

Title: Monte Carlo methods in Dynamical Triangulations - 3

Date: Jun 22, 2017 08:45 AM

URL: <http://pirsa.org/17060082>

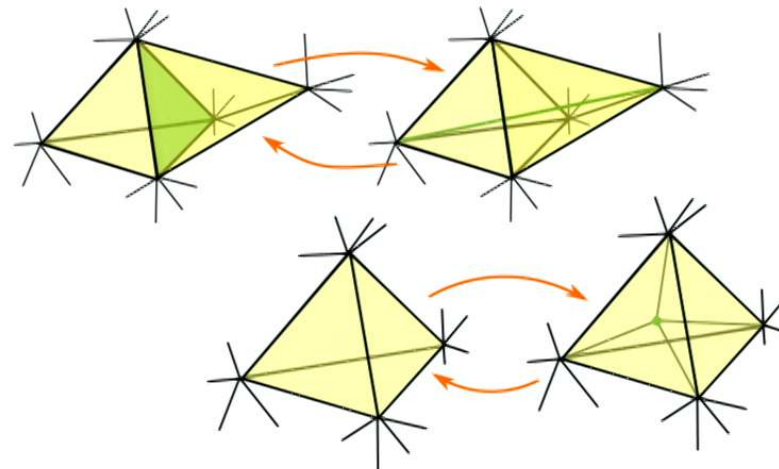
Abstract:

Making Quantum Gravity Computable, 22-06-2017

## Monte Carlo methods in Dynamical Triangulations

Part II: Higher dimensions

Timothy Budd



IPhT, CEA, Université Paris-Saclay

[timothy.budd@cea.fr](mailto:timothy.budd@cea.fr), <http://www.nbi.dk/~budd/>



# Outline

- ▶ Day 1: 2D random geometry
  - ▶ Combinatorial representation
  - ▶ Markov Chain Monte Carlo (MCMC) methods
  - ▶ Matter coupling
  - ▶ Observables
- ▶ Day 2: Dynamical Triangulations in higher dimensions
  - ▶ Quantum gravity
  - ▶ Combinatorial representation
  - ▶ MCMC methods
  - ▶ Phase diagram
  - ▶ Causal Dynamical Triangulations
- ▶ Tutorials: numerical analysis of various 2D random geometries
  - ▶ Measure observables for random geometries (produced by black box)
  - ▶ Extract critical exponents.
  - ▶ Experiment with (new?) observables.
  - ▶ Conclusions will be collected at the end and be discussed.

## A space-time path integral?

$$\int_{\text{Lorentzian metrics}} \frac{d\mu(g_{\alpha\beta})}{\text{Diff}} e^{iS[g_{\alpha\beta}]}$$

Difficulties:

- QFT in perturbative regime: non-renormalizable
- Infinite-dimensional integral
- What is a good diffeo-invariant measure?
- Destructive interference is delicate
- How to interpret integrand?
- Numerical evaluation is hard

## A space-time path integral?

$$\int_{\text{Lorentzian metrics}} \frac{d\mu(g_{\alpha\beta})}{\text{Diff}} e^{iS[g_{\alpha\beta}]} \xrightarrow[\text{Quantum} \rightarrow \text{Statistical}]{\text{Wick rotation?}} \int_{\text{Euclidean metrics}} \frac{d\mu(g_{ab})}{\text{Diff}} e^{-S[g_{ab}]}$$

Lorentzian → Euclidean

### Difficulties:

- QFT in perturbative regime: non-renormalizable
- Infinite-dimensional integral
- What is a good diffeo-invariant measure?
- ~~Destructive interference is delicate~~
- ~~How to interpret integrand?~~ Probability distribution
- Numerical evaluation is hard
- Classical solutions? Action is unbounded below.

## A space-time path integral?


$$\int_{\text{Lorentzian metrics}} \frac{d\mu(g_{\alpha\beta})}{\text{Diff}} e^{iS[g_{\alpha\beta}]} \xrightarrow[\text{Quantum} \rightarrow \text{Statistical}]{\text{Wick rotation?}} \int_{\text{Euclidean metrics}} \frac{d\mu(g_{ab})}{\text{Diff}} e^{-S[g_{ab}]}$$

Lorentzian → Euclidean

### Difficulties:

- QFT in perturbative regime: non-renormalizable
- ~~Infinite-dimensional integral~~
- What is a good diffeo-invariant measure?
- ~~Destructive interference is delicate~~
- ~~How to interpret integrand?~~ Probability distribution
- Numerical evaluation is ~~hard~~ doable in principle
- Classical solutions? Action is unbounded below.
- Does the integral converge?
- Does it possess a continuum limit?

Cut-off



$$\sum_{\{\text{PL geometries } g_{ab}\}} \iint \frac{d\mu(l_i)}{\text{Diff}} e^{-S[g_{ab}]}$$

# A space-time path integral?

$$\int_{\text{Lorentzian metrics}} \frac{d\mu(g_{\alpha\beta})}{\text{Diff}} e^{iS[g_{\alpha\beta}]} \xrightarrow[\text{Quantum} \rightarrow \text{Statistical}]{\text{Wick rotation?}} \int_{\text{Euclidean metrics}} \frac{d\mu(g_{ab})}{\text{Diff}} e^{-S[g_{ab}]}$$

Lorentzian → Euclidean

## Difficulties:

- QFT in perturbative regime: non-renormalizable
- ~~Infinite-dimensional integral~~
- ~~What is a good diffeo-invariant measure?~~
- ~~Destructive interference is delicate~~
- ~~How to interpret integrand?~~ Probability distribution
- Numerical evaluation is ~~hard~~ doable in principle
- Classical solutions? ~~Action is unbounded below.~~
- Does the integral converge?
- Does it possess a continuum limit?

Cut-off

$$\sum_{\{\text{Combinatorial geometries}\}} e^{-S[g_{ab}]} \xleftarrow{\text{Discretize}} \sum \iint \frac{d\mu(l_i)}{\text{Diff}} e^{-S[g_{ab}]}_{\{\text{PL geometries } g_{ab}\}}$$



# A space-time path integral?

$$\int_{\text{Lorentzian metrics}} \frac{d\mu(g_{\alpha\beta})}{\text{Diff}} e^{iS[g_{\alpha\beta}]} \xrightarrow[\text{Quantum} \rightarrow \text{Statistical}]{\text{Wick rotation?}} \int_{\text{Euclidean metrics}} \frac{d\mu(g_{ab})}{\text{Diff}} e^{-S[g_{ab}]}$$

Lorentzian → Euclidean

## Difficulties:

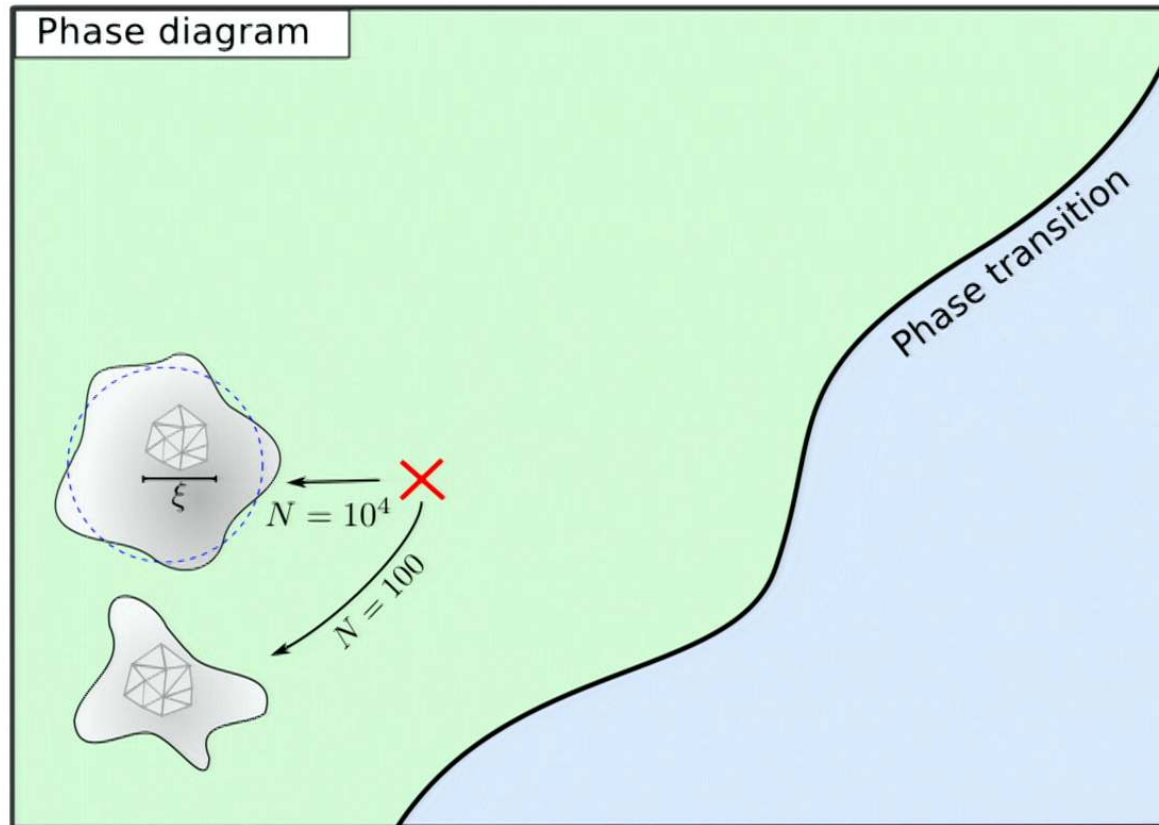
- QFT in perturbative regime: non-renormalizable
- ~~Infinite-dimensional integral~~
- ~~What is a good diffeo-invariant measure?~~
- ~~Destructive interference is delicate~~
- ~~How to interpret integrand?~~ Probability distribution
- Numerical evaluation is ~~hard~~ doable in principle
- Classical solutions? ~~Action is unbounded below.~~
- Does the integral converge?
- Does it possess a continuum limit?

Cut-off

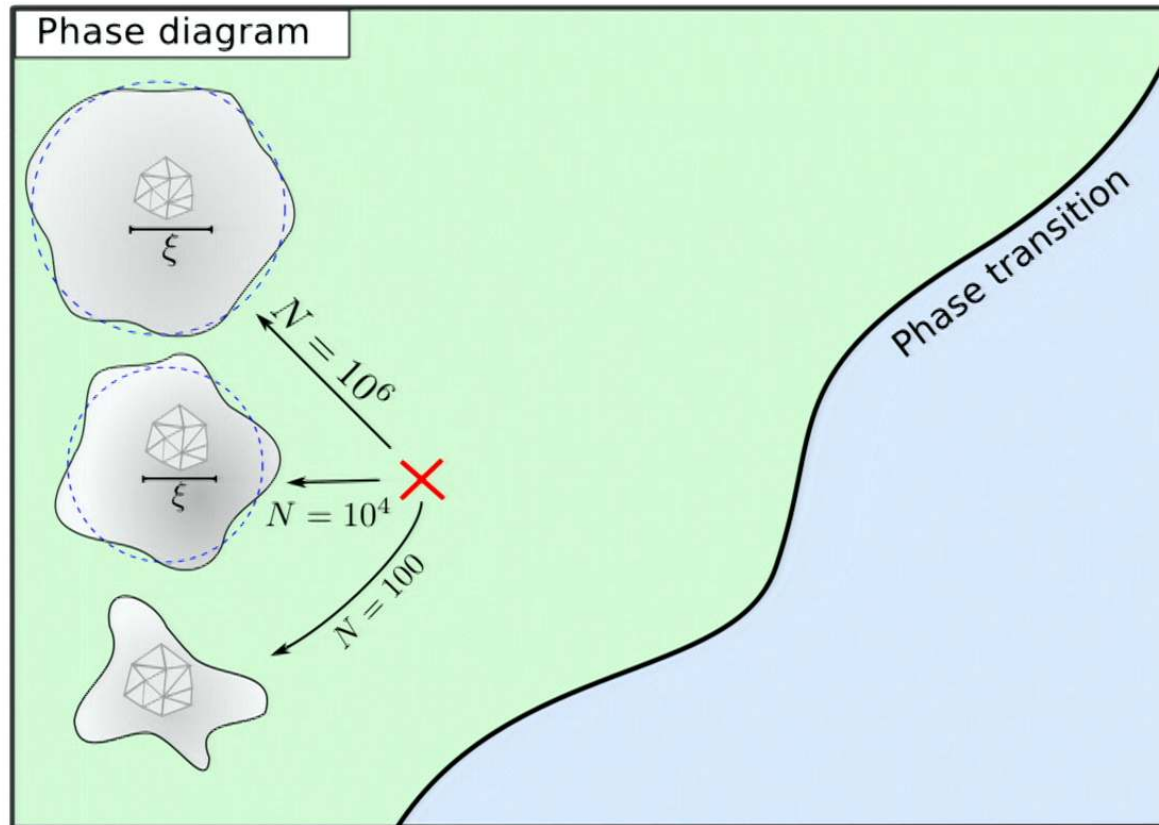
$$\sum_{\{\text{Combinatorial geometries}\}} e^{-S[g_{ab}]} \xleftarrow{\text{Discretize}} \sum \iint \frac{d\mu(l_i)}{\text{Diff}} e^{-S[g_{ab}]}_{\{\text{PL geometries } g_{ab}\}}$$



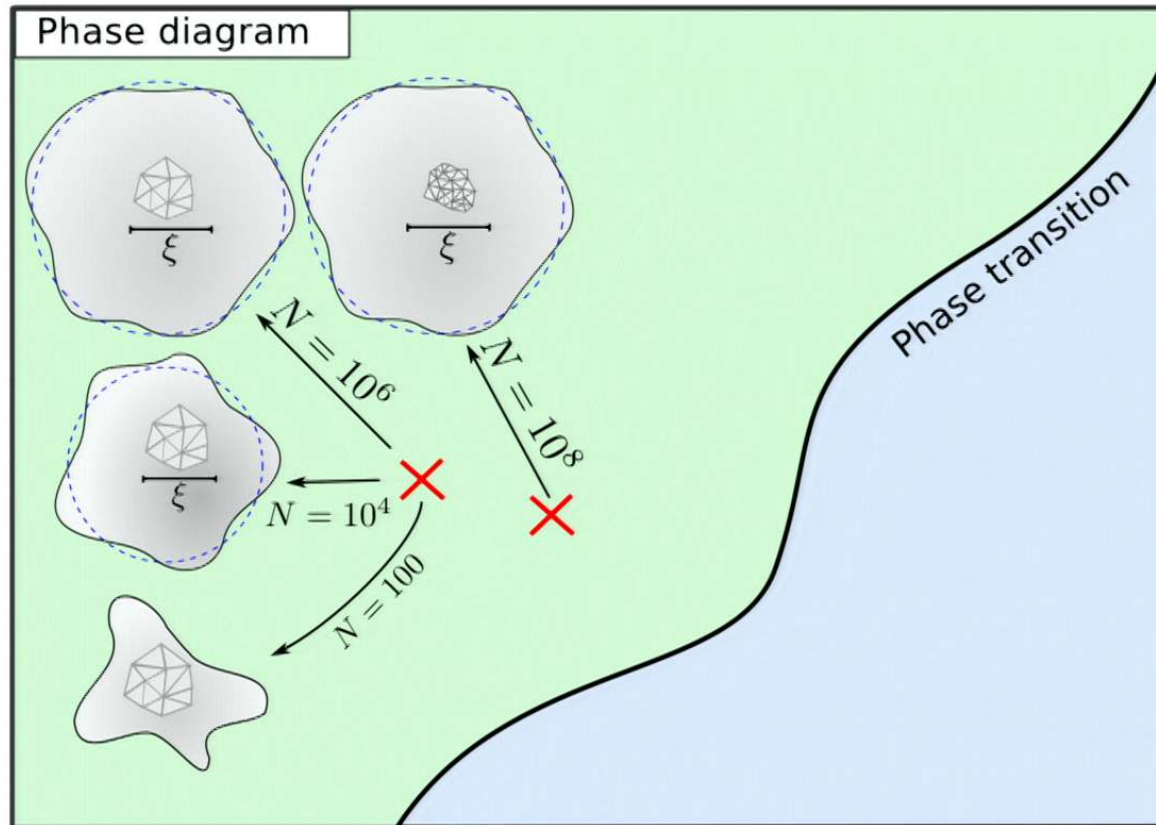
What would be the best scenario?



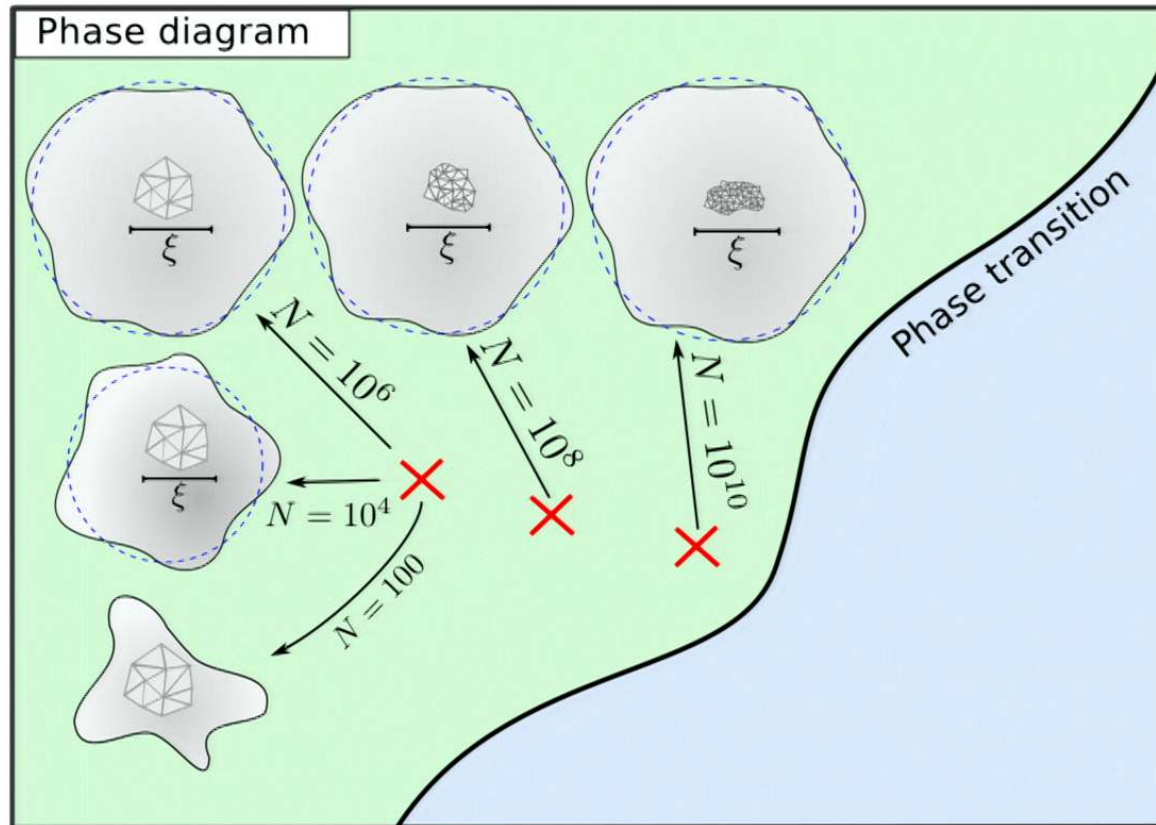
What would be the best scenario?



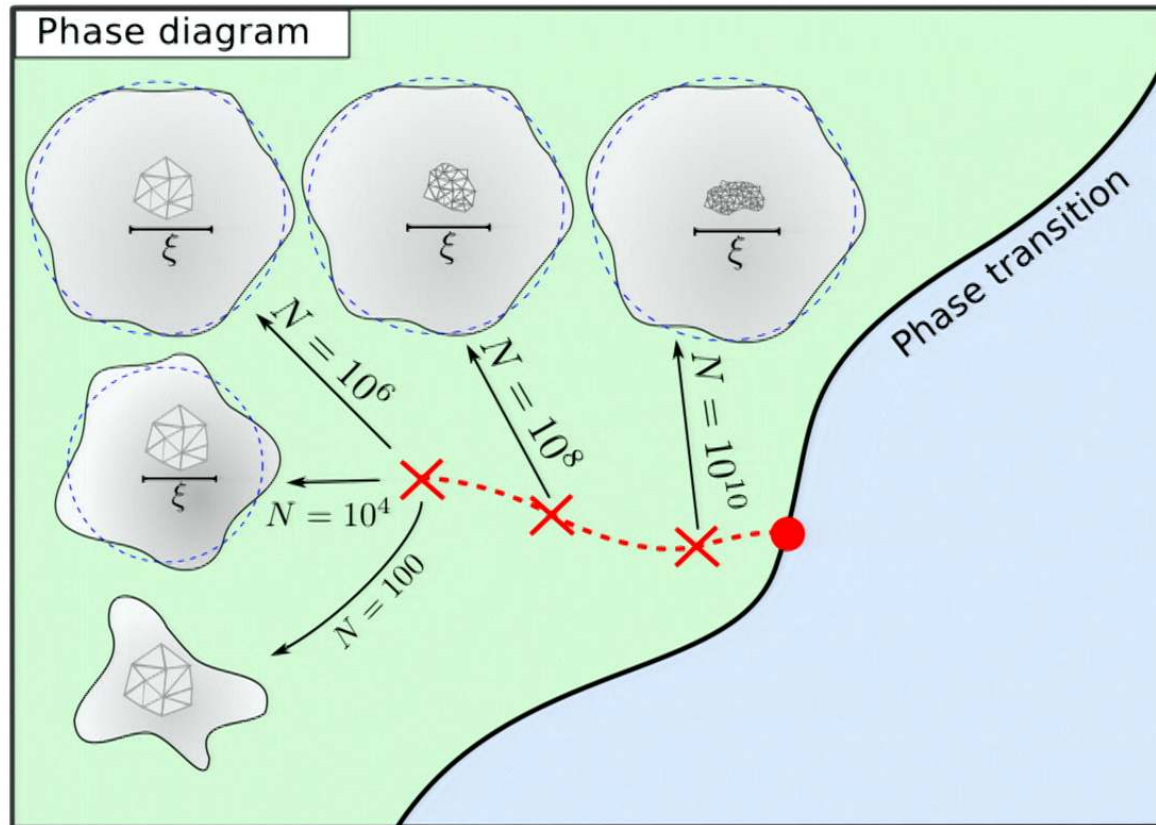
What would be the best scenario?



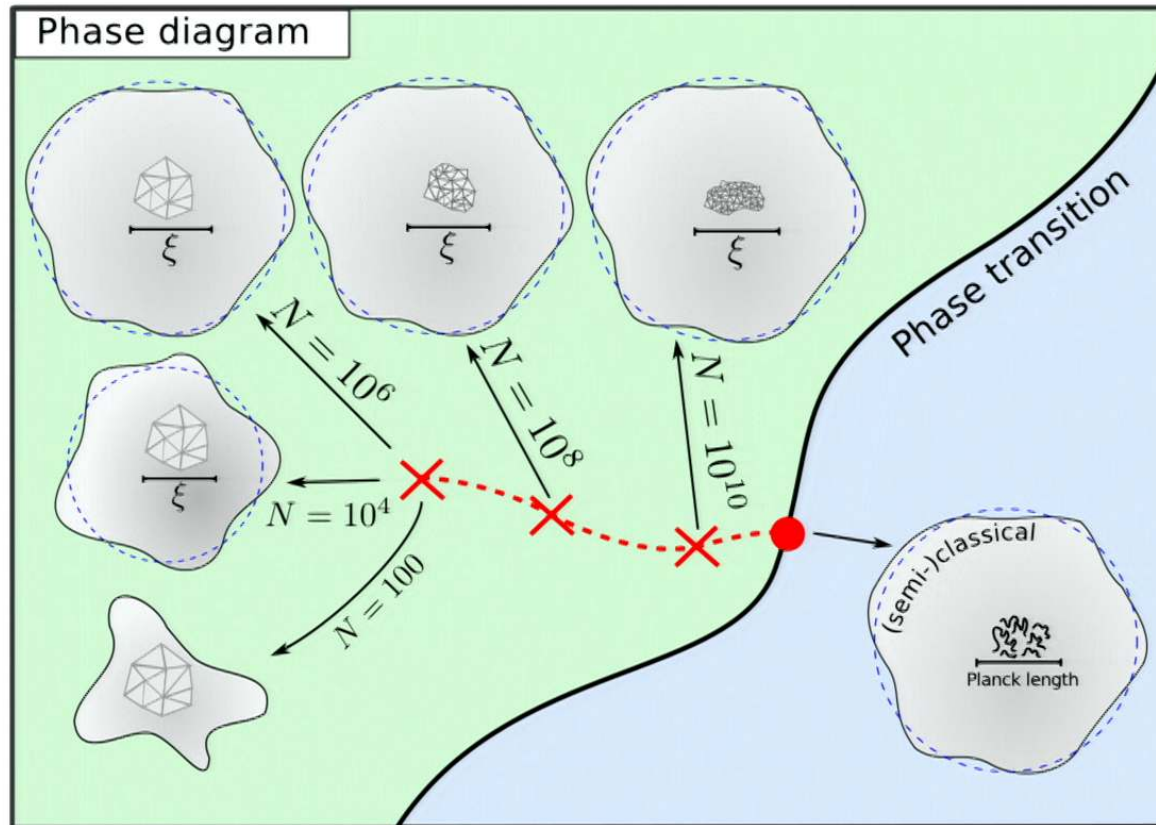
What would be the best scenario?



What would be the best scenario?

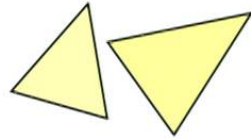


What would be the best scenario?

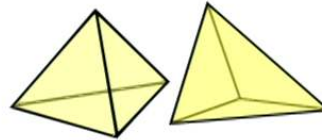


## Piecewise linear geometry

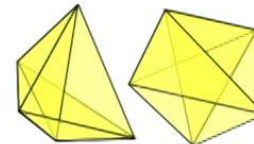
- ▶  $D$ -simplex:  $\{\sum_{i=0}^D \lambda_i \mathbf{x}_i : \lambda_i \in [0, 1], \sum \lambda_i = 1\} \subset \mathbb{R}^D$  with Euclidean geometry.



$D = 2$



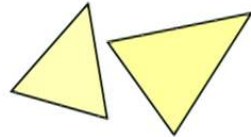
$D = 3$



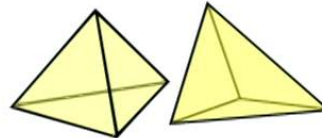
$D = 4$

## Piecewise linear geometry

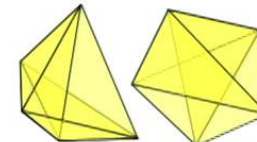
- ▶  $D$ -simplex:  $\{\sum_{i=0}^D \lambda_i \mathbf{x}_i : \lambda_i \in [0, 1], \sum \lambda_i = 1\} \subset \mathbb{R}^D$  with Euclidean geometry.



$D = 2$

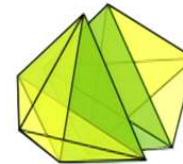
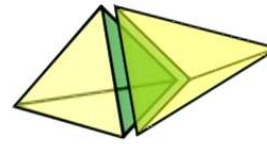
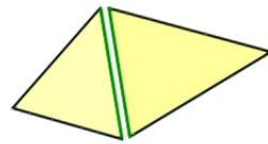


$D = 3$



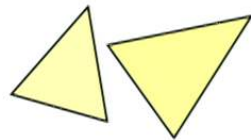
$D = 4$

- ▶  $D$ -simplices can be glued into larger metric spaces along matching  $(D - 1)$ -simplices.

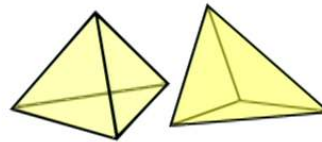


## Piecewise linear geometry

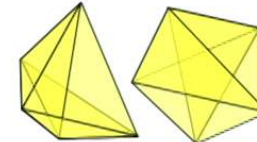
- ▶  $D$ -simplex:  $\{\sum_{i=0}^D \lambda_i \mathbf{x}_i : \lambda_i \in [0, 1], \sum \lambda_i = 1\} \subset \mathbb{R}^D$  with Euclidean geometry.



$D = 2$

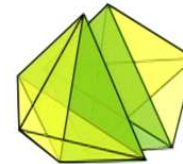
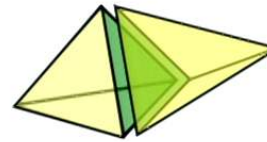
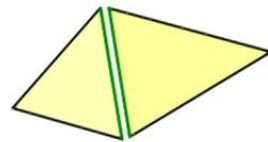


$D = 3$

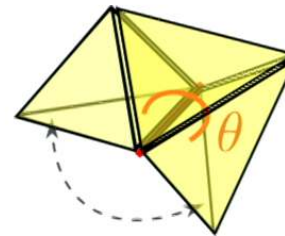
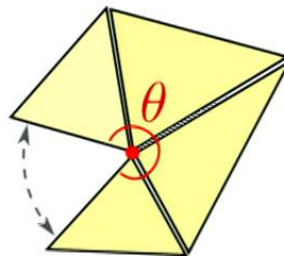


$D = 4$

- ▶  $D$ -simplices can be glued into larger metric spaces along matching  $(D - 1)$ -simplices.



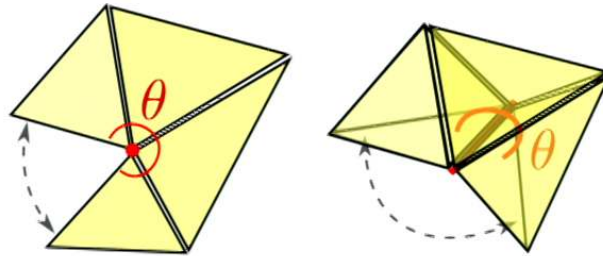
- ▶ Resulting geometry has curvature supported on  $(D - 2)$ -simplices.



## Einstein-Hilbert action

- ▶ Integrated curvature is naturally expressed in terms of deficit angles  
[Regge, '61]

$$\int d^D x \sqrt{g} R \longrightarrow \sum_{(D-2)\text{-simplices } \sigma} |\sigma| (2\pi - \theta_\sigma)$$



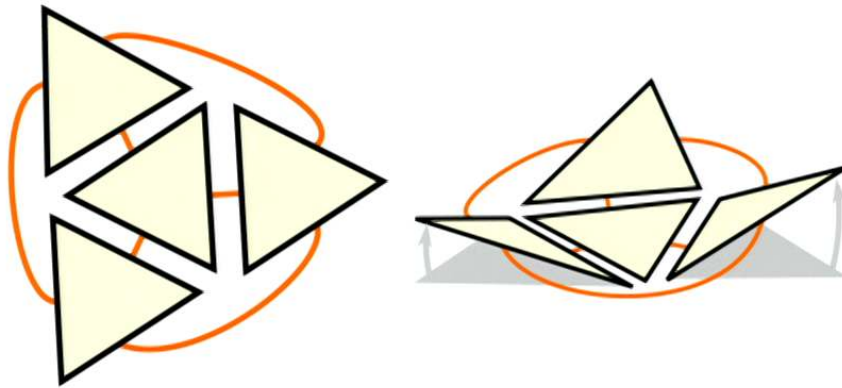
- ▶ If all simplices are taken of equal shape (say, equilateral) then linearity of Regge action implies that EH ( $+\int d^D x \sqrt{g} \Lambda$ ) is a simple linear combination

$$\kappa_D N_D - \kappa_{D-2} N_{D-2}.$$

- ▶ Makes sense to include in MCMC at least such two terms in Boltzmann weight.

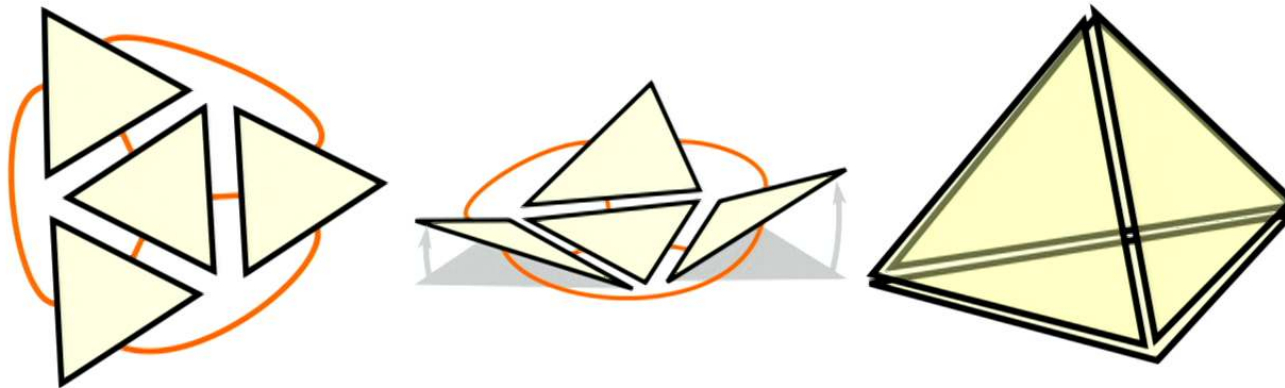
## Combinatorial representation

- ▶ Recall: need **n**ext and **a**djacent to navigate a map, or a polyhedron.



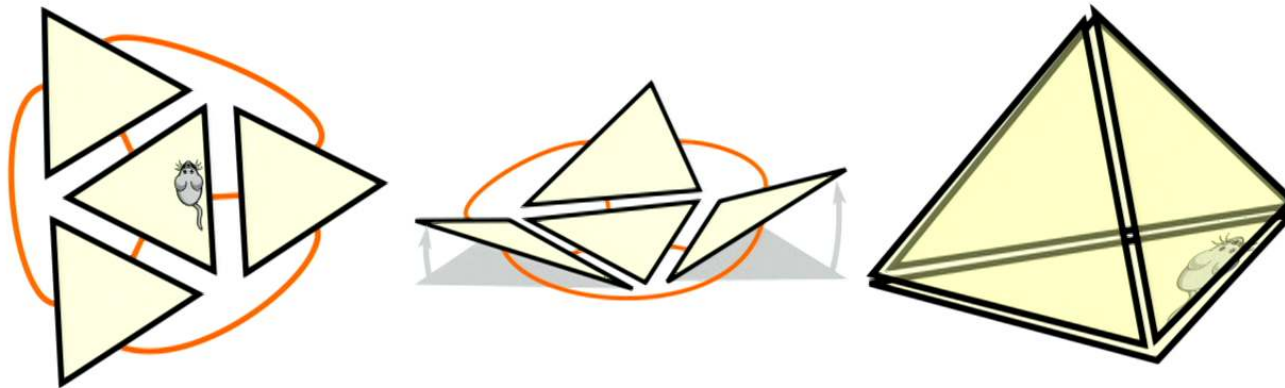
## Combinatorial representation

- ▶ Recall: need **n**ext and **a**djacent to navigate a map, or a polyhedron.



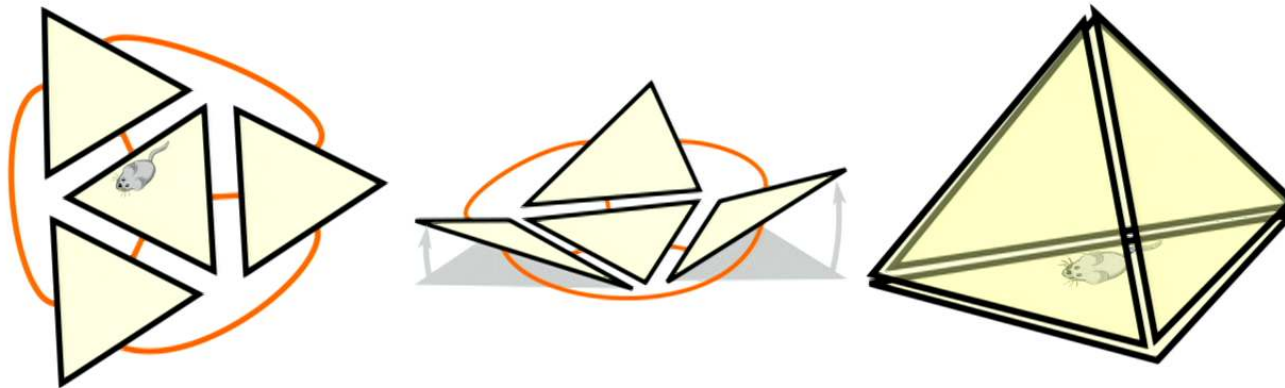
## Combinatorial representation

- ▶ Recall: need **n**ext and **a**djacent to navigate a map, or a polyhedron.



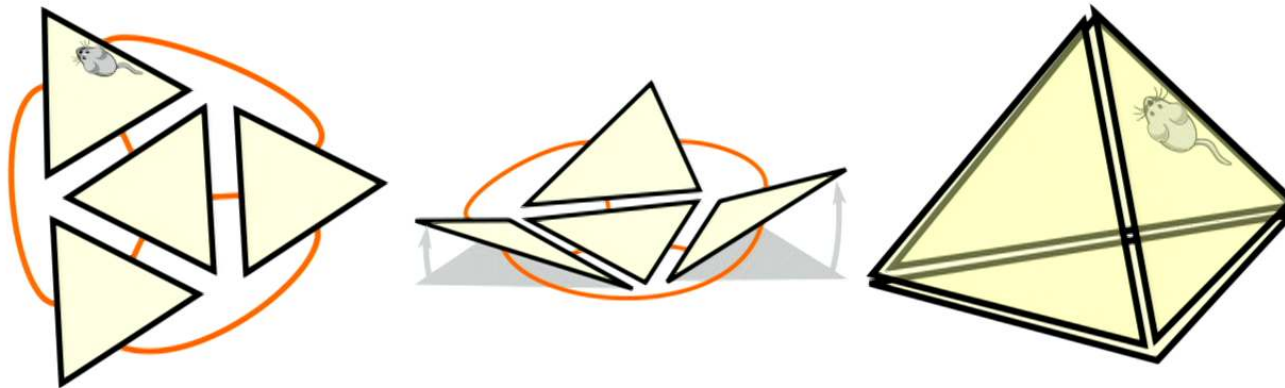
## Combinatorial representation

- ▶ Recall: need **n**ext and **a**djacent to navigate a map, or a polyhedron.



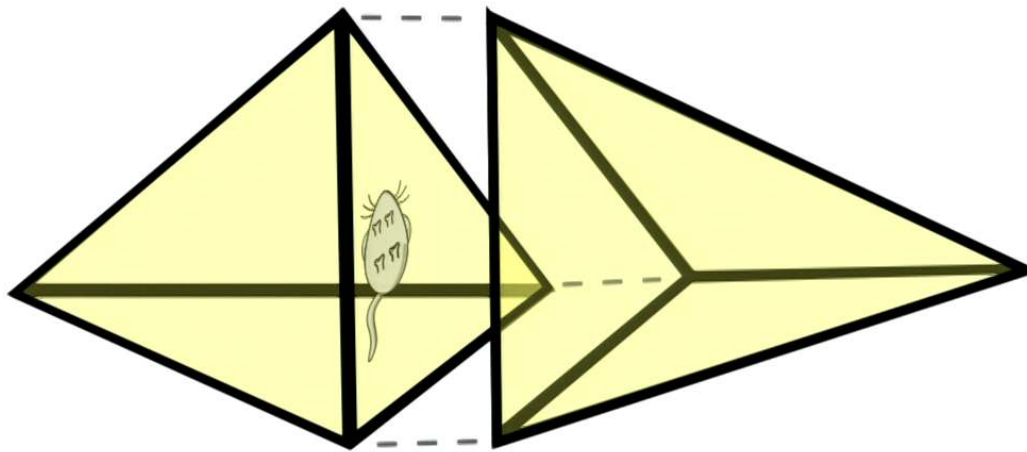
## Combinatorial representation

- ▶ Recall: need **n**ext and **a**djacent to navigate a map, or a polyhedron.



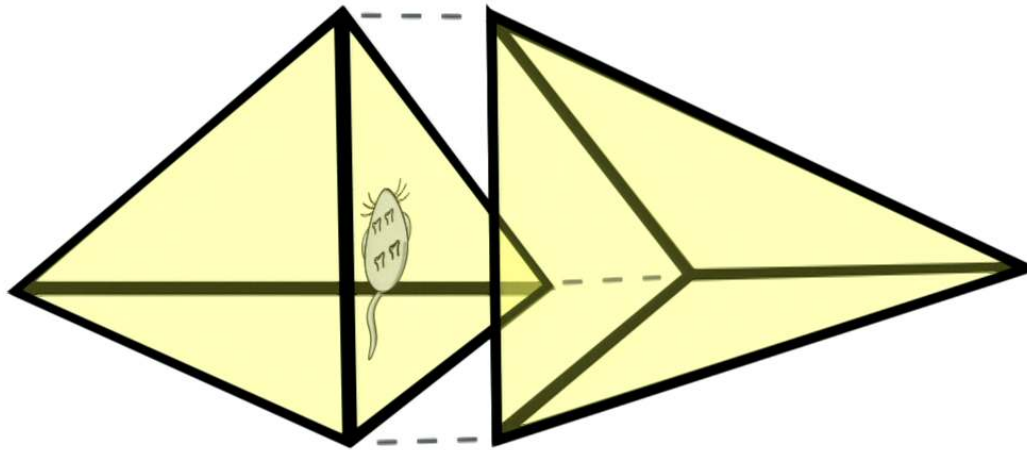
## Combinatorial representation

- ▶ Recall: need **n**ext and **a**djacent to navigate a map, or a polyhedron.



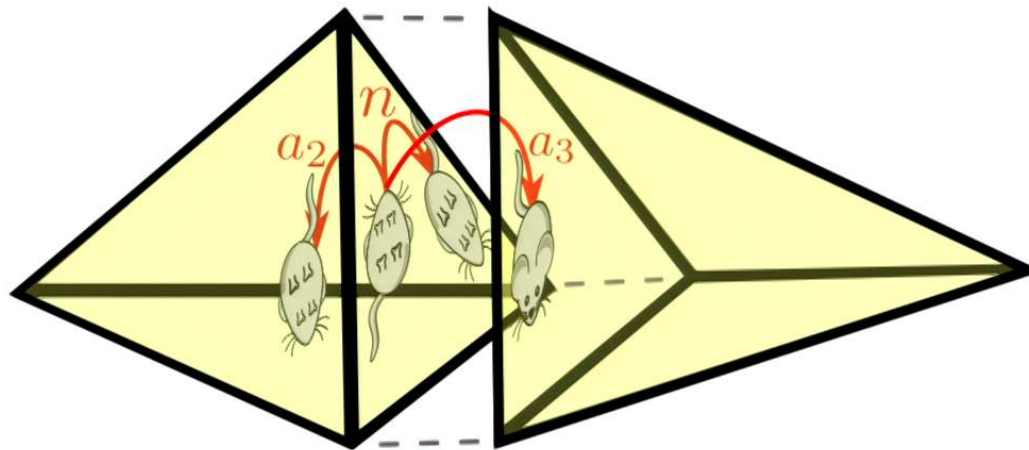
## Combinatorial representation

- ▶ Recall: need **n**ext and **a**djacent to navigate a map, or a polyhedron.
- ▶ Generalize: For  $D$ -dimensional geometry,  $(n, a) \rightarrow (n, a_2, \dots, a_D)$ .  
 $a_d$  maps half-edge  $i$  to its  $d$ -dimensional neighbor  $a_d(i)$ .



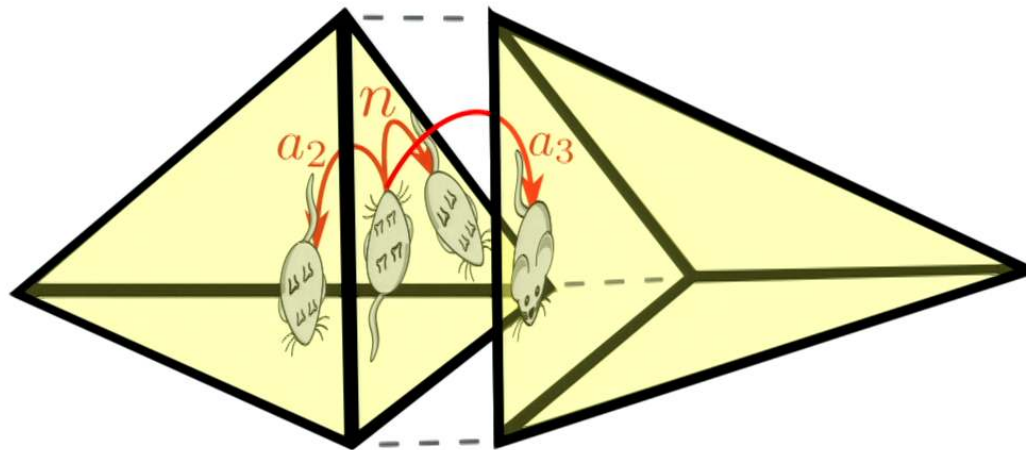
## Combinatorial representation

- ▶ Recall: need **n**ext and **a**djacent to navigate a map, or a polyhedron.
- ▶ Generalize: For  $D$ -dimensional geometry,  $(n, a) \rightarrow (n, a_2, \dots, a_D)$ .  
 $a_d$  maps half-edge  $i$  to its  $d$ -dimensional neighbor  $a_d(i)$ .



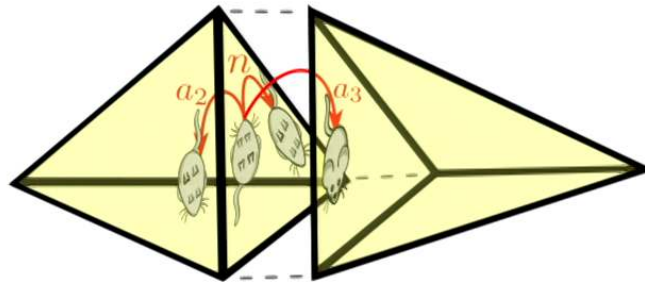
## Combinatorial representation

- ▶ Recall: need **n**ext and **a**djacent to navigate a map, or a polyhedron.
- ▶ Generalize: For  $D$ -dimensional geometry,  $(n, a) \rightarrow (n, a_2, \dots, a_D)$ .  $a_d$  maps half-edge  $i$  to its  $d$ -dimensional neighbor  $a_d(i)$ .
- ▶ Cells of various dimensions are identified as orbits. In 3D:  
 $(n, a_2) \rightarrow$  polyhedra,  $(n, a_3) \rightarrow$  faces,  $(a_2, a_3) \rightarrow$  edges,  
 $(n \circ a_2, n \circ a_3) \rightarrow$  vertices.



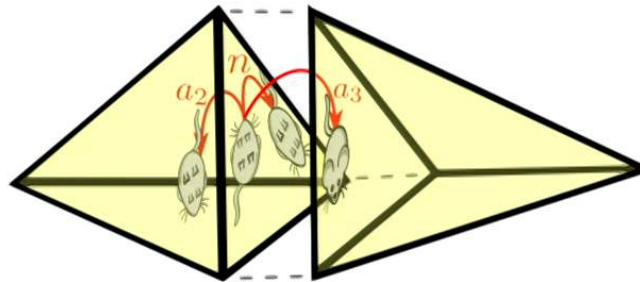
## Remarks on combinatorics in 3D

- ▶ When does a triple of permutations  $(n, a_2, a_3)$  determine a topological 3-manifold?



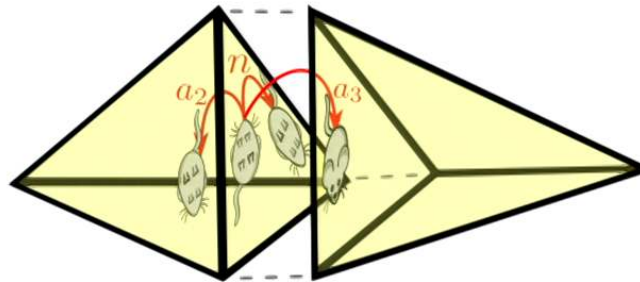
## Remarks on combinatorics in 3D

- ▶ When does a triple of permutations  $(n, a_2, a_3)$  determine a topological 3-manifold?
  - ▶  $a_d \circ a_d = \mathbf{1}$ ,  $a_d(x) \neq x$  for all  $x$  and  $d$ .
  - ▶ Proper gluing:  $n \circ a_3 \circ n = a_3$ .
  - ▶ Polyhedra (orbits under  $n, a_2$ ) should have 3-ball topology (i.e. boundary  $S^2$ ): Euler formula!
  - ▶ Neighbourhood of vertices (orbits under  $n \circ a_2, n \circ a_3$ ) should have 3-ball topology: Euler formula!



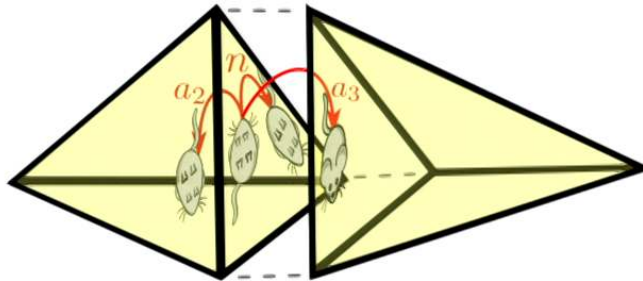
## Remarks on combinatorics in 3D

- ▶ When does a triple of permutations  $(n, a_2, a_3)$  determine a topological 3-manifold?
  - ▶  $a_d \circ a_d = \mathbf{1}$ ,  $a_d(x) \neq x$  for all  $x$  and  $d$ .
  - ▶ Proper gluing:  $n \circ a_3 \circ n = a_3$ .
  - ▶ Polyhedra (orbits under  $n, a_2$ ) should have 3-ball topology (i.e. boundary  $S^2$ ): Euler formula!
  - ▶ Neighbourhood of vertices (orbits under  $n \circ a_2, n \circ a_3$ ) should have 3-ball topology: Euler formula!



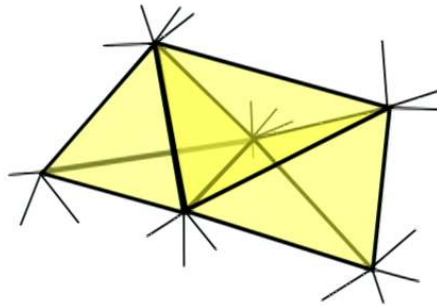
## Remarks on combinatorics in 3D

- ▶ When does a triple of permutations  $(n, a_2, a_3)$  determine a topological 3-manifold?
  - ▶  $a_d \circ a_d = \mathbf{1}$ ,  $a_d(x) \neq x$  for all  $x$  and  $d$ .
  - ▶ Proper gluing:  $n \circ a_3 \circ n = a_3$ .
  - ▶ Polyhedra (orbits under  $n, a_2$ ) should have 3-ball topology (i.e. boundary  $S^2$ ): Euler formula!
  - ▶ Neighbourhood of vertices (orbits under  $n \circ a_2, n \circ a_3$ ) should have 3-ball topology: Euler formula!
- ▶ What is the topology of the resulting 3-manifold?
  - ▶ Unfortunately, no simple combinatorial/algorithmic way to decide!
  - ▶ Luckily, any two geometries with equal topology are connected by a finite sequence of local moves!
- ▶ Situation very similar in 4D (and higher).



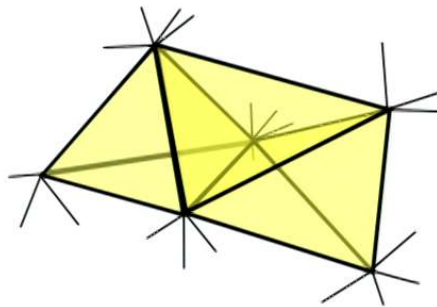
## Simplicial manifolds

- ▶ *D-triangulation*: all  $D$ -cells are taken to be  $D$ -simplices (i.e. triangles in  $2D$ , tetrahedra in  $3D$ , 4-simplices in  $4D$ ).



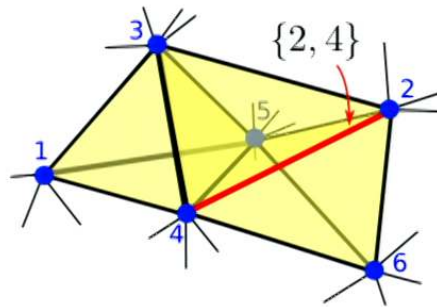
## Simplicial manifolds

- ▶ *D*-triangulation: all *D*-cells are taken to be *D*-simplices (i.e. triangles in  $2D$ , tetrahedra in  $3D$ , 4-simplices in  $4D$ ).
- ▶ In *D*-triangulations all dynamical information is stored in  $a_D$ .
- ▶ Amounts to  $(D + 1)!/2$  numbers to store/update per *D*-simplex.



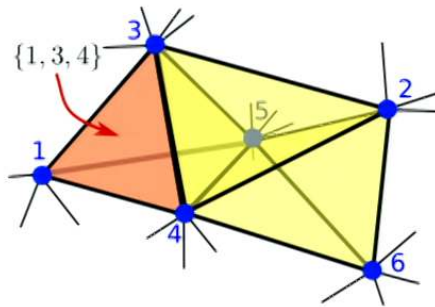
## Simplicial manifolds

- ▶ *D-triangulation*: all  $D$ -cells are taken to be  $D$ -simplices (i.e. triangles in  $2D$ , tetrahedra in  $3D$ , 4-simplices in  $4D$ ).
- ▶ In  $D$ -triangulations all dynamical information is stored in  $a_D$ .
- ▶ Amounts to  $(D + 1)!/2$  numbers to store/update per  $D$ -simplex.
- ▶ Label the vertices of a  $D$ -triangulation.
- ▶ *Simplicial D-triangulation*: each edge, face,  $\dots$ ,  $D$ -simplex must be uniquely characterized by its set of incident vertices.



## Simplicial manifolds

- ▶ *D*-triangulation: all *D*-cells are taken to be *D*-simplices (i.e. triangles in  $2D$ , tetrahedra in  $3D$ , 4-simplices in  $4D$ ).
- ▶ In *D*-triangulations all dynamical information is stored in  $a_D$ .
- ▶ Amounts to  $(D + 1)!/2$  numbers to store/update per *D*-simplex.
- ▶ Label the vertices of a *D*-triangulation.
- ▶ *Simplicial D-triangulation*: each edge, face,  $\dots$ , *D*-simplex must be uniquely characterized by its set of incident vertices.



## Simplicial manifolds

- ▶ *D-triangulation*: all  $D$ -cells are taken to be  $D$ -simplices (i.e. triangles in  $2D$ , tetrahedra in  $3D$ , 4-simplices in  $4D$ ).
- ▶ In  $D$ -triangulations all dynamical information is stored in  $\mathbf{a}_D$ .
- ▶ Amounts to  $(D + 1)!/2$  numbers to store/update per  $D$ -simplex.
- ▶ Label the vertices of a  $D$ -triangulation.
- ▶ *Simplicial D-triangulation*: each edge, face,  $\dots$ ,  $D$ -simplex must be uniquely characterized by its set of incident vertices.
- ▶ Knowing the set  $\{\{1, 3, 4, 5\}, \{2, 3, 4, 5\}, \{2, 4, 5, 6\}, \dots\}$  of  $D$ -simplices, can reproduce the triple  $(n, \mathbf{a}_2, \mathbf{a}_3)$  up to relabeling (and orientation).

