Title: Towards postquantum information relativity: a status report

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Abstract: In this talk I will: 1) review the results of my work on a geometric approach to foundations for a postquantum information theory; 2) discuss how it is related to other foundational approaches, including some resource theories of knowledge and quantum histories; 3) present some of my research on a category theoretic framework for a multi-agent information relativity. More details on part 1: this approach does not rely on probability theory, spectral theory, or Hilbert spaces. Normalisation of states, convexity, and tensor products are allowed but not assumed foundationally. Nonlinear generalisation of quantum kinematics and dynamics is constructed using geometric structures (quantum relative entropies and Banach Lie-Poisson structure) over the sets of quantum states on W*-algebras. In particular, unitary evolution is generalised to nonlinear hamiltonian flows, while Lueders' rules are generalised to constrained relative entropy maximisations. Combined together, they provide a framework for causal inference that is a generalisation and replacement for completely positive maps, with information dynamics determined directly by epistemic constraints, and no requirement for lack of correlation. Orthodox probability theory and quantum mechanics are special cases of this framework. I will also give the progress report on the reconstruction conjecture: given the category of sets of abstract "states" equipped with the suitably defined entropic distances and BLP structure, how one reconstructs the W*-algebraic case? The discussion of the consistent operational semantics for this approach will lead us to the parts 2 and 3.

Plan

1. Nonlinear generalisations of quantum dynamics:

- Geometric structures on quantum state spaces \rightarrow relative entropies & Poisson brackets
- Lüders' rules \rightarrow constrained relative entropy maximisations
- Unitary evolution \rightarrow nonlinear hamiltonian flows

2. Geometric (post)quantum information foundations:

- Mathematical and physical principles
- Global and local dynamics
- Global and local reconstruction of QM

3. Category-theoretic operational semantics:

- Adjointness in foundations, functorial localisation
- Resource theories a la LdR–LK–RR
- Beyond adjointness: local monad–comonad systems

4. Towards [(post)quantum] local information relativity:

- From equilibrium to nonequilibrium space-time thermodynamics
- **•** Two-dimensional surfaces (θ, σ) and geometry in Klauder–Daubechies quantisation
- Quantum dynamics of (θ, σ) -spaces

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trace class operators: $\mathcal{T}(\mathcal{H}) := \{ \rho \in \mathfrak{B}(\mathcal{H}) \mid \rho \geq 0, \ \operatorname{tr}_{\mathcal{H}} |\rho| < \infty \}$ we will consider arbitrary sets of denormalised quantum states: $\mathcal{M}(\mathcal{H}) \subseteq \mathcal{T}(\mathcal{H})^+$

Quantum information distances $D: \mathcal{M}(\mathcal{H}) \times \mathcal{M}(\mathcal{H}) \rightarrow [0, \infty]$ s.t. $D(\rho, \sigma) = 0 \iff \rho = \sigma$.

E.g.

- $D_1(\rho, \sigma) := \operatorname{tr}_{\mathcal{H}}(\rho \log \rho \rho \log \sigma)$ [Umegaki'62]
- $D_{1/2}(\rho,\sigma) := 2 \|\sqrt{\rho} \sqrt{\sigma}\|_{\mathfrak{G}_{2}(\mathcal{H})}^{2} = 4 \operatorname{tr}_{\mathcal{H}}(\frac{1}{2}\rho + \frac{1}{2}\sigma \sqrt{\rho}\sqrt{\sigma})$ (Hilbert-Schmidt norm²)
- $D_{L_1(\mathcal{N})}(\rho,\sigma) := \frac{1}{2} \|\rho \sigma\|_{\mathcal{T}(\mathcal{H})} = \frac{1}{2} \operatorname{tr}_{\mathcal{H}} |\rho \sigma| (L_1/\text{predual norm})$
- $D_{\gamma}(\rho,\sigma) := \frac{1}{\gamma(1-\gamma)} \operatorname{tr}_{\mathcal{H}}(\gamma \rho + (1-\gamma)\sigma \rho^{\gamma}\sigma^{1-\gamma}); \gamma \in \mathbb{R} \setminus \{0,1\}$ [Hasegawa'93]
- $D_{\alpha,z}(\rho,\sigma) := \frac{1}{1-\alpha} \log \operatorname{tr}_{\mathcal{H}}(\rho^{\alpha/z} \sigma^{(1-\alpha)/z})^z; \alpha, z \in \mathbb{R}$ [Audenauert–Datta'14]
- $D_{\mathfrak{f}}(\rho,\sigma) := \operatorname{tr}_{\mathcal{H}}(\sqrt{\rho}\mathfrak{f}(\mathfrak{L}_{\rho}\mathfrak{R}_{\sigma}^{-1})\sqrt{\rho}); \mathfrak{f} \text{ operator convex, } \mathfrak{f}(1) = 0$ [Kosaki'82,Petz'85]

for $ran(\rho) \subseteq ran(\sigma)$, and with all $D(\rho, \sigma) := +\infty$ otherwise.

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DQC

Quantum entropic projections
Let
$$Q \subseteq T(\mathcal{H})^*$$
 be such that
for each $v \in \mathcal{M}(\mathcal{H})$
there exists a unique solution
 $\left\| \overline{\mathcal{P}(G)} = \arg \inf_{n \in \mathcal{A}}(G) \left(\overline{\mathcal{P}}(G) \right) \right\|$.
Let Ub be alled an entropic projection.
Eg:
 $for D_{1/2}(p, \sigma) = 2 \left[\sqrt{p} - \sqrt{p} \right]_{\mathcal{H}_{1}^{*}}^{2}$
consider the entropic projections Ψ_{0}^{2}
where Q are imagines of closed convex. subspaces $Q \subseteq \mathcal{K}^{*} := \Phi_{2}(\mathcal{H})^{*}$
under the mapping $Q \supseteq \sqrt{p} \mapsto p \in Q$.
They coincide with the ordinary projection operators in $\mathfrak{B}(\mathcal{K}) \cong \mathfrak{B}(\mathcal{H} \otimes \mathcal{H}^{*})$.

Quantum bayesian inference from quantum entropic projections

• RPK'13'14, F.Hellmann–W.Kamiński–RPK'14:

weak Lüders' rule is a special case of

$$\rho \mapsto \operatorname*{arg\,inf}_{\sigma \in \mathcal{Q}} \left\{ D_1(\rho, \sigma) \right\}$$

with

$$\mathcal{Q} = \{ \sigma \in \mathcal{T}(\mathcal{H})^+ \mid [P_i, \sigma] = 0 \; \forall i \}$$

estrong Lüders' rule derived from

$$\rho \mapsto \argmin_{\sigma \in \mathcal{Q}} \left\{ D_1(\rho, \sigma) \right\}$$

with

$$\mathcal{Q} = \{ \sigma \in \mathcal{T}(\mathcal{H})^+ \mid [P_i, \sigma] = 0, \ \operatorname{tr}_{\mathcal{H}}(\sigma P_i) = p_i \ \forall i \}$$

under the limit $p_2, \ldots, p_n \to 0$.

• hence, weak and strong Lüders' rules are special cases of quantum entropic projection $\mathfrak{P}_{\mathcal{Q}}^{D_0}$ based on relative entropy $D_0(\sigma, \rho) = D_1(\rho, \sigma)$.

Bayes–Laplace and Lüders' conditionings are special cases of entropic projections \Rightarrow "quantum bayesianism \subseteq quantum relative entropism".

Meaning: the rule of maximisation of relative entropy (entropic projection on the subspace of constraints) can be considered as a nonlinear generalisation of the dynamics describing "quantum measurement". [RPK'10'11]

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Principles of geometric (post)quantum kinematics
Global/sequential and local/parallel dynamics
Global and local reconstruction of QM

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Towards new foundations Key mathematical and conceptual change: A shift from ontology of eigenvalues (implemented by operators on Hilbert spaces and probabilistic statistics) to epistemology of expectations (implemented by geometry of state spaces of W*-algebras and quantum statistics). Idea: \circ consider spaces $\mathcal{M}(\mathcal{H})$ as fundamental • allow any nonlinear functions $\mathcal{M}(\mathcal{H}) \to \mathbb{R}$ as observables (smooth determine hamiltonian functions, affine determine self-adjoint operators) • define geometry of $\mathcal{M}(\mathcal{H})$ by means of $D(\cdot, \cdot)$ and $\{\cdot, \cdot\}$ • define dynamics of $\mathcal{M}(\mathcal{H})$ by means of $\mathfrak{P}^D_O(\cdot, \cdot)$ and $w^{\{h, \cdot\}}_t$ Questions: what's up with Hilbert spaces? what's up with spectral theory, probability, Born rule, etc? Answers: • replace Hilbert spaces \mathcal{H} by W^* -algebras \mathcal{N} • replace sets $\mathcal{M}(\mathcal{H})$ of density matrices on \mathcal{H} by sets $\mathcal{M}(\mathcal{N})$ of positive integrals on W^* -algebras e this setting is an exact generalisation of Kolmogorov's measure theoretic setting for probabili theory Ryszard Pawel Kostechi (Perimeter Institute)

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CO.C.

W*-algebras and integration • A W*-algebra N: ► an algebra over C with unit I, ▶ with " operation s.t. $(xy)^* = y^*x^*$, $(x+y)^* = x^* + y^*$, $(x^*)^* = x$, $(\lambda x)^* = \lambda^*x^*$, that is also a Banach space, ▶ with \cdot , +, * continuous in the norm topology (implied by the condition $||x^*x|| = ||x||^2$), ▶ such that there exists a Banach space \mathcal{N}_* satisfying Banach duality: $(\mathcal{N}_*)^* \cong \mathcal{N}$, Special cases: $\blacktriangleright \text{ if } \mathcal{N} \text{ is commutative then } \exists \text{ a measure space } (\mathcal{X}, \mu) \text{ s.t. } \mathcal{N}^+ \cong L_\infty(\mathcal{X}, \mu)^+ \text{ and }$ $\mathcal{N}_* \cong L_1(\mathcal{X}, \mu)$ $\models \text{ if } \mathcal{N} \text{ is "type I factor" then } \exists \text{ a Hilbert space } \mathcal{H} \text{ s.t. } \mathcal{N} \cong \mathfrak{B}(\mathcal{H}) \text{ and } \mathcal{N}_{\star}^+ \cong \mathcal{T}(\mathcal{H})^+.$ • Hence, the element $\phi \in (\mathcal{N}_{*})^{+}$ provides a joint generalisation of probability density and of density operator. By mean of embedding of \mathcal{N}_{*} into \mathcal{N}^{*} , it is also an integral on \mathcal{N}_{*} . • We chose $\mathcal{M}(\mathcal{N}) \subseteq \mathcal{N}^+_*$ as our generic quantum state spaces. Rynned Pawel Kontechi (Perimeter Institute)

	Noncommutative integration on W^* -algebras
	Commutative integration:
	underlying object localisable measure space: $(\mathcal{X}, U(\mathcal{X}), \mu)$ localisable boolean algebra: \mathcal{A}
	$\begin{array}{c c} L_p(\mathcal{A}) & L_p(\mathcal{A}, \bigcup(\mathcal{A}), \mu) \\ \hline \\ \text{states} \\ \text{expectations of observables} \end{array} & q \in \mathcal{M}(\mathcal{A}, \bigcup(\mathcal{A}), \mu) \subseteq L_1(\mathcal{X}, \bigcup(\mathcal{X}), \mu)^+ & \phi \in \mathcal{M}(\mathcal{A}) \subseteq L_1(\mathcal{A})^+ \\ L_{\infty}(\mathcal{X}, \bigcup(\mathcal{X}), \mu) \equiv f \mapsto \int_{\mathcal{X}} \mu q f \in \mathbb{R} \\ \end{array} & \phi \in L_{\infty}(\mathcal{A}) \equiv f \mapsto \phi(f) \in \mathbb{R} \end{array}$
	Noncommutative integration:
	underlying object Hilbert space with std. trace: (H, tray) W [*] -algebra: N
	$\begin{array}{c c} L_p\text{-spaces} & \mathfrak{O}_p(\mathcal{H}) = L_p(\mathfrak{O}(\mathcal{H}), \operatorname{tr}) & L_p(\mathcal{N}) \\ \text{states} & \rho \in \mathcal{M}(\mathcal{H}) \subseteq \mathfrak{O}_1(\mathcal{H})^+ \cong \mathfrak{O}(\mathcal{H})^+ & \phi \in \mathcal{M}(\mathcal{N}) \subseteq L_1(\mathcal{N})^+ \cong \mathcal{N}^+ \\ \text{expectations of observables} & \mathfrak{B}(\mathcal{H}) = \mathfrak{O}_{\infty}(\mathcal{H}) \ni x \mapsto \operatorname{tr}(\rho_X) \in \mathbb{C} & \mathcal{N} = L_{\infty}(\mathcal{N}) \ni x \mapsto \operatorname{tr}(\rho_X) \in \mathbb{C} \end{array}$
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Smooth quantum information geometries

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Under some conditions, D induces a generalisation of smooth riemannian geometry on $\mathcal{M}(\mathcal{N})$.

• $\mathcal{M}(\mathcal{H}) := \{\rho(\theta) \in \mathcal{T}(\mathcal{H}) \mid \rho(\theta) > 0 | \theta \in \Theta \subseteq \mathbb{R}^n \text{ open}, \theta \mapsto \rho(\theta) \text{ smooth} \} \text{ is a C-manifold}$

 Jenčová'05: a general construction of smooth manifold structure on the space of all strictly positive states over arbitrary W^{*}-algebra, with tangent spaces given by noncommutative Orlicz spaces.

• Eguchi'83/Ingarden et al'82/Lesnie ski-Ruskai'99/Jenčová'04: Every smooth distance D with positive definite hessian determines a riemannian metric g^D and a pair $(\nabla^D, \nabla^D^{\dagger})$ of torsion-free affine connections:

$$\begin{split} \mathbf{g}_{\phi}(u, \mathbf{v}) &:= -\partial_{u|\phi} \partial_{v|\omega} D(\phi, \omega)|_{\omega = \phi}, \\ \mathbf{g}_{\phi}((\nabla_{u})_{\phi} \mathbf{v}, w) &:= -\partial_{u|\phi} \partial_{v|\phi} \partial_{w|\omega} D(\phi, \omega)|_{\omega = \phi}, \\ \mathbf{g}_{\phi}(\mathbf{v}, (\nabla_{u}^{\dagger})_{\phi} w) &:= -\partial_{u|\phi} \partial_{v|\phi} \partial_{w|\phi} \partial_{w|\phi} D(\phi, \omega)|_{\omega = \phi}, \end{split}$$

which satisfy the characteristic equation of the Norden['37]-Sen['44] geometry,

$$\mathbf{g}^{D}(u,v) = \mathbf{g}^{D}(\mathbf{t}_{c}^{\nabla D}(u), \mathbf{t}_{c}^{\nabla D^{\dagger}}(v)) \quad \forall u, v \in \mathsf{T}\mathcal{M}(\mathcal{N}).$$

• A riemannian geometry $(\mathcal{M}(\mathcal{N}), \mathbf{g}^D)$ has Levi-Civita connection $\bar{\nabla} = (\nabla^D + \nabla^{D^{\dagger}})/2$.

Hessian geometries = dually flat Norden–Sen geometries

If $(\mathcal{M}, g, \nabla, \nabla^{\dagger})$ is a Norden–Sen geometry with flat ∇ and ∇^{\dagger} , then:

• there exists a unique pair of functions $\Phi : \mathcal{M} \to \mathbb{R}, \Phi^{L} : \mathcal{M} \to \mathbb{R}$ such that g is their hessian metric,

$$\mathbf{g}_{ij}(\rho) = \frac{\partial^2 \Phi(\rho(\theta))}{\partial \theta^i \partial \theta^j} \mathrm{d}\theta^i \otimes \mathrm{d}\theta^j, \ \mathbf{g}_{ij}(\rho) = \frac{\partial^2 \Phi^{\mathsf{L}}(\rho(\eta))}{\partial \eta^i \partial \eta^j} \mathrm{d}\eta^i \otimes \mathrm{d}\eta^j,$$

where: $\{\theta^i\}$ is a coordinate system s.t. $\Gamma_{ijk}^{\nabla}(\rho(\theta)) = 0 \ \forall \rho \in \mathcal{M},$ $\{\eta^i\}$ is a coordinate system s.t. $\Gamma^{\nabla^{\dagger}}ijk(\rho(\eta)) = 0 \ \forall \rho \in \mathcal{M}.$

the Eguchi equations applied to the Brègman distance

$$D_{\Phi}(\rho,\sigma) := \Phi(\rho) + \Phi^{\mathsf{L}}(\sigma) - \sum_{i} \theta^{i}(\rho) \eta^{i}(\sigma)$$

yield $(g, \nabla, \nabla^{\dagger})$ above.

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Smooth generalised pythagorean theorem

Let $(\mathcal{M}, \mathbf{g}, \nabla, \nabla^{\dagger})$ be a hessian geometry. Then for any $\mathcal{Q} \subseteq \mathcal{M}$ which is:

- ∇^{\dagger} -autoparallel := $\nabla_{u}^{\dagger} v \in \mathbf{T} \mathcal{Q} \ \forall u, v \in \mathbf{T} \mathcal{Q};$
- ∇^{\dagger} -convex := $\forall \rho_1, \rho_2 \in \mathcal{Q} \exists ! \nabla^{\dagger}$ -geodesics in \mathcal{Q} connecting ρ_1 and ρ_2 ;

there exists a unique projection

$$\mathcal{M} \ni \rho \mapsto \mathfrak{P}_{\mathcal{Q}}^{D_{\Phi}}(\rho) := \arg \inf_{\sigma \in \mathcal{Q}} \{ D_{\Phi}(\sigma, \rho) \} \in \mathcal{Q}.$$

- it is equal to a unique projection of ρ onto Q along a ∇-geodesic that is g-orthogonal at Q.
- it satisfies a generalised pythagorean equation

$$D_{\Phi}(\omega, \mathfrak{P}_{\mathcal{Q}}^{D_{\Phi}}(\rho)) + D_{\Phi}(\mathfrak{P}_{\mathcal{Q}}^{D_{\Phi}}(\rho), \rho) = D_{\Phi}(\omega, \rho) \quad \forall (\omega, \rho) \in \mathcal{Q} \times \mathcal{M}$$

Hence, for Brègman distances D_{Φ} the local entropic projections are equivalent with geodesic projections.

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Local effective dynamics

- One can combine locally the entropic projections with hamiltonian flows, by passing to the derived geodesic projections, and combining both in a single formula for effective dynamics.
- Given a hamiltonian observable h and a relative entropy D, the 1-form dh(φ) − d_∇ρ(φ) represents a local perturbation of causal dynamics by the information flow along entropic geodesics.
- In particular, $D_{1/2} = 2 \|\sqrt{\rho} \sqrt{\sigma}\|_{\mathcal{H}}^2$ gives Wigner–Yanase metric $\mathbf{g}^{1/2}$, with $d_{\mathbf{g}^{1/2}}(\rho, \sigma) = 2 \arccos(\operatorname{tr}_{\mathcal{H}}(\sqrt{\rho}\sqrt{\sigma}))$. The free fall along the geodesics of Levi-Civita connection $\nabla^{1/2}$ encodes the continuous process of projective measurement.
- The resulting effective dynamics can be given mathematically exact form in terms of a continuous-time regularised path-integral

$$\lim_{\varepsilon \to +0} \int \mathcal{D}\phi(\cdot) \mathrm{e}^{\mathrm{i} \int_{\gamma} \mathrm{d}t \left\langle \Omega_{\phi(t)}, \mathbf{d}_{\nabla^{1/2}}(\phi(t)\Omega_{\phi(t)} \right\rangle_{\mathcal{H}_{\phi(t)}}} . \tag{1}$$

$$\cdot e^{-i \int_{\gamma} dt \left\langle \Omega_{\phi(t)}, \pi_{\phi(t)}(dh(\phi(t))) \Omega_{\phi(t)} \right\rangle} e^{-\frac{\varepsilon}{2} \int_{\gamma} dt g_{ab}^{1/2}(\phi(t)) \dot{\phi}^{a} \dot{\phi}^{b}},$$
(2)

• If evaluated only on boundary pure states, and for $h(\phi) = \phi(\mathcal{H})$, it is known (Daubechies–Klauder'85, Anastopoulos–Savvidou'03) to be equal to $\langle \Omega(t = s), e^{-iHs} \Omega(t = 0) \rangle_{\mathcal{H}}$.

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Towards (post)quantum information relativity

Backwards compatibility: Global reconstructions

1a. (Global) Reconstruction of quantum mechanics:

- ▶ \mathcal{N} : type I W^* -algebras
- $\mathcal{M}(\mathcal{N})$: normalised states
- $D: D_{1/2} \text{ or } D_0$
- $\{\cdot, \cdot\}$: generated by Banach Lie algebra \mathcal{N}^{sa}
- observables: linear functions on $\mathcal{M}(\mathcal{N})$

2. Reconstruction of probability theory:

- ► N: commutative algebras
- $\mathcal{M}(\mathcal{N})$: normalised states
- D: arbitrary (but for D₁ or D₀, and specific types of constraints, Bayes' and Jeffrey's rules are recovered)
- $\{\cdot, \cdot\}$: trivialises for commutative algebras
- observables: arbitrary or affine functions on *M*(*N*)



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Backwards compatibility: Local reconstruction of [W*-]QM

D localc kinematics (only in tangent space):

- ▶ states: vectors of $\mathbf{T}_{\phi}\mathcal{M}(\mathcal{N})$ (configurations: $\phi(\theta) \rightarrow \theta \rightarrow \frac{\partial}{\partial \theta}$)
- ▶ effects: vectors of $T^{\circledast}_{\phi}\mathcal{M}(\mathcal{N})$ (observables: $f \to df(\phi)$)

local dynamics (only in tangent space):

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- causality: hamiltonian causality is local
- inference: arbitrary entropic projections are nonlocal, but the Norden-Sen geometries derived from relative entropies allow to localise entropic projections
- causality+inference: as presented few slides ago

reconstruction of W^* -algebras: Can we start from *arbitrary* sets \mathcal{M} , equipped with geometric structures $\{\cdot, \cdot\}$ and $D(\cdot, \cdot)$, without knowing that they are over W^* -algebras, and reconstruct $\mathcal{M} = \mathcal{M}(\mathcal{N})$ from some conditions? \rightarrow work in progress!

Basic idea of a proof: W^* -algebras = LJBW*-algebras = BLP submanifolds extendible to convex hull, with observables having Jordan structure = BLP submanifolds (=Poisson spaces) \mathcal{M} with riemannian structure induced from relative entropy and Kähler compatibility condition on the convex hull of $\mathcal{M} \leftarrow$ main conjecture

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- causality+inference: as presented few slides ago

reconstruction of W^* -algebras: Can we start from *arbitrary* sets \mathcal{M} , equipped with geometric structures $\{\cdot, \cdot\}$ and $D(\cdot, \cdot)$, without knowing that they are over W^* -algebras, and reconstruct $\mathcal{M} = \mathcal{M}(\mathcal{N})$ from some conditions? \rightarrow work in progress!

Basic idea of a proof: W^{-} -algebras = LJBW⁻-algebras = BLP submanifolds extendible to convex hull, with observables having Jordan structure = BLP submanifolds (=Poisson spaces) \mathcal{M} with riemannian structure induced from relative entropy and Kähler compatibility condition on the convex hull of $\mathcal{M} \leftarrow$ main conjecture

Plan

Nonlinear generalisations of quantum dynamics:

- Geometric structures on quantum state spaces \rightarrow relative entropies & Poisson brackets
- Lüders' rules \rightarrow constrained relative entropy maximisations
- Unitary evolution \rightarrow nonlinear hamiltonian flows

Geometric (post)quantum information foundations:

- Mathematical and physical principles
- Global and local dynamics
- Global and local reconstruction of QM

Category-theoretic operational semantics:

- Adjointness in foundations, functorial localisation
- Resource theories a la LdR–LK–RR
- Beyond adjointness: local monad–comonad systems

Towards [(post)quantum] local information relativity:

- From equilibrium to nonequilibrium space-time thermodynamics
- **•** Two-dimensional surfaces (θ, σ) and geometry in Klauder–Daubechies quantisation
- Quantum dynamics of (θ, σ) -spaces

Ryszard Paweł Kostecki (Perimeter Institute)

Towards (post)quantum information relativity 25

What is the predictive content of semantics of probability theory?

Consider:

- Θ : a space of possible configurations
- $\Theta \ni \theta = (\theta_1, \ldots, \theta_n)$: average values of *n* types of experimental configuration variables
- Ξ: a space of registrations

Example: MaxEnt + entropic projections (or Bayes' rule) + prediction:



Towards new semantics

Ryszard Passel Kostecki (Perimet

- One can use other model construction principles
- There is no need to use linear expectation type constraints
- This what we should care about is the relationship between model construction (information encoding), inference (information processing), and predictive verifiability (information decoding).

 $\geq (\{\rho(\theta) = \operatorname{proc}(f, \Theta) \mid \theta \in \Theta\}, f)$

 $\succeq (\{\vec{\rho} = \mathfrak{P}^{D}_{\mathcal{Q}(\Xi)}(\rho(\theta)) \mid \theta \in \Theta\}, f)$

PPQ(II)

 $\mathfrak{P}^{D}_{\mathcal{Q}(\tilde{\Xi})}$

in the test of the

 $f{=}\ell_{\Theta}(f_{\Theta}(\theta))$

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