

Title: Stereoscopic CFT Tools for Holography

Date: Apr 13, 2016 11:00 AM

URL: <http://pirsa.org/16040089>

Abstract: <p>I will discuss a natural basis of CFT operators for probing dual gravitational physics in a diffeomorphism-invariant manner. On the CFT side, these operators are already well-known: they are 'OPE Blocks' that contribute to the Operator Product Expansion with fixed Casimir. On the gravity side, I will show that these OPE blocks are dual to diff-invariant geodesic or surface operators. Our new entry to the holographic dictionary can be understood as an operator generalization of the Ryu-Takayanagi proposal and I will show it gives a unified description for a host of important results in holography. </p>

A Stereoscopic CFT Lens for Holography

JAMES SULLY

B. Czech, L. Lamprou, S.McCandlish, B. Mosk, JS arXiv: 1604.03110

B. Czech, L. Lamprou, S.McCandlish, B. Mosk, JS arXiv: 1605.XXXX

(Related Work: de Boer, Haehl, Heller, Myers)

Perimeter Institute
April 2016

Motivation

There is an uncomfortable asymmetry in our use of the holographic dictionary:

Boundary: *Gauge-invariance is sacrosanct.*

- We always use gauge-invariant observables (eg. $O = \text{Tr}(X)$) to probe the bulk and vice-versa.

Bulk: *Diff-invariance is required... in the same way that flossing is required.*

- When we visit an expert twice a year, we acknowledge the importance of diff-invariance (naïve local observables require gravitational dressing).
- We really only worry about it once a month or so.
- We are usually happy to work with local quantities (eg. some field $\phi(x)$).

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Worrying about **diff-invariance** is largely seen as adding **unpleasant (and unnecessary) complications**.

Is this a fair assessment?

Aim of this talk: To convince you the answer is **NO**.

NO to what?

No, talking about bulk gravitational physics in naturally diff-invariant, non-local variables is **NOT** more complicated nor unpleasant.

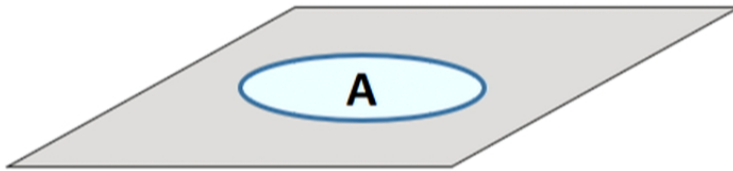
There is ample historical precedent that this might be true, or is at least conceptually pleasing.

- (Strings, branes, S-matrices, ...)

From amplitudes: have learned it can be important to be mindful of the symmetries we make manifest, and useful to get a little healthy distance from locality.

Prototypical Example

- We already have one *well-known, well-defined* example of what we're looking for:
- The **Ryu-Takayanagi (RT/HRT) proposal** connects:
1) In the CFT:



The **entanglement entropy** of a region A on the boundary as well as its **modular Hamiltonian** H_{mod} (*Natural, nonlocal, Gauge-invariant*)

A Better Dictionary 1: The Boundary

What are natural non-local variables in the CFT?

- There already exists a well-understood and powerful framework: **The Operator Product Expansion (OPE)**:

- Decompose bilocal operators into a sum of non-local OPE blocks $\mathcal{B}(x, y)$

$$\mathcal{O}_i(x) \mathcal{O}_j(0) = \sum_k C_{ijk} |x|^{\Delta_k - \Delta_i - \Delta_j} (1 + b_1 x^\mu \partial_\mu + b_2 x^\mu x^\nu \partial_\mu \partial_\nu + \dots) \mathcal{O}_k(0)$$

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 - Separates **kinematics** of conformal invariance and **dynamical** data of theory
- The OPE block is a natural choice of **fundamental** variable for CFT

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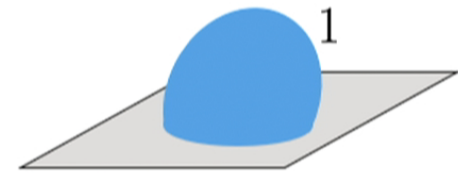
- Central to our understanding of CFT (bootstrap, etc...)
 - Separates **kinematics** of conformal invariance and **dynamical** data of theory
- The OPE block is a natural choice of **fundamental** variable for CFT
 - **Non-local, gauge-invariant**, transforms in **simple representation** of Conformal Group
 - *It already appears in our benchmark example: we will see that the modular Hamiltonian has a simple expression in the language of OPE blocks.*

A Better Dictionary 2: The Bulk

What are natural non-local variables in the CFT?

- Precisely as in RT, a natural set of non-local, diff-invariant objects are **minimal (extremal) surfaces and geodesics**.
- We can think of their areas as integrating the unit operator over the minimal surface:

$$A = \int d^n x \sqrt{h}(1)$$



- A natural generalization then is:

$$\tilde{\phi} = \int d^n x \sqrt{h}(\phi)$$



The Kinematic Dictionary

- In this talk I will **establish a correspondence**

$$\mathcal{B}(x, y) \leftrightarrow \tilde{\phi}(x, y)$$

between **OPE Blocks** and **geodesic operators** (and extensions to surface operators)

- This will be a **powerful framework**. It brings together many familiar ideas in holography, including:
 1. The **Entanglement First Law** and **Einstein's Equations** [Faulkner, Guica, Hartman, Lashkari, McDermont, Myers, Swingle, Van Raamsdonk]
 2. **Geodesic Witten diagrams** and **conformal blocks** [Hijano, Kraus, Perlmutter, Snively]
 3. The **HKLL** construction of interacting '**local**' **bulk fields** [Hamilton, Kabat, Lifschytz, Lowe]+...
 4. **de Sitter dynamics** for the variations of **EE** [de Boer, Heller, Myers, Neiman] [Nozaki, Numasawa, Prudenziati, Takayanagi], [Bhattacharya, Takayanagi]



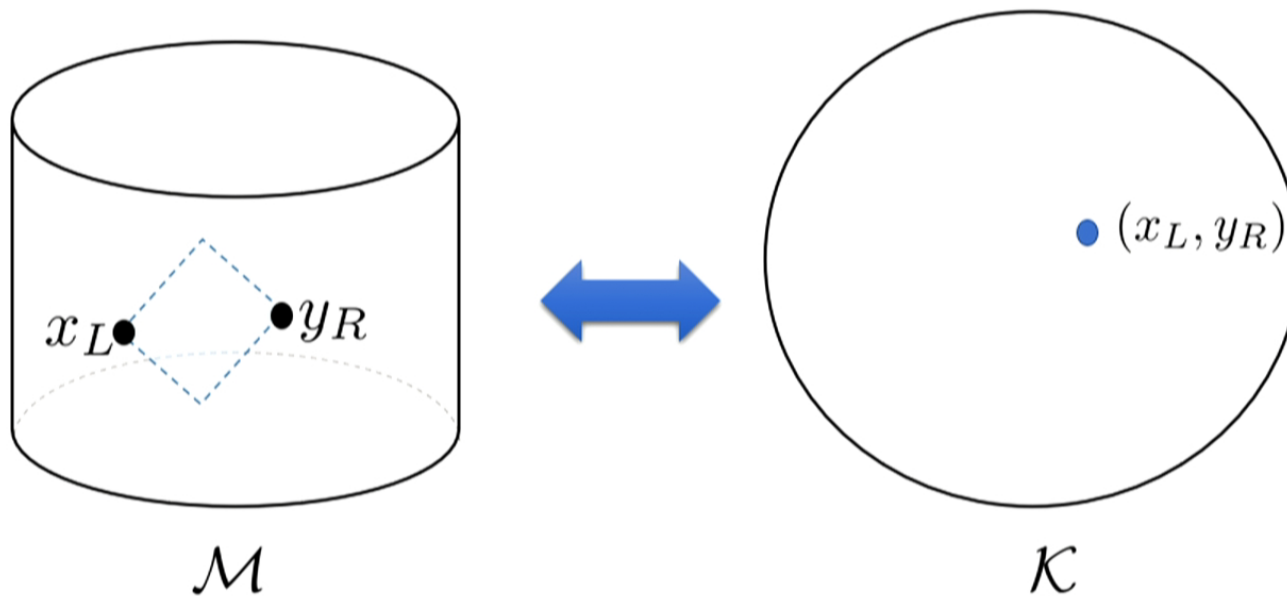
A Survey of Kinematic Space

Kinematic Space

- Our non-local, gauge-invariant entries to the holographic dictionary are best organized by a **'kinematic space'**:
 - Consider **ordered pairs of spacelike separated points** on the CFT_2 cylinder

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Kinematic Space

- Can we assign a **metric** to kinematic space?

$$ds_{\mathcal{K}}^2 = f_{\mu\nu}^{xy}(x, y) dx^\mu dy^\nu + f_{\mu\nu}^{xx}(x, y) dx^\mu dx^\nu + f_{\mu\nu}^{yy}(x, y) dy^\mu dy^\nu$$

- The metric on \mathcal{K} should be **invariant under conformal transformations**.

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- The metric on \mathcal{K} should be **invariant under conformal transformations**.
 - No terms like $dx^\mu dx^\nu$ or $dy^\mu dy^\nu$:

$$x \circlearrowleft \begin{matrix} \bullet y \\ \bullet y + dy \end{matrix} \qquad x + dx \circlearrowleft \begin{matrix} \bullet y \\ \bullet y + dy \end{matrix}$$

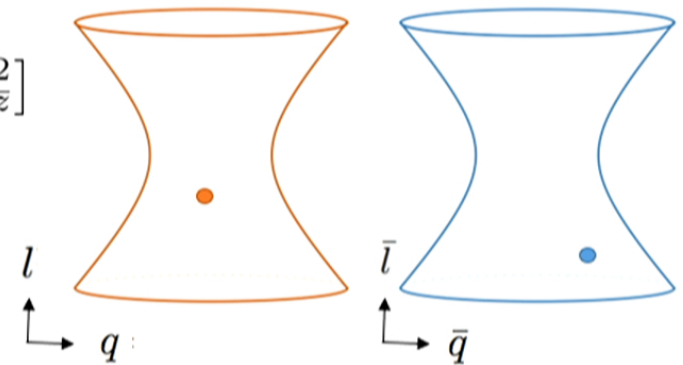
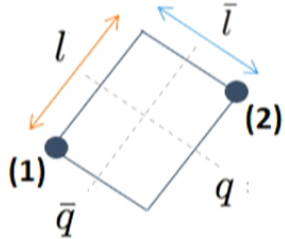
- Metric transforms like a pair of operators of conformal dimension (1,1)

$$f_{\mu\nu}(x, y) \rightarrow \frac{dx'^\alpha}{dx^\mu} \frac{dy'^\beta}{dy^\nu} f_{\alpha\beta}(x', y')$$

Kinematic Space for AdS₃/CFT₂

- This metric simplifies for **d=2** because $SO(2,2) = SO(2,1) \times SO(2,1)$:
 - Change to left-moving and right-moving coordinates $\{ \Delta z = l, z_c = q, z \leftrightarrow \bar{z} \}$ for the CFT

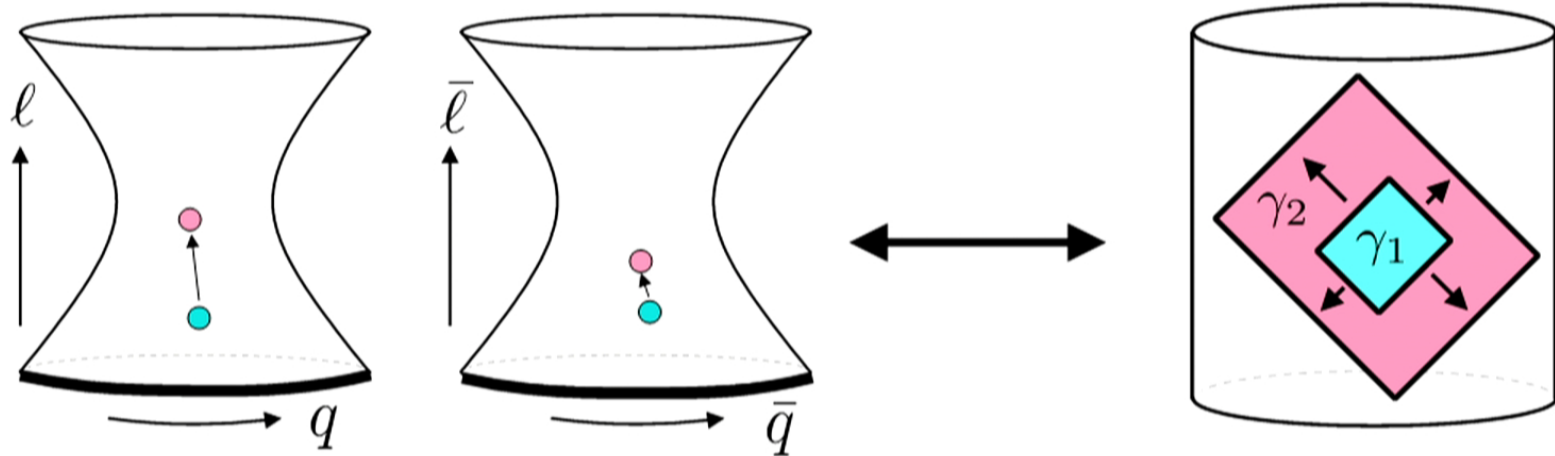
$$ds^2 = \frac{1}{2} \left[\underbrace{\frac{dq^2 - dl^2}{l^2}}_{dS_z} + \underbrace{\frac{d\bar{q}^2 - d\bar{l}^2}{\bar{l}^2}}_{dS_{\bar{z}}} \right] = \frac{1}{2} [ds_z^2 + ds_{\bar{z}}^2]$$



- We can also restrict to **pairs of points that lie on a time slice**, say $t=0$, (or geodesics that lie in a 2-dimensional hyperbolic plane). Then fix $z = \bar{z}$, and take the **diagonal space** in the two coordinates

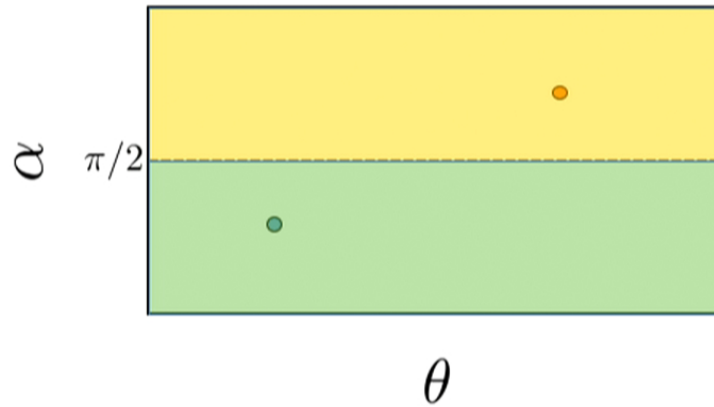
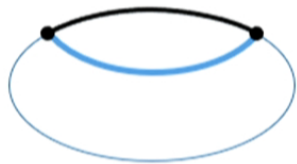
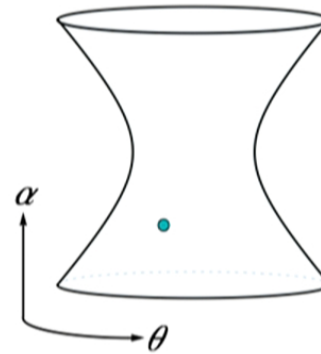
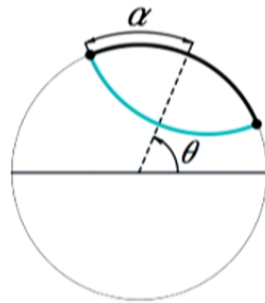
Kinematic Metric

- Has a notion of **causality**: Partial order of causal diamonds.



Kinematic Space for $\text{AdS}_3/\text{CFT}_2$

- Our coordinates on the plane cover a patch of de Sitter. In global coordinates:



$$\theta \rightarrow \theta + \pi$$

$$\alpha \rightarrow \pi - \alpha$$

Summary

- **Kinematic Space** is the space of:
 1. **Ordered pairs of points** (x_L, y_R) in the CFT
 2. **Oriented geodesics** $\gamma_{x_L y_R}$ in the AdS_3
- Kinematic space is **Lorentzian metric space** of signature (2,2), with a **causal ordering**
- For AdS_3 Kinematic space is $dS_2 \times \overline{dS_2}$
 - For the spatial slice, H_2 , it is dS_2

OPE Blocks

The Operator Product Expansion

- Consider two quasi-primary operators $\mathcal{O}_i(x), \mathcal{O}_j(y)$ of dimensions Δ_i, Δ_j . We can expand the product of these two operators using a local basis of operators:

$$\mathcal{O}_i(x) \mathcal{O}_j(0) = \sum_k C_{ijk} |x|^{\Delta_k - \Delta_i - \Delta_j} (1 + b_1 x^\mu \partial_\mu + b_2 x^\mu x^\nu \partial_\mu \partial_\nu + \dots) \mathcal{O}_k(0)$$

Dynamical Parameters
 Conformal Kinematics

- Let us introduce a more compact notation for this expansion

$$\mathcal{O}_i(x) \mathcal{O}_j(y) = |x - y|^{-\Delta_i - \Delta_j} \sum_k C_{ijk} \mathcal{B}_k^{ij}(x, y)$$

OPE Blocks as Kinematic Fields

- The OPE block carries coordinates of two points (x, y) , so we might naturally identify it with a **field living in our kinematic space**.

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Consider a scalar block $(\Delta_k, l = 0)$. Let's characterize this field:

1) What type of field is an OPE block on KS?

- Consider a conformal transformation $x \rightarrow x'$ and $\Omega(x') = \det\left(\frac{\partial x'^{\mu}}{\partial x^{\nu}}\right)$.
Then

$$\mathcal{B}_k^{ij}(x, y) \rightarrow \left(\frac{\Omega(x')}{\Omega(y')}\right)^{(\Delta_i - \Delta_j)/2} \mathcal{B}_k^{ij}(x', y')$$

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- In the simplest **case where $\Delta_i = \Delta_j$** , this transforms as a **scalar field** under isometries of KS.

Let's keep this simplifying assumption for the purposes of this talk: $\mathcal{B}_k(x, y)$

OPE Blocks as Kinematic Fields

2) What is its equation of motion?

- A quasi-primary operator and its descendants have the same conformal Casimir so the OPE block satisfies the equation

$$[L^2, \mathcal{B}_k(x, y)] = C_{\mathcal{O}_k} \mathcal{B}_k(x, y)$$

$$C_{\mathcal{O}_k} = -\Delta(\Delta - d) - \ell(\ell + d - 2)$$

- The OPE block transforms in a bi-local representation of the conformal group, so the Casimir is represented

$$\mathcal{L}_{(B)}^2 = (\mathcal{L}_x + \mathcal{L}_y)^2 = 2 [\ell^2 (-\partial_\ell^2 + \partial_q^2) + \bar{\ell}^2 (-\partial_{\bar{\ell}}^2 + \partial_{\bar{q}}^2)]$$

$$\ell = \frac{z_y - z_x}{2}, \quad q = \frac{z_y + z_x}{2}$$

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$$\ell = \frac{z_y - z_x}{2}, \quad q = \frac{z_y + z_x}{2}$$

$$\mathcal{L}_{(B)}^2 = 2 [\square_{\text{dS}_2} + \bar{\square}_{\text{dS}_2}]$$

OPE Blocks as Kinematic Fields

4) Does this boundary-value problem give a well-posed definition of the field?

- The $dS_2 \times dS_2$ equation of motion has two time directions
 - The equation of motion is a **ultra-hyperbolic** equation.
 - This ultra-hyperbolic BVP is **NOT** well-posed.

But we also forgot one thing:

- The conformal group in 2D factorizes and there are two **quadratic Casimirs**:

Smearred OPE Operators

- We could now solve for a representation of the OPE block using the de Sitter dynamics.
- We can also find the result in a more instantly transparent way:
 - The OPE block expansion is in terms of local operators at a point

$$\mathcal{B}_k(x, 0) = |x|^{\Delta_k} (1 + b_1 x^\mu \partial_\mu + b_2 x^\mu x^\nu \partial_\mu \partial_\nu + \dots) \mathcal{O}_k(0)$$

- Analogous to how we Taylor expand an operator

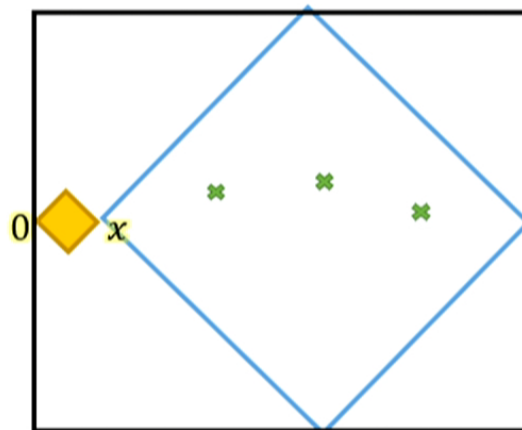
$$\mathcal{O}(x) = (1 + x^\mu \partial_\mu + \dots) \mathcal{O}(0)$$

- There is a choice of basis $\{\mathcal{O}(x)\}_x$ or $\{\partial^n \mathcal{O}(0)\}_n$
- Can we write the OPE block in this other basis using some smearing function?

Smearred OPE Operators

- To choose the integration region, we match the boundary conditions:

$$\lim_{x \rightarrow 0} \mathcal{B}_k(x, 0) = x^{\Delta_k} \mathcal{O}_k(0)$$



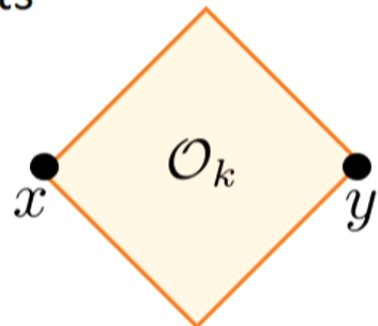
Summary

- We have established that the **OPE block** $\mathcal{B}_k(x, y)$ behaves like a scalar field on the kinematic space of pairs of spacelike points.
 1. **EOM**
 2. **Constraint**
 3. **Boundary conditions**

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We also wrote down a representation of this operator as a smeared operator over the causal diamond formed by the points

$$\mathcal{O}_1(x) \quad \mathcal{O}_2(y) = \sum_k \mathcal{O}_k$$
A diagram illustrating the causal diamond formed by two spacelike points, x and y . The diamond is a yellow-shaded region bounded by four lines connecting the two points. The label \mathcal{O}_k is placed inside the diamond, representing the smeared operator over this region.

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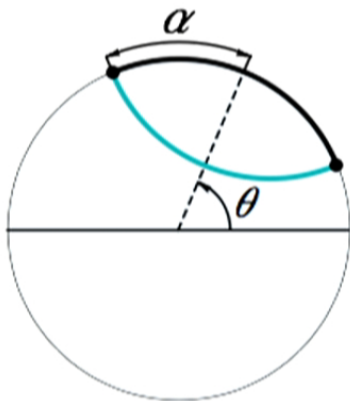
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The OPE block is just what we have been looking for: a suitably **invariant**, **nonlocal** building block in the CFT.

X-Ray Transform

- The analogue of this problem for functions in Hyperbolic space is a well-studied field of integral geometry: it's the **X-ray transform**

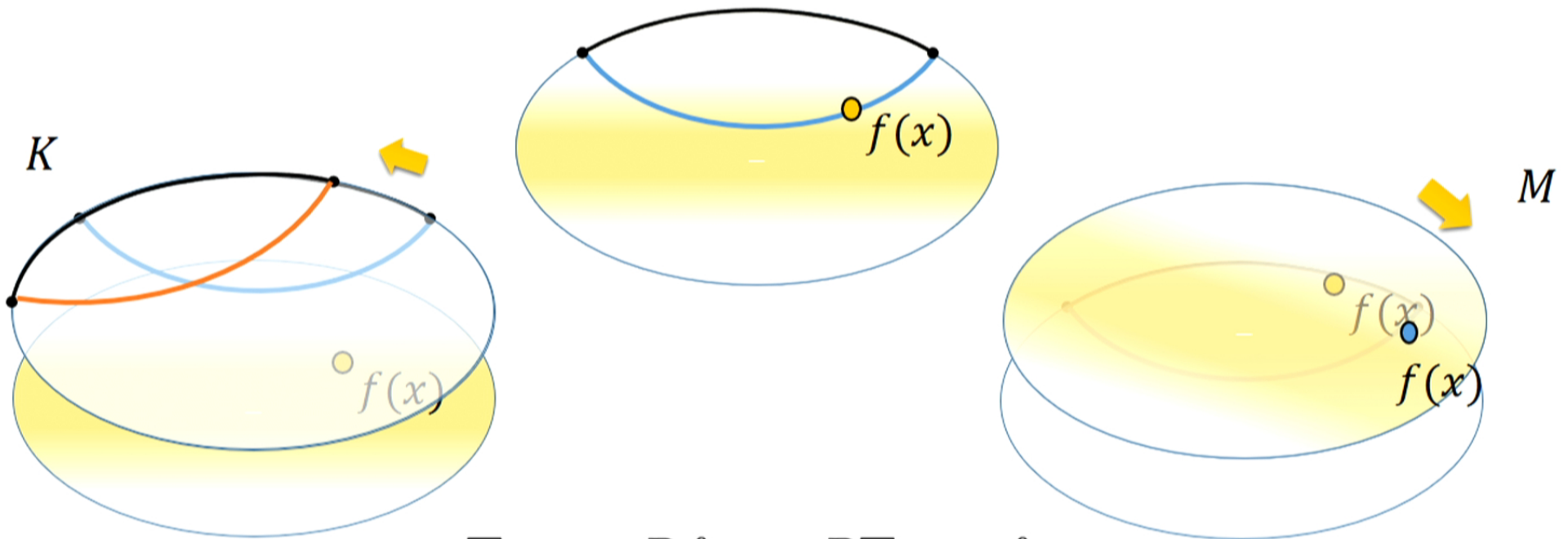
$f(x)$



X-Ray Transform

X-Ray Transform

- The X-ray transform has nice properties under isometries of the geometry:



$$\square_{dS \times dS} Rf = -R \square_{AdS_3} f$$

“Intertwining Operators”

X-Ray Transform

- $dS_2 \times dS_2$ is a **4-dimensional** space AdS_3 is **3-dimensional**.
 - KS is a redundant description of the real geometry and functions that live on it

X-Ray Transform

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 - Many more functions \tilde{f} we can specify on KS than are consistent images Rf of the transform

What constraints do the ray transforms obey?

- **John's equation:**

$$(\square_{dS} - \square_{d\bar{S}}) \tilde{g} = 0 \iff \tilde{g} = Rf$$

X-Ray Transform

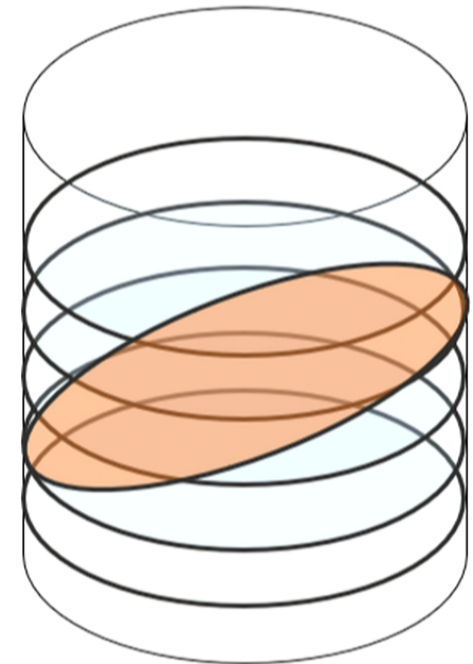
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- *Intuitive meaning:* we can determine function from flat slicing geodesics. Boosted geodesics are a redundant description.



Geodesic Operators

- We can apply the same transform to a 'local' bulk operator ϕ :

$$\tilde{\phi}(\alpha, \theta_c) = \int_{\gamma(\alpha, \theta_c)} ds \phi(x)$$

- Let's assume ϕ is a bulk operator such that $(\square_{AdS} - m^2) \phi(x) = 0$

Intertwinement of the EOM: $(\square_{dS} + \square_{d\bar{S}} + m^2) \tilde{\phi}(\gamma) = 0$

John's equation: $(\square_{dS} - \square_{d\bar{S}}) \tilde{\phi}(\gamma) = 0$

- Let's also assume that ϕ is dual to the bulk field \mathcal{O} ($\phi(x, z) \sim z^\Delta \mathcal{O}_k(x)$).
Then

$$\lim_{\alpha \rightarrow 0} \tilde{\phi}(\alpha, \theta_c) \sim \alpha^\Delta \mathcal{O}_k(\theta_c)$$

Gauge-Invariant Kinematic Dictionary

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1. The same EOM

$$(\square_{dS} + \square_{\bar{d}S} + m^2)\tilde{\phi}(\gamma) = 0$$

$$[\square_{dS_2} + \bar{\square}_{dS_2} + m^2]\mathcal{B}_k(x, y) = 0$$

2. The same constraint

$$(\square_{dS} - \square_{\bar{d}S})\tilde{\phi}(\gamma) = 0$$

$$[\square_{dS_2} - \bar{\square}_{dS_2}]\mathcal{B}_k(x, y) = 0$$

Gauge-Invariant Kinematic Dictionary

- We have now established that the geodesic operator $\tilde{\phi}_\Delta$ and the OPE block $\mathcal{B}_k^{ij}(x, y)$ both share:

- The same EOM
- The same constraint
- The same boundary conditions

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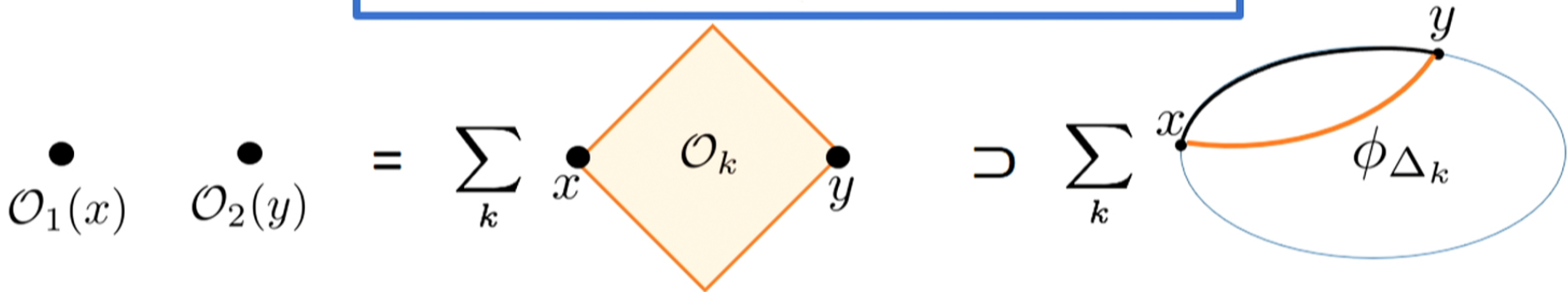
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$$[\square_{dS_2} - \bar{\square}_{dS_2}] \mathcal{B}_k(x, y) = 0$$

$$\lim_{x \rightarrow 0} \mathcal{B}_k(x, 0) \sim x^{\Delta_k} \mathcal{O}_k(0)$$

$$\mathcal{B}_k(x, y) = \tilde{\phi}(\gamma) = \int ds \phi(x, z) \Big|_\gamma$$



Extensions

Higher Dimensions

Most of what I've said extends to higher dimensions.

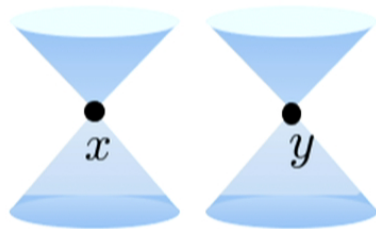
1. There is a **good kinematic metric** on pairs of points:

$$ds_{\mathcal{K}_g}^2 = \frac{I_{\mu\nu}(x-y)}{|x-y|^2} dx^\mu dy^\nu$$

2. Geodesics and OPE blocks are still both described as **scalar fields in \mathcal{K}** .
3. **But**, we **no longer have a nice smearing function** because there is no compact conformally invariant integration region.

Higher Dimensions

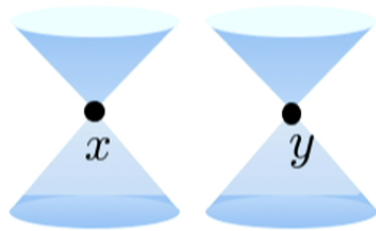
- In higher dimensions, there is a difference between specifying two **spacelike points** and two **timelike points**:



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Higher Dimensions

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- The kinematic space of pairs of **timelike separated points** is now the **kinematic space of bulk minimal surfaces** for the boundary region.
 - For d -dim Hyperbolic space, this kinematic space is d -dim de Sitter [de Boer, Heller, Myers, Neiman]
- Instead of **X-ray transform**, have **Radon transform** over minimal surface of bulk operator: **bulk surface operators**
- We can study to contribution of operators of fixed Casimir to the expansion of loop/surface operators: **surface operator OPE**.

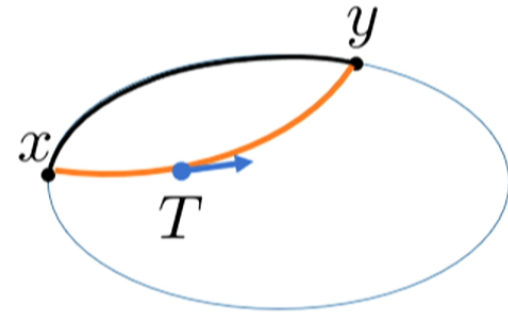
Operators with Spin

- Our **smearing functions** can equally be written for **operators with spin**:

$$(x - y)^{-2\Delta_0} \mathcal{B}_k(x, y) = \int d^d z \langle \mathcal{O}_{\Delta_0}(x) \mathcal{O}_{\Delta_0}(y) \tilde{\mathcal{O}}_{\Delta_k}^{\mu \dots \nu}(z) \rangle \mathcal{O}_{\mu \dots \nu, \Delta_k}(z)$$

- We can correspondingly write **X-Ray transforms of bulk tensor fields**

$$\tilde{T}(\alpha, \theta_c) = \int_{\gamma(\alpha, \theta_c)} ds T^{\mu_1 \dots \nu_k} \dot{x}_{\mu_1} \dots \dot{x}_{\mu_k}$$



Stress Tensor OPE

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- Let's consider the **smearing function** for the **stress tensor** $T(z)$, $\bar{T}(\bar{z})$:

$$\mathcal{B}_T(x_1, x_2) = 6 \int_{z_1}^{z_2} \frac{(z_2 - z)(z - z_1)}{z_2 - z_1} T(z)$$

$$\mathcal{B}_{\bar{T}}(x_1, x_2) = 6 \int_{\bar{z}_1}^{\bar{z}_2} \frac{(\bar{z}_2 - \bar{z})(\bar{z} - \bar{z}_1)}{\bar{z}_2 - \bar{z}_1} \bar{T}(\bar{z})$$

- Adding the two we find:

$$\mathcal{B}_{T_{00}} = -12\pi \int_{x_1}^{x_2} dx \frac{(x_2 - x)(x - x_1)}{x_2 - x_1} T_{00}(x)$$



Stress Tensor OPE

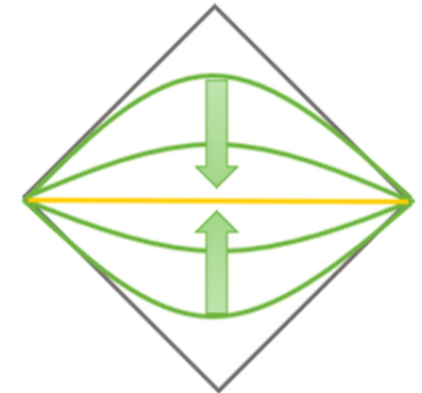
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- This may look familiar, because:

$$H_{\text{mod}} = -\frac{1}{6} \mathcal{B}_{T_{00}}$$

- So the **modular Hamiltonian** is just an **OPE block** (and is a field on KS).

[de Boer, Myers, Heller, Neiman]

Einstein's Equations

- Since H_{mod} is a kinematic operator, we know it **obeys a de Sitter wave equation**:

$$(\square_{\mathcal{K}} + 2d)H_{\text{mod}} = 0$$

- The geodesic operator that is dual to the perturbation in the modular Hamiltonian is just the perturbation in the entanglement entropy

$$\delta S = \delta \langle H_{\text{mod}} \rangle \quad \delta S = \int_{\gamma} \delta g_{\mu\nu} \dot{x}^{\mu} \dot{x}^{\nu}$$

- Using intertwinement of the Laplacian, we can find

$$(\square_{\mathcal{K}} + 2d)\delta H = - \int_{\gamma} (\square_{AdS} - 2d)\delta g_{\mu\nu} \dot{x}^{\mu} \dot{x}^{\nu} = 0$$

Geodesic Witten Diagrams

- The 4-point function of a CFT has an expansion in terms of conformal partial waves

Geodesic Witten Diagrams

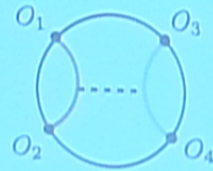
- The 4-point function of a CFT has an expansion in terms of conformal partial waves

$$\langle \mathcal{O}_1 \mathcal{O}_2 \mathcal{O}_3 \mathcal{O}_4 \rangle = \sum_k C_{12k} C_{k34} \mathcal{W}_{k|1234}(x_i)$$

$$\mathcal{W}_{k|1234}(x_i) = \frac{1}{C_{12k} C_{k34}} \underbrace{\langle \mathcal{O}_1 \mathcal{O}_2 P_k \mathcal{O}_3 \mathcal{O}_4 \rangle}_{\sim \mathcal{B}_k^{\Delta_1}(x, y) \mathcal{B}_k^{\Delta_4}(x, y)}$$

- This is simplest when $\Delta_1 = \Delta_2, \Delta_3 = \Delta_4$ and we find

$$\mathcal{W}_{k|1234}(x_i) = \frac{\langle 0 | \mathcal{B}_k(x_1, x_2) \mathcal{B}_k(x_3, x_4) | 0 \rangle}{x_{12}^{\Delta_1 + \Delta_2} x_{34}^{\Delta_3 + \Delta_4}}$$



[Hijano, Kraus, Perlmutter, Snively]

Local Bulk Operators

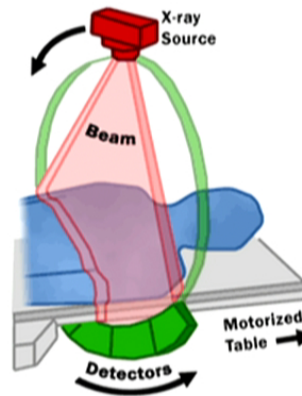
So far:

Geodesic operators give non-local, diff-invariant probes of bulk physics.

Nevertheless:

Would still like to understand the **emergence** of (approximate) **local effective field theory** in a gravitational background.

- Of course, we don't have just one projection of the bulk data—**we have the projections in all 'angles'**
- Reconstructing a complete 3D image from all of these projections (geodesic integrals) is a well-understood problem. It's what allows this:



Inversion Formulae for the Radon Transform

What data do we need to reconstruct a function in the bulk geometry?

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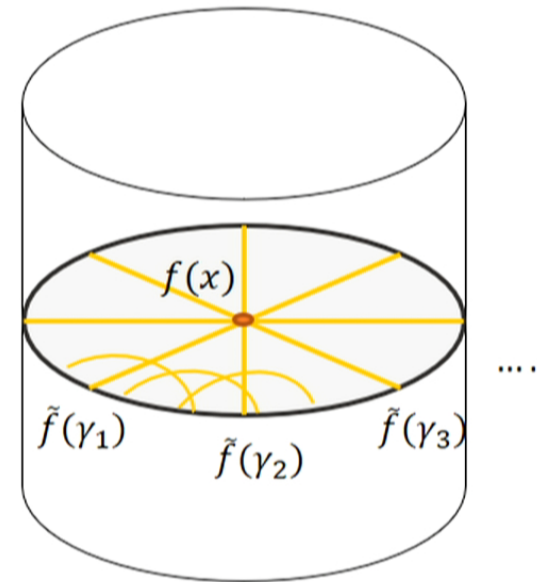
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$$f(x) = -\frac{1}{\pi} \int_0^\infty \frac{dp}{\sinh p} \frac{d}{dp} \left(\text{average } \tilde{f}(\gamma) \right)_{d(x,\gamma)=p}$$



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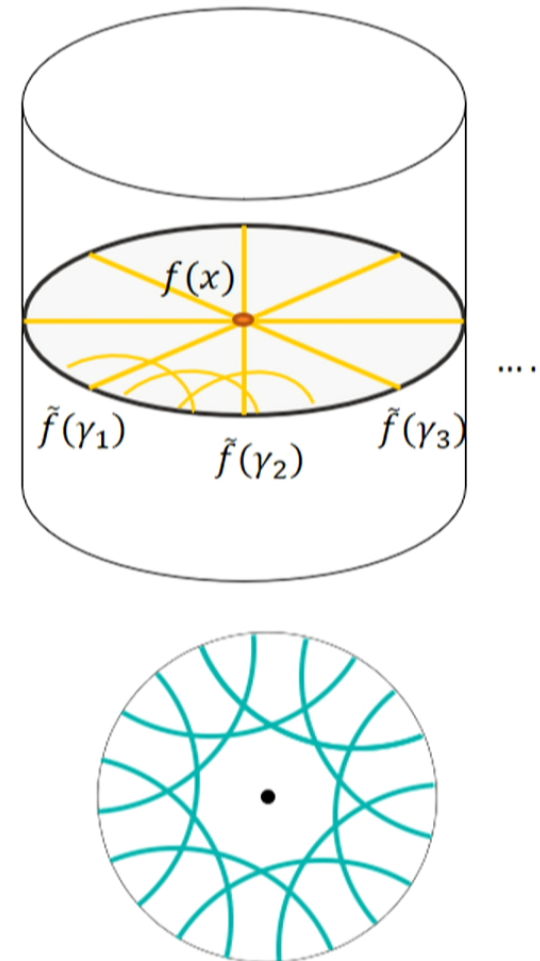
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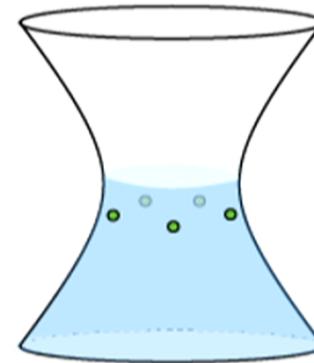
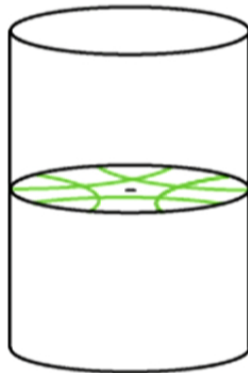
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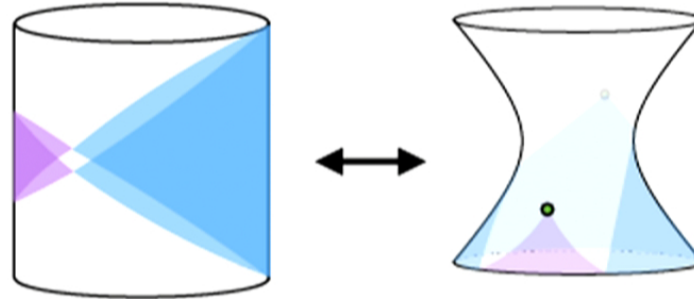
- We **integrate over the parameters** (α, θ_c) , while leaving the boundary integrals in $\mathcal{B}(\alpha, \theta_c)$ unintegrated.
 - This gives the **bulk operator** as an **integral over the spacelike separated boundary region**

$$\phi(\rho = 0) = \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} dt \int_0^{2\pi} d\theta K_{\Delta}(t) \mathcal{O}_{\Delta}(t, \theta) \quad K_{\Delta}(t) = -\frac{k}{\pi} (\cos t)^{\Delta-2} \log \cos t$$

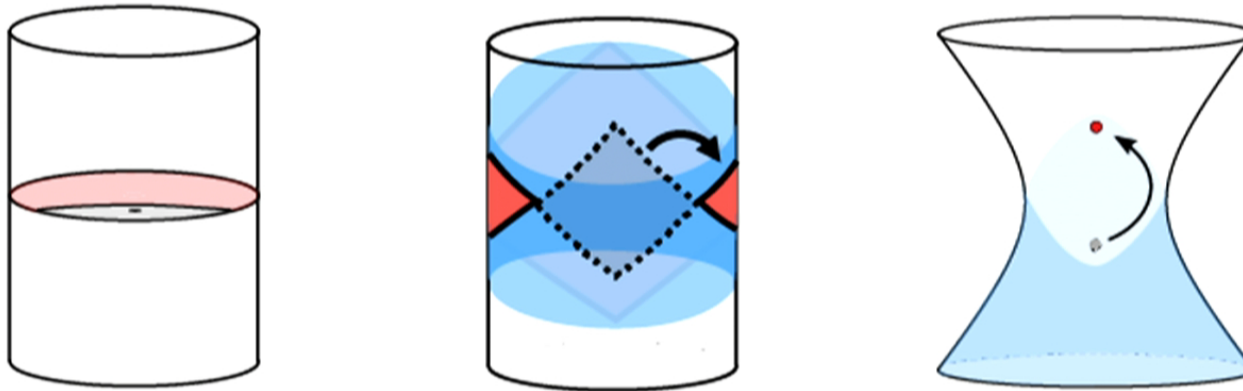
- We have recovered the well-known **HKLL global smearing function**



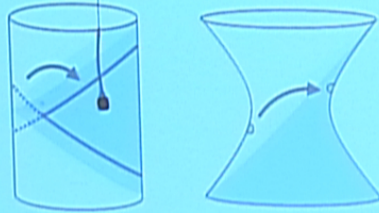
- Our domain of integration is over $\frac{1}{2}$ of the oriented KS.



- We made a **choice of which orientation/causal diamond** to choose for each geodesic.
- We have the apparent **freedom to swap one causal diamond for another...**



- An interesting choice is to choose all of the diamonds that don't contain a fixed boundary point:



- This is now the HKLL smearing function for the Poincare patch
- There is an interesting relation between the different representations of bulk operators and a choice of OPE channel in the boundary theory

Interactions

- The construction of local bulk operators can be **extended to include interactions**:

$$\phi(x, z) = \int d^d x' K(x, z|x') \mathcal{O}(x') + \frac{1}{N} \sum_n a_n^{CFT} \int d^d x' K_n(x, z|x') \mathcal{O}_n(x')$$

[Kabat,Lifschytz,Lowe; Heemskerck,Marolf,Polshinski,JS]

- The explicit corrections were computed up to **O(1/N)** for *specific conformal dimensions* (and conjectured more generally).
- We are able to **compute these to higher order** (much more easily) and for **arbitrary conformal dimension**, confirming the conjectured form at O(1/N).
- The simplification comes by **not solving for the local operator, but solving for the geodesic operator**:

$$\tilde{\phi}_\Delta(\gamma) = \mathcal{B}_\Delta(\gamma) + \frac{1}{N} \sum_n a_n^{CFT} \mathcal{B}_n(\gamma)$$