

Title: Gravity Basics

Date: Jul 18, 2016 09:10 AM

URL: <http://pirsa.org/16070007>

Abstract:

L1: Intro to General Relativity

GR = th. of gravity

~ ST curvature

matter (stress-energy-momentum tensor $T_{\mu\nu}$)

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Einstein's eqn. (for metric $g_{\mu\nu}$ + \rightarrow)
matter (stress-energy-momentum tensor $T_{\mu\nu}$)

BSI
↳ soln. LZ. A) BH, B) AdS, ...

$ST = (M, g_{ms})$
manifold
(eg. \mathbb{R}^4)
~ locally looks like \mathbb{R}^d



CAUTION

matter (stress-energy-momentum tensor $T_{\mu\nu}$)
Einstein's eqn. (for metric $g_{\mu\nu}$ + \rightarrow)

ST is curved + dynamical

OUTLINE: L1 A) \rightarrow B) \rightarrow soln. L2: A) BH, B) ADS, ...

manifold
(eg. \mathbb{R}^d)
~ locally looks like \mathbb{R}^d

- implements dot product
" $\vec{v} \cdot \vec{w}$ " = $g_{\mu\nu} V^\mu W^\nu$
implicitly $\sum_\mu \sum_\nu$

-- lower indices. $V_\mu \equiv g_{\mu\nu} V^\nu$
raise -- \checkmark inverse metric $g^{\mu\nu}$ defined via

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metric

- encodes distances + durations

- implements dot product

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v/ inverse metric

$g^{\mu\nu}$ defined via

$$g_{\mu\nu} g^{\nu\sigma} = \delta_\mu^\sigma$$

$$v^\mu = g^{\mu\nu} V_\nu$$

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Ex. Minkowski (flat) ST:

described by line element $ds^2 = g_{\mu\nu} dx^\mu dx^\nu = -dt^2 + dx^2 + dy^2 + dz^2$

$$\text{Mink } g_{\mu\nu} = \eta_{\mu\nu} = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$$

$$X^\mu = (t, x, y, z)$$

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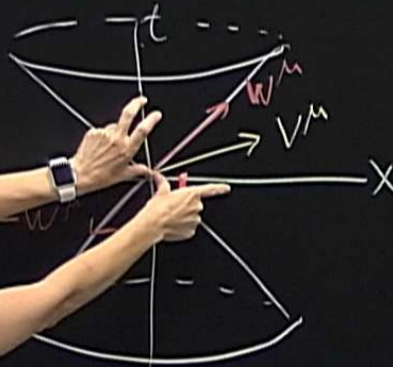
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Causal characterization:

$$X^\mu = (t, x, y, z)$$

$$V_\mu V^\mu > 0 \rightarrow \text{spacelike}$$

$$W_\mu W^\mu = 0$$



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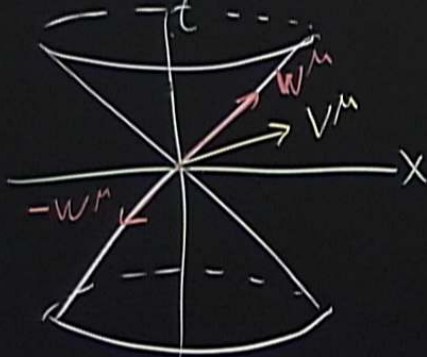
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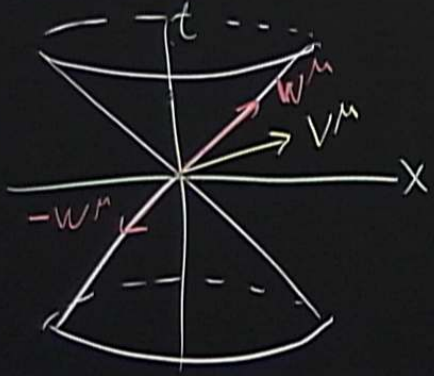
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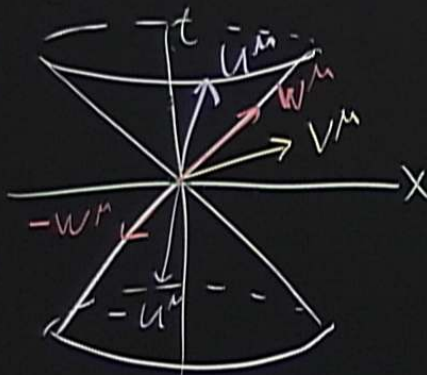
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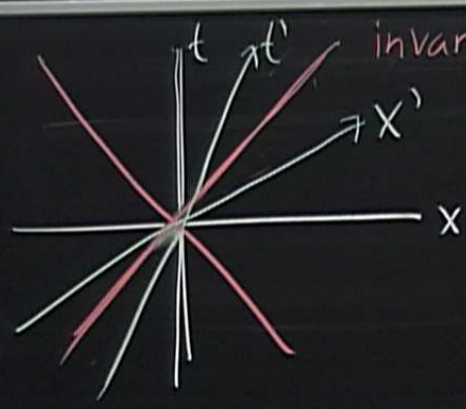
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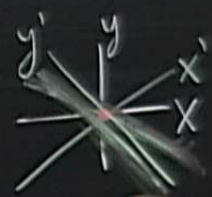


dns

$\sum_n s$



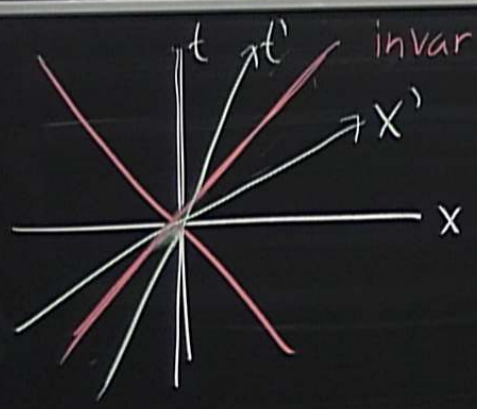
invariant under boost of rotation



CAUTION
Do not touch the blackboard
Do not touch the blackboard

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015



invariant under boost
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$\eta_{\mu\nu}$ is inv. Under Lorentz transf. Λ^μ_ν
 $\tilde{V}^\mu = \Lambda^\mu_\nu X^\nu$
 $\hookrightarrow \eta = \Lambda^T \eta \Lambda$



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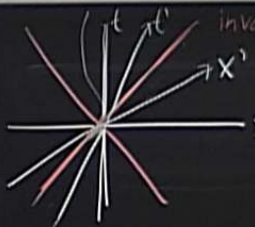
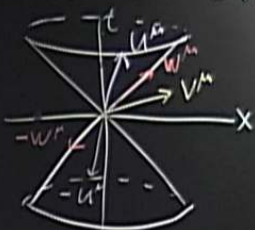
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raise -1- inverse metric $g^{\mu\nu}$ defined via $g_{\mu\nu} g^{\nu\sigma} = \delta_{\mu}^{\sigma}$
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 $g_{\mu\nu} V^{\mu} W^{\nu} = V_{\nu} W^{\nu} = V^{\mu} W_{\mu} = V^{\mu} W_{\mu}$

Causal characterization.

Define $g_{\mu\nu} = \eta_{\mu\nu} = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$

$x^{\mu} = (t, x, y, z)$

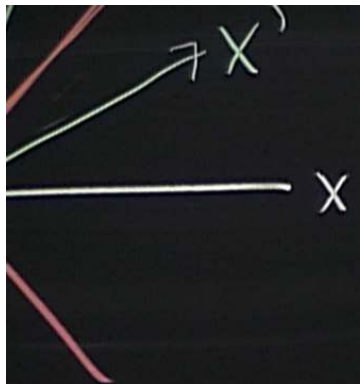
- $V_{\mu} V^{\mu} > 0 \rightarrow$ spacelike
- $W_{\mu} W^{\mu} = 0 \rightarrow \pm w^{\mu} \rightarrow$ future-directed null lightlike
- $U_{\mu} U^{\mu} < 0 \rightarrow \pm u^{\mu} \rightarrow$ -1- timelike



invariant under boost of rotation

$g_{\mu\nu}$ is inv. under Lorentz transf. Λ^{μ}_{ν}
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cf rotation



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$$\hookrightarrow \underline{\eta} = \Lambda^T \underline{\eta} \Lambda$$

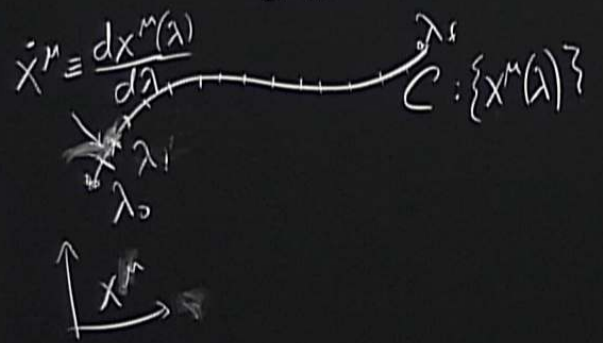
\uparrow
SO(3,1)

eg. $\left(\begin{array}{cc|cc} \cosh \alpha & \sinh \alpha & & \\ \sinh \alpha & \cosh \alpha & & \\ \hline & & \cos \theta & \sin \theta \\ & & -\sin \theta & \cos \theta \\ \hline & & & \text{etc.} \end{array} \right)$



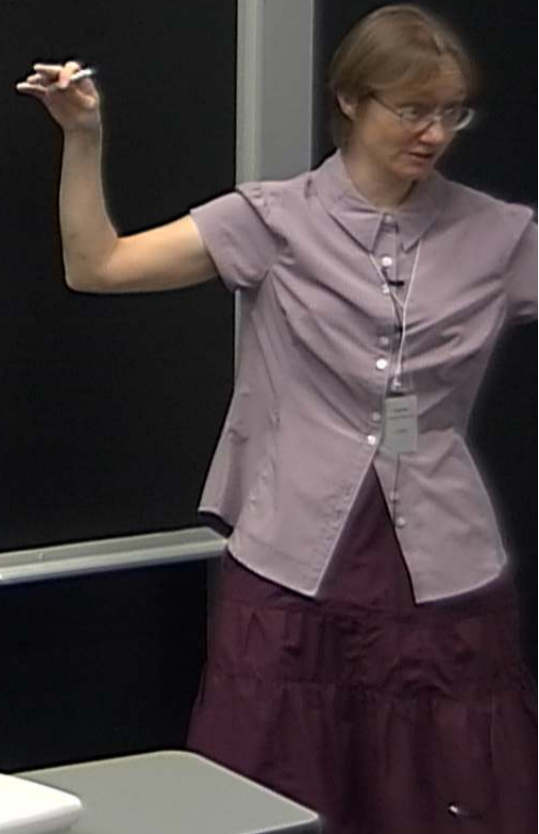
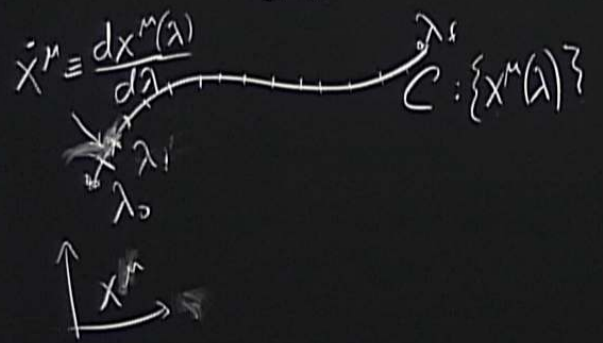
Proper length
time

$$L = \int_C \sqrt{|ds^2|} = \int_{\lambda_0}^{\lambda_f} \sqrt{|g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu|} d\lambda$$

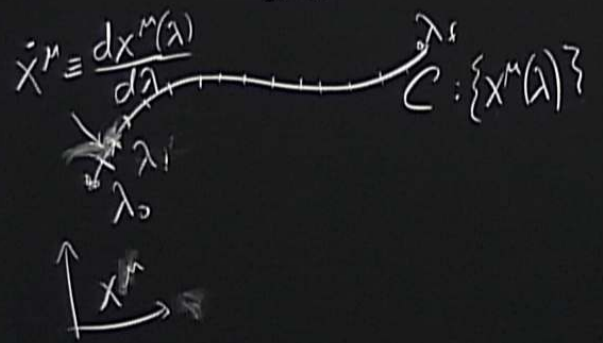


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 \uparrow
 $g_{\mu\nu}(x^\beta(\lambda))$



$(3,1)$
 $\left. \begin{matrix} \dots \\ \dots \end{matrix} \right\}$

CAUTION
 DO NOT TOUCH THE BOARD WHEN IT IS HOT
 IT IS HEATED BY THE BOARD
 LIGHT SOURCE OPERATING UNIT
 PLEASE REMAIN SEATED

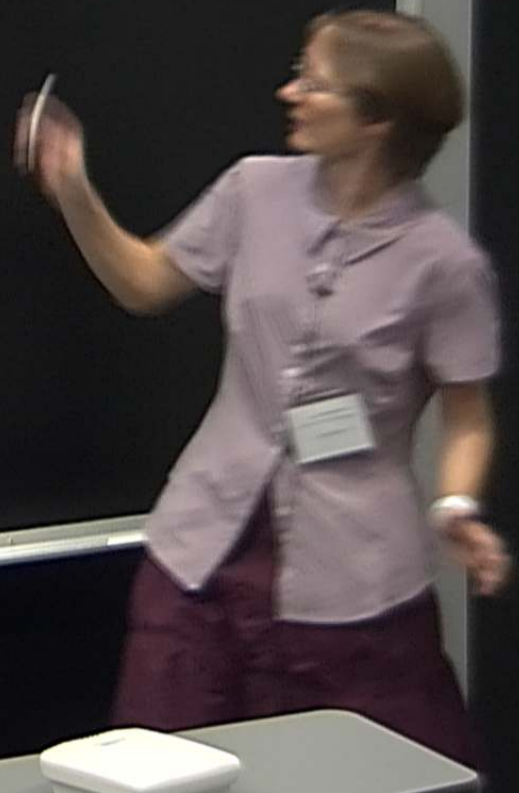
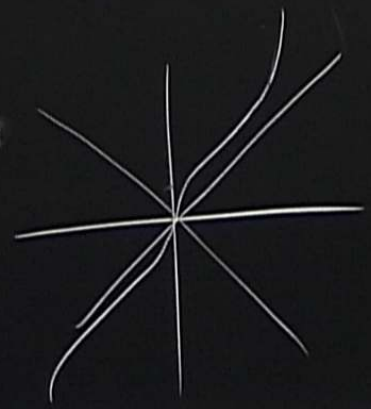
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$$\dot{x}^\mu \equiv \frac{dx^\mu(\lambda)}{d\lambda}$$

$C: \{x^\mu(\lambda)\}$



CAUTION
DO NOT TOUCH THE BOARD OR THE CHALK
OR THE CHALKBOARD ERASER
OR THE CHALKBOARD MARKER

sf. Λ^{μ}_{ν}
 \uparrow
 $SO(3,1)$
 \uparrow
 $\begin{pmatrix} \cosh \theta & \sinh \theta \\ -\sinh \theta & \cosh \theta \end{pmatrix}$
 etc.

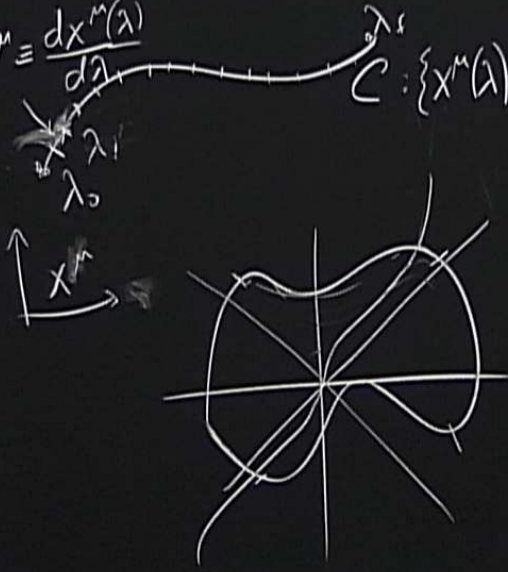
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invariant under reparam. $\lambda \rightarrow f(\lambda)$
 & coord. transformations

$$L(C, g_{\mu\nu})$$

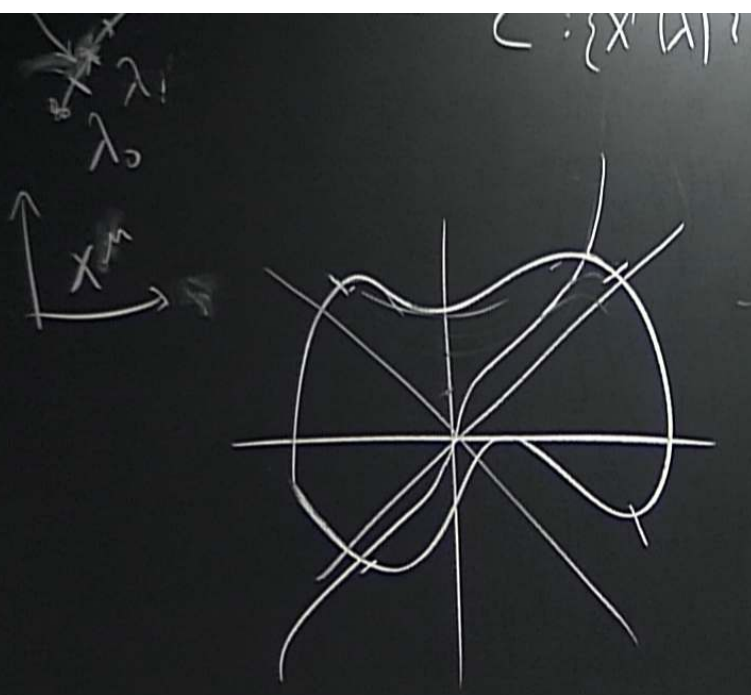


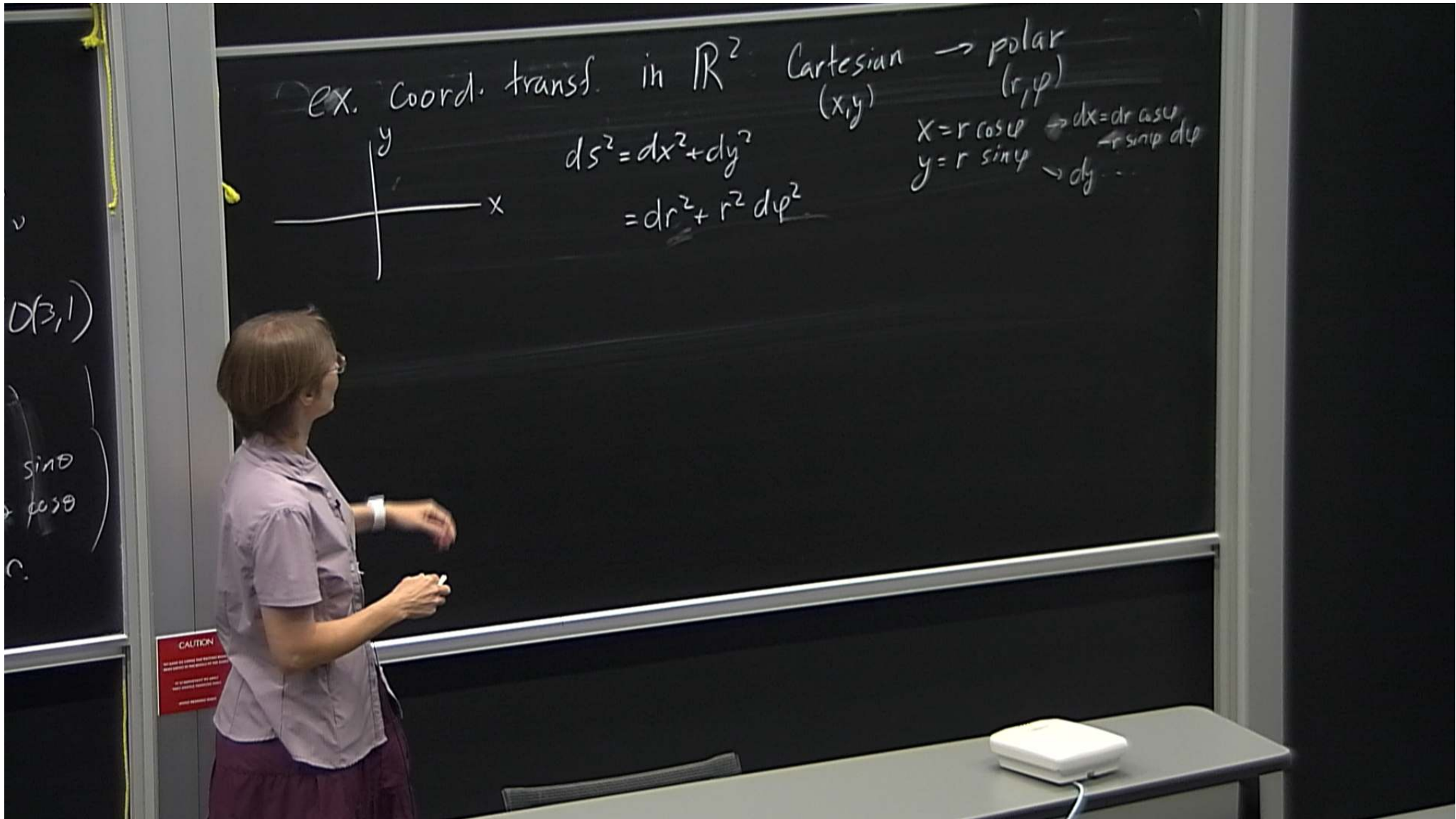
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 or the equipment on the board
 as they may be damaged

Invariant under reparam. $\lambda \rightarrow f(\lambda)$
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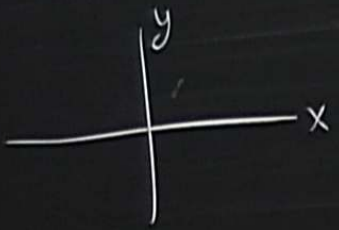
$$\mathcal{L}(C, g_{\mu\nu})$$

GR: diffeomorphism inv. (generally covariant)
→ all physical/geom. quantities are indep. of coords.





ex. coord. transf. in \mathbb{R}^2 Cartesian \rightarrow polar
 (x, y) (r, ϕ)
 $x = r \cos \phi \rightarrow dx = dr \cos \phi - r \sin \phi d\phi$
 $y = r \sin \phi \rightarrow dy = r \sin \phi d\phi + dr \sin \phi$

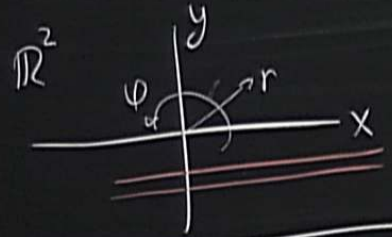


$$ds^2 = dx^2 + dy^2 = dr^2 + r^2 d\phi^2$$

$D(3,1)$
 $\sin \theta$
 $\cos \theta$

CAUTION

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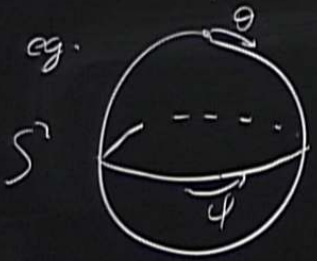
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Curved ST



$$ds^2 = d\theta^2 + \sin^2 \theta d\varphi^2$$

- initially || "lines" don't stay ||

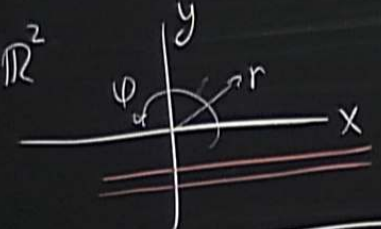
$(3,1)$



CAUTION

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\mathbb{R}^2

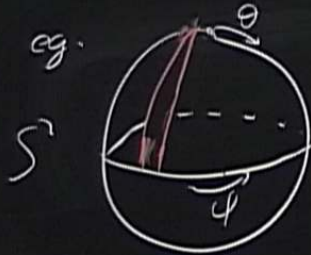


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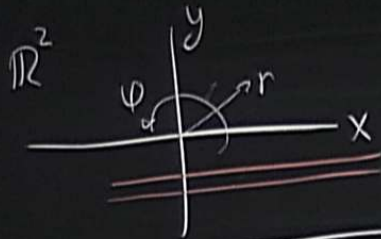
eg.



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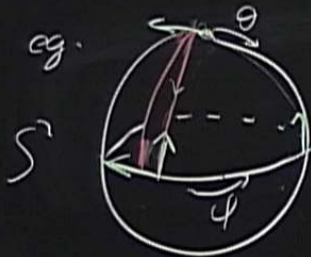
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Curved ST

eg.



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- initially || "lines" don't stay ||
- parallel-transported vector along closed curve doesn't return to itself

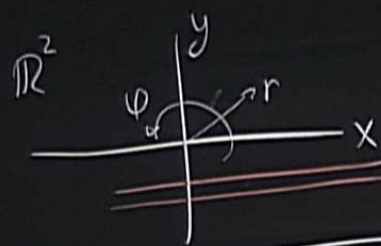


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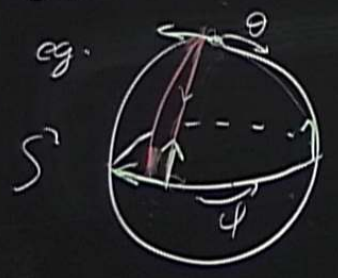
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\mathbb{R}^2



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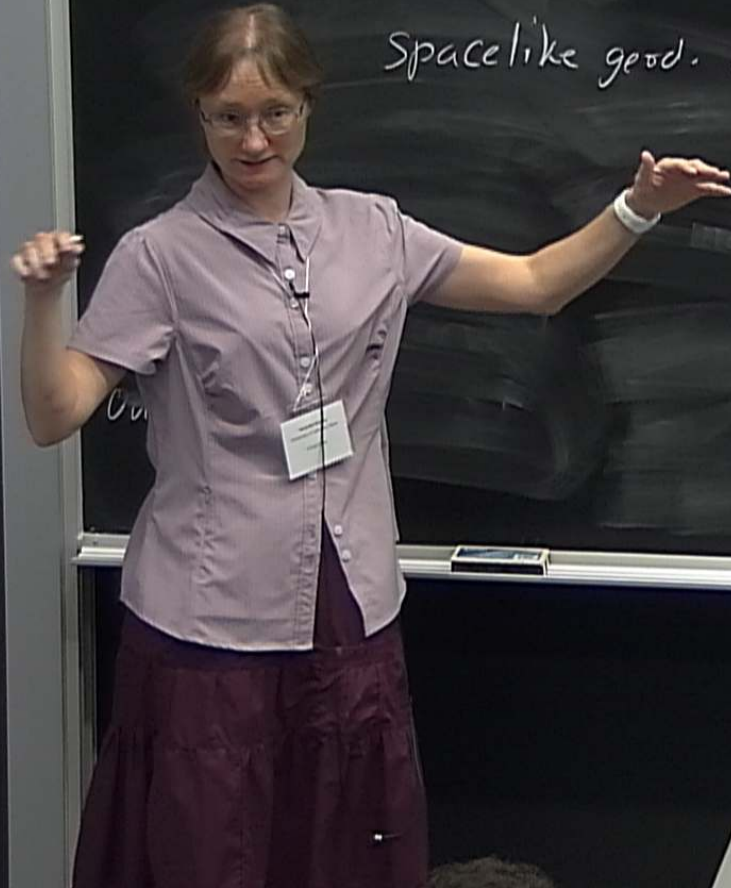


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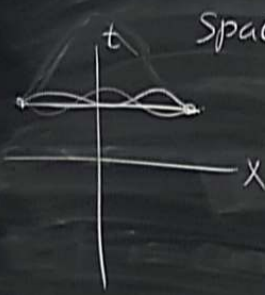
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- parallel-transported vector along closed curve doesn't return to itself
- curvature



Geodesic: = curve of zero acceleration
for timelike geods. → path followed by "test" particle
null → "curve of longest proper time"
Spacelike geod. in Riemannian geom = curve of shortest length
($g_{\mu\nu}$ is positive definite) ^{massive} ^{massless}



Geodesic: = curve of zero acceleration
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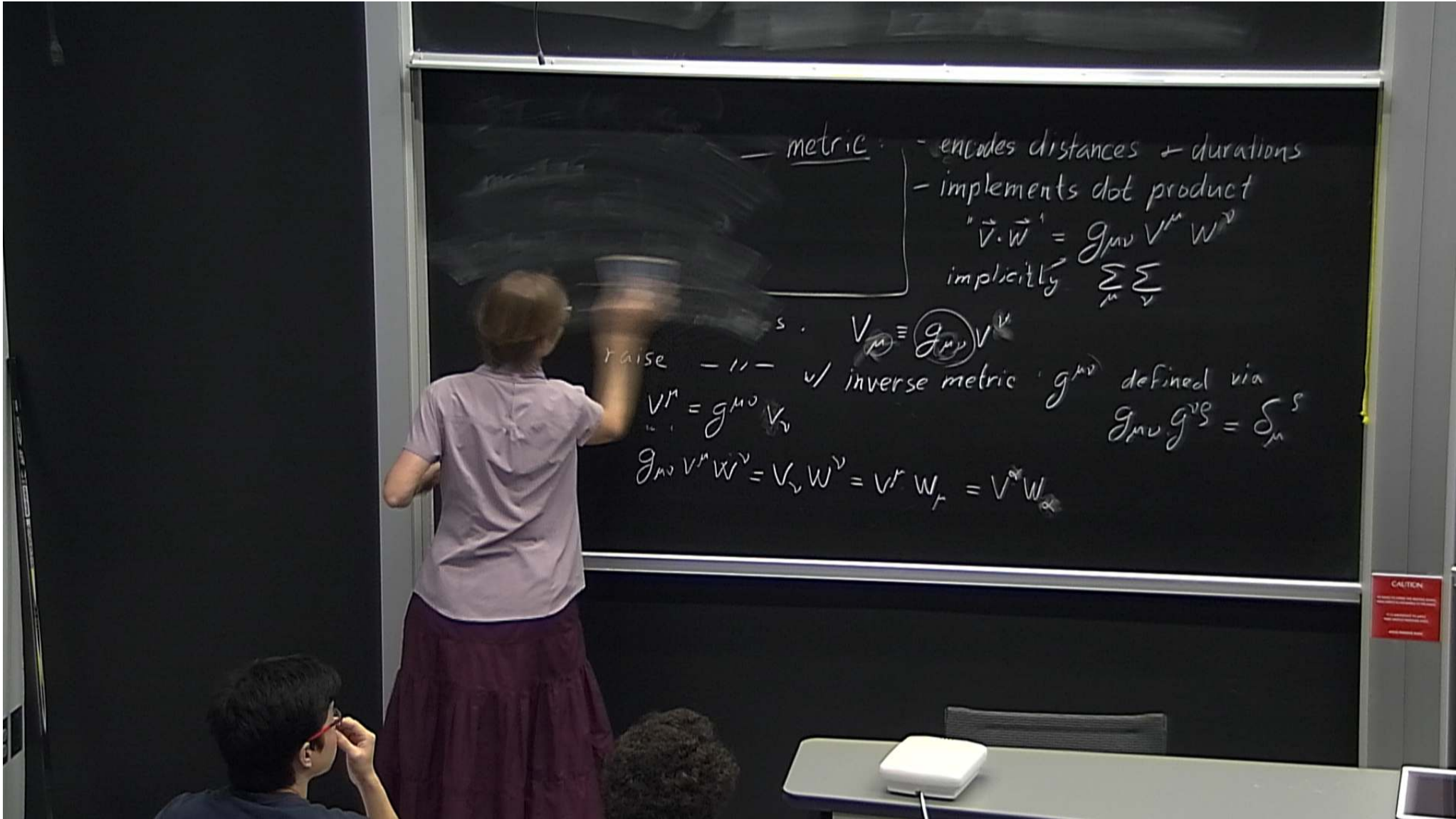


Spacelike geod. in Riemannian geom = curve of shortest length
 ($g_{\mu\nu}$ is positive definite)

determine from action

$$S = \int "ds^2"$$

0.01



— metric —

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$\delta S = 0 \rightarrow$ geodesic eqn:

$$\ddot{X}^M + \Gamma^M_{\alpha\beta} \dot{X}^\alpha \dot{X}^\beta = 0$$

$$\frac{d^2}{d\lambda^2} X^M(\lambda)$$

↳ Christoffel symbols:

$$\Gamma^M_{\alpha\beta} = \frac{1}{2} g^{M\gamma} (\partial_\alpha g_{\beta\gamma} + \partial_\beta g_{\alpha\gamma} - \partial_\gamma g_{\alpha\beta})$$

$$\frac{\partial}{\partial X^\alpha}$$

$$\text{sum} \sum_\gamma$$

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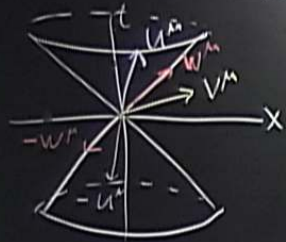
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X^M

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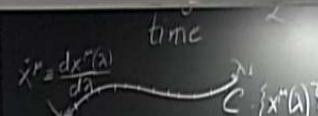
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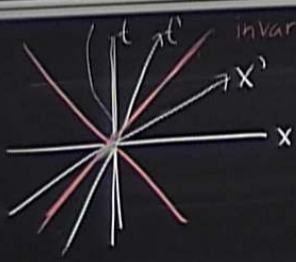
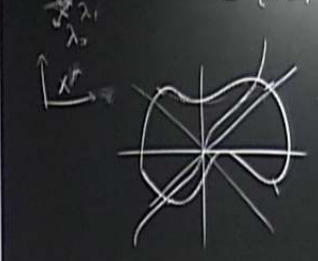
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invariant under reparam $(\lambda \rightarrow \tilde{\lambda})$
& coord. transformations
 $\mathcal{L}(C, g_{\mu\nu})$
GR: diffeomorphism inv. (generally covariant)
 \rightarrow all physical/geom. quantities are indep. of coords.



invariant under boost of rotation



$\eta_{\mu\nu}$ is inv. under Lorentz transf. Λ^μ_ν

$$\tilde{v}^\mu = \Lambda^\mu_\nu v^\nu$$

$$\rightarrow \eta = \Lambda^T \eta \Lambda$$

$$\Lambda = \begin{pmatrix} \cosh \theta & \sinh \theta & & \\ \sinh \theta & \cosh \theta & & \\ & & \cos \theta & \sin \theta \\ & & -\sin \theta & \cos \theta \end{pmatrix}$$

etc.

ex. coord. trans in \mathbb{R}^2 Cartesian \rightarrow polar (r, ϕ)
 \mathbb{R}^2 $x = r \cos \phi$
 $y = r \sin \phi$
 $ds^2 = dx^2 + dy^2 = dr^2 + r^2 d\phi^2$

Curved ST $ds^2 = d\theta^2 + \sin^2 \theta d\phi^2$

- initially || lines don't stay ||
- parallel-transported vector along closed curve doesn't return to itself
- curvature

Curvature:

Riemann curvature tensor

$$R_{\alpha\beta\gamma\delta} = \left(\partial_{\beta} \Gamma_{\alpha\gamma}^{\delta} + \Gamma_{\alpha\gamma}^{\mu} \Gamma_{\beta\mu}^{\delta} \right) - (\alpha \leftrightarrow \beta)$$

traceless/
Weyl. $C_{\alpha\beta\gamma\delta}$

trace

Ricci tensor $R_{\alpha\beta} = R_{\alpha\mu\beta}^{\mu}$

Riemann curvature tensor

$$R_{\alpha\beta\gamma\delta} = \left(\partial_{\beta} \Gamma_{\alpha\gamma}^{\delta} + \Gamma_{\alpha\eta}^{\mu} \Gamma_{\beta\gamma}^{\delta} - (\alpha \leftrightarrow \beta) \right)$$

traceless

Weyl: $C_{\alpha\beta\gamma\delta}$

trace

$$\text{Ricci tensor } R_{\alpha\beta} = R_{\alpha\mu\beta}^{\mu}$$

trace

$$\text{Ricci scalar } R = R_{\alpha}^{\alpha} = g^{\alpha\beta} R_{\alpha\beta}$$

etc.

CAUTION

B) Dynamics:
given by Einstein eqn:

$$R_{\mu\nu} - \frac{1}{2}R g_{\mu\nu} + \Lambda g_{\mu\nu} = 8\pi G_N T_{\mu\nu}$$

Annotations:
- A bracket under $R_{\mu\nu} - \frac{1}{2}R g_{\mu\nu}$ is labeled "curvature".
- An arrow points from $\Lambda g_{\mu\nu}$ to "cosmol. const."
- An arrow points from $8\pi G_N$ to "Newton's const".
- An arrow points from $T_{\mu\nu}$ to "stress-tensor".

B) Dynamics:

given by Einstein eqn:

$$R_{\mu\nu} - \frac{1}{2}R g_{\mu\nu} + \Lambda g_{\mu\nu} = 8\pi G_N T_{\mu\nu}$$

Annotations:
 - A bracket under $R_{\mu\nu}$ and $-\frac{1}{2}R g_{\mu\nu}$ is labeled "curvature".
 - An arrow points from $\Lambda g_{\mu\nu}$ to "Cosmol. const.".
 - An arrow points from $8\pi G_N$ to "Newton's const".
 - An arrow points from $T_{\mu\nu}$ to "stress-tensor".

→ d-dim: $\frac{d(d+1)}{2}$, 2nd order coupled, nonlinear PDEs
for $(g_{\mu\nu}(x) + T_{\mu\nu}(x))$



CAUTION
Do not touch the chalkboard
Do not use the chalk
Do not use the eraser

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 - A bracket under $R_{\mu\nu} - \frac{1}{2}R g_{\mu\nu}$ is labeled "curvature".
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B) Dynamics:

given by Einstein eqn:

$$R_{\mu\nu} - \frac{1}{2}R g_{\mu\nu} + \Lambda g_{\mu\nu} = 8\pi G_N T_{\mu\nu}$$

Annotations:
 - A bracket under $R_{\mu\nu}$ is labeled "curvature".
 - An arrow points from Λ to "cosmol. const.".
 - An arrow points from $8\pi G_N$ to "Newton's const.".
 - An arrow points from $T_{\mu\nu}$ to "stress-tensor".

→ d-dim: $\frac{d(d+1)}{2}$, 2nd order coupled, nonlinear PDEs
for $(g_{\mu\nu}(x) \pm T_{\mu\nu}(x))$

Vac. $\Lambda=0$ E eq. $R_{\mu\nu}=0$

$$\nabla^2 \phi = 4\pi G \rho$$

$$\underbrace{\hspace{10em}}_{g_{\mu\nu}}$$

$$\sim R_{\mu\nu}$$

$$T_{\mu\nu}$$

$$\nabla^\mu T_{\mu\nu} = 0$$

$$\uparrow$$
$$\partial + \Gamma$$

CAUTION

112 ... ar ... $\partial S = \partial x$...

$$\nabla^2 \phi = 4\pi G \rho$$

\downarrow \downarrow
 $g_{\mu\nu}$ $T_{\mu\nu}$

$\sim R_{\mu\nu}$

$$\nabla^\mu T_{\mu\nu} = 0$$

\uparrow
 $\partial + \Gamma$

Einstein-Hilbert action

$$S = \int d^4x \sqrt{-g}$$

CAUTION

ex. coord. trans. in \mathbb{R}^2 (x,y) (r,φ)
 $ds^2 = dx^2 + dy^2$

$$\nabla^2 \phi = 4\pi G \rho$$

\downarrow
 $g_{\mu\nu}$

$T_{\mu\nu}$

$\sim R_{\mu\nu}$

$$\nabla^\mu T_{\mu\nu} = 0$$

\uparrow
 $\partial + \Gamma$

Einstein-Hilbert action

$$S_{EH} = \int d^4x \sqrt{-g} (R - 2\Lambda)$$

$$S_{tot} = \frac{1}{16\pi G_N} S_{EH} + S_{matter}$$

$$T_{\mu\nu} = \frac{-1}{\sqrt{-g}} \frac{\delta S_{matter}}{\delta g^{\mu\nu}}$$

