Title: Direct experimental reconstruction of the Bloch sphere

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Abstract: The scientific journey from the first hints of quantum behaviour to the Bloch sphere in your textbook was a long and tortuous one. But using some of the technological and conceptual fruits of that journey, we show that an experiment can manifest the Bloch sphere via an analysis that doesn't require any quantum theory at all. Our technique is to fit experimental data to a generalised probabilistic theory, which allows us to infer both the dimension and shape of the state and measurement spaces of the system under study. We test our technique on an experiment measuring a variety of single-photon polarization states. As expected, the reconstructed state space closely resembles the Bloch sphere, and we are able to place small upper bounds on how much the true theory describing our experiment could possibly deviate from quantum mechanics.

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#### Information processing in generalized probabilistic theories

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I introduce a framework in which a variety of probabilistic theories can be defined, including classical and quantum theories, and many others. From two simple assumptions, a tensor product rule for combining separate systems can be derived. Certain features, usually thought of as specifically quantum, turn out to be generic in this framework, meaning that they are present in all except classical theories. These include the nonunique decomposition of a mixed state into pure states, a theorem involving disturbance of a system on measurement (suggesting that the possibility of secure key distribution is generic), and a no-cloning theorem. Two particular theories are then investigated in detail, for the sake of comparison with the classical and quantum cases. One of these includes states that can give rise to arbitrary nonsignaling correlations, including the superquantum correlations that have become known in the literature as nonlocal machines or Popescu-Rohrlich boxes. By investigating these correlations in the context of a theory with well-defined dynamics, I hope to make further progress with a question raised by Popescu and Rohrlich, which is why does quantum theory not allow these strongly nonlocal correlations? The existence of such correlations forces much of the dynamics in this theory to be, in a certain sense, classical, with consequences for teleportation, cryptography, and computation. I also investigate another theory in which all states are local. Finally, I raise the question of what further axiom(s) could be added to the framework in order to identify quantum theory uniquely, and hypothesize that quantum theory is optimal for computation.

DOI: 10.1103/PhysRevA.75.032304 PACS number(s): 03.67.-a, 03.65.Ta

#### I. INTRODUCTION

A question periodically raised is what is responsible for the power of quantum computation (or cryptography, or information processing in general)? At a recent meeting in broad range of different theories can be defined. The framework, described in Secs. II–IV, is based on that used by Hardy in his derivation of quantum theory from simple axioms [14]. The basic idea is that a state is represented as a



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#### Quantum Theory From Five Reasonable Axioms

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Selected for a Viewpoint in Physics

PHYSICAL REVIEW A 84, 012311 (2011)

#### Informational derivation of quantum theory

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We derive quantum theory from purely informational principles. Five elementary axioms—causality, perfect distinguishability, ideal compression, local distinguishability, and pure conditioning—define a broad class of theories of information processing that can be regarded as standard. One postulate—purification—singles out quantum theory within this class.

DOI: 10.1103/PhysRevA.84.012311

I. INTRODUCTION

the very beginning. Von Neumann himself expressed

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$$p(k|\mathcal{P}_i,\mathcal{M}_j)$$

Ø



$$\begin{pmatrix}
1 & p(0|\mathcal{P}_{1}, \mathcal{M}_{1}) & p(0|\mathcal{P}_{1}, \mathcal{M}_{2}) & \dots \\
1 & p(0|\mathcal{P}_{1}, \mathcal{M}_{1}) & p(0|\mathcal{P}_{1}, \mathcal{M}_{2}) & \dots \\
1 & p(0|\mathcal{P}_{2}, \mathcal{M}_{1}) & p(0|\mathcal{P}_{2}, \mathcal{M}_{2}) & \dots \\
1 & p(0|\mathcal{P}_{3}, \mathcal{M}_{1}) & p(0|\mathcal{P}_{3}, \mathcal{M}_{2}) & \dots \\
\vdots & \vdots & \vdots & \ddots
\end{pmatrix}$$

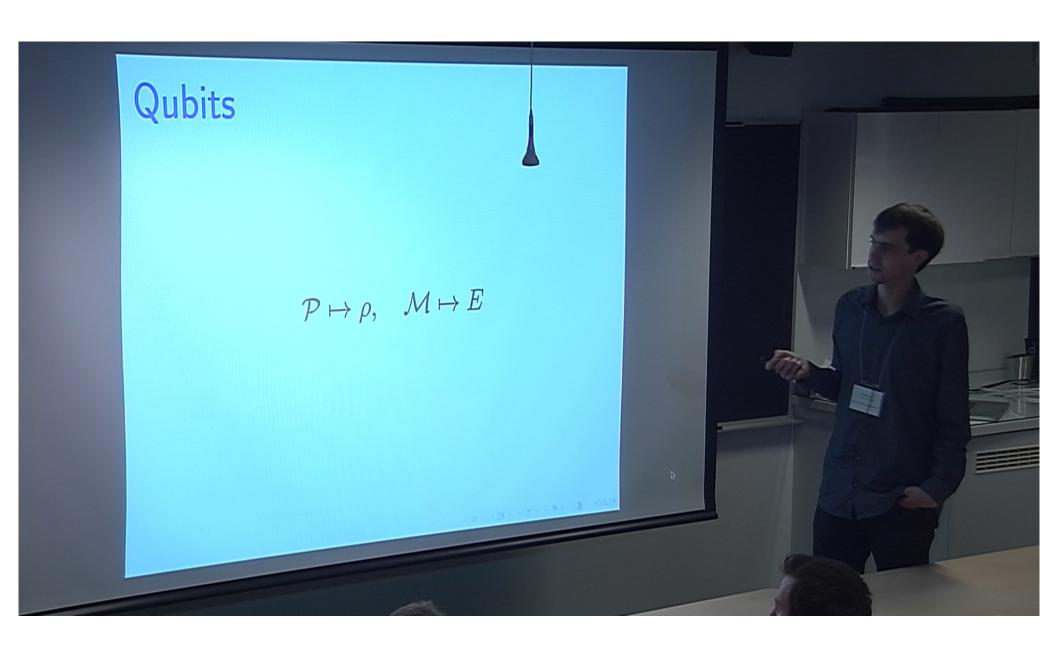
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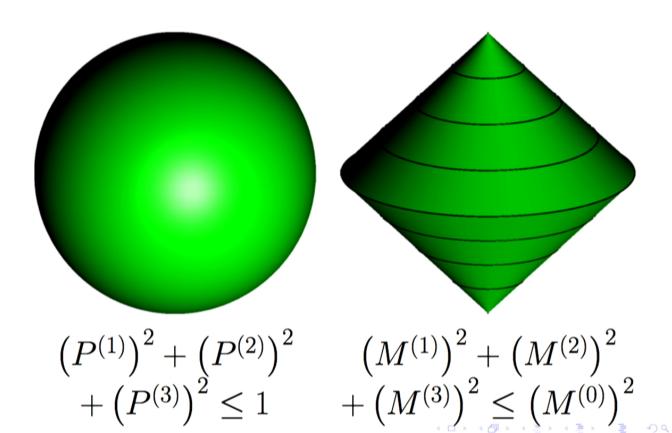
$$\begin{pmatrix}
1 & P_1^{(1)} & P_1^{(2)} & P_1^{(3)} \\
1 & P_2^{(1)} & P_2^{(2)} & P_2^{(3)} \\
1 & P_3^{(1)} & P_3^{(2)} & P_3^{(3)} \\
\vdots & \vdots & \vdots & \vdots
\end{pmatrix}
\begin{pmatrix}
1 & M_1^{(0)} & M_2^{(0)} & \dots \\
0 & M_1^{(1)} & M_2^{(1)} & \dots \\
0 & M_1^{(2)} & M_2^{(2)} & \dots \\
0 & M_1^{(3)} & M_2^{(3)} & \dots
\end{pmatrix}$$

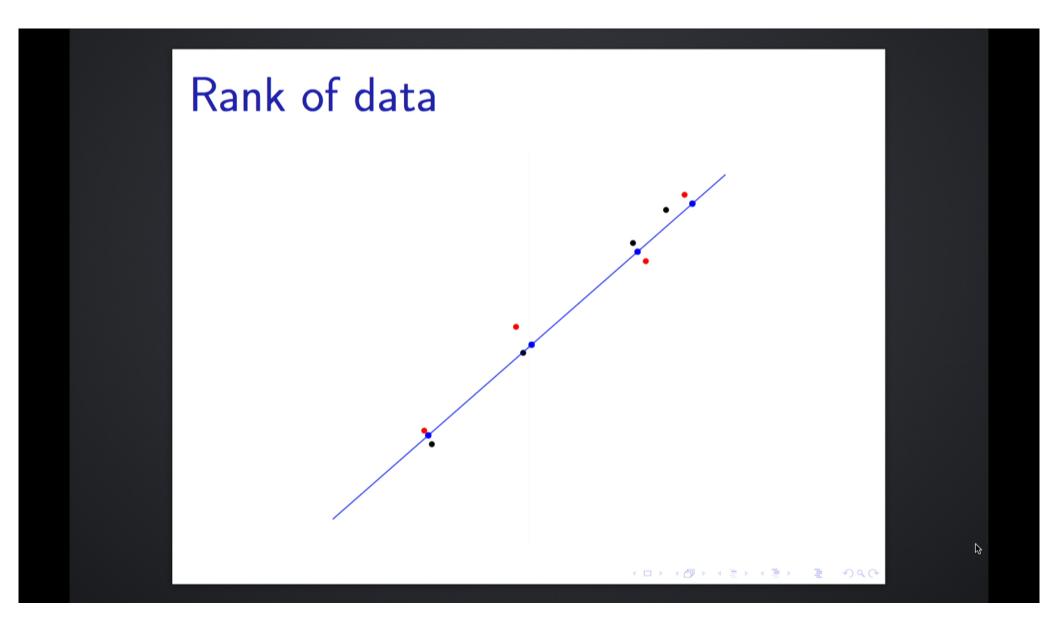
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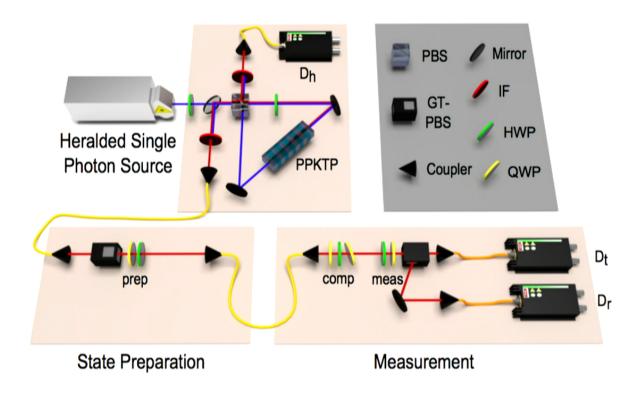
### Rank of data

minimize 
$$\sum_{i,j} \frac{(D_{i,j} - F_{i,j})^2}{(\sigma_{i,j})^2}$$
 subject to  $\operatorname{rank}(F) = r$ 

Δ



# Experimental setup

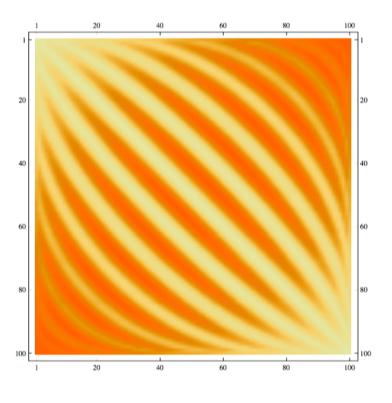


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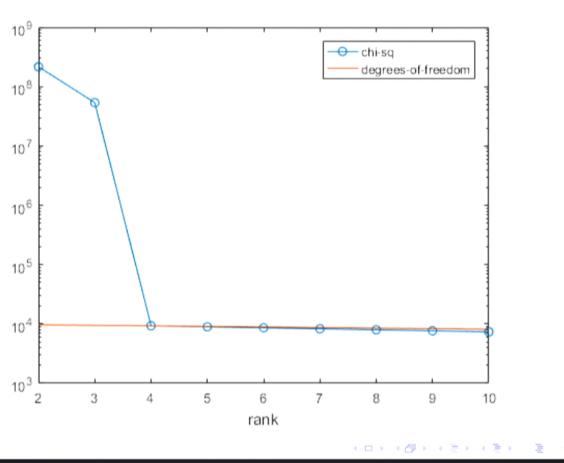




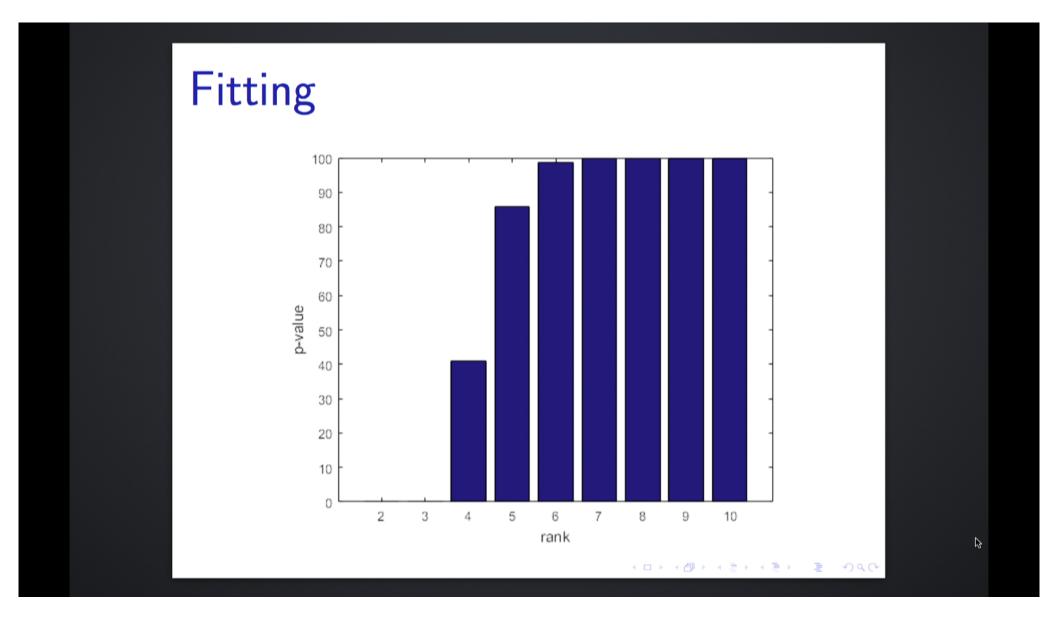
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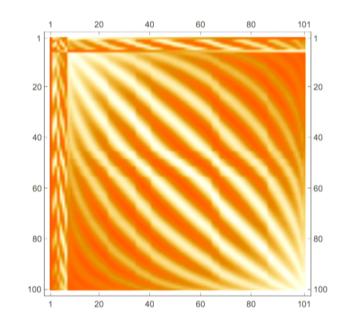


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# Predictive power



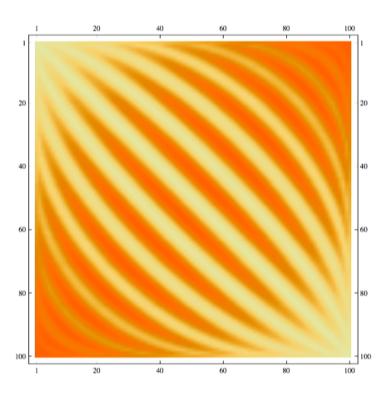
Model rank	RMSE
4	0.003
5	0.003 0.006 0.035
6	0.035

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## Fitted rank-4 GPT



$$P=41\%$$

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## Singular value decomposition

$$D_{(m\times n)} \to F_{(m\times n)} = P M_{(m\times r)(r\times n)}$$

1



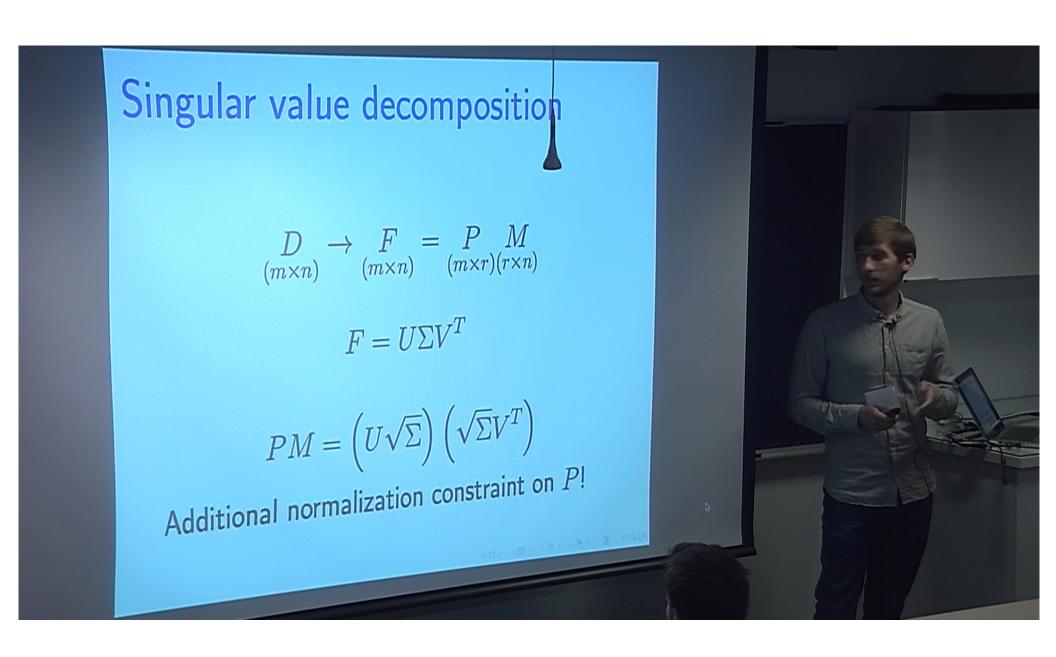
## Singular value decomposition

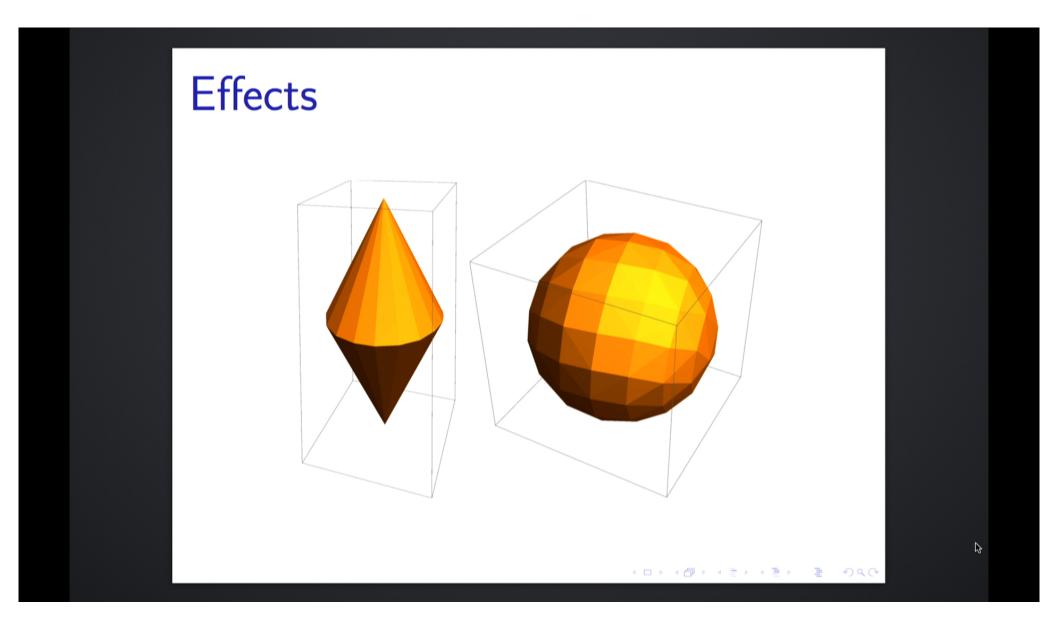
$$D_{(m\times n)} \to F_{(m\times n)} = P M_{(m\times r)(r\times n)}$$

$$F = U\Sigma V^T$$

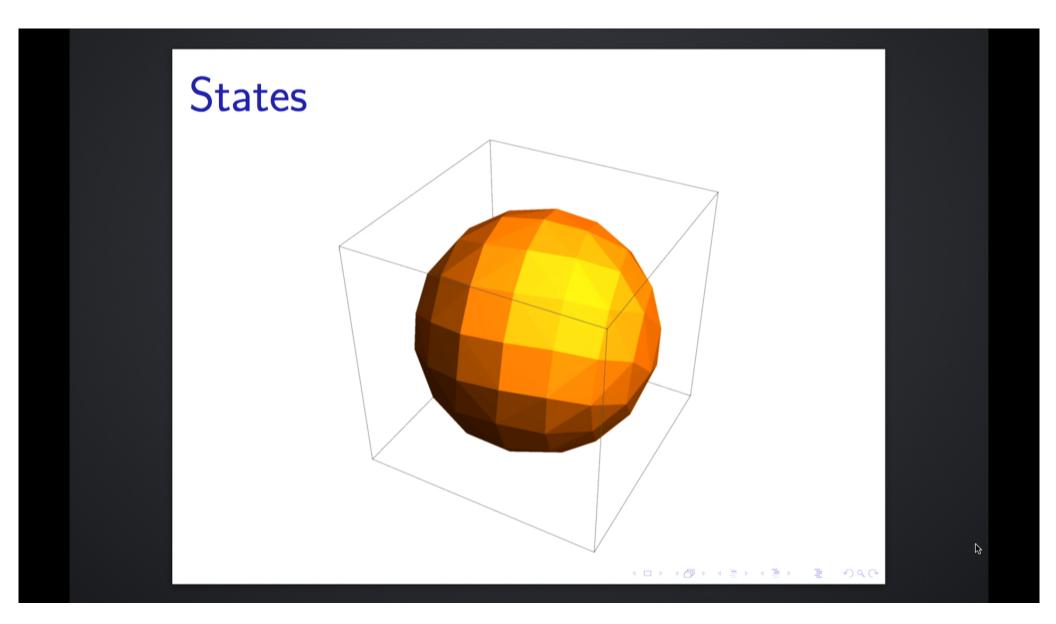
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## Dual of effects

- Measured state space incomplete
  - noise, finite number
- Dual effect space contains all logically-valid state vectors

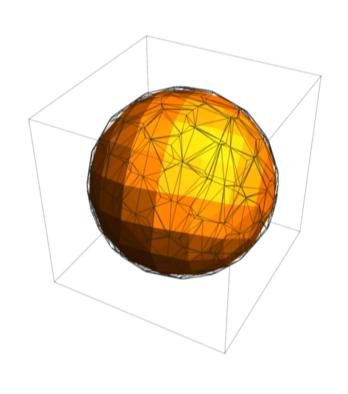
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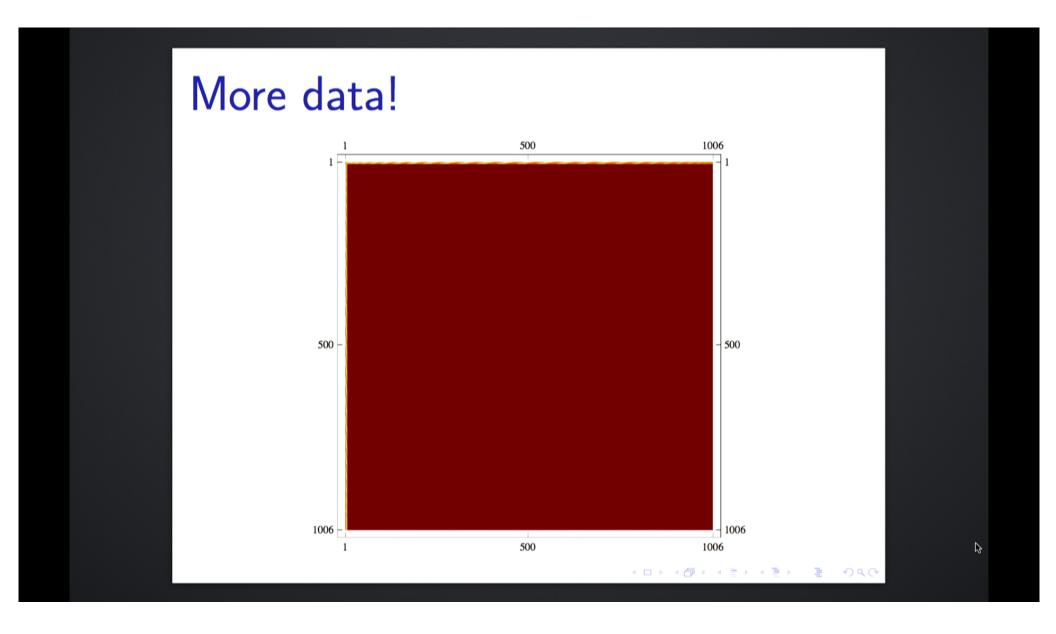
## Dual of effects

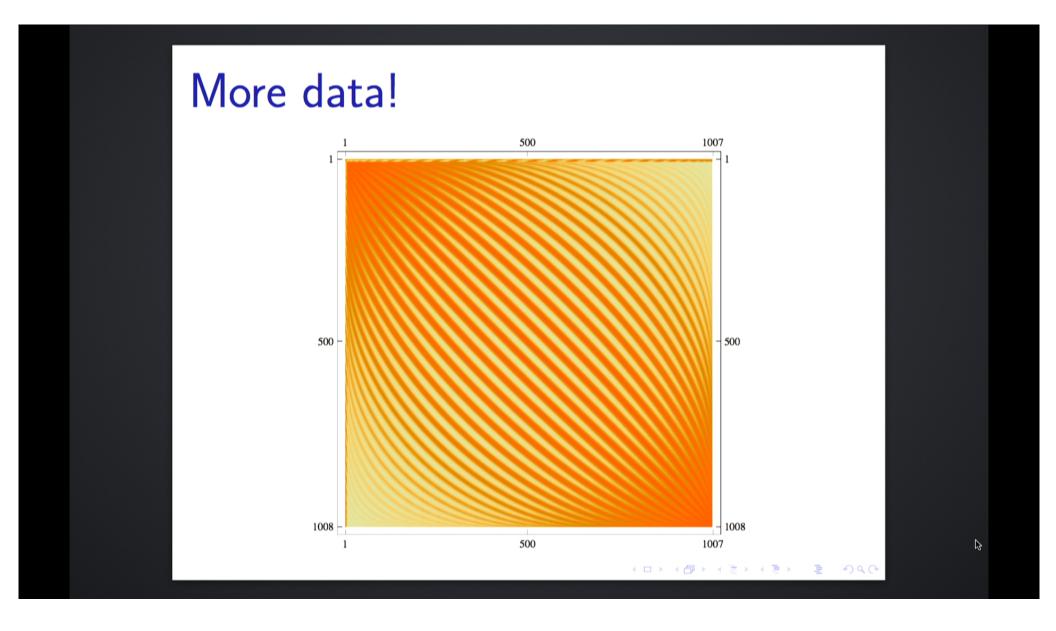
- Measured state space incomplete
  - noise, finite number
- Dual effect space contains all logically-valid state vectors
  - LV-states return valid probabilities



**N** 







# Duality gap

- GPT-of-best-fit not quite self-dual.
  - True spaces are somewhere in-between
- Compare (4-d) volumes of spaces
- ▶ 100 x 100 data:

$$V_P/V_{\bar{E}} = 0.91267 \pm 0.00001$$

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- GPT-of-best-fit not quite self-dual.
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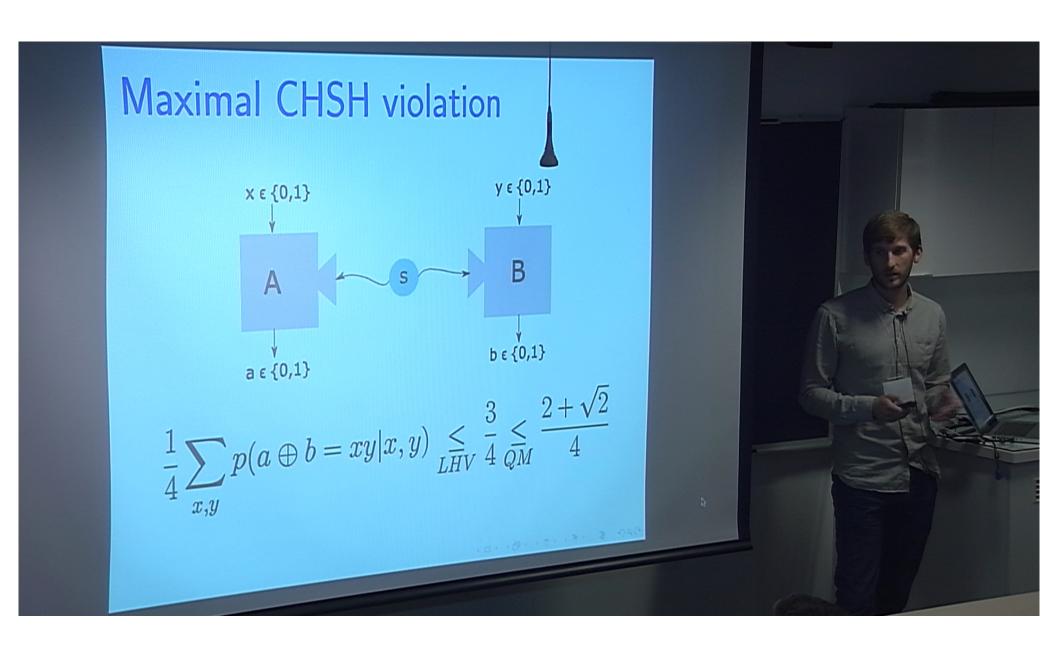
$$V_P/V_{\bar{E}} = 0.91267 \pm 0.00001$$

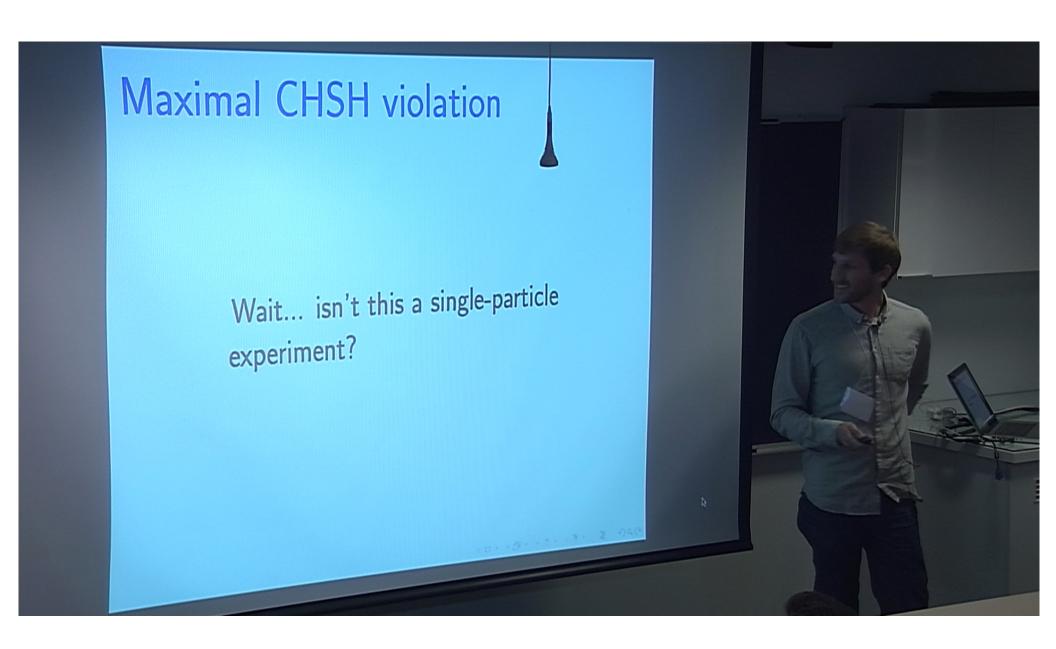
▶ 1000 x 1000 data:

$$V_P/V_{\bar{E}} = 0.968 \pm 0.001$$

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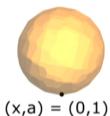


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 Assume Alice's measurement choice and outcome steers Bob's state



$$(x,a) = (0,0)$$



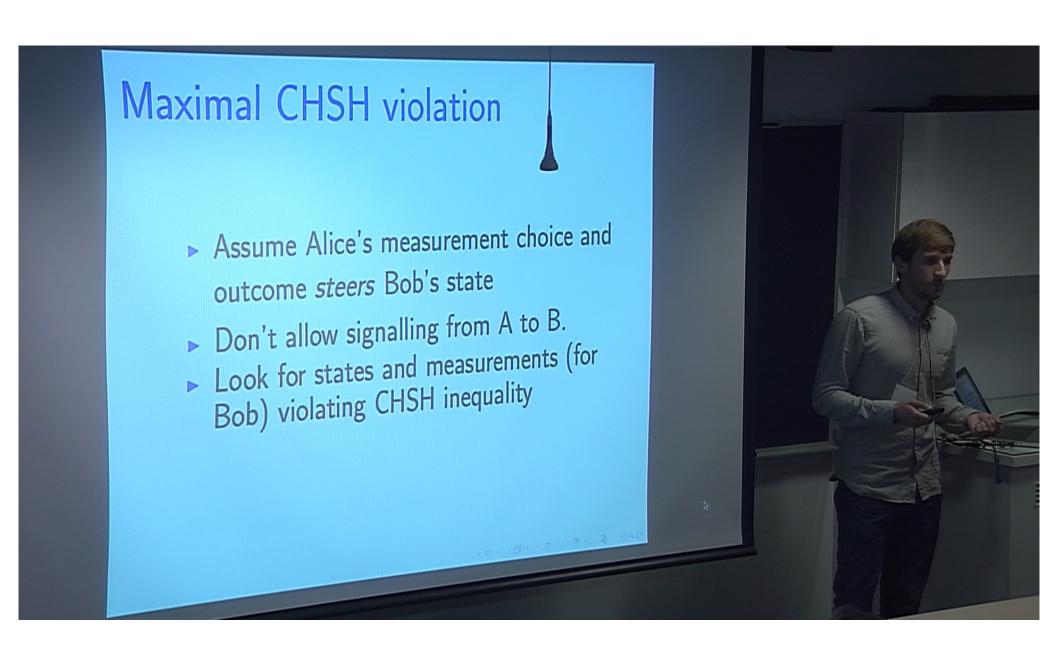
$$(x,a) = (1,0)$$

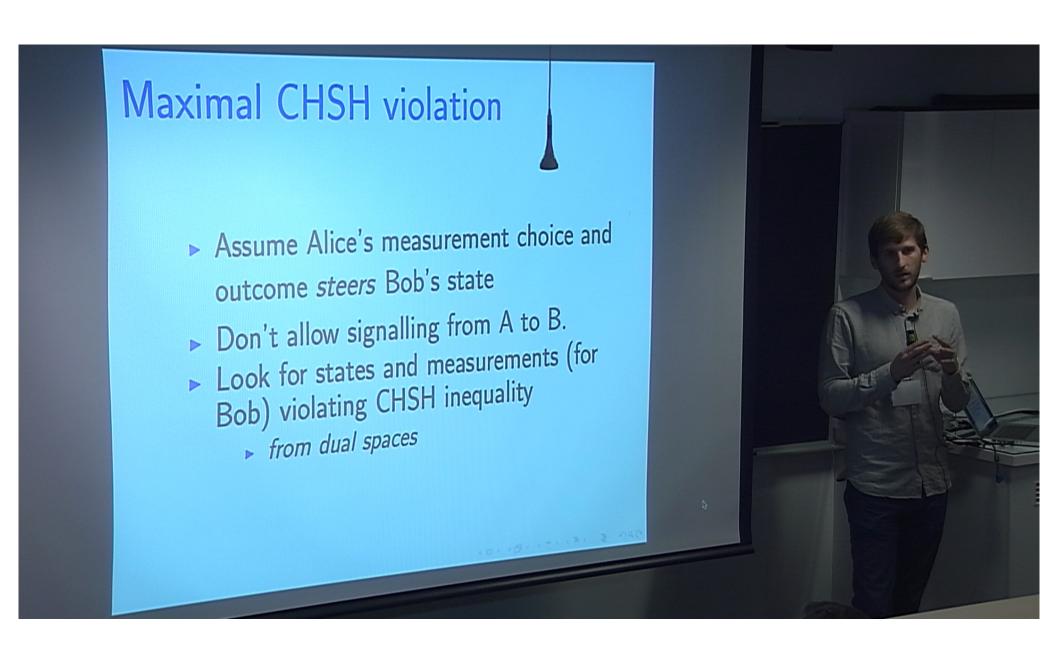


(x,a) = (1,1)

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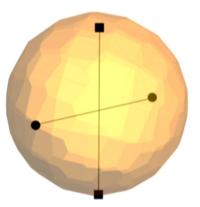






- Choose two pairs of (extremal) effects for Bob from dual state space.
- Maximize violation without signalling

   over all normalized, steerable states
   from dual effect space (with an LP).



4 L 2 4 A D 2 4 E 2 4 E 4 O Q C

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- Choose two pairs of (extremal) effects for Bob from dual state space.
- Maximize violation without signalling

   over all normalized, steerable states
   from dual effect space (with an LP).
- Repeat for all pairs of Bob's measurements, keep maximum violation

^



For our GPT-of-best-fit we find

$$\frac{1}{4} \sum_{x,y} p(a \oplus b = xy | x, y) \le 0.87196 \pm 0.00006$$

Maximal QM value:

$$\frac{2+\sqrt{2}}{4} \approx 0.85355$$

 $\triangleright$ 



### Future work

- ▶ POVMs
- Transformations
- ► Higher dimensions!
- ▶ Treatment of errors
- Other systems

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