{T}\left(\lambda+\lambda^{\prime}\right)=\Sigma_{n}^{T}(\lambda+c \gamma)=0+c \neq 0$.

## Measurement update rules - prime case

## Adding/Removing generators

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$\Sigma_{n}^{T}\left(\lambda+\lambda^{\prime}\right)=\Sigma_{n}^{T}(\lambda+c \gamma)=0+c \neq 0$.
$V^{\prime \perp}=\bigcup_{c}\left(V^{\perp}+c \gamma\right) \equiv \bigcup_{w_{n} \in V_{n}}\left(V^{\perp}+w_{n}\right)=V^{\perp} \oplus V_{n}$.

Commuting (non-disturbing) case

$$
\text { - } V^{\prime \perp}=\left(V^{\perp}+\mathbf{w}-\mathbf{w}^{\prime}\right) \cap\left(V_{\Pi}^{\perp}+\mathbf{r}-\mathbf{w}^{\prime}\right)
$$



## Measurement update rules - prime case

## Commuting (non-disturbing) case

- $V^{\prime \perp}=\left(V^{\perp}+\mathbf{w}-\mathbf{w}^{\prime}\right) \cap\left(V_{\Pi}^{\perp}+\mathbf{r}-\mathbf{w}^{\prime}\right)$
- $\mathbf{w}^{\prime}=\mathbf{w}+\sum_{i} \mathbf{\Sigma}_{i}^{\prime T}(\mathbf{r}-\mathbf{w}) \gamma_{i}, \quad \boldsymbol{\Sigma}^{\prime}{ }_{i}^{T} \gamma_{i}=1$.

Proof.
Let us assume only one generator of the measurement, $\Sigma^{\prime}$, whose associated outcome is $\sigma^{\prime}$.
Say $\mathbf{w}$ not compatible with this outcome, then $\mathbf{\Sigma}^{\prime T} \mathbf{w}=\sigma^{\prime}+x$, where $x \in \mathbb{Z}_{d}$.
We want $\mathbf{w}^{\prime}$ such that $\boldsymbol{\Sigma}^{\prime T} \mathbf{w}^{\prime}=\sigma^{\prime}$.
$\mathbf{w}^{\prime}=\mathbf{w}-x \gamma$, where $\Sigma^{\prime T} \gamma=1$.

## Measurement update rules - prime case

## Commuting (non-disturbing) case

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We want $\mathbf{w}^{\prime}$ such that $\boldsymbol{\Sigma}^{\prime T} \mathbf{w}^{\prime}=\sigma^{\prime}$.
$\mathbf{w}^{\prime}=\mathbf{w}-x \gamma$, where $\Sigma^{\prime T} \gamma=1$.
Therefore $\mathbf{w}^{\prime}=\mathbf{w}+\left(\sigma^{\prime}-\mathbf{\Sigma}^{\prime T} \mathbf{w}\right) \gamma=\mathbf{w}+\mathbf{\Sigma}^{\prime T}(\mathbf{r}-\mathbf{w}) \gamma$.
In prime dimensions $\gamma=k^{-1} \boldsymbol{\Sigma}^{\prime}$, where $k=\boldsymbol{\Sigma}^{\prime T} \boldsymbol{\Sigma}^{\prime}$.

## Commuting (non-disturbing) case

Simple example:


Nothing known

Measurement
$\left(V_{\Pi}, \mathbf{r}\right)$

$P=0$

State after measurement $\left(V^{\prime}, \mathbf{w}^{\prime}\right)$

$\mathrm{P}=0$

## Non-commuting (disturbing) case

- $V^{\prime \perp}=\left(V_{\text {commute }}^{\perp}+\mathbf{w}-\mathbf{w}^{\prime}\right) \cap\left(V_{\Pi}^{\perp}+\mathbf{r}-\mathbf{w}^{\prime}\right)$
$V_{\text {commute }}^{\perp}=V^{\perp} \oplus V_{\text {other }}$,
$V=V_{\text {commute }} \oplus V_{\text {other }}$.


## Measurement update rules - prime case

Recap and issues

Prime dimensions. $\quad$ Non disturbing case $\quad V \rightarrow V^{\prime}=V \oplus V_{\Pi}$

$$
V^{\perp} \rightarrow V^{\prime \perp}=V^{\perp} \cap V_{\Pi}^{\perp}
$$

## Measurement update rules - prime case

## Recap and issues

Prime dimensions. Non disturbing case

$$
\begin{aligned}
& V \rightarrow V^{\prime}=V \oplus V_{\Pi} \\
& V^{\perp} \rightarrow V^{\prime \perp}=V^{\perp} \cap V_{\Pi}^{\perp}
\end{aligned}
$$

Disturbing case

$$
\begin{aligned}
& V^{\perp} \rightarrow V^{\prime \perp}=V \text { ©ommut } \cap \square \\
& V_{\text {commute }}^{\perp}=\bigcup\left(V^{\perp}+c \gamma\right) .
\end{aligned}
$$

Updated shift vector
$\mathbf{w} \rightarrow \mathbf{w}^{\prime}=\mathbf{w}-x \gamma$
$\Sigma^{\prime T} \gamma=1$

## Problematic observables

Example

| 位 |  | Epistemic state |
| :---: | :---: | :---: |
|  |  | $5{ }_{5}{ }^{\text {¢ }}$ |
|  |  | 4 |
| Coarse-graining observable | $3 X=0$ | ${ }_{2}^{3}$ |
|  |  | $1-1-1$ |
|  |  | $\bigcirc-1-1-\square$ |

## Measurement update rules - non prime case

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## Problematic observables

Coarse graining observable $=O_{c g}=a X+b P=D\left(a^{\prime} X+b^{\prime} P\right), D$ shared by $a, b$.
Fine graining observables $=O_{f g}=a^{\prime} X+b^{\prime} P \Longleftrightarrow \gamma$ exists.

Example

Coarse-graining observable
$3 X=0$


Fine-graining observables

Epistemic state

$X=2$


$$
d=6
$$

$$
X=4
$$



## States and Measurements

Stabilizer state $=$ joint eigenstates of a set of commuting pauli operators.

## Stabilizer quantum mechanics

## States and Measurements

Stabilizer state $=$ joint eigenstates of a set of commuting pauli operators.
1
$\rho=\rho_{1} \cdot \rho_{2} \cdots \rho_{n}, \quad \rho_{j}=\left(\mathbb{I}_{d}+g_{j}+g_{j}^{2}+\cdots+g_{j}^{d-1}\right)$.
$\downarrow$
$\rho \rightarrow\left\langle g_{1}, \ldots, g_{n}\right\rangle$

## Transformations

Clifford group (unitary representation of the symplectic affine group)

- Map Pauli to Pauli
- Preserve commuting relations


## Stabilizer quantum mechanics

## Gross' theory

- Theorem (d=Odd) : Pure state + non-negative W.f. $\longleftrightarrow$ Stabilizer state.
- Stabilizer Wigner function $W_{\rho}(\lambda)=\operatorname{Tr}(\rho A(\lambda))=\frac{1}{d^{n}} \delta_{M^{C}+\mathbf{w}}(\lambda)$.


## Equivalence of the theories

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## Equivalence of the theories

Wigner functions of stabilizer states = Spekkens epistemic states.

$$
P_{(V, \mathbf{w})}(\lambda)=\frac{1}{d^{n}} \delta_{V^{\perp}+\mathbf{w}}(\lambda)=W_{(M, \mathbf{w})}(\lambda)=\frac{1}{d^{n}} \delta_{M^{C}+\mathbf{w}}(\lambda)
$$

$$
\uparrow
$$

$$
M=J V
$$

## Equivalence of the theories

## Measurement update rules

- Non-disturbing (commuting) case

$$
\begin{array}{cc}
V^{\perp} \rightarrow V^{\prime \perp}=V^{\perp} \cap V_{\Pi}^{\perp} & \longleftrightarrow
\end{array} W_{\rho^{\prime}}(\lambda)=\frac{1}{N} W_{\rho}(\lambda) R_{\Pi}(\lambda)
$$

## Equivalence of the theories - prime case

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|  | Non-disturbing Measurements <br> (Localization stage) $\lfloor\rho, \Pi\rfloor=0$ | Disturbing Measurements <br> (Localization + randomization stage) $[\rho, \Pi] \neq 0$ |
| :---: | :---: | :---: |
| Stabilizer Quantum Mechanics | $\begin{aligned} \rho & \rightarrow\left\langle g_{1}, \ldots, g_{N}\right\rangle \\ \Pi & \rightarrow\left\langle p_{1}, \ldots, p_{M}\right\rangle \end{aligned}$ <br> Add generators $\rho^{\prime} \rightarrow\left\langle g_{1}, g_{2}, \ldots, g_{N}, p_{1}, p_{2}, \ldots, p_{M}\right\rangle$ | $\begin{gathered} \rho \rightarrow\left\langle g_{1}, \ldots, g_{N}\right\rangle \\ \Pi \rightarrow\left\langle p_{1}, \ldots, p_{M}\right\rangle \\ \text { Add generators } \downarrow \text { Remove } \mathrm{g}_{\mathrm{N}} \\ \rho^{\prime} \rightarrow\left\langle g_{1}, g_{2}, \ldots, g_{N-1}, p_{1}, p_{2}, \ldots, p_{M}\right\rangle \end{gathered}$ |
| Spekkens Theory | $\begin{gathered} V^{\prime}=V \oplus V_{\Pi} \\ V^{\prime \perp}=V^{\perp} \cap V_{\Pi}^{\perp} \\ \mathbf{w}^{\prime}=\mathbf{w}+\sum_{i}^{n} \mathbf{\Sigma}_{i}^{\prime T}(\mathbf{r}-\mathbf{w}) \gamma_{i} \end{gathered}$ | $\begin{aligned} V^{\prime} & =V_{\text {commute }} \oplus V_{\Pi} \\ V^{\prime \perp} & =\left(V^{\perp} \oplus V_{\text {other }}\right) \cap V_{\Pi}^{\perp} \\ \mathbf{w}^{\prime} & =\mathbf{w}+\sum_{i}^{n} \mathbf{\Sigma}_{i}^{\prime T}(\mathbf{r}-\mathbf{w}) \gamma_{i} \end{aligned}$ |
| Wigner Functions | $W_{\rho^{\prime}}(\lambda)=\frac{1}{N} W_{\rho}(\lambda) R_{\Pi}(\lambda)$ | $W_{\rho^{\prime}}(\lambda)=\frac{1}{N} \sum_{\mathbf{t} \in V_{\text {other }}} W_{\rho}(\lambda-\mathbf{t}) R_{\Pi}(\lambda)$ |
|  |  | Lorenzo Catani |



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－Conclusions
－Future directions


## Spekkens' sub-theories compatible with QM

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## Spekkens' sub-theories

A set of q. states, transformations and measurements $(\mathcal{S}, \mathcal{T}, \mathcal{O})$ such that
i. $\quad$ Close subtheory. $\forall U \in \mathcal{T}, U \rho U^{\dagger} \in \mathcal{S} \forall \rho \in \mathcal{S}$.
ii. Spekkens representability. $\exists W_{\rho}, W_{\pi}, P_{U} \geq 0$ such that,
$W_{\rho}(\lambda)=\frac{1}{N} \operatorname{Tr}(\rho A(\lambda))=\frac{1}{N} \delta_{\left(V^{\perp}+\mathbf{w}\right)}$
$W_{\Pi}\left(\mathbf{k} / \lambda^{\prime}\right)=\frac{1}{N^{\prime}} \operatorname{Tr}\left(\Pi_{\mathbf{k}} A(\lambda)\right)=\frac{1}{N^{\prime}} \delta_{\left(V_{\Pi_{k}}+\mathbf{r}\right)}(\lambda)$
$P_{U}\left(\lambda / \lambda^{\prime}\right)=\frac{1}{N^{\prime \prime}} \delta_{\lambda, S \lambda^{\prime}+\mathbf{a}} \quad$ This exists if $W_{\rho}$ is covariant.
$p(\mathbf{k} \mid \rho, U, \Pi)=\frac{1}{N} \operatorname{Tr}\left(\Pi_{k} U \rho U^{\dagger}\right)=\frac{1}{N} \sum_{\lambda \in \Omega} W_{\Pi}(\mathbf{k} / \lambda) \sum_{\lambda^{\prime} \in \Omega} P_{U}\left(\lambda / \lambda^{\prime}\right) W_{\rho}\left(\lambda^{\prime}\right)$

Maximal SS if it is not possible to add any other $\rho, \Pi, U$ without contradicting i), ii).

## Conclusions and future directions

## Conclusions

- Measurement update rules for Spekkens' theory, both prime and non-prime dimensional systems.
- Measurement update rules for Gross Wigner functions.
- Enforced the equivalence between Spekkens' theory and SQM in odd dimensions and depict the equivalence in terms of updating rules.
- What are the sub-theories of Spekkens' model that are compatible with QM (qubit)?
- Use Spekkens' sub-theories to represent the non-contextual cheap part of stateinjection schemes of computation.
$\left\{\prod_{k}\right\}$
Lodk $\rho \stackrel{k}{\longrightarrow} \pi_{k} \rho \Pi_{k}$
$\Pi_{0}=\mid D\langle 0|+|1\rangle\langle 1|$
Lubs $\rho \rightarrow T_{0} \rho \Pi_{0}($ projection $)$
NN $\rho \rightarrow|0\rangle\langle 0| \rho|0\rangle<0|+|D<||\rho| D<1|$
$\square$

