

Title: Front End - Mathematica - 2

Date: Aug 26, 2016 10:30 AM

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Abstract:

Solving Partial Differential Equations Approximately

PSI Lecture, 2016-08-26

Erik Schnetter

Discretization

Basis functions

`n = 4`

```
Plot[Table[ChebyshevT[i, x], {i, 0, n}], {x, -1, +1}]
```

```
cheb[i_, x_] := If[i == 0,  $\frac{1}{\sqrt{2}}$ , 1] ChebyshevT[i, x]
```

$$2 \int_{-1}^{+1} \frac{f(x)}{\sqrt{1-x^2}} dx$$

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Approximately

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Erik Schnetter

1. Approximate functions on a manifold
2. Find discrete versions of operators (e.g. derivative operator)
3. Solve a PDE (stationary heat equation)

Discretization

Basis functions

`n = 4`

```
Plot[Table[ChebyshevT[i, x], {i, 0, n}], {x, -1, +1}]
```

```
cheb[i_, x_] := If[i == 0,  $\frac{1}{\sqrt{2}}$ , 1] ChebyshevT[i, x]
```

```
chebInt[f_] :=  $\frac{2 \int_{-1}^{+1} \frac{f[x]}{\sqrt{1-x^2}} dx}{\pi}$ 
```

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Approximately

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1. Approximate functions on a manifold
2. Find discrete versions of operators (e.g. derivative operator)
3. Solve a PDE (stationary heat equation)

Discretization

Manifold: Interval [-1; +1]

Basis functions

`n = 4`

```
Plot[Table[ChebyshevT[i, x], {i, 0, n}], {x, -1, +1}]
```

```
cheb[i_, x_] := If[i == 0,  $\frac{1}{\sqrt{2}}$ , 1] ChebyshevT[i, x]
```

```
∫+1  $\frac{f(x)}{\sqrt{2}}$  dx
```

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Approximately

PSI Lecture, 2016-08-26

Erik Schnetter

1. Approximate functions on a manifold
2. Find discrete versions of operators (e.g. derivative operator)
3. Solve a PDE (stationary heat equation)

Discretization

Manifold: Interval $[-1; +1]$

Choose basis

Truncate basis

Represent functions as coefficients for that basis

Basis functions

$n = 4$

```
Plot[Table[ChebyshevT[i, x], {i, 0, n}], {x, -1, +1}]
```

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Discretization

Manifold: Interval [-1; +1]

Choose basis

Truncate basis

Represent functions as coefficients for that basis

Basis functions

Keep 4 basis functions:

```
In[1]:= n = 4
```

```
Out[1]= 4
```

```
Plot[Table[ChebyshevT[i, x], {i, 0, n}], {x, -1, +1}]
```

```
cheb[i_, x_] := If[i == 0,  $\frac{1}{\sqrt{2}}$ , 1] ChebyshevT[i, x]
```

```
chebInt[f_] :=  $\frac{2 \int_{-1}^{+1} \frac{f[x]}{\sqrt{1-x^2}} dx}{\pi}$ 
```

```
Table[chebInt[cheb[i, #] cheb[i, #] &], {i, 0, n}, {i, 0, n}] // MatrixForm
```

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Discretization

Manifold: Interval [-1; +1]

Choose basis

Truncate basis

Represent functions as coefficients for that basis

Basis functions

Keep 4 basis functions:

```
In[1]:= n = 4
```

```
Out[1]= 4
```

Choose Chebyshev functions as basis

```
Plot[Table[ChebyshevT[i, x], {i, 0, n}], {x, -1, +1}]
```

```
cheb[i_, x_] := If[i == 0,  $\frac{1}{\sqrt{2}}$ , 1] ChebyshevT[i, x]
```

```
chebInt[f_] :=  $\frac{2 \int_{-1}^{+1} \frac{f[x]}{\sqrt{1-x^2}} dx}{\pi}$ 
```

```
Table[chebInt[cheb[i, #] cheb[i, #] &], {i, 0, n}, {i, 0, n}] // MatrixForm
```

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Basis functions

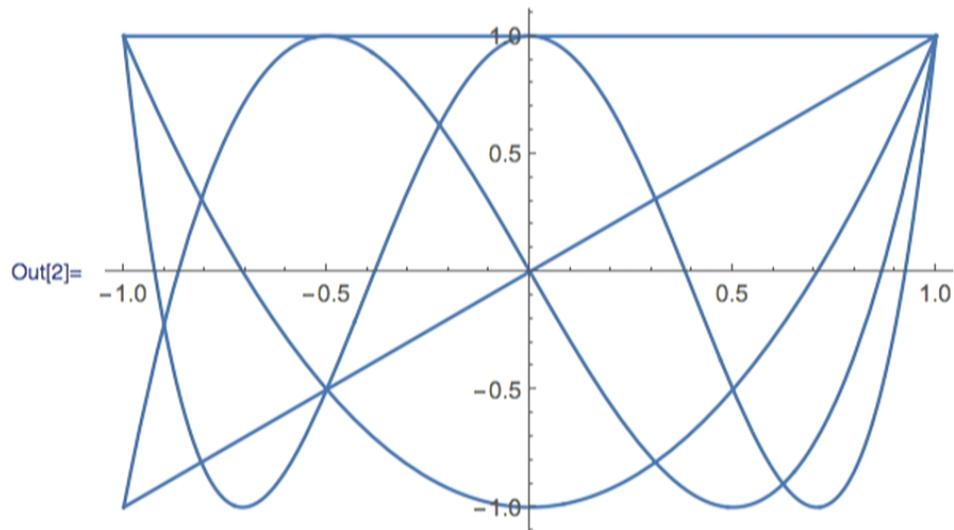
Keep 4 basis functions:

```
In[1]:= n = 4
```

```
Out[1]= 4
```

Choose Chebyshev functions as basis

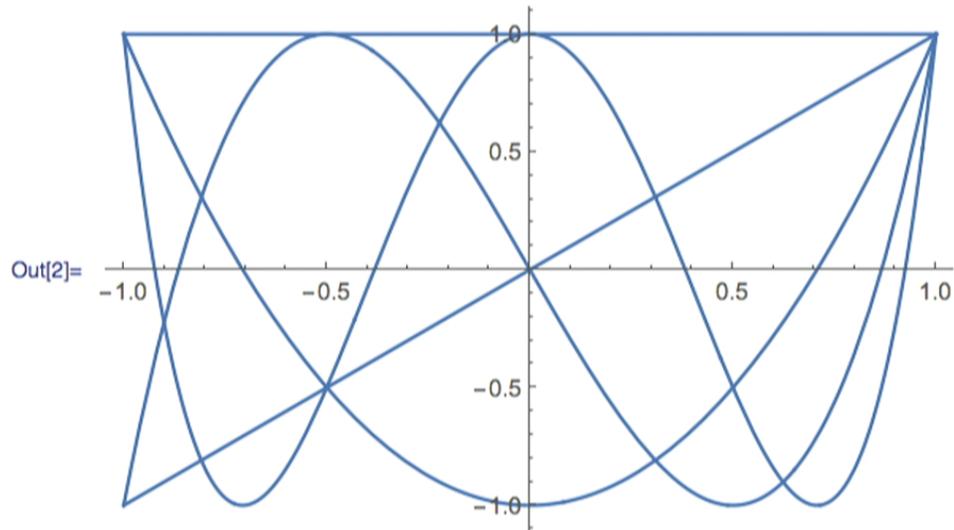
```
In[2]:= Plot[Table[ChebyshevT[i, x], {i, 0, n}], {x, -1, +1}]
```



```
cheb[i_, x_] := If[i == 0,  $\frac{1}{\sqrt{2}}$ , 1] ChebyshevT[i, x]
```

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```
In[2]:= Plot[Table[ChebyshevT[i, x], {i, 0, n}], {x, -1, +1}]
```



Chebyshev functions are orthogonal

```
cheb[i_, x_] := If[i == 0,  $\frac{1}{\sqrt{2}}$ , 1] ChebyshevT[i, x]
```

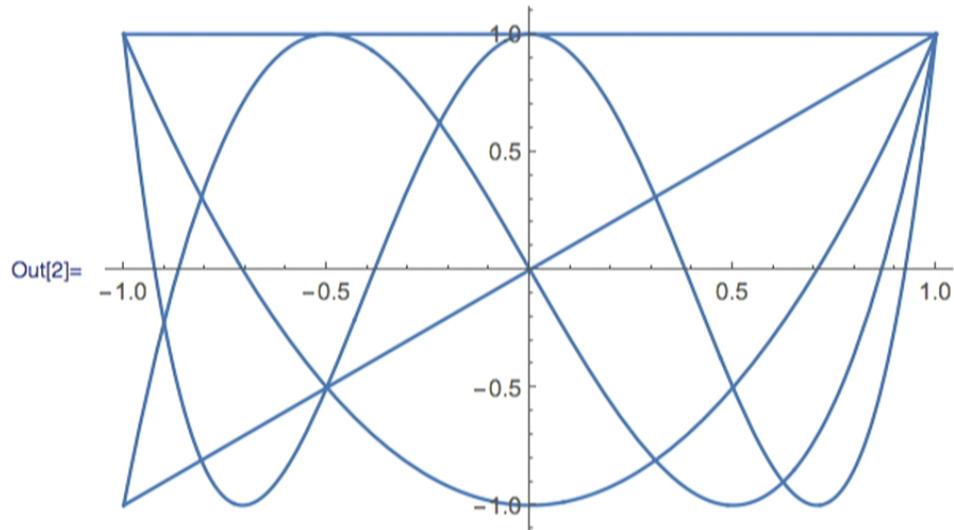
```
chebInt[f_] :=  $\frac{2 \int_{-1}^{+1} \frac{f[x]}{\sqrt{1-x^2}} dx}{\pi}$ 
```

```
Table[chebInt[cheb[i, #] cheb[j, #] &], {i, 0, n}, {j, 0, n}] // MatrixForm
```

Reconstruction and Projection onto basis

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```
In[2]:= Plot[Table[ChebyshevT[i, x], {i, 0, n}], {x, -1, +1}]
```



Chebyshev functions are orthogonal with respect to this integral

$$\text{chebInt}[f_] := \frac{2 \int_{-1}^{+1} \frac{f[x]}{\sqrt{1-x^2}} dx}{\pi}$$

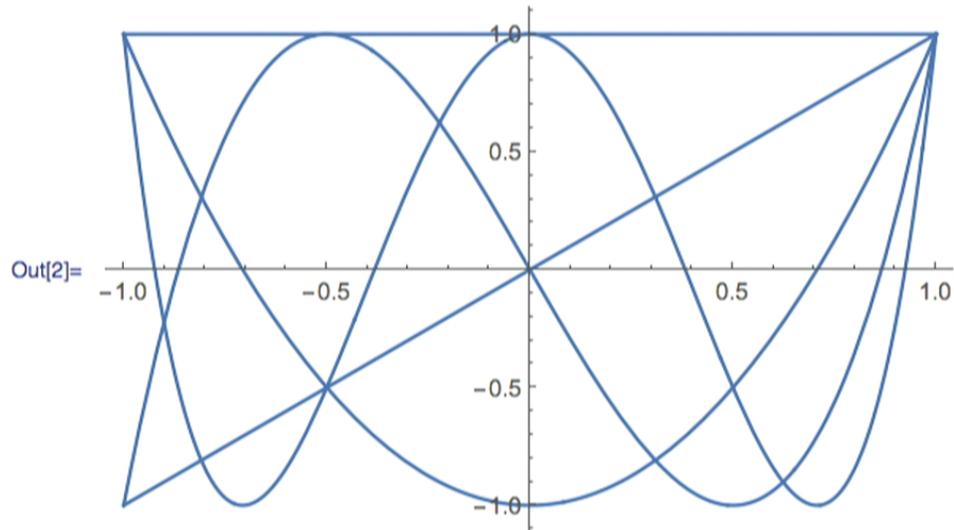
$$\text{cheb}[i_, x_] := \text{If}[i == 0, \frac{1}{\sqrt{2}}, 1] \text{ChebyshevT}[i, x]$$

```
Table[chebInt[cheb[i, #] cheb[j, #] &], {i, 0, n}, {j, 0, n}] // MatrixForm
```

Reconstruction and Projection onto basis

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```
In[2]:= Plot[Table[ChebyshevT[i, x], {i, 0, n}], {x, -1, +1}]
```



Chebyshev functions are orthogonal with respect to this integral

```
In[3]:= chebInt[f_] := 
$$\frac{2 \int_{-1}^{+1} \frac{f[x]}{\sqrt{1-x^2}} dx}{\pi}$$

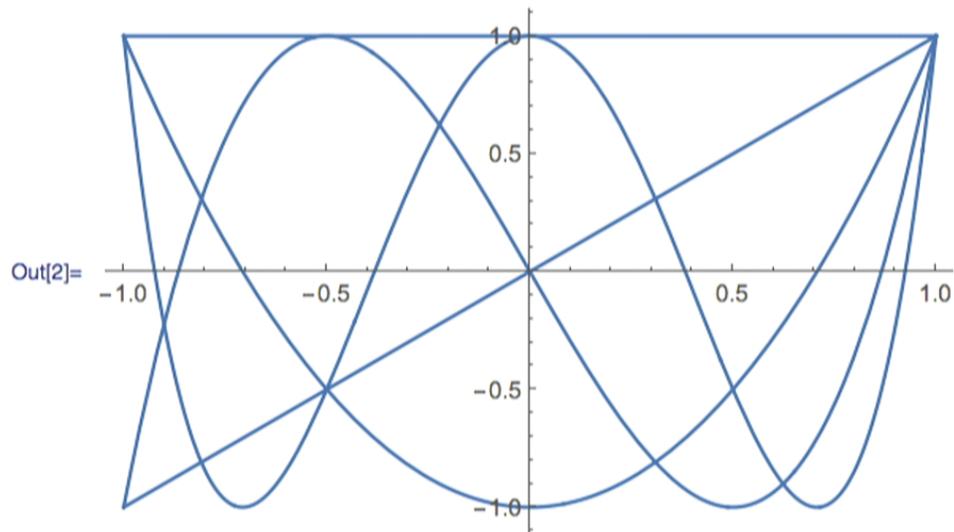
```

```
chebInt[ChebyshevT[0, #] ChebyshevT[0, #]]|
```

```
cheb[i_, x_] := If[i == 0,  $\frac{1}{\sqrt{2}}$ , 1] ChebyshevT[i, x]
```

```
Table[chebInt[cheb[i, #] cheb[j, #] &], {i, 0, n}, {j, 0, n}] // MatrixForm
```

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Chebyshev functions are orthogonal with respect to this integral

$$\text{In[3]:= } \mathbf{chebInt}[f_] := \frac{2 \int_{-1}^{+1} \frac{f[x]}{\sqrt{1-x^2}} dx}{\pi}$$

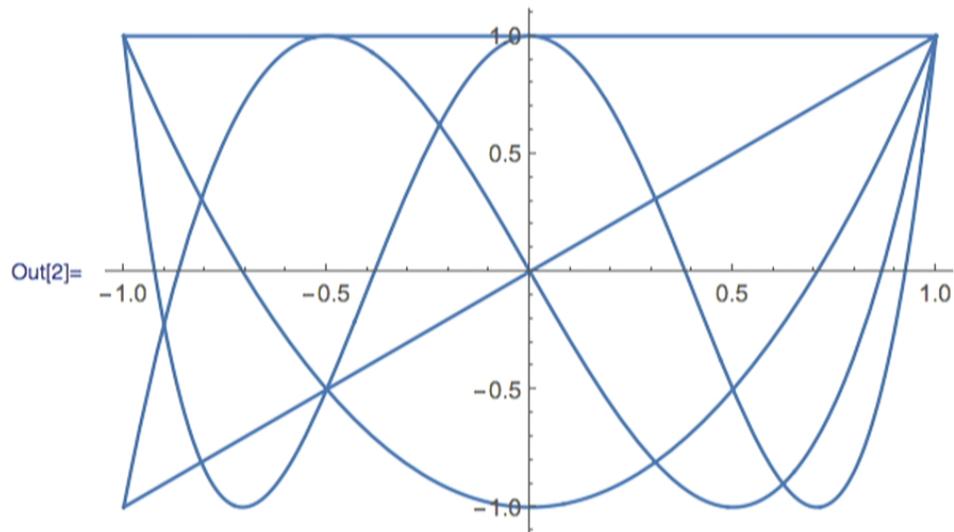
In[5]:= `chebInt[ChebyshevT[0, #] ChebyshevT[0, #] &]`

Out[5]= 2

```
cheb[i_, x_] := If[i == 0, 1/sqrt[2], 1] ChebyshevT[i, x]
```

```
Table[chebInt[cheb[i, #] cheb[j, #] &], {i, 0, n}, {j, 0, n}] // MatrixForm
```

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Chebyshev functions are orthogonal with respect to this integral

$$\text{In[3]:= } \text{chebInt}[f_] := \frac{2 \int_{-1}^{+1} \frac{f[x]}{\sqrt{1-x^2}} dx}{\pi}$$

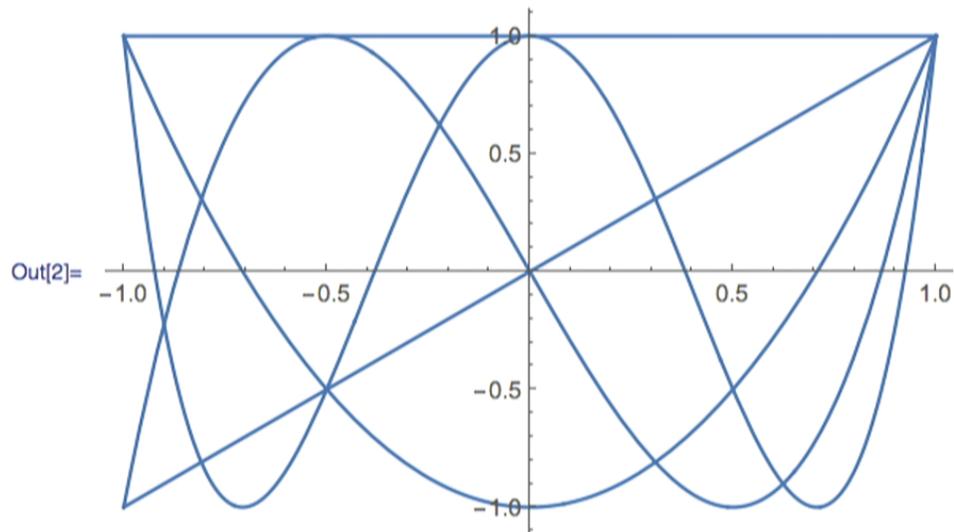
```
chebInt[ChebyshevT[1, #] ChebyshevT[1, #] &]
```

Out[5]= 2

```
cheb[i_, x_] := If[i == 0, 1/sqrt[2], 1] ChebyshevT[i, x]
```

```
Table[chebInt[cheb[i, #] cheb[j, #] &], {i, 0, n}, {j, 0, n}] // MatrixForm
```

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Chebyshev functions are orthogonal with respect to this integral

$$\text{In[3]:= } \mathbf{chebInt}[f_] := \frac{2 \int_{-1}^{+1} \frac{f[x]}{\sqrt{1-x^2}} dx}{\pi} \quad \mathbb{I}$$

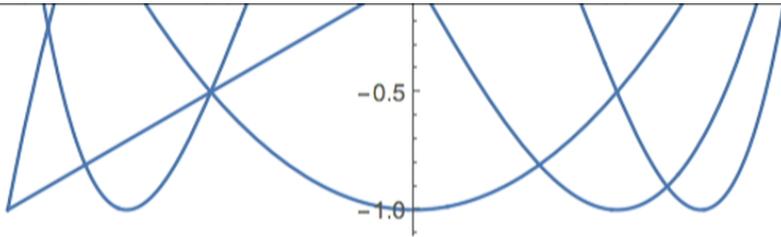
```
In[7]:= chebInt[ChebyshevT[0, #] ChebyshevT[1, #] &]
```

Out[7]= 0

```
cheb[i_, x_] := If[i == 0, 1/sqrt[2], 1] ChebyshevT[i, x]
```

```
Table[chebInt[cheb[i, #] cheb[j, #] &], {i, 0, n}, {j, 0, n}] // MatrixForm
```

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Chebyshev functions are orthogonal with respect to this integral

$$\text{In[3]:= } \text{chebInt}[f_] := \frac{2 \int_{-1}^{+1} \frac{f[x]}{\sqrt{1-x^2}} dx}{\pi}$$

In[7]:= `chebInt[ChebyshevT[0, #] ChebyshevT[1, #] &]`

Out[7]= 0

Define modified orthonormal Chebyshev functions

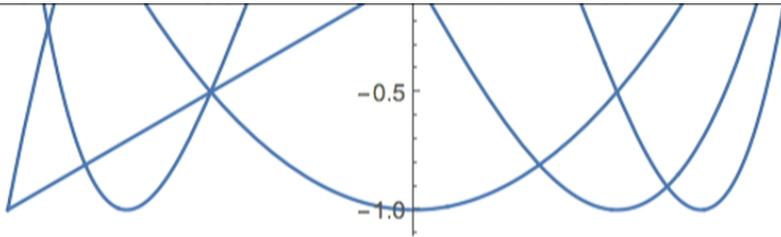
`cheb[i_, x_] := If[i == 0, 1/sqrt[2], 1] ChebyshevT[i, x]`

`Table[chebInt[cheb[i, #] cheb[j, #] &], {i, 0, n}, {j, 0, n}] // MatrixForm`

Reconstruction and Projection onto basis

`c2f[cs_] := Function[x, Sum[cs[[i + 1]] cheb[i, x], {i, 0, n}]]`

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Chebyshev functions are orthogonal with respect to this integral

$$\text{In[3]:= } \text{chebInt}[f_] := \frac{2 \int_{-1}^{+1} \frac{f[x]}{\sqrt{1-x^2}} dx}{\pi}$$

In[7]:= `chebInt[ChebyshevT[0, #] ChebyshevT[1, #] &]`

Out[7]= 0

Define modified orthonormal Chebyshev functions

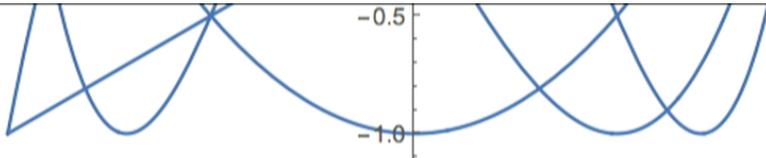
In[8]:= `cheb[i_, x_] := If[i == 0, 1/sqrt[2], 1] ChebyshevT[i, x]`

`Table[chebInt[cheb[i, #] cheb[j, #] &], {i, 0, n}, {j, 0, n}] // MatrixForm`

Reconstruction and Projection onto basis

`c2f[cs_] := Function[x, Sum[cs[[i + 1]] cheb[i, x], {i, 0, n}]]`

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Chebyshev functions are orthogonal with respect to this integral

$$\text{In[3]:= } \mathbf{chebInt}[f_] := \frac{2 \int_{-1}^{+1} \frac{f[x]}{\sqrt{1-x^2}} dx}{\pi}$$

In[7]:= `chebInt[ChebyshevT[0, #] ChebyshevT[1, #] &]`

Out[7]= 0

Define modified orthonormal Chebyshev functions

In[8]:= `cheb[i_, x_] := If[i == 0, 1/sqrt[2], 1] ChebyshevT[i, x]`

In[9]:= `Table[chebInt[cheb[i, #] cheb[j, #] &], {i, 0, n}, {j, 0, n}] // MatrixForm`

Out[9]//MatrixForm=

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

Reconstruction and Projection onto basis

```
In[3]:= chebInt[f_] :=  $\frac{\quad}{\pi}$ 
```

```
In[7]:= chebInt[ChebyshevT[0, #] ChebyshevT[1, #] &]
```

```
Out[7]= 0
```

Define modified orthonormal Chebyshev functions

```
In[8]:= cheb[i_, x_] := If[i == 0,  $\frac{1}{\sqrt{2}}$ , 1] ChebyshevT[i, x]
```

Check orthonormality

```
In[9]:= Table[chebInt[cheb[i, #] cheb[j, #] &], {i, 0, n}, {j, 0, n}] // MatrixForm
```

```
Out[9]//MatrixForm=
```

```

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

```

Reconstruction and Projection onto basis

```
c2f[cs_] := Function[x,  $\sum_{i=0}^n$  cs[[i + 1]] cheb[i, x]]
```

```
f2c[f_] := Table[chebInt[f[#] cheb[i, #] &], {i, 0, n}]
```

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Define modified orthonormal Chebyshev functions

```
In[8]:= cheb[i_, x_] := If[i == 0,  $\frac{1}{\sqrt{2}}$ , 1] ChebyshevT[i, x]
```

Check orthonormality

```
In[9]:= Table[chebInt[cheb[i, #] cheb[j, #] &], {i, 0, n}, {j, 0, n}] // MatrixForm
```

Out[9]//MatrixForm=

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

⌘

Reconstruction and Projection onto basis

```
c2f[cs_] := Function[x,  $\sum_{i=0}^n cs[[i + 1]] cheb[i, x]$ ]
```

```
f2c[f_] := Table[chebInt[f[#] cheb[i, #] &], {i, 0, n}]
```

```
cs = Table[ci, {i, 0, n}]
```

```
cs // c2f
```

```
cs // c2f // f2c
```

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$\sqrt{2}$

Check orthonormality

```
In[9]:= Table[chebInt[cheb[i, #] cheb[j, #] &], {i, 0, n}, {j, 0, n}] // MatrixForm
```

Out[9]//MatrixForm=

```
( 1 0 0 0 0 )
( 0 1 0 0 0 )
( 0 0 1 0 0 )
( 0 0 0 1 0 )
( 0 0 0 0 1 )
```

Reconstruction and Projection onto basis

Approximated functions are represented as a vector of basis coefficients

c2f converts such a vector to a function

```
c2f[cs_] := Function[x, Sum[cs[[i + 1]] cheb[i, x], {i, 0, n}]]
```

```
f2c[f_] := Table[chebInt[f[#] cheb[i, #] &], {i, 0, n}]
```

```
cs = Table[c_i, {i, 0, n}]
```

```
cs // c2f
```

```
cs // c2f // f2c
```

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$\sqrt{2}$

Check orthonormality

```
In[9]:= Table[chebInt[cheb[i, #] cheb[j, #] &], {i, 0, n}, {j, 0, n}] // MatrixForm
```

Out[9]//MatrixForm=

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

Reconstruction and Projection onto basis

Approximated functions are represented as a vector of basis coefficients

c2f converts such a vector to a function

```
In[10]:= c2f[cs_] := Function[x, Sum[cs[[i + 1]] cheb[i, x], {i, 0, n}]]
```

```
In[12]:= c2f[{1, 0, 1, 0, 0}][x]
```

Out[12]= $-1 + \frac{1}{\sqrt{2}} + 2x^2$

```
f2c[f_] := Table[chebInt[f[#] cheb[i, #] &], {i, 0, n}]
```

Check orthonormality

```
In[9]:= Table[chebInt[cheb[i, #] cheb[j, #] &], {i, 0, n}, {j, 0, n}] // MatrixForm
```

Out[9]//MatrixForm=

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

Reconstruction and Projection onto basis

Approximated functions are represented as a vector of basis coefficients

c2f converts such a vector to a function

```
In[10]:= c2f[cs_] := Function[x, Sum[cs[[i + 1]] cheb[i, x], {i, 0, n}]]
```

```
In[15]:= c2f[{ $\frac{\sqrt{2}}{2}$ , 0,  $\frac{1}{2}$ , 0, 0}][x] // Simplify
```

Out[15]= x^2

```
f2c[f_] := Table[chebInt[f[#] cheb[i, #] &], {i, 0, n}]
```

```
cs = Table[c_i, {i, 0, n}]
```

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Reconstruction and Projection onto basis

Approximated functions are represented as a vector of basis coefficients

c2f converts such a vector to a function

```
In[10]:= c2f[cs_] := Function[x, Sum[cs[[i + 1]] cheb[i, x], {i, 0, n}]]
```

Example:

```
In[15]:= c2f[{{Sqrt[2]/2, 0, 1/2, 0, 0}}][x] // Simplify
```

```
Out[15]= x^2
```

Project any function f onto our set of basis vectors

```
f2c[f_] := Table[chebInt[f[#] cheb[i, #] &], {i, 0, n}]
```

```
cs = Table[c_i, {i, 0, n}]
```

```
cs // c2f
```

```
cs // c2f // f2c
```

Derivatives

Reconstruction and Projection onto basis

Approximated functions are represented as a vector of basis coefficients

c2f converts such a vector to a function

```
In[10]:= c2f[cs_] := Function[x, Sum[cs[[i + 1]] cheb[i, x], {i, 0, n}]]
```

Example:

```
In[15]:= c2f[{{Sqrt[2]/2, 0, 1/2, 0, 0}][x] // Simplify
```

```
Out[15]= x^2
```

Project any function f onto our set of basis vectors

```
In[16]:= f2c[f_] := Table[chebInt[f[#] cheb[i, #] &], {i, 0, n}]
```

Example

```
In[17]:= f2c[#^2 &]
```

```
Out[17]= {1/Sqrt[2], 0, 1/2, 0, 0}
```

```
cs = Table[c_i, {i, 0, n}]
```

```
cs // c2f
```

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```
In[10]:= c2f[cs_] := Function[x, Sum[cs[[i + 1]] cheb[i, x], {i, 0, n}]]
```

Example:

```
In[15]:= c2f[{Sqrt[2]/2, 0, 1/2, 0, 0}][x] // Simplify
```

```
Out[15]= x^2
```

Project any function f onto our set of basis vectors

```
In[16]:= f2c[f_] := Table[chebInt[f[#] cheb[i, #] &], {i, 0, n}]
```

Example

```
In[17]:= f2c[#^2 &]
```

```
Out[17]= {1/Sqrt[2], 0, 1/2, 0, 0}
```

```
In[18]:= f2c[Sin]
```

```
Out[18]= {0, 2 BesselJ[1, 1], 0, -2 BesselJ[3, 1], 0}
```

```
cs = Table[ci, {i, 0, n}]
```

```
cs // c2f
```

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```
In[10]:= c2f[cs_] := Function[x,  $\sum_{i=0}^n cs[[i + 1]] cheb[i, x]$ ]
```

Example:

```
In[15]:= c2f[ $\left\{\frac{\sqrt{2}}{2}, 0, \frac{1}{2}, 0, 0\right\}$ ][x] // Simplify
```

```
Out[15]= x2
```

Project any function f onto our set of basis vectors

```
In[16]:= f2c[f_] := Table[chebInt[f[#] cheb[i, #] &], {i, 0, n}]
```

Example

```
In[17]:= f2c[#^2 &]
```

```
Out[17]=  $\left\{\frac{1}{\sqrt{2}}, 0, \frac{1}{2}, 0, 0\right\}$ 
```

```
In[18]:= f2c[Sin]
```

```
Out[18]= {0, 2 BesselJ[1, 1], 0, -2 BesselJ[3, 1], 0}
```

```
In[19]:= f2c[Sin] // N
```

```
Out[19]= {0., 0.880101, 0., -0.0391267, 0.}
```

```
cs = Table[ci, {i, 0, n}]
```

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```
In[15]:= c2f[{ $\frac{\sqrt{2}}{2}$ , 0,  $\frac{1}{2}$ , 0, 0}][x] // Simplify
```

```
Out[15]= x2
```

Project any function f onto our set of basis vectors

```
In[16]:= f2c[f_] := Table[chebInt[f[#] cheb[i, #] &], {i, 0, n}]
```

Example

```
In[17]:= f2c[#^2 &]
```

```
Out[17]= { $\frac{1}{\sqrt{2}}$ , 0,  $\frac{1}{2}$ , 0, 0}
```

```
In[18]:= f2c[Sin]
```

```
Out[18]= {0, 2 BesselJ[1, 1], 0, -2 BesselJ[3, 1], 0}
```

```
In[19]:= f2c[Sin] // N
```

```
Out[19]= {0., 0.880101, 0., -0.0391267, 0.}
```

```
In[20]:= c2f[f2c[Sin]]
```

```
Out[20]= Function[x$,  $\sum_{i=0}^n \{0, 2 \text{BesselJ}[1, 1], 0, -2 \text{BesselJ}[3, 1], 0\}[[i + 1]] \text{cheb}[i, x\$]$ ]
```

```
cs = Table[ci, {i, 0, n}]
```

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```
In[15]:= c2f[{ $\frac{\sqrt{2}}{2}$ , 0,  $\frac{1}{2}$ , 0, 0}][x] // Simplify
```

```
Out[15]= x2
```

Project any function f onto our set of basis vectors

```
In[16]:= f2c[f_] := Table[chebInt[f[#] cheb[i, #] &], {i, 0, n}]
```

Example

```
In[17]:= f2c[#^2 &]
```

```
Out[17]= { $\frac{1}{\sqrt{2}}$ , 0,  $\frac{1}{2}$ , 0, 0}
```

```
In[18]:= f2c[Sin]
```

```
Out[18]= {0, 2 BesselJ[1, 1], 0, -2 BesselJ[3, 1], 0}
```

```
In[19]:= f2c[Sin] // N
```

```
Out[19]= {0., 0.880101, 0., -0.0391267, 0.}
```

```
In[21]:= c2f[f2c[Sin]][x]
```

```
Out[21]= 2 x BesselJ[1, 1] - 2 (-3 x + 4 x3) BesselJ[3, 1]
```

```
cs = Table[ci, {i, 0, n}]
```

```
cs // c2f
```

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```
In[15]:= c2f[{ $\frac{\sqrt{2}}{2}$ , 0,  $\frac{1}{2}$ , 0, 0}][x] // Simplify
```

```
Out[15]= x2
```

Project any function f onto our set of basis vectors

```
In[16]:= f2c[f_] := Table[chebInt[f[#] cheb[i, #] &], {i, 0, n}]
```

Example

```
In[17]:= f2c[#^2 &]
```

```
Out[17]= { $\frac{1}{\sqrt{2}}$ , 0,  $\frac{1}{2}$ , 0, 0}
```

```
In[18]:= f2c[Sin]
```

```
Out[18]= {0, 2 BesselJ[1, 1], 0, -2 BesselJ[3, 1], 0}
```

```
In[19]:= f2c[Sin] // N
```

```
Out[19]= {0., 0.880101, 0., -0.0391267, 0.}
```

```
In[21]:= c2f[f2c[Sin]][x]
```

```
Out[21]= 2 x BesselJ[1, 1] - 2 (-3 x + 4 x3) BesselJ[3, 1]
```

```
cs = Table[ci, {i, 0, n}]
```

```
cs // c2f
```

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```
In[16]:= f2c[f_] := Table[chebInt[f[#] cheb[i, #] &], {i, 0, n}]
```

Example

```
In[17]:= f2c[#^2 &]
```

```
Out[17]= {  $\frac{1}{\sqrt{2}}$ , 0,  $\frac{1}{2}$ , 0, 0 }
```

```
In[18]:= f2c[Sin]
```

```
Out[18]= { 0, 2 BesselJ[1, 1], 0, -2 BesselJ[3, 1], 0 }
```

```
In[19]:= f2c[Sin] // N
```

```
Out[19]= { 0., 0.880101, 0., -0.0391267, 0. }
```

```
In[21]:= c2f[f2c[Sin]][x]
```

```
Out[21]= 2 x BesselJ[1, 1] - 2 (-3 x + 4 x^3) BesselJ[3, 1]
```

Define generic coefficient

```
In[22]:= cs = Table[ci, {i, 0, n}]
```

```
Out[22]= {c0, c1, c2, c3, c4}
```

```
cs // c2f
```

```
cs // c2f // f2c
```

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Out[17]= $\left\{ \frac{1}{\sqrt{2}}, 0, \frac{1}{2}, 0, 0 \right\}$

In[18]:= **f2c[Sin]**

Out[18]= $\{0, 2 \text{ BesselJ}[1, 1], 0, -2 \text{ BesselJ}[3, 1], 0\}$

In[19]:= **f2c[Sin] // N**

Out[19]= $\{0., 0.880101, 0., -0.0391267, 0.\}$

In[21]:= **c2f[f2c[Sin]][x]**

Out[21]= $2 x \text{ BesselJ}[1, 1] - 2 (-3 x + 4 x^3) \text{ BesselJ}[3, 1]$

Define generic coefficient

In[22]:= **cs = Table[c_i, {i, 0, n}]**

Out[22]= $\{c_0, c_1, c_2, c_3, c_4\}$

In[24]:= **(cs // c2f)[x]**

Out[24]= $\frac{c_0}{\sqrt{2}} + x c_1 + (-1 + 2 x^2) c_2 + (-3 x + 4 x^3) c_3 + (1 - 8 x^2 + 8 x^4) c_4$

cs // c2f // f2c

Derivatives

Out[17]= $\left\{ \frac{1}{\sqrt{2}}, 0, \frac{1}{2}, 0, 0 \right\}$

In[18]:= **f2c[Sin]**

Out[18]= $\{0, 2 \text{ BesselJ}[1, 1], 0, -2 \text{ BesselJ}[3, 1], 0\}$

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Out[19]= $\{0., 0.880101, 0., -0.0391267, 0.\}$

In[21]:= **c2f[f2c[Sin]][x]**

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Define generic coefficient

In[22]:= **cs = Table[c_i, {i, 0, n}]**

Out[22]= $\{c_0, c_1, c_2, c_3, c_4\}$

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In[25]:= **cs // c2f // f2c** $\{$

Out[25]= $\{c_0, c_1, c_2, c_3, c_4\}$

```
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Define generic coefficient

```
In[22]:= cs = Table[ci, {i, 0, n}]
```

```
Out[22]= {c0, c1, c2, c3, c4}
```

```
In[24]:= (cs // c2f)[x]
```

```
Out[24]=  $\frac{c_0}{\sqrt{2}} + x c_1 + (-1 + 2 x^2) c_2 + (-3 x + 4 x^3) c_3 + (1 - 8 x^2 + 8 x^4) c_4$ 
```

```
In[25]:= cs // c2f // f2c
```

```
Out[25]= {c0, c1, c2, c3, c4}
```

This shows that f2c is the inverse of c2f (for this choice of n)

Derivatives

150% ▶

```
In[18]:= f2c[Sin]
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```
Out[18]= {0, 2 BesselJ[1, 1], 0, -2 BesselJ[3, 1], 0}
```

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In[19]:= f2c[Sin] // N
```

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In[21]:= c2f[f2c[Sin]][x]
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Out[21]= 2 x BesselJ[1, 1] - 2 (-3 x + 4 x^3) BesselJ[3, 1]
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In[22]:= cs = Table[ci, {i, 0, n}]
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Out[22]= {c0, c1, c2, c3, c4}
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```
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```

```
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```

```
Out[25]= {c0, c1, c2, c3, c4}
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This shows that f2c is the inverse of c2f (for this choice of n)

Derivatives

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In[22]:= cs = Table[ci, {i, 0, n}]
```

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Out[22]= {c0, c1, c2, c3, c4}
```

```
In[24]:= (cs // c2f) [x]
```

```
Out[24]=  $\frac{c_0}{\sqrt{2}} + x c_1 + (-1 + 2 x^2) c_2 + (-3 x + 4 x^3) c_3 + (1 - 8 x^2 + 8 x^4) c_4$ 
```

```
In[25]:= cs // c2f // f2c
```

```
Out[25]= {c0, c1, c2, c3, c4}
```

This shows that f2c is the inverse of c2f (for this choice of n)

Derivatives

We need to be able to represent e.g. derivative operators in our discrete (truncated) bases to solve PDEs

```
dd = Module[{dcs}, dcs = f2c[c2f[cs]'];  
  Table[Coefficient[dcs[[i + 1]], cs[[j + 1]]], {i, 0, n}, {j, 0, n}]];
```

```
dd // MatrixForm
```

```
dd.dd // MatrixForm
```

```
dsin = dd.(Sin // f2c) // c2f
```

```
Plot[{Sin'[x], dsin[x]}, {x, -1, +1}]
```

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$\sqrt{2}$

```
In[25]:= cs // c2f // f2c
```

```
Out[25]= {c0, c1, c2, c3, c4}
```

This shows that f2c is the inverse of c2f (for this choice of n)

Derivatives

We need to be able to represent e.g. derivative operators in our discrete (truncated) bases to solve PDEs

Next steps:

1. Take a generic function represented in our basis
2. Calculate its derivative
3. Determine ("read off") the matrix representation of the derivative operator in our basis

```
dd = Module[{dcs}, dcs = f2c[c2f[cs]'];  
  Table[Coefficient[dcs[[i + 1]], cs[[j + 1]], {i, 0, n}, {j, 0, n}]]];
```

```
dd // MatrixForm
```

```
dd.dd // MatrixForm
```

```
dsin = dd.(Sin // f2c) // c2f
```

```
Plot[{Sin'[x], dsin[x]}, {x, -1, +1}]
```

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```
In[25]:= cs // c2f // f2c
```

```
Out[25]= {c0, c1, c2, c3, c4}
```

This shows that f2c is the inverse of c2f (for this choice of n)

Derivatives

We need to be able to represent e.g. derivative operators in our discrete (truncated) bases to solve PDEs

Next steps:

1. Take a generic function represented in our basis
2. Calculate its derivative
3. Determine ("read off") the matrix representation of the derivative operator in our basis

Generic set of coefficients:

```
In[27]:= cs
```

```
Out[27]= {c0, c1, c2, c3, c4}
```

```
In[26]:= dd = Module[{dcs}, dcs = f2c[c2f[cs]'];  
Table[Coefficient[dcs[[i + 1]], cs[[j + 1]], {i, 0, n}, {j, 0, n}]]];
```

```
dd // MatrixForm
```

```
dd.dd // MatrixForm
```

```
dsin = dd.(Sin // f2c) // c2f
```

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Derivatives

We need to be able to represent e.g. derivative operators in our discrete (truncated) bases to solve PDEs

Next steps:

1. Take a generic function represented in our basis
2. Calculate its derivative
3. Determine ("read off") the matrix representation of the derivative operator in our basis

Generic set of coefficients:

```
In[27]:= cs
```

```
Out[27]= {c0, c1, c2, c3, c4}
```

Generic function:

```
In[28]:= c2f[cs][x]
```

```
Out[28]=  $\frac{c_0}{\sqrt{2}} + x c_1 + (-1 + 2 x^2) c_2 + (-3 x + 4 x^3) c_3 + (1 - 8 x^2 + 8 x^4) c_4$ 
```

Take

```
In[26]:= dd = Module[{dcs}, dcs = f2c[c2f[cs]'];  
Table[Coefficient[dcs[[i + 1]], cs[[j + 1]], {i, 0, n}, {j, 0, n}]]];
```

```
dd // MatrixForm
```

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Next steps:

1. Take a generic function represented in our basis
2. Calculate its derivative
3. Determine ("read off") the matrix representation of the derivative operator in our basis

Generic set of coefficients:

```
In[27]:= cs
```

```
Out[27]= {c0, c1, c2, c3, c4}
```

Generic function:

```
In[28]:= c2f[cs][x]
```

```
Out[28]=  $\frac{c_0}{\sqrt{2}} + x c_1 + (-1 + 2 x^2) c_2 + (-3 x + 4 x^3) c_3 + (1 - 8 x^2 + 8 x^4) c_4$ 
```

Take derivative of this function:

```
In[29]:= c2f[cs]'[x]
```

```
Out[29]= c1 + 4 x c2 + 3 (-1 + 4 x2) c3 + 4 (-4 x + 8 x3) c4
```

```
In[26]:= dd = Module[{dcs}, dcs = f2c[c2f[cs]'];  
Table[Coefficient[dcs[[i + 1]], cs[[j + 1]], {i, 0, n}, {j, 0, n}];  
  
dd // MatrixForm
```

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1. Take a generic function represented in our basis
2. Calculate its derivative
3. Determine ("read off") the matrix representation of the derivative operator in our basis

Generic set of coefficients:

In[27]:= **cs**

Out[27]= { c_0 , c_1 , c_2 , c_3 , c_4 }

Generic function:

In[28]:= **c2f[cs][x]**

Out[28]= $\frac{c_0}{\sqrt{2}} + x c_1 + (-1 + 2 x^2) c_2 + (-3 x + 4 x^3) c_3 + (1 - 8 x^2 + 8 x^4) c_4$

Take derivative of this function:

In[29]:= **c2f[cs]'[x]**

Out[29]= $c_1 + 4 x c_2 + 3(-1 + 4 x^2) c_3 + 4(-4 x + 8 x^3) c_4$

Project back onto our basis:

f2c[c2f[cs]']

In[26]:= **dd = Module[{dcs}, dcs = f2c[c2f[cs]'];
Table[Coefficient[dcs[[i + 1]], cs[[j + 1]], {i, 0, n}, {j, 0, n}]]];**

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Generic set of coefficients:

In[27]:= **cs**

Out[27]= { c_0 , c_1 , c_2 , c_3 , c_4 }

Generic function:

In[28]:= **c2f[cs][x]**

Out[28]= $\frac{c_0}{\sqrt{2}} + x c_1 + (-1 + 2 x^2) c_2 + (-3 x + 4 x^3) c_3 + (1 - 8 x^2 + 8 x^4) c_4$

Take derivative of this function:

In[29]:= **c2f[cs]'[x]**

Out[29]= $c_1 + 4 x c_2 + 3 (-1 + 4 x^2) c_3 + 4 (-4 x + 8 x^3) c_4$

Project back onto our basis:

In[30]:= **f2c[c2f[cs]']**

Out[30]= { $\sqrt{2} (c_1 + 3 c_3)$, $4 (c_2 + 2 c_4)$, $6 c_3$, $8 c_4$, 0 }

```
In[26]:= dd = Module[{dcs}, dcs = f2c[c2f[cs]'];  
          Table[Coefficient[dcs[[i + 1]], cs[[j + 1]], {i, 0, n}, {j, 0, n}]]];  
  
dd // MatrixForm  
  
dd.dd // MatrixForm
```

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$$\text{Out[28]} = \frac{1}{\sqrt{2}} + x c_1 + (-1 + 2 x^2) c_2 + (-3 x + 4 x^3) c_3 + (1 - 8 x^2 + 8 x^4) c_4$$

Take derivative of this function:

In[29]:= **c2f[cs]'** [x]

$$\text{Out[29]} = c_1 + 4 x c_2 + 3 (-1 + 4 x^2) c_3 + 4 (-4 x + 8 x^3) c_4$$

Project back onto our basis:

In[30]:= **f2c[c2f[cs]']**

$$\text{Out[30]} = \{\sqrt{2} (c_1 + 3 c_3), 4 (c_2 + 2 c_4), 6 c_3, 8 c_4, 0\}$$

In[26]:= **dd = Module[{dcs}, dcs = f2c[c2f[cs]'];
Table[Coefficient[dcs[[i + 1]], cs[[j + 1]], {i, 0, n}, {j, 0, n}]]];**

In[31]:= **dd // MatrixForm**

Out[31]//MatrixForm=

$$\begin{pmatrix} 0 & \sqrt{2} & 0 & 3\sqrt{2} & 0 \\ 0 & 0 & 4 & 0 & 8 \\ 0 & 0 & 0 & 6 & 0 \\ 0 & 0 & 0 & 0 & 8 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

dd.dd // MatrixForm

dsin = dd.(Sin // f2c) // c2f

$$\text{Out[28]} = \frac{\sqrt{2}}{2} + x c_1 + (-1 + 2x^2) c_2 + (-3x + 4x^3) c_3 + (1 - 8x^2 + 8x^4) c_4$$

Take derivative of this function:

In[29]:= **c2f[cs]'** [x]

$$\text{Out[29]} = c_1 + 4x c_2 + 3(-1 + 4x^2) c_3 + 4(-4x + 8x^3) c_4$$

Project back onto our basis:

In[30]:= **f2c[c2f[cs]']**

$$\text{Out[30]} = \{\sqrt{2}(c_1 + 3c_3), 4(c_2 + 2c_4), 6c_3, 8c_4, 0\}$$

Matrix representation of derivative operator for our trubasis (modified Chebyshev polynomials)

In[26]:= **dd = Module[{dcs}, dcs = f2c[c2f[cs]'];**
Table[Coefficient[dcs[[i + 1]], cs[[j + 1]], {i, 0, n}, {j, 0, n}]]];

In[31]:= **dd // MatrixForm**

Out[31]/MatrixForm=

$$\begin{pmatrix} 0 & \sqrt{2} & 0 & 3\sqrt{2} & 0 \\ 0 & 0 & 4 & 0 & 8 \\ 0 & 0 & 0 & 6 & 0 \\ 0 & 0 & 0 & 0 & 8 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

dd.dd // MatrixForm

$$\text{Out[28]} = \frac{\sqrt{2}}{2} + x c_1 + (-1 + 2x^2) c_2 + (-3x + 4x^3) c_3 + (1 - 8x^2 + 8x^4) c_4$$

Take derivative of this function:

In[29]:= `c2f[cs]'[x]`

$$\text{Out[29]} = c_1 + 4x c_2 + 3(-1 + 4x^2) c_3 + 4(-4x + 8x^3) c_4$$

Project back onto our basis:

In[30]:= `f2c[c2f[cs]']`

$$\text{Out[30]} = \{\sqrt{2}(c_1 + 3c_3), 4(c_2 + 2c_4), 6c_3, 8c_4, 0\}$$

Matrix representation of derivative operator for our truncated basis (modified Chebyshev polynomials)

In[26]:= `dd = Module[{dcs}, dcs = f2c[c2f[cs]'];
Table[Coefficient[dcs[[i + 1]], cs[[j + 1]], {i, 0, n}, {j, 0, n}]]];`

In[31]:= `dd // MatrixForm`

Out[31]/MatrixForm=

$$\begin{pmatrix} 0 & \sqrt{2} & 0 & 3\sqrt{2} & 0 \\ 0 & 0 & 4 & 0 & 8 \\ 0 & 0 & 0 & 6 & 0 \\ 0 & 0 & 0 & 0 & 8 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

`dd.dd // MatrixForm`

Project back onto our basis:

```
In[30]:= f2c[c2f[cs]']
```

```
Out[30]= { $\sqrt{2}$  (c1 + 3 c3), 4 (c2 + 2 c4), 6 c3, 8 c4, 0}
```

Matrix representation of derivative operator for our truncated basis (modified Chebyshev polynomials)

```
In[26]:= dd = Module[{dcs}, dcs = f2c[c2f[cs]'];  
Table[Coefficient[dcs[[i + 1]], cs[[j + 1]], {i, 0, n}, {j, 0, n}]]];
```

```
In[31]:= dd // MatrixForm
```

Out[31]/MatrixForm=

$$\begin{pmatrix} 0 & \sqrt{2} & 0 & 3\sqrt{2} & 0 \\ 0 & 0 & 4 & 0 & 8 \\ 0 & 0 & 0 & 6 & 0 \\ 0 & 0 & 0 & 0 & 8 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Second derivative

```
dd.dd // MatrixForm
```

```
dsin = dd.(Sin // f2c) // c2f
```

```
Plot[{Sin'[x], dsin[x]}, {x, -1, +1}]
```

Boundaries

Matrix representation of derivative operator for our truncated basis (modified Chebyshev polynomials)

```
In[26]:= dd = Module [{dcs}, dcs = f2c[c2f[cs]''];  
      Table[Coefficient[dcs[[i + 1]], cs[[j + 1]], {i, 0, n}, {j, 0, n}]];
```

```
In[31]:= dd // MatrixForm
```

Out[31]/MatrixForm=

$$\begin{pmatrix} 0 & \sqrt{2} & 0 & 3\sqrt{2} & 0 \\ 0 & 0 & 4 & 0 & 8 \\ 0 & 0 & 0 & 6 & 0 \\ 0 & 0 & 0 & 0 & 8 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Second derivative

```
In[32]:= dd.dd // MatrixForm
```

Out[32]/MatrixForm=

$$\begin{pmatrix} 0 & 0 & 4\sqrt{2} & 0 & 32\sqrt{2} \\ 0 & 0 & 0 & 24 & 0 \\ 0 & 0 & 0 & 0 & 48 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

```
dsin = dd. (Sin // f2c) // c2f
```

```
Plot [{Sin' [x], dsin[x]}, {x, -1, +1}]
```

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Out[31]/MatrixForm=

$$\begin{pmatrix} 0 & \sqrt{2} & 0 & 3\sqrt{2} & 0 \\ 0 & 0 & 4 & 0 & 8 \\ 0 & 0 & 0 & 6 & 0 \\ 0 & 0 & 0 & 0 & 8 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Second derivative

In[32]:= `dd.dd // MatrixForm`

Out[32]/MatrixForm=

$$\begin{pmatrix} 0 & 0 & 4\sqrt{2} & 0 & 32\sqrt{2} \\ 0 & 0 & 0 & 24 & 0 \\ 0 & 0 & 0 & 0 & 48 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Example: Derivative of sine function

```
dsin = dd.(Sin // #2c) // c2f
```

```
Plot[{Sin'[x], dsin[x]}, {x, -1, +1}]
```

Boundaries

```
bb = Module[{bcs}, bcs = c2f[cs][{-1, +1}];  
  Table[Coefficient[bcs[[i]], cs[[j + 1]], {i, 1, 2}, {j, 0, n}]];
```

```
bb // MatrixForm
```

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$$\begin{pmatrix} 0 & 0 & 0 & 6 & 0 \\ 0 & 0 & 0 & 0 & 8 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Second derivative

In[32]:= **dd.dd // MatrixForm**

Out[32]/MatrixForm=

$$\begin{pmatrix} 0 & 0 & 4\sqrt{2} & 0 & 32\sqrt{2} \\ 0 & 0 & 0 & 24 & 0 \\ 0 & 0 & 0 & 0 & 48 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Example: Derivative of sine function

In[33]:= **dsin = dd.(Sin // f2c) // c2f**

Out[33]= **Function**[x\$,

$$\sum_{i=0}^n \{2\sqrt{2} \text{BesselJ}[1, 1] - 6\sqrt{2} \text{BesselJ}[3, 1], 0, -12 \text{BesselJ}[3, 1], 0, 0\}[[i + 1]] \text{cheb}[i, x$]$$

Plot[{Sin'[x], dsin[x]}, {x, -1, +1}]

Boundaries

bb = Module[{bcs}, **bcs = c2f**[cs][{-1, +1}];

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Example: Derivative of sine function

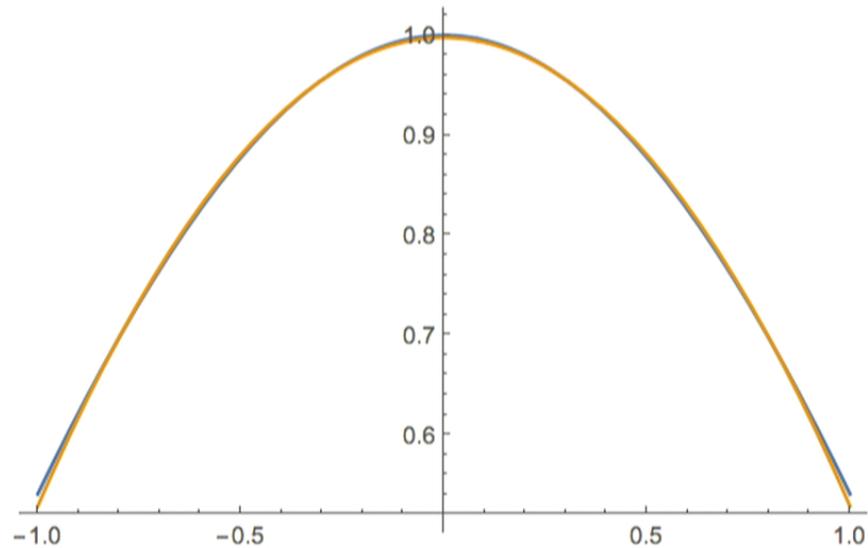
```
In[33]:= dsin = dd. (Sin // f2c) // c2f
```

```
Out[33]= Function [x$,
```

$$\sum_{i=0}^n \{2\sqrt{2} \text{BesselJ}[1, 1] - 6\sqrt{2} \text{BesselJ}[3, 1], 0, -12 \text{BesselJ}[3, 1], 0, 0\} [[i + 1]] \text{cheb}[i, x$]$$

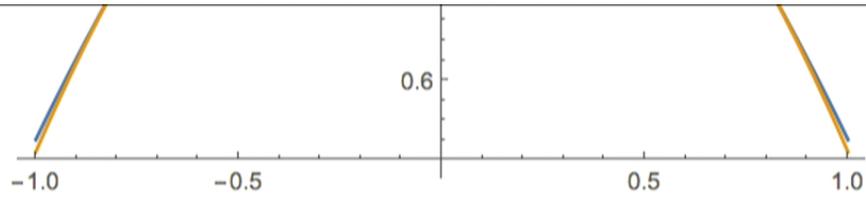
```
In[34]:= Plot [{Sin' [x], dsin[x]}, {x, -1, +1}]
```

```
Out[34]=
```



Boundaries

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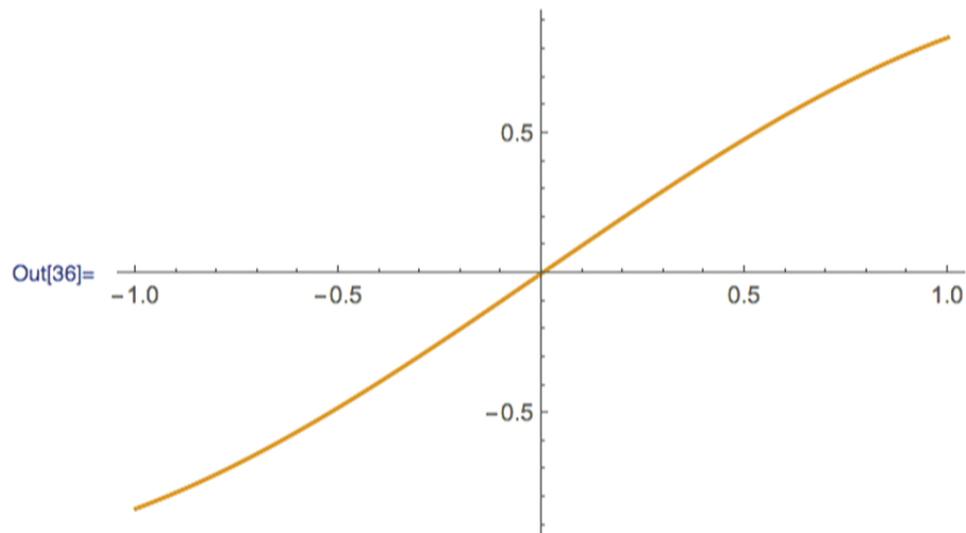


Example: sine function itself

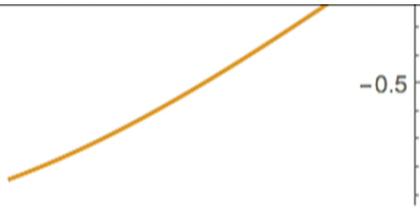
```
In[35]:= sin = (Sin // f2c) // c2f
```

```
Out[35]= Function[x$,  $\sum_{i=0}^n \{0, 2 \text{ BesselJ}[1, 1], 0, -2 \text{ BesselJ}[3, 1], 0\}[[i + 1]] \text{ cheb}[i, x$]$ ]
```

```
In[36]:= Plot[{Sin[x], sin[x]}, {x, -1, +1}]
```

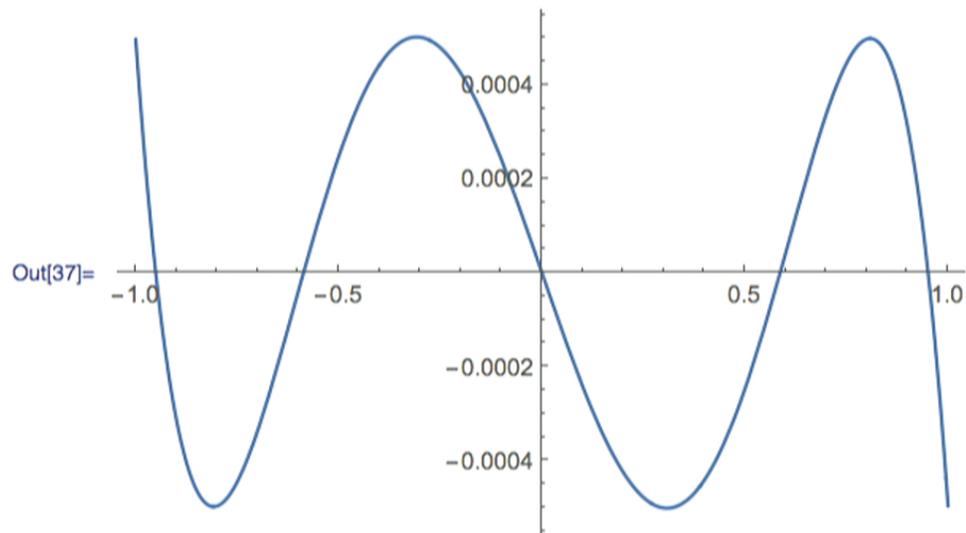


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Show error

```
In[37]:= Plot[sin[x] - Sin[x], {x, -1, +1}]
```

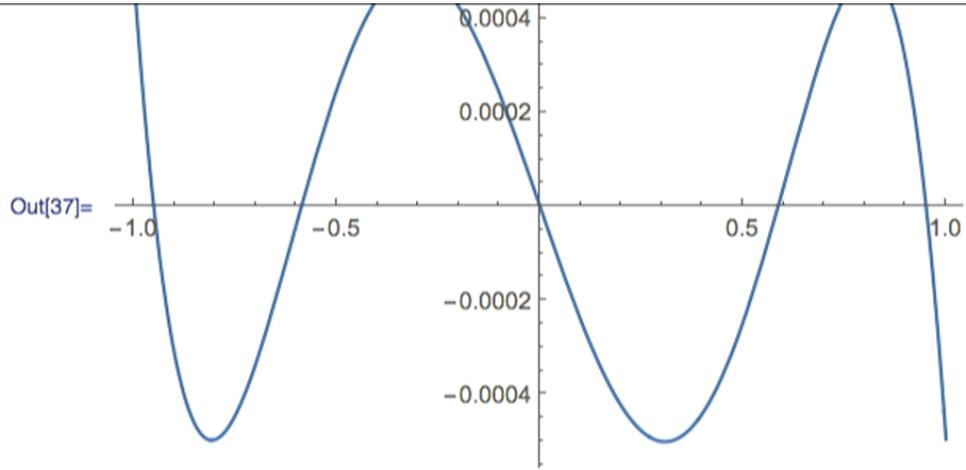


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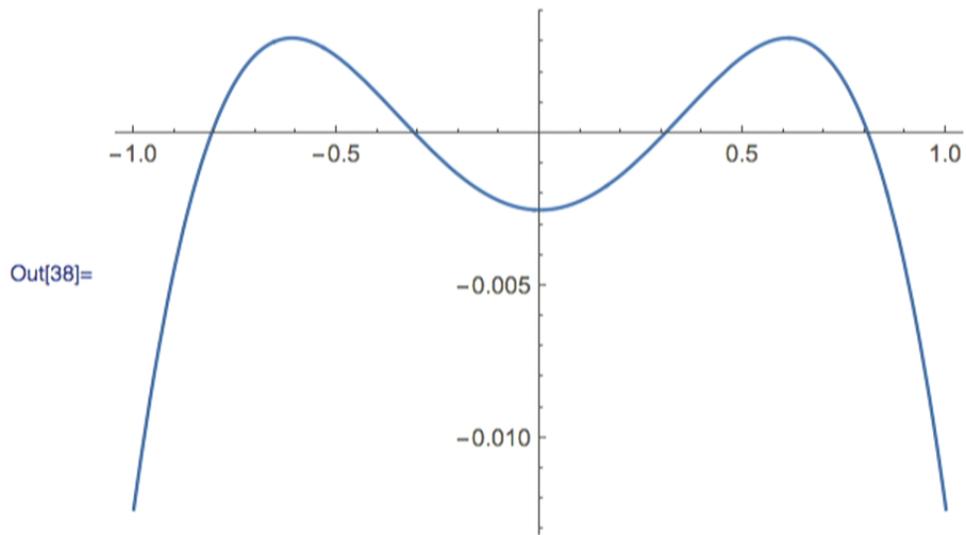
Boundaries

```
bb = Module[{bcs}, bcs = c2f[cs][{-1, +1}];  
Table[Coefficient[bcs[[i]], cs[[i + 1]], {i, 1, 2}, {i, 0, n}]];
```

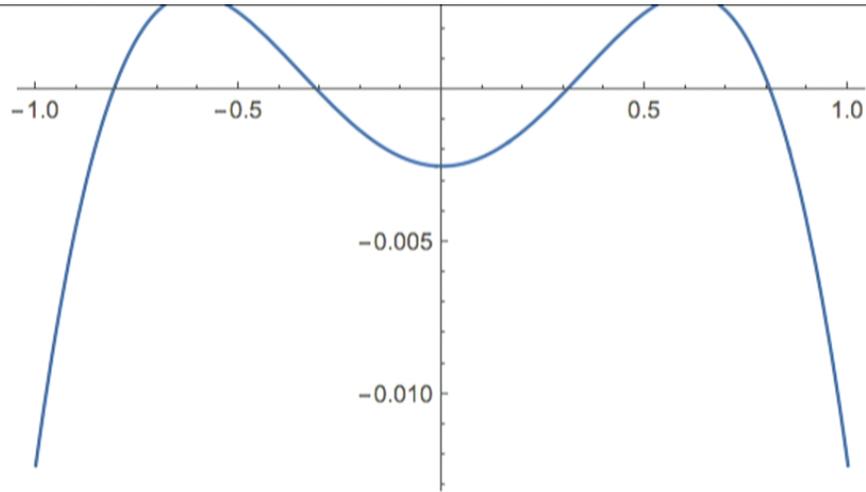
150% ▶



In[38]:= `Plot[dsin[x] - Sin'[x], {x, -1, +1}]`



Out[38]=

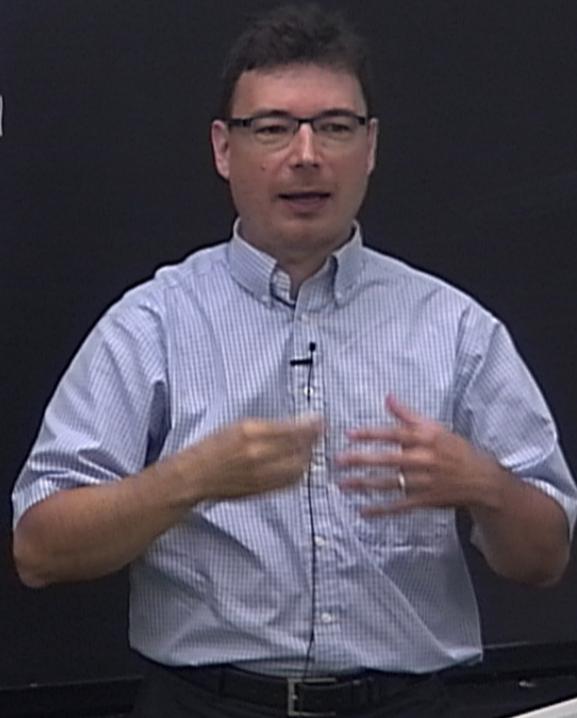
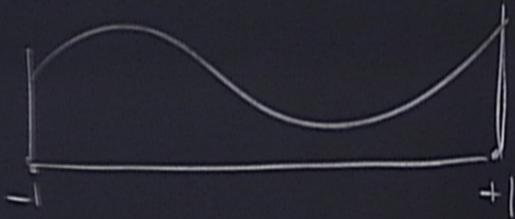


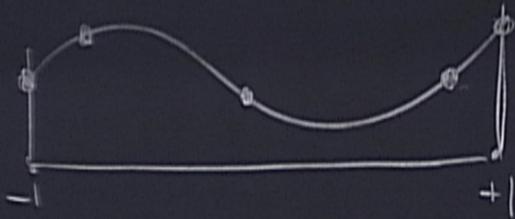
Boundaries

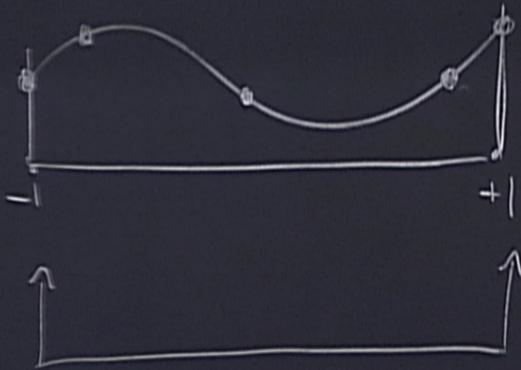
Define “boundary operator” that evaluates a function at the boundary

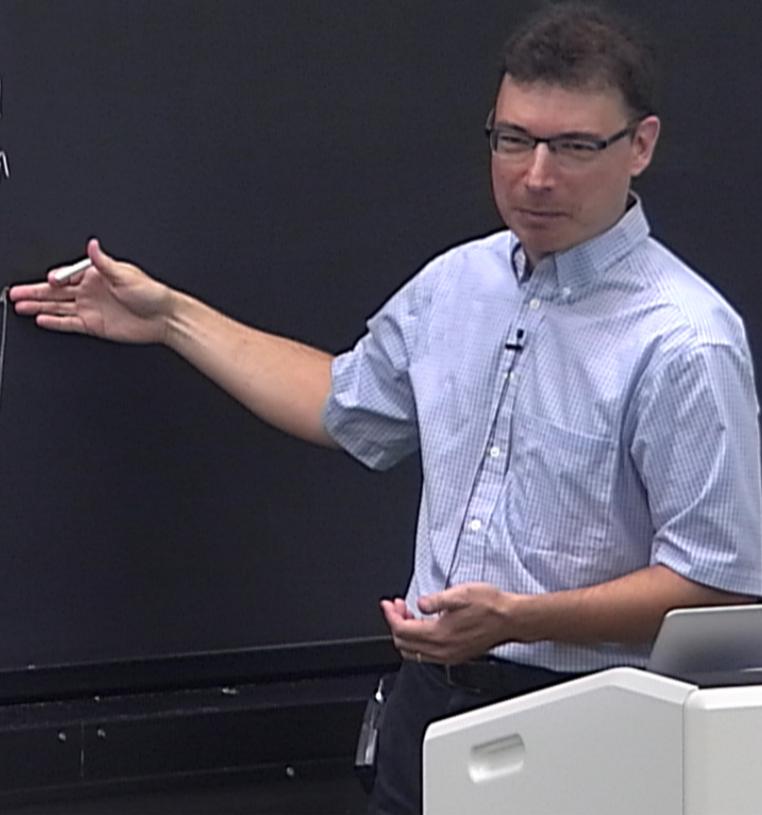
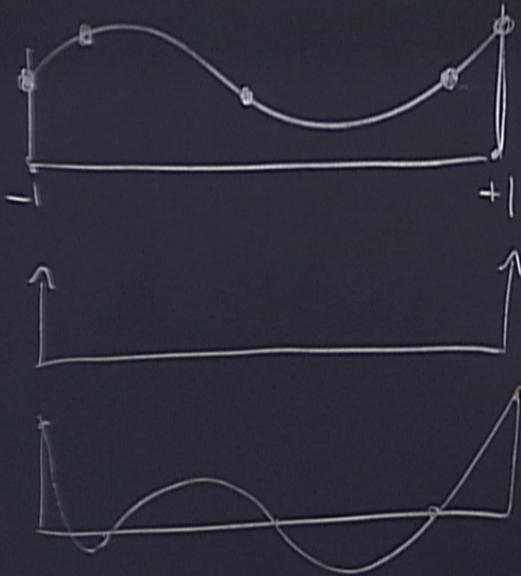
```
bb = Module[{bcs}, bcs = c2f[cs][{-1, +1}];  
  Table[Coefficient[bcs[[i]], cs[[j + 1]], {i, 1, 2}, {j, 0, n}}];  
  
bb // MatrixForm  
  
bb1 = Join[Array[0 &, {n - 2 + 1, n + 1}], bb];  
  
bb1 // MatrixForm  
  
dd + bb1 // MatrixForm
```

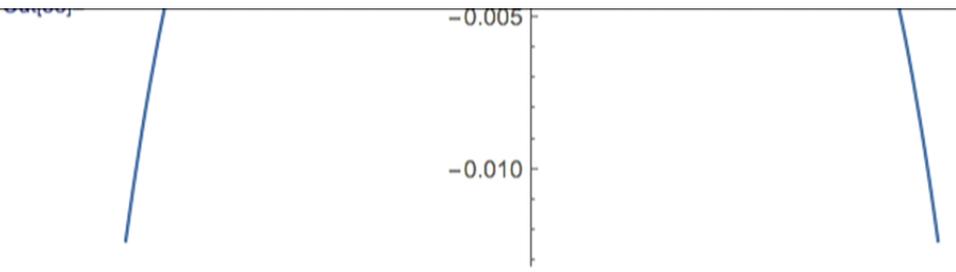
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Boundaries

Define “boundary operator” that evaluates a function at the boundary

Generic set of coefficients

```
In[39]:= cs
Out[39]= {c0, c1, c2, c3, c4}
```

Reconstruct generic functions I

```
In[40]:= c2f[cs]
Out[40]= Function[x$,  $\sum_{i=0}^n \{c_0, c_1, c_2, c_3, c_4\}[[i + 1]] \text{cheb}[i, x$]$ ]
```

```
bb = Module[{bcs}, bcs = c2f[cs][{-1, +1}];
  Table[Coefficient[bcs[[i]], cs[[j + 1]], {i, 1, 2}, {j, 0, n}]];
bb // MatrixForm
```

Boundaries

Define "boundary operator" that evaluates a function at the boundary

Generic set of coefficients

```
In[39]:= cs
```

```
Out[39]= {c0, c1, c2, c3, c4}
```

Reconstruct generic functions

```
In[40]:= c2f[cs]
```

```
Out[40]= Function[x$,  $\sum_{i=0}^n \{c_0, c_1, c_2, c_3, c_4\}[[i+1]] \text{cheb}[i, x$]$ ]
```

Evaluate function at boundary

```
In[42]:= c2f[cs][+1]
```

```
Out[42]=  $\frac{c_0}{\sqrt{2}} + c_1 + c_2 + c_3 + c_4$ 
```

```
bb = Module[{bcs}, bcs = c2f[cs][{-1, +1}];  
Table[Coefficient[bcs[[i]], cs[[j+1]], {i, 1, 2}, {j, 0, n}]];
```

150% ▶

```
In[39]:= cs
```

```
Out[39]= {c0, c1, c2, c3, c4}
```

Reconstruct generic functions

```
In[40]:= c2f[cs]
```

```
Out[40]= Function[x$,  $\sum_{i=0}^n \{c_0, c_1, c_2, c_3, c_4\}[[i+1]] \text{cheb}[i, x\$]$ ]
```

Evaluate function at boundary

```
In[44]:= c2f[cs][{-1, +1}] // MatrixForm
```

```
Out[44]/MatrixForm=
```

$$\begin{pmatrix} \frac{c_0}{\sqrt{2}} - c_1 + c_2 - c_3 + c_4 \\ \frac{c_0}{\sqrt{2}} + c_1 + c_2 + c_3 + c_4 \end{pmatrix}$$

I

```
bb = Module[{bcs}, bcs = c2f[cs][{-1, +1}];  
Table[Coefficient[bcs[[i]], cs[[j + 1]], {i, 1, 2}, {j, 0, n}]];
```

```
bb // MatrixForm
```

```
bb1 = Join[Array[0 &, {n - 2 + 1, n + 1}], bb];
```

```
bb1 // MatrixForm
```

```
dd + bb1 // MatrixForm
```

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```
In[39]:= cs
```

```
Out[39]= {c0, c1, c2, c3, c4}
```

Reconstruct generic functions

```
In[40]:= c2f[cs]
```

```
Out[40]= Function[x$,  $\sum_{i=0}^n \{c_0, c_1, c_2, c_3, c_4\} [[i + 1]] \text{cheb}[i, x$]$ ]
```

Evaluate function at boundary

```
In[44]:= c2f[cs][{-1, +1}] // MatrixForm
```

```
Out[44]/MatrixForm=
```

$$\begin{pmatrix} \frac{c_0}{\sqrt{2}} - c_1 + c_2 - c_3 + c_4 \\ \frac{c_0}{\sqrt{2}} + c_1 + c_2 + c_3 + c_4 \end{pmatrix}$$

```
In[45]:= bb = Module[{bcs}, bcs = c2f[cs][{-1, +1}];  
Table[Coefficient[bcs[[i]], cs[[j + 1]], {i, 1, 2}, {j, 0, n}]];
```

```
bb // MatrixForm
```

```
bb1 = Join[Array[0 &, {n - 2 + 1, n + 1}], bb];
```

```
bb1 // MatrixForm
```

```
dd + bb1 // MatrixForm
```

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```
In[40]:= c2f[cs]
```

```
Out[40]= Function[x$,  $\sum_{i=0}^n \{c_0, c_1, c_2, c_3, c_4\} [[i + 1]] \text{cheb}[i, x\$]$ ]
```

Evaluate function at boundary

```
In[44]:= c2f[cs][{-1, +1}] // MatrixForm
```

```
Out[44]/MatrixForm=
```

$$\begin{pmatrix} \frac{c_0}{\sqrt{2}} - c_1 + c_2 - c_3 + c_4 \\ \frac{c_0}{\sqrt{2}} + c_1 + c_2 + c_3 + c_4 \end{pmatrix}$$

Matrix representation of boundary operator (i.e. projection onto boundary)

```
In[45]:= bb = Module[{bcs}, bcs = c2f[cs][{-1, +1}]];  
Table[Coefficient[bcs[[i]], cs[[j + 1]]], {i, 1, 2}, {j, 0, n}];
```

```
In[46]:= bb // MatrixForm
```

```
Out[46]/MatrixForm=
```

$$\begin{pmatrix} \frac{1}{\sqrt{2}} & -1 & 1 & -1 & 1 \\ \frac{1}{\sqrt{2}} & 1 & 1 & 1 & 1 \end{pmatrix}$$

```
bb1 = Join[Array[0 &, {n - 2 + 1, n + 1}], bb];
```

```
bb1 // MatrixForm
```

```
dd + bb1 // MatrixForm
```

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$$\left(\frac{1}{\sqrt{2}} + c_1 + c_2 + c_3 + c_4 \right)$$

Matrix representation of boundary operator (i.e. projection onto boundary)

```
In[45]:= bb = Module[{bcs}, bcs = c2f[cs][{-1, +1}];  
         Table[Coefficient[bcs[[i]], cs[[j + 1]], {i, 1, 2}, {j, 0, n}]]];
```

```
In[46]:= bb // MatrixForm
```

Out[46]/MatrixForm=

$$\begin{pmatrix} \frac{1}{\sqrt{2}} & -1 & 1 & -1 & 1 \\ \frac{1}{\sqrt{2}} & 1 & 1 & 1 & 1 \end{pmatrix}$$

Prolongate boundary operator to (n+1) dimensions

```
In[47]:= bb1 = Join[Array[0 &, {n - 2 + 1, n + 1}], bb];
```

```
In[48]:= bb1 // MatrixForm
```

Out[48]/MatrixForm=

$$\begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ \frac{1}{\sqrt{2}} & -1 & 1 & -1 & 1 \\ \frac{1}{\sqrt{2}} & 1 & 1 & 1 & 1 \end{pmatrix}$$

I

```
dd + bb1 // MatrixForm
```

```
Table[Coefficient[bcs[[i]], cs[[j + 1]], {i, 1, 2}, {j, 0, n}]]];
```

```
In[46]:= bb // MatrixForm
```

```
Out[46]//MatrixForm=
```

$$\begin{pmatrix} \frac{1}{\sqrt{2}} & -1 & 1 & -1 & 1 \\ \frac{1}{\sqrt{2}} & 1 & 1 & 1 & 1 \end{pmatrix}$$

Prolongate boundary operator to (n+1) dimensions

```
In[47]:= bb1 = Join[Array[0 &, {n - 2 + 1, n + 1}], bb];
```

```
In[48]:= bb1 // MatrixForm
```

```
Out[48]//MatrixForm=
```

$$\begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ \frac{1}{\sqrt{2}} & -1 & 1 & -1 & 1 \\ \frac{1}{\sqrt{2}} & 1 & 1 & 1 & 1 \end{pmatrix}$$

```
dd + bb1 // MatrixForm
```

Equations and Boundary Conditions

```
rhs[x_] = Sin[ $\pi$  x]
```

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Out[46]/MatrixForm=

$$\begin{pmatrix} \frac{1}{\sqrt{2}} & -1 & 1 & -1 & 1 \\ \frac{1}{\sqrt{2}} & 1 & 1 & 1 & 1 \end{pmatrix}$$

Prolongate boundary operator to (n+1) dimensions

In[47]:= **bb1 = Join[Array[0 &, {n - 2 + 1, n + 1}], bb];**

In[48]:= **bb1 // MatrixForm**

Out[48]/MatrixForm=

$$\begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ \frac{1}{\sqrt{2}} & -1 & 1 & -1 & 1 \\ \frac{1}{\sqrt{2}} & 1 & 1 & 1 & 1 \end{pmatrix}$$

In[50]:= **dd.dd + bb1 // MatrixForm**

Out[50]/MatrixForm=

$$\begin{pmatrix} 0 & 0 & 4\sqrt{2} & 0 & 32\sqrt{2} \\ 0 & 0 & 0 & 24 & 0 \\ 0 & 0 & 0 & 0 & 48 \\ \frac{1}{\sqrt{2}} & -1 & 1 & -1 & 1 \\ \frac{1}{\sqrt{2}} & 1 & 1 & 1 & 1 \end{pmatrix}$$



Prolongate boundary operator to (n+1) dimensions

```
In[47]:= bb1 = Join[Array[0 &, {n - 2 + 1, n + 1}], bb];
```

```
In[48]:= bb1 // MatrixForm
```

Out[48]/MatrixForm=

$$\begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ \frac{1}{\sqrt{2}} & -1 & 1 & -1 & 1 \\ \frac{1}{\sqrt{2}} & 1 & 1 & 1 & 1 \end{pmatrix}$$

Combined second derivative and boundary operator

```
In[50]:= dd.dd + bb1 // MatrixForm
```

Out[50]/MatrixForm=

$$\begin{pmatrix} 0 & 0 & 4\sqrt{2} & 0 & 32\sqrt{2} \\ 0 & 0 & 0 & 24 & 0 \\ 0 & 0 & 0 & 0 & 48 \\ \frac{1}{\sqrt{2}} & -1 & 1 & -1 & 1 \\ \frac{1}{\sqrt{2}} & 1 & 1 & 1 & 1 \end{pmatrix}$$

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Equations and Boundary Conditions

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$$\begin{pmatrix} \frac{1}{\sqrt{2}} & -1 & 1 & -1 & 1 \\ \frac{1}{\sqrt{2}} & 1 & 1 & 1 & 1 \end{pmatrix}$$

As example, the combined second derivative and boundary operator

```
In[50]:= dd.dd + bb1 // MatrixForm
```

```
Out[50]/MatrixForm=
```

$$\begin{pmatrix} 0 & 0 & 4\sqrt{2} & 0 & 32\sqrt{2} \\ 0 & 0 & 0 & 24 & 0 \\ 0 & 0 & 0 & 0 & 48 \\ \frac{1}{\sqrt{2}} & -1 & 1 & -1 & 1 \\ \frac{1}{\sqrt{2}} & 1 & 1 & 1 & 1 \end{pmatrix}$$

Equations and Boundary Conditions

We want to solve this PDE: $f''[x] == \sin(\pi x)$

```
rhs[x_] = Sin[ $\pi$  x]
```

```
(*rhs[x_] = If[x >= 0 && x <= 1/2, 1, 0] *)
```

```
Plot[rhs[x], {x, -1, +1}]
```

```
deq =  $\partial_{x,x} f[x] == rhs[x]$ 
```

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$$\begin{pmatrix} \frac{1}{\sqrt{2}} & -1 & 1 & -1 & 1 \\ \frac{1}{\sqrt{2}} & 1 & 1 & 1 & 1 \end{pmatrix}$$

As example, the combined second derivative and boundary operator

```
In[50]:= dd.dd + bb1 // MatrixForm
```

```
Out[50]/MatrixForm=
```

$$\begin{pmatrix} 0 & 0 & 4\sqrt{2} & 0 & 32\sqrt{2} \\ 0 & 0 & 0 & 24 & 0 \\ 0 & 0 & 0 & 0 & 48 \\ \frac{1}{\sqrt{2}} & -1 & 1 & -1 & 1 \\ \frac{1}{\sqrt{2}} & 1 & 1 & 1 & 1 \end{pmatrix}$$

Equations and Boundary Conditions

We want to solve this PDE:

$$f''[x] == \sin(\pi x)$$

$$f[0] == f_0$$

$$f[1] == f_1$$

```
rhs[x_] = Sin[π x]
```

```
(*rhs[x_] = If[x > 0 && x <= 1/2, 1, 0] *)
```

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Out[50]/MatrixForm=

$$\begin{pmatrix} 0 & 0 & 4\sqrt{2} & 0 & 32\sqrt{2} \\ 0 & 0 & 0 & 24 & 0 \\ 0 & 0 & 0 & 0 & 48 \\ \frac{1}{\sqrt{2}} & -1 & 1 & -1 & 1 \\ \frac{1}{\sqrt{2}} & 1 & 1 & 1 & 1 \end{pmatrix}$$

Equations and Boundary Conditions

We want to solve this PDE:

$$f''[x] == \sin(\pi x)$$

$$f[0] == f_0$$

$$f[1] == f_1$$

Define RHS:

$$\text{rhs}[x_] = \text{Sin}[\pi x]$$

$$(*\text{rhs}[x_] = \text{If}[x \geq 0 \&\& x \leq \frac{1}{2}, 1, 0] *)$$

$$\text{Plot}[\text{rhs}[x], \{x, -1, +1\}]$$

$$\text{deq} = \partial_{x,x} f[x] == \text{rhs}[x]$$

$$\text{bcs} = \{f[-1] == \frac{1}{2}, f[+1] == 0\}$$

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We want to solve this PDE:

$$f''[x] == \sin(\pi x)$$

$$f[0] == f_0$$

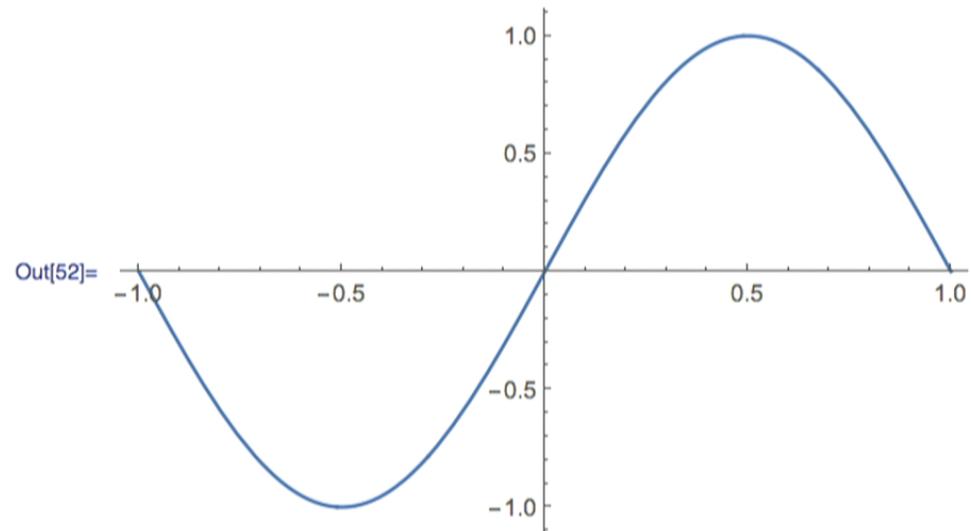
$$f[1] == f_1$$

Define RHS:

```
In[51]:= rhs[x_] = Sin[π x]
```

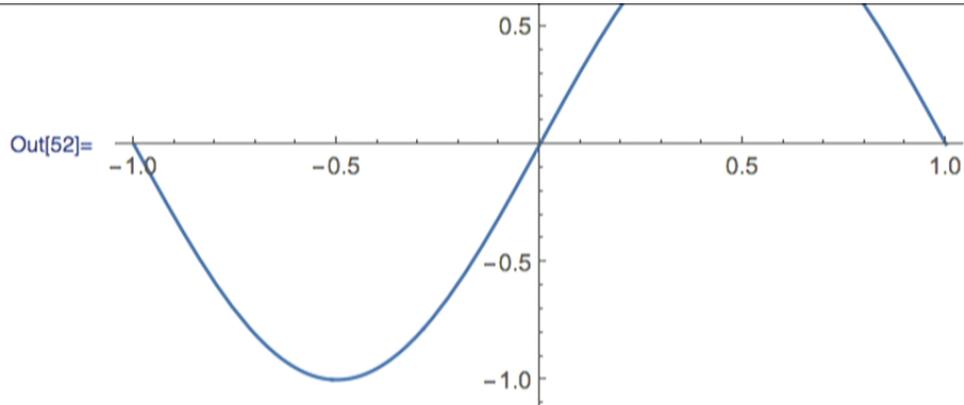
```
Out[51]= Sin[π x]
```

```
In[52]:= Plot[rhs[x], {x, -1, +1}]
```



```
deq = ∂x,x f[x] == rhs[x]
```

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Define differential equation:

In[53]:= **deq** = $\partial_{x,x} f[x] == rhs[x]$

Out[53]= $f''[x] == \text{Sin}[\pi x]$

Define boundary conditions:

In[54]:= **bcs** = $\{f[-1] == \frac{1}{10}, f[+1] == 0\}$

Out[54]= $\{f[-1] == \frac{1}{10}, f[1] == 0\}$

Analytic Solution

Define differential equation:

```
In[53]:= deq =  $\partial_{x,x} f[x] == \text{rhs}[x]$ 
```

```
Out[53]=  $f''[x] == \text{Sin}[\pi x]$ 
```

Define boundary conditions:

```
In[54]:= bcs = {  $f[-1] == \frac{1}{10}$ ,  $f[+1] == 0$  }
```

```
Out[54]= {  $f[-1] == \frac{1}{10}$ ,  $f[1] == 0$  }
```

Analytic Solution

Ask Mathematica to solve this PDE:

```
In[55]:= asol = DSolve[Join[{deq}, bcs], f, x]
```

```
Out[55]= { {  $f \rightarrow \text{Function} \left[ \{x\}, \frac{\pi^2 - \pi^2 x - 20 \text{Sin}[\pi x]}{20 \pi^2} \right] \} \} }$ 
```

```
Simplify[Join[{deq}, bcs] /. asol[[1]]] I
```

```
Plot[f[x] /. asol[[1]], {x, -1, 1}]
```

Numeric solution from NDSolve

150% ▶

```
In[53]:= deq =  $\sigma_{x,x} f[x] == rns[x]$ 
```

```
Out[53]=  $f''[x] == \text{Sin}[\pi x]$ 
```

Define boundary conditions:

```
In[54]:= bcs =  $\{f[-1] == \frac{1}{10}, f[+1] == 0\}$ 
```

```
Out[54]=  $\{f[-1] == \frac{1}{10}, f[1] == 0\}$ 
```

Analytic Solution

Ask Mathematica to solve this PDE:

```
In[55]:= asol = DSolve[Join[{deq}, bcs], f, x]
```

```
Out[55]=  $\left\{ \left\{ f \rightarrow \text{Function}\left[\{x\}, \frac{\pi^2 - \pi^2 x - 20 \text{Sin}[\pi x]}{20 \pi^2}\right] \right\} \right\}$ 
```

```
In[56]:= Simplify[Join[{deq}, bcs] /. asol[[1]]]
```

```
Out[56]= {True, True, True}
```

```
Plot[f[x] /. asol[[1]], {x, -1, 1}]
```

Numeric solution from NDSolve

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In[54]:= **bcs** = { **f**[-1] == $\frac{1}{10}$, **f**[+1] == 0 }

Out[54]= { **f**[-1] == $\frac{1}{10}$, **f**[1] == 0 }

Analytic Solution

Ask Mathematica to solve this PDE:

In[55]:= **asol** = **DSolve**[**Join**[{**deq**}, **bcs**], **f**, **x**]

Out[55]= { { **f** → **Function**[{ **x**, $\frac{\pi^2 - \pi^2 \mathbf{x} - 20 \text{Sin}[\pi \mathbf{x}]}{20 \pi^2}$] }] }

Check whether our solution solves the equations:

In[56]:= **Simplify**[**Join**[{**deq**}, **bcs**] /. **asol**[[1]]]

Out[56]= { **True**, **True**, **True** }

Plot[**f**[**x**] /. **asol**[[1]], {**x**, -1, 1}]

Numeric solution from NDSolve

ndsol = **NDSolve**[**Join**[{**deq**}, **bcs**], **f**, {**x**, -1, +1}]

150% ▶

```
Out[54]= {f[-1] == 1/10, f[1] == 0}
```

Analytic Solution

Ask Mathematica to solve this PDE:

```
In[55]:= asol = DSolve[Join[{deq}, bcs], f, x]
```

```
Out[55]= {{f -> Function[{x}, (pi^2 - pi^2 x - 20 Sin[pi x]) / (20 pi^2)]}}
```

Check whether our solution solves the equations:

```
In[56]:= Simplify[Join[{deq}, bcs] /. asol[[1]]]
```

```
Out[56]= {True, True, True}
```

Show analytic solution:

```
Plot[f[x] /. asol[[1]], {x, -1, 1}]
```

Numeric solution from NDSolve

```
ndsol = NDSolve[Join[{deq}, bcs], f, {x, -1, +1}]
```

```
Plot[{f[x] /. asol[[1]], f[x] /. ndsol[[1]]}, {x, -1, 1}]
```

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```
In[55]:= asol = DSolve[Join[{deq}, bcs], f, x]
```

```
Out[55]=  $\left\{ \left\{ \mathbf{f} \rightarrow \text{Function} \left[ \left\{ \mathbf{x} \right\}, \frac{\pi^2 - \pi^2 \mathbf{x} - 20 \text{Sin}[\pi \mathbf{x}]}{20 \pi^2} \right] \right\} \right\}$ 
```

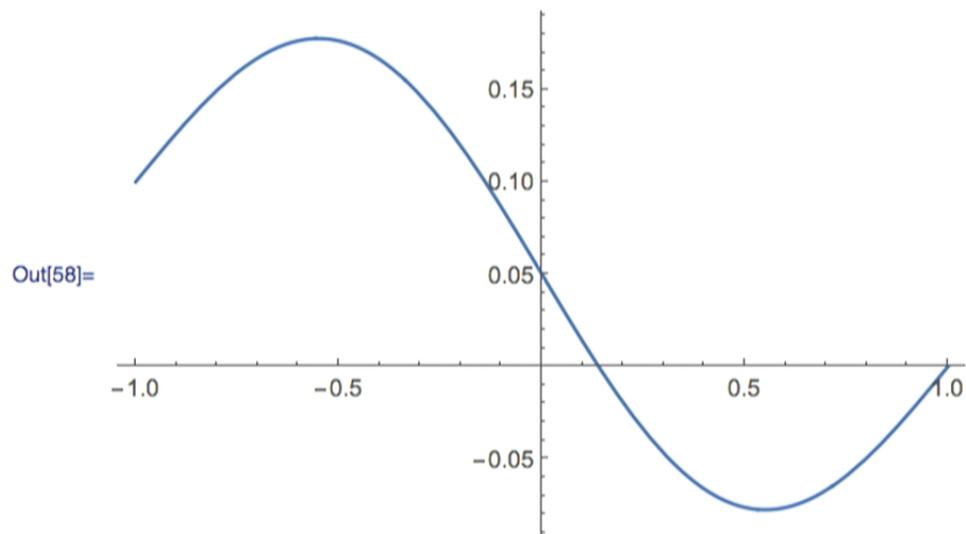
Check whether our solution solves the equations:

```
In[56]:= Simplify[Join[{deq}, bcs] /. asol[[1]]]
```

```
Out[56]= {True, True, True}
```

Show analytic solution:

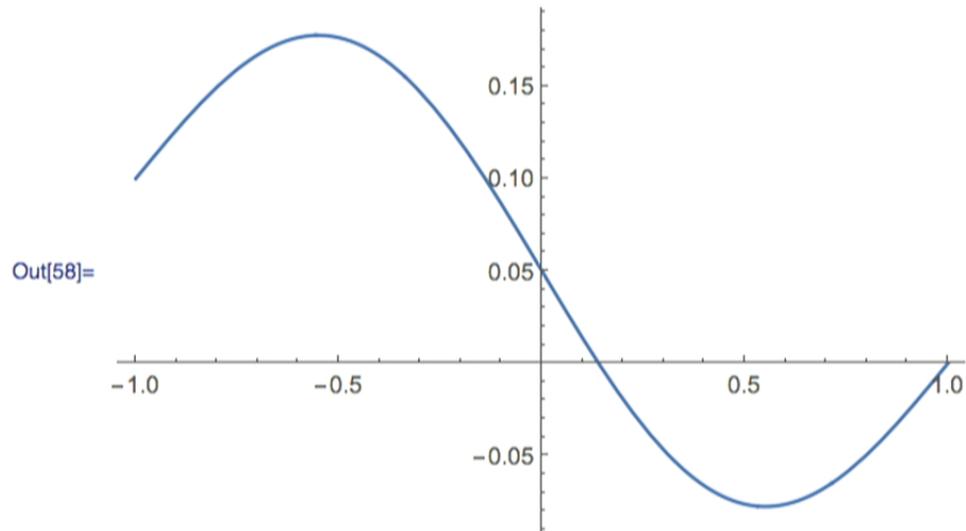
```
In[58]:= Plot[f[x] /. asol[[1]], {x, -1, 1}]
```



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Show analytic solution:

```
In[58]:= Plot[f[x] /. asol[[1]], {x, -1, 1}]
```



Numeric solution from NDSolve

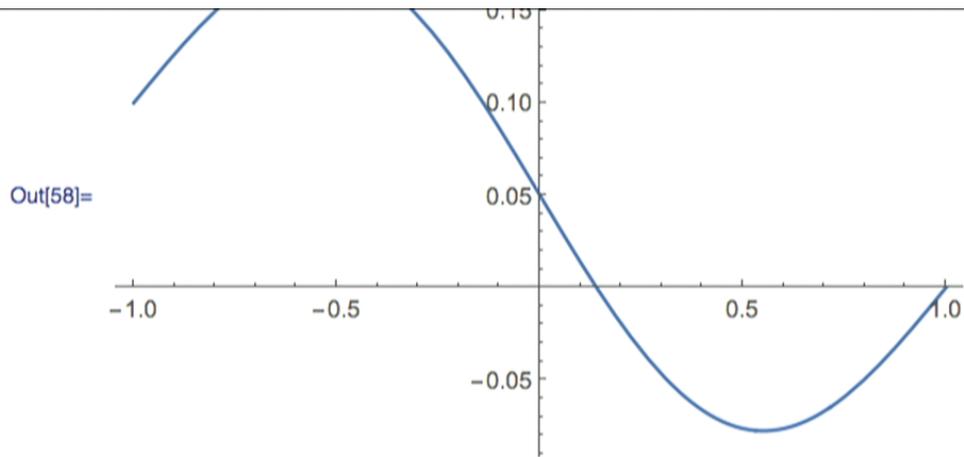
Repeat this with Mathematica's numerical method

```
ndsol = NDSolve[Join[{deq}, bcs], f, {x, -1, +1}]
```

```
Plot[{f[x] /. asol[[1]], f[x] /. ndsol[[1]]}, {x, -1, 1}]
```

Numeric Solution

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Numeric solution from NDSolve

Repeat this with Mathematica's numerical method

```
In[59]:= ndsol = NDSolve[Join[{deq}, bcs], f, {x, -1, +1}]
```

```
Out[59]= {{f → InterpolatingFunction[  Domain: {{-1., 1.}} Output: scalar ]}}
```

```
Plot[{f[x] /. asol[[1]], f[x] /. ndsol[[1]]}, {x, -1, 1}]
```

Numeric Solution

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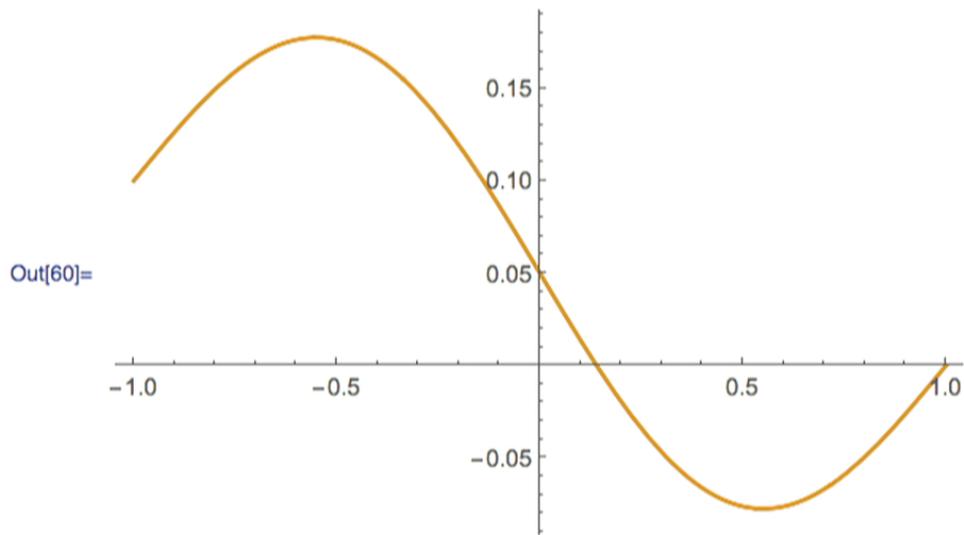
Numeric solution from NDSolve

Repeat this with Mathematica's numerical method

```
In[59]:= ndsol = NDSolve[Join[{deq}, bcs], f, {x, -1, +1}]
```

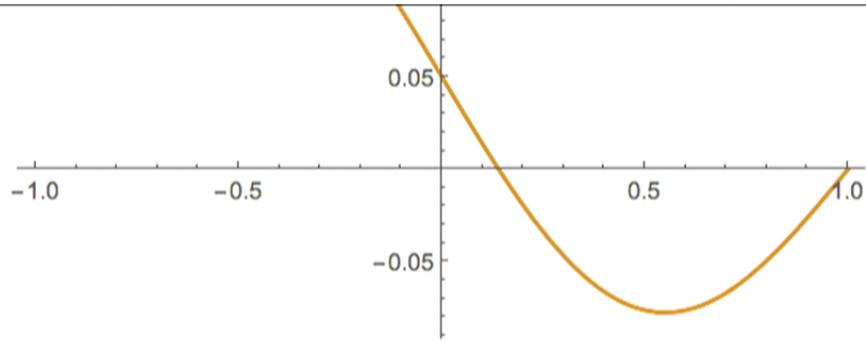
```
Out[59]= {{f → InterpolatingFunction[ Domain: {{-1., 1.}} Output: scalar ]}}
```

```
In[60]:= Plot[{f[x] /. asol[[1]], f[x] /. ndsol[[1]]}, {x, -1, 1}]
```



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Out[60]=



Numeric Solution

Now we repeat this with our own representation of approximated functions

1. Take differential equation and boundary condition, and find their matrix representation (for our basis)
2. Solve this a linear (matrix) equation

RHS

```
drhs = rhs // f2c // N
```

```
Plot [{rhs[x], (drhs // c2f)[x]}, {x, -1, +1}]
```

```
dbcs = {f[-1], f[+1]} /. (bcs /. (lhs_ == rhs_) → (lhs → rhs)) // N
```

```
drhs1 = Join[Take[drhs, n - 2 + 1], {0, 0}]
```

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Numeric Solution

Now we repeat this with our own representation of approximated functions

1. Take differential equation and boundary condition, and find their matrix representation (for our basis)
2. Solve this a linear (matrix) equation

RHS

Project RHS onto our basis functions

```
drhs = rhs // f2c
Plot[{rhs[x], (drhs // c2f)[x]}, {x, -1, +1}]
dbcs = {f[-1], f[+1]} /. (bcs /. (lhs_ == rhs_) -> (lhs -> rhs)) // N
drhs1 = Join[Take[drhs, n - 2 + 1], {0, 0}]
dbcs1 = Join[Table[0, {i, n - 2 + 1}], dbcs]
nsol = LinearSolve[dd.dd + bb1, drhs1 + dbcs1]
Plot[{f[x] /. asol[[1]], c2f[nsol][x]}, {x, -1, +1}]
```

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Numeric Solution

Now we repeat this with our own representation of approximated functions

1. Take differential equation and boundary condition, and find their matrix representation (for our basis)
2. Solve this a linear (matrix) equation

RHS

Project RHS onto our basis functions

```
In[61]:= drhs = rhs // f2c
```

```
Out[61]= {0, 2 BesselJ[1,  $\pi$ ], 0, -2 BesselJ[3,  $\pi$ ], 0}
```

```
Plot[{rhs[x], (drhs // c2f)[x]}, {x, -1, +1}]
```

```
dbcs = {f[-1], f[+1]} /. (bcs /. (lhs_ == rhs_) → (lhs → rhs)) // N
```

```
drhs1 = Join[Take[drhs, n - 2 + 1], {0, 0}]
```

```
dbcs1 = Join[Table[0, {i, n - 2 + 1}], dbcs]
```

```
nsol = LinearSolve[dd.dd + bb1, drhs1 + dbcs1]
```

```
Plot[{f[x] /. asol[[1]], c2f[nsol][x]}, {x, -1, +1}]
```

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Numeric Solution

Now we repeat this with our own representation of approximated functions

1. Take differential equation and boundary condition, and find their matrix representation (for our basis)
2. Solve this a linear (matrix) equation

RHS

Project RHS onto our basis functions

```
In[62]:= drhs = rhs // f2c // N
```

```
Out[62]= {0., 0.569231, 0., -0.666917, 0.}
```

```
Plot [{rhs[x], (drhs // c2f)[x]}, {x, -1, +1}]
```

```
dbcs = {f[-1], f[+1]} /. (bcs /. (lhs_ == rhs_) → (lhs → rhs)) // N
```

```
drhs1 = Join[Take[drhs, n - 2 + 1], {0, 0}]
```

```
dbcs1 = Join[Table[0, {i, n - 2 + 1}], dbcs]
```

```
nsol = LinearSolve[dd.dd + bb1, drhs1 + dbcs1]
```

```
Plot [{f[x] /. asol[[1]], c2f[nsol][x]}, {x, -1, +1}]
```

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Now we repeat this with our own representation of approximated functions

1. Take differential equation and boundary condition, and find their matrix representation (for our basis)
2. Solve this a linear (matrix) equation

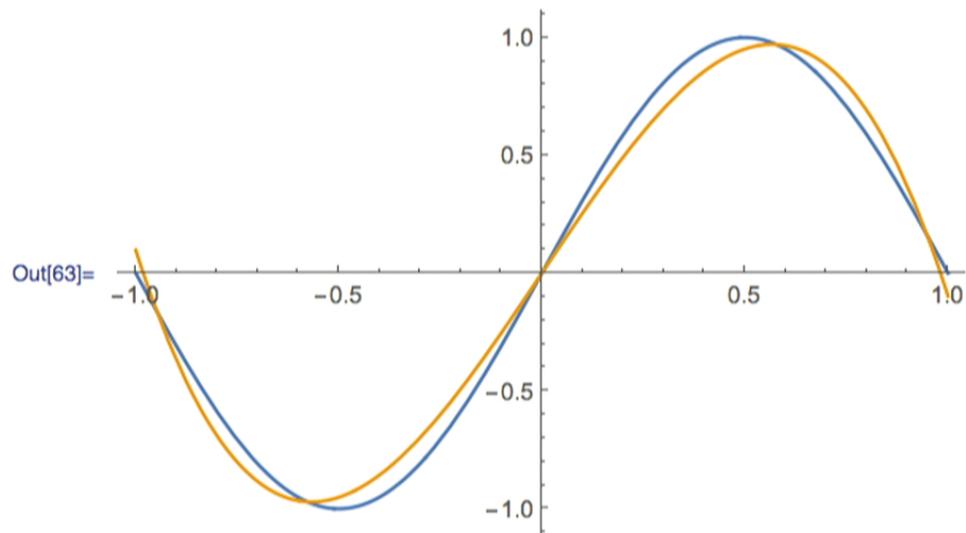
RHS

Project RHS onto our basis functions

```
In[62]:= drhs = rhs // f2c // N
```

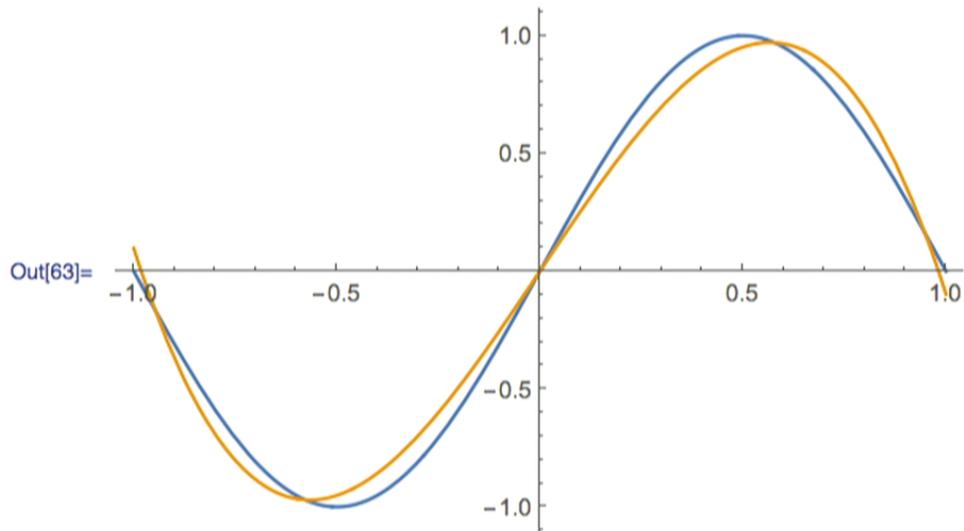
```
Out[62]= {0., 0.569231, 0., -0.666917, 0.}
```

```
In[63]:= Plot[{rhs[x], (drhs // c2f)[x]}, {x, -1, +1}]
```



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```
In[63]:= Plot[{rhs[x], (drhs // c2f)[x]}, {x, -1, +1}]
```



Project boundary conditions onto our basis

```
In[64]:= dbcs = {f[-1], f[+1]} /. (bcs /. (lhs_ == rhs_) -> (lhs -> rhs)) // N
```

```
Out[64]= {0.1, 0.}
```

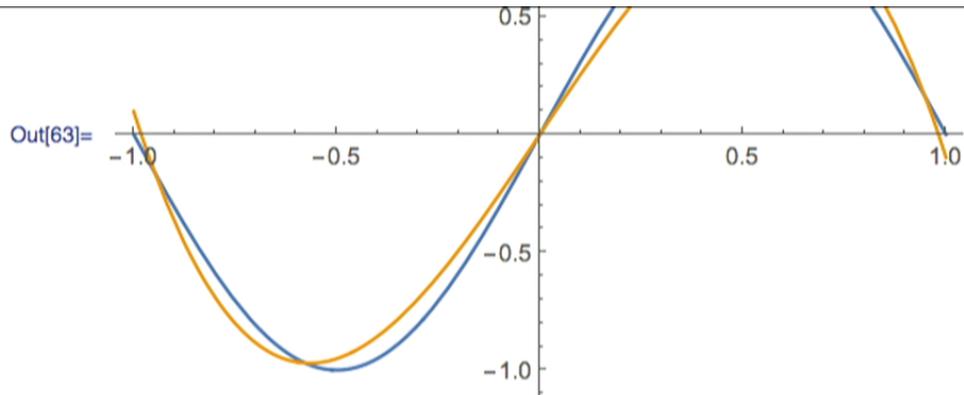
```
drhs1 = Join[Take[drhs, n - 2 + 1], {0, 0}]
```

```
dbcs1 = Join[Table[0, {i, n - 2 + 1}], dbcs]
```

```
nsol = LinearSolve[dd.dd + bb1, drhs1 + dbcs1]
```

```
Plot[{f[x] /. asol[[1]], c2f[nsol][x]}, {x, -1, +1}]
```

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Project boundary conditions onto our basis

```
In[64]:= dbcs = {f[-1], f[+1]} /. (bcs /. (lhs_ == rhs_) → (lhs → rhs)) // N
```

```
Out[64]= {0.1, 0.}
```

```
In[65]:= drhs1 = Join[Take[drhs, n - 2 + 1], {0, 0}]
```

```
Out[65]= {0., 0.569231, 0., 0, 0}
```

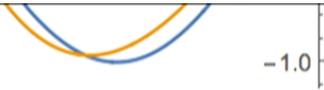
```
In[66]:= dbcs1 = Join[Table[0, {i, n - 2 + 1}], dbcs]
```

```
Out[66]= {0, 0, 0, 0.1, 0.}
```

```
nsol = LinearSolve[dd.dd + bb1, drhs1 + dbcs1]
```

```
Plot[{f[x] /. asol[[1]], c2f[nsol][x]}, {x, -1, +1}]
```

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Project boundary conditions onto our basis

```
In[64]:= dbcs = {f[-1], f[+1]} /. (bcs /. (lhs_ == rhs_) → (lhs → rhs)) // N
```

```
Out[64]= {0.1, 0.}
```

Take first (n-1) conditions from differential equation

```
In[65]:= drhs1 = Join[Take[drhs, n - 2 + 1], {0, 0}]
```

```
Out[65]= {0., 0.569231, 0., 0, 0}
```

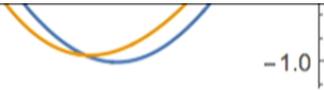
Take 2 conditions from boundary conditions

```
In[66]:= dbcs1 = Join[Table[0, {i, n - 2 + 1}], dbcs]
```

```
Out[66]= {0, 0, 0, 0.1, 0.}
```

```
nsol = LinearSolve[dd.dd + bb1, drhs1 + dbcs1]
```

```
Plot[{f[x] /. asol[[1]], c2f[nsol][x]}, {x, -1, +1}]
```



Project boundary conditions onto our basis

```
In[64]:= dbcs = {f[-1], f[+1]} /. (bcs /. (lhs_ == rhs_) → (lhs → rhs)) // N
```

```
Out[64]= {0.1, 0.}
```

Take first (n-1) conditions from differential equation

```
In[65]:= drhs1 = Join[Take[drhs, n - 2 + 1], {0, 0}]
```

```
Out[65]= {0., 0.569231, 0., 0, 0}
```

Take 2 conditions from boundary conditions

```
In[66]:= dbcs1 = Join[Table[0, {i, n - 2 + 1}], dbcs]
```

```
Out[66]= {0, 0, 0, 0.1, 0.}
```

Stitch conditions together; solve them

```
In[67]:= nsol = LinearSolve[dd.dd + bb1, drhs1 + dbcs1]
```

```
Out[67]= {0.0707107, -0.0737179, 0., 0.0237179, 0.}
```

```
Plot[{f[x] /. asol[[1]], c2f[nsol][x]}, {x, -1, +1}]
```

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Take 2 conditions from boundary conditions

```
In[66]:= dbcs1 = Join[Table[0, {i, n - 2 + 1}], dbcs]
```

```
Out[66]= {0, 0, 0, 0.1, 0.}
```

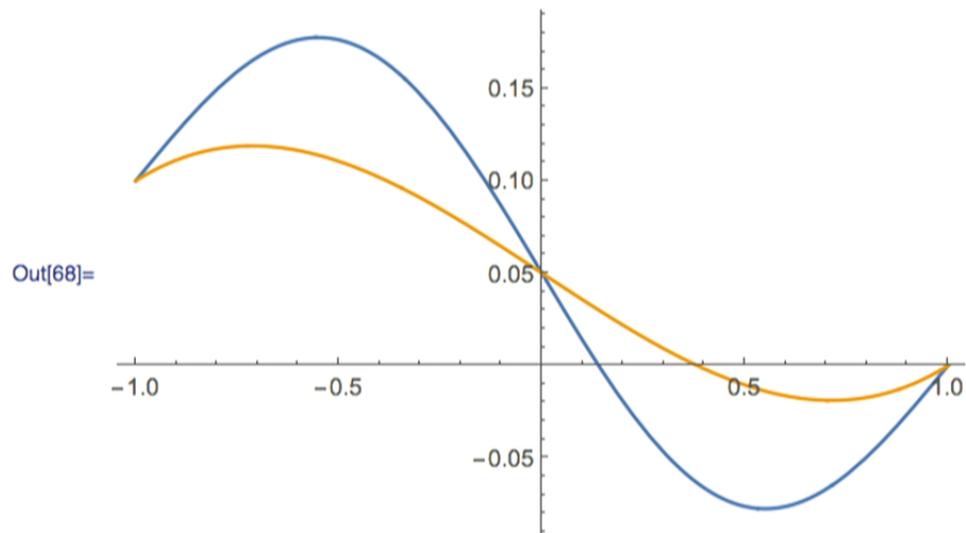
Stitch conditions together; solve them

```
In[67]:= nsol = LinearSolve[dd.dd + bb1, drhs1 + dbcs1]
```

```
Out[67]= {0.0707107, -0.0737179, 0., 0.0237179, 0.}
```

Show solution

```
In[68]:= Plot[{f[x] /. asol[[1]], c2f[nsol][x]}, {x, -1, +1}]
```



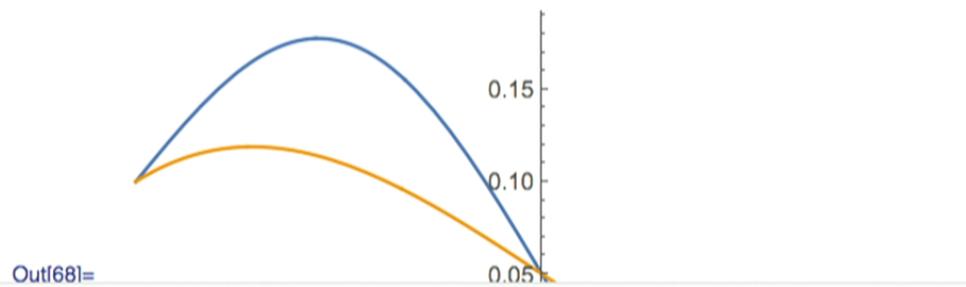
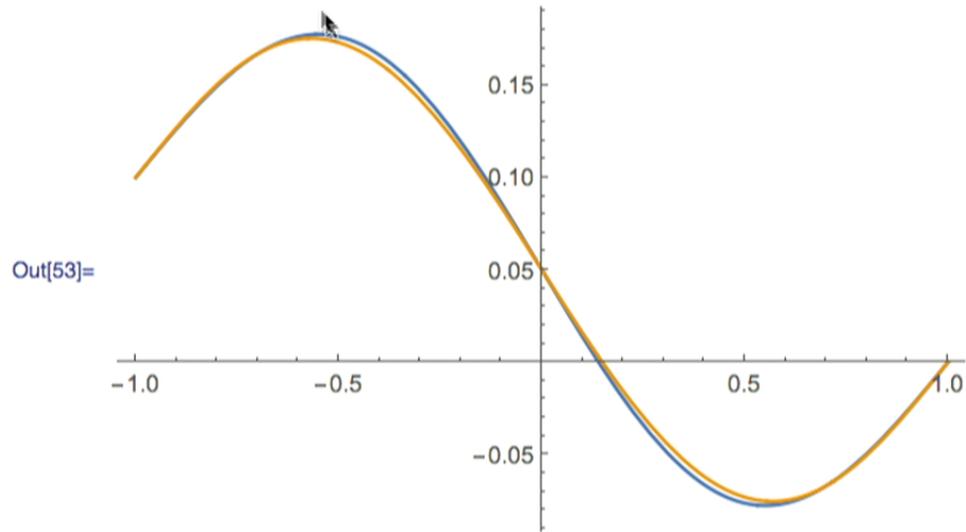
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```
In[52]:= nsol = LinearSolve[dd.dd + bb1, drhs1 + dbcs1]
```

```
Out[52]= {0.0707107, -0.107064, 0., 0.0654002, 0., -0.00833646, 0.}
```

Show solution

```
In[53]:= Plot[{f[x] /. asol[[1]], c2f[nsol][x]}, {x, -1, +1}]
```



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