Title: Abstract quantum theory

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Abstract: What is the essence of quantum theory? In the present talk I want to approach this question from a particular operationalist perspective. I take advantage of a recent convergence between operational approaches to quantum theory and axiomatic approaches to quantum field theory. Removing anything special to particular physical models, including underlying notions of space and (crucially) time, what remains is what I shall call "abstract quantum theory". This embeds into a more general framework that also includes classical theory, with classical and quantum theory representing two extremes in a spectrum of possible theories. I shall present this within a "hierarchy of abstraction", where adding structure leads to more specialized frameworks. In particular, adding topological spacetime and locality leads to the recently proposed positive formalism and recovers quantum field theory. Further rigidifying time and adding causality recovers the standard formulation of quantum theory. There are other promising specializations such as Hardy's proposal to work in op-space.

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Abstract quantum theory

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Perimeter Institute, Waterloo 20 April 2017



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Origins

Quantum Field Theory

- Dirac (1933): generalized transformation functions
- Feynman (1948): path integral
- Witten, Segal, Atiyah (1988): TQFT aka. FQFT

Foundations of QT

- convex operational framework
- quantum information theory: quantum operation, channel
- specific approaches:
 - ► Hardy: causaloid (2005), formalism locality (2010)
 - ▶ Brukner, Oreshkov, ...: process matrix (2011), timeless approach (2014)
 - ► Selinger, ...: categorical approach (2005)
 - ▶ ...



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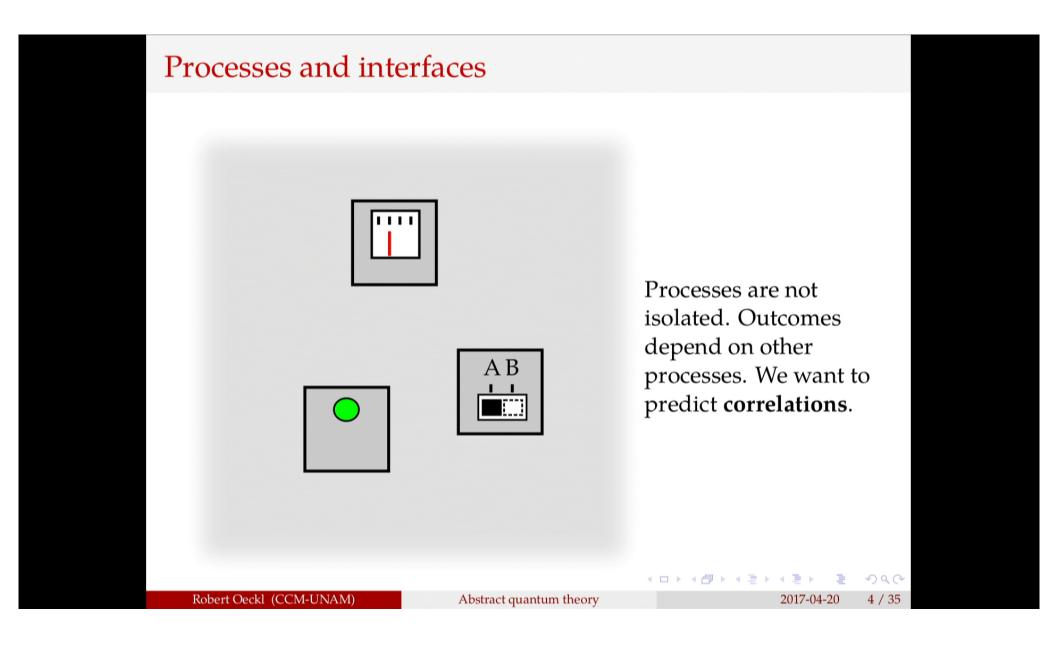
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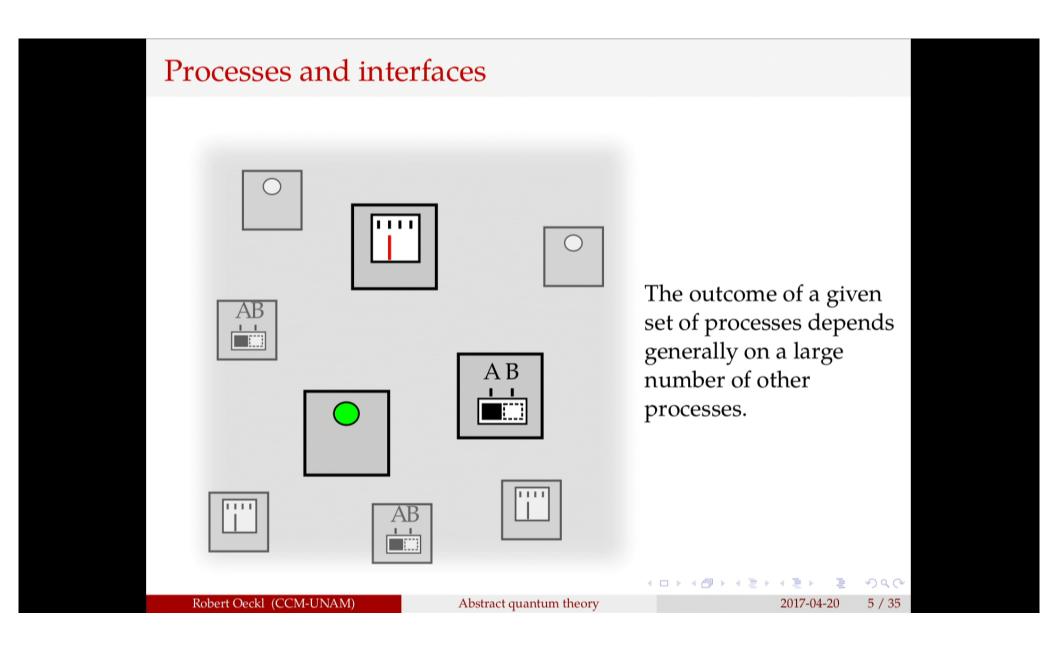
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Processes and interfaces Operational approach: Fundamental notions experiment measurement observation preparation intervention Subsume instance as: process Processes have outcomes. Represent processes as boxes. ◆ロト ◆団 ト ◆ 差 ト ◆ 差 ・ 夕 Q C ・ Robert Oeckl (CCM-UNAM) Abstract quantum theory 3 / 35 2017-04-20

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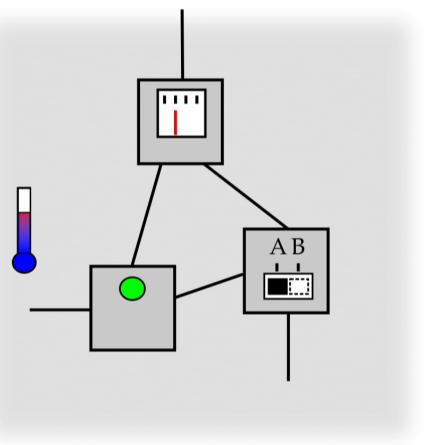


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Processes and interfaces



We introduce the notion of **interface** to model interaction between processes. An interface encodes communication or information exchange between processes. we depict this as a **link**.

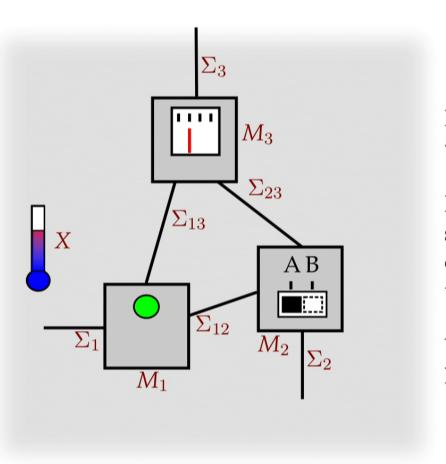
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Processes and interfaces



Processes are of specific **types**.

Interfaces are of a specific **type** depending on the processes which they connect.

We indicate this with **labels**.

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Processes and probes

Associated to each process of type M is a space \mathcal{P}_M of **probes**.

A probe provides a finer description of a process, specifying e.g. a

- specific experimental outcome
- specific apparatus settings

There is always a **null-probe** $\square \in \mathcal{P}_M$, representing the absence of any apparatus, observation or intervention.

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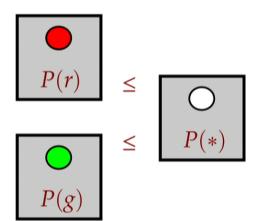
Hierarchies of probes

Probes form hierarchies of generality. This induces a partial order on the space of probes \mathcal{P}_M .

Consider an apparatus with one light that shows either red or green, encoded in three different probes:

- P(r) for outcome red
- P(g) for outcome green
- P(*) for an unspecified outcome

The unspecified state is more **general** than the others. Encode this in a **partial order** on \mathcal{P}_M , setting $P(r) \leq P(*)$ and $P(g) \leq P(*)$.



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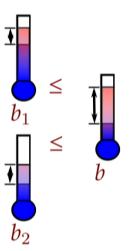
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Hierarchies of boundary conditions

Boundary conditions also form **hierarchies of generality**. This gives rise to a **partial order** on \mathcal{B}_{M}^{+} . Here:

$$b_1 \le b$$

$$b_2 \le b$$



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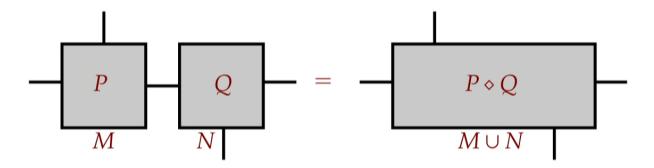
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Composition

A set of processes joined by interfaces may be considered itself a process. Say we have a process of type M and one of type N. We say the **composite** process has type $M \cup N$.



This induces a composition of associated probes $P \in \mathcal{P}_M$ with $Q \in \mathcal{P}_N$. We write for the composite probe $P \diamond Q \in \mathcal{P}_{M \cup N}$. This yields a **composition map** $\diamond : \mathcal{P}_M \times \mathcal{P}_N \to \mathcal{P}_{M \cup N}$.

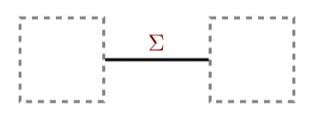
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Interfaces and boundary conditions



We associate to each interface Σ a space of **boundary conditions** \mathcal{B}_{Σ}^{+} . This parametrizes possible signals/information exchange between adjacent processes.

Interfaces between the same pair of processes can be combined arbitrarily. Write: $\Sigma = \Sigma_1 \cup \Sigma_2 \cup \cdots \cup \Sigma_n$.

$$\begin{bmatrix} \begin{bmatrix} \vdots \\ \vdots \\ \Sigma_1 \Sigma_2 & \Sigma_n & \Sigma \end{bmatrix}$$

Induces a map between spaces of boundary conditions:

boundary conditions:
$$\mathcal{B}_{\Sigma_1}^+ \times \mathcal{B}_{\Sigma_2}^+ \times \cdots \times \mathcal{B}_{\Sigma_n}^+ \to \mathcal{B}_{\Sigma}^+$$

We denote the joint interface for a process of type M by ∂M .

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Values

Consider a process of type M.

$$\llbracket P, b \rrbracket_M = \boxed{P \qquad b}$$

To a **probe** $P \in \mathcal{P}_M$ and a **boundary condition** $b \in \mathcal{B}_{\partial M}^+$ we associate a **value** $[\![P,b]\!]_M$. We shall take this to be a **real number**. Formally, there is a **pairing** $[\![\cdot,\cdot]\!]_M:\mathcal{P}_M\times\mathcal{B}_{\partial M}^+\to\mathbb{R}$.

 $[\![P,b]\!]_M \in \mathbb{R}^+$ quantifies **compatibility** between the apparatus or outcome represented by the (primitive) probe $P \in \mathcal{P}_M^+$ and the **boundary condition** $b \in \mathcal{B}_{\partial M}^+$.

Pairing and partial order structures are compatible:

$$P \leq Q \iff [P, b]_{M} \leq [Q, b]_{M} \quad \forall b \in \mathcal{B}_{\partial M}^{+}$$
$$b \leq c \iff [P, b]_{M} \leq [P, c]_{M} \quad \forall P \in \mathcal{P}_{M}^{+}$$

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From values to measurements

A measurement is encoded by at least two **probes**:

- One **non-selective probe** *Q* encodes the **measurement apparatus**.
- One **selective probe** *P* encodes the measurement apparatus with a selected outcome.

 $[\![Q,b]\!]_M \in \mathbb{R}^+$ quantifies **compatibility** of the **boundary condition** $b \in \mathcal{B}_{\partial M}^+$ with the presence of the **apparatus**.

 $[P, b]_M \in \mathbb{R}^+$ quantifies **compatibility** of the **boundary condition** $b \in \mathcal{B}_{\partial M}^+$ with the presence of the apparatus with **selected outcome**.

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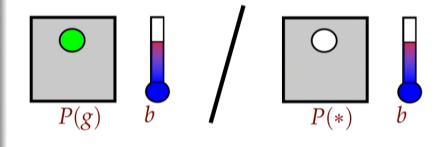
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Measurement probabilities

In M consider the probe $P(*) \in \mathcal{P}_{M}^{+}$ encoding a measurement device and P(g) encoding in addition a selected outcome.

Given $b \in \mathcal{B}_{\partial M}^+$ the **probability** Π for an affirmative outcome is:

$$\Pi = \frac{[\![P(g), b]\!]_M}{[\![P(*), b]\!]_M}$$



Since $0 \le P(g) \le P(*)$ we have $0 \le \Pi \le 1$ (if $[P(*), b]_M \ne 0$).

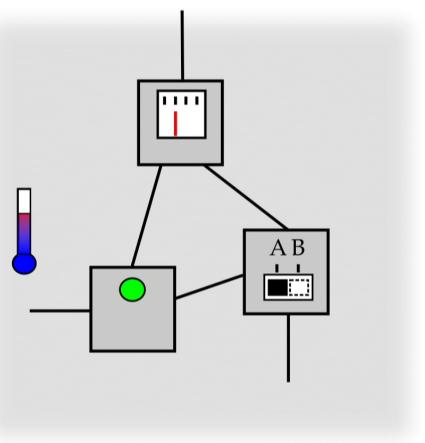
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Convexity

In a probabilistic setting it makes sense to combine different probes probabilistically, even when they correspond to different experimental situations. Say we have probes P_1, \ldots, P_n and probabilities p_1, \ldots, p_n such that $\sum_k p_k = 1$. Then we can consider $P := \sum_k p_k P_k$ as a probe.

Since an arbitrary real multiple of a probe is a probe, this equips the space \mathcal{P}_M of probes with the structure of a **real vector space**. The subset of primitive probes $\mathcal{P}_M^+ \subset \mathcal{P}_M$ is a **positive cone** making \mathcal{P}_M into a **partially ordered vector space**.

Similarly, the set of boundary conditions \mathcal{B}_{Σ}^{+} forms a **positive cone** in the **partially ordered vector space** \mathcal{B}_{Σ} generated by it. We call this the space of **generalized boundary conditions**.

We extend the pairing, $[\cdot,\cdot]_M:\mathcal{P}_M\times\mathcal{B}_{\partial M}\to\mathbb{R}$

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Slice processes and inner product

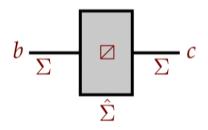
For any type Σ of **interface** we postulate a type of **slice process** $\hat{\Sigma}$:

- $\bullet \ \partial \hat{\Sigma} = \Sigma \cup \Sigma$
- the null probe "passes signals through"

$$\Sigma$$
 Σ Σ

Putting **boundary conditions** on the two sides allows evaluation. This yields an **inner product** $\mathcal{B}_{\Sigma} \times \mathcal{B}_{\Sigma} \to \mathbb{R}$ on the space of boundary conditions.

$$(b,c)_{\Sigma} := [\![\varnothing,b\otimes c]\!]_{\hat{\Sigma}}$$



This should be **symmetric** and **positive-definite**.

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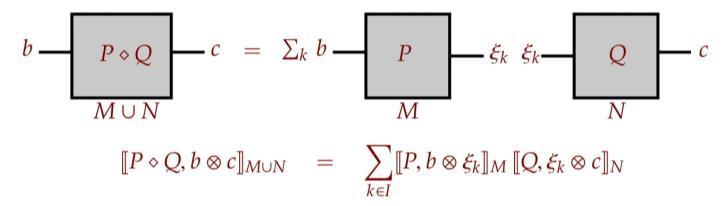
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Composition rule for probes

As a generalization we obtain the **composition rule for probes**.



Here, $\{\xi_k\}_{k\in I}$ is an ON-basis of \mathcal{B}_{Σ} .



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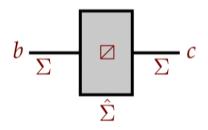
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This should be **symmetric** and **positive-definite**.

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(Abstract) Positive Formalism

We obtain an **axiomatic framework** for encoding physical theories that requires no notion of space or time.

Adding structure as necessary (but no new rules!) this specializes to:

- the convex operational framework
- the spacetime positive formalism
- "abstract" quantum theory
- quantum field theory (as axiomatized in the sense of Segal)
- the standard formulation of quantum theory

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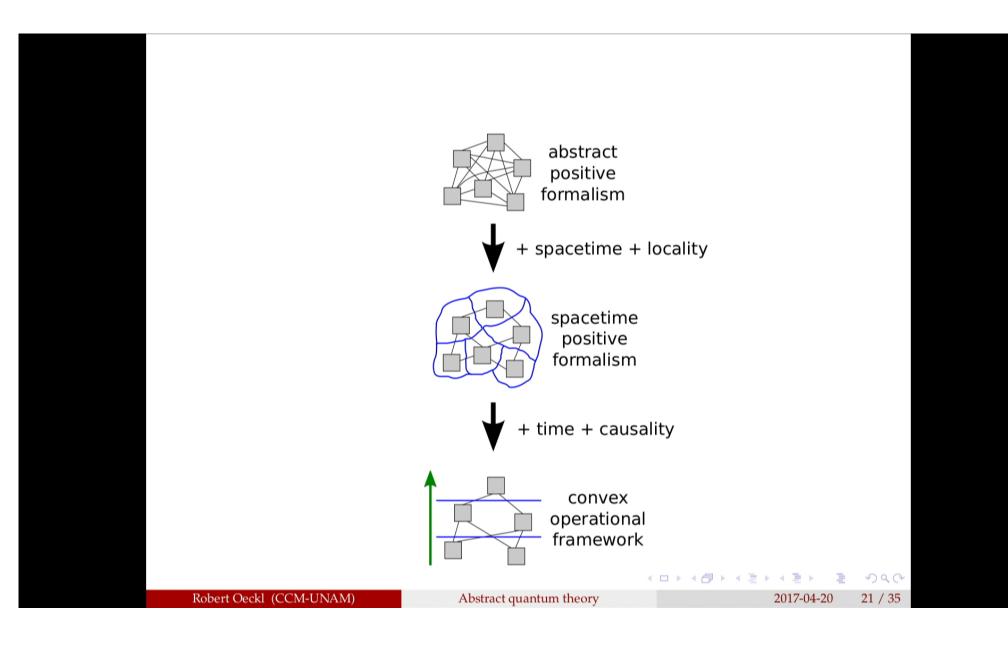
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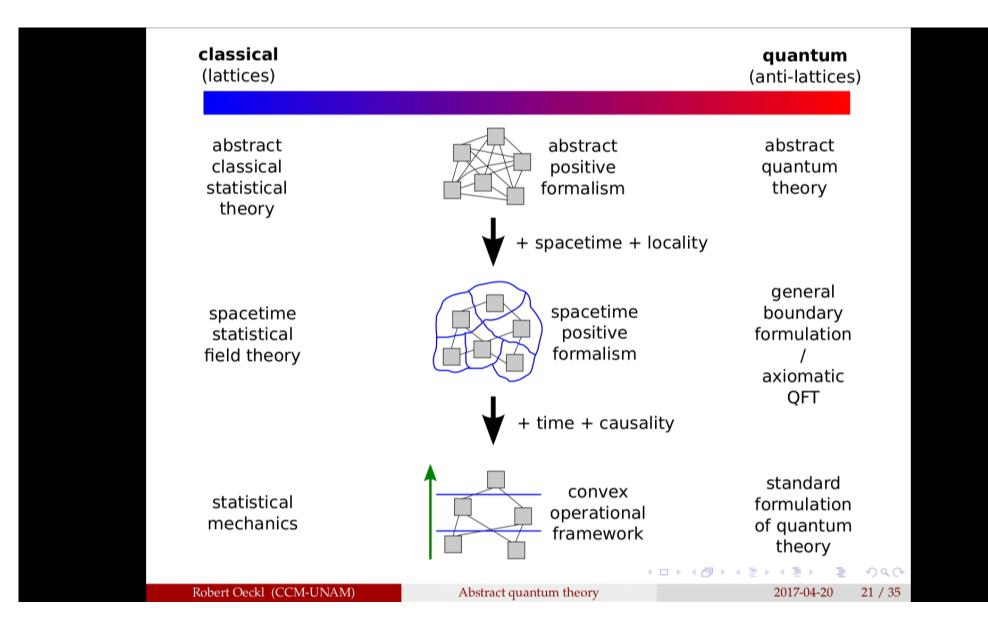
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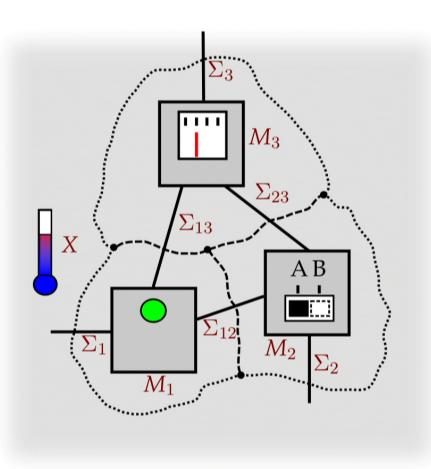


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Adding spacetime and locality



Spacetime locality
provides a powerful
organizing principle.
Processes only interface
with adjacent processes.
This decreases
considerably the
interconnectivity of the
graph.

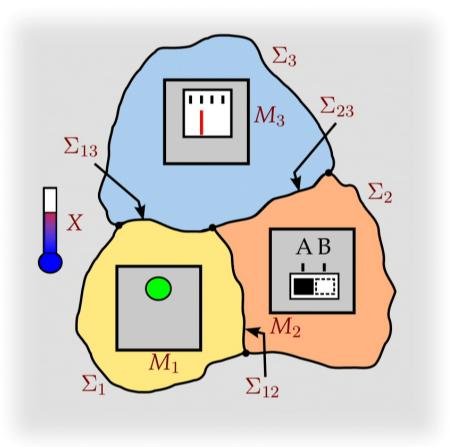
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Adding spacetime and locality



We may forget about the graph and identify process types with regions and interface types with hypersurfaces.

This framework is called the **spacetime version** of the **positive formalism**.

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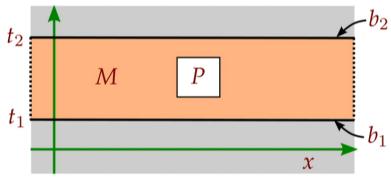
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Time-evolution

Specialize to a global factorizing spacetime $\mathbb{R} \times \Sigma$ and restrict the spacetime system to **equal-time hyperplanes** Σ_t and **time-interval regions** $[t_1, t_2] = [t_1, t_2] \times \Sigma$.

Write $\mathcal{B}_t := \mathcal{B}_{\Sigma_t}$ and call this the (generalized) state space at time t.



Consider probe $P \in \mathcal{P}_{[t_1,t_2]}$. Define the **probe map** $\tilde{P} : \mathcal{B}_{t_1} \to \mathcal{B}_{t_2}$ via

$$\{b_2, \tilde{P}(b_1)\}_{t_2} = [\![P, b_1 \otimes b_2]\!]_{[t_1, t_2]}, \qquad \forall b_1 \in \mathcal{B}_{t_1}, b_2 \in \mathcal{B}_{t_2}.$$

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Primitive probe maps and positivity

Probe maps for **primitive probes** are **positive**. They map proper states to proper states, $\mathcal{B}_{t_1}^+ \to \mathcal{B}_{t_2}^+$. They even have the stronger property of **boundary positivity**,

$$\sum_{i} (c_i, \tilde{P}(b_i))_{t_2} \ge 0 \qquad \text{if} \quad \sum_{i} b_i \otimes c_i \in \mathcal{B}^+_{\partial[t_1, t_2]} \supseteq \mathcal{B}^+_{t_1} \otimes \mathcal{B}^+_{t_2}$$

In classical theory, positivity and boundary positivity are equivalent. In quantum theory, boundary positivity is **complete positivity**.



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Time-evolution maps

The probe map associated to the **null-probe** is the **time-evolution map** $T_{[t_1,t_2]}: \mathcal{B}_{t_1} \to \mathcal{B}_{t_2}$,

$$(b_2, T_{[t_1, t_2]}(b_1))_{t_2} = [\![\square, b_1 \otimes b_2]\!]_{[t_1, t_2]}$$

The time-evolution maps compose for $t_1 \le t_2 \le t_3$ as,

$$T_{[t_1,t_3]} = T_{[t_3,t_2]} \circ T_{[t_1,t_2]}.$$

Usually, time-evolution preserves the state space. Thus, $\mathcal{B} = \mathcal{B}_t$. Probe maps become **operators** on \mathcal{B} . Assume this from now on.

Many systems are also **time-translation symmetric** meaning that $T_{[t_1,t_1+\Delta]}=T_{[t_2,t_2+\Delta]}=T_{\Delta}$. We then get a **one-parameter semigroup** of boundary positive operators,

$$T_{\Delta_1+\Delta_2}=T_{\Delta_1}\circ T_{\Delta_2}.$$

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The state of maximal uncertainty

Recall that the **boundary conditions** form a **hierarchy of generality**.

We assume that there exists a state $e \in \mathcal{B}^+$ that is maximally general, call this the **state of maximal uncertainty**. This encodes a complete lack of knowledge.

Mathematically, for any $b \in \mathcal{B}^+$ there exists $\lambda > 0$ such that $b \leq \lambda \mathbf{e}$. This is called an **order unit**.

Most often in a measurement, we are only interested in the outcome given a fixed initial state b_1 , but do not care about the state after the measurement.

This is encoded by setting the final state $b_2 = \mathbf{e}$.

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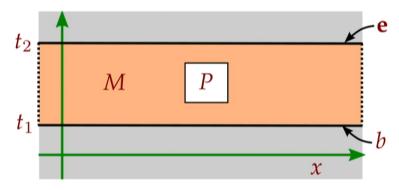
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Measurement without post-selection

Consider a binary measurement in $[t_1, t_2]$ encoded by a **non-selective probe** Q and a **selective probe** P.



The probability Π for an affirmative outcome given an initial state $b \in \mathcal{B}$, but disregarding the final fate of the system is thus,

$$\Pi = \frac{\llbracket P, b \otimes \mathbf{e} \rrbracket_{[t_1, t_2]}}{\llbracket Q, b \otimes \mathbf{e} \rrbracket_{[t_1, t_2]}} = \frac{\langle \mathbf{e}, \tilde{P}(b) \rangle}{\langle \mathbf{e}, \tilde{Q}(b) \rangle}.$$

One also says that this is a measurement without post-selection.

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Normalization

The **positivity** and **positive-definiteness** of the inner product implies that for any $b \in \mathcal{B}^+$ with $b \neq 0$ we have $(\mathbf{e}, b) > 0$.

 $b \in \mathcal{B}^+$ is **normalized** iff $(\mathbf{e}, b) = 1$.

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 $b \in \mathcal{B}^+$ is **normalized** iff $(|\mathbf{e}, b|) = 1$.

This suggests corresponding notions for probe maps $\tilde{P}: \mathcal{B} \to \mathcal{B}$.

 $\tilde{P}: \mathcal{B} \to \mathcal{B}$ is **normalization preserving** iff $(\mathbf{e}, \tilde{P}(b)) = (\mathbf{e}, b)$ for all $b \in \mathcal{B}$.

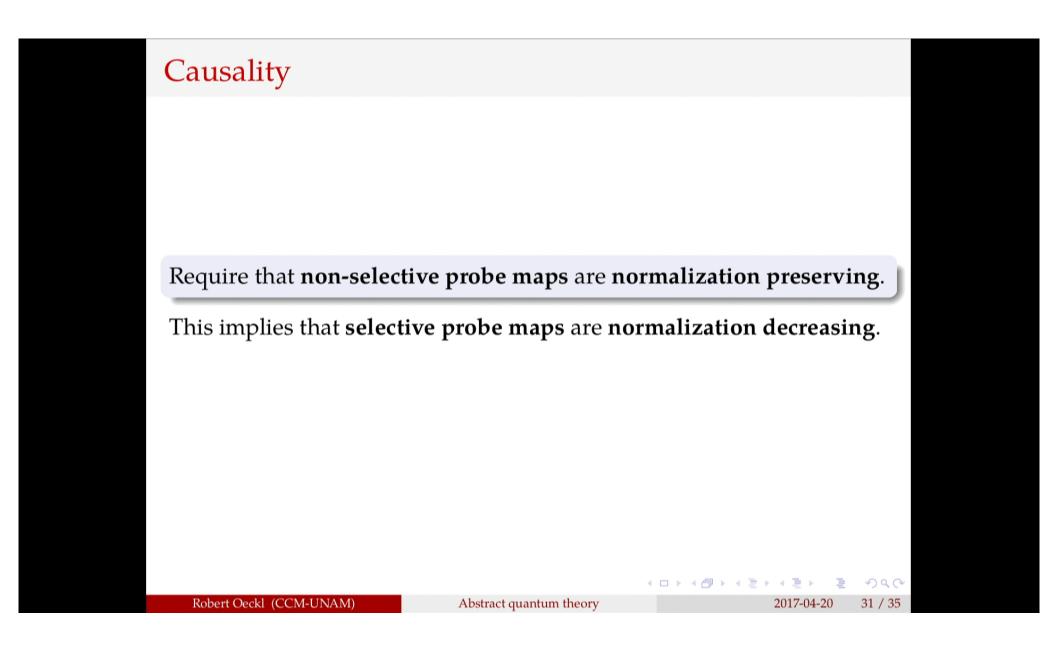
 $\tilde{P}: \mathcal{B} \to \mathcal{B}$ is **normalization decreasing** iff $(\mathbf{e}, \tilde{P}(b)) \leq (\mathbf{e}, b)$ for all $b \in \mathcal{B}$.

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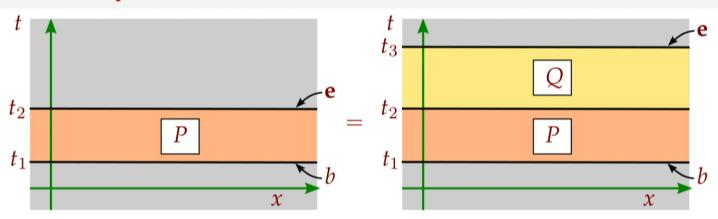
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Causality



Consider a binary measurement given by non-selective probe P_* and selective probe P_r . Possibly, a later measurement is performed given by non-selective probe Q.

The probability Π of an affirmative outcome of the first measurement does not depend on the second measurement being performed or not.

$$\Pi = \frac{\langle |\mathbf{e}, \tilde{P}_r(b)| \rangle}{\langle |\mathbf{e}, \tilde{P}_*(b)| \rangle} = \frac{\langle |\mathbf{e}, \tilde{Q}(\tilde{P}_r(b))| \rangle}{\langle |\mathbf{e}, \tilde{Q}(\tilde{P}_*(b))| \rangle}$$

Note: If b is normalized the denominators are equal to 1.

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Time-asymmetry

The normalization conditions for probe maps are **time-asymmetric**. The normalization preserving condition,

$$\{\mathbf{e},b\} = \{\mathbf{e},\tilde{P}(b)\} \qquad \forall b \in \mathcal{B}$$

reads in the general formalism as,

$$\llbracket \boxtimes, b \otimes \mathbf{e} \rrbracket = \llbracket P, b \otimes \mathbf{e} \rrbracket \qquad \forall b \in \mathcal{B}.$$

The time-reversed condition reads,

$$\llbracket \boxtimes, \mathbf{e} \otimes b \rrbracket = \llbracket P, \mathbf{e} \otimes b \rrbracket \qquad \forall b \in \mathcal{B}.$$

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Classical and quantum theory

If we take \mathcal{B} to be a **lattice**, i.e., the space of real valued functions on a set (**phase space**) we obtain **classical statistical mechanics**.

- e = 1 the constant function with value 1.
- $(\cdot, \cdot) = \int \cdot \cdot d\mu$ the L² inner product
- certain probe maps describe observables, others describe modified dynamics

If we take \mathcal{B} to be an **anti-lattice**, i.e., the space of self-adjoint operators on a Hilbert space \mathcal{H} , we obtain **quantum statistical mechanics**.

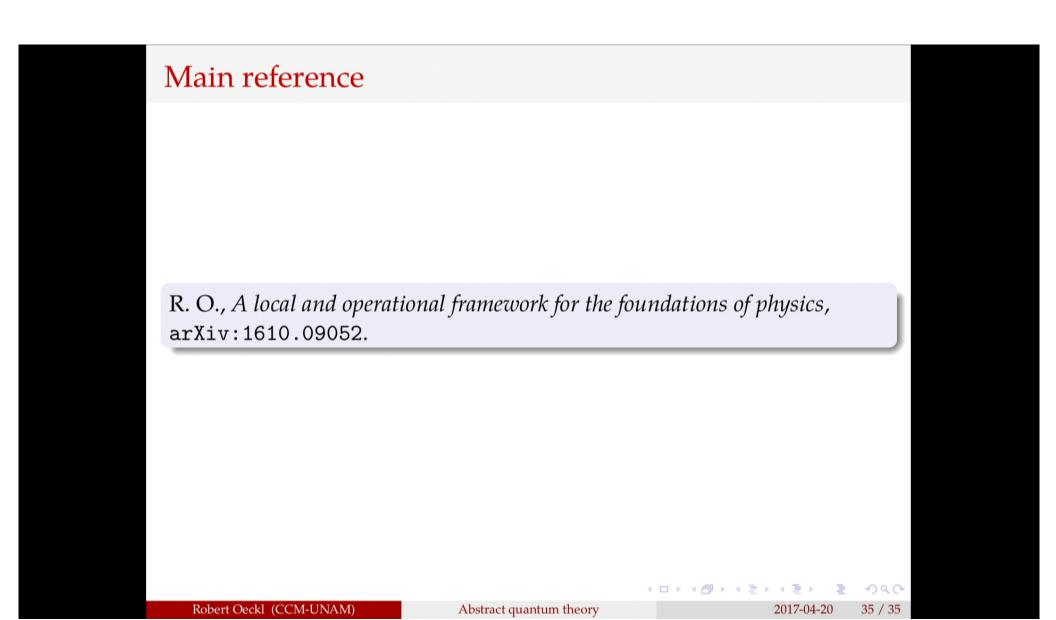
- $e = id_{\mathcal{H}}$ the identity operator
- $(\cdot, \cdot) = tr(\cdot)$ the Hilbert-Schmidt inner product
- primitive probe maps are quantum operations

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Abstract quantum theory

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