

Title: PSI 2016/2017 Explorations in Quantum Gravity - Lecture 7

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Abstract:

$$S = \int d^3x \sqrt{g} \mathcal{R} - \int e_{\alpha}^{\mu} F_{\mu\nu}^{\rho} \tilde{E}^{\sigma\mu\nu} d^3x$$

Canonical variables: $A_a^j ; E_b^k$

From e.o.m \rightarrow get constraints \rightarrow Gauss
 \searrow Flatness

\rightsquigarrow Smear out \rightarrow

$$\begin{aligned} \delta_{\Lambda} E_i^a &= \epsilon_{jmk} E^{am} \Lambda^k \\ \delta_{\Lambda} A_a^j &= -(\partial_a \Lambda^j + \epsilon_{im}^j A_a^i \Lambda^m) \end{aligned}$$

Dirac Quantization

- ① Phase space variables \rightarrow Operators, $\mathcal{H}_{kin} \xrightarrow{L^2(\mathbb{R}^2)}$ (q, t, p_q, p_t)
 \downarrow
 $q \frac{\partial}{\partial q}, t \frac{\partial}{\partial t}, -\frac{i\hbar}{2q} \frac{\partial}{\partial q}, -\frac{i\hbar}{2t} \frac{\partial}{\partial t}$
- ② Constraints \rightarrow Self-Adjoint op in $\mathcal{H}_{kin} \rightarrow$ Schrödinger eqn.
- ③ Constraints + Inner Product $\rightarrow \mathcal{H}_{phys}$
- ④ Find complete set of gauge invariant observables $\rightarrow \hat{F}_1, \hat{F}_2$

◦ Quantum Geometry

↳ Basic variables: holonomies

↳ Basic variables: fluxes

1st step
of
DIRAC
PROGRAM.

Dirac program to 3d gravity \rightarrow Basic variables

- $\{f, g\}$ form an algebra.

- transform in a simple way under gauge transfo.

- Δ field theory $\{ \phi(x), \pi(y) \} = \delta(x, y)$ distribution

Dirac program to 3d gravity \rightarrow Basic variables

- $\{f, g\}$ form an algebra

transform in a simple way under gauge transfo.
field theory $\{\phi(x), \pi(y)\} = \delta(x, y)$ distribution

\hookrightarrow need to smear the functions

Solution: to smear the basic

Find complete set of gauge invariant observables $\rightarrow \Gamma_1$
 $\rightarrow \Gamma_{\mathbb{P}^1}$

Dirac program to 3d gravity \rightarrow Basic variables

- $\{f, g\}$ form an algebra

- transform in a simple way under gauge transfo.

- Δ field theory $\{\phi(x), \pi(y)\} = \delta(x, y)$ distribution

\hookrightarrow need to smear the functions

Solution: to smear the basic variables over k -dimensional hypersurfaces and the conjugated variables over $(d-k)$ d ones

\hookrightarrow need to smear variables over k -dimensional configuration
 Solution: to smear the basic variables over k -dimensional configuration
 \hookrightarrow LQG holonomies-fluxes \Rightarrow

• Configuration, connection = 1-form
 \hookrightarrow integrate over one dimensional object: curve $\gamma \rightarrow$ holonomy (finite, // transport along γ)



$$\begin{aligned}
 \text{hol}_\gamma[A] &\in \text{SU}(2) \\
 \text{hol}_\gamma[A] &= \text{Pexp} \int_\gamma A
 \end{aligned}$$

• Conjugated variables, triads \rightarrow co-triad (one-form) $e_a = e_a^d T_d = \epsilon_{ab} E^{bj} T^d$ smeared over a curve γ^a
 $T_d = \frac{i}{2} \sigma_d$ $[T_i, T_j] = \epsilon_{ijk} T^k$ (su(2) algebra)
 \hookrightarrow Lie algebra one form

Transformer of basic fields Lie algebra valued objects.

$$g \in \text{SU}(2) \quad R_k^l(g) T_l = \bar{g}^i \cdot T_k \cdot g \quad (\text{adjoint representation of SU}(2) \Rightarrow \text{vector rep. of SO}(3) \text{ on its Lie algebra})$$

n^k We have seen that e_a^i, F_{ab}^i with internal index i transform in the vector representation of the rotation group.

$$\underbrace{n^k R_k^l(g) T_l}_{(R^i(j) n)^l} = \bar{g}^i (n^k T_k) g \Rightarrow (R(g) n)^j T_j = g (n^k T_k) \cdot \bar{g}^i$$

$$E_a^i \rightarrow R_{jk}^i E_a^k \rightarrow E^a = E_b^i T^b$$

Transformation of basic fields. Lie algebra valued objects.

$g \in \text{SU}(2)$ $\cdot R_k^l(g) T_l = \bar{g}^{-1} \cdot T_k \cdot g$ (adjoint representation of $\text{SU}(2)$ (\Rightarrow vector rep. of $\text{SO}(3)$) on its Lie algebra)

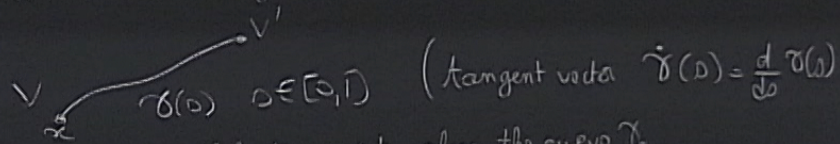
We have seen that e_a^d, F_{ab}^d with internal index j transform in the vector representation of the rotation group.

$$\underbrace{N^k R_k^l(g) T_l}_{(R^l(g) N)^d} = \bar{g}^{-1} (N^k T_k) g \Rightarrow \left[\begin{array}{l} (R(g) N)^d T_j = g (N^k T_k) \bar{g}^{-1} \\ E_a^b \rightarrow R_k^d E_a^k \rightarrow E^a = E_a^b T^b \rightarrow \left[g E^a \bar{g}^{-1} \right] \\ F_{ab} = F_{ab}^d T_d \rightarrow \left[g F_{ab} \bar{g}^{-1} \right] \end{array} \right]$$

n^k We have seen that e_a^i, F_{ab}^d with internal index j transform the vector representation of the rotation group
 $(R^k(g) n^l) T_l = g^i (n^k T_k) \cdot g^{-1}$
 $(R^{-1}(g) n^l) T_l = g^i (n^k T_k) \cdot g^{-1}$
 $E_a^b \rightarrow R_{ab}^c E_c^d \rightarrow E^a = E_a^b T^b \rightarrow \left[g E^a g^{-1} \right]$
 $F_{ab} = F_{ab}^c T_c \rightarrow \left[g F_{ab} g^{-1} \right]$

$$\hookrightarrow g A_a g^{-1} + g \dot{a}_a g^{-1}$$

Holonomy Given an internal vector $V = V^j T_j$ at a point σ



\Rightarrow parallel transport along the curve γ_s

V transforms in the adjoint rep

So we define the // transport of V by $\left[V(s) = h(s) V(0) h(s)^{-1} \right]$ $h(s)$ holonomy from $\gamma(0) = x$ to $\gamma(s)$

→ the transformation under local gauge transfo. $g(x) \in SU(2)$ of the holonomy

$$h(s) \rightarrow g(\gamma(s)) h(s) g(\gamma(0))^{-1}$$

Covariant derivative with the motivation to // transport objects

$$D_a V = \partial_a V + [A_a, V]$$

$$([A_a^i T_i, V^j T_j] = A_a^i V^j [T_i, T_j])$$

Le algebra valued scalar

$$\partial_a \omega^i = \partial_a \omega^i + \epsilon_{ijk} A_a^j \omega^k$$

Solution to smear the basic variables configuration

LAG holonomy-flux

• configuration connection = 1-form
 dimensional object: curve γ → holonomy (finite // transport along γ)

Solution to smear the basic variables configuration

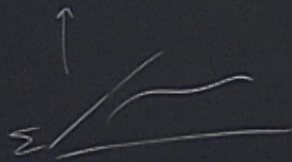
\Rightarrow LQG holonomy-frames

• configuration connection = 1-form

\hookrightarrow integrate over one dimensional object: curve $\gamma \rightarrow$ holonomy (finite // transport along γ)

$$h_\gamma[A] \in \text{SU}(2)$$

$$h_\gamma[A] = \text{Pexp} \int_\gamma A$$



• conjugated variables triads \rightarrow co-triad (one-form) $e_a = e_a^d T_d = \epsilon_{ab} E^{bj} T^j$ smeared over a curve γ^*

$$T_j = \frac{i}{2} \sigma_j$$

$$[T_i, T_j] = \epsilon_{ijk} T^k$$

($\text{su}(2)$ algebra)

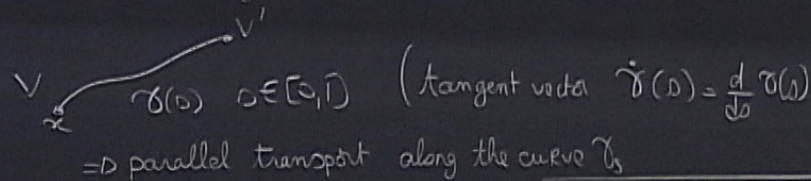
\hookrightarrow Lie values one form

N^k We have seen that e_a^d, F_{ab}^d with internal index j transform the vector representation of the rotation group.

$$\hookrightarrow g A_a g^{-1} + g \partial_a g^{-1}$$

$$\begin{aligned}
 N^k R_k^l(g) T_l &= g' (N^k T_k) g \Rightarrow (R(g) N^j) T_j = g (N^k T_k) g^{-1} \\
 E_a^j &\rightarrow R_k^j E_a^k \rightarrow E^a = E_j^a T^j \rightarrow g E^a g^{-1} \\
 F_{ab} &= F_{ab}^d T_d \rightarrow g F_{ab} g^{-1}
 \end{aligned}$$

Holonomies Given an internal vector $V = V^a T_a$ at a point σ



V transforms in the adjoint rep.
 So we define the // transport of V by $V(s) = h(s) V(0) h(s)^{-1}$ $h(s)$ holonomy from $\sigma(0) = \sigma$ to $\sigma(s)$

using \otimes

$$= \left(\frac{d h(s)}{ds} \right) V(s) h(s) + \dots$$

$$= \left[\frac{d h(s)}{ds} h^{-1}, h V h^{-1} \right] + \left[\dot{\gamma}^a A_a, h V h^{-1} \right]$$

$$\Rightarrow \boxed{\frac{d h}{ds} = - \dot{\gamma}^a A_a(\gamma(s)) h(s)}$$

differential eq with initial condition $h(s)=1$

* e_1 e_2

$$h(A) = h_{e_1}(A) h_{e_2}(A)$$

* e

$$h_{e^{-1}}(A) = h_e^{-1}(A)$$

step by step

$$h(s) = 1 - \int_0^s \dot{\gamma}^a A_a(\gamma(s')) h(s') ds'$$

\hookrightarrow iterate this kind solution

$$\rightarrow h_{\gamma}(s) = \mathbb{P} \exp \left[- \int_0^s A \right] = \sum_{n=0}^{\infty} (-1)^n \int_0^s ds_n \int_0^{s_{n-1}} ds_{n-1} \dots \int_0^{s_2} ds_2 A(s_2) A(s_{n-1}) \dots A(s_2) A(s_1)$$

where $A(s) = \dot{\gamma}^a(s) A_a(\gamma(s))$