Title: Entanglement of spacetime

Date: May 05, 2016 11:00 AM

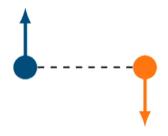
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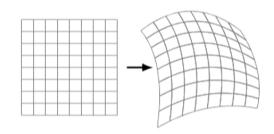
Abstract: Entanglement is both a central feature of quantum mechanics and a powerful tool for studying quantum systems. Even empty spacetime is a highly entangled state, and this entanglement has the potential to explain puzzling thermodynamic properties of black holes. In order to apply the methods of quantum information theory to problems in gravity we have to confront a more fundamental question: what is a local subsystem, and what are its physical degrees of freedom? I will show that local subsystems in gravity come with new physical degrees of freedom living on the boundary, as well as new physical symmetries. These structures offer us new insight into how spacetime is entangled, and a new perspective on the problem of quantizing gravity.

Pirsa: 16050020 Page 1/48

Quantum gravity

Quantum gravity must be consistent with principles of both quantum mechanics and general relativity.





Entanglement

General covariance

9

Pirsa: 16050020 Page 2/48

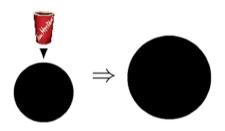
Black holes are thermodynamic systems

Thought experiment: Could we violate the second law of thermodynamics by throwing entropy down a black hole?

[Bekenstein 1972]

Black holes are thermodynamic systems, they radiate at the Hawking temperature [Hawking 1975]

$$T_H = \frac{\hbar c^3}{8\pi G k_B} \frac{1}{M}.$$



When we throw things in, the black hole grows according to the first law of black hole thermodynamics:

$$dE = T dS$$
.

Where $E = Mc^2$.

3

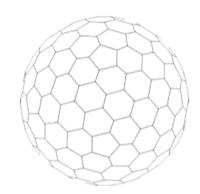
Pirsa: 16050020 Page 3/48

Black holes have entropy

From the first law we infer that black holes have **Bekenstein-Hawking entropy**

$$S_{\rm BH} = \frac{A \, c^3}{4 \, G \, \hbar}.$$

$$3 \times 10^{69} \text{ bits/m}^2$$



Usually entropy is the logarithm of phase space volume.

- What is the phase space?
- Why does S_{BH} scale like area, and not volume?

.

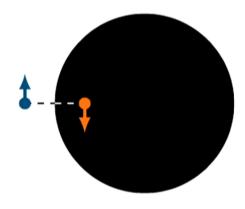
Pirsa: 16050020 Page 4/48

Entanglement

The inside of the black hole is entangled with its radiation.

This would naturally explain the area scaling of the entropy.

[Sorkin; Bombelli, Koul, Lee & Sorkin; Srednicki]



Entanglement plays many roles in theoretical physics:

- A probe of bulk geometry in AdS/CFT. [Ryu & Takayanagi]
- A renormalization-group monotone. [Vidal, Latorre, Rico & Kitaev; Casini & Huerta]
- A probe of confinement in QCD. [Klebanov, Kutasov & Murugan; Lewkowycz]
- An order parameter for topological phases. [Levin & Wen; Kitaev & Preskill]

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Pirsa: 16050020 Page 5/48

Entanglement & local symmetry

In all of these applications one encounters local symmetry.

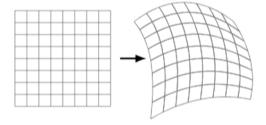
• AdS/CFT CFT is an SU(N) gauge theory.

Renormalization
 What can flow to the standard model?

• Confinement QCD is an SU(3) gauge theory.

Topological phases
 Systems with emergent gauge symmetry.

Gravity also has a local symmetry: general covariance.



Problem: In theories with local symmetry the usual rules of entanglement don't apply.

6

Pirsa: 16050020 Page 6/48

A new approach to subsystems

Local symmetries demand a new approach to subsystems.

Surface degrees of freedom

New states on the two-dimensional boundary of a subsystem.

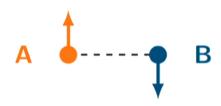
Surface symmetry

A symmetry that determines how states are entangled.

Pirsa: 16050020 Page 7/48

Entanglement

Entanglement is information about a quantum system that is not reducible to information about its subsystems.



$$|\psi\rangle = \frac{1}{\sqrt{2}} (|\uparrow\rangle \otimes |\downarrow\rangle - |\downarrow\rangle \otimes |\uparrow\rangle)$$

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Entanglement entropy

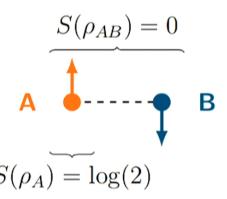
Lack of information is quantified with entropy.

For quantum states this is the von Neumann entropy:

$$S(\rho) = -\operatorname{tr}(\rho \log \rho).$$

A pure state has no entropy,

$$S(|\psi\rangle\langle\psi|) = 0.$$



If AB is in a pure state, $S(\rho_A) = S(\rho_B) = S$.

S is called the **entanglement entropy**.

Subsystems can have more entropy than the whole system.

10

Pirsa: 16050020 Page 9/48

Symmetry determines entanglement

The singlet state $|\psi\rangle$ is invariant under rotations.

$$\frac{1}{\sqrt{2}}(|\uparrow\rangle\otimes|\downarrow\rangle-|\downarrow\rangle\otimes|\uparrow\rangle) = \frac{1}{\sqrt{2}}(|\nwarrow\rangle\otimes|\searrow\rangle-|\searrow\rangle\otimes|\nwarrow\rangle)$$

$$A \longrightarrow B = A \longrightarrow \cdots \longrightarrow B$$

The reduced density matrices ρ_A and ρ_B are invariant.

This determines ρ_A and ρ_B , and hence $S = \log(2)$.

11

Pirsa: 16050020 Page 10/48

Entanglement of the vacuum

States in field theory — even the vacuum — are entangled.

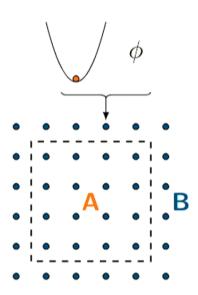
On each lattice site we place a harmonic oscillator ϕ .

The Hilbert space is a tensor product:

$$\mathcal{H} = igotimes_{\mathsf{vertices}} {}_v \mathcal{H}_v$$

The Hamiltonian includes interactions that couple neighbouring oscillators.

The ground state exhibits vacuum fluctuations that are correlated between regions A and B.



12

Pirsa: 16050020 Page 11/48

Entanglement scaling

Vacuum correlations are strongest at short distances.

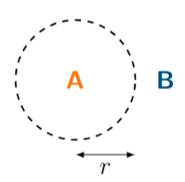
Ground state entanglement naturally follows an area law.

In a conformal field theory,

$$S = \# \frac{r^2}{\epsilon^2} - 4a \log \frac{r}{\epsilon} + \dots$$

where a is a central charge.

[Solodukhin; Casini, Huerta & Myers]



Entanglement entropy encodes universal information.

13

Pirsa: 16050020 Page 12/48

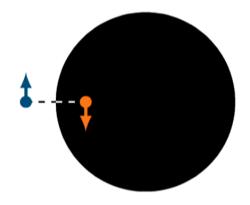
The area law

The area law term is divergent in field theory:

$$S = \#\frac{A}{\epsilon^2} + \dots$$

This term looks a lot like the Bekenstein-Hawking entropy:

$$S_{\rm BH}=rac{Ac^3}{4G\hbar}.$$

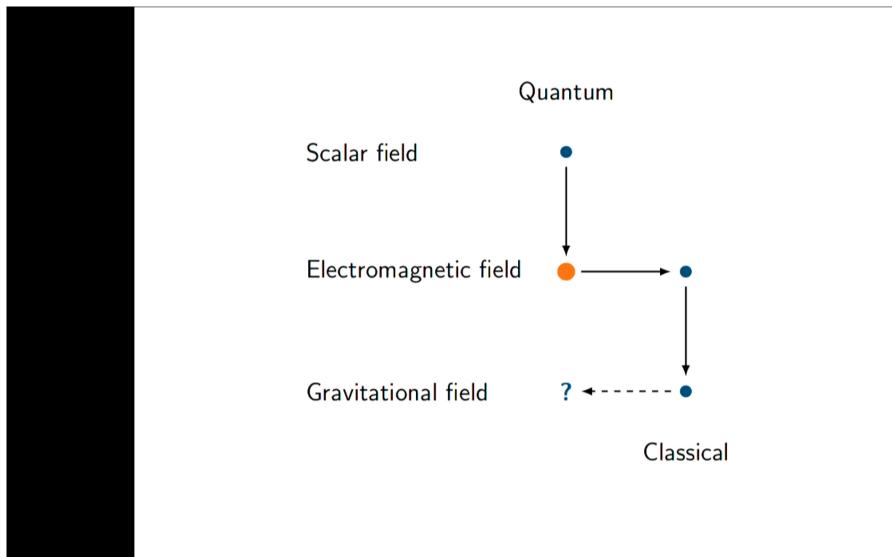


The entanglement result is consistent with G=0.

What happens when we turn on gravity?

1/

Pirsa: 16050020 Page 13/48



Pirsa: 16050020 Page 14/48

15

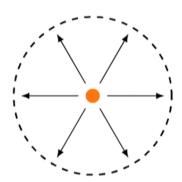
Electromagnetism

In a gauge theory, the degrees of freedom are non-local.

Electric field lines can only end on charges:

$$\nabla \cdot E = \rho.$$

A constraint equation.



How do we divide these non-local degrees of freedom?

16

Pirsa: 16050020 Page 15/48

Lattice gauge theory

Electromagnetism has a more subtle structure than a scalar.

For each link, let φ be the phase picked up by a hopping electron:

$$\varphi \in \mathbb{C}, \qquad |\varphi| = 1.$$

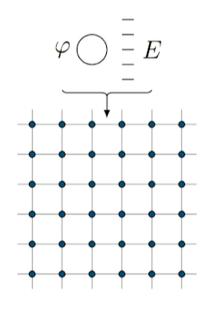
Let E be the electric field,

$$E = n e, \qquad n \in \mathbb{Z}.$$

They are canonically conjugate

$$[\varphi, E] = \varphi.$$

Each link of the lattice is a quantum system: a free particle on a circle of radius 1/e.



17

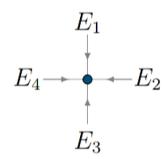
Pirsa: 16050020 Page 16/48

Gauss's law

Constraints restrict the Hilbert space.

In electrodynamics without charges, the constraint is Gauss's law:

$$\nabla \cdot E = 0.$$



Gauss's law generates a gauge transformation G_v at v.

On the lattice, we impose Gauss's law at each site:

$$\mathcal{H} = \bigotimes_e \mathcal{H}_e / \bigotimes_v G_v$$
.

Because of these constraints, ${\cal H}$ no longer factors.

18

Pirsa: 16050020 Page 17/48

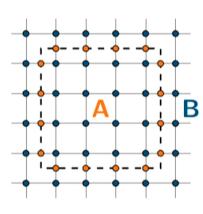
Extended Hilbert space

How do we divide the degrees of freedom between two regions?

We split each boundary link in half, putting half in A and half in B.

Define the extended Hilbert space:

$$\mathcal{H}_A = \bigotimes_{e \in A} \mathcal{H}_e / \bigotimes_{v \in A} G_v .$$



Where we impose Gauss's law at all interior vertices v.

 \mathcal{H}_A contains surface degrees of freedom: (φ, E_{\perp}) at all points on the boundary.

19

Pirsa: 16050020 Page 18/48

Symmetry determines entanglement

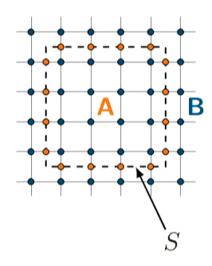
The tensor product $\mathcal{H}_A \otimes \mathcal{H}_B$ contains unphysical states.

Gauss's law at points on S says that electric fields match on both sides.

The space of physical states is

$$\mathcal{H} = \mathcal{H}_A \otimes \mathcal{H}_B/\mathcal{G}_S$$
.

This amounts to matching E_{\perp} at S.



The symmetry tells us how to combine subsystems.

2

Pirsa: 16050020 Page 19/48

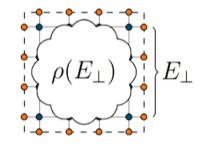
Reduced density matrix

States of ${\cal H}$ are invariant under the surface symmetry.

Hence ρ_A commutes with the electric fields normal to S.

We can simultaneously diagonalize E_{\perp} , and ρ_A is block diagonal in this basis:

$$\rho_A = \bigoplus_{E_\perp} p(E_\perp) \rho(E_\perp)$$



 $p(E_{\perp})$ is the probability distribution over different boundary conditions E_{\perp} .

 $\rho(E_{\perp})$ is a density matrix with fixed boundary conditions.

22

Pirsa: 16050020 Page 20/48

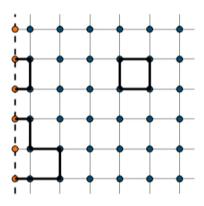
Entanglement entropy

For gauge-invariant states the entropy simplifies: [WD 2011]

$$S = -\operatorname{tr}(\rho_A \log \rho_A)$$

$$= -\sum_{E_{\perp}} p(E_{\perp}) \log p(E_{\perp}) + \sum_{E_{\perp}} p(E_{\perp}) S(\rho(E_{\perp})).$$

The first term is the entropy of the surface degrees of freedom.



23

Pirsa: 16050020 Page 21/48

Surface degrees of freedom matter

Surface degrees of freedom make up O(1) of the entropy.

$$S = -\sum_{E_{\perp}} p(E_{\perp}) \log p(E_{\perp}) + \sum_{E_{\perp}} p(E_{\perp}) S(\rho(E_{\perp})).$$

This result has been checked for many systems:

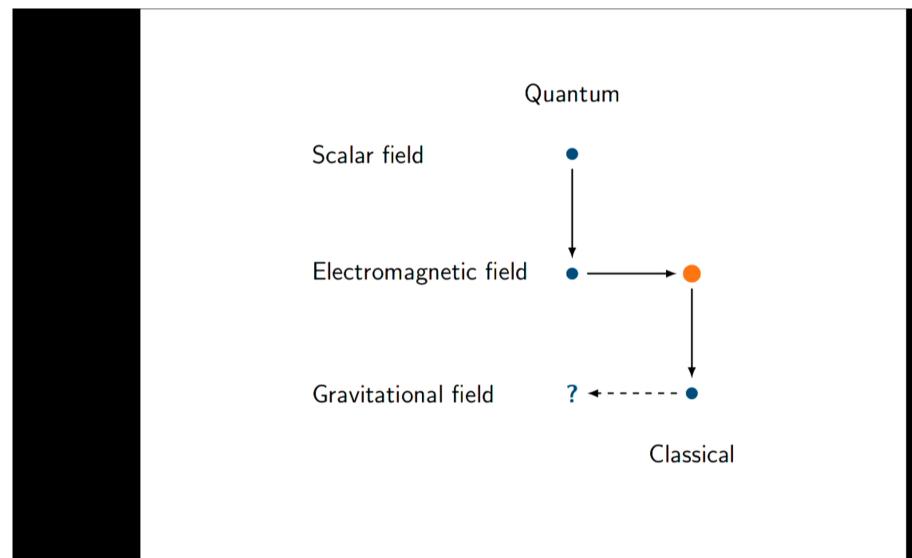
- The toric code [WD 2011]
- Electrodynamics in 2+1 [Agon, Headrick, Jafferis, & Kasko 2013]
- Electrodynamics in 3+1 [WD & Wall 2014]

The results generalizes to nonabelian theories [WD 2014]

- Quark-antiquark pairs [Lewkowycz & Maldacena 2013]
- ullet Yang-Mills in 1+1 [WD 2014, Gromov & Santos 2014]
- ullet Yang-Mills in 2+1 at weak coupling [Radičević 2015]

24

Pirsa: 16050020 Page 22/48



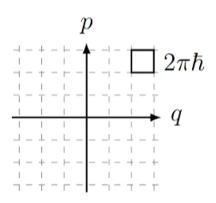
Pirsa: 16050020 Page 23/48

Phase space

The classical analog of a Hilbert space is a phase space.

The key structure is the symplectic potential

$$\Theta = p \, \delta q$$
.



 Θ encodes all the structure of classical mechanics:

- Relates symmetries and conserved charges.
- Tells us what is physical and what is gauge.
- Determines the Poisson brackets (\sim commutators).
- Gives the density of states in phase space.

26

Pirsa: 16050020 Page 24/48

Covariant phase space

We can associate a phase space to electrodynamics in a region.

This phase space is defined by the symplectic potential:

$$\Theta = \int_{\Sigma} d\Sigma_{\mu} \; \theta^{\mu}.$$

In electrodynamics we have

$$\theta^{\mu} = F^{\mu\nu} \, \delta A_{\nu}.$$

Σ

The vector potential is conjugate to the electric field.

27

Pirsa: 16050020 Page 25/48

Covariant phase space

The symplectic potential Θ must be gauge invariant.

Under a gauge transformation $A_{\mu} \rightarrow A_{\mu} + \partial_{\mu} \alpha$.

$$\theta^{\mu} = F^{\mu\nu} \, \delta A_{\nu}.$$

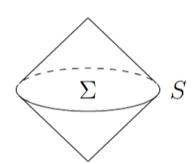
$$\theta^{\mu} \to \theta^{\mu} + \partial_{\nu} \left(F^{\mu\nu} \, \delta \alpha \right).$$

This is a total derivative, hence a surface integral

$$\Theta \to \Theta + \oint_S dS \, E_\perp \delta \alpha.$$



We must not set $E_{\perp} = 0$: we would undercount the entropy.



28

Pirsa: 16050020 Page 26/48

Extended phase space

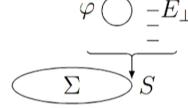
Key idea: extend the phase space. [WD & Freidel 2016]

We introduce the $\varphi \in U(1)$ to the phase space.

This allows us to define an extended symplectic potential:

$$\Theta = \int_{\Sigma} d\Sigma_{\mu} \; \theta^{\mu} + \oint_{S} dS \; E_{\perp} \varphi^{-1} \delta \varphi.$$

 Θ is determined by gauge invariance: the boundary term cancels out the anomalous term.

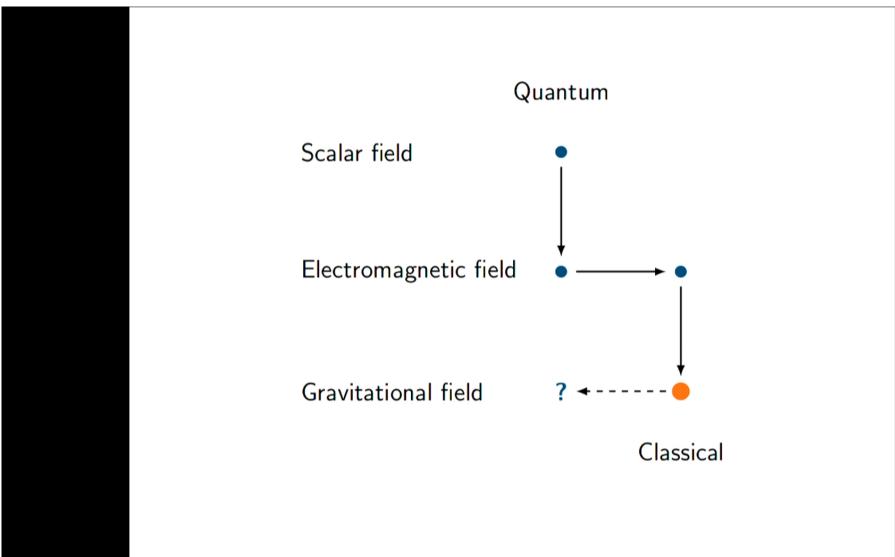


The surface degrees of freedom (φ, E_{\perp}) are physical.

 E_{\perp} generates rotations of φ — the surface symmetry.

20

Pirsa: 16050020 Page 27/48



Pirsa: 16050020 Page 28/48

30

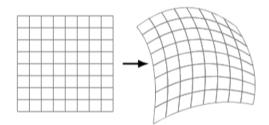
Gravity

Gravity is a theory with a local symmetry, general covariance.

This symmetry leads to constraint equations: equations of motion with no time derivatives.

The constraints are responsible for the force of gravity:

$$\nabla^2 \Phi = 4\pi G \,\rho.$$



Regions of space are not independent subsystems.

We can treat them the same way as in electrodynamics.

3

Pirsa: 16050020 Page 29/48

General relativity

The covariant canonical formalism extends naturally to gravity.

In general relativity the fundamental field is the metric $g_{\mu\nu}$.

In units where $16\pi G = 1$, the symplectic potential is

$$\Theta = \int_{\Sigma} d\Sigma_{\mu} \; \theta^{\mu}.$$



Where the vector field θ is given by:

[Ashtekar; Crnković; Witten; Wald;...]

$$\theta^{\mu} = (g^{\mu\alpha}g^{\nu\beta} - g^{\mu\nu}g^{\alpha\beta})\nabla_{\nu}\delta g_{\alpha\beta}.$$

32

Pirsa: 16050020 Page 30/48

General covariance

The symplectic potential Θ is not diffeomorphism invariant.

Let $Y: M \to M$ be a diffeomorphism.

Under this symmetry, θ transforms as:

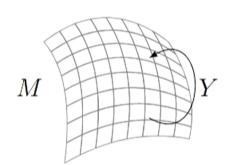
$$\theta^{\mu} \to Y^*(\theta^{\mu} + \partial_{\nu}Q^{\mu\nu}[\delta_Y]).$$

Q is Wald's Noether charge: [Wald 1993]

$$Q_{\mu\nu}[\xi] = \partial_{\mu}\xi_{\nu} - \partial_{\nu}\xi_{\mu}.$$



- θ^{μ} transforms like a vector field.
- There is a boundary term that depends on δ_Y .



33

Pirsa: 16050020 Page 31/48

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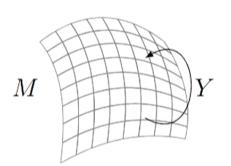
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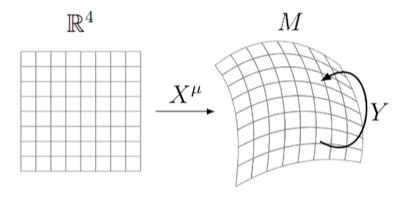
33

Pirsa: 16050020 Page 32/48

Extended phase space

In gravity, a choice of gauge is a choice of coordinates.

Introduce $X^{\mu}:\mathbb{R}^4 o M$ to the phase space [WD & Freidel 2016]



 X^{μ} is the gravitational analog of φ .

Pirsa: 16050020

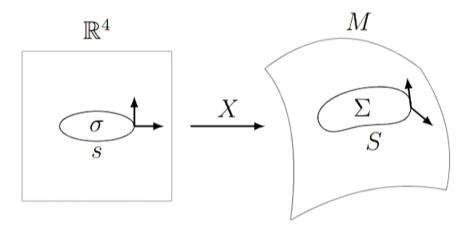
3

Extended phase space

Using X we define the extended symplectic potential:

$$\Theta = \int_{X(\sigma)} d\Sigma_{\mu} \, \theta^{\mu} + \oint_{X(s)} dS_{\mu\nu} \, Q^{\mu\nu} [\delta_X].$$

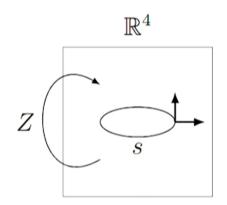
 Θ is determined by diffeomorphism invariance.



35

Surface symmetry

The surface symmetries are diffeomorphisms $Z: \mathbb{R}^4 \to \mathbb{R}^4$ that change s and its frame.



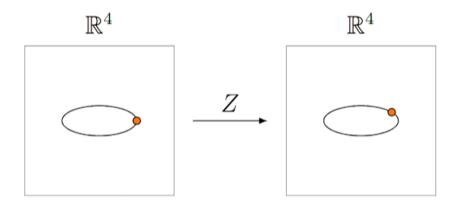
There are three classes of symmetries.

37

Pirsa: 16050020 Page 35/48

Surface diffeomorphisms

Surface diffeomorphisms leave the entangling surface invariant, but move the points around.



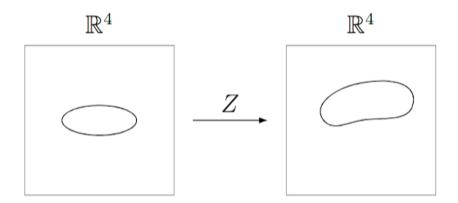
Infinitesimal surface diffeomorphisms are vector fields such that

$$W_{\perp}|_{S} = 0$$
 and $W_{\parallel}|_{S} \neq 0$.

39

Surface translations

Surface translations move the entangling surface.



Infinitesimal surface translations are vector fields such that

$$W_{\perp}|_{S} \neq 0.$$

They are not canonical symmetries of the phase space; there can be flux of states through the boundary.

40

Surface symmetry algebra

The generators are precisely encoded in the geometry of S:

 Surface diffeomorphisms are generated by the curvature of the normal connection:

$$\mathsf{Diff}(S).$$

• Surface boosts are generated by the normal metric:

$$SL(2,\mathbb{R}).$$

The Casimir is the area element.

These are the surface degrees of freedom analogous to E_{\perp} .

They generate a nonabelian algebra: [WD & Freidel 2016]

$$\mathsf{Diff}(S) \ltimes \mathsf{SL}(2,\mathbb{R})^S$$
.

The geometry of the boundary is noncommutative.

41

Pirsa: 16050020 Page 38/48

Surface symmetry algebra

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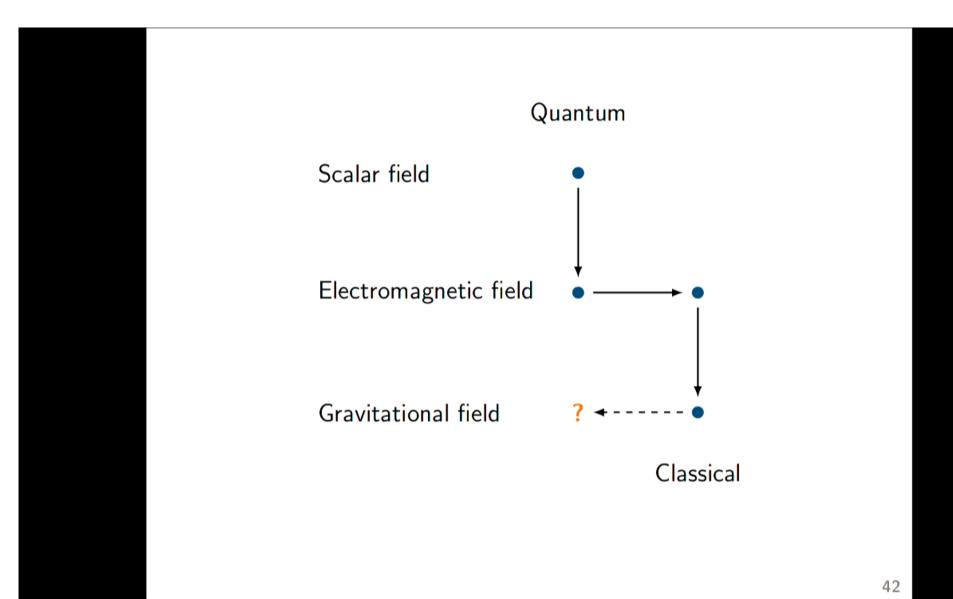
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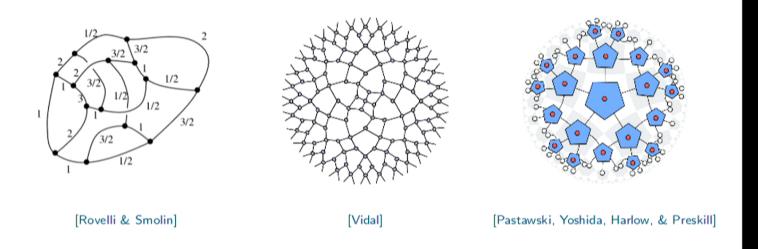
Pirsa: 16050020 Page 39/48



Pirsa: 16050020 Page 40/48

Building blocks of space

Space is a network of entangled subsystems.



What are the subsystems for gravity?

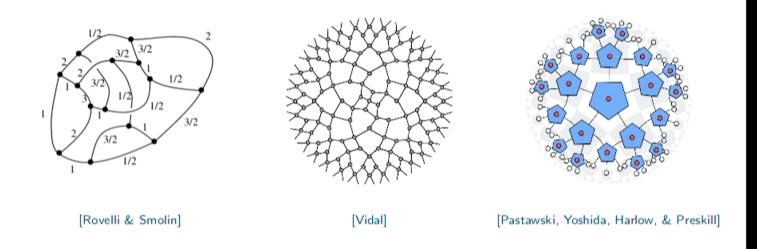
How are they entangled?

43

Pirsa: 16050020 Page 41/48

Building blocks of space

Space is a network of entangled subsystems.



What are the subsystems for gravity?

How are they entangled?

43

Pirsa: 16050020 Page 42/48

Quantization

We have constructed classical subsystems, the next step is to quantize them.

To quantize a system, first study representations of its symmetries.

We have a huge symmetry group

$$\mathsf{Diff}(S) \ltimes \mathsf{SL}(2,\mathbb{R})^S$$
.

What can we say about its representations?



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Pirsa: 16050020 Page 43/48

Quantum surface symmetries

The surface symmetry is a semidirect product, like Poincaré.

[Wigner 1939]

Poincaré	Surface symmetry
$SO(1,3) \ltimes \mathbb{R}^4$	$Diff(S) \ltimes SL(2,\mathbb{R})^S$
Translations	Surface boosts
4-momentum	Area element
Mass	Total area
Little group $SO(3)$	Area-Preserving Diffeomorphisms $APD(S)$
Spin	Irreducible representation of $APD(S)$

Representations labelled by area and transform under APD.

45

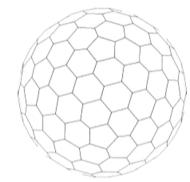
Pirsa: 16050020 Page 44/48

Quantum phase space

What are the area-preserving diffeomorphisms?

 $\mathsf{APD}(S^2)$ is the symmetry group of a classical phase space: a sphere!

Representations are quantizations of this phase space.



The size of a Planckian cell is determined by Θ : the Planck area $\sim G\hbar/c^3$.

Is the horizon quantized just like a phase space?

4

Pirsa: 16050020 Page 45/48

Conclusions

- Entanglement is everywhere even empty space.
- Local symmetries demand a new approach to subsystems:

Surface degrees of freedom Surface symmetry

- Surface symmetry determines how states are entangled.
- Surface symmetry is present in classical gravity, and offers:

A definition of local subsystems,

A way to understand entropy of black holes, and

A new perspective on quantizing gravity.

Thank you!

Pirsa: 16050020

4

Surface symmetry generators

The generators of surface-preserving symmetries are geometric.

In coordinates around S the metric takes the form

$$ds^{2} = h_{ij}dx^{i}dx^{j} + q_{\mu\nu} \left(d\sigma^{\mu} - A_{i}^{\mu}dx^{i}\right) \left(d\sigma^{\nu} - A_{j}^{\nu}dx^{j}\right)$$

The generators are given by

$$H_w = \int_S \left(H_i^{\ j} (\partial_j W_\perp^i) + W_\parallel^\mu F_\mu \right)$$

The boost generator is the conformal normal metric:

$$H_i{}^j = \frac{\sqrt{q}}{\sqrt{|h|}} h_{ik} \epsilon^{kj}$$

The diffeomorphism generator is the curvature of A_i^{μ} :

$$F^{\mu} = \frac{\sqrt{q}}{\sqrt{|h|}} \left(\partial_0 A_1^{\mu} - \partial_1 A_0^{\mu} + [A_0, A_1]^{\mu} \right)$$

49

Pirsa: 16050020 Page 47/48

Surface symmetry algebra

The relation $\{H_v, H_w\} = H_{[v,w]}$ gives the Poisson brackets:

$$\{H_{i}^{j}(\sigma), H_{k}^{l}(\sigma')\} = (\delta_{i}^{l}H_{k}^{j} - H_{i}^{l}\delta_{k}^{j})(\sigma)\delta^{(D-2)}(\sigma, \sigma'),$$

$$\{F_{\mu}(\sigma), F_{\nu}(\sigma')\} = F_{\mu}(\sigma')\partial_{\nu}\delta^{(D-2)}(\sigma, \sigma') - F_{\nu}(\sigma)\partial'_{\mu}\delta^{(D-2)}(\sigma, \sigma'),$$

$$\{H_{i}^{j}(\sigma), F_{\mu}(\sigma')\} = H_{i}^{j}(\sigma')\partial_{\mu}\delta^{(D-2)}(\sigma, \sigma').$$

These realize the surface symmetry group

$$\mathcal{G} = \mathsf{Diff}(S) \ltimes \mathsf{SL}(2,\mathbb{R})^S$$

The $SL(2,\mathbb{R})$ Casimir is $\det H = -\det q$.

The normal metric breaks $SL(2, \mathbb{R})$ to a boost subgroup (c.f. Carlip & Teitelboim)

50

Pirsa: 16050020 Page 48/48